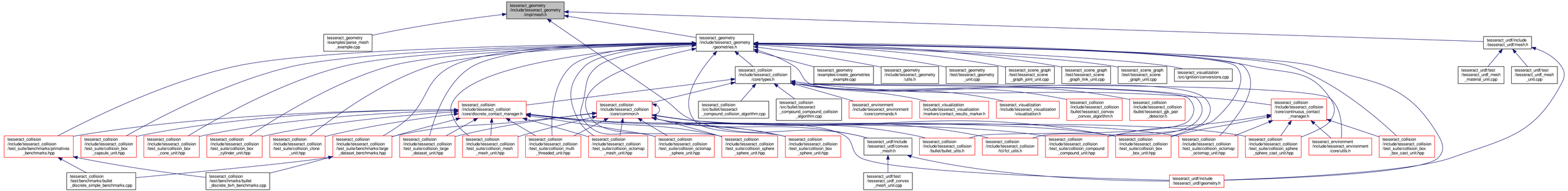
tesseract_geometry /include/tesseract_geometry /impl/mesh.h
tesseract_geometry /examples/parse_mesh _example.cpp
tesseract_geometry /include/tesseract_geometry /geometries.h
tesseract_urdf/include /tesseract_urdf/mesh.h
tesseract_urdf/test /tesseract_urdf_mesh _material_unit.cpp
tesseract_urdf/test /tesseract_urdf_mesh _unit.cpp
tesseract_collision /include/tesseract_collision /core/types.h
tesseract_geometry /examples/create_geometries _example.cpp
tesseract_geometry /include/tesseract_geometry /utils.h
tesseract_geometry /test/tesseract_geometry _unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_joint_unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_link_unit.cpp
tesseract_scene_graph /test/tesseract_scene _graph_unit.cpp
tesseract_visualization /src/ignition/conversions.cpp
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tesseract_collision /src/bullet/tesseract _compound_collision_algorithm.cpp
tesseract_environment /include/tesseract_environment /core/commands.h
tesseract_visualization /include/tesseract_visualization /markers/contact_results_marker.h
tesseract_visualization /include/tesseract_visualization /visualization.h
tesseract_collision /include/tesseract_collision /bullet/tesseract_convex _convex_algorithm.h
tesseract_collision /include/tesseract_collision /bullet/tesseract_gjk_pair _detector.h
tesseract_collision /include/tesseract_collision /core/continuous_contact _manager.h
tesseract_collision /include/tesseract_collision /test_suite/benchmarks/primitives _benchmarks.hpp
tesseract_collision /include/tesseract_collision /test_suite/collision_box _capsule_unit.hpp
tesseract_collision /include/tesseract_collision /test_suite/collision_box _cone_unit.hpp
tesseract_collision /include/tesseract_collision /test_suite/collision_box _cylinder_unit.hpp
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tesseract_collision /test/benchmarks/bullet _discrete_simple_benchmarks.cpp
tesseract_collision /test/benchmarks/bullet _discrete_bvh_benchmarks.cpp
tesseract_urdf/test /tesseract_urdf_convex _mesh_unit.cpp
tesseract_urdf/include /tesseract_urdf/geometry.h