# Volume estimation via integrating on a curve fitted point cloud

HiPEDS 2018 Cohort: G. Bisbas, L. Castiglione, D. Grumberg, S. Karolčík, L. Keeble, D. Kulon, B. Kwan, C. McMeel, R. Miles, J. Ortiz, N. Perez-Nieves, V. Pham Ngoc, J. Vandebon, D. Vink

Imperial College London add logos

October 26, 2018



#### Overall structure

#### **HiPEDS Group workflow**

- Cohort meetings on a regular basis
- Identify our goals and split into subgroups
- Integrate our progress
- Redefine goals

#### Point cloud integration team overall checkpoints

- Capture images
- Extract point cloud
- Fit a curve
- Find the volume inside

More details in the next slides...



# The problem and the goal



Figure: Royal vans

- ullet Problem: Packaging in vans is not optimal o lots of empty space
- Goal: Fast estimation of available volume to ensure optimal packaging

## The hardware

- •
- •

### Extracting the point cloud

- •
- •
- 0

## Denoising the point cloud

# The ICP algorithm

### Curve fitting with Linear Interpolation

#### Integration

$$\iiint_V f(x, y, z) \, dx \, dy \, dz \tag{1}$$

#### Results

#### References

## Acknowledgements

This project was proposed and supported by Royal Mail, EPSRC and Imperial College London. A special thanks to Jeremy Bradley and Ben Glocker for their support and advice throughout.