Joint To Be Rotated (y-axis)	Rotation Parameters					
	Set 1			Set 2		
	Φ_a	Φ_b	Φ_c	Φ_a	Φ_b	Φ_c
PMCP	PPIP	PMCP	RMCP	*None*		
RMCP	RPIP	RMCP	PMCP	RPIP	RMCP	MMCP
MMCP	MPIP	MMCP	RMCP	MPIP	MMCP	IMCP
IMCP	IPIP	IMCP	MMCP	*None*		
TMCP	TPIP	TMCP	IMCP	*None*		