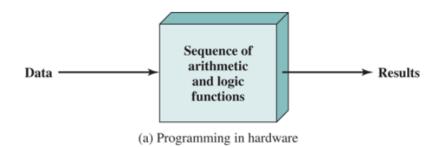


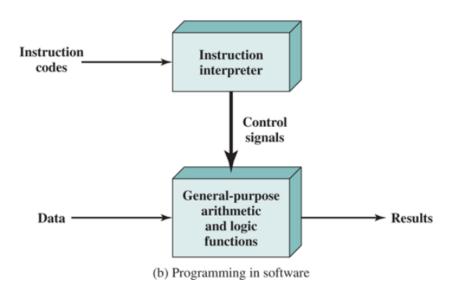
CpE 3202 Computer Organization & Architecture

The Control Unit

Program Concept

- Hardwired systems are inflexible
- General purpose hardware can do different tasks, given correct control signals
- Instead of re-wiring, supply a new set of control signals

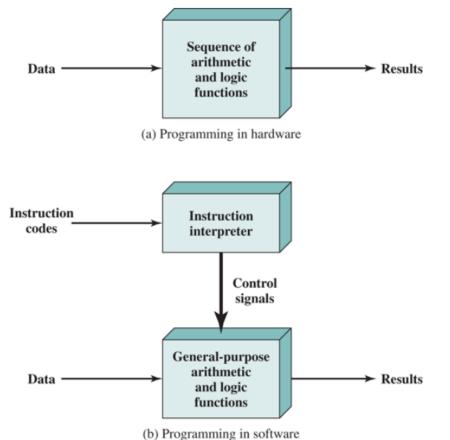






What is a Program?

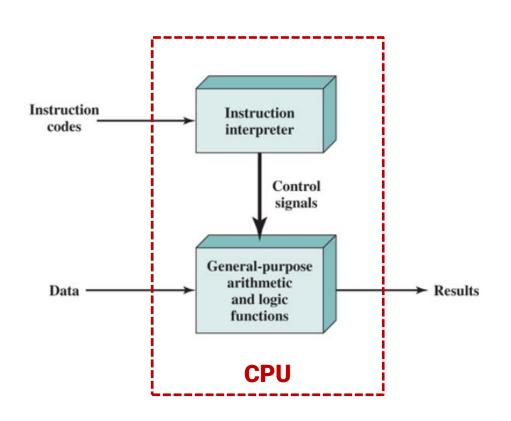
- A sequence of steps
- For each step, an arithmetic or logical operation is done
- For each operation, a different set of control signals is needed





Function of Control Unit

- For each operation, a unique code is provided
 - e.g. ADD, MOVE
- A hardware segment accepts the code and issues the control signals
- We have a computer!



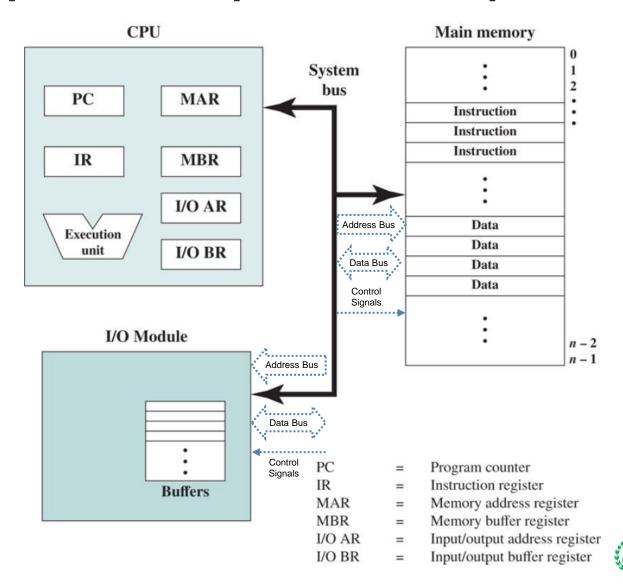


Components

- The Control Unit (CU) and the Arithmetic and Logic Unit (ALU) constitute the Central Processing Unit (CPU)
- Data and instructions need to get into the system and results out
 - Input/output
- Temporary storage of code and results is needed
 - Main memory
 - For von Neumann architectures, same memory for both instructions and data



Computer Components: Top Level View



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Buses

- Address Bus *n*-bit parallel wires which connects to the address lines of data and I/O memory. It carries the address bits and is unidirectional (*read only*).
- Data Bus 2ⁿ-bit parallel wires which connects to the data lines of data and I/O memory. It carries the data bits and is bi-directional (read/write).
- Control Signals *n*-bit signals which carries control signals from the control unit.



Registers (Address Pointers)

- Program Counter (PC) contains a memory address that points to the next instruction to be fetched.
- Instruction Register (IR) holds the instruction that is fetched.
- Memory Address Register (MAR) contains a memory address that points to the data to be read/written from/to the <u>data</u> <u>memory</u>.
- I/O Address Register (IOAR) contains a memory address that points to the data to be read/written from/to the I/O memory.



Registers (Data)

- Memory Buffer Register (MBR) contains the data that is read or to be written from/to the <u>data memory</u>.
- I/O Buffer Register (IOAR) contains the data that is read or to be written from/to the I/O memory.



Control Signals (External)

- **IOM** a 1-bit signal that indicates which memory will be accessed data or I/O memory and is connected to both data and I/O memory.
- **RW** a 1-bit signal that tells the data or I/O memory what operation to perform, read or write and is connected to both data and I/O memory.
- OE enables the output of the data or I/O memory.
- Other signals which will be generated depending on the instruction to control other components like the bus controller, DMA controller, etc.

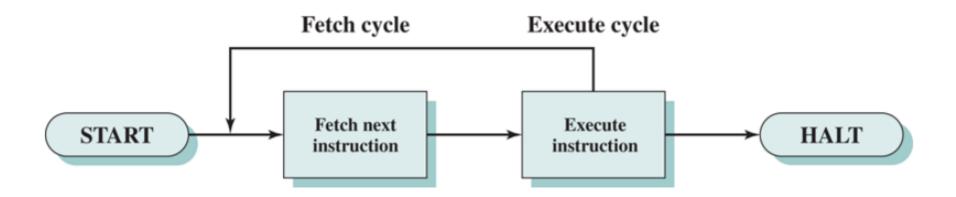
Control Signals (Internal)

- The control unit might generate also "internal signals" within the CPU.
 - These signals will be connected to the ALU and registers.
 - Example: Instruction Code (Operation Code)
 - An *n*-bit word
 - Tells the ALU and control unit which instruction to perform
 - This code is extracted from the instruction during the decode process.



Basic Instruction Cycle

- Two steps:
 - Fetch
 - Execute





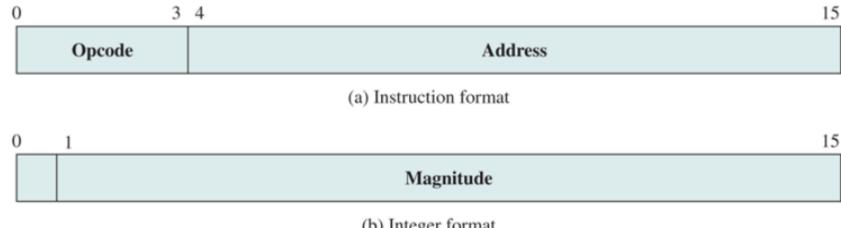
Fetch Cycle

- Program Counter (PC) holds address of next instruction to fetch
- Processor fetches instruction from memory location pointed to by PC
- Increment PC
 - Unless told otherwise
- Fetched instruction is loaded into Instruction Register (IR)
- Processor interprets instruction and performs required actions





A Hypothetical Example



(b) Integer format

Program counter (PC) = Address of instruction Instruction register (IR) = Instruction being executed Accumulator (AC) = Temporary storage

(c) Internal CPU registers

0001 = Load AC from memory 0010 =Store AC to memory 0101 = Add to AC from memory

(d) Partial list of opcodes



Execute Cycle

- Processor-memory
 - Data transfer between CPU and main memory
- Processor I/O
 - Data transfer between CPU and I/O module
- Data processing
 - Some arithmetic or logical operation on data
- Control
 - Alteration of sequence of operations
 - e.g. JUMP instruction



Data Flow (1)

- When the control unit fetches the next instruction:
 - ADDR* <= PC
 - IR <= data from memory
 - Control signals: $\overline{IOM} = 1$, $\overline{RW} = 0$, OE = 1
- When an instruction needs to perform a branch operation:
 - PC <= instruction address (instruction operand)
 - Control signals: $\overline{IOM} = x$, $\overline{RW} = x$, OE = x
- When an instruction needs to perform a register-register operation:
 - REG1 <= REG2 (Example: ACC <= MBR)
 - Control signals: $\overline{IOM} = x$, $\overline{RW} = x$, OE = x



Data Flow (2)

- When an instruction reads data from data memory:
 - MAR <= memory address
 - BUS* <= data from memory
 - Control signals: $\overline{IOM} = 1$, $\overline{RW} = 0$, OE = 1
- When an instruction writes data to data memory:
 - MAR <= memory address
 - Data memory [address] <= BUS*
 - Control signals: $\overline{IOM} = 1$, $\overline{RW} = 1$, OE = 0



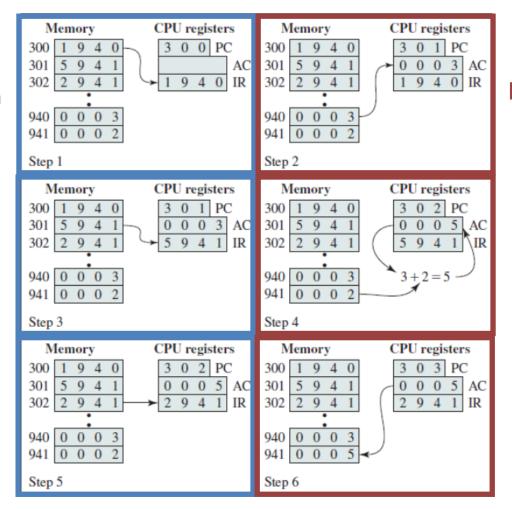
Data Flow (3)

- When an instruction reads data from I/O memory:
 - IOAR <= memory address
 - BUS* <= data from memory
 - Control signals: $\overline{IOM} = 0$, $\overline{RW} = 0$, OE = 1
- When an instruction writes data to I/O memory:
 - IOAR <= memory address
 - I/O memory [address] <= BUS*
 - Control signals: $\overline{IOM} = 0$, $\overline{RW} = 1$, OE = 0



Example of Program Execution

Fetch



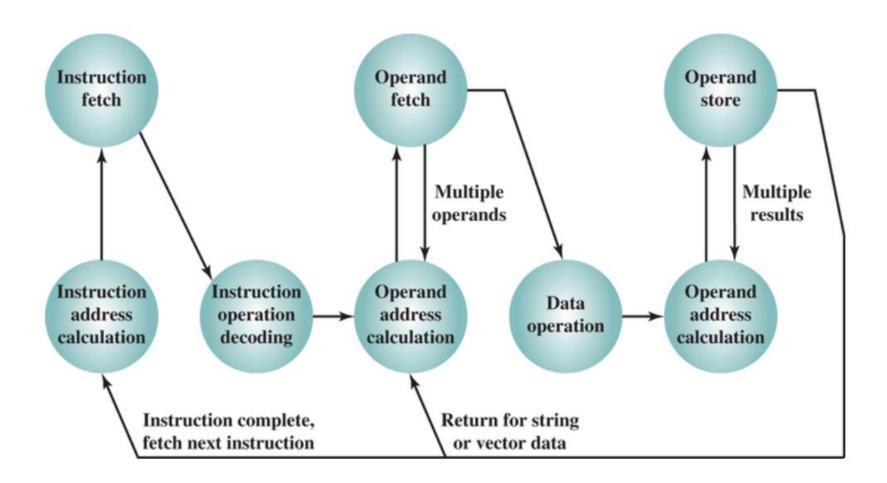
Decode-Execute

PC++

0001 = Load AC from memory 0010 = Store AC to memory 0101 = Add to AC from memory



Instruction Cycle - State Diagram





Interrupts

- Mechanism by which other modules (e.g. I/O) may interrupt normal sequence of processing
- Provided to improve processing efficiency

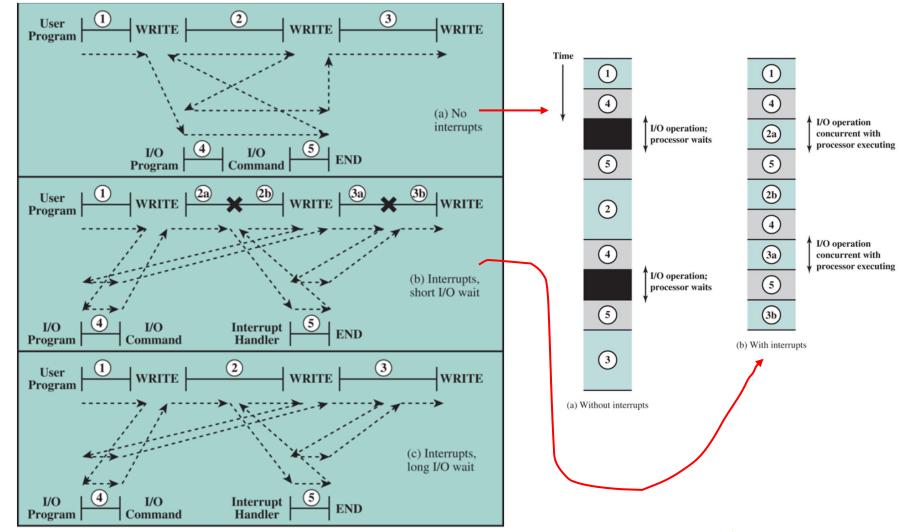


Classes of Interrupts

- Program
 - Result of an instruction execution (e.g. overflow, division by zero)
- Timer
 - Generated by internal processor timer
 - Used in pre-emptive multi-tasking
- I/O
 - From an I/O controller (e.g. signal completion of operation, request service, signal error conditions)
- Hardware failure
 - e.g. memory parity error, power failure

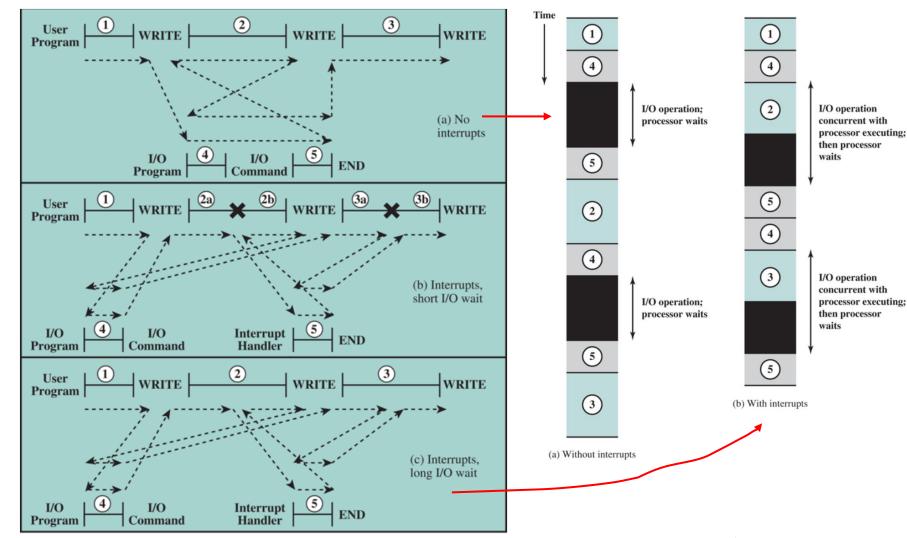


Program Flow Control (1)





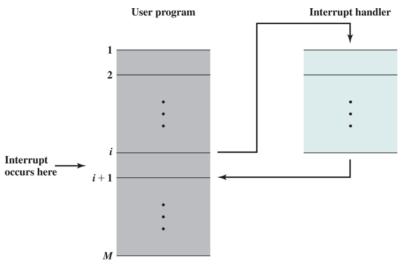
Program Flow Control (2)





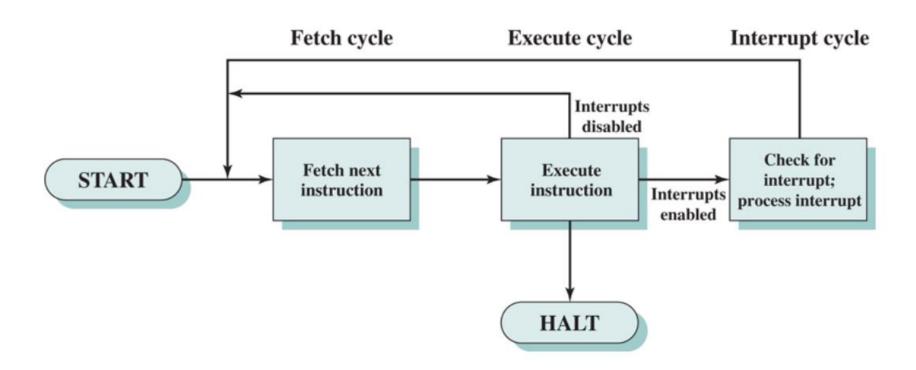
Interrupt Cycle

- Added to instruction cycle
- Processor checks for interrupt
 - Indicated by an interrupt signal
- If no interrupt, fetch next instruction
- If interrupt pending:
 - Suspend execution of current program
 - Save context
 - Set PC to start address of interrupt handler routine
 - Process interrupt
 - Restore context and continue interrupted program





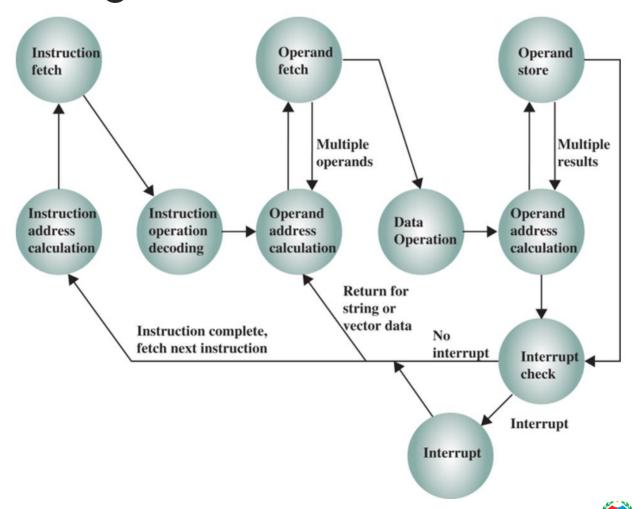
Instruction Cycle with Interrupts







Instruction Cycle with Interrupts - State Diagram



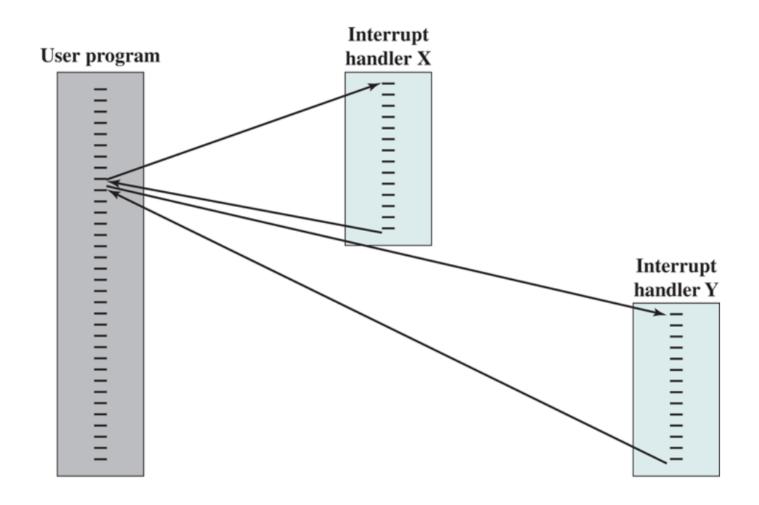
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Multiple Interrupts

- Disable interrupts
 - Processor will ignore further interrupts while processing one interrupt
 - Interrupts remain pending and are checked after first interrupt has been processed
 - Interrupts handled in sequence as they occur



Multiple Interrupts - Sequential





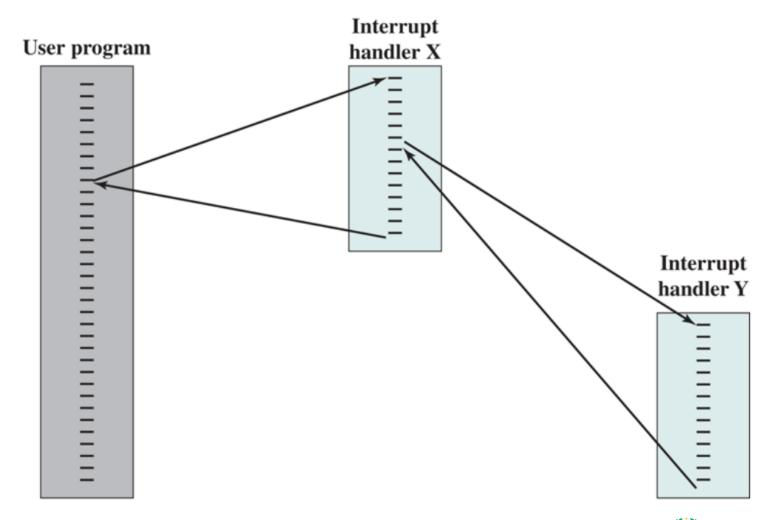
Multiple Interrupts

- Define priorities
 - Low priority interrupts can be interrupted by higher priority interrupts
 - When higher priority interrupt has been processed, processor returns to previous interrupt



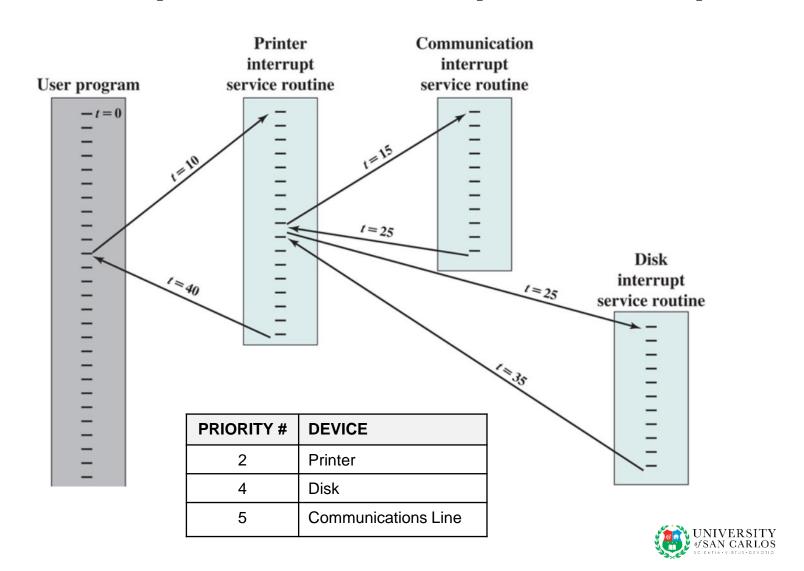


Multiple Interrupts - Nested





Time Sequence of Multiple Interrupts



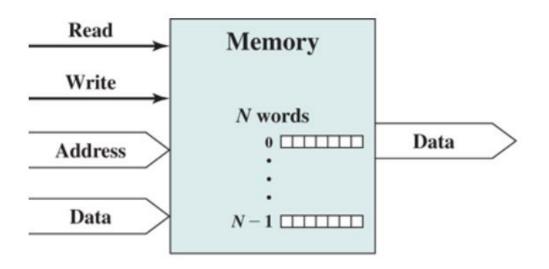
Interconnection Structure

- All the units must be connected
- Different type of connection for different type of unit
 - Memory
 - Input/Output
 - CPU



Memory Connection

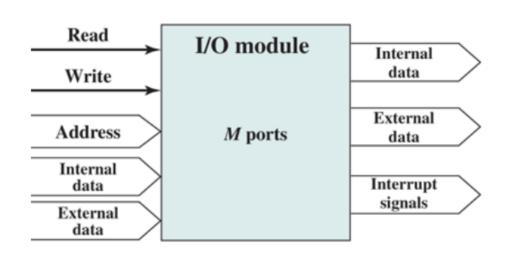
- Receives and sends data
- Receives addresses (of locations)
- Receives control signals
 - Read
 - Write
 - Timing





Input/Output Connection (1)

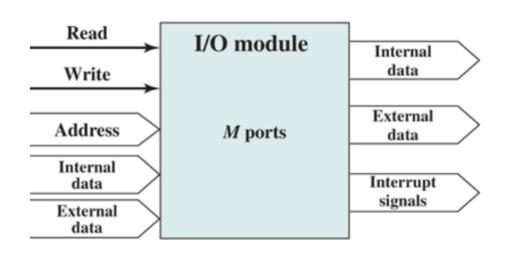
- Similar to memory from computer's viewpoint
- Output
 - Receive data from computer
 - Send data to peripheral
- Input
 - Receive data from peripheral
 - Send data to computer





Input/Output Connection (2)

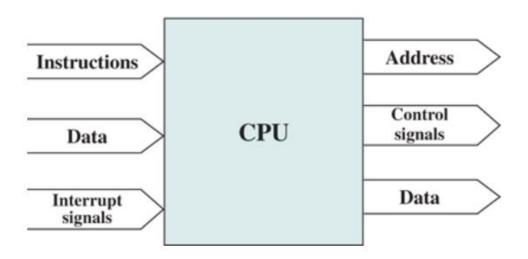
- Receive control signals from computer
- Send control signals to peripherals
 - e.g. spin disk
- Receive addresses from computer
 - e.g. port number
 to identify peripheral
- Send interrupt signals





CPU Connection

- Reads instruction and data
- Writes out data (after processing)
- Sends control signals to other units
- Receives (& acts on) interrupts







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End of Lecture

Note: The lecture slide was based on the accompanying lecture material from the Computer Organization and Architecture textbook by William Stallings. Some contents are contributed by Van B. Patiluna (USC). All contents contributed are copyright to the respective authors. For instructional use only. **Do not distribute.**

References:

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