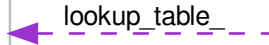


```
std::unordered_map  
< tesseract_common::  
LinkNamesPair, double,  
tesseract_common::PairHash >
```

lookup_table_

A dashed purple line with an arrowhead pointing left connects the two boxes. The label 'lookup_table_' is centered above the line.

```
tesseract_collision  
::CollisionMarginData
```