

## MA508 – Worksheet 2

An overdamped pendulum on a torsional spring obeys the following differential equation

$$0 = \zeta \dot{\theta} + \kappa \theta - mg\ell \sin(\theta)$$

where  $\theta(t)$  is the angle of the pendulum (with  $\theta = 0$  being straight up),  $\zeta$  is the torsional damping coefficient,  $\kappa$  is the torsional spring constant,  $m$  is the mass of the pendulum,  $g$  is the gravity constant and  $\ell$  is the length of the pendulum.

The equation can be non-dimensionalized to

$$\frac{d\hat{\theta}}{d\hat{t}} = -\beta \hat{\theta} + \sin \hat{\theta}$$

1. In the non-dimensionalized form, what are  $\hat{t}$  and  $\beta$  in terms of the dimensional variables and parameters  $(t, \theta, \zeta, \kappa, m, g, \ell)$ ?

2a) Sketch a phase portrait for the non-dimensionalized equation, for the case  $\beta = 0.1$  [Note: “phase portrait” is a generic term for what I’ve been calling the phase line in class]. In your diagram:

- i. Indicate stable fixed points with a filled circle and unstable ones with a hollow circle.
- ii., Indicate flow directions with arrows on the horizontal axis.

2b) For this case, sketch  $\theta(t)$  when  $\theta(0)$  is a small positive number (the pendulum is initially pointing almost straight up).

- 3) Sketch a bifurcation diagram for the non-dimensionalized equation. In your diagram:
- i. Indicate stable fixed points with a solid line and unstable fixed points with a dashed line
  - ii. Show your calculations for how you determined the fixed points
  - iii. Explain how you determined stability and/or show your calculations
  - iv. Clearly indicate any bifurcation(s) (if they exist)
  - v. Clearly identify and label any saddle-node bifurcation(s)

4) If you’ve done part 3 correctly, you found a bifurcation at  $\beta = 1, \theta = 0$ . This is a new kind of bifurcation, called a transcritical bifurcation. By doing a Taylor expansion about this point, show that transcritical bifurcations (including this one) have the normal form  $\dot{x} = ax - x^2$ .

5) Suppose you have a pendulum whose stiffness,  $\kappa$ , can be tuned. You perform a series of experiments, where the pendulum starts nearly vertical and then is released. For the first experiment, the spring is very weak ( $\kappa \ll 1$ ) and you make it stronger for each subsequent experiment. Explain what would happen.