

ROS and ROS 2 packages for accelerated deep learning nodes

- https://github.com/dusty-nv/ros_deep_learning
- This repo contains deep learning inference nodes and camera/video streaming nodes for ROS and ROS 2 with support for Jetson Nano, TX1, TX2, Xavier NX, NVIDIA AGX Xavier, and TensorRT.

This repository provides firmware artifacts for the NVIDIA Jetson Nano board meant to accelerate ROS 2 robotic applications.

- https://github.com/ros-acceleration/acceleration_firmware_jetson_nano
- The following is the whole source code:
 - o <https://drive.google.com/file/d/1Ry9qgRqOGp0FLywqutEhItI-i82lZfs/view?usp=sharing>