Index

A	
Abelian groups	vol.1:p.24
Adjoint operators	vol.1: pp.43 - 44, 87, 103
Affine spaces	vol.1: p.93
Autonomous systems	vol.1:p.7
B	
Bifurcation	vol.1: pp.11 - 12, 63 - 64
Body velocity	vol.1:p.38
C	
Centroid of area	vol.1: pp.4-6
Connection vector field	vol.1: pp.118 - 119
Constraint, holonomic	vol.1:pp.76-77
Constraint, nonholonomic	vol.1: pp.110 - 117, 135 - 136
Cotangent bundle	vol.1:p.126
Cotangent space	vol.1:p.126
Cotangent vector	vol.1: pp.127 - 130
Cross product	vol.1: pp.1-2
D	
Degrees of freedom	vol.1:p.17
Diffeomorphic	vol.1:p.20
Direct product of two sets	vol.1:p.20
Direct sum of two sets	vol.1:p.125
Directional linearity	vol.1:p.106
E	
Embedding	vol.1: p.96
Equivalent vectors w.r.t. functions	vol.1: pp.100 - 101
Euler-lagrange equation	vol.1:p.136
Existence and uniqueness theorem	vol.1:pp.11,13
Exponential map	vol.1: pp.48 - 51, 103 - 104
External forces	vol.1:p.1
F	
Force couple	vol.1:p.2
Force couple system	vol.1:p.3
Forward kinematics	vol.1: pp.78, 83 - 84
Fundamental vector field (infinitesimal generators)	vol.1: pp.99 - 100
G	11 101
Gait generation	vol.1: p.124
Generalized coordinates	vol.1: p.78
Geodesics Chadiant vector field	vol.1: pp.44 - 46, 51, 96 - 99
Gradient vector field	vol.1: pp.129 - 130
Group invariant vectors	vol.1: pp.21, 94 - 95
Group left / right section	vol.1: p.100
Group, left/right action	vol.1: pp.24 - 29, 33, 80, 96, 137
Group, symmetry	vol.1: pp.108 - 109, 137
H	

Holonomic constraint	vol.1: pp.76-77
Homeomorphic	vol.1:p.19
Hysteresis	vol.1: pp.66, 70-71
I	
Image (algebra)	vol.1: p.124
Internal forces	vol.1:p.1
Isomorphic	vol.1:p.22
J	
Jacobian	vol.1: pp.84 - 86
K	14 404 405
Kernel	vol.1: pp.124 - 125
Kinematic locomotion	vol.1: pp.105 - 107
	41 00 100 100
Lie algebra	vol.1: pp.41, 98 - 100, 103
Lie groups	vol.1: pp.21, 96 - 99
Lifted actions	vol.1: pp.31 - 42, 52 - 54, 85, 137
Linearity (mapping)	vol.1: pp.106 - 107
Linearization at a fixed point Local connection	vol.1: pp.10 - 11
Locomotion	vol.1: pp.114 - 117, 120, 122 - 123, 130 vol.1: p.104
Locomotion M	voi.1: p.104
Manifolds	vol.1: pp.17-19,93
Manifolds, accessible	vol.1: pp.17 - 19, 93 vol.1: pp.76 - 78
Manifolds, c^k -differentiable	
Manifolds, curvature	$vol.1: p.20 \ vol.1: p.93$
Manifolds, topology	vol.1: p.93 vol.1: p.93
Modular addition	vol.1: p.35 vol.1: p.21
Monotonic function	vol.1: p.21 vol.1: p.13
Multiplicative calculus	vol.1: p.34 - 38, 46 - 47
N	000.1 . pp.04 00, 40 41
Noether's theorem	vol.1: pp.131 - 134
Nonholonomic constraint	vol.1: pp.110 - 117, 135 - 136
0	111,100
One-form	vol.1: pp.125, 127 - 129
Optimal frame	vol.1: p.83
P	•
Pfaffian constraint	vol.1: pp.111 - 117
Phase portrait	vol.1: pp.7 - 9
Position trajectory	vol.1:p.105
Potentials	vol.1:p.17
Preimage (algebra)	vol.1:p.124
Principle of least action	vol.1: pp.131 - 133
R	
Reaction force	vol.1:p.4
Rigid body	vol.1:p.23
Rigid body, left lifted action	vol.1: pp.38-41
Rigid body, right lifted action	vol.1: pp.41 - 43

S	
Semidirect product of two sets	vol.1:p.24
Shape trajectory	vol.1:p.105
Spatial velocity	vol.1:pp.43,85
Special euclidean group	vol.1:p.23
Special orthogonal group, $so(n)$	vol.1:p.22
Symmetry	vol.1: pp.108 - 109, 131
T	
Tangent spaces	vol.1: pp.29 - 30
U	
Underactuated system	vol.1:p.104
V	
Varignon's theorem	vol.1:p.1
Vector field	vol.1: pp.30 - 31
Vertical space	vol.1:p.125
Z	
Zero set	vol.1: pp.76, 110-111