

tesseract/tesseract
_collision/include/tesseract
_collision/bullet/tesseract
_compound_compound_collision
_algorithm.h

```
graph BT; A["tesseract/tesseract_collision/src/bullet/tesseract_collision_configuration.cpp"] --> C["tesseract/tesseract_collision/include/tesseract_collision/bullet/tesseract_compound_compound_collision_algorithm.h"]; B["tesseract/tesseract_collision/src/bullet/tesseract_compound_compound_collision_algorithm.cpp"] --> C;
```

The diagram illustrates the relationship between three source files in the Tesseract project. At the top is a header file, `tesseract/tesseract_collision/include/tesseract_collision/bullet/tesseract_compound_compound_collision_algorithm.h`, which is shaded gray. Below it are two source files: `tesseract/tesseract_collision/src/bullet/tesseract_collision_configuration.cpp` on the left and `tesseract/tesseract_collision/src/bullet/tesseract_compound_compound_collision_algorithm.cpp` on the right. Both source files have blue arrows pointing to the header file, indicating that they include it.

tesseract/tesseract
_collision/src/bullet
/tesseract_collision_configuration.cpp

tesseract/tesseract
_collision/src/bullet
/tesseract_compound_compound
_collision_algorithm.cpp