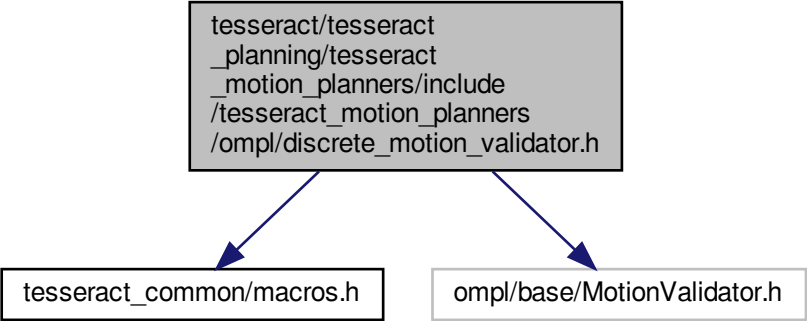


tesseract/tesseract
_planning/tesseract
_motion_planners/include
/tesseract_motion_planners
/ompl/discrete_motion_validator.h



```
graph TD; A["tesseract/tesseract  
_planning/tesseract  
_motion_planners/include  
/tesseract_motion_planners  
/ompl/discrete_motion_validator.h"] --> B["tesseract_common/macros.h"]; A --> C["ompl/base/MotionValidator.h"]
```

tesseract_common/macros.h

ompl/base/MotionValidator.h