

tesseract_planning
::TrajOptPlanProfile

```
std::vector< std::tuple  
< sco::VectorOfVector  
::func, sco::MatrixOfVector  
::func, sco::ConstraintType,  
Eigen::VectorXd > >
```

VectorXd

constraint_error_functions
cartesian_coeff
joint_coeff

tesseract_planning
::TrajOptDefaultPlanProfile

