

CpE 3202
Computer Organization & Architecture

# Computer Memory (Internal)

# Characteristics of Computer Memory Systems

- Location
- Capacity
- Unit of transfer
- Access method
- Performance
- Physical type
- Physical characteristics
- Organization



### Location

- CPU
  - Registers and L1 cache
- Internal
  - Main
- External
  - Secondary



# Capacity

#### Word size

- The natural unit of organization
- Typically equal to the number of bits used to represent a number and to the instruction length

#### Number of words

- Or bytes
- Has to do with the number of addressable units



#### Unit of Transfer

#### Internal

- Usually governed by data bus width

#### External

- Usually a block which is much larger than a word

#### Addressable unit

- Smallest location which can be uniquely addressed
- Word internally
- Cluster on M\$ disks



### Access Methods (1)

#### Sequential Access

- Start at the beginning and read through in order
- Access time is highly variable depends on location of data and previous access
- e.g. tape

#### Direct Access

- Individual blocks have unique addresses based on physical location
- Access is direct by jumping to vicinity plus sequential search
- Access time is still variable but not as much as sequential
   depends on location of data and previous access
- e.g. disk



### Access Methods (2)

#### Random Access

- Individual addresses identify physical locations exactly
- Access is direct to desired location
- Access time is independent of location or previous access
- e.g. RAM

#### Associative

- Data is retrieved by comparing a sub-part of the data with a desired mask (location is not needed)
- All matches to the mask are retrieved simultaneously
- Access time is independent of location or previous access
- e.g. cache



# Memory Hierarchy

- Registers
  - In CPU
- Internal or Main memory
  - May include one or more levels of cache
  - "RAM"
- External memory
  - Backing store



#### Performance

#### Access time

 Time between presenting the address and getting the valid data

#### Memory Cycle time

- Time may be required for the memory to "recover" before next access
- Cycle time is access + recovery

#### Transfer Rate

Rate at which data can be moved (bits/sec)



### Physical Types

- Semiconductor
  - RAM
- Magnetic
  - Disk & Tape
- Optical
  - CD & DVD
- Others
  - Bubble (stationary disk with spinning bits)
  - Hologram (optical, will go beneath the surface and use the volume of the recording medium for storage)



### Physical Characteristics

- Decay
- Volatility
  - Volatile (information is lost without power)
  - Non-volatile (information retains until changed; no electrical power needed)
- Erasable
  - Erasable
  - Non-erasable (information can't be altered with a normal memory access cycle; must be nonvolatile)
- Power consumption



### Organization

- Physical arrangement of bits into words
- Not always obvious
- e.g. interleaved organization, characters vs. integers vs. floating point numbers



# The Bottom Line: Design Constraints

#### • How much?

- Capacity
- Applications tend to be built to use any commonly available amount

#### How fast?

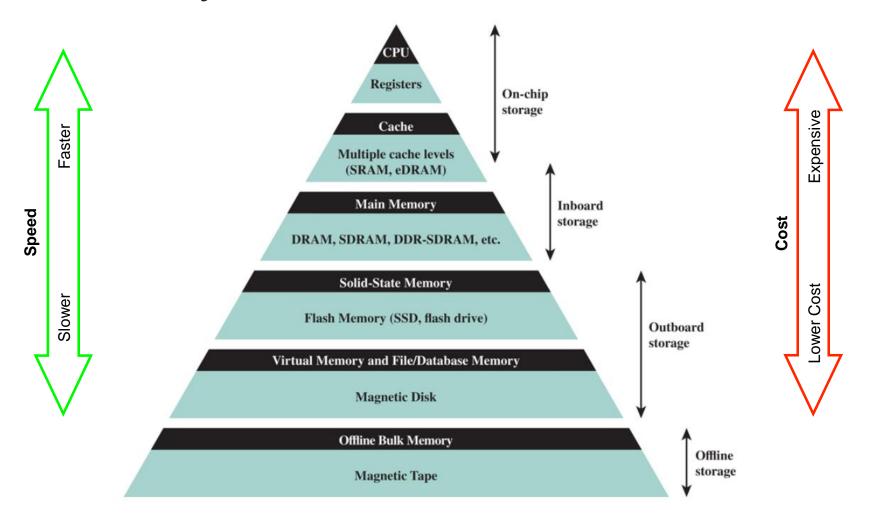
- Time is money
- Must be able to keep up with the CPU

### How expensive?

Cost must be reasonable



# Hierarchy List





# So you want fast?

- It is possible to build a computer which uses only static RAM (see later)
- This would be very fast
- This would need no cache
  - How can you cache cache?
- This would cost a very large amount



# Locality of Reference

- Success depends upon the locality of reference
- During the course of the execution of a program, memory references tend to cluster (e.g. loops)
- Temporal locality
  - If a location is referenced, it is likely to be referenced again in the near future
- Positional locality
  - Time is money
- Basis for caching and virtual memory



# Semiconductor Memory

#### RAM

- Misnamed as all semiconductor memory is random access
- Read/Write
- Volatile
- Temporary storage
- Static or Dynamic



# Dynamic RAM

- Bits stored as charge in capacitors
- Charges leak
- Need refreshing even when powered
- Simpler construction
- Smaller per bit
- Less expensive
- Need refresh circuits
- Slower
- Main memory



DRAMs in SODIMM Form Factor



#### Static RAM

- Bits stored as on/off switches
- No charges to leak
- No refreshing needed when powered
- More complex construction
- Larger per bit
- More expensive
- Does not need refresh circuits
- Faster
- Cache



SRAM in an SOIC Package



# Read Only Memory (ROM)

- Permanent storage
- Microprogramming (see later)
- Library subroutines
- Systems programs (BIOS)
- Function tables



### Types of ROM

- Written during manufacture
  - Very expensive for small runs
- Programmable (once) PROM
  - Needs special equipment to program
- Read "mostly"
  - Erasable Programmable (EPROM)
    - Erased by UV
  - Electrically Erasable (EEPROM)
    - Byte-level writing
    - Takes much longer to write than read
  - Flash memory
    - Erase whole memory electrically



EPROM in DIP Package



Flash memory in Quad-Flat Package



### Organization in detail

- A 16Mbit chip can be organized as 1M of 16 bit words
- A bit per chip system has 16 lots of 1Mbit chip with bit 1 of each word in chip 1 and so on
- A 16Mbit chip can be organized as a 2048 x 2048 x 4bit array
  - Reduces number of address pins
    - Multiplex row address and column address
    - 11 pins to address (2<sup>11</sup>=2048)
    - Adding one more pin doubles range of values

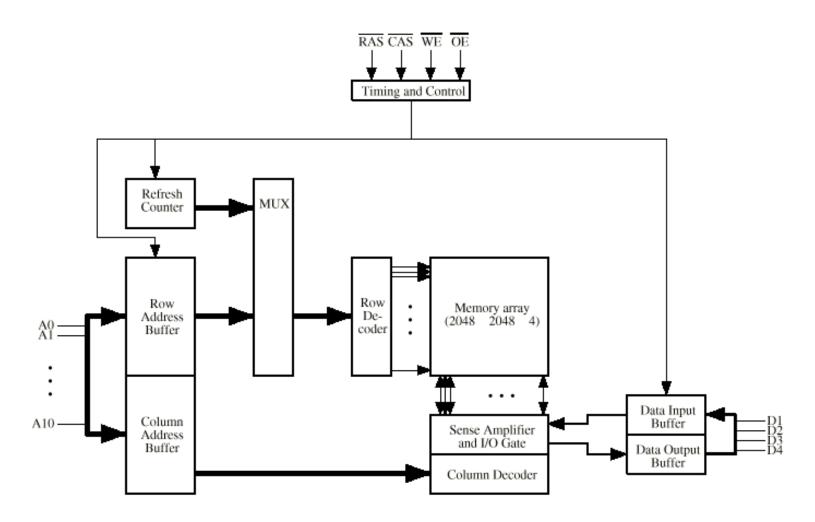


# Refreshing

- Refresh circuit included on chip
- Disable chip
- Count through rows
- Read & Write back
- Takes time
- Slows down apparent performance

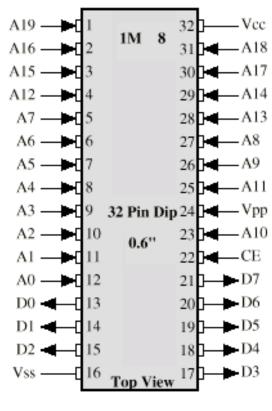


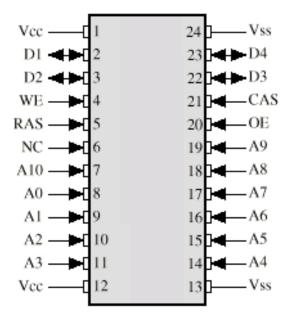
### Typical 16 Mb DRAM (4M x 4)





#### Packaging

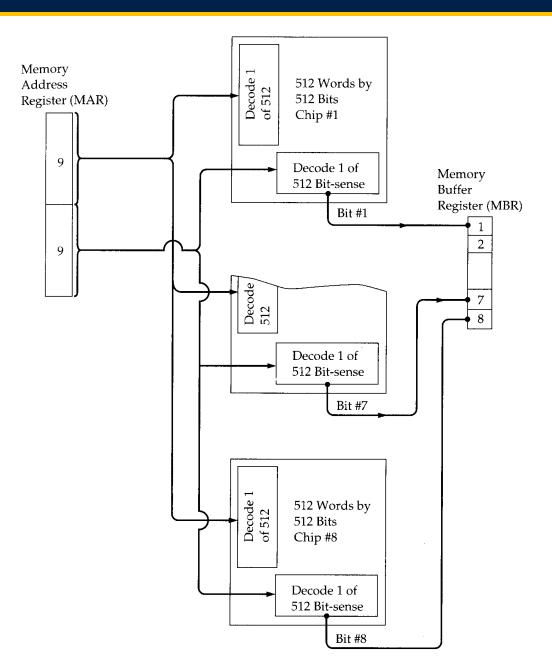




(a) 8 Mbit EPROM

(b) 16 Mbit DRAM



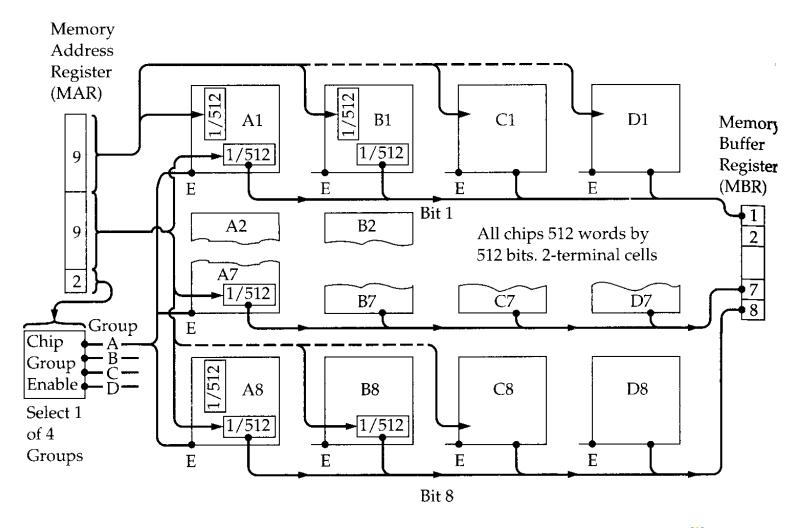


Module organization





### Module organization (2)





#### **Error Correction**

#### Hard Failure

Permanent defect

#### Soft Error

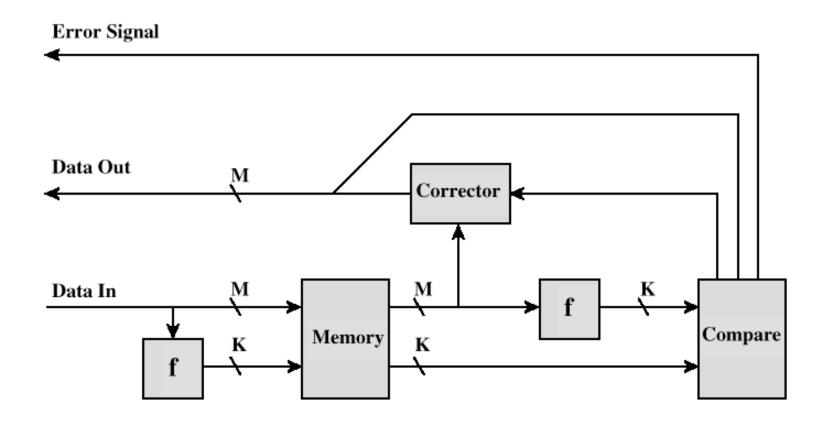
- Random, non-destructive
- No permanent damage to memory
- Caused by power supply problems, alpha particles

#### Detection and Correction

- Hamming error correcting code
- SEC-DED codes



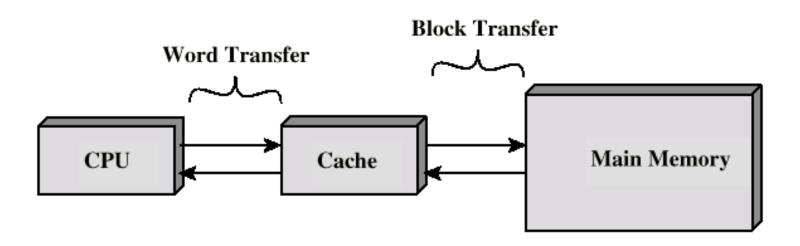
# **Error Correcting Code Function**





### Cache

- Small amount of fast memory
- Sits between normal main memory and CPU
- May be located on CPU chip or module





### Cache operation - overview

- CPU requests contents of memory location
- Check cache for this data
- If present, get from cache (fast)
- If not present, read required block from main memory to cache
- Then deliver from cache to CPU
- Cache includes tags to identify which block of main memory is in each cache slot
- The proportion of memory references, which are found already stored in cache, is called the hit ratio.



# Elements of Cache Design

- Size
- Mapping Function
- Replacement Algorithm
- Write Policy
- Block Size
- Number of Caches

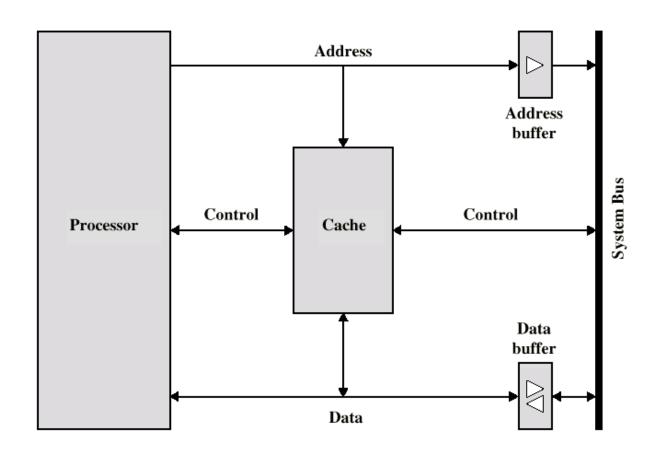


### Size does matter

- Cost
  - More cache is expensive
- Speed
  - More cache is faster (up to a point)
  - Checking cache for data takes time



# Typical Cache Organization





# Mapping Function

- Determines which cache line to use for a particular block of main memory (since number\_of\_cache\_lines << number\_of\_blocks)</li>
- Cache of 64kByte
- Cache block of 4 bytes
  - -i.e. cache is 16k (2<sup>14</sup>) lines of 4 bytes
- 16MBytes main memory
- 24 bit address
  - $-(2^{24}=16M)$



# **Direct Mapping**

- Each block of main memory maps to only one cache line
  - i.e. if a block is in cache, it must be in one specific place
- Address is in two parts
- Least Significant w bits identify unique word
- Most Significant s bits specify one memory block
- The MSBs are split into a cache line field r and a tag of s-r (most significant)



#### Direct Mapping Address Structure

Tag s-r	Line or Slot r	Word w
8	14	2

- 24 bit address
- 2 bit word identifier (4 byte block)
- 22 bit block identifier
  - 8 bit tag (=22-14)
  - 14 bit slot or line
- No two blocks in the same line have the same Tag field
- Check contents of cache by finding line and checking Tag

#### Direct Mapping Cache Line Table

Cache line

Main Memory blocks held

• (

0, m, 2m, 3m...2s-m

• 1

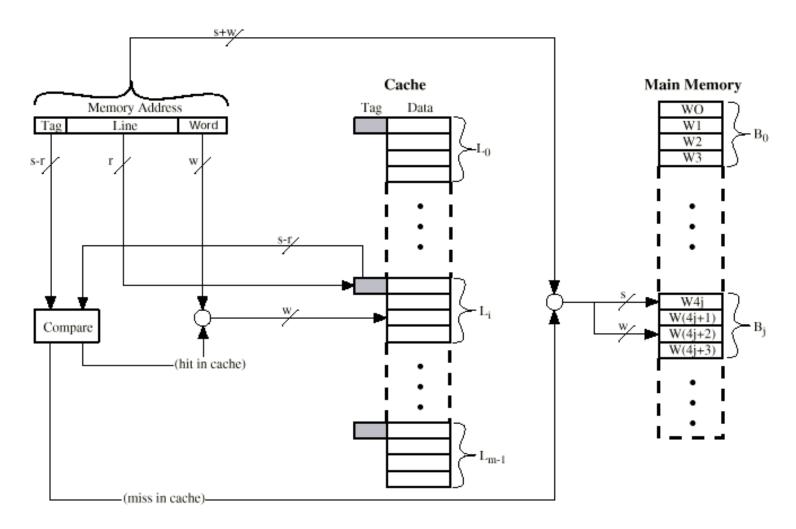
1,m+1, 2m+1...2s-m+1

• m-1

m-1, 2m-1,3m-1...2s-1



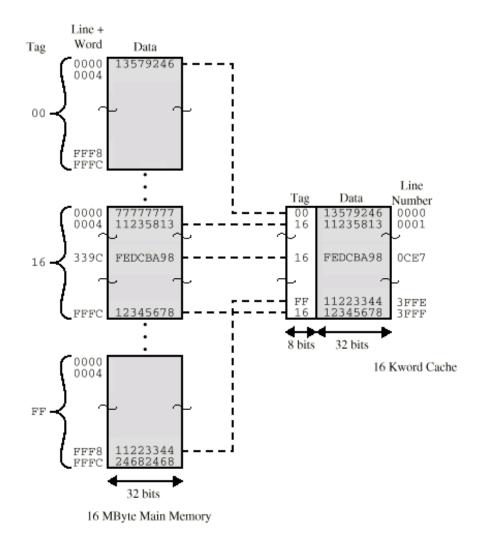
#### Direct Mapping Cache Organization







### Direct Mapping Example





### Direct Mapping pros & cons

- Simple
- Inexpensive
- Fixed location for given block
  - If a program accesses 2 blocks that map to the same line repeatedly, cache misses are very high

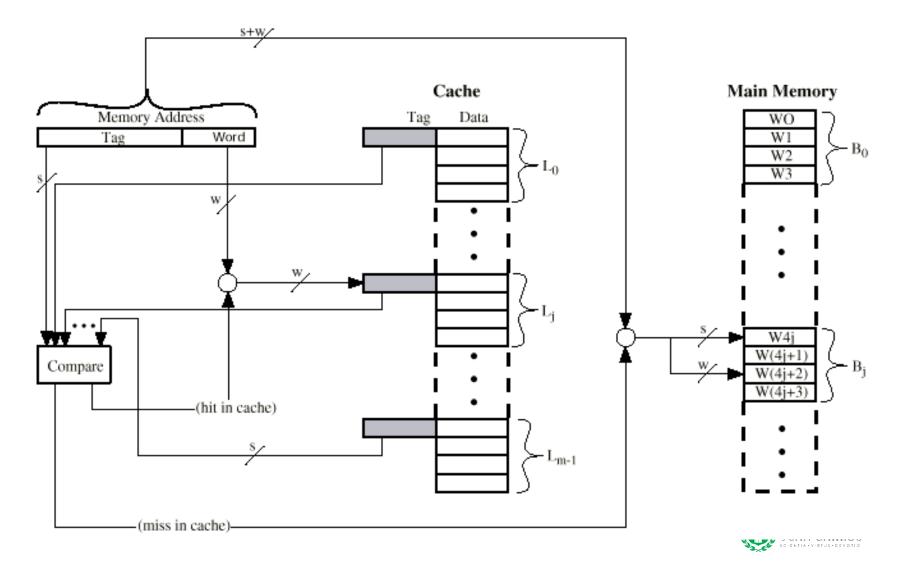


## **Associative Mapping**

- A main memory block can load into any line of cache
- Memory address is interpreted as tag and word
- Tag uniquely identifies block of memory
- Every line's tag is examined for a match
- Cache searching gets expensive

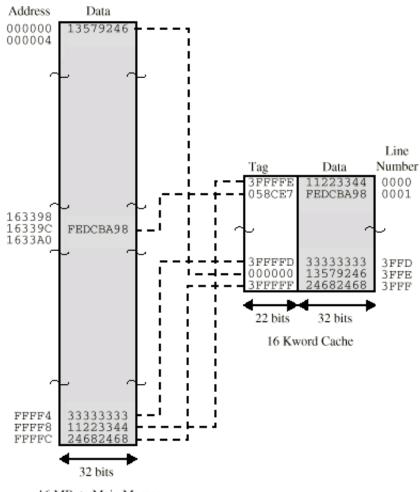


## Fully Associative Cache Organization





#### Associative Mapping Example







#### Associative Mapping Address Structure

Tag 22 bit Word 2 bit

- 22 bit tag stored with each 32 bit block of data
- Compare tag field with tag entry in cache to check for hit
- Least significant 2 bits of address identify which 16 bit word is required from 32 bit data block
- e.g.

AddressTagDataCache line

- FFFFC FFFFC 24682468 3FFF



## Set Associative Mapping

- Cache is divided into a number of sets
- Each set contains a number of lines
- A given block maps to any line in a given set
  - e.g. Block B can be in any line of set i
- e.g. 2 lines per set
  - 2 way associative mapping
  - A given block can be in one of 2 lines in only one set

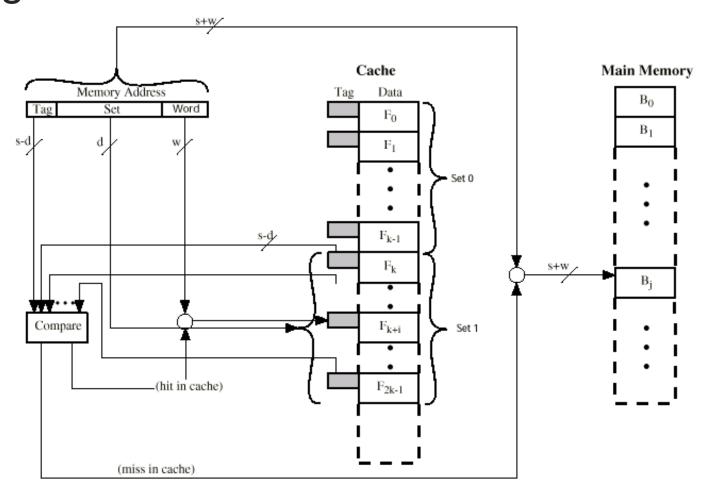


## Set Associative Mapping Example

- 13 bit set number
- Block number in main memory is modulo 2<sup>13</sup>
- 000000, 00A000, 00B000, 00C000 ... map to same set



## Two Way Set Associative Cache Organization





## Set Associative Mapping Address Structure

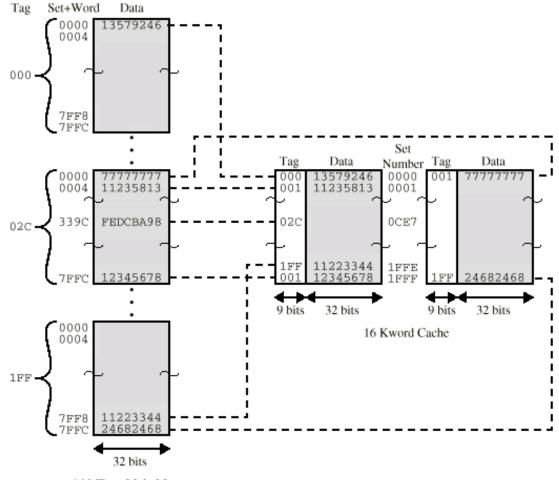
Tag 9 bit	Set 13 bit	Word 2 bit
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- Use set field to determine cache set to look in
- Compare tag field to see if we have a hit
- e.g
  - AddressTag DataSet number
  - 1FF 7FFC 1FF 123456781FFF
  - 001 7FFC 001 112233441FFF





# Two Way Set Associative Mapping Example



16 MByte Main Memory



# Replacement Algorithms (1) Direct mapping

- No choice
- Each block only maps to one line
- Replace that line



#### Replacement Algorithms (2) Associative & Set Associative

- Hardware implemented algorithms (speed)
- Least Recently used (LRU)
- e.g. in 2 way set associative
  - Which of the 2 block is LRU?
- First in first out (FIFO)
  - replace block that has been in cache longest
- Least frequently used
  - replace block which has had fewest hits
- Random



## Write Policy

- Must not overwrite a cache block unless main memory is up to date
- Multiple CPUs may have individual caches
- I/O may address main memory directly



### Write through

- All writes go to main memory as well as cache
- Multiple CPUs can monitor main memory traffic to keep local (to CPU) cache up to date
- Lots of traffic
- Slows down writes
- Generates substantial memory traffic and may create a bottleneck



#### Write back

- Updates initially made in cache only
- Update bit for cache slot is set when update occurs
- If block is to be replaced, write to main memory only if update bit is set
- Other caches get out of sync
- I/O must access main memory through cache
- N.B. 15% of memory references are writes



#### Pentium Cache

- Foreground reading
- Find out detail of Pentium II cache systems
- NOT just from Stallings!



## New RAM Technology (1)

- Basic DRAM same since first RAM chips
- Enhanced DRAM
  - Contains small SRAM as well
  - SRAM holds last line read (c.f. Cache!)
- Cache DRAM
  - Larger SRAM component
  - Use as cache or serial buffer



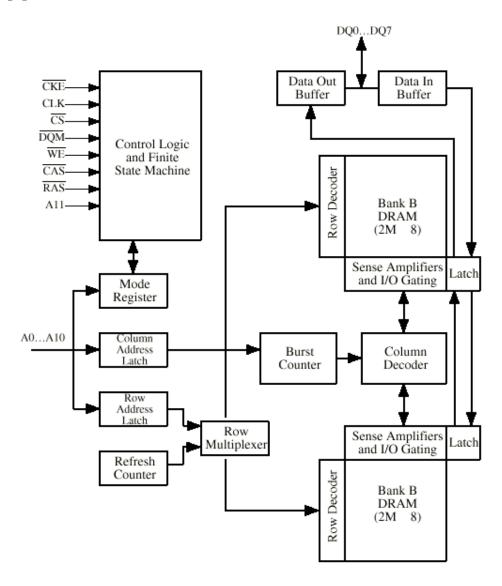
## New RAM Technology (2)

#### Synchronous DRAM (SDRAM)

- currently on DIMMs
- Access is synchronized with an external clock
- Address is presented to RAM
- RAM finds data (CPU waits in conventional DRAM)
- Since SDRAM moves data in time with system clock,
   CPU knows when data will be ready
- CPU does not have to wait, it can do something else
- Burst mode allows SDRAM to set up stream of data and fire it out in block



#### **SDRAM**





## New RAM Technology (3)

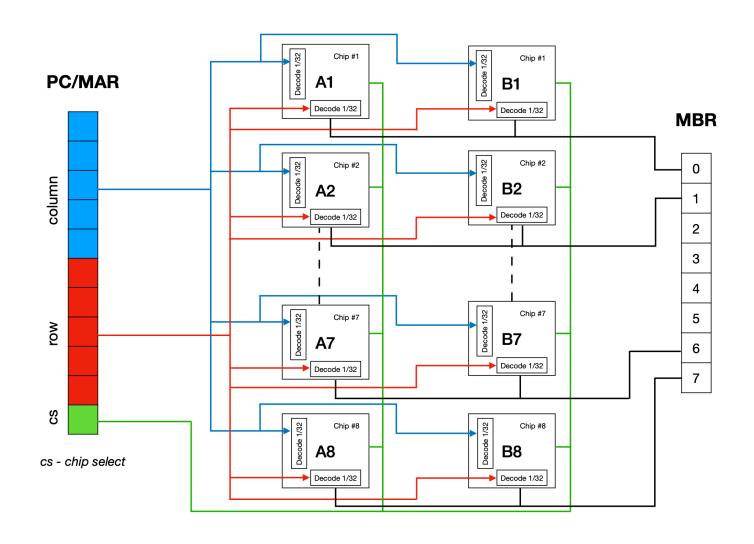
- Foreground reading
- Check out any other RAM you can find
- See Web site:
  - The RAM Guide



## TRACS Memory Organization (RAM)

- Composed of sixteen (16) 32x32 bit chips for total of 16Kbit
- Two (2) chip groups A & B
- Organized into (32 + 32) bit columns and (32 x
   8) rows
- Chip Select (cs) identify the chip group A or B
- Address bus is composed of column address, row address and chip group selector





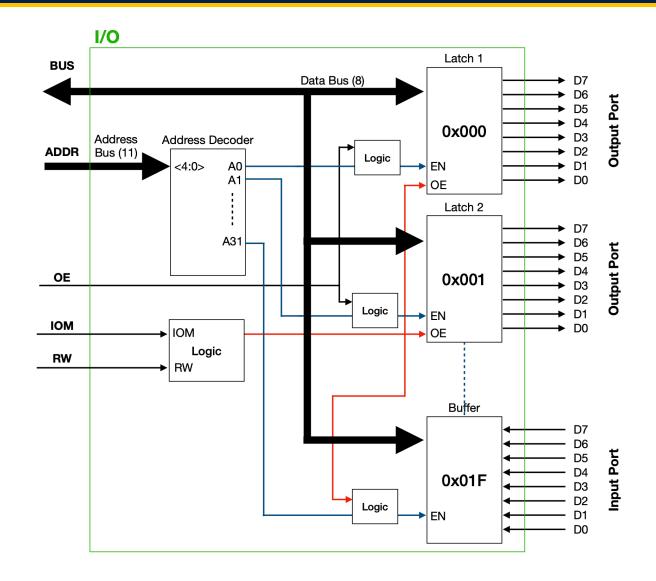
**TRACS Memory Organization** 



## TRACS Memory Organization (I/O)

- Isolated from Main Memory (as I/O Memory)
- Maximum of 32 addressable latch/buffer
- IO address decoding, enables the proper latch or buffer
- Latches for output signals and buffer for input signals
- I/O read and write control via IOM and RW control lines
- Data latched (output) when IOM=0 and RW=1
- Data buffered (input) when IOM=0 and RW=0





**TRACS I/O Memory Organization** 





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Computer Organization & Architecture
End of Lecture

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#### References:

- Brey, Barry B. The Intel microprocessors 8086/8088, 80186/80188, 80286, 80386, 80486, Pentium, Pentium Pro processor, Pentium II, Pentium III, Pentium 4, and Core2 with 64-bit extensions: architecture, programming, and interfacing / Barry B. Brey—8th ed.
- Stallings, W. Computer Organization and Architecture, 6th edition, Pearson Education, Inc. (2003).