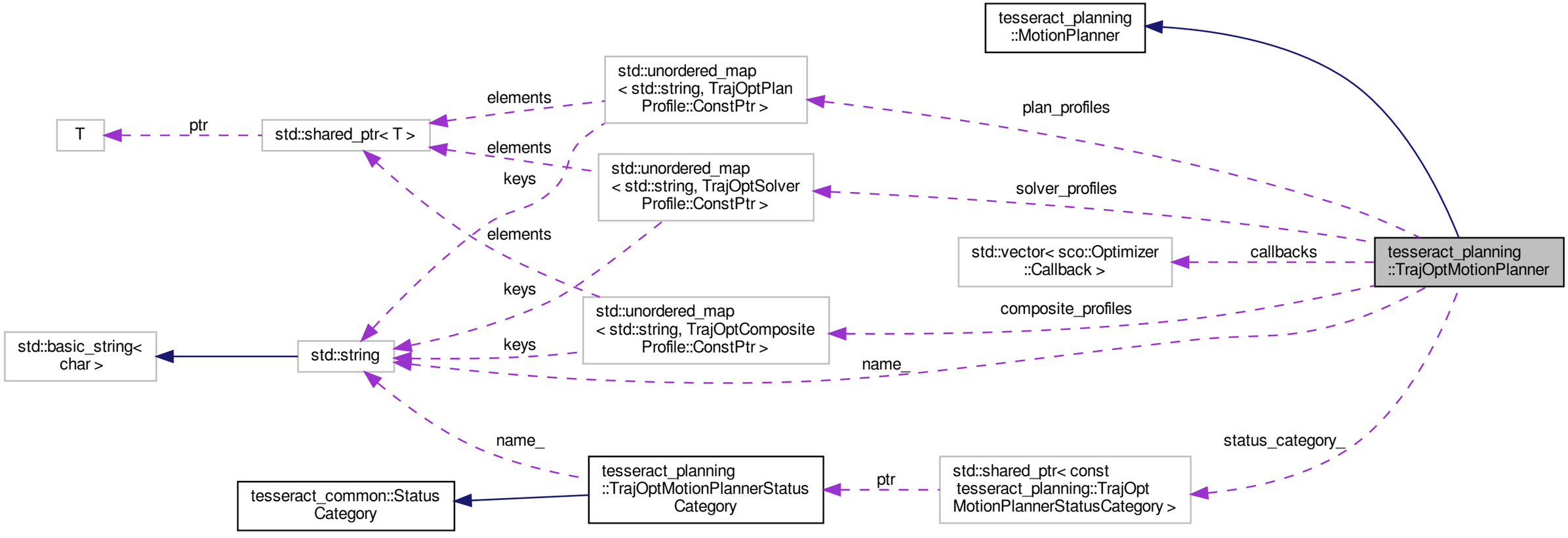
tesseract_planning ::MotionPlanner
std::unordered_map < std::string, TrajOptPlan Profile::ConstPtr >
plan_profiles
elements
T
ptr
std::shared_ptr< T >
elements
std::unordered_map < std::string, TrajOptSolver Profile::ConstPtr >
solver_profiles
keys
elements
std::vector< sco::Optimizer ::Callback >
callbacks
tesseract_planning ::TrajOptMotionPlanner
keys
std::unordered_map < std::string, TrajOptComposite Profile::ConstPtr >
composite_profiles
std::basic_string< char >
std::string
keys
name_
name_
status_category_
tesseract_planning ::TrajOptMotionPlannerStatus Category
ptr
std::shared_ptr< const tesseract_planning::TrajOpt MotionPlannerStatusCategory >
tesseract_common::Status Category