1. Let 
$$A = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 4 & 1 \\ -2 & 1 & 1 \end{bmatrix}$$

(a) Use elimination to turn A into an upper triangular matrix. How many pivots does A have?

First subtract one times row one from row two:

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 4 & 1 \\ -2 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & 1 \\ -2 & 1 & 1 \end{bmatrix}$$

Next add two times row one to row three:

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & 1 \\ -2 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & 1 \\ 0 & 3 & 1 \end{bmatrix}$$

Finally, subtract one times row two from row three:

$$\begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & 1 \\ 0 & 3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

We can read now that there are two pivots.

(b) Let b = (1, 6, 3). Does Ax = b have a solution?

Appending the vector b and repeating the same steps of reduction gives:

$$\begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 1 & 4 & 1 & | & 6 \\ -2 & 1 & 1 & | & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 3 & 1 & | & 5 \\ -2 & 1 & 1 & | & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 3 & 1 & | & 5 \\ 0 & 3 & 1 & | & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 3 & 1 & | & 5 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

This system does have a solution, since there are no contradictions produced here. In other words, since b is in the row space of A, Ax = b has a solution.

(c) Let b = (1, 6, 5). Does Ax = b have a solution?

Appending the vector b and repeating the same steps of reduction gives

$$\begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 1 & 4 & 1 & | & 6 \\ -2 & 1 & 1 & | & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 3 & 1 & | & 5 \\ -2 & 1 & 1 & | & 5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 3 & 1 & | & 5 \\ 0 & 3 & 1 & | & 7 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & | & 1 \\ 0 & 3 & 1 & | & 5 \\ 0 & 0 & 0 & | & 2 \end{bmatrix}$$

This gives us a contradiction since it claims 0 = 2. Thus, there is no solution to Ax = b.

(d) Can you find multiple solutions in either part (b) or part (c)? If so, find 2.

In part (b), there are multiple solutions. For one, choose  $x_3 = 2$ . Then back substitution says  $3x_2 + 2 = 5 \implies x_2 = 1$  and  $x_1 + x_2 = 1 \implies x_1 = 0$ . So one solution is

$$x = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

For another solution, choose  $x_3 = -1$ . Then,  $3x_2 - 1 = 5 \implies x_2 = 2$ . Then,  $x_1 + 2 = 1 \implies x_1 = -1$ . Thus, a second solution is

$$x = \begin{bmatrix} -1\\2\\-1 \end{bmatrix}.$$

(e) Does A have an inverse? Justify your answer using results from this exercise.

A does not have an inverse because it it is a  $3 \times 3$  matrix that has fewer than 3 pivots.

- 2. Suppose AB = I and CA = I where I is the  $n \times n$  identity matrix.
  - (a) What are the dimensions of the matrices A, B and C?

First consider AB = I. Since the result has n rows and n columns, A must have n rows and B must have n columns. Furthermore, A must have the same number of columns as B has rows (call this m).

Now consider CA = I. Since the result has n rows and n columns, C must have n rows and A must have n columns. Furthermore, C must have the same number of columns as A has rows (call this p).

Combining these two arguments, we can see that A is  $n \times n$ , which implies that B and C are also  $n \times n$ .

(b) Show that B = C.

AB = I Multiply on the left by C on both sides.

$$CAB = CI$$

$$(CA)B = C$$

$$IB = C$$

$$B = C$$

(c) Is A invertible?

A is invertible because there is a matrix B such that AB = I and BA = I (since we showed in (b) that B and C are the same).

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3. Let A be a square matrix with the property that  $A^2 = A$ . Simplify  $(I - A)^2$  and  $(I - A)^7$ .

$$(I - A)^{2} = (I - A)(I - A)$$

$$= I - A - A + A^{2}$$

$$= I - 2A + A$$

$$= I - A$$

$$(I - A)^{7} = (I - A)^{2}(I - A)^{2}(I - A)^{2}(I - A)$$

$$= (I - A)(I - A)(I - A)(I - A)$$

$$= (I - A)^{2}(I - A)^{2}$$

$$= (I - A)(I - A)$$

$$= I - A$$

Where we used the result from the first half to simplify the second half.

4. (a) Write the vector (9, 2, -5) as a linear combination of the vectors (1, 2, 3) and (6, 4, 2) or explain why it can't be done.

We use row reduction to help with this

$$\begin{bmatrix} 1 & 6 & 9 \\ 2 & 4 & 2 \\ 3 & 2 & -5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 6 & 9 \\ 0 & -8 & -16 \\ 3 & 2 & -5 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 6 & 9 \\ 0 & -8 & -16 \\ 0 & -16 & -32 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 6 & 9 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

Reading this off we see we need  $x_2 = 2$  and  $x_1 + 12 = 9 \implies x_1 = -3$ . Thus,

$$-3\begin{bmatrix}1\\2\\3\end{bmatrix} + 2\begin{bmatrix}6\\4\\2\end{bmatrix} = \begin{bmatrix}9\\2\\-5\end{bmatrix}$$

(b) How many pivots does a system of equations with coefficient matrix

$$A = \begin{bmatrix} 1 & 6 & 9 \\ 2 & 4 & 2 \\ 3 & 2 & -5 \end{bmatrix}$$

3

have?

Our work in (a) showed that this matrix has two pivots.

- 5. Suppose A is a  $6 \times 20$  matrix and B is a  $20 \times 7$  matrix.
  - (a) What are the dimensions of C = AB?

Because A is  $6 \times 20$  and B is  $20 \times 7$ , their product, C, will be  $6 \times 7$ .

(b) Suppose A, B, and C have been partitioned into block matrices like so:

$$A = \begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \end{bmatrix}, \quad B = \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \\ B_{31} & B_{32} \end{bmatrix}, \quad C = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix},$$

Suppose that  $A_{11}$  is  $2 \times 10$ ,  $B_{22}$  is  $4 \times 3$ , and  $C_{11}$  is  $? \times 4$ . What are the dimensions of each block of A, B, and C?

[Hint: Make note of every fact you know, sketch all three matrices, and fill in the unknowns step by step]

First, we know that  $A_{11}$ ,  $A_{12}$ , and  $A_{13}$  can only sit next to each other if they each have 2 rows. Thus,  $A_{12}$  is  $2\times$ ? and  $A_{13}$  is  $2\times$ ?. In order for A to have 6 rows in total,  $A_{21}$ ,  $A_{22}$ , and  $A_{23}$  should have 4 rows. In order for  $A_{21}$  to sit below  $A_{11}$ , it must have 10 columns. Thus,  $A_{21}$  is  $4\times 10$ , and  $A_{22}$  and  $A_{23}$  are both  $4\times$ ?.

Similarly for B,  $B_{12}$  and  $B_{32}$  can only line up with  $B_{22}$  if they have 3 columns. Thus,  $B_{12}$  and  $B_{32}$  are both ? × 3. In order for B to have 7 columns in total,  $B_{11}$ ,  $B_{21}$ , and  $B_{31}$  must each have 4 columns.  $B_{21}$  must have 4 rows in order to line up with  $B_{22}$ . Thus,  $B_{11}$  and  $B_{31}$  are ? × 4 and  $B_{21}$  is 4 × 4.

In order for the products  $A_{12}B_{21}$  and  $A_{22}B_{21}$  to make sense,  $A_{12}$  and  $A_{22}$  must have 4 columns. Thus,  $A_{12}$  is  $2 \times 4$  and  $A_{22}$  is  $4 \times 4$ . In order for the product  $A_{11}B_{11}$  to make sense,  $B_{11}$  must have 10 rows. In order to fit next to  $B_{11}$ ,  $B_{12}$  must also have 10 rows. Thus  $B_{11}$  is  $10 \times 4$  and  $B_{12}$  is  $10 \times 3$ .

A will have 20 columns in total only if  $A_{13}$  and  $A_{23}$  have 6 columns each. Thus  $A_{13}$  is  $2 \times 6$  and  $A_{23}$  is  $4 \times 6$ . Similarly, B will only have 20 rows in total if  $B_{31}$  and  $B_{32}$  each have 6 rows. Thus,  $B_{31}$  is  $6 \times 4$  and  $B_{32}$  is  $6 \times 3$ .

 $C_{11} = A_{11}B_{11} + A_{12}B_{21} + A_{13}B_{31}$ . The dimensions of each of these products is  $2 \times 4$ .  $C_{12} = A_{11}B_{12} + A_{12}B_{22} + A_{13}B_{32}$ . The dimensions of each of these products is  $2 \times 3$ .  $C_{21} = A_{21}B_{11} + A_{22}B_{21} + A_{23}B_{31}$ . The dimensions of each of these products is  $4 \times 4$ .  $C_{22} = A_{21}B_{12} + A_{22}B_{22} + A_{23}B_{32}$ . The dimensions of each of these products is  $4 \times 3$ .

In summary:

$$\begin{bmatrix} A_{11} & A_{12} & A_{13} \\ A_{21} & A_{22} & A_{23} \end{bmatrix} = \begin{bmatrix} 2 \times 10 & 2 \times 4 & 2 \times 6 \\ 4 \times 10 & 4 \times 4 & 4 \times 6 \end{bmatrix}$$

$$\begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \\ B_{31} & B_{32} \end{bmatrix} = \begin{bmatrix} 10 \times 4 & 10 \times 3 \\ 4 \times 4 & 4 \times 3 \\ \hline 6 \times 4 & 6 \times 3 \end{bmatrix}$$

$$\begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix} = \begin{bmatrix} 2 \times 4 & 2 \times 3 \\ 4 \times 4 & 4 \times 3 \end{bmatrix}$$

(c) Write each block of C in terms of blocks of A and B.

We did this during our work in part (b):

$$C_{11} = A_{11}B_{11} + A_{12}B_{21} + A_{13}B_{31}.$$

$$C_{12} = A_{11}B_{12} + A_{12}B_{22} + A_{13}B_{32}.$$

$$C_{21} = A_{21}B_{11} + A_{22}B_{21} + A_{23}B_{31}.$$

$$C_{22} = A_{21}B_{12} + A_{22}B_{22} + A_{23}B_{32}.$$

- 6. Let A be an  $m \times n$  matrix.
  - (a) The full A = QR factorization contains more information than necessary to reconstruct A. What are the smallest matrices  $\tilde{Q}$  and  $\tilde{R}$  such that  $\tilde{Q}\tilde{R} = A$ ?

If A is  $m \times n$ , the dimensions of  $\tilde{Q}$  are  $m \times n$  and the dimensions of  $\tilde{R}$  are  $n \times n$ . In order to span the columns of A we only need as many columns in  $\tilde{Q}$  as were originally in A so we can excise the columns to the right of n.  $\tilde{R}$  can be trimmed since it included only zeros below n anyway.

(b) Let  $\tilde{A}$  be an  $m \times n$  matrix (m > n) whose columns each sum to zero, and let  $\tilde{A} = \tilde{Q}\tilde{R}$  be the reduced QR factorization of  $\tilde{A}$ . The squared Mahalanobis distance to the point  $\tilde{x}_i^T$  (the  $i^{\text{th}}$  row of  $\tilde{A}$ ) is

$$d_i^2 = \tilde{x}_i^T \hat{S}^{-1} \tilde{x}_i$$

where  $\hat{S} = \frac{1}{m-1} \tilde{A}^T \tilde{A}$  is a covariance matrix. Compute  $d_i^2$  without inverting a matrix.

We substitute in the QR factorization of  $\tilde{A}$ :

$$d_i^2 = \tilde{x}_i^T \left(\frac{1}{m-1} (\tilde{Q}\tilde{R})^T \tilde{Q}\tilde{R}\right)^{-1} \tilde{x}_i$$

$$= (m-1)\tilde{x}_i^T (\tilde{R}^T (\tilde{Q}^T \tilde{Q})\tilde{R})^{-1} \tilde{x}_i$$

$$= (m-1)\tilde{x}_i^T \tilde{R}^{-1} (\tilde{R}^T)^{-1} \tilde{x}_i$$

$$= (m-1) \left(\tilde{R}^{-T} \tilde{x}_i\right)^T \left(\tilde{R}^{-T} \tilde{x}_i\right)$$

The term in parentheses can be computed with forward substitution without computing a matrix inverse.

Alternatively, we can recognize that, since  $\tilde{x}_i$  is the  $i^{\text{th}}$  row of  $\tilde{A}$ , we can use the row definition of matrix multiplication to recognize that  $\tilde{x}_i^T = \tilde{Q}_i \tilde{R}$  where  $\tilde{Q}_i$  is the  $i^{\text{th}}$  row

of  $\tilde{Q}$ . Then,

$$\begin{split} d_i^2 = & (m-1)\tilde{x}_i^T \tilde{R}^{-1} \tilde{R}^{-T} \tilde{x}_i \\ = & (m-1)(\tilde{Q}_i \tilde{R}) \tilde{R}^{-1} \tilde{R}^{-T} (\tilde{Q}_i \tilde{R})^T \\ = & (m-1)\tilde{Q}_i (\tilde{R} \tilde{R}^{-1}) (\tilde{R}^{-T} \tilde{R}^T) \tilde{Q}_i^T \\ = & (m-1)\tilde{Q}_i \tilde{Q}_i^T. \end{split}$$

Thus,  $d_i^2$  is equal to the dot product of the  $i^{\text{th}}$  row of  $\tilde{Q}$  with itself. If this were the full QR factorization, this would be one, because Q would be orthogonal. But since this is the reduced decomposition, we do not have that guarantee! This formulation also does not require any inverses to be taken.