

Index

A

Algebraic Lyapunov Equation	<i>pp.</i> 80 – 82
Arrow Matrix	<i>pp.</i> 150 – 154
Asymptotically Stable	<i>pp.</i> 7, 61 – 62, 67 – 69, 75
Attractiveness	<i>pp.</i> 61, 99
Augmented Lagrangian Optimization Method	<i>pp.</i> 209 – 221

B

Bendixson's Theorem	<i>pp.</i> 25 – 29
Bifurcation	<i>pp.</i> 12 – 13
Bifurcation (Fold)	<i>pp.</i> 12 – 13, 57
Bifurcation (Transcritical)	<i>pp.</i> 12 – 15
Bifurcation Diagram	<i>pp.</i> 12, 15 – 17

C

Carrying Capacity	<i>p.</i> 9
Center Manifold Theory	<i>pp.</i> 39 – 45
Centers (Equilibrium Point)	<i>pp.</i> 22, 26
Characteristic Equation	<i>p.</i> 34
Class K (Comparison Functions)	<i>pp.</i> 93 – 97, 102 – 112
Class K L (Comparison Functions)	<i>pp.</i> 93 – 97, 102 – 112
Class K_∞ (Comparison Functions)	<i>pp.</i> 93 – 96, 105
Comparison Function	<i>pp.</i> 93 – 96, 102 – 103
Continuity w.r.t. Initial Conditions	<i>pp.</i> 53 – 55
Continuity w.r.t. Parameters	<i>pp.</i> 54 – 55
Continuously Differentiable	<i>pp.</i> 48 – 52
Control Lyapunov Function	<i>pp.</i> 167, 179 – 180
Controllability Gramian	<i>p.</i> 80
Coordinate Transformation Matrix	<i>pp.</i> 18, 20 – 41

D

Diagonalization	<i>p.</i> 79
Diffeomorphic	<i>p.</i> 196
Differentiable	<i>pp.</i> 51 – 52
Differential Lyapunov Equation	<i>pp.</i> 121 – 122, 128
Dissipation Like Functions	<i>pp.</i> 206 – 208
Divergence	<i>pp.</i> 25 – 29

E

Equilibrium Point	<i>pp.</i> 3 – 4
Estimation of Constant Parameters	<i>pp.</i> 130 – 149
Existence And Uniqueness Theorem	<i>pp.</i> 46 – 52, 91
Exponential Stability	<i>pp.</i> 103 – 104, 107, 116 – 123, 168

F

Feedback Linearization	<i>pp.</i> 185, 194
Finite Escape Time	<i>pp.</i> 9 – 10
Focus Node	<i>pp.</i> 22, 33
Fold Bifurcation	<i>pp.</i> 12 – 13, 57

G

Geometric Series	<i>p.</i> 92
Globally Asymptotically Stable	<i>pp.</i> 62, 67
Green's Theorem	<i>pp.</i> 25 – 27
<i>H</i>	
Hartman Grobman Theorem	<i>pp.</i> 23 – 24
Homeomorphic	<i>p.</i> 23
Hopf Bifurcation	<i>pp.</i> 35 – 38
Huber Function	<i>p.</i> 71
Hurwitz Matrix	<i>pp.</i> 81 – 82
Hyperbolic Equilibrium Point	<i>pp.</i> 22 – 24
<i>I</i>	
Index Theory	<i>p.</i> 35
Infinity Norm	<i>p.</i> 61
Input Output Linearization	<i>pp.</i> 185 – 187, 190 – 191, 197 – 199
Input To State Stability	<i>pp.</i> 201 – 208
Integrator Backstepping	<i>pp.</i> 165 – 178
Invariant Manifold	<i>pp.</i> 42 – 45, 191 – 192
Invariant Set	<i>pp.</i> 74 – 77
Inverted Pendulum	<i>pp.</i> 192 – 194
<i>J</i>	
Jacobian	<i>pp.</i> 56 – 58
<i>L</i>	
L1 Norm	<i>p.</i> 61
L2 Norm	<i>p.</i> 61
La Salle's Invariance Principle	<i>pp.</i> 74 – 77, 85 – 87
Level Sets	<i>pp.</i> 66 – 69
Lie Derivative	<i>pp.</i> 179 – 184
Limit Cycle	<i>pp.</i> 10 – 12, 33 – 38
Linearization at a Fixed Point	<i>pp.</i> 5 – 8, 23 – 24, 88
Lipschitz Continuous Function	<i>pp.</i> 49 – 55, 91
Locally Asymptotically Stable	<i>pp.</i> 61 – 62, 67 – 69
Logistic Equation	<i>p.</i> 9
Lorenz Attractor	<i>p.</i> 12
Lyapunov Functions	<i>pp.</i> 65 – 87
Lyapunov Stability	<i>pp.</i> 59 – 69, 106 – 121
<i>M</i>	
Manifolds, C^k Differentiable	<i>pp.</i> 48 – 52
Markov Parameters	<i>pp.</i> 188 – 190
Metzler Matrix	<i>p.</i> 31
Minima Phase Transfer Function	<i>pp.</i> 194 – 195
Model Reference Adaptive Control	<i>pp.</i> 154 – 165
Moreau Envelope	<i>pp.</i> 211 – 214
<i>N</i>	
Negative Semidefinite Function	<i>pp.</i> 67, 74 – 162
Nesterov Acceleration	<i>p.</i> 98
Node	<i>pp.</i> 21, 33
Normal Form	<i>pp.</i> 195 – 200

<i>O</i>	
Observability	<i>pp.</i> 86 – 87, 127, 130, 138 – 141
Observability Gramian	<i>pp.</i> 80, 129
Observer Based Controller	<i>pp.</i> 135 – 136
<i>P</i>	
P Norm	<i>p.</i> 61
Pendulum	<i>pp.</i> 7 – 8, 63 – 64, 72 – 77
Periodic Orbits	<i>pp.</i> 25 – 34
Phase Portrait	<i>pp.</i> 5, 17 – 19
Pitchfork Bifurcation	<i>pp.</i> 12, 15 – 17
Poincare Bendixson Criterion	<i>pp.</i> 32 – 34
Positive Definite Function	<i>pp.</i> 65 – 66
Positive Definite Matrix	<i>pp.</i> 78 – 79
Positive Invariant Set	<i>pp.</i> 21, 29 – 34, 69
Positive System	<i>p.</i> 31
Predator/prey Model	<i>pp.</i> 30 – 31
Proximal Operator	<i>pp.</i> 210 – 214
<i>R</i>	
Radially Unbounded	<i>pp.</i> 67 – 68, 105 – 107
Reference Signal Tracking	<i>pp.</i> 177 – 178, 183, 199 – 200
Region of Attraction	<i>pp.</i> 15, 92 – 93
Relative Degree	<i>pp.</i> 181 – 193
Routh Hurwitz Criterion	<i>pp.</i> 34, 83
<i>S</i>	
Saddle Node	<i>pp.</i> 19 – 21
Sector Bounded Nonlinearities	<i>p.</i> 72
Sensitivity Function	<i>pp.</i> 55 – 58
Sink Node	<i>pp.</i> 19, 21
Sontag's Formula	<i>p.</i> 180
Source Node	<i>pp.</i> 19, 21
Stability	<i>pp.</i> 5, 98 – 103
Stability Via Linearization	<i>pp.</i> 88 – 90
Stable	<i>p.</i> 5
State Transition Matrix	<i>pp.</i> 105 – 106, 121 – 123
Subcritical Hopf Bifurcation	<i>pp.</i> 37 – 38
Subcritical Pitchfork Bifurcation	<i>p.</i> 17
Supercritical Hopf Bifurcation	<i>pp.</i> 35 – 37
Supercritical Pitchfork Bifurcation	<i>pp.</i> 15 – 16
Symmetric Matrix	<i>p.</i> 78
<i>T</i>	
Taylor Series Expansion	<i>pp.</i> 6, 39 – 40, 44 – 45
Transcritical Bifurcation	<i>pp.</i> 12 – 15
<i>U</i>	
Uniform Observability	<i>pp.</i> 129 – 130, 138 – 143
Uniformly Asymptotically Stable	<i>pp.</i> 100 – 104, 107 – 116
Uniformly Exponentially Stable	<i>pp.</i> 103 – 104, 107, 116 – 123
Uniformly Stable	<i>pp.</i> 100 – 102, 104, 107 – 114

Unitary Diagonal Coordinate Transformation	<i>p.</i> 79
<i>V</i>	
Van Der Pol Oscillator	<i>pp.</i> 11 – 12
Variations of Constants Formula	<i>p.</i> 203
<i>Z</i>	
Zero Dynamics	<i>pp.</i> 181 – 182, 185, 193 – 195