

#### 4.1 Distributions and the Delta Function

For a differential operator  $L$ , it is reasonable to expect that the inverse operator  $L^{-1}$  is an integral operator, say

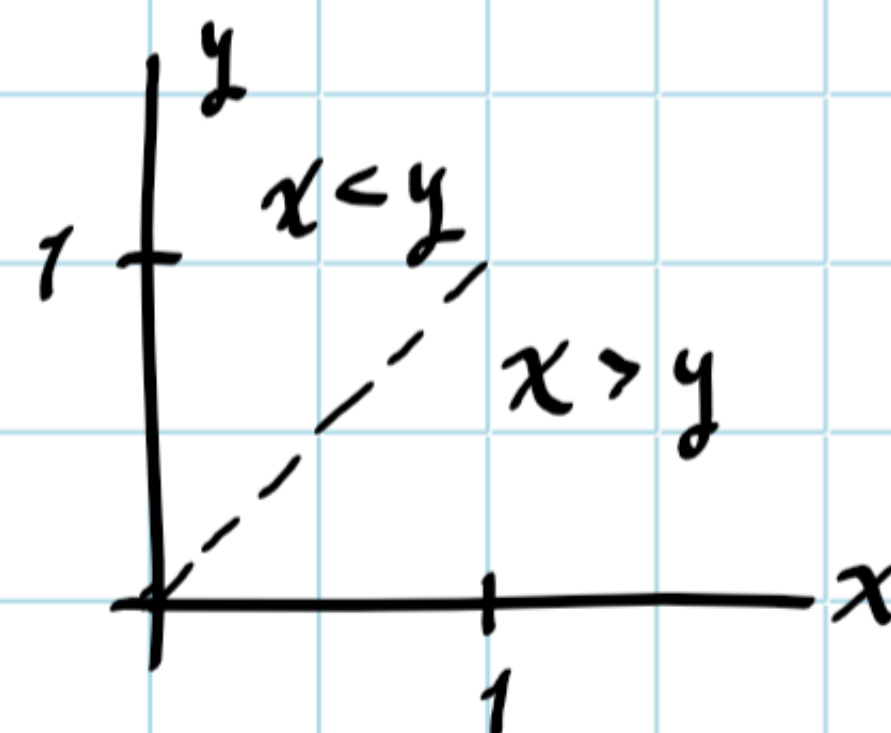
$$L^{-1}(\phi) = \int_a^b g(x,t) \phi(t) dt$$

For example, the differential equation

$$Lu \equiv u'' = \phi(x) \quad u(0) = u(1) = 0$$

has the solution

$$u(x) = \int_0^1 K(x,y) \phi(y) dy, \quad K(x,y) = \begin{cases} y(x-1) & 0 \leq y < x \leq 1 \\ x(y-1) & 0 \leq x < y \leq 1 \end{cases}$$



Verify:

$$u(x) = \int_0^x y(x-1) \phi(y) dy + \int_x^1 x(y-1) \phi(y) dy$$

$$\frac{du}{dx} = \int_0^x \phi(y) \frac{\partial}{\partial x} [y(x-1)] dy + \int_x^1 \phi(y) \frac{\partial}{\partial x} [x(y-1)] dy$$

$$= \int_0^x \phi(y) y dy + \int_x^1 \phi(y) (y-1) dy$$

$$= \int_0^1 \phi(y) y dy - \int_x^1 \phi(y) dy = \int_0^1 \phi(y) y dy + \int_1^x \phi(y) dy$$

$$\frac{d^2 u}{dx^2} = \frac{d}{dx} \left\{ \int_0^1 \phi(y) y dy \right\} + \frac{d}{dx} \left\{ \int_1^x \phi(y) dy \right\} = \phi(x)$$

$$u(0) = \int_0^1 0 \phi(y) dy = 0 \quad u(1) = \int_0^1 y(1-1) \phi(y) dy = \int_0^1 0 dy = 0 \quad \checkmark$$

If the inverse operator is indeed an integral operator, we expect

$$\phi(x) = L(L^{-1}(\phi)) = L\left(\int_a^b g(x,t) \phi(t) dt\right) = \int_a^b L(g(x,t)) \phi(t) dt$$

Written another way:

$$L(g(x,t)) = \delta(x,t) \text{ where } \delta(x,t) \text{ satisfies } \int_a^b \delta(x,t) \phi(t) dt = \phi(x)$$

for any 'reasonable' choice of  $\phi(x)$ . However, no such function  $\delta(x,t)$  exists.

We can still make sense of  $\delta(x,t)$  through the ideas of delta-sequences and the theory of distributions.



## Delta Sequences

Does there exist a sequence of functions  $\{S_k(x)\}$  which satisfies

$$\lim_{k \rightarrow \infty} \int_{-\infty}^{\infty} S_k(t) \phi(t) dt = \phi(0) \quad \forall \phi(x) \in C(\mathbb{R})$$

The existence of such a sequence implies the existence of  $\{S_k(t-x)\}$  satisfying

$$\lim_{k \rightarrow \infty} \int_{-\infty}^{\infty} S_k(t-x) \phi(t) dt = \phi(x)$$

Example)  $S_k(x) = \begin{cases} k, & -1/2k \leq x \leq 1/2k \\ 0, & |x| > 1/2k \end{cases}$

For any function  $\phi(x)$  continuous near  $x=0$ ,

$$\int_{-\infty}^{\infty} S_k(t) \phi(t) dt = \int_{-1/2k}^{1/2k} k \phi(t) dt = k \int_{-1/2k}^{1/2k} \phi(t) dt \rightarrow \phi(0) \text{ as } k \rightarrow \infty$$

Example)  $\{S_k(x)\}$  with  $S_k(x) = \frac{\sin kx}{\pi x}$  is a delta-sequence with the requirement  $\phi(x)$  is Lipschitz continuous.

Delta sequences can be difficult to use. The idea would be to find a sequence

$$\mathcal{L}(g_k(x,t)) = S_k(x-t) \rightarrow g(x,t) = \lim_{k \rightarrow \infty} \mathcal{L}^{-1}(S_k(x-t))$$

From this obtain  $\mathcal{L}^{-1}(\phi) = \int_a^b g(x,t) \phi(t) dt$  for a given differential operator  $\mathcal{L}$ . One would need to both find the  $g_k(x,t)$  and prove that the limit is independent of the choice of delta sequence.

## Distribution Theory

Definition A test function is a function  $\phi(x) \in C^\infty(\mathbb{R})$  with compact support.

The support of  $\phi(x)$  is the closure of the set of  $x$  for which  $\phi(x) \neq 0$ . Since compact subsets of  $\mathbb{R}$  are bounded, one describes  $\phi(x)$  as a function which is infinitely many times continuously differential and which vanishes for sufficiently large  $|x|$ .

Definition A linear functional  $t$  on  $D$  is a real number  $t(\phi)$  which is defined  $\forall \phi \in D$  and is linear in  $\phi$ . The notation we use for linear functionals in  $D$  is  $t(\phi) \equiv \langle t, \phi \rangle$ , referring to  $\langle t, \phi \rangle$  as the action of the linear functional  $t$  on  $\phi$ . Linearity means

$$\langle t, \alpha \phi_1 + \beta \phi_2 \rangle = \alpha \langle t, \phi_1 \rangle + \beta \langle t, \phi_2 \rangle \quad \forall \phi_1, \phi_2 \in D, \forall \alpha, \beta \in \mathbb{R}$$