

Joint To Be Rotated ( $x$ -axis)	Rotation Parameters		
	$\Phi_a$	$\Phi_b$	$\Phi_c$
TMCP	WRIST	TMCP	TPIP
IMCP	WRIST	IMCP	IPIP
MMCP	WRIST	MMCP	MPIP
RMCP	WRIST	RMCP	RPIP
PMCP	WRIST	PMCP	PPIP
TPIP	TMCP	TPIP	TDIP
IPIP	IMCP	IPIP	IDIP
MPIP	MMCP	MPIP	MDIP
RPIP	RMCP	RPIP	RDIP
PPIP	PMCP	PPIP	PDIP
TDIP	TPIP	TDIP	TTIP
IDIP	IPIP	IDIP	ITIP
MDIP	MPIP	MDIP	MTIP
RDIP	RPIP	RDIP	RTIP
PDIP	PPIP	PDIP	PTIP