Parallel Programmability and the Cowichan Problems

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The Parallel Problem

- Parallel hardware is becoming ubiquitous faster than developers are learning how to use it effectively.
 - as a result, hundreds of parallel programming systems for various systems and programming languages have cropped up—with various degrees of polish, usefulness, and success
- Wilson [94] developed a set of "toy" problems to implement using various parallel systems to assess their degrees of programmability, dubbed the "Cowichan problems".
- We have implemented an updated version of the Cowichan problem set using two state-of-the-art parallel systems in order to assess ease of implementation and overall usefulness
- We define programmability a qualitative metric encompassing effort on the part of the application developer—how difficult it is to get ideas "onto paper" with the parallel system (intuitiveness).

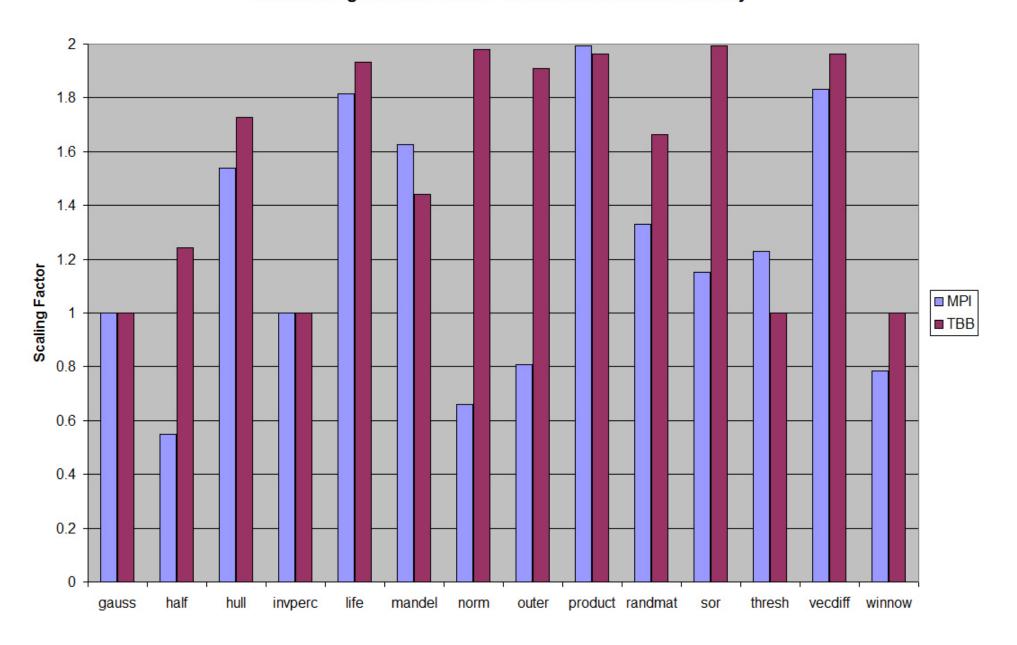
Message Passing Interface

- Message Passing Interface (MPI) is a specification for an API that allows many computers to communicate with one another.
- Boost.MPI is a library for message passing in highperformance parallel applications.
- Boost MPI is not a completely new parallel programming library. Rather, it is a C++-friendly interface to the standard Message Passing Interface, the most popular library interface for high-performance, distributed computing.
- MPICH is an MPI implementation that efficiently supports various computation and communication platforms.
- There are other implementations of MPI, but we used MPICH since it is platform independent (in particular, it runs on windows)

Threading Building Blocks

- TBB is a high-level parallelism library developed by Intel for C++ developers, incorporating many basic threading ideas not covered by system call interfaces
 - It also contains primitives and classes that implement a form of the data-parallel paradigm; refer to this as TBB/DP
- The data-parallel paradigm (DP) expresses work-sharing by doing exactly the same thing to (potentially) large collections of data
 - Worker sub-processes cannot communicate
 - Programmer defines the data domain (where), and the operation to do with that data (what)
 - **Key Insight:** TBB decides the *how* (i.e. splitting up the range onto different workers)

Best Scaling with 2 Threads/Processes and 4GB of Memory



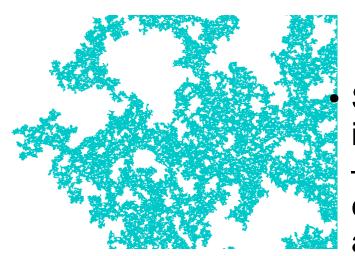
Performance Analysis

- Problems that are hard to parallelize in both: gauss, invperc, winnow
- Problems that perform better with MPI: mandel (due to use of task farm), thresh, product
- Problems that perform better with TBB: half, hull, life, norm, outer, randmat, sor, vecdiff
- Generally, TBB performs better because of the low cost of communicating the result—MPI communication is done between nodes that do not share any memory, while TBB uses threads and does use shared memory.

- Developers looking to effectively utilize parallel hardware aren't always starting at square one. The opposite is probably true, in fact—an existing serial codebase is being "parallelized".
- The natural question that arises from these developers is a simple one: "can my code be made

parallel, or am I wasting my time?"

 The Invasion Percolation problem from the Cowichan problem can be solved in parallel, but the serial implementation is <u>orders of magnitude</u> faster. This is because every step of Some programming problems are impossible to effectively parallelize.



evaluation depends on the results of the previous step.

Some programming problems are impossible to effectively parallelize, and —more broadly—some problems cannot be phrased in the "language" of a specific parallel system.

MPI: Practical Uses

- Running on supercomputers or clusters
- Algorithms should be restricted to those that have very good parallelization potential, due to slow communication speed
- Boost::MPI is good choice for algorithms that work on enormous datasets that cannot necessarily fit in the memory of a single node
- The best-case scenario for parallel speed-up was with the matrix vector product cowichan problem.
- We used 8 machines (on CDF), with 1 process per machine.
- The resulting speed-up was 6.4, that is, the MPI implementation was able to solve the problem at 640% of the speed of the serial version.

MPI: Point-by-Point

ADVANTAGES

- Full support for both primitive and user-defined data types
- Built-in operations on arrays, vectors, strings
- Boost.Serialization facilitates transfer of arbitrary data between nodes
- Allows heterogeneous operations on aggregates
- Support for process groups
- Synchronization is hidden from the user
- Boost::MPI and MPICH are both very well-maintained and platform independent

DISADVANTAGES

- Very invasive code modification or restructuring required for existing applications, as MPI must be used everywhere
- Slow startup/shutdown when using a lot of nodes
- Performance limited by communication since memory is not shared between nodes
- Precisely the same executable must be used on every node.
- Memory usage can be a problem when running multiple nodes on the same computer
- Generally, requires large datasets to show performance benefits

TBB/DP: Point-by-Point

ADVANTAGES

- Simple set-up and non-invasive code modification needs for existing applications (very drop-in friendly)
- Conceptually simple—a low learning curve contributes to a good level of programmability
- Shared memory architecture is familiar to application developers
- Well-maintained by a large company, and cross-platform
- Work is split automatically; write for n processors rather than a specific #
- Good parallel speed-up, even for small datasets
- Implements work-stealing

DISADVANTAGES

- Expressing problems as dataparallel problems (identical subtasks) can be the most challenging part, and some problems do not translate well to this paradigm
- Work can only be split up locally; there is no cluster or network capability
- Work can only be split into new threads; therefore, as of now, there is no support for GPU programming

Code Examples

```
int lo, hi;
               /* work controls */
               /* loop indices */
int r, c;
int rank;
// work
if (get block rows mpi (world, 0, nr, &lo, &hi))
  for (r = lo; r < hi; r ++) {
   result[r] = matrix[r * nc] * vector[0];
    for (c = 1; c < nc; c++) {
      result[r] += matrix[r*nc + c] * vector[c];
  }
}
// broadcast result
for (rank = 0; rank < world.size (); rank++){</pre>
  if (get block rows mpi
      (world, 0, nr, &lo, &hi, rank)) {
    broadcast (world, &result[lo], hi-lo, rank);
}
```

MATRIX-VECTOR PRODUCT

Implementation of product using Boost::MPI

```
// use TBB to iterate over the given range
parallel for(
    blocked range2d<size t,size t>
    (0, BOARD SIZE, 0, BOARD SIZE),
    myGame, auto partitioner());
void Game::operator()(const
blocked range2d<size t,size t>& range)
const {
  // calculate this section of the game
  for (y in range.rows()) {
    for (x in range.cols()) {
      int peers = sumNeighbours(x, y);
      if (peers<2 | peers>3)
        (*second)[y][x] = 0;
      elif (peers == 3)
        (*second)[y][x] = 1;
      else
        (*second)[y][x] = (*first)[y][x];
  }
```

GAME OF LIFE

Implementation of <u>life</u> using TBB/DP

Conclusions

- MPI, while being an extremely powerful platform, has a prohibitively large number of disadvantages that make it a poor choice for the wider audience of application developers.
- TBB and data parallelism is relatively simple to program, but lacks the ability to distribute work over a network or cluster. It is, however, a good choice if work will remain on the same computer.
- A novel library with a high degree of programmability that combines local and distributed parallel processing approaches would fill the gap.
 - an application could simply use both TBB and MPI for the same purpose—but this "solution" has a very <u>low</u> degree of programmability due to its complexity and the extreme amount of effort required by the application developer.