## ADLxMLDS HW4 GAN NETWORK

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## Model description(2%)

GAN 的模型參考此篇 github: <a href="https://github.com/pavitrakumar78/Anime-Face-GAN-Keras">https://github.com/pavitrakumar78/Anime-Face-GAN-Keras</a> 由於期末沒有很多時間調 hyperparameter · 因此我嘗試先以此篇的模型為基礎並針對此次作業做修改(如改成 ACGAN)。下圖是我的 generator 的部分。我的生成器有三個 input · 分別是 100 維的 noise 、 hair label 與 eyes label。後兩個 input 分別 embedding 成 5 維的矩陣後 concatenate 在 noise 後面。接著開始做 Conv2DTranspose · 從(1,1,512) -> (4,4,256) -> (8,8,128) -> (16,16,64) -> (32,32,64) -> (64,64,3)。最後根據根據 Paper 中的方法採用 tanh activation。Optimizers 的設定則根據助教的 PPT。

```
gen_input = Input(shape = noise_shape) #if want to directly use with conv layer next
hair_input = Input(shape = (1,)) |
hair = Embedding(hair_len, 5)(hair_input)
hair_reshape = Reshape((1,1,5), input_shape=(1,5))(hair)
eyes_input = Input(shape = (1,)) |
eyes = Embedding(eyes_len, 5)(eyes_input)
eyes_reshape = Reshape((1,1,5), input_shape=(1,5))(eyes) |
_______concat = concatenate([gen_input, hair_reshape, eyes_reshape])
generator = Conv2DTranspose(filters = 512, kernel_size = (
generator = BatchNormalization(momentum = 0.5)(generator)
                                                                                  = (4,4), strides = (1,1), padding = "valid", kernel_initializer = kernel_init)(concat)
generator = BatchNormalization(momento
generator = LeakyReLU(0.2)(generator)
generator = Conv2DTranspose(filters = 256, kernel_size = (4,4), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(generator) generator = BatchNormalization(momentum = 0.5)(generator)
               = BatchNormalization(moment
= LeakyReLU(0.2)(generator)
generator
generator = Conv2DTranspose(filters = 128, kernel_size = (4,4), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(generator)
generator = BatchNormalization(momentum = 0.5)(generator)
generator = LeakyReLU(0.2)(generator)
                                                           , kernel_size = (4,4), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(generator) = 0.5)(generator)
generator = Conv2DTranspose(filters = 64, kernel_size
generator = BatchNormalization(momentum = 0.5)(generation)
                 LeakyReLU(0.2)(generator)
generator = Conv2DTranspose(filters = 64, kernel_size = (3,3), strides = (1,1), padding = "same", kernel_initializer = kernel_init)(generator)
generator = BatchNormalization(momentum = 0.5)(generator)
generator = LeakyReLU(0.2)(generator)
generator = Conv2DTranspose(filters = 3, kernel_size = (4,4), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(generator)
generator = Activation('tanh')(generator)
generator
gen_opt = Adam(lr=0.0002, beta_1=0.5)
generator_model = Model(input = [gen_input, hair_input, eyes_input], output = generator)
generator_model = Model(input = [gen_input, hair_input, eyes_input], output = generator)
generator_model.compile(loss='binary_crossentropy', opti
```

Discriminator 的模型則是傳統的 CNN,但採用跟 Paper 一樣的做法不使用 maxpooling(2,2)

而是設定 stride = (2,2)。ACGAN 除了判斷照片是否為 fake 之外還需要能 predict 出正確的 class label,因此 Discriminator 的 output 有三個,分別使用 sigmoid(判斷照片真偽), softmax(判斷 hair label)與 softmax(判斷 eyes label) activation。Optimizers 的設定則與 generator 相同。

```
kernel_init = 'glorot_uniform'
dis_input = Input(shape = image_shape)
discriminator = Conv2D(filters = 64, kernel_size = (3,3), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(dis_input) | discriminator = LeakyReLU(0.2)(discriminator)
discriminator = Conv2D(filters = 128, kernel_size = (3,3), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(discriminator) discriminator = BatchNormalization(momentum = 0.5)(discriminator) discriminator = LeakyReLU(0.2)(discriminator)
discriminator = Conv2D(filters = 256, kernel_size = (3,3), strides
discriminator = BatchNormalization(momentum = 0.5)(discriminator)
discriminator = LeakyReLU(0.2)(discriminator)
                                                                                                                                                                                                                            (2,2), padding =
discriminator = Conv2D(filters = 512, kernel_size = (3,3), strides = discriminator = BatchNormalization(momentum = 0.5)(discriminator)
                                                                                                                                                                                                                            (2,2), <u>padding</u> = "same", <u>kernel_initializer</u> = kernel_init)(discriminator)
discriminator = LeakyReLU(0.2)(discriminator)
discriminator = Conv2D(filters = 1024, kernel_size = (3,3), strides = (2,2), padding = "same", kernel_initializer = kernel_init)(discriminator) | discriminator = BatchNormalization(momentum = 0.5)(discriminator) | discriminator = LeakyReLU(0.2)(discriminator)
discriminator = Flatten()(discriminator)
img = Dense(1)(discriminator)
img = Activation('sigmoid')(img)
hair_output = Dense(hair_len)(discriminator)
hair_output = Activation('softmax')(hair_output)
⊐
eyes_output = Dense(eyes_len)(discriminator)
eyes_output = Activation('softmax')(eyes_output)
dis_opt = Adam(lr=0.0002, beta_1=0.5)
discriminator_model = Model(input = dis_input, output = [img, hair_output, eyes_output])
discriminator_model.compile(loss=['binary_crossentropy', 'categorical_crossentropy', 'categori
'categorical_crossentropy'],_
```

ACGAN 的 objextive function 與作業 slide 上的相同,分為 Ls 與 Lc 兩個部分,分別是 Source 的 Log Likelihood 與 Class 的 Log Likelihood。Discriminator 會嘗試最大化 Ls+Lc、Generator 則是最小化 Lc-Ls。

$$L_S = E[\log P(S = real \mid X_{real})] + E[\log P(S = fake \mid X_{fake})]$$

$$L_C = E[\log P(C = c \mid X_{real})] + E[\log P(C = c \mid X_{fake})]$$

How do you improve your performance (2%)

- 1. Feature Embedding: 原本採用 one-hot 的方式將 hair 與 eyes 直接 concat 在 noise 後面,後來參考幾篇 github 後決定採用 embedding。Embedding 的好處是相近的顏色應該會 embedding 成相近的 vector,而不是完全正交的兩個 one-hot vector。
- 2. Smooth Label: 參考此篇 <a href="https://github.com/soumith/ganhacks">https://github.com/soumith/ganhacks</a>,GAN 之所以不太穩定有可能是一位 gererate 出來的 distribution 其實很怪,或是甚至與真實 data 的 distribution沒有重疊,因此做 label smoothing 可以使 network 不要 predict 出很極端的值。
- 3. Normalize 照片至[1,-1]區間:按照 paper 的方法,generator 的 output 應該採用 tanh activation,因此應該將照片 map 到[1, -1]區間。

## Experiment settings and observation (2%)

我將 learning curve 繪製成下圖。可以發現 Discriminator 前期針對真實照片的分辨能力較高,而對於假的照片要到約 900 個 step 以後才顯著下降。我自己認為合理的 gan 模型中,discriminator應該要稍微比 generator 強一點,才可以發揮類似老師的作用,引導 generator 生出更接近真實的照片,從圖中可以看見 generator 的 loss 永遠都是比 discriminator 高的,也代表每一個 step 由於 discriminator 都會進步一些,generator 訓練後即使變強了,也沒辦法騙過 discriminator,loss 才會維持再 1-2 區間,甚至有小幅上升的趨勢。本次作業我認為最困難的部分是 generator 與 discriminator 強度的調整,要使他們保持平衡不太容易,網路上有多篇的 github 也提到 gan 模型對參數非常敏感,可能多疊個一層 CNN 就會讓整個訓練過程壞掉。未來有時間的話希望能夠嘗試實作 WGAN,並比較其與 ACGAN 之差異。

