

## § 8.2 The Simplex Method and Karmarkar's Method

B.2.1 Suppose the cost is  $CX = x_1 + x_2 + x_3$  and the constraint is  $x_1 + 2x_2 + 3x_3 = 12$  with  $x \geq 0$ . Start from  $(12, 0, 0)$  and take a simplex step:

- a) If  $x_2$  goes up from 0 with  $x_3 = 0$  and  $x_1 + 2x_2 = 12$ , find the cost in terms of  $x_2$ .

$$CX = 12 - 2x_2 + x_1 = 12 - x_2.$$

cost decreases as  $x_2$  enters,  $r_2 = -1$ .

- b) If  $x_3$  is increased from 0 with  $x_2 = 0$  and  $x_1 + 3x_3 = 12$ , find the cost in terms of  $x_3$ . What is the reduced cost  $r_3$ ? Why should  $x_3$  be the entering variable?

$$CX = 12 - 3x_3 + x_1 = 12 - 2x_3.$$

cost decreases as  $x_3$  enters,  $r_3 = -2$ .

Since  $r_3 < r_2$  cost decreases more per unit increase of  $x_3$  than  $r_2$ , so  $x_3$  should be the entering variable.

c) The new corner is  $(0, 0, 4)$  when  $x_3$  enters and  $x_1$  leaves. Show that increasing  $x_2$  from zero with  $x_1 = 0$  and  $2x_2 + 3x_3 = 12$  increases cost; the corner  $(0, 0, 4)$  is optimal.

$Cx = x_2 + x_3 = x_2 + 4 - \frac{2}{3}x_2 = 4 + \frac{1}{3}x_2$ ,  $r_2 = \frac{1}{3}$ .  
 cost increases as  $x_2$  enters. Since moving from  $(12, 0, 0)$  to  $(0, 0, 4)$  reduced cost, we would not want to let  $x_1$  enter back either. Conclude  $(0, 0, 4)$  minimizes cost in the feasible region.

8.2.2 With cost vector  $c = [0, 7, 9, 0]$  and constraints  $x_1 + x_2 + x_3 = 6$ ,  $x_2 + 2x_3 + x_4 = 1$ ,  $x_i \geq 0$ , explain directly why  $\bar{x} = (6, 0, 0, 1)$  is optimal.

Since the first and fourth component of  $c$  are zero, we minimize cost by setting  $x_2 = x_3 = 0$  and determine  $x_1, x_4$  satisfying the constraints. Then  $x_1 = 6$  and  $x_4 = 1$  must hold so  $\bar{x} = (6, 0, 0, 1)$  minimizes cost.

B.2.3

Write down the tableau T for the previous question. How do you see the stopping test is passed?

$$T = \left[ \begin{array}{c|c} A & b \\ \hline c & 0 \end{array} \right] = \left[ \begin{array}{cccc|c} 1 & 1 & 1 & 0 & 6 \\ 0 & 1 & 2 & 1 & 1 \\ 0 & 7 & 9 & 0 & 0 \end{array} \right]$$

Since none of the reduced costs  $r_1 = 0$ ,  $r_2 = 7$ ,  $r_3 = 9$ ,  $r_4 = 0$  are negative, this corner minimizes cost in the feasible region.

B.2.4

For the same problem start the simplex method at the wrong corner  $x = (5, 1, 0, 0)$ . Use elimination on T to reach a tableau  $T'$  in which columns 1 and 2 come directly from the identity matrix. What is  $r$ , the vector of reduced costs in the last row. What is the cost at the corner  $(5, 1, 0, 0)$ ? Should  $x_3$  or  $x_4$  be the entering variable?

$$T' = \begin{bmatrix} 1 & 0 & -1 & -1 & 5 \\ 0 & 1 & 2 & 1 & 1 \\ 0 & 0 & -5 & -7 & -7 \end{bmatrix}$$

$r = [0 \ 0 \ -5 \ -7]$   
 At  $(5, 1, 0, 0)$ ,  $Cx = 7$   
 Since  $r_4 = -7 < -5 = r_3$ ,  $x_4$   
 should be the entering variable.

8.2.5 Instead of the tableau split A and c into

$$A = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{bmatrix} = [B \ N] \text{ and}$$

$$c = [0 \ 7 \ 9 \ 0] = [c_B \ c_N].$$

Compute the reduced costs  $r = c_N - c_B B^{-1}N$ .  
 Should  $x_3$  or  $x_4$  be the entering variable?

$$r = [9 \ 0] - [0 \ 7] \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix} = [9 \ 0] - [0 \ 7] \begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}$$

$$= [9 \ 0] - [14 \ 7] = [-5 \ -7] \quad \text{This shows } r_3 = -5, r_4 = -7  
 x_4 \text{ should enter since } r_4 < r_3.$$

### 8.2.6

If  $x_4$  enters the basis then  $x_1$  or  $x_2$  must leave. Keeping  $x_3 = 0$  and  $Ax = b$  show that  $x_1 = 5 + x_4$  and  $x_2 = 1 - x_4$ . Which of these is first to reach zero as  $x_4$  increases. What is  $x$  at this new corner?

$$b = x_1 + x_2 + x_3 = x_1 + x_2 \rightarrow x_1 = b - x_2 = 5 + x_4$$

$$1 = x_2 + 2x_3 + x_4 = x_2 + x_4 \quad x_2 = 1 - x_4$$

$x_2$  reaches 0 first as  $x_4$  increases ( $x_1$  actually increases as  $x_4$  increases). This occurs when  $x_4 = 1$ . The new corner is  $x = (6, 0, 0, 1)$  and the cost is  $Cx = 0$ . This is the optimal corner we started with in 8.2.2.

### 8.2.8

In equation 12,  $B_{\text{new}}^{-1} = \begin{bmatrix} 1 & v_1 \\ \vdots & \vdots \\ 1 & v_m \end{bmatrix}^{-1}$   $B_{\text{old}}^{-1}$ , what is  $\begin{bmatrix} 1 & v_1 \\ \vdots & \vdots \\ 1 & v_m \end{bmatrix}^{-1}$ ?

$$\begin{bmatrix} 1 & v_1 \\ \vdots & \vdots \\ 1 & v_m \end{bmatrix}^{-1} = \begin{bmatrix} 1 & -v_1/v_m \\ \vdots & \vdots \\ 1 & -v_{m-1}/v_m \\ & \ddots \\ & 1/v_m \end{bmatrix}$$

The last column has entries:  
 $-v_1/v_m, -v_2/v_m, \dots, -v_{m-1}/v_m, 1/v_m$ . Otherwise identity.

8.2.9

If we wanted to maximize  $cx$  (still with  $Ax=b$  and  $x \geq 0$ ), what would be the stopping test on  $r$  and what rules would choose the entering variable  $x_i$  and leaving variable  $x_j$ ?

We would stop if  $r \leq 0$  (no reduced costs positive). The entering variable  $x_j$  is chosen by finding the most positive  $r_j$ . The leaving variable  $x_i$  is the first  $x_i$  to reach 0 as  $x_j$  is increased.

8.2.13

- a) Why does ordinary multiplication of an  $m$  by  $n$  matrix by an  $n$  by  $p$  matrix lead to  $mp$  individual multiplications?

Suppose  $A$  is  $m$  by  $n$ ,  $B$  is  $n$  by  $p$  and  $C = AB$ .

The element  $c_{ij}$  of  $C$  is the product of row  $i$  of  $A$ , which is length  $n$ , with column  $j$  of  $B$ , also length  $n$ . Since there are  $mp$  such  $c_{ij}$ ,  $mnp$  multiplications are needed.

b) To compute  $ABC$ , where  $A$  is  $m$  by  $n$ ,  $B$  is  $n$  by  $p$ , and  $C$  is  $p$  by  $q$ , how many multiplications are used in the order  $(AB)C$ ? How many in the order  $A(BC)$ ?

For  $(AB)C$ , first  $mnp$  to compute  $AB$ . Since  $AB$  is  $m$  by  $p$ , multiplying by  $C$  requires  $mpq$  multiplications. Altogether,  $mnp + mpq$ .

For  $A(BC)$ , first  $npq$  to compute  $BC$ . Then  $mnq$  to multiply  $A$  by the  $n$  by  $q$   $BC$ . Altogether,  $npq + mnq$ .

c) If  $B$  is square ( $n=p$ ) which order is better?

$(AB)C$  requires  $mn^2 + mnq$  and  $A(BC)$  requires  $n^2q + mnq$ . If  $m < q$ ,  $(AB)C$  is better and  $A(BC)$  is better if  $q < m$ .

8.Q.14

In Karmarkar's method with  $A = \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$ , what is the projection matrix  $P$ ? Verify that  $P$  is positive semidefinite and  $AP = 0$ .

$$P = I - A^T(AA^T)^{-1}A$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \left( \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right)^{-1} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

$$AP = \frac{1}{3} [(2-1-1) \quad (-1+2-1) \quad (-1-1+2)] = [0 \ 0 \ 0]$$

$$P \sim \begin{bmatrix} 2 & -1 & -1 \\ 0 & 3/2 & -3/2 \\ 0 & -3/2 & 3/2 \end{bmatrix} \sim \begin{bmatrix} 2 & -1 & -1 \\ 0 & 3/2 & -3/2 \\ 0 & 0 & 0 \end{bmatrix}$$

The pivots  $2$ ,  $3/2$ , and  $0$  are all nonnegative  $\Leftrightarrow P$  is positive semidefinite.