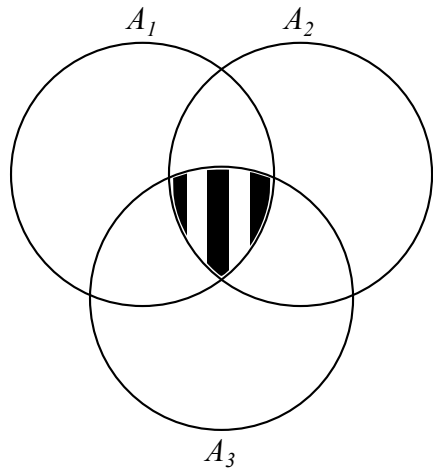


$$Q_1(x; z, w) := A_1(x, y), A_2(y, z), A_3(y, w)$$



$$Q_2(x; z, w) := A_1(x, y), A_2(y, z), A_3(y, w)$$

