

tesseract/tesseract
_collision/include/tesseract
_collision/bullet/tesseract
_convex_convex_algorithm.h

```
graph BT; A["tesseract/tesseract_collision/src/bullet/tesseract_collision_configuration.cpp"] --> C["tesseract/tesseract_collision/include/tesseract_collision/bullet/tesseract_convex_convex_algorithm.h"]; B["tesseract/tesseract_collision/src/bullet/tesseract_convex_convex_algorithm.cpp"] --> C;
```

The diagram illustrates a dependency structure where two source files, `tesseract_collision_configuration.cpp` and `tesseract_convex_convex_algorithm.cpp`, both include the header file `tesseract_convex_convex_algorithm.h`. The header file is represented by a grey box at the top, while the source files are in white boxes at the bottom. Blue arrows point from each source file to the header file.

tesseract/tesseract
_collision/src/bullet
/tesseract_collision_configuration.cpp

tesseract/tesseract
_collision/src/bullet
/tesseract_convex_convex
_algorithm.cpp