

1. ARMA (1,2)

$$(1 - \phi B) X_t = (1 - \theta_1 B - \theta_2 B^2) Z_t$$

$$Y_0 = E[X_1^2] = E[X_1 [(1 - \theta_1 B - \theta_2 B^2) Z_t + \phi X_{t-1}]]$$

$$= \phi Y_1 + \underbrace{E[X_1 Z_t]}_{\sigma_z^2} - \theta_1 E[X_1 Z_{t-1}] - \theta_2 E[X_1 Z_{t-2}]$$

$$= \phi Y_1 + \sigma_z^2 (1 - \theta_1 (\phi - \theta_1) - \theta_2 (-\theta_2 + \phi^2 - \phi \theta_1))$$

$$Y_1 = E[X_1 X_{t-1}] = E[X_{t-1} [(1 - \theta_1 B - \theta_2 B^2) Z_t + \phi X_{t-1}]]$$

$$= \phi Y_0 + \underbrace{E[Z_t X_{t-1}]}_0 + \theta_1 \underbrace{E[Z_{t-1} X_{t-1}]}_{\sigma_z^2}$$

$$= \phi Y_0 + \theta_1 \sigma_z^2 (\theta_1 + \theta_2 (\phi - \theta_1))$$

$$Y_k = E[X_t X_{t-k}] = E[X_{t-k} [(1 - \theta_1 B - \theta_2 B^2) Z_t + \phi X_{t-1}]]$$

$$= \phi Y_{k-1} + 0$$

$$E[X_t Z_{t-1}] = E[E[X_t | X_{t-1}, Z_{t-2}]]$$

$$= E[Z_{t-1} [(-\theta_1 B - \theta_2 B^2) Z_t + \phi X_{t-1}]]$$

$$= \sigma_z^2 (\phi - \theta_1)$$

$$E[X_t Z_{t-2}] = E[Z_{t-2} [-\theta_2 B^2 Z_t + \phi X_{t-1}]]$$

$$= \sigma_z^2 (-\theta_2) + \phi E[X_t Z_{t-1}]$$

$$= \sigma_z^2 (-\theta_2 + \phi^2 - \phi \theta_1)$$

2,

a_j

I $0.9 < 1, 0.8 < 1 \Rightarrow$ invertible, stabilisierend

II $0.1 < 1, 0.8 < 1 \Rightarrow$ invertible, stabilisierend

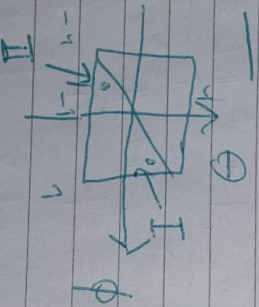
III $0.1 < 1 \Rightarrow$ stabilisierend

$$X_{1,2}: \text{roots of } -0.7x^2 + 0.2x + 1$$

$$X_1 = 1.3 > 1$$

$$|X_2| = 1.06 > 1$$

\Rightarrow invertible



b) I. $\rho = 1$

$$\rho_1 = 0.9^2 \frac{(1 + 0.9 \cdot 0.8)(0.9 + 0.8)}{1 - 2 \cdot 0.9 \cdot (-0.8) + 0.8^2} = \frac{731}{770} \approx 0.949$$

$$\rho_2 = 0.854 \quad \rho_3 = 0.769 \quad \rho_4 = 0.692 \quad \rho_5 = 0.622$$

II. $\rho = 1$

$$\rho_1 = (-0.4)^2 \frac{(1 - 0.1 \cdot 0.8)(-0.1 + 0.8)}{1 - 2 \cdot 0.1 \cdot 0.8 + 0.8^2} = 0.435$$

$$\rho_2 = -0.043 \quad \rho_3 = 4.85 \cdot 10^{-3} \quad \rho_4 = -4.35 \cdot 10^{-4} \quad \rho_5 = 4.35$$

III

$$X_1 + 0.1X_2 \quad \phi = -0.1$$

$$\theta_1 = -0.2 \quad \theta_2 = 0.7$$

$$a = 1 - 0.1 + 0.2 = 1.1$$

$$= 1 - 0.02 + 0.2^2 - 0.1^2 \cdot 0.7 + 0.02 \cdot 0.7 + 0.7^2$$

$$= 1.517$$

$$b = -0.2 \cdot 0.7 + 0.2 \cdot 0.1 + 0.1 \cdot 0.7 = 10.13$$

$$\rho_0 = 1 \quad \rho_1 = \frac{\phi_1 b + \phi_1^2 a - \phi_1^{-1} \theta_2 + \theta_2 \phi_1}{\phi_1 b + a} = -46.3$$

b) I

$$\phi_{11} = \rho_1 = 0.941$$

$$\phi_{12} = \frac{\rho_2 - \rho_1^2}{1 - \rho_1^2} = -0.4655$$

$$\phi_{33} = \frac{\begin{vmatrix} \rho_1 & \rho_2 & \rho_3 \\ \rho_2 & \rho_1 & \rho_3 \\ \rho_3 & \rho_3 & \rho_1 \end{vmatrix}}{\begin{vmatrix} \rho_1 & \rho_2 \\ \rho_2 & \rho_1 \end{vmatrix}} = \frac{\rho_1^2 \rho_3^2 + 2\rho_1 \rho_2 \rho_3}{1 + 2\rho_1^2 \rho_2 - \rho_2^2 - 2\rho_1^2} = 0.290$$

II

$$\phi_{11} = \rho_1 = 0.852$$

$$\phi_{22} = \frac{\rho_2 - \rho_1^2}{1 - \rho_1^2} = -0.187$$

$$\phi_{33} = \frac{\begin{vmatrix} \rho_1 & \rho_2 & \rho_3 \\ \rho_2 & \rho_1 & \rho_3 \\ \rho_3 & \rho_3 & \rho_1 \end{vmatrix}}{\begin{vmatrix} \rho_1 & \rho_2 \\ \rho_2 & \rho_1 \end{vmatrix}} = 0.109$$

not an autocorrelation

3.

$$\pi_t \cdot \phi(B) X_t = \Theta(B) Z_t$$

$$\frac{\phi(B)}{\Theta(B)} X_t = Z_t$$

$$\Rightarrow \pi(B) = \frac{\phi(B)}{\Theta(B)}$$

$$\Rightarrow \boxed{\pi(B) \Theta(B) = \phi(B)}$$

$$X_t = \frac{\Theta(B)}{\phi(B)} Z_t$$

$$\Rightarrow \boxed{\phi(B) \phi(B) = \Theta(B)}$$

I.

$$\pi(B) (1 + 0.8B) = (1 - 0.3B)$$

$$\begin{aligned} (1 - \pi_1 B) (1 + 0.8B) &= 1 - 0.3B \\ 1 + (0.8 - \pi_1) B - \pi_1 0.8 B^2 &= 1 - 0.3B \end{aligned}$$

$$(\pi_0 + \pi_1 B + \pi_2 B^2 + \pi_3 B^3 + \dots) (1 + 0.8B) = \dots$$

$$\pi_0 (1 + 0.8B) + \pi_1 B (1 + 0.8B) + \pi_2 B^2 (1 + 0.8B) + \dots = 1 - 0.3B$$

$$\pi_0 + (0.8\pi_0 + \pi_1) B + (0.8\pi_1 + \pi_2) B^2 + (0.8\pi_2 + \pi_3) B^3 + \dots = 1 - 0.3B$$

$$\Rightarrow \pi_0 = 1$$

$$- \pi_n + \pi_{n-1} \cdot 0.8 = 0 \text{ for } n > 1$$

$$- \pi_1 + 0.8 = -0.3$$

$$\Rightarrow \pi_1 = 1.1, \pi_n = -\pi_{n-1} \cdot 0.8 \text{ for } n > 1$$

4.

$$(1 - 0.4B) \nabla Z_t = (1 + 0.5B - 0.44B^2) a_t$$

2) Z_t :

$$(1 - 0.4B) (1 - B) Z_t = 1 + 0.5B - 0.44B^2 a_t$$

$$(1 - B - 0.4B + 0.4B^2) Z_t = \dots$$

$$(1 - 1.4B + 0.4B^2) Z_t = \dots$$

Invertible:

• roots of X_1, X_2 of $-0.44x^2 + 0.5x + 1$

$$|X_1| = 5^{1/2}, |X_2| = 4.4 \dots > 1$$

process invertible ✓

Stationary:

roots X_1, X_2 of $0.4x^2 - 1.4x + 1$

$$X_1 = \frac{5}{2} > 1, X_2 = 1 \neq 1$$

process is not stationary

b) $\nabla^2 Z_1$ from a, we conclude invertibility

$$(1-0.4B) \frac{24}{4}$$

$$1-0.4x = 0$$

$$x = \frac{1}{0.4} > 0 \Rightarrow \text{stationarity}$$

c) $\nabla^2 Z_1$:

$$\nabla (1-0.4B) \nabla^2 Z_1 = \nabla (1+0.5B-0.44B^2) a_1$$

$$(1-0.4B) \nabla^2 Z_1 = (1+0.5B-0.44B^2-B-0.5B^2+0.44B^3) a_1$$

From b we conclude stationarity.

Invertibility:

Let x_1, x_2, x_3 be roots of: $0.44x^3 - 0.64x^2 - 0.5x + 1$

$$x_1 = 1 > 1,$$

$$x_2 = -1$$

$$x_3 = -\frac{10}{2}$$

\Rightarrow non invertible

$$d) \quad \frac{1}{2} \nabla (1+B) z_1 = \frac{1}{2} \nabla z_1 + \frac{1}{2} \nabla z_{1-1}$$

$$\frac{1}{2} (1+B) (1-0.4B) \nabla z_1 = \frac{1}{2} (1+B) (1+0.5B - 0.44B^2) a_1$$

b)

$$(1-0.44B) \left(\frac{1}{2} \nabla z_1 + \frac{1}{2} \nabla z_{1-1} \right) = \frac{1}{2} (1+(0.5+1)B + (-0.44+0.5)B^2 - 0.44B^3) a_1$$

• z_1 is stationary since $|-0.4| < 1$

• let x_1, x_2, x_3 be roots of $\frac{1}{2} (-0.44x^3 + 0.36x^2 + 1.5x + 1)$

$$x_1 = \bar{5}, \quad x_2 = -1, \quad x_3 = -\frac{10}{7}$$

\Rightarrow non invertible