

tesseract\_kinematics  
/include/tesseract\_kinematics  
/kdl/kdl\_inv\_kin\_chain\_lma  
\_factory.h

```
graph BT; A["tesseract_environment  
/src/core/manipulator  
_manager.cpp"] --> C["tesseract_kinematics  
/include/tesseract_kinematics  
/kdl/kdl_inv_kin_chain_lma  
_factory.h"]; B["tesseract_kinematics  
/test/kdl_kinematics  
_unit.cpp"] --> C;
```

A diagram showing the relationship between three files. At the top is a grey box containing the header file path: `tesseract_kinematics /include/tesseract_kinematics /kdl/kdl_inv_kin_chain_lma _factory.h`. Below it are two white boxes. The left box contains `tesseract_environment /src/core/manipulator _manager.cpp` and the right box contains `tesseract_kinematics /test/kdl_kinematics _unit.cpp`. Blue arrows point from the bottom of each white box to the bottom of the grey box, indicating that both source files include this header.

tesseract\_environment  
/src/core/manipulator  
\_manager.cpp

tesseract\_kinematics  
/test/kdl\_kinematics  
\_unit.cpp