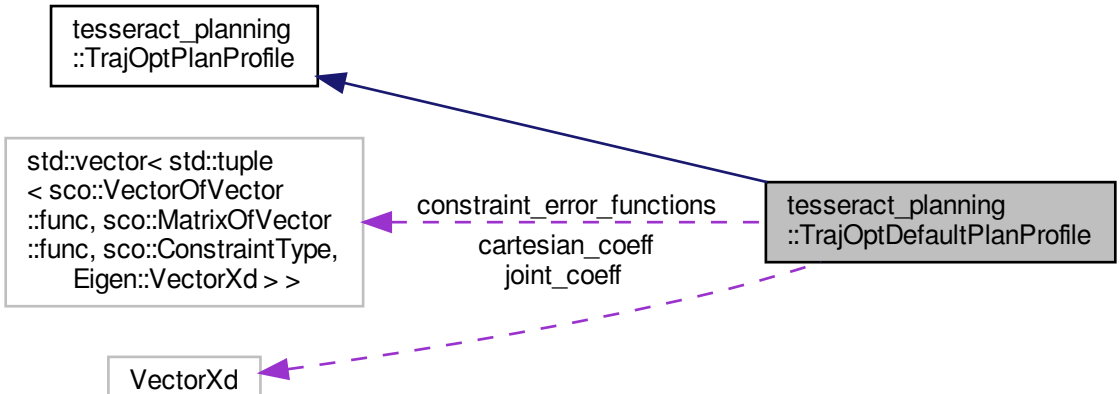
tesseract_planning
::TrajOptPlanProfile
std::vector< std::tuple
< sco::VectorOfVector
::func, sco::MatrixOfVector
::func, sco::ConstraintType,
Eigen::VectorXd > >
constraint_error_functions
cartesian_coeff
joint_coeff
tesseract_planning
::TrajOptDefaultPlanProfile
VectorXd