



# **Solving Medium and Large Size Problems of the Literature by the Accelerated Hyperbolic Smoothing Clustering Method**

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# Outline of Presentation

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- 1 - Cluster Analysis
- 2 - Hyperbolic Smoothing Clustering Method (HSCM)
- 3 - The HSCM applied for Solving the Minimum Sum-of-Squares Clustering Problem
- 4 - Partition into Boundary and Gravitational Regions (PBGR)
- 5 - HSCM + PBGR Applied to General Clustering Problem
- 6 - HSCM + PBGR Applied to Minimum Sum-of-Squares Clustering Problem (MSSC)
- 7 – HSCM Applied to MSSC → Large Instances (Bagirov et al – December 2012)
- 8 - HSCM + PBGR Applied to MSSC → Very Large Instances (March 2013)
- 9 - HSCM + PBGR Applied to MSSC → Medium and Large Instances (April 2014)
- 10 - CONCLUSIONS



# Cluster Analysis

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In the Cluster Analysis scope, algorithms use traditionally two main strategies:

- **Hierarchical** clustering methods
- **Partition** clustering methods...
- Here we introduce a **New Approach** for solving the problem...



# Hyperbolic Smoothing Clustering Method - HSCM

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General Problem Formulation:

$S = \{S_1, \dots, S_m\}$     Set of  $m$  observations

$x_i$  ,  $i = 1, \dots, q$     Centroides of the clusters

$z_j = \min_{i=1, \dots, q} \|s_j - x_i\|$     Distance of the observation  $j$  to nearest centroide

Objective function specification

$$\text{Minimize } \sum_{j=1}^m f(z_j)$$

where  $f(z_j)$  is an arbitrary monotonic increasing function of the distance  $z_j$ .



# Hyperbolic Smoothing Clustering Method - HSCM

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General Problem Formulation:

$$\text{Minimize} \quad \sum_{j=1}^m f(z_j)$$

$$z_j = \min_{i=1,\dots,q} \|s_j - x_i\|, j = 1, \dots, m$$

Trivial Examples of monotonic increasing functions:

$$\sum_{j=1}^m f(z_j) = \sum_{j=1}^m z_j^2 \quad \sum_{j=1}^m f(z_j) = \sum_{j=1}^m z_j$$

Possible Distance Metrics:

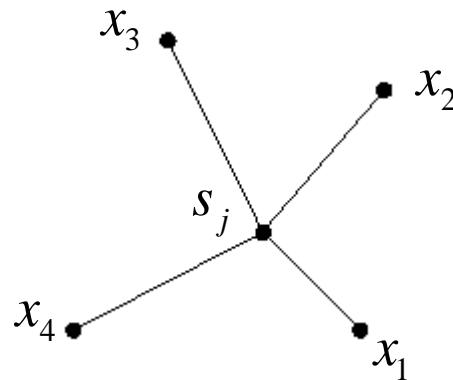
$L_2$  (Euclidean)     $L_1$  (Manhattan)     $L_\infty$  (Chebychev)     $L_p$  (Minkowski)



# HSCM: Resolution Methodology

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## The General Clustering Problem



Consider a general observation point  $s_j$ .

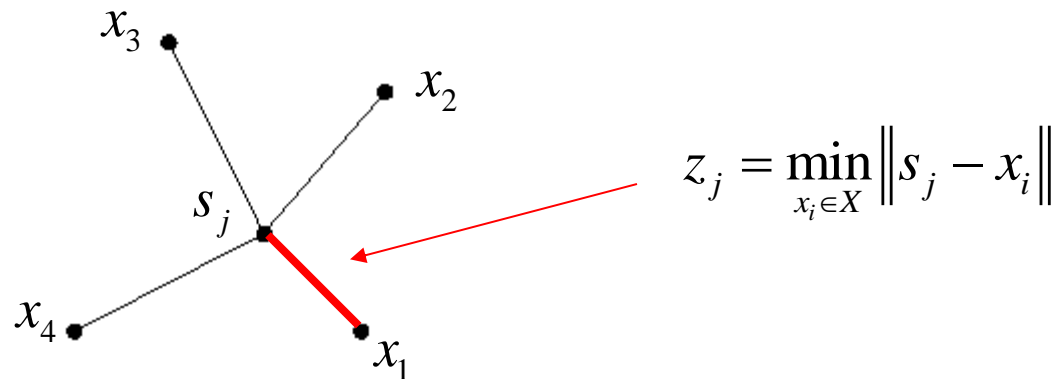
Let be  $x_i, i = 1, \dots, q$ , the centroids of clustersm where each set of these centroid coordinates will be represented by  $X \in \Re^{nq}$ .

# HSCM: Resolution Methodology

## The General Clustering Problem

Consider a general observation point

$s_j$



Let be  $x_i, i = 1, \dots, q$ , the centroids of clusters where each set of these centroid coordinates will be represented by  $s_j$

$$X \in \mathfrak{R}^{nq}$$

This procedure is strongly non differentiable.



# HSCM: Resolution Methodology

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## Problem transformation

The general clustering problem is equivalent to the following problem:

$$\begin{aligned} \text{(P1) Minimize} \quad & \sum_{j=1}^m f(z_j) \\ \text{Subject to:} \quad & z_j = \min_{i=1,\dots,q} \|s_j - x_i\|, \quad j = 1, \dots, m. \end{aligned}$$






# HSCM: Resolution Methodology

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## Problem transformation

From the problem (P1), it is obtained the relaxed problem:

$$\begin{aligned} \text{(P2) Minimize} \quad & \sum_{j=1}^m f(z_j) \\ \text{Subject to:} \quad & z_j - \|s_j - x_i\| \leq 0, \quad j = 1, \dots, m, \quad i = 1, \dots, q. \end{aligned}$$




# HSCM: Resolution Methodology

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## Problem transformation

Let us use the auxiliary function

$$\psi(y) = \max\{0, y\}$$

From the inequalities

$$z_j - \|s_j - x_i\| \leq 0, \quad j = 1, \dots, m, \quad i = 1, \dots, q,$$

it follows:

$$\sum_{i=1}^q \Psi(z_j - \|s_j - x_i\|) = 0, \quad j = 1, \dots, m$$



# HSCM: Resolution Methodology

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## Problem transformation

Using this set of equality constraints in place of the constraints in (P2), we obtain the following problem

$$(P3) \quad \text{Minimize} \quad \sum_{j=1}^m f(z_j)$$
$$\text{Subject to : } \sum_{i=1}^q \Psi\left(z_j - \|s_j - x_i\|\right) \stackrel{\downarrow}{=} 0, \quad j = 1, \dots, m$$

This problem corresponds also to a relaxation!!



# HSCM: Resolution Methodology

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## Problem transformation

By performing a  $\varepsilon$  perturbation, it is obtained the problem:

$$(P4) \quad \text{Minimize} \quad \sum_{j=1}^m f(z_j)$$
$$\text{Subject to : } \sum_{i=1}^q \Psi\left(z_j - \|s_j - x_i\|\right) \geq \varepsilon, \quad j = 1, \dots, m$$



# HSCM: Resolution Methodology

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## Smoothing the problem

Let us define the auxiliary function

$$\phi(y, \tau) = (y + \sqrt{y^2 + \tau^2}) / 2$$

for  $y \in \mathbb{R}$  and  $\tau > 0$  .



# HSCM: Resolution Methodology

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## Smoothing the problem

Function  $\phi$  has the following properties:

(a)  $\phi(y, \tau) > \Psi(y), \forall \tau > 0$

(b)  $\lim_{\tau \rightarrow 0} \phi(y, \tau) = \Psi(y)$

(c)  $\phi(y, \tau)$  is an increasing convex  $C^\infty$  function.



# HSCM: Resolution Methodology

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## Smoothing the problem

By using the Hyperbolic Smoothing approach for the problem (P4) it is obtained

$$\begin{aligned} \text{(P5) Minimize} \quad & \sum_{j=1}^m f(z_j) \\ \text{Subject to:} \quad & \sum_{i=1}^q \phi(z_j - \|s_j - x_i\|, \tau) \geq \varepsilon, \quad j = 1, \dots, m. \end{aligned}$$



# HSCM: Resolution Methodology

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## Smoothing the distance calculation

For the Euclidian metric, let us define the auxiliary function

$$\theta(s_j, x_i, \gamma) = \sqrt{\sum_{l=1}^n (s_{jl} - x_{il})^2 + \gamma^2}$$

for  $\gamma > 0$  .





# HSCM: Resolution Methodology

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## Smoothing the Euclidian distance:

Function  $\theta$  has the following properties:

- (a)  $\lim_{\gamma \rightarrow 0} \theta(s_j, x_i, \gamma) = \|s_j - x_i\|_2;$
- (b)  $\theta$  is a  $C^\infty$  function.

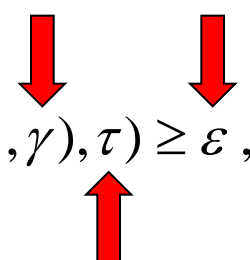


# HSCM: Resolution Methodology

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## Smoothing the problem

Therefore, it is now obtained the completely smooth problem:

$$\begin{array}{ll} \text{(P6) Minimize} & \sum_{j=1}^m f(z_j) \\ \text{Subject to:} & \sum_{i=1}^q \phi(z_j - \theta(s_j, x_i, \gamma), \tau) \geq \varepsilon, \quad j = 1, \dots, m. \end{array}$$




# HSCM: Resolution Methodology

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## Problem resolution

By considering the KKT conditions for the problem (P6), it is possible to conclude that all inequalities will certainly be active.

$$(P7) \text{ Minimize } \sum_{j=1}^m f(z_j)$$

$$\text{Subject to : } h(x, z_j) = \sum_{i=1}^q \phi(z_j - \theta(s_j, x_i, \gamma), \tau) - \varepsilon = 0, \quad j = 1, \dots, m.$$



# HSCM: Resolution Methodology

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## Problem resolution

Therefore, by using the Implicit Function Theorem, it is obtained the unconstrained problem

$$(P8) \text{ Minimize } F(x) = \sum_{j=1}^m f(z_j)$$

where each  $z_j$  is obtained by the calculation of a zero of each equation

$$h(x, z_j) = \sum_{i=1}^q \phi(z_j - \theta(s_j, x_i, \gamma), \tau) - \varepsilon = 0, \quad j = 1, \dots, m.$$



# HSCM: Resolution Methodology

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## Problem resolution

Again, due to the Implicit Function Theorem, the functions  $z_j(x)$  have all derivatives in relation to the variables  $x_i$ ,  $i = 1, \dots, q$ . So, it is possible to calculate the gradient of the objective function of the problem (P8)

$$\nabla F(x) = \sum_{j=1}^m \frac{df(z_j(x))}{dz_j} \nabla z_j(x)$$

where

$$\nabla z_j(x) = -\nabla h(x, z_j) / \frac{\partial h(x, z_j)}{\partial z_j}.$$



# HSCM: Resolution Methodology

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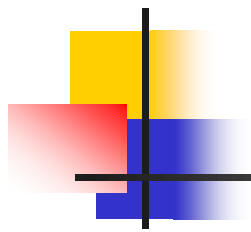
## Problem resolution

Some remarks about the problem (P8):

It can be solved by making use of any method based in the first and second order derivatives information (conjugate gradient, quasi-Newton, Newton methods, etc).

It is defined in a *nq*-dimensional space, therefore a smaller dimension problem in relation to the original problem (P7).

# Hyperbolic Smoothing Clustering Method: The Main Result



Parameters  
 $\tau, \gamma, \varepsilon, \dots$

Original Problem:  
Non-differentiable  
Non-Linear  
Programming  
Problem with  
Constraints

remodel

Completely  
Differentiable  
Non Linear  
Programming  
Problem  
**WITHOUT  
Constraints**



# Simplified HSC Algorithm

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Initialization Step: Choose values  $0 < \rho_1 < 1$ ,  $0 < \rho_2 < 1$ ,  $0 < \rho_3 < 1$ ;

Choose initial values:  $x^0$ ,  $\gamma^1$ ,  $\tau^1$ ,  $\varepsilon^1$ ; Let  $k = 1$ .

Main Step: Repeat indefinitely

Solve the unconstrained problem (P8)

$$\text{minimize } F(x) = \sum_{j=1}^m f(z_j(x))$$

with  $\gamma = \gamma^k$ ,  $\tau = \tau^k$ ,  $\varepsilon = \varepsilon^k$ , starting at the initial point  $x^{k-1}$ ,  
and let  $x^k$  be the solution obtained.

Let  $\gamma^{k+1} = \rho_1 \gamma^k$ ,  $\tau^{k+1} = \rho_2 \tau^k$ ,  $\varepsilon^{k+1} = \rho_3 \varepsilon^k$ ,  $k = k + 1$ .



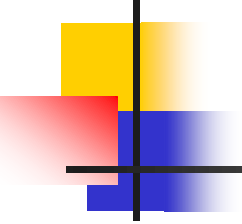


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# Hyperbolic Smoothing Clustering Method

applied to:

## Minimum Sum-of-Squares Clustering Problem



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# Hyperbolic Smoothing and Partition into Boundary and Gravitational Regions Applied to General Clustering Problem



# The Computational Task of the HSC Algorithm

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The most relevant computational task associated to HSC Algorithm is the determination of the zeros of  $m$  equations:

$$\sum_{i=1}^q \phi\left(z_j - \theta(s_j, x_i, \gamma), \tau\right) - \varepsilon = 0, \quad j = 1, \dots, m$$



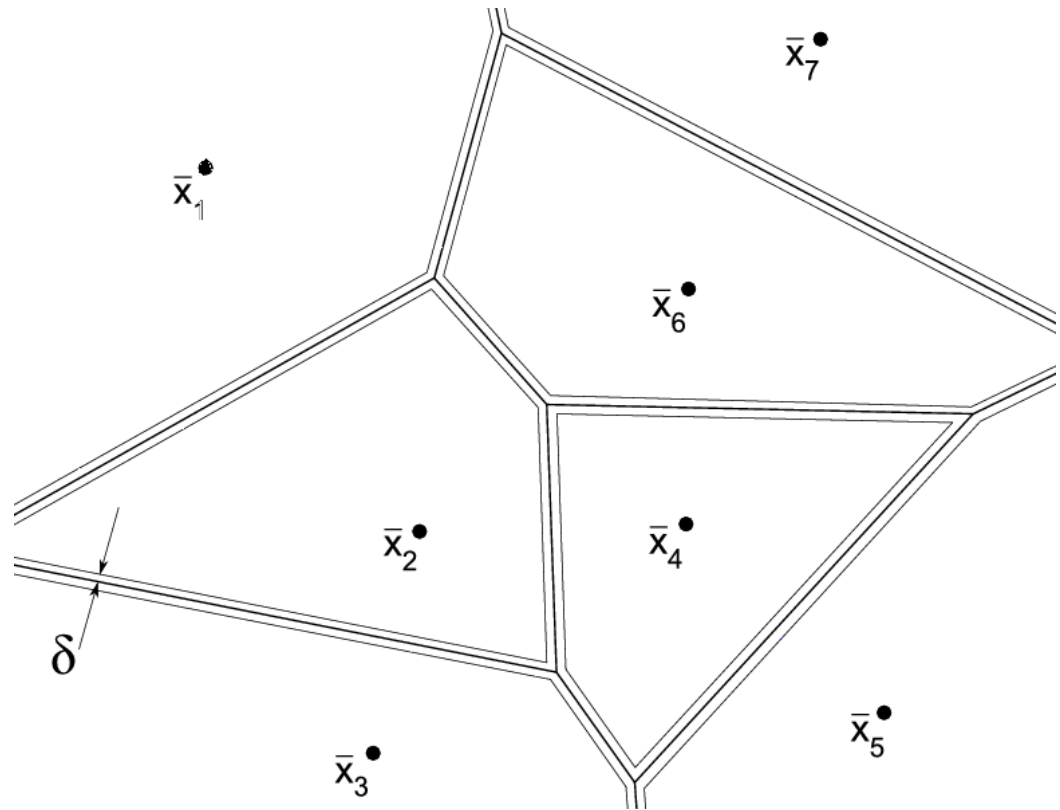
# The Partition into Boundary and Gravitational Regions

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The basic idea of the approach is the partition of the set of observations in two non overlapping parts:

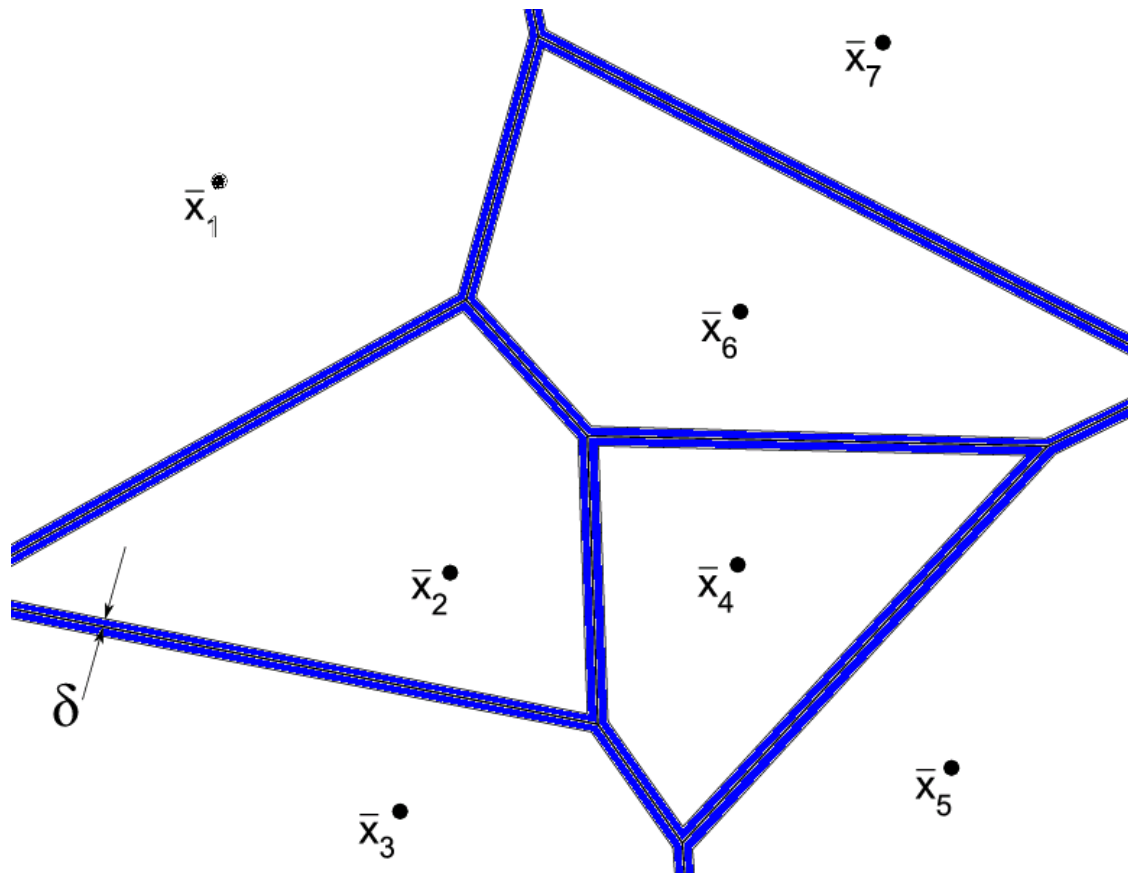
- the first set corresponds to the observation points that are relatively close to two or more centroids;
- the second set corresponds to the observation points that are significantly close to a unique centroid in comparison with the other ones.

# Partition of the Set of Observations

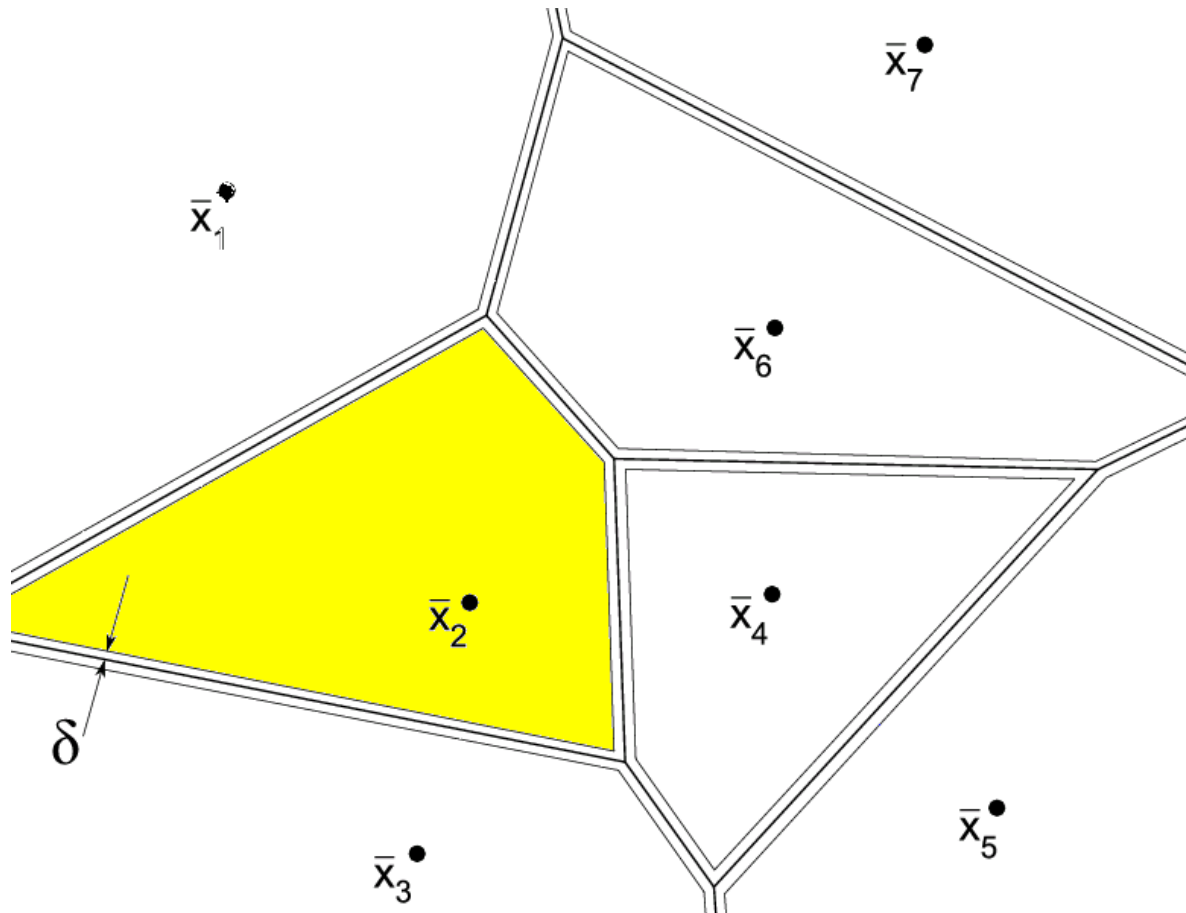


$\bar{x}$ : the referencial point  
 $\delta$ : the band zone width

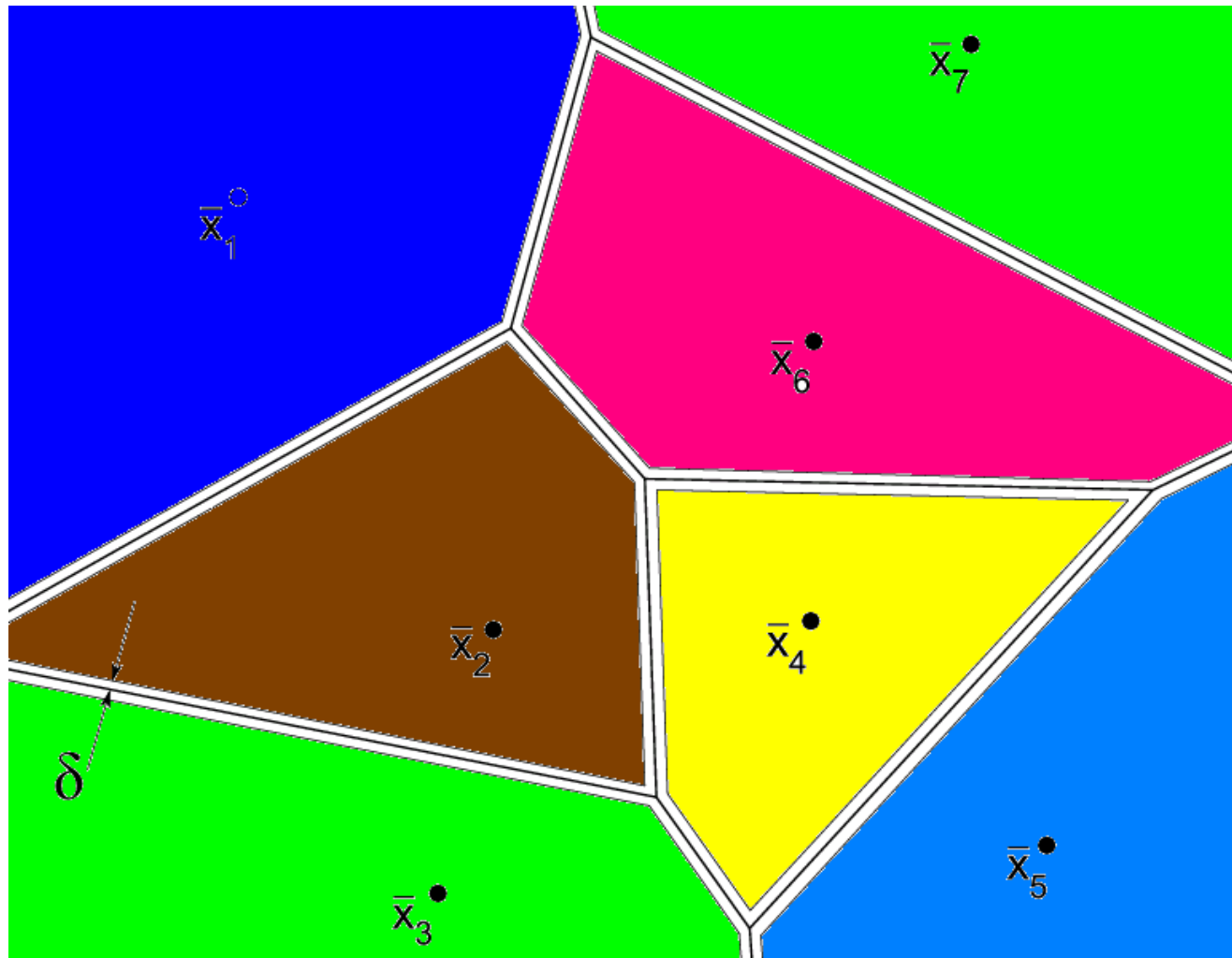
# The Boundary Band Zone



Gravitational Region  $\Rightarrow \bar{x}_2$



# Gravitational Regions







# The Partition of the Set of Observations

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Let us define:

- $J_B$  is the set of boundary observations;
- $J_G$  is the set of gravitational observations.

Considering this partition, the objective function can be expressed in the following way:

$$\textit{Minimize } F(x) = \sum_{j=1}^m f(z_j) = \sum_{j \in J_B} f(z_j) + \sum_{j \in J_G} f(z_j)$$

So, the objective function can be expressed in the following way:

$$\textit{Minimize } F(x) = f_B(x) + f_G(x)$$



# The First Component of the Objective Function

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The component associated with the set of boundary observations, can be calculated by using the previous presented smoothing approach:

$$\textit{Minimize } F_B(x) = \sum_{j \in J_B} f(z_j)$$

where each  $z_j$  results from the calculation of a zero of each equation:

$$h(x, z_j) = \sum_{i=1}^q \phi(z_j - \theta(s_j, x_i, \gamma), \tau) - \varepsilon = 0, j \in J_B$$



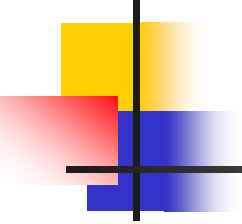
# The Second Component of the Objective Function

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The component associated with the gravitational regions, can be calculated in a simpler form:

$$\textit{Minimize } F_G(x) = \sum_{i=1}^q \sum_{j \in J_i} f(\|s_j - x_i\|)$$

where  $J_i$  is the set of observations associated to cluster  $i$ .



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# Hyperbolic Smoothing and Partition into Boundary and Gravitational Regions Applied to Minimum Sum-of-Squares Clustering Problem



# The Second Component for the MSSC

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For The Minimum Sum-of-Squares Clustering formulation,  
the second component, associated with the gravitational regions,  
can be calculated in a direct form:

$$\textit{Minimize } F_G(x) = \sum_{i=1}^q \sum_{j \in J_i} \|s_j - v_i\|_2^2 + \sum_{i=1}^q |J_i| \|x_i - v_i\|_2^2$$

where  $J_i$  is the set of observations associated to centroid  $i$   
 $v_i$  is the gravity center of cluster  $i$ .



# The Gradient of the Second Component for the MSSC

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The gradient of the second component, associated with the gravitational regions, can be calculated in an easy way:

$$\nabla F_G(x) = \sum_{i=1}^q 2|J_i| (x_i - v_i)$$

where  $J_i$  is the number the of observations associated to centroid  $i$



# Simplified Accelerated Algorithm: AHSCM

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Initialization Step: Choose values  $0 < \rho_1 < 1$ ,  $0 < \rho_2 < 1$ ,  $0 < \rho_3 < 1$ ;

Choose initial values:  $x^0$ ,  $\gamma^1$ ,  $\tau^1$ ,  $\varepsilon^1$ ; Let  $k = 1$ .

Specify the initial boundary band width:  $\delta^1$ .

Main Step:

Repeat indefinitely

By using  $\bar{x} = x^{k-1}$  and  $\delta = \delta^k$  determine partitions  $J_B$  and  $J_G$ .

Solve the problem

$$\text{minimize } f(x) = \sum_{j \in J_B} z_j(x)^2 + \sum_{j \in J_G} z_j(x)^2$$

with  $\gamma = \gamma^k$ ,  $\tau = \tau^k$ ,  $\varepsilon = \varepsilon^k$ , starting at the initial point  $x^{k-1}$ ,  
and let  $x^k$  be the solution obtained.

Redefine the boundary band width value  $\delta^{k+1}$ .

Let  $\gamma^{k+1} = \rho_1 \gamma^k$ ,  $\tau^{k+1} = \rho_2 \tau^k$ ,  $\varepsilon^{k+1} = \rho_3 \varepsilon^k$ ,  $k = k + 1$ .

# Comparison of Results: TSPLIB-3038

Hyperbolic Smoothing Clustering & Accelerated HSC Methods

Results published in Pattern Recognition 44 (2011) 70-77

q	$f_{\text{opt}}$	Algorithm HSC		Algorithm AHSC-L2		Speed up
		Error	Time (s)	Error	Time (s)	
2	0.31688E10	0.05	0.60	0.05	0.07	<b>8.6</b>
10	0.56025E09	0.01	16.16	0.01	0.28	<b>57.7</b>
20	0.26681E09	<b>-0.02</b>	62.90	0.05	0.59	<b>107</b>
30	0.17557E09	<b>-0.08</b>	169.17	0.31	0.86	<b>197</b>
40	0.12548E09	<b>-0.06</b>	333.92	<b>-0.11</b>	1.09	<b>306</b>
50	0.98400E08	0.50	662.33	0.44	1.36	<b>487</b>
60	0.82006E08	<b>-1.09</b>	1049.97	<b>-0.80</b>	1.91	<b>550</b>
80	0.61217E08	<b>-0.31</b>	2038.31	<b>-0.73</b>	6.72	<b>303</b>
100	0.48912E08	<b>-0.90</b>	3499.76	<b>-0.60</b>	9.79	<b>357</b>

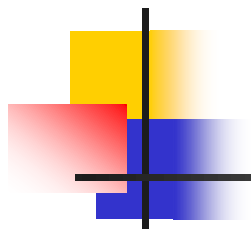


# Comparison of Results: Pla85900

Hyperbolic Smoothing Clustering & Accelerated HSC Methods

Results published in Pattern Recognition 44 (2011) 70-77

q	$f_{\text{opt}}$	Algorithm HSC		Algorithm AHSC-L2		Speed up
		Error	Time (s)	Error	Time (s)	
2	0.37491E16	0.86	23.07	0.58	3.65	<b>6.3</b>
3	0.22806E16	0.00	47.41	0.04	4.92	<b>9.6</b>
4	0.15931E16	0.00	76.34	0.00	5.76	<b>13.3</b>
5	0.13397E16	0.80	124.32	1.35	7.78	<b>16.0</b>
6	0.11366E16	0.12	173.44	1.25	7.87	<b>22.0</b>
7	0.97110E15	0.42	254.37	0.87	9.33	<b>27.3</b>
8	0.83774E15	0.55	353.61	0.37	12.96	<b>27.3</b>
9	0.74660E15	0.68	438.71	0.25	13.00	<b>33.8</b>
10	0.68294E15	0.29	551.98	0.46	14.75	<b>37.4</b>



# Hyperbolic Smoothing Applied to Minimum Sum-of-Squares Clustering Problem

Bagirov et al - December 2012

## An incremental clustering algorithm based on hyperbolic smoothing

A.M. Bagirov<sup>1</sup>, B. Ordin<sup>2</sup>, G. Ozturk<sup>3</sup> and A.E. Xavier<sup>4</sup>

<sup>1</sup>*School of Science, Information Technology and Engineering, University of Ballarat, Victoria, Australia,*

<sup>2</sup>*Department of Mathematics, Faculty of Science, Ege University, Izmir, Turkey,*

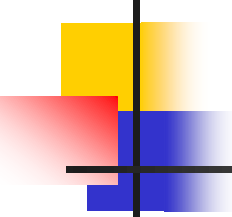
<sup>2</sup>*Department of Industrial Engineering, Faculty of Engineering, Anadolu University, Eskisehir, Turkey,*

<sup>4</sup>*Department of Systems Engineering and Computer Science, Graduate School of Engineering, Federal University of Rio de Janeiro, Rio de Janeiro, Brazil.*

# Comparison Results

General k-means, Modified General, Hyperbolic Smoothing

## D15112

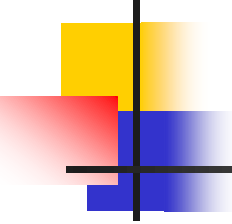


		GKM			MGKM			SMOOTH		
q	f <sub>opt</sub>	E	α	t	E	α	t	E	α	t
2	0.36840·10 <sup>12</sup>	0.00	0.22	2.75	0.00	0.46	4.51	0.00	0.42	5.15
5	0.13271·10 <sup>12</sup>	0.00	0.92	8.50	0.00	1.83	13.85	0.00	1.52	18.41
10	0.64892·10 <sup>11</sup>	0.78	2.07	14.87	0.78	4.12	24.98	0.00	3.44	41.50
15	0.43136·10 <sup>11</sup>	0.26	3.24	21.00	0.26	6.44	35.51	0.00	5.74	68.23
20	0.32177·10 <sup>11</sup>	0.25	4.43	26.99	0.25	8.77	45.68	0.00	8.65	101.82
25	0.25423·10 <sup>11</sup>	0.03	5.62	32.71	0.03	11.11	55.47	0.00	11.96	139.53

# Comparison Results

General k-means, Modified General k-means, Hyperbolic Smoothing

Pla85900



		GKM			MGKM			SMOOTH		
q	f <sub>opt</sub>	E	α	t	E	α	t	E	α	t
2	$0.37491 \cdot 10^{16}$	0.00	0.07	89.54	0.00	0.15	115.99	0.00	0.12	123.96
5	$0.13397 \cdot 10^{16}$	0.00	0.30	408.60	0.00	0.59	512.31	0.00	0.37	452.96
10	$0.68294 \cdot 10^{15}$	0.00	0.67	754.67	0.00	1.33	994.29	0.00	0.79	1011.17
15	$0.46029 \cdot 10^{15}$	0.51	1.04	1083.04	0.51	2.07	1448.94	0.00	1.24	1596.67
20	$0.35087 \cdot 10^{15}$	0.01	1.42	1355.85	0.00	2.82	1844.34	0.00	1.71	2210.91
25	$0.28323 \cdot 10^{15}$	0.74	1.80	1570.37	0.73	3.57	2186.20	0.00	2.21	2863.18

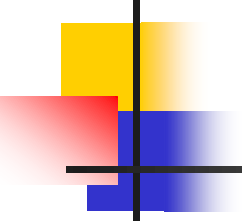


# Very Large Clustering Instances

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Hyperbolic Smoothing and  
Partition into Boundary and  
Gravitational Regions    Applied to  
Minimum Sum-of-Squares  
Clustering Problem

Synthetic Problems – 03/2013



# Synthetic Problem

## 5.000.000 Observations

### Euclidian Space with $n = 10$ dimensions

<b>q</b>	<b><math>f_{\text{AHSC-L2}}</math></b>	<b>Occur.</b>	<b><math>E_{\text{Mean}}</math></b>	<b><math>T_{\text{Mean}}</math></b>
2	0.456807E7	3	0.94	16.12
3	0.373567E7	1	1.21	24.69
4	0.323058E7	1	0.91	32.90
5	0.274135E7	1	0.09	26.06
6	0.248541E7	1	0.04	36.55
7	0.222897E7	1	0.19	43.24
8	0.197977E7	2	0.12	45.38
9	0.173581E7	2	0.10	42.78
10	0.149703E7	10	0.00	32.98
<b>c</b>	0.150000E7	-	-	-



# Medium and Large Clustering Instances

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Hyperbolic Smoothing and  
Partition into Boundary and  
Gravitational Regions    Applied to  
Minimum Sum-of-Squares  
Clustering Problem

Comparison with Bagirov et al

January-April 2014





# Medium Size Instances

## Starting Point - Tight Way

### Breast Cancer (m=683 , n=9)

<i>k</i>	<i>F<sub>opt</sub></i>	GKM		MGKM		HSCM		AHSCM	
		<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>
2	1,93E08	0	0	0	0.02	0	0.05	0.00	0.04
5	1,37E08	2.28	0.03	1.86	0.05	0	0.61	0.00	0.14
10	1,02E08	0.26	0.06	0.28	0.11	0	2.14	0.16	0.37
15	8,69E07	1.02	0.08	1.07	0.16	0	9.08	-0.36	0.62
20	7,65E07	3.64	0.11	1.80	0.20	0	27.36	-0.19	1.12
25	6,90E07	5.08	0.14	0.93	0.27	0	44.65	0.11	1.53



# Medium Size Instances

## Starting Point - Tight Way

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### TSPLIB3038 (m=3038 , n=2)

<i>k</i>	<i>F<sub>opt</sub></i>	GKM		MGKM		HSCM		AHSCM	
		<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>
2	3,17E13	0	0.06	0	0.11	0	0.25	0.06	0.11
5	1,20E13	0	0.25	0	0.39	0	0.98	0.00	0.21
10	5,60E12	2.78	0.48	0.58	0.81	0	2.64	0.56	0.69
15	3,56E12	0.07	0.70	1.06	1.20	0	5.16	0.03	1.40
20	2,67E12	2.00	0.94	0.48	1.61	0.11	8.86	0.22	2.39
25	2,15E12	0.78	1.20	0.23	1.98	0.01	14.01	0.18	3.84

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# Medium Size Instances

## Starting Point - Tight Way

### Pendigit (m=10992, n=16)

<i>k</i>	<i>F<sub>opt</sub></i>	GKM		MGKM		HSCM		AHSCM	
		<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>
2	1,28E12	0.39	2.56	0	5.23	0	5.37	0.00	0.38
5	7,53E11	0	9.73	0	18.72	0	22.60	0.00	1.76
10	4,93E11	0	20.45	0	39.31	0	61.71	0.00	4.99
15	3,91E11	0	30.79	0	59.19	0	120.46	0.00	10.33
20	3,41E11	0	41.25	0.17	78.37	0.16	250.80	-0.31	19.21
25	3,00E11	0.24	51.87	0.24	98.47	0	446.37	-0.12	33.06



# Large Size Instances

## Starting Point - Tight Way

### D15112 (m=15112, n=2)

<i>k</i>	<i>F<sub>opt</sub></i>	GKM		MGKM		HSCM		AHSCM	
		<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>
2	3,68E15	0	2.75	0	4.51	0	5.15	0.00	0.31
5	1,33E15	0	8.50	0	13.85	0	18.41	0.00	1.36
10	6,49E14	0.78	14.87	0.78	24.98	0	41.50	-0.62	4.21
15	4,31E14	0.26	21.00	0.26	35.51	0	68.23	0.15	9.31
20	3,22E14	0.25	26.99	0.25	45.68	0	101.82	0.62	17.43
25	2,54E14	0.03	32.71	0.03	55.47	0	139.53	-0.49	30.22



# Large Size Instances

## Starting Point - Tight Way

### Shuttle (m=58000, n=9)

$k$	$F_{opt}$	GKM		MGKM		HSCM		AHSCM	
		$E$	$t$	$E$	$t$	$E$	$t$	$E$	$t$
2	2,13E13	0	63.20	0	123.82	0	86.74	0.00	0.20
5	7,24E12	0	251.65	0	521.81	0	351.50	0.00	1.35
10	2,83E12	0.02	581.28	0	1207.20	0	813.73	0.00	4.87
15	1,53E12	0	888.24	0	1776.88	0	1272.75	0.00	11.09
20	1,06E12	0	1195.84	0	2338.99	0	1798.88	-3.60	26.80
25	7,98E11	0.17	1512.55	0.17	2917.41	0	2396.82	-3.13	51.97

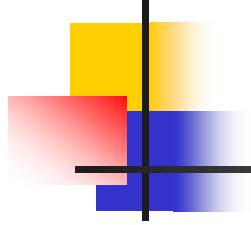


# Large Size Instances

## Starting Point - Tight Way

### Pla85900 (m=85900 , n=2)

<i>k</i>	<i>F<sub>opt</sub></i>	GKM		MGKM		HSCM		AHSCM	
		<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>	<i>E</i>	<i>t</i>
2	3,75E19	0	89.54	0	115.99	0	123.96	0.00	1.17
5	1,34E19	0	408.60	0	512.31	0	452.96	0.00	5.04
10	6,83E18	0	754.67	0	994.29	0	1011.17	0.00	15.66
15	4,60E18	0.51	1083.04	0.51	1448.94	0	1596.67	0.00	38.01
20	3,51E18	0.01	1355.85	0	1844.34	0	2210.91	0.00	73.09
25	2,83E18	0.74	1570.37	0.73	2186.20	0	2863.18	0.13	135.62



# Conclusions

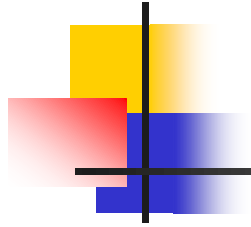


# Conclusions

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In view of the preliminary results obtained, where the proposed methodology performed **efficiently** and **robustly**, these algorithms can represent a possible approach for dealing with the solving of clustering of problems of real applications.





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END