Daniel George

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# Education

University of California, San Diego graduation June 2024

Bachelor of Science in Computer Engineering

### Relevant Courses

* CSE 11 – Computer Science (Java)
* COGS 9 – Intro to Data Science
* MATH 20D – Differential equations
* MATH 20C – Multivariable Calculus

# Skills

* Java and C/C++: high proficiency
* Python: Medium
* HTML, CSS and JS: Medium
* Bash/Unix Commands: Medium
* Highly Proficient in designing parts and assemblies with Solidworks for manufacture on laser cutter, CNC Mill/Router, and 3D printer
* Moderately proficient in Eagle EDA for PCB design

# Work Experience

**EE/Software Intern at Medical Robotics Startup (Jun-Aug 2019, Redwood City, CA)**

* Created wiring schematic for motor control, which was used in working robot prototype
* Designed and built constant [Voltage LED driver circuit](https://drive.google.com/open?id=1Pn8i5gw39Lxq_b8LXLnbMQYzqQCrJJ4y) to analyze LED brightness and Color to find the best one for the robot
* Wrote software to display pose of 7DOF Robot arm using API in C++

# Personal Projects

* **Neural Networks** – wrote a [feedforward neural network](https://github.com/dangeo314/neural-networks) from scratch to classify handwritten numbers from the MNIST database to ~95% accuracy
* **Home amplifier and speaker set** – built from scratch starting from just PCBs and components. Learned about circuit assembly, transistor circuit design, crossover circuit design (high and low pass filters) and specialized types of capacitors for low noise applications

# Leadership Experience

**Robotics** [**Team 254**](https://www.team254.com/leaders/) **Technical Lead and Competition/Operations Director (2016-20)**

* Led design and assembly of electronics and “Serializer” subsystem for 2020 robot
* Led high school FRC robotics team in electrical and mechanical design for 2019 season
* Hosted workshops for team, teaching physics of electricity, brushless motors, encoders, sensors, and CAN protocol
* Led robot pit crew to victory at 5 competitions as Competition Director
* Worked on electronics for world championship winning, undefeated 2018 robot

**Arduino Club (2019-20)** – Founding member and Vice president of school Arduino Club, taught students about basics of electronics and programming. Used Arduino to create a new, more robust (higher range/reliability) control system for my robotics team’s T-shirt Cannon robot, *Shockwave*.

**VEX Captain (2017)-** Lead a team of ~10 freshmen as Captain for VEX team 254H, involved teaching new members about design process, and leading a team to build a competing robot

**Bellarmine ASB (2017-18)-** Took leadership as part of Bellarmine’s Student Body as Media Tech commissioner. Worked with others to manage audio and technical needs for event

# Awards

**Science department award for excellence in Physics –**  As a TA for AP Physics 1 and AP Physics C, I helped peers during office hours, set up labs, and graded lab reports

## Hobbies

* Play saxophone and piano