

Examen Localización de un robot diferencial

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1.- Un robot diferencial se encuentra en la posición inicial $(-1, -5, 0^\circ)$, posteriormente genera el siguiente historial de pasos:

Paso	$v(\text{m/s})$	$\omega \text{ (rad/s)}$	$\Delta t \text{ (s)}$
1	1.0	0.0	1.0
2	0.0	$\pi/3$	1.0
3	1.0	0.0	1.0
4	0.0	$\pi/3$	1.0
5	1.0	0.0	1.0
6	0.0	$\pi/3$	1.0
7	1.0	0.0	1.0
8	0.0	$\pi/3$	1.0
9	1.0	0.0	1.0
10	0.0	$\pi/3$	1.0
11	1.0	0.0	1.0
12	0.0	$\pi/3$	1.0

- a) Obtén la pose del robot en cada paso, integrando numéricamente siguiendo la suposición de Markov. Muestra tus resultados en una tabla.
- b) Calcula la pose final (x, y, θ) del robot tras completar los 12 pasos.

Paso	X	Y	θ
1	0.0	-5.0	0.0
2	0.0	-5.0	60°
3	0.5	-4.13	60°
4	0.5	-4.13	120°
5	0.0	-3.26	120°
6	0.0	-3.26	180°

7	-1.0	-3.26	180°
8	-1.0	-3.26	240°
9	-1.5	-4.13	240°
10	-1.5	-4.13	300°
11	-1.0	-5.0	300°
12	-1.0	-5.0	360°

2.- Un robot diferencial con los siguientes parámetros:

Radio de las ruedas: 0.1m.

Distancia entre ruedas (eje): $L = 0.4\text{m}$

Pose inicial $(x_0, y_0, \theta_0) = (0, 0, 0^\circ)$

Recibe las siguientes señales de entrada:

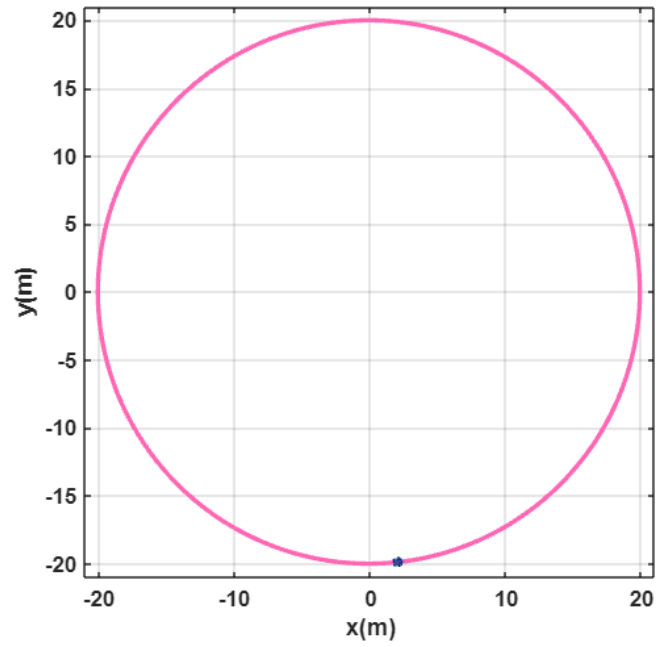
t (s)	v (m/s) ω (rad/s) ω_R (rad/s) ω_L (rad/s) x (m) y (m)						Θ (grados)
0	0.15	0.800	4.582	1.701	0.0	0.0	0

1	0.15	0.672	4.773	2.353	0.10	0.11	45
2	0.22	0.449	5.291	3.676	0.12	0.29	84.37
3	0.27	0.307	5.960	4.856	0.05	0.50	110.07
4	0.30	0.242	6.490	5.618	-0.11	0.71	127.64

t (s)	v (m/s) ω (rad/s) ω_R (rad/s) ω_L (rad/s) x (m) y (m)						Θ (grados)
5	0.31	-4.140	-1.168	13.735	-0.35	0.90	141.52
6	0.30	-4.121	-1.364	13.472	-0.38	0.59	264.33
7	0.27	0.307	5.960	4.856	-0.11	0.73	28.21
8	0.22	0.449	5.291	3.676	0.07	0.92	45.78
9	0.17	0.672	4.773	2.353	0.14	1.14	71.48
10	0.15	0.800	4.582	1.701	0.08	1.30	110.0
11	0.17	0.672	4.773	2.353	-0.06	1.37	155.85
12	0.22	0.449	5.291	3.676	-0.23	1.32	194.37
13	0.27	0.307	5.960	4.856	-0.40	1.18	220.07
14	0.30	0.242	6.490	5.618	-0.55	0.95	237.64
15	0.31	0.224	6.686	5.881	-0.64	0.66	251.52
16	0.30	0.242	6.490	5.618	-0.67	0.35	264.33
17	0.27	0.307	5.960	4.856	-0.63	0.05	278.21
18	0.22	0.449	5.291	3.676	-0.51	-0.18	295.78
19	0.17	0.672	4.773	2.353	-0.34	-0.32	321.48
20	0.15	0.800	4.582	1.701	-0.16	-0.32	360

Completa la tabla y genera la simulación de la trayectoria del robot en Matlab

3.- Considerando los parámetros del robot descrito en el reactivo 2. Obtén la tabla de las señales de entrada ω_R (rad/s) y ω_L (rad/s) requeridas en cada instante de muestreo si se desea obtener una trayectoria circular con un radio de 20m, cuyo centro sea el origen (0, 0). Genera la simulación en Matlab.



1		$\omega_R = 202.000$		$\omega_L = 198.00$
2		$\omega_R = 202.000$		$\omega_L = 198.00$
3		$\omega_R = 202.000$		$\omega_L = 198.00$
4		$\omega_R = 202.000$		$\omega_L = 198.00$
5		$\omega_R = 202.000$		$\omega_L = 198.00$
6		$\omega_R = 202.000$		$\omega_L = 198.00$
7		$\omega_R = 202.000$		$\omega_L = 198.00$
8		$\omega_R = 202.000$		$\omega_L = 198.00$
9		$\omega_R = 202.000$		$\omega_L = 198.00$
10		$\omega_R = 202.000$		$\omega_L = 198.00$
11		$\omega_R = 202.000$		$\omega_L = 198.00$
12		$\omega_R = 202.000$		$\omega_L = 198.00$
13		$\omega_R = 202.000$		$\omega_L = 198.00$
14		$\omega_R = 202.000$		$\omega_L = 198.00$
15		$\omega_R = 202.000$		$\omega_L = 198.00$
16		$\omega_R = 202.000$		$\omega_L = 198.00$
17		$\omega_R = 202.000$		$\omega_L = 198.00$
18		$\omega_R = 202.000$		$\omega_L = 198.00$
19		$\omega_R = 202.000$		$\omega_L = 198.00$
20		$\omega_R = 202.000$		$\omega_L = 198.00$
21		$\omega_R = 202.000$		$\omega_L = 198.00$
22		$\omega_R = 202.000$		$\omega_L = 198.00$
23		$\omega_R = 202.000$		$\omega_L = 198.00$
24		$\omega_R = 202.000$		$\omega_L = 198.00$
25		$\omega_R = 202.000$		$\omega_L = 198.00$
26		$\omega_R = 202.000$		$\omega_L = 198.00$
27		$\omega_R = 202.000$		$\omega_L = 198.00$
28		$\omega_R = 202.000$		$\omega_L = 198.00$
29		$\omega_R = 202.000$		$\omega_L = 198.00$
30		$\omega_R = 202.000$		$\omega_L = 198.00$
31		$\omega_R = 202.000$		$\omega_L = 198.00$
32		$\omega_R = 202.000$		$\omega_L = 198.00$
33		$\omega_R = 202.000$		$\omega_L = 198.00$

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628	$\omega_R = 202.000$	$\omega_L = 198.00$
629	$\omega_R = 202.000$	$\omega_L = 198.00$
630	$\omega_R = 202.000$	$\omega_L = 198.00$
631	$\omega_R = 202.000$	$\omega_L = 198.00$
632	$\omega_R = 202.000$	$\omega_L = 198.00$
633	$\omega_R = 202.000$	$\omega_L = 198.00$
634	$\omega_R = 202.000$	$\omega_L = 198.00$
635	$\omega_R = 202.000$	$\omega_L = 198.00$
636	$\omega_R = 202.000$	$\omega_L = 198.00$
637	$\omega_R = 202.000$	$\omega_L = 198.00$
638	$\omega_R = 202.000$	$\omega_L = 198.00$
639	$\omega_R = 202.000$	$\omega_L = 198.00$
640	$\omega_R = 202.000$	$\omega_L = 198.00$