

tesseract\_scene\_graph  
/include/tesseract\_scene  
\_graph/srdf/group\_rop\_kinematics.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/group_rop_kinematics.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

A diagram showing the relationship between three files. At the top is a grey box containing the header file path: `tesseract_scene_graph/include/tesseract_scene_graph/srdf/group_rop_kinematics.h`. Below it are two white boxes. The left box contains the source file path: `tesseract_scene_graph/src/srdf_model.cpp`. The right box contains the test file path: `tesseract_scene_graph/test/tesseract_scene_graph_srdf_unit.cpp`. Two blue arrows point from the bottom of each white box to the bottom of the grey box, indicating that both source files include the header file.

tesseract\_scene\_graph  
/src/srdf\_model.cpp

tesseract\_scene\_graph  
/test/tesseract\_scene  
\_graph\_srdf\_unit.cpp