

tesseract\_collision  
/include/tesseract\_collision  
/bullet/tesseract\_compound  
\_compound\_collision\_algorithm.h

```
graph BT; A["tesseract_collision  
/src/bullet/tesseract  
_collision_configuration.cpp"] --> C["tesseract_collision  
/include/tesseract_collision  
/bullet/tesseract_compound  
_compound_collision_algorithm.h"]; B["tesseract_collision  
/src/bullet/tesseract  
_compound_compound_collision  
_algorithm.cpp"] --> C;
```

The diagram illustrates the relationship between two source files and a header file. At the top is a grey box representing the header file: `tesseract_collision`, `/include/tesseract_collision`, `/bullet/tesseract_compound_compound_collision_algorithm.h`. Below it are two white boxes representing source files. The left box is `tesseract_collision`, `/src/bullet/tesseract_collision_configuration.cpp`. The right box is `tesseract_collision`, `/src/bullet/tesseract_compound_compound_collision_algorithm.cpp`. Two blue arrows point from the source files up to the header file, indicating that they include or depend on it.

tesseract\_collision  
/src/bullet/tesseract  
\_collision\_configuration.cpp

tesseract\_collision  
/src/bullet/tesseract  
\_compound\_compound\_collision  
\_algorithm.cpp