

tesseract_scene_graph
/include/tesseract_scene
_graph/srdf/group_rop_kinematics.h

```
graph BT; A["tesseract_scene_graph  
/src/srdf_model.cpp"] --> C["tesseract_scene_graph  
/include/tesseract_scene_graph/srdf/group_rop_kinematics.h"]; B["tesseract_scene_graph  
/test/tesseract_scene_graph_srdf_unit.cpp"] --> C;
```

The diagram illustrates the inclusion relationships between three files in the tesseract_scene_graph library. At the top is a header file, 'tesseract_scene_graph/include/tesseract_scene_graph/srdf/group_rop_kinematics.h', which is shaded gray. Below it are two source files: 'tesseract_scene_graph/src/srdf_model.cpp' on the left and 'tesseract_scene_graph/test/tesseract_scene_graph_srdf_unit.cpp' on the right. Blue arrows point from each source file to the header file, indicating that both source files include this header.

tesseract_scene_graph
/src/srdf_model.cpp

tesseract_scene_graph
/test/tesseract_scene
_graph_srdf_unit.cpp