Index

| A | | |
|--------------------|----------------------------------|--------------------------------|
| | — Abelian groups | vol.1:p.24 |
| | Adjoint operators | vol.1: pp.43-44 |
| | Autonomous systems | vol.1:p.7 |
| <u>B</u> | <u> </u> | |
| | Bifurcation | vol.1: pp.11 - 12, 63 - 64 |
| | Body velocity | vol.1:p.38 |
| <u>C</u> | | |
| | Centroid of area | vol.1: pp.4-6 |
| | Cross product | vol.1: pp.1-2 |
| <u>D</u> | _ | |
| | Degrees of freedom | vol.1:p.17 |
| | Diffeomorphic | vol.1:p.20 |
| | Direct product of two sets | vol.1:p.20 |
| <u>E</u> | _ | |
| | Existence and uniqueness theorem | vol.1:pp.11,13 |
| | Exponential map | vol.1: pp.48-51 |
| | External forces | vol.1:p.1 |
| \underline{F} | _ | |
| | Force couple | vol.1:p.2 |
| | Force couple system | vol.1:p.3 |
| | Forward kinematics | vol.1:p.78 |
| \underline{G} | | |
| | Generalized coordinates | vol.1:p.78 |
| | $\operatorname{Geodesics}$ | vol.1: pp.44 - 46, 51 |
| | Group | vol.1: p.21 |
| | Group, $left/right$ action | vol.1: pp.24 - 29, 33 - 33, 80 |
| <u>H</u> | _ | |
| | Holonomic constraint | vol.1: pp.76 - 77 |
| | Homeomorphic | vol.1: p.19 |
| T | Hysteresis | vol.1: pp.66, 70-71 |
| <u>I</u> | | 7.1 1 |
| | Internal forces | vol.1 : p.1 |
| т | Isomorphic | vol.1:p.22 |
| <u>J</u> | | |
| $\frac{\kappa}{L}$ | | |
| <u>L</u> | — Lie algebra | vol.1:p.41 |
| | Lie groups | vol.1: p.41 vol.1: p.21 |
| | Lifted actions | vol.1: p.31 - 34 |
| | Linearization at a fixed point | vol.1: pp.10 - 11 |
| \underline{M} | Efficientiation at a fixed point | 000.1 . pp.10 11 |
| 212 | — Manifolds | vol.1: pp.17 - 19 |
| | Manifolds, accessible | vol.1: pp.76 - 78 |
| | Manifolds, c^k -differentiable | vol.1: pp.10 $vol.1: p.20$ |
| | Manifolds, C. differentiable | $0.06.1 \cdot p.20$ |

| | Modular addition | vol.1:p.21 |
|-----------------|-----------------------------------|----------------------------|
| | Monotonic function | vol.1:p.13 |
| | Multiplicative calculus | vol.1: pp.34 - 38, 46 - 47 |
| N | _ | |
| 0 | | |
| \underline{P} | | |
| | Phase portrait | vol.1: pp.7-9 |
| | Potentials | vol.1:p.17 |
| Q | | |
| \overline{R} | | |
| | Reaction force | vol.1:p.4 |
| | Rigid body | vol.1:p.23 |
| | Rigid body, left lifted action | vol.1: pp.38-41 |
| | Rigid body, right lifted action | vol.1: pp.41-43 |
| \underline{S} | _ | |
| | Semidirect product of two sets | vol.1:p.24 |
| | Spatial velocity | vol.1:p.43 |
| | Special euclidean group | vol.1:p.23 |
| | Special orthogonal group, $so(n)$ | vol.1:p.22 |
| <u>T</u> | _ | |
| | Tangent spaces | vol.1: pp.29 - 30 |
| \underline{U} | _ | |
| \underline{V} | _ | |
| | Varignon's theorem | vol.1:p.1 |
| | Vector field | vol.1: pp.30 - 31 |
| \underline{W} | _ | |
| <u>X</u> | _ | |
| <u>Y</u> | _ | |
| \underline{Z} | _ | |
| | Zero set | vol.1:p.76 |