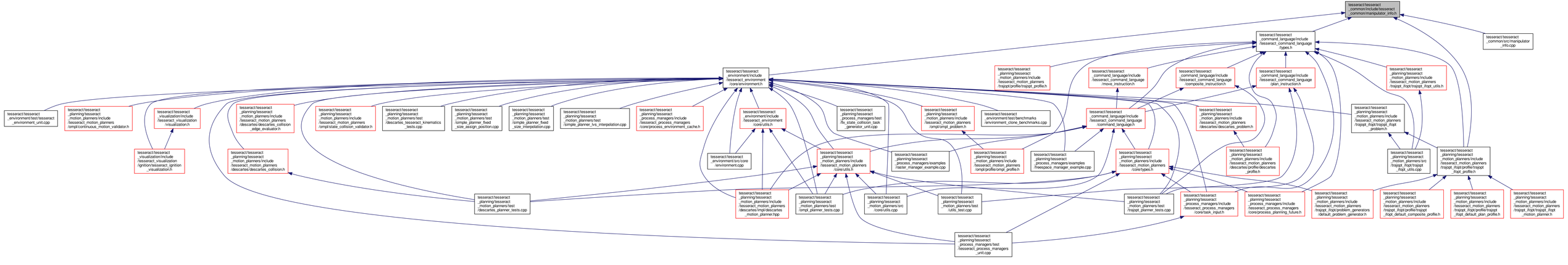
tesseract/tesseract_common/include/tesseract_common/manipulator_info.h
tesseract/tesseract_common/src/manipulator_info.cpp
tesseract/tesseract_command_language/include/tesseract_command_language/types.h
tesseract/tesseract_environment/include/tesseract_environment/core/environment.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt_profile.h
tesseract/tesseract_command_language/include/tesseract_command_language/move_instruction.h
tesseract/tesseract_command_language/include/tesseract_command_language/composite_instruction.h
tesseract/tesseract_command_language/include/tesseract_command_language/plan_instruction.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt_utils.h
tesseract/tesseract_environment/test/tesseract_environment_unit.cpp
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/ompl/continuous_motion_validator.h
tesseract/tesseract_visualization/include/tesseract_visualization/visualization.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/descartes/descartes_collision_edge_evaluator.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/descartes/descartes_collision.h
tesseract/tesseract_visualization/include/tesseract_visualization/ignition/tesseract_ignition_visualization.h
tesseract/tesseract_planning/tesseract_motion_planners/test/descartes_planner_tests.cpp
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/descartes/state_collision_validator.h
tesseract/tesseract_planning/tesseract_motion_planners/test/descartes_tesseract_kinematics_tests.cpp
tesseract/tesseract_planning/tesseract_motion_planners/test/simple_planner_fixed_size_assign_position.cpp
tesseract/tesseract_planning/tesseract_motion_planners/test/simple_planner_fixed_size_interpolation.cpp
tesseract/tesseract_planning/tesseract_motion_planners/test/simple_planner_lvs_interpolation.cpp
tesseract/tesseract_process_managers/include/tesseract_process_managers/core/process_environment_cache.h
tesseract/tesseract_environment/include/tesseract_environment/core/utils.h
tesseract/tesseract_environment/src/core/environment.cpp
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/core/utils.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/descartes/impl/descartes_motion_planner.hpp
tesseract/tesseract_planning/tesseract_motion_planners/test/ompl_planner_tests.cpp
tesseract/tesseract_planning/tesseract_motion_planners/test/descartes_tesseract_generator_unit.cpp
tesseract/tesseract_planning/tesseract_motion_planners/test/ompl_motion_planners/ompl/ompl_problem.h
tesseract/tesseract_environment/test/benchmarks/environment_clone_benchmarks.cpp
tesseract/tesseract_planning/tesseract_process_managers/examples/raster_manager_example.cpp
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/ompl/profile/ompl_profile.h
tesseract/tesseract_planning/tesseract_process_managers/examples/freespace_manager_example.cpp
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/core/types.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/descartes/descartes_problem.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/descartes/profile/descartes_profile.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt_problem.h
tesseract/tesseract_planning/tesseract_motion_planners/test/utils_test.cpp
tesseract/tesseract_planning/tesseract_motion_planners/test/trajopt_planner_tests.cpp
tesseract/tesseract_planning/tesseract_process_managers/include/tesseract_process_managers/core/task_input.h
tesseract/tesseract_planning/tesseract_process_managers/include/tesseract_process_managers/core/process_planning_future.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt/problem_generators/default_problem_generator.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt/profile/trajopt/default_composite_profile.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt/profile/trajopt/default_plan_profile.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt/trajopt_motion_planner.h
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt/trajopt_utils.cpp
tesseract/tesseract_planning/tesseract_motion_planners/include/tesseract_motion_planners/trajopt/trajopt/profile/trajopt/trajopt_profile.h
tesseract/tesseract_planning/tesseract_process_managers/test/tesseract_process_managers_unit.cpp