FFNN Multiclass Classification

September 11, 2022

1 Initialisation

1.1 Imports and General Functions

```
[2]: def IsNotebook():
                       """Indicate the shell name, whether code is running on a notebook, and if_\sqcup
                ⇔so whether it's hosted on googlecolab."""
                       isnotebook, isgooglecolab, shell = None, None, None
                      try:
                                 shell = get_ipython().__class__.__name__
                                 if shell == 'ZMQInteractiveShell':
                                            isnotebook, isgooglecolab = True, False # Jupyter notebook or
                \rightarrowqtconsole
                                 elif shell == "Shell":
                                            isnotebook, isgooglecolab = True, True
                                                                                                                                                  # Google Colab
                                 elif shell == 'TerminalInteractiveShell':
                                           isnotebook, isgooglecolab = False, False # Terminal running IPython
                                 else:
                                           isnotebook, isgooglecolab = False, False # Other type (?)
                       except NameError:
                                 isnotebook, isgooglecolab = False, False  # Probably standard  # 
               \hookrightarrowPython interpreter
                      return shell, isnotebook, isgooglecolab
            shell, isnotebook, isgooglecolab = IsNotebook()
            if isnotebook and not isgooglecolab: \#If we are in a notebook but not on google_{\sqcup}
                ⇔colab, let's use all the available screen
                      from IPython.display import display, HTML
                      display(HTML("<style>.container { width:99% !important; }</style>"))
                       if not isgooglecolab:
                                 try: #Using the jedi completer takes too long to complete words
                                           %config Completer.use_jedi = False
                                 except:
                                           pass
            if isgooglecolab: \#If we are in a google colab environment, we probably need to
                →mount our google drive
                      try:
                                 from google.colab import drive
```

```
drive.mount('/content/drive')
except Exception as e:
    print(e)
```

<IPython.core.display.HTML object>

```
### General Imports ###
     import os #Making sure we're using all CPU cores for faster calculations
     IsWindows = os.name == 'nt'
     os.environ["OMP_NUM_THREADS"] = str(os.cpu_count())
     os.environ["OPENBLAS_NUM_THREADS"] = str(os.cpu_count())
     os.environ["MKL_NUM_THREADS"] = str(os.cpu_count())
     os.environ["VECLIB_MAXIMUM_THREADS"] = str(os.cpu_count())
     os.environ["NUMEXPR_NUM_THREADS"] = str(os.cpu_count())
     import sys #Printing version for posterity
     print("Python version:", sys.version)
     try: #Allows saving and loading of variables
         import pickle5 as pickle
     except:
         import pickle
     try: #Printing version for posterity
         print("Pickle version:", pickle.__version__)
     except:
         print("Pickle version:", pickle.format_version)
     import dill as dill #Allows even deeper saving (associated classes, etc., as⊔
       ⇔well)
     print("Dill version:", dill.__version__)
     import warnings #Ability to create custom warnings, like warnings.
       →warn("deprecated", DeprecationWarning)
     import itertools #Needed for Confusion Matrix
     if IsWindows:
          import winsound #Uses the computer's speakers to alert you (e.g. when⊔
       ⇔training is done)
     from tqdm import tqdm #Iterations can show a progress bar (like in Training)
     from collections import Counter #Allows for frequency counting similar with R'su
       "table"
     from collections import OrderedDict
      ######################
      #########################
```

```
### Date and Time ###
import time #Gets the current time
from pytz import timezone #Allows for timezones to be set. #pytz.all_timezones
from datetime import datetime #Allows for Datetime objects like current ⊔
→Datetime. #datetime.fromisoformat('2021-05-24')
#There's also: np.datetime64('2021-08-01')
#######################
###################
### Mathematics ###
import numpy as np #Working with numeric arrays
print("Numpy version:", np.__version__)
###################
### Statistics and Machine Learning ###
#Utility
from sklearn.preprocessing import OrdinalEncoder, StandardScaler, MinMaxScaler
 ⇒#Various ways of scaling the data
from sklearn.model_selection import train_test_split
#Metrics
from sklearn.metrics import f1_score, precision_score, recall_score,
 →RocCurveDisplay, PrecisionRecallDisplay
from sklearn.metrics import roc auc score
from sklearn.metrics import confusion_matrix
###################
### Dataframes ###
import pandas as pd
##################
#############
### Plots ###
import matplotlib.pyplot as plt #Allows use of Pyplot plots
import seaborn as sns #Allows use of Seaborn plots
sns.set() #Sets default plot theme
from matplotlib.ticker import AutoMinorLocator, MultipleLocator
############
```

```
###########################
### Images / Pictures ###
from PIL import Image
#############################
#########################
### String or Text ###
import json #Can encode or decode JSON string objects
import string #Provides functions for strings
#######################
######################################
### Files, Directories, Folders ###
from pathlib import Path
### Neural Network Libraries ###
#General
import torch
import torch.nn as nn
# from torchsummary import summary
if isgooglecolab:
           !pip install torchinfo
from torchinfo import summary
#Data
from torch.utils.data import Dataset, TensorDataset
#Images
from torchvision import datasets, transforms, models
#Info and configuration
print()
print(f"PyTorch v{torch.__version__}")
IS_GPU_AVAILABLE = torch.cuda.is_available()
print(f"CUDA device available: {IS_GPU_AVAILABLE}")
if (torch.cuda.is_available()):
          print(f"{torch.cuda.device_count()} devices available")
          for n in range(torch.cuda.device_count()):
                    print("\t" + torch.cuda.get_device_name(n))
          print(f"cuda: {torch.cuda.current_device()}") #It can give you information uniformation print(f"cuda: {torch.cuda.current_device()}") #It can give you information print(f"cuda.current_device()}") #It can give you
   → like the GPU is not supported
```

```
print("Num threads set to:", os.cpu_count())
torch.set_num_threads(os.cpu_count())
### Useful functions ###
if "OrigFigSize" not in locals() and "OrigFigSize" not in globals(): #Just in_
 ⇔case Initialisation is re-run after any of these have chaned
   OrigFigSize = plt.rcParams["figure.figsize"]
NonNans = lambda List: List[np.logical_not(np.isnan(List))]
LastNonNan = lambda List: NonNans(List)[-1] if np.sum(np.isnan(List)) <__
 Glen(List) else np.array([]) if type(List) == np.ndarray else []
def ZeroANumber(Number, MaxLength, ForceMaxLength = False):
    """Take a single Number and prepend 'O's to it until it meets MaxLength, or \Box
 _{	o} if ForceMaxLength then also clip digits from the end until it meets_{\sqcup}
 ⇔MaxLength."""
   res = str(Number).zfill(MaxLength)
   if ForceMaxLength: res = res[:MaxLength]
   return res
def SpaceAString(CurString, MaxLength, SpaceTheFront = True, ForceMaxLength = ___
 →False, ForceRemoveFromFront = False):
    """Prepend/Append (SpaceTheFront) spaces to CurString until it meets\sqcup
 GreeMaxLength or if ForceMaxLength also Clip characters from the beginning/
 ⇔end (ForceRemoveFromFront) until it meets ForceMaxLength."""
   CurLen = len(CurString)
   Result = CurString
   if CurLen < MaxLength:</pre>
        if SpaceTheFront:
           Result = (" " * (MaxLength-CurLen)) + CurString
            Result = CurString + (" " * (MaxLength-CurLen))
   elif CurLen > MaxLength and ForceMaxLength:
        if ForceRemoveFromFront:
            Result = CurString[(CurLen - MaxLength):]
        else:
            Result = CurString[:-(CurLen - MaxLength)]
   return Result
def WriteText(TextParsableVar, FullFilePath):
    """Take a string (or string-parsable variable) and save it as text file on_{\sqcup}
 ⇔the directory and with a name indicated by FullFilePath."""
```

```
try:
        DirName = Path(FullFilePath).parent.absolute()
        os.makedirs(DirName, exist_ok = True)
        FileOptions = open(FullFilePath, "w")
        FileOptions.writelines(
            f"{TextParsableVar}"
    except Exception as e:
        print(f"Exception:\n{e}")
    finally:
        try:
            FileOptions.close()
        except Exception:
            pass
SaveText = lambda TextParsableVar, FullFilePath: WriteText(TextParsableVar,
 →FullFilePath) #Alias for WriteText to be the same as Save/Load Variable
def ReadText(FullFilePath):
    """Read the string content of a text file given by FullFilePath and return_{\!\scriptscriptstyle \sqcup}
 ⇔it as a string."""
    with open(FullFilePath, "r+", encoding = "utf8") as io:
        TextString = io.read()
    return TextString
LoadText = lambda FullFilePath: ReadText(FullFilePath) #Alias for ReadText to_
 ⇒be the same as Save/Load Variable
def SaveVariable(Variable, FileName):
    """Create the directory path for and pickle Variable under FileName."""
    DirName = Path(FileName).parent.absolute()
    os.makedirs(DirName, exist_ok = True)
    with open(FileName, 'wb') as io:
        pickle.dump(Variable, io)
def SaveVariableDill(Variable, FileName):
    """Create the directory path for and deep-save Variable under FileName_\sqcup
 ⇔using dill."""
    DirName = Path(FileName).parent.absolute()
    os.makedirs(DirName, exist_ok = True)
    with open(FileName, 'wb') as io:
        dill.dump(Variable, io)
def LoadVariable(FileName):
    """Un-pickle a binary file saved under FileName and return it as a variable.
    with open(FileName, "rb") as io:
        Res = pickle.load(io)
```

```
return Res
def LoadVariableDill(FileName):
    """Read the content of a binary file saved under FileName and return it as \Box
 ⇔a variable."""
    with open(FileName, 'rb') as io:
        Res = dill.load(io)
    return Res
def RemLastLine(s):
    """Remove the last line in the string s."""
    return s[:s.rfind('\n')]
#######################
device = "cuda" if torch.cuda.is_available() else "cpu"
# device = "cpu" #To FORCE CPU
print("device=", device)
Python version: 3.8.13 (default, Mar 28 2022, 06:59:08) [MSC v.1916 64 bit
(AMD64)]
Pickle version: 4.0
Dill version: 0.3.4
Numpy version: 1.21.5
PyTorch v1.11.0
CUDA device available: True
1 devices available
        NVIDIA GeForce RTX 2080 SUPER
cuda: 0
Num threads set to: 48
device= cuda
```

1.2 Architecture

```
[189]: #FeedForward Neural Network
       class Net(nn.Module):
           def <u>init</u> (self, K Length, num units, activation, dropout, usebias):
               super(Net, self).__init__()
               self.K_Length = K_Length
               self.num_units = num_units
               self.activation = activation
               self.dropout = dropout
               self.usebias = usebias
               self.layers = nn.ModuleList([
                   nn.Linear(in_features = self.num_units[0], out_features = self.
        →num_units[1], bias = self.usebias[0]),
```

```
nn.Dropout(p = self.dropout[0], inplace = False),
           self.GetActivationLayer(0),
           nn.Linear(in_features = self.num_units[1], out_features = self.

    unum_units[2], bias = self.usebias[1]),

           nn.Dropout(p = self.dropout[1], inplace = False),
           self.GetActivationLayer(1),
           nn.Linear(in features = self.num units[2], out features = self.

¬num_units[3], bias = self.usebias[2]),
           nn.Dropout(p = self.dropout[2], inplace = False),
           self.GetActivationLayer(2),
          nn.Linear(in_features = self.num_units[3], out_features = self.

→K Length, bias = self.usebias[3])
      1)
  def forward(self, x):
      output = x.view(x.size(0), -1)
      output = self.layers[0](output)
      output = self.layers[1](output)
      output = self.layers[2](output)
      output = self.layers[3](output)
      output = self.layers[4](output)
      output = self.layers[5](output)
      output = self.layers[6](output)
      output = self.layers[7](output)
      output = self.layers[8](output)
      output = self.layers[9](output)
      return output
  def GetActivationLayer(self, layer):
      Result = None
      if (self.activation[layer] == "relu"): #Not differentiable at 0.
→Doesn't need Greedy layer-wise pretraining (Hinton) because it doesn't
⇒suffer from vanishing gradient
           Result = nn.LeakyReLU(ReluAlpha) if ReluAlpha != 0 else nn.ReLU()
⇔#alpha: Controls the angle of the negative slope
      elif (self.activation[layer] == "relu6"):
           Result = nn.ReLU6()
      elif (self.activation[layer] == "elu"): #Like ReLu but allows values to_{\square}
⇒be negative, so they can be centred around 0, also potential vanishing __
⇔gradient on the left side but doesn't matter
           Result = nn.ELU(alpha = EluAlpha) #alpha: Slope on the left side
      elif (self.activation[layer] == "tanh"): #Suffers from Vanishing_
\hookrightarrow Gradient
           Result = nn.Tanh()
      elif (self.activation[layer] == "sigmoid"): #Suffers from Vanishinqu
\hookrightarrow Gradient
```

```
Result = nn.Sigmoid() #Result isn't centred around 0. Maximum_derivative: 0.25
return Result
print("Done")
```

Done

1.3 Dataset Functions

```
[6]: def train_valid_test_split(X_Data, train_size, valid_size, Y_Data = None, __
             →random_state = None, shuffle = True, stratify = None):
                   """Split the dataset, optionally in a stratified manner, into a Train, \sqcup
             ⇔Validation and Test set"""
                   if (type(train_size) == int and sum([train_size, valid_size]) >=__
             Galerian or (type(train_size) != int and sum([train_size, valid_size])∪
                           raise ValueError(f"The train_size [{train_size}] + the valid_size_
             →[{valid_size}] should sum up to less than 100% so that there's some_
             →percentage left for the test set")
                   TrainIdx, ValidTestIdx = train_test_split(np.arange(len(X_Data)),_
             →train_size = train_size, shuffle = shuffle, stratify = stratify, □
             →random_state = random_state)
                                         = X_Data[TrainIdx]
                   ValidTestX = X_Data[ValidTestIdx]
                   if Y_Data is not None:
                                               = Y_Data[TrainIdx]
                           TrainY
                           ValidTestY = Y_Data[ValidTestIdx]
                   if type(train_size) != int: #For the 2nd split we need the validation_
             →percent relative to the Valid/Test portion of the dataset alone
                           test size = 1 - train size - valid size #Actual test size
                           valid_size = 1 - (test_size / (valid_size + test_size)) #Relative (tou
             → ValidTest) valid size
                           test_size = 1 - valid_size #Relative (to ValidTest) test size
                   if Y Data is not None:
                           ValidX, TestX, ValidY, TestY = train test split(ValidTestX, ValidTestY, ...
             ⇒stratify[ValidTestIdx] if stratify is not None else None, random_state =
             →random_state)
                           return TrainX, ValidX, TestX, TrainY, ValidY, TestY
                   else:
                            ValidX, TestX = train_test_split(ValidTestX, train_size = valid_size,_
             ⊸shuffle = shuffle, stratify = stratify[ValidTestIdx] if stratify is not None of the stratific is not None of None 
              ⇔else None, random_state = random_state)
```

```
return TrainX, ValidX, TestX
```

```
[40]: def Scale(x_data, scaler_mean, scaler_sd, verbose = True):
          """Scale a Torch Tensor or Numpy Array to have zero mean and unit variance.
          if isinstance(x_data, torch.Tensor):
              if (isinstance(scaler_mean, np.number) or isinstance(scaler_sd, np.
       →number)) and x_data.shape[1] != 1:
                  if verbose:
                      print("Info: Scaler is a scalar but X's observations are not. ...
       Safely ignore this if you intended to normalise with scalar parameters.")
                  return ((x_data - scaler_mean) / scaler_sd).float()
              else:
                  return ((x_data - torch.from_numpy(scaler_mean)) / torch.
       →from_numpy(scaler_sd)).float()
          elif isinstance(x data, np.ndarray):
              if verbose and (isinstance(scaler_mean, np.number) or_
       ⇒isinstance(scaler_sd, np.number)) and x_data.shape[1] != 1:
                  print("Info: Scaler is a scalar but X's observations are not.
       Safely ignore this if you intended to normalise with scalar parameters.")
              return ((x_data - scaler_mean) / scaler_sd).astype(np.float32)
          else:
              raise Exception ("Cannot scale the variable because it is neither a_{\sqcup}
       →Torch Tensor nor a Numpy Array")
              return None
      def UnScale(x_data, scaler_mean, scaler_sd, verbose = True):
          """Inverse the scaling of a Torch Tensor or Numpy Array that currently have
       ⇔zero mean and unit variance."""
          if isinstance(x data, torch.Tensor):
              if (isinstance(scaler_mean, np.number) or isinstance(scaler_sd, np.
       →number)) and x_data.shape[1] != 1:
                  if verbose:
                      print("Info: Scaler is a scalar but X's observations are not. __
       Safely ignore this if you intended to normalise with scalar parameters.")
                  return ((x_data * scaler_sd) + scaler_mean).float()
              else:
                  return ((x_data * torch.from_numpy(scaler_sd)) + torch.
       →from_numpy(scaler_mean)).float()
          elif isinstance(x_data, np.ndarray):
              if verbose and (isinstance(scaler_mean, np.number) or_
       ⇒isinstance(scaler_sd, np.number)) and x_data.shape[1] != 1:
                  print("Info: Scaler is a scalar but X's observations are not.")
       -Safely ignore this if you intended to normalise with scalar parameters.")
              return ((x_data * scaler_sd) + scaler_mean).astype(np.float32)
          else:
```

```
1.4 Optimisation Functions
[7]: def ClassAccMulti(Targets, Preds, K):
         """Calculate the Class-Wise accuracy for a multi-class task"""
         return(np.mean([(Targets == k) == (Preds == k) for k in range(K)]))
[8]: def AccCalculation(Y_Hat, Targets):
         """Calculate the Accuracy given the Actual values and Predictions for |
      →Binary and Multiclass Classification."""
         if isinstance(Targets, torch.Tensor):
             Targets = Targets.cpu().numpy()
         if isinstance(Y_Hat, torch.Tensor):
             Y_Hat = Y_Hat.cpu().numpy()
         return np.mean(Y_Hat == Targets)
[9]: def AUCCalculation(Targets, Y_Prob, Y_Hat, Verbose = True):
         """Calculate the Area Under the Receiver Operating Characteristic Curve_\sqcup
      _{
ightarrow q} qiven the Actual values and Predictions for Binary and Multiclass_{\sqcup}
      →Classification using sklearn's roc_auc_score()."""
         if isinstance(Targets, torch.Tensor):
             Targets = Targets.cpu().numpy()
         if isinstance(Y Prob, torch.Tensor):
             Y_Prob = Y_Prob.cpu().numpy()
         if isinstance(Y_Hat, torch.Tensor):
             Y_Hat = Y_Hat.cpu().numpy()
         try:
             CurMetric2 = roc_auc_score(Targets, Y_Prob, multi_class = "ovr", __
      →average = 'weighted') #Calculating Weighted AUC #Cares for performance both
      in Positives and Negatives (but may not fare well with heavy class imbalance)
         except Exception as exc:
             CurMetric2 = np.nan
             if Verbose:
                 warnings.warn(f"\nAn error occurred in AUC calculation (probably,
      ⇒because of missing classes in the random batch of data?).\nThe error reads:⊔
                 print("AUC Warning. set(Targets):", list(set(Targets.reshape(-1))), u
```

¬"set(Outputs): ", list(set(Y_Hat.reshape(-1))))

```
return CurMetric2
[10]: def F1ScoreCalculation(Targets, Y_Hat):
          """Calculate the F1 score given the Actual values and Predictions for \Box
       →Binary and Multiclass Classification using sklearn's f1_score()."""
          if isinstance(Targets, torch.Tensor):
              Targets = Targets.cpu().numpy()
          if isinstance(Y_Hat, torch.Tensor):
              Y_Hat = Y_Hat.cpu().numpy()
          try:
              CurMetric3 = f1_score(Targets, Y_Hat, average = 'weighted')_
       ⊶#Calculating Weighted F1 #Cares about balance between Precision and Recall
       → (Sensitivity)
          except Exception as exc:
              CurMetric3 = np.nan
              warnings.warn(f"\nAn error occurred in F1 score calculation (probably⊔
       \hookrightarrowbecause of missing classes in the random batch of data?).\nThe error reads:\sqcup
       →{exc}")
          return CurMetric3
[11]: def PrintIterationMetrics(it, epochs, t0, train loss, test loss, first metric,
       first_metric_Name, second_metric, second_metric_Name, third_metric,_u
       htird_metric_Name, MaxTrainLossLen, MaxTestLossLen, MaxMetric1Len,
       →MaxMetric2Len, MaxMetric3Len):
          """Print information about the Current Epoch, Train/Test losses as well as \sqcup
```

```
def PrintIterationMetrics(it, epochs, t0, train_loss, test_loss, first_metric,_u

first_metric_Name, second_metric, second_metric_Name, third_metric,_u

third_metric_Name, MaxTrainLossLen, MaxTestLossLen, MaxMetric1Len,_u

MaxMetric2Len, MaxMetric3Len):

"""Print information about the Current Epoch, Train/Test losses as well as_u

metrics and duration, and return the Max length of each metric viewed as a_u

string in order to keep a consistent text alignment amongst consecutive_u

epochs."""

dt = datetime.now() - t0

strTrainLoss = f"{train_loss:.4f}"

strMetric1 = f'{first_metric:.3f}'

strMetric2 = f'{second_metric:.3f}'

if it == 0:

MaxTrainLossLen = len(strTrainLoss)

MaxTestLossLen = len(strTestLoss)

MaxMetric1Len = len(strMetric1)

MaxMetric2Len = len(strMetric2)

MaxMetric3Len = len(strMetric3)
```

```
print(f'Epoch {ZeroANumber(it+1, len(str(epochs)))}/{epochs}, Train Loss:
       SpaceAString(strTrainLoss, MaxTrainLossLen)}, Test Loss:
⊔
       →{SpaceAString(strTestLoss, MaxTestLossLen)} | {first_metric_Name}:
       SpaceAString(strMetric1, MaxMetric1Len)}, {second_metric_Name}:⊔
       →{SpaceAString(strMetric2, MaxMetric1Len)}, {third_metric_Name}:__
       →{SpaceAString(strMetric3, MaxMetric1Len)}, Duration: {dt}')
         return MaxTrainLossLen, MaxTestLossLen, MaxMetric1Len, MaxMetric2Len,
       →MaxMetric3Len
[12]: def UpdateMetricsAndSaveModel(model, train_loss, test_loss, train_best_loss,__
       otest_best_loss, CurMetric1, Metric1, CurMetric2, Metric2, CurMetric3,
       →Metric3):
         →update best performance metrics to reflect this model's."""
         if (test_loss < test_best_loss): #Saving the model if it outperforms⊔
       ⇔previous iteration's model
             test_best_loss = test_loss
             train best loss = train loss
             torch.save(model.state_dict(), f"model_dict.pt") #Saving Model's_
       \hookrightarrow Dictionary
             if np.isfinite(CurMetric1) and CurMetric1 >= Metric1:
                 Metric1 = CurMetric1
                 Metric2 = CurMetric2
                 Metric3 = CurMetric3
                 torch.save(model.state_dict(), f"acc_model_dict.pt") #Savinq_
       → Model's Dictionary
         return train_best_loss, test_best_loss, Metric1, Metric2, Metric3
```

```
[14]: def TrainModel(model, optimiser, criterion, X_Train, Y_Train):
    """Train by calculating the gradients and taking one step."""
    model.train() #Putting model in training mode so that things like dropout()
    ⊶are activated again
```

```
optimiser.zero_grad() #Initialisation of the gradient of
          outputs = model(X_Train) #Getting the prediction using the forward_
       ⇔direction of the Neural Net
          loss = criterion(outputs, Y_Train) #Calculating the loss according to the
       ⇔loss function
          loss.backward() #Calculating the Gradient \Delta of the loss function with
       →respect to the parameters
          optimiser.step() #Calculates and updates the parameters using gradient
       \hookrightarrow descent, as = - *\Delta
          return optimiser, outputs, loss
[15]: def EvaluateModelFromPreds(criterion, Y_Prob, Targets, Verbose):
          """Use the forward direction of the model following with a
       \hookrightarrow sigmoid+threshold or softmax+argmax for binary or multiclass classification \sqcup
       \negrespectively, and calculate and return the predictions and evaluation\sqcup
       ⇔metrics."""
          with torch.no_grad(): #Making sure that we don't update the gradient ∪
       →outside the training part
              loss_scalar = criterion(Y_Prob, Targets).item() #Calculating the loss_
       →according to the loss function
              Y_Prob = nn.Softmax(dim = 1)(Y_Prob) #dim: every slice along dim will_
       ⇔sum to 1
               , Y Hat = torch.max(Y Prob, 1) #Prediction. torch.max returns both max
       \rightarrow (value) and argmax (index)
              CurMetric1, CurMetric2, CurMetric3 = GetCategoricalMetrics(Y_Prob,_

¬Y_Hat, Targets, Verbose = Verbose)
              return loss_scalar, CurMetric1, CurMetric2, CurMetric3
[16]: def EvalForwardPass(model, inputs, criterion = None, Targets = None): #This is_
       ⇔used at the very end on "Evaluation" Section. Unifies the forward pass, but⊔
       →doesn't calculate loss/metrics like EvaluateModel() does as we need greater
       \hookrightarrow granularity.
           """Use the forward direction of the model, potentially following with a_{\!\scriptscriptstyle \sqcup}
       \hookrightarrow sigmoid+threshold or softmax+argmax for binary or multiclass classification \sqcup
       ⇔respectively."""
          if Targets is not None and criterion is None:
              warnings.warn(f"\nTargets are present but loss cannot be calculated ∪
       ⇔because criterion is None.")
```

```
model.eval() #Putting model in evaluation mode so that things like
       ⇔dropout() are deactivated
          with torch.no_grad(): #Making sure that we don't update the gradient_
       →outside the training part
              Y_Prob = model(inputs) #Getting the prediction using the forward ⊔
       ⇔direction of the Neural Net
              if Targets is not None:
                  loss_scalar = criterion(Y_Prob, Targets).item() #Calculating the_
       ⇔loss according to the loss function
              Y Prob = nn.Softmax(dim = 1)(Y Prob) #dim: every slice along dim will
       ⇔sum to 1
              _, Y_Hat = torch.max(Y_Prob, 1) #Prediction. torch.max returns both max_
       \hookrightarrow (value) and argmax (index)
          if Targets is not None:
              return Y_Prob, Y_Hat, loss_scalar
          else:
              return Y_Prob, Y_Hat
[17]: def FixFormatAndDTypes(device, Inputs, Targets):
          """Ensure that the Inputs and Targets are Torch Tensors and of the correct_{\sqcup}
       ⇒shape and dtype before returning them."""
          if isinstance(Inputs, np.ndarray):
              Inputs = torch.from_numpy(Inputs)
          if isinstance(Targets, np.ndarray):
              Targets = torch.from_numpy(Targets)
```

Inputs = Inputs.to(device) Targets = Targets.to(device) Targets = Targets.long() return Inputs, Targets

1.5 Evaluation Functions

```
[18]: def plot_confusion_matrix(cm, classes, normalise = False, title = 'Confusion_
       →matrix', colourmap = plt.cm.Blues):
          """Plot the Confusion Matrix object returned by sklearn's_{\sqcup}
       ⇒confusion_matrix() and normalise it if normalise==True."""
          plt.grid(False)
          if normalise:
              print('Confusion matrix')
              print(cm)
```

```
cm = cm.astype('float') / cm.sum(axis = 1)[:, np.newaxis]
        plt.imshow(cm, interpolation = 'nearest', cmap = colourmap)
        plt.clim(0.0, 1.0)
        plt.imshow(cm, interpolation = 'nearest', cmap = colourmap)
    plt.title(title)
    with warnings.catch_warnings():
        warnings.simplefilter("ignore")
        plt.colorbar()
    tick_marks = np.arange(len(classes))
    plt.xticks(tick_marks, classes, rotation = 45)
    plt.yticks(tick_marks, classes)
    fmt = '.2f' if normalise else 'd'
    thresh = cm.max() / 2.
    for i, j in itertools.product(range(cm.shape[0]), range(cm.shape[1])):
        plt.text(j, i, format(cm[i, j], fmt),
                 horizontalalignment = "center",
                 color = "white" if cm[i, j] > thresh else "black")
    plt.tight_layout()
    plt.ylabel('True label')
    plt.xlabel('Predicted label')
    plt.show()
def PlotHistory (Train_History, Test_History = None, Key = "Loss", figsize = Loss"
 →(12, 8), MajorLineStyle = "--", MinorLineStyle = ":", MajorLines = 10, ⊔

→MinorInbetweenLinesEvery = 4, test_alpha = 1.0):
    """Plot a juxtaposition of a Train and Test metric (parametrised by Key),\Box
 ousually 'Loss'"""
    fig, ax = plt.subplots(figsize = figsize)
    plt.plot(Train_History, label = f"Train {Key}")
    if (Test_History is not None):
        plt.plot(Test History, label = f"Test {Key}", alpha = test alpha)
    xfrom, xto = ax.get_xlim()
    yfrom, yto = ax.get_ylim()
    ax.xaxis.set_major_locator(MultipleLocator(int(np.ceil((xto-xfrom)/
 →MajorLines))))
    ax.yaxis.set_major_locator(MultipleLocator((yto-yfrom)/MajorLines))
    ax.xaxis.set_minor_locator(AutoMinorLocator(MinorInbetweenLinesEvery))
    ax.yaxis.set_minor_locator(AutoMinorLocator(MinorInbetweenLinesEvery))
    ax.grid(which = 'major', color='#FFFFFF', linestyle = MajorLineStyle)
    ax.grid(which = 'minor', color='#CCCCCC', linestyle = MinorLineStyle)
    plt.legend()
    plt.show()
    return None
```

```
def PlotAllMetrics(Titles, TrainMetrics, TestMetrics = None, figsize = [19, ⊔
       \hookrightarrow13], test_alpha = 1.0):
          fig, ((ax1, ax2), (ax3, ax4)) = plt.subplots(2, 2, figsize = figsize)
          ax1.set title(Titles[0])
          ax1.plot(TrainMetrics[0], label = f"Train")
          if TestMetrics is not None:
              ax1.plot(TestMetrics[0], label = f"Test", alpha = test_alpha)
          ax1.legend()
          ax2.set_title(Titles[1])
          ax2.plot(TrainMetrics[1], label = f"Train")
          if TestMetrics is not None:
              ax2.plot(TestMetrics[1], label = f"Test", alpha = test_alpha)
          ax2.legend()
          ax3.set_title(Titles[2])
          ax3.plot(TrainMetrics[2], label = f"Train")
          if TestMetrics is not None:
              ax3.plot(TestMetrics[2], label = f"Test", alpha = test alpha)
          ax3.legend()
          ax4.set title(Titles[3])
          ax4.plot(TrainMetrics[3], label = f"Train")
          if TestMetrics is not None:
              ax4.plot(TestMetrics[3], label = f"Test", alpha = test_alpha)
          ax4.legend()
          plt.show()
          return None
[19]: def GetCategoricalMetrics(Y_Prob, Y_Hat, Targets, Verbose = True):
          """Calculate Categorical variable metrics (Accuracy, Area Under the Curve,_{\sqcup}
       _{\circ}F1 score) given the class Probability vector (binary) / matrix (multiclass),_{\sqcup}
       \hookrightarrow the class index (0 to K-1), and the Actual values."""
          test_Acc = AccCalculation(Y_Hat, Targets)
          test_AUC = AUCCalculation(Targets, Y_Prob, Y_Hat, Verbose = Verbose)
          test_F1 = F1ScoreCalculation(Targets, Y_Hat)
          return test_Acc, test_AUC, test_F1
[20]: def PlotCategoricalMetrics(Y_Hat, Targets, ClassNames, normalise, figsize = ___
       →None):
          """Plots the Confusion matrix given the class index (0 to K-1), and the \Box
       ⇔Actual values."""
          PrevFigSize = plt.rcParams['figure.figsize']
          plt.rcParams['figure.figsize'] = figsize if figsize is not None else⊔
       →PrevFigSize
          cm = confusion_matrix(Targets, Y_Hat)
          plot_confusion_matrix(cm, ClassNames, normalise = normalise)
```

```
plt.rcParams['figure.figsize'] = PrevFigSize
[21]: def EvalPredict(model, device, test_loader_or_X_Test):
          """Use EvalForwardPass() to use the forward direction of the model and \Box
       ⇒return the Y_probability, Y_Hat, and respective Y given X."""
          Preds_prob = []
          Preds = []
          Targets = []
          for inputs, targets in tqdm(test_loader_or_X_Test, total =_
       →len(test_loader_or_X_Test), leave = False):
              inputs, targets = FixFormatAndDTypes(device, inputs, targets)
              outputs prob, outputs = EvalForwardPass(model, inputs, criterion = ____
       ⇔None, Targets = None)
              Preds_prob.append(outputs_prob)
              Preds.append(outputs)
              Targets.append(targets)
          Preds_prob = torch.cat(Preds_prob).cpu().numpy()
          Preds = torch.cat(Preds).cpu().numpy()
          Targets = torch.cat(Targets).cpu().numpy()
          del inputs
          del outputs prob
          del outputs
          del targets
          if IS_GPU_AVAILABLE:
              torch.cuda.empty_cache()
          return Preds_prob, Preds, Targets
```

1.6 Gradient Descent Functions

```
[22]: def batch_gd(model, device, criterion, optimiser, scheduler, train_loader, u

test_loader, epochs, PrintInfoEverynEpochs, train_best_loss, test_best_loss, u

BestMetric1, BestMetric2, BestMetric3, Verbose = True):

"""Use the Train, Evaluation, Metrics calculation and printing functions to u

train a model over certain epochs taking steps in every batch and keeping u

track of the metrics on each epoch as well as the overall best metrics"""

MaxTrainLossLen, MaxTestLossLen, MaxMetric1Len, MaxMetric2Len, u

MaxMetric3Len = None, None, None, None #For output text formatting

start_time = time.time() #To calculate the duration of the whole learning u

procedure

model.to(device) #If there is a GPU, let's ensure model is sent to the GPU u

□
```

```
#Initialising the Metrics
      train_losses, test_losses, train_metric1s, train_metric2s, train_metric3s,__
 stest metric1s, test_metric2s, test_metric3s = np.repeat(np.nan, epochs), np.
 repeat(np.nan, epochs), np.repeat(np.nan, epochs), np.repeat(np.nan, up.nan, 
depochs), np.repeat(np.nan, epochs), np.repeat(np.nan, epochs), np.repeat(np.
→nan, epochs), np.repeat(np.nan, epochs)
      for it in range(epochs):
               t0 = datetime.now() #To calculate the duration of the current epoch
               ProbsTrain = []
               TargetsTrain = []
               Probs = []
               Targets = []
               #== Training ==#
               for inputs, targets in train loader:
                  for inputs, targets in tqdm(train_loader, total = len(train_loader), ___
\hookrightarrow leave = False):
                        inputs, targets = FixFormatAndDTypes(device, inputs, targets)
→#Making sure we have Tensors of the correct Format and Data Type
                        optimiser, outputs, loss = TrainModel(model, optimiser, criterion,
 ⇔inputs, targets) #Training the model on Train set
                        #This loss includes dropout() and stuff as it was not done under_
→model.eval()
                        ProbsTrain.append(outputs.cpu())
                        TargetsTrain.append(targets.cpu())
                        del inputs, targets, outputs
               ProbsTrain = torch.cat(ProbsTrain)
               TargetsTrain = torch.cat(TargetsTrain)
               train loss, CurTrainMetric1, CurTrainMetric2, CurTrainMetric3 = 1
→EvaluateModelFromPreds(criterion, ProbsTrain, TargetsTrain, Verbose =
→Verbose) #Evaluating the model on Train set
               #== Evaluation ==#
               for inputs, targets in test_loader:
                   for inputs, targets in tqdm(test_loader, total = len(test_loader), u
\hookrightarrow leave = False):
                        inputs, targets = FixFormatAndDTypes(device, inputs, targets)
→#Making sure we have Tensors of the correct Format and Data Type
                        Y_Prob, _ = EvalForwardPass(model, inputs)
                       Probs.append(Y_Prob.cpu())
                        Targets.append(targets.cpu())
```

```
del inputs, targets, Y_Prob#, Y_Hat
      Probs = torch.cat(Probs)
      Targets = torch.cat(Targets)
      test_loss, CurMetric1, CurMetric2, CurMetric3 =_
⊸EvaluateModelFromPreds(criterion, Probs, Targets, Verbose = Verbose)
→#Evaluating the model on Evaluation set
      if np.any(np.logical_or(torch.isinf(Probs).cpu().numpy(), torch.
→isnan(Probs).cpu().numpy())):
          print(f"!Predictions contain infinities ({np.mean(np.logical or(np.
→isinf(Probs), np.isnan(Probs))) * 100:.2f}%); Stopping!")
          break
      if np.logical_or(np.isinf(test_loss), np.isnan(test_loss)):
          print("!Loss is Infinite; Stopping!")
          break
      if scheduler is not None:
           if list(scheduler.keys())[0].lower() == "Plateau".lower():
               scheduler[list(scheduler.keys())[0]].step(test_loss)
          elif list(scheduler.keys())[0].lower() == "StepLR".lower():
               scheduler[list(scheduler.keys())[0]].step()
       #Saving the metrics
      train_losses[it], train_metric1s[it], train_metric2s[it],
utrain_metric3s[it], test_losses[it], test_metric1s[it], test_metric2s[it],
ctest_metric3s[it] = train_loss, CurTrainMetric1, CurTrainMetric2,
→CurTrainMetric3, test_loss, CurMetric1, CurMetric2, CurMetric3
      if (it + 1) % PrintInfoEverynEpochs == 0 or it == 0 or it == epochs - 1:
          MaxTrainLossLen, MaxTestLossLen, MaxMetric1Len, MaxMetric2Len,
→MaxMetric3Len = PrintIterationMetrics( #Prints Iteration Metrics
               it, epochs, t0, train_loss, test_loss,
               CurMetric1, "Acc",
               CurMetric2, "AUC",
              CurMetric3, "F1",
              MaxTrainLossLen, MaxTestLossLen,
              MaxMetric1Len, MaxMetric2Len, MaxMetric3Len
          )
      train_best_loss, test_best_loss, BestMetric1, BestMetric2, BestMetric3_
→= UpdateMetricsAndSaveModel(model, train_loss, test_loss, train_best_loss, __
→test_best_loss, CurMetric1, BestMetric1, CurMetric2, BestMetric2, 
CurMetric3, BestMetric3) #Updating Metrics and Saving the model if it_
→outperforms previous iteration's model
```

2 Data

```
[23]: #Configuring the basic structure of our current directory
path_root = f"{os.getcwd()}"
path_data = f"{Path(path_root).absolute()}/Data"
path_models = f"{path_root}/Models"
print(path_root)
print(path_data)
print(path_models)
```

D:\GiannisM\Downloads\Exercises\Fiver\100. frotribe FFNN Multiclass Classification

D:\GiannisM\Downloads\Exercises\Fiver\100. frotribe FFNN Multiclass Classification/Data

```
## Data Hyperparameters ####
     Seed
                  = 42
     batch_size
                  = 256
                 = 0.8
     TrainPerc
     ValidPerc
                  = 0.1
                  = 1 - TrainPerc - ValidPerc
     TestPerc
     CustomNAString = None
     ###################################
     #######################
     ### Reading the Data ###
     Classes = ['drinking water', 'smoking', 'standing up', 'sit down', 'mopping the_
      ⇒floor', 'sweeping the floor', 'walking', 'unknown']
     XY_DF = pd.read_csv(f"{path_data}/11-16 (1).csv", header = None)
     display(XY_DF)
     #######################
     #####################
     ### Handling NAs ###
     NBeforeCustomNADrop = None
     DroppedCustomNARows = None
```

```
NBeforeNADrop = len(XY_DF)
XY_DF = XY_DF.dropna()
DroppedNARows = NBeforeNADrop - len(XY_DF)
if DroppedNARows > 0:
   print(f"Dropped NA rows count: {DroppedNARows} (out of {NBeforeNADrop})")
if CustomNAString is not None:
   NBeforeCustomNADrop = len(XY_DF)
   XY DF = XY DF.replace(CustomNAString, np.nan, regex = False).dropna()
   DroppedCustomNARows = NBeforeCustomNADrop - len(XY_DF)
   if DroppedCustomNARows > 0:
       print(f"Dropped custom NA rows count: {DroppedCustomNARows} (out of

√{NBeforeCustomNADrop})", )
if DroppedNARows > 0 or (DroppedCustomNARows is not None and_
 →DroppedCustomNARows > 0):
   print()
#####################
### Creating Train/Valid/Test sets ###
X_Data = XY_DF.iloc[:, 1:].values.astype(np.float32)
Y_Data = XY_DF.iloc[:, 0 ].values.astype(int).squeeze() - 1
Labels_Data = np.array([Classes[y] for y in Y_Data])
#==Stratified Split
TrainIndx, ValidIndx, TestIndx = train valid test split(np.arange(X Data.
shape[0]), train_size = TrainPerc, valid_size = ValidPerc, Y_Data = None,
→random_state = Seed, shuffle = True, stratify = Y_Data)
X Train
           =
                  X_Data[TrainIndx]
Y_Train
                   Y_Data[TrainIndx]
Labels_Train = Labels_Data[TrainIndx]
X_Valid
                  X_Data[ValidIndx]
Y Valid
                  Y_Data[ValidIndx]
Labels_Valid = Labels_Data[ValidIndx]
X_Test
           =
                  X_Data[TestIndx ]
Y Test
                  Y_Data[TestIndx ]
Labels Test = Labels Data[TestIndx ]
###########################
### Scaling the Data ###
\# scaler = LoadVariable(f"{SaveFolder}/scaler") \#After loading a model with a_{\sqcup}
different scaler we need to re-run this using the newly loaded scaler.
\# print("\n\n\n!!!!!!!!\nDEBUGGING:\nScaling with SaveFolder scaler!!!\n!!!!
 \hookrightarrow !!!!!!!\n\n\n")
```

```
# if os.path.exists(f"{path_models}/scaler"):
    print("!! \ n!! \ Using \ saved \ scaler. \ n!! \ n")
     scaler = LoadVariable(f"{path_models}/scaler")
# else:
scaler = StandardScaler(with_mean = True, with_std = True).fit(X_Train)
SaveVariable(scaler, f"{path_models}/scaler")
scaler_mean = scaler.mean_
scaler sd = scaler.scale
scaler_mean_sd = (scaler_mean, scaler_sd)
#Numpy takes care of the broadcasting automatically
X Train = Scale(X Train, *scaler mean sd)
X_Valid = Scale(X_Valid, *scaler_mean_sd)
X_Test = Scale(X_Test , *scaler_mean_sd)
############################
# ### Creating Dataset/Dataloader ###
Dataset_Train = TensorDataset(torch.from_numpy(X_Train), torch.

¬from_numpy(Y_Train))
Dataset Valid = TensorDataset(torch.from numpy(X Valid), torch.
 →from_numpy(Y_Valid))
Dataset_Test = TensorDataset(torch.from_numpy(X_Test ), torch.
→from_numpy(Y_Test ))
Loader Train = torch.utils.data.DataLoader(
    dataset = Dataset_Train,
    batch_size = batch_size,
    shuffle = True,
    pin_memory = True
Loader_Valid = torch.utils.data.DataLoader(
    dataset = Dataset_Valid,
    batch_size = batch_size,
    shuffle = False,
    pin_memory = True
Loader Test = torch.utils.data.DataLoader(
    dataset = Dataset_Test,
    batch size = batch size,
    shuffle = False,
    pin memory = True
# ####################################
```

```
### Extracting Information ###
tmpx, tmpy = next(iter(Loader_Valid))
K_Length, O_Length, N, D_Length, H1, W1 = len(set(Y_Train.squeeze().tolist())),__
→1, len(Y_Train), tmpx.shape[1], 1, 1
print(f"X Data.shape : {(len(X Data ), *tmpx.shape[1:])} min: {X Data.min():.
 print(f"X_Train.shape: {(len(X_Train), *tmpx.shape[1:])} min: {X_Train.min():.
 print(f"X_Valid.shape: {(len(X_Valid), *tmpx.shape[1:])} min: {X_Valid.min():.
 →2f} max: {X_Valid.max():.2f} Y_Valid.shape: {Y_Valid.shape}")
print(f"X Test.shape : {(len(X_Test ), *tmpx.shape[1:])} min: {X_Test.min():.
 print(f"K_Length: {K_Length}")
print(f"N: {N} H1: {H1} W1: {W1} D_Length: {D_Length}")
plt.rcParams['figure.figsize'] = [13, 4]
print(f"\nClasses:")
sns.countplot(x = [Classes[int(y)] for y in sorted(Y_Data.squeeze())])
plt.show()
CountData = sorted(Counter(Y_Data.squeeze()).items())
FreqKeys = [kv[0] for kv in CountData]
FreqData = np.array([kv[1] for kv in CountData]) / len(Y Data) * 100
for i in range(len(FreqData)):
   print(f"{FreqKeys[i]}: {SpaceAString(f'{FreqData[i]:.2f}', MaxLength = 5)}%__
 print(f"\nClasses [TRAIN]:")
sns.countplot(x = [Classes[int(y)] for y in sorted(Y_Train.squeeze())])
plt.show()
print(f"\nClasses [Valid]:")
sns.countplot(x = [Classes[int(y)] for y in sorted(Y_Valid.squeeze())])
plt.show()
print(f"\nClasses [Test ]:")
sns.countplot(x = [Classes[int(y)] for y in sorted(Y_Test.squeeze() )])
plt.show()
CountTrain = sorted(Counter(Y Train.squeeze()).items())
FreqTrain = np.array([kv[1] for kv in CountTrain]) / len(Y_Train) * 100
CountValid = sorted(Counter(Y Valid.squeeze()).items())
FreqValid = np.array([kv[1] for kv in CountValid]) / len(Y_Valid) * 100
CountTest = sorted(Counter(Y Test.squeeze()).items())
FreqTest = np.array([kv[1] for kv in CountTest ]) / len(Y_Test ) * 100
```

```
for i in range(len(FreqKeys)):
    print(f"{FreqKeys[i]}: Train {SpaceAString(f'{FreqTrain[i]:.2f}', MaxLengthu
 -= 5)}% [{SpaceAString(f'{CountTrain[i][1]}', MaxLength = 5)}], Valid

¬{SpaceAString(f'{FreqValid[i]:.2f}', MaxLength = 5)}%

□

 SpaceAString(f'{FreqTest[i]:.2f}', MaxLength = 5)}%⊔
 print("\nDone")
     0
               1
                        2
                                 3
                                           4
                                                    5
                                                              6
                                                                   \
0
        1 0.147911 0.133120 0.025052 -0.070056 -0.060896 -0.121567
1
        1 0.096198 -0.066323 -0.180289 -0.175182 -0.108132 -0.080090
2
        1 - 0.500452 - 0.502092 - 0.475572 - 0.425861 - 0.389736 - 0.402447
3
        1 -0.307718 -0.320017 -0.344007 -0.309607 -0.289414 -0.333693
4
        1 -0.103104 -0.148786 -0.189899 -0.093382 0.025787
                                                          0.158881
        8 -0.064396 -0.178618 -0.246944 -0.049874
                                                          0.079402
4830
                                                0.179200
                                                0.011479
4831
                    0.049382 0.134941
                                       0.065425
                                                          0.212872
        8 0.117115
4832
        8 0.213987
                    0.145185
                             0.117739
                                       0.140440
                                                0.290152
                                                          0.308540
4833
        8 0.088052
                    0.105103 -0.000214
                                       0.090305
                                                0.115749
                                                          0.151577
4834
        8 0.115733 0.043828 0.224749
                                       0.098849
                                                0.132058
                                                          0.092996
                                    1191
                                          1192
                                               1193
                                                     1194 1195
                  8
                                                                1196 \
0
    -0.098642 -0.011251 -0.005818
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                                                 0.0
                                     0.0
                                                0.0
                                                      0.0
1
     0.250950 -0.125172 0.287903
                                           0.0
                                                            0.0
                                                                 0.0
2
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                                 0.0
    -0.495722 -0.568901 -0.576617
                                                            0.0
3
    -0.414461 -0.556066 -0.711506
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                                                 0.0
4
     0.220521 0.142476 0.063623
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                                                 0.0
4830
     0.045606
              0.273751 0.224829
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                                                 0.0
                                                                 0.0
4831 0.394126 0.320238 0.258048
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                     0.0
4832 0.079455
               0.088747
                        0.010922
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                                                 0.0
4833
               0.152081 -0.005337
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
                                                            0.0
                                                                 0.0
     0.101945
4834
                                     0.0
                                           0.0
                                                0.0
                                                      0.0
     0.096625 0.142984 0.051117
                                                            0.0
                                                                 0.0
                      1200
     1197
           1198
                1199
0
      0.0
            0.0
                 0.0
                       0.0
                 0.0
                       0.0
1
      0.0
            0.0
2
      0.0
            0.0
                 0.0
                       0.0
3
      0.0
            0.0
                  0.0
                       0.0
4
      0.0
                  0.0
                       0.0
            0.0
                 0.0
                       0.0
4830
      0.0
            0.0
4831
      0.0
            0.0
                  0.0
                       0.0
4832
      0.0
            0.0
                  0.0
                       0.0
```

```
4833 0.0 0.0 0.0 0.0
4834 0.0 0.0 0.0 0.0
```

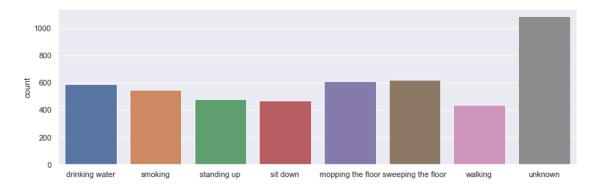
[4835 rows x 1201 columns]

X_Data.shape : (4835, 1200) min: -40.75 max: 49.11 Y_Data.shape : (4835,)
X_Train.shape: (3868, 1200) min: -48.25 max: 51.08 Y_Train.shape: (3868,)
X_Valid.shape: (483, 1200) min: -54.38 max: 36.09 Y_Valid.shape: (483,)
X_Test.shape : (484, 1200) min: -26.58 max: 37.10 Y_Test.shape : (484,)

K_Length: 8

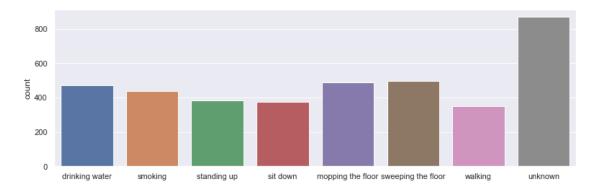
N: 3868 H1: 1 W1: 1 D_Length: 1200

Classes:

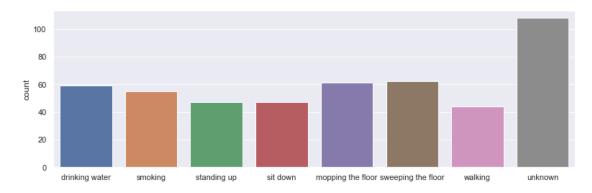


0: 12.18% [589] 1: 11.35% [549] 2: 9.87% [477] 3: 9.64% [466] 4: 12.57% [608] 5: 12.86% [622] 6: 9.06% [438] 7: 22.46% [1086]

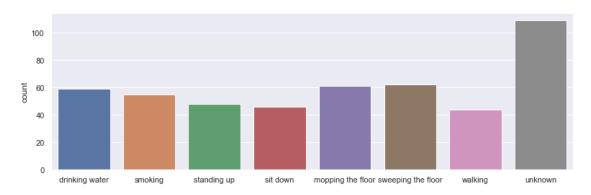
Classes [TRAIN]:



Classes [Valid]:



Classes [Test]:



```
0: Train 12.18% [ 471], Valid 12.22% [
                                         59], Test 12.19% [
                                                              59]
1: Train 11.35% [ 439], Valid 11.39% [
                                         55], Test 11.36% [
                                                              55]
                  382], Valid 9.73% [
                                         47], Test 9.92% [
2: Train 9.88% [
                                                              48]
3: Train 9.64% [
                  373], Valid 9.73% [
                                         47], Test 9.50% [
                                                              46]
4: Train 12.56% [ 486], Valid 12.63% [
                                         61], Test 12.60% [
                                                              61]
                  498], Valid 12.84% [
                                         62], Test 12.81% [
5: Train 12.87% [
                                                              62]
6: Train 9.05% [ 350], Valid 9.11% [
                                         44], Test 9.09% [
                                                              44]
7: Train 22.47% [ 869], Valid 22.36% [ 108], Test 22.52% [
                                                             109]
```

Done

3 Neural Network

3.1 Hyper Parameters

```
[155]: conv_input_size = (H1, W1, D_Length)
      input_size = np.prod(conv_input_size)
      output_size = K_Length
      print("conv_input_size: " + str(conv_input_size) + ", input_size: " + "
       str(input_size) + ", D_Length: " + str(D_Length) + ", output_size: " +
       ⇔str(output_size))
      hn1 = D_Length
      ReluAlpha = 0
      EluAlpha = 0
      layer type = ["conv", "stridedconv", "convpool", "dense", "dense"]
      NUM = 2
      num units = [hn1, 32, 64, 128, 256, 512]
      num_units = [num_units[0]] + [n_unit * NUM for n_unit in num_units[1:]]
      activation = ["relu", "relu", "relu", "relu", "relu"]
      dropout = [0.3, 0.3, 0.3, 0.4, 0.4]
      usebias = [False, False, False, True, True] + [True]
      batchnorm_momentum = [0.7, 0.7, 0.7, None, None]
      ###
      conv_filter_size
                          = ["same" if l in ["conv", "stridedconv", "convpool"] else
      conv_mode
       →None for l in layer_type]
      conv stride
                         = 2
      conv_dilation
                        = 1
      ###
      conv_pool_size
                        = 2
      conv_pool_dilation = 1 #Dilation on Pooling layer
      conv_pool_stride = conv_pool_size #Stride on Pooling: a 2x2 pooling with_
       ⇔stride 2 will half the size of an image
      conv_pool_padding = 0 #Used when the input size is not an integer multiple of
       → the kernel size, so usually just 0.
      ###
      conv_padding, conv_output_size = [2, 2, 2, None, None], [28, 28, 14, 36864, __
       →*num_units[-2:]] #18432 #36864
      print()
      print("nPadding:", conv_padding)
      print("X's Dims:", conv output size)
      print("num_units", num_units)
      print(f"\nbatch size: {batch size}")
      12\_lamda = 0.35
```

```
mu = 0.99 #Momentum
      conv input size: (48, 48, 1), input size: 2304, D Length: 1, output size: 3
      nPadding: [2, 2, 2, None, None]
      X's Dims: [28, 28, 14, 50176, 512, 1024]
      num_units [1, 64, 128, 256, 512, 1024]
      batch_size: 256
[161]: #Regular
       conv_input_size = X_Train[0].shape if X_Train is not None else X_Data[0].shape_
       →#Also used in RNNs
       input_size = np.prod(conv_input_size)
       output_size = np.prod(0_Length)
       print("conv_input_size: " + str(conv_input_size) + ", input_size: " +__
       str(input_size) + ", D_Length: " + str(D_Length) + ", output_size: " +
       ⇔str(output size))
       hn1 = D_Length
       ReluAlpha = 0 #0.01 def leakyRelu
       EluAlpha = 0.8
       layer_type = ["dense", "dense", "dense"]
       ###
       NUM = 1
       num units = [hn1, 128, 256, 512]
       num_units = num_units if len(num_units) == 1 else [num_units[0]] +
        → [num_units[LayerIndex+1] if layer_type[LayerIndex] in ["transfenc", __
       "customtransfenc"] else num_units[LayerIndex+1] * NUM for LayerIndex in_
       →range(len(layer_type))] #MAKING SURE TRANSFORMER INPUT AND OUTPUT num units __
       →ARE THE SAME AFTER NUM IS APPLIED
       ###
       activation = ["relu"] + ["relu"] * (len(layer_type)-1) #None, "relu6" "relu", |
       →"elu", "softplus", "tanh", "sigmoid"
       ###
                 = [0.3] * 1 + [0.3] * (len(layer_type)-1)
       dropout
       ###
                 = [True] * len(layer_type) + [True]
       usebias
       ###
       12_{\text{lamda}} = 0.25
       mu = 0.99 \#Momentum
       ###
       print()
```

```
print("num_units", num_units)
       print(f"\nbatch_size: {batch_size}")
      conv_input_size: (1200,), input_size: 1200, D_Length: 1200, output_size: 1
      doFlatten= False
      num_units [1200, 128, 256, 512]
      batch_size: 256
      3.2 Optimisation
      3.2.1 Structure
[162]: print(device)
       Debug = False
       model = Net(K_Length, num_units, activation, dropout, usebias)
       # if device != "cpu":
             model = nn.DataParallel(model)
       print(model)
       #Initialising the Metrics
       train_losses, train_metric1s, train_metric2s, train_metric3s, valid_losses,
        avalid_metric1s, valid_metric2s, valid_metric3s = np.array([]), np.array([]),
        anp.array([]), np.array([]), np.array([]), np.array([]), np.array([]), np.array([])
        →array([])
       train_best_loss, valid_best_loss, valid_best_metric1, valid_best_metric2,_u
        ⇒valid_best_metric3 = np.Inf, np.Inf, 0, np.nan, np.nan
      cuda
      Net(
        (layers): ModuleList(
          (0): Linear(in_features=1200, out_features=128, bias=True)
          (1): ReLU()
          (2): Dropout(p=0.3, inplace=False)
          (3): Linear(in_features=128, out_features=256, bias=True)
          (4): ReLU()
          (5): Dropout(p=0.3, inplace=False)
          (6): Linear(in_features=256, out_features=512, bias=True)
          (7): ReLU()
          (8): Dropout(p=0.3, inplace=False)
          (9): Linear(in_features=512, out_features=8, bias=True)
        )
      )
[163]: print("conv_input_size:", conv_input_size, "\n")
```

```
summary(model, input_size = [1, D_Length], device = device, verbose = 1, \( \top \col_names = ["kernel_size", "input_size", "output_size", "num_params", \( \top \)"mult_adds"], depth = 3)
if IS_GPU_AVAILABLE:
    torch.cuda.empty_cache()
```

conv_input_size: (1200,)

====				
Layer (type:depth-idx)	D #	Kernel Shape		Input Shape
Output Shape	Param #		Mult-Adds	
====				
Net				
ModuleList: 1-1				
Linear: 2-1		[1200, 128]		[1, 1200]
[1, 128]	153,728		153,728	
ReLU: 2-2				[1, 128]
[1, 128]				[4 400]
Dropout: 2-3 [1, 128]				[1, 128]
Linear: 2-4		[128, 256]		[1, 128]
[1, 256]	33,024	[120, 200]	33,024	[1, 120]
ReLU: 2-5	00,021		00,021	[1, 256]
[1, 256]				- , -
Dropout: 2-6				[1, 256]
[1, 256]				
Linear: 2-7		[256, 512]		[1, 256]
[1, 512]	131,584		131,584	
ReLU: 2-8				[1, 512]
[1, 512]				5
Dropout: 2-9				[1, 512]
[1, 512] Linear: 2-10		[510 0]		[1 510]
[1, 8]	4,104	[512, 8]	4,104	[1, 512]
=======================================		.=======		=========

=====

Total params: 322,440 Trainable params: 322,440 Non-trainable params: 0 Total mult-adds (M): 0.32

CrossEntropyLoss
Multiclass Classification

```
[165]:  # for prm_grp in optimiser.param_groups:  # prm_grp['lr'] = 1e-4  # # prm_grp['weight_decay'] = 0.1
```

3.2.2 Stochastic Gradient Descent (Dataset)

```
[167]: Epochs = int(50)
       PrintInfoEverynEpochs = 1
       scheduler = None
       # scheduler = torch.optim.lr scheduler.StepLR(optimiser, step size = Epochs //__
        \rightarrow 10 if Epochs > 10 else 3, gamma = 0.8)
       new_train_losses, new_valid_losses, train_best_loss, valid_best_loss,__
        onew train metric1s, new train metric2s, new train metric3s, 11
        →new_valid_metric1s, new_valid_metric2s, new_valid_metric3s,\
       Metric1, Metric2, Metric3, valid_best_metric1, valid_best_metric2,__
        ovalid_best_metric3, elapsed_time = \
           batch_gd(model, device, criterion, optimiser, scheduler, Loader_Train,_
        →Loader_Valid, epochs = Epochs, PrintInfoEverynEpochs = PrintInfoEverynEpochs,
                    train_best_loss = train_best_loss, test_best_loss =_
        →valid_best_loss, BestMetric1 = valid_best_metric1, BestMetric2 =

        →valid_best_metric2, BestMetric3 = valid_best_metric3,
                    Verbose = False
           )
```

```
train_losses, valid_losses = np.append(train_losses, new_train_losses), np.
  →append(valid_losses, new_valid_losses)
train_metric1s, train_metric2s, train_metric3s = np.append(train_metric1s,_u
  -new_train_metric1s), np.append(train_metric2s, new_train_metric2s), np.
  →append(train_metric3s, new_train_metric3s)
valid metric1s, valid metric2s, valid metric3s = np.append(valid metric1s,
  onew_valid_metric1s), np.append(valid_metric2s, new_valid_metric2s), np.
  →append(valid_metric3s, new_valid_metric3s)
train_loss, valid_loss, valid_metric1, valid_metric2, valid_metric3 = u
  LastNonNan(new_train_losses), LastNonNan(new_valid_losses), Metric1,_
  →Metric2, Metric3
print(f'\ntrain_best_loss: {train_best_loss:.5f}, valid_best_loss:u
 →{valid_best_loss:.5f}, Acc: {valid_metric1:.5f}, AUC: {valid_metric2:.5f}, ___
 →F1: {valid_metric3:.5f}')
if IS_GPU_AVAILABLE:
    torch.cuda.empty_cache()
if IsWindows:
    winsound.PlaySound('SystemExit', winsound.SND_NOSTOP)
Epoch 01/50, Train Loss: 0.0633, Test Loss: 1.3704 | Acc: 0.907, AUC: 0.987, F1:
0.906, Duration: 0:00:00.156999
Epoch 02/50, Train Loss: 0.0608, Test Loss: 1.3698 | Acc: 0.907, AUC: 0.987, F1:
0.906, Duration: 0:00:00.148500
Epoch 03/50, Train Loss: 0.0604, Test Loss: 1.3692 | Acc: 0.911, AUC: 0.986, F1:
0.910, Duration: 0:00:00.146000
Epoch 04/50, Train Loss: 0.0555, Test Loss: 1.3688 | Acc: 0.911, AUC: 0.986, F1:
0.910, Duration: 0:00:00.144500
Epoch 05/50, Train Loss: 0.0556, Test Loss: 1.3681 | Acc: 0.909, AUC: 0.986, F1:
0.908, Duration: 0:00:00.145000
Epoch 06/50, Train Loss: 0.0553, Test Loss: 1.3660 | Acc: 0.915, AUC: 0.986, F1:
0.915, Duration: 0:00:00.147000
Epoch 07/50, Train Loss: 0.0550, Test Loss: 1.3648 | Acc: 0.915, AUC: 0.986, F1:
0.915, Duration: 0:00:00.158000
Epoch 08/50, Train Loss: 0.0517, Test Loss: 1.3654 | Acc: 0.913, AUC: 0.986, F1:
```

0.913, Duration: 0:00:00.148000

0.913, Duration: 0:00:00.159500

0.913, Duration: 0:00:00.154000

0.911, Duration: 0:00:00.147999

0.913, Duration: 0:00:00.148501

Epoch 09/50, Train Loss: 0.0543, Test Loss: 1.3657 | Acc: 0.913, AUC: 0.985, F1:

Epoch 10/50, Train Loss: 0.0520, Test Loss: 1.3660 | Acc: 0.913, AUC: 0.985, F1:

Epoch 11/50, Train Loss: 0.0532, Test Loss: 1.3666 | Acc: 0.911, AUC: 0.985, F1:

Epoch 12/50, Train Loss: 0.0471, Test Loss: 1.3669 | Acc: 0.913, AUC: 0.985, F1:

```
Epoch 14/50, Train Loss: 0.0486, Test Loss: 1.3693 | Acc: 0.905, AUC: 0.985, F1:
0.904, Duration: 0:00:00.151498
Epoch 15/50, Train Loss: 0.0549, Test Loss: 1.3698 | Acc: 0.907, AUC: 0.985, F1:
0.906, Duration: 0:00:00.151500
Epoch 16/50, Train Loss: 0.0502, Test Loss: 1.3704 | Acc: 0.907, AUC: 0.984, F1:
0.905, Duration: 0:00:00.144498
Epoch 17/50, Train Loss: 0.0449, Test Loss: 1.3707 | Acc: 0.907, AUC: 0.984, F1:
0.906, Duration: 0:00:00.152000
Epoch 18/50, Train Loss: 0.0493, Test Loss: 1.3698 | Acc: 0.905, AUC: 0.984, F1:
0.904, Duration: 0:00:00.150500
Epoch 19/50, Train Loss: 0.0482, Test Loss: 1.3689 | Acc: 0.907, AUC: 0.983, F1:
0.906, Duration: 0:00:00.146001
Epoch 20/50, Train Loss: 0.0491, Test Loss: 1.3692 | Acc: 0.907, AUC: 0.983, F1:
0.906, Duration: 0:00:00.144500
Epoch 21/50, Train Loss: 0.0470, Test Loss: 1.3706 | Acc: 0.905, AUC: 0.983, F1:
0.904, Duration: 0:00:00.146000
Epoch 22/50, Train Loss: 0.0427, Test Loss: 1.3716 | Acc: 0.903, AUC: 0.983, F1:
0.902, Duration: 0:00:00.147500
Epoch 23/50, Train Loss: 0.0487, Test Loss: 1.3719 | Acc: 0.903, AUC: 0.983, F1:
0.902, Duration: 0:00:00.147999
Epoch 24/50, Train Loss: 0.0398, Test Loss: 1.3702 | Acc: 0.907, AUC: 0.983, F1:
0.906, Duration: 0:00:00.145501
Epoch 25/50, Train Loss: 0.0410, Test Loss: 1.3689 | Acc: 0.909, AUC: 0.983, F1:
0.909, Duration: 0:00:00.149502
Epoch 26/50, Train Loss: 0.0420, Test Loss: 1.3679 | Acc: 0.909, AUC: 0.983, F1:
0.909, Duration: 0:00:00.148498
Epoch 27/50, Train Loss: 0.0341, Test Loss: 1.3675 | Acc: 0.909, AUC: 0.984, F1:
0.908, Duration: 0:00:00.151000
Epoch 28/50, Train Loss: 0.0438, Test Loss: 1.3674 | Acc: 0.907, AUC: 0.983, F1:
0.906, Duration: 0:00:00.147498
Epoch 29/50, Train Loss: 0.0446, Test Loss: 1.3674 | Acc: 0.907, AUC: 0.982, F1:
0.906, Duration: 0:00:00.153000
Epoch 30/50, Train Loss: 0.0431, Test Loss: 1.3685 | Acc: 0.907, AUC: 0.982, F1:
0.906, Duration: 0:00:00.144500
Epoch 31/50, Train Loss: 0.0428, Test Loss: 1.3689 | Acc: 0.907, AUC: 0.982, F1:
0.906, Duration: 0:00:00.149500
Epoch 32/50, Train Loss: 0.0413, Test Loss: 1.3716 | Acc: 0.907, AUC: 0.981, F1:
0.906, Duration: 0:00:00.150500
Epoch 33/50, Train Loss: 0.0344, Test Loss: 1.3737 | Acc: 0.907, AUC: 0.981, F1:
0.906, Duration: 0:00:00.151000
Epoch 34/50, Train Loss: 0.0388, Test Loss: 1.3728 | Acc: 0.907, AUC: 0.981, F1:
0.906, Duration: 0:00:00.151000
Epoch 35/50, Train Loss: 0.0310, Test Loss: 1.3710 | Acc: 0.907, AUC: 0.981, F1:
0.906, Duration: 0:00:00.150500
Epoch 36/50, Train Loss: 0.0331, Test Loss: 1.3694 | Acc: 0.905, AUC: 0.981, F1:
0.904, Duration: 0:00:00.146002
Epoch 37/50, Train Loss: 0.0317, Test Loss: 1.3682 | Acc: 0.913, AUC: 0.981, F1:
0.912, Duration: 0:00:00.151000
```

```
0.910, Duration: 0:00:00.148000
      Epoch 39/50, Train Loss: 0.0368, Test Loss: 1.3671 | Acc: 0.911, AUC: 0.979, F1:
      0.910, Duration: 0:00:00.147999
      Epoch 40/50, Train Loss: 0.0324, Test Loss: 1.3665 | Acc: 0.915, AUC: 0.978, F1:
      0.914, Duration: 0:00:00.153003
      Epoch 41/50, Train Loss: 0.0357, Test Loss: 1.3665 | Acc: 0.915, AUC: 0.978, F1:
      0.914, Duration: 0:00:00.151998
      Epoch 42/50, Train Loss: 0.0309, Test Loss: 1.3676 | Acc: 0.915, AUC: 0.978, F1:
      0.914, Duration: 0:00:00.150000
      Epoch 43/50, Train Loss: 0.0287, Test Loss: 1.3697 | Acc: 0.907, AUC: 0.980, F1:
      0.905, Duration: 0:00:00.148000
      Epoch 44/50, Train Loss: 0.0317, Test Loss: 1.3717 | Acc: 0.905, AUC: 0.980, F1:
      0.903, Duration: 0:00:00.149500
      Epoch 45/50, Train Loss: 0.0326, Test Loss: 1.3707 | Acc: 0.907, AUC: 0.980, F1:
      0.905, Duration: 0:00:00.155002
      Epoch 46/50, Train Loss: 0.0275, Test Loss: 1.3670 | Acc: 0.917, AUC: 0.980, F1:
      0.916, Duration: 0:00:00.149998
      Epoch 47/50, Train Loss: 0.0276, Test Loss: 1.3664 | Acc: 0.915, AUC: 0.981, F1:
      0.915, Duration: 0:00:00.148500
      Epoch 48/50, Train Loss: 0.0255, Test Loss: 1.3667 | Acc: 0.915, AUC: 0.980, F1:
      0.915, Duration: 0:00:00.147502
      Epoch 49/50, Train Loss: 0.0329, Test Loss: 1.3671 | Acc: 0.913, AUC: 0.980, F1:
      0.912, Duration: 0:00:00.156498
      Epoch 50/50, Train Loss: 0.0300, Test Loss: 1.3672 | Acc: 0.913, AUC: 0.980, F1:
      0.912, Duration: 0:00:00.151502
      Done (Sun, 2022-09-11 19:42 EEST +0300) Elapsed time: 7.5 seconds
      train_best_loss: 0.05500, valid_best_loss: 1.36480, Acc: 0.91304, AUC: 0.98049,
      F1: 0.91242
[150]: #Loading the best trained model (in case the last one was overfitted)
       model.load_state_dict(torch.load("model_dict.pt"))
       model.eval()
       train_loss = train_best_loss
       valid_loss = valid_best_loss
       valid_metric1 = valid_best_metric1
       valid_metric2 = valid_best_metric2
       valid_metric3 = valid_best_metric3
```

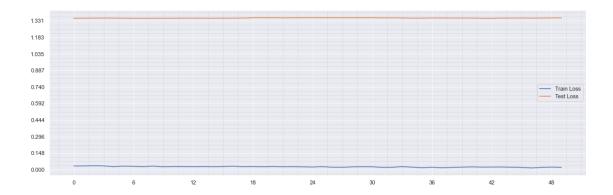
Epoch 38/50, Train Loss: 0.0417, Test Loss: 1.3676 | Acc: 0.911, AUC: 0.980, F1:

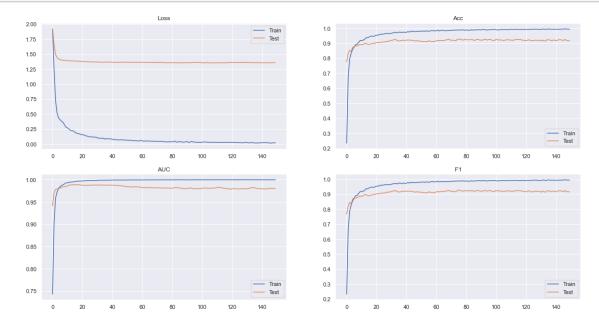
4 Evaluation

4.1 Training Metrics

```
[184]: PlotHistory(train_losses[-(50):], valid_losses[-(50):], figsize=(19, 6), 

stest_alpha = 1)
```





4.2 Multiclass Classification

[195]: Labels = Classes
with torch.no_grad(): #Making sure that we don't update the gradient outside_
the training part
model.eval() #Putting model in evaluation mode so that things like_
dropout() are deactivated

```
model.to(device) #Moving the model to the appropriate device (CPU/CUDA/
  ⇔etc.)
        #Using the Forward direction of the model to get the Predictions (also_{f \sqcup}
 →returning the corresponding Targets in case there's suffling and X_Test_
  \hookrightarrow isn't indexed the same)
        Preds_prob, Preds, Targets = EvalPredict(model, device, Loader_Test)
test_Acc, test_AUC, test_F1 = GetCategoricalMetrics(Preds_prob, Preds, Targets)
print(f'Sample-wise Acc: {test_Acc * 100:.2f},, AUC: {test_AUC:.2f}, F1:__
 print(f"Class-wise Acc: {ClassAccMulti(Targets, Preds, K_Length) * 100:.2f},, u
  →Recall: {recall_score(Targets, Preds, average = 'weighted'):.3f}, Precision:
 →{precision_score(Targets, Preds, average = 'weighted'):.3f}\n") #'micro', □
 ⇔'macro', 'weighted', 'samples'
#Viewing the overall Categorical metrics and Plotting the Confusion Matrix
PlotCategoricalMetrics(Preds, Targets, Labels, normalise = True, figsize = [17, __
 46.5])
print("")
PrevFigSize = plt.rcParams['figure.figsize']
plt.rcParams['figure.figsize'] = [5, 5]
for k in range(K_Length):
    PredClass = Preds
    TrueClass = Targets == k
    print(f"Class {Classes[k]}. Sample-Wise Acc: {np.mean(TrueClass ==__
 →PredClass):.3f}, Recall: {recall_score(TrueClass, PredClass):.3f}, Precision:
 → {precision_score(TrueClass, PredClass):.3f}, F1: {f1_score(TrueClass, ⊔
 ⇔PredClass):.3f}")
    RocCurveDisplay.from predictions(TrueClass, Preds prob[:, k])
    plt.plot(np.linspace(0, 1, num = 20), np.linspace(0, 1, num = 20), 'b--')
    plt.show()
    print()
plt.rcParams['figure.figsize'] = PrevFigSize
#Sample-wise Acc: 94.01%, AUC: 0.99, F1: 0.94
Sample-wise Acc: 94.01%, AUC: 0.99, F1: 0.94
Class-wise Acc: 98.50%, Recall: 0.940, Precision: 0.942
Confusion matrix
[[ 56
       3
           0
                   0
                           0
                                0]
 [ 0 55
                  0
                       0
                           0
                               0]
           0
              0
                  0
                       0
                          0
                               0]
   0
      0 48
 ΓΟ
       0
          0 46
                  0
                       0
                          0
                               0]
```

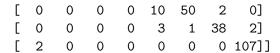
0 0

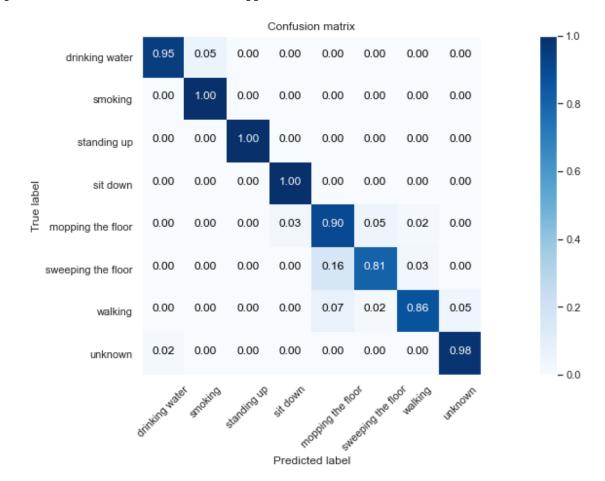
0

2 55

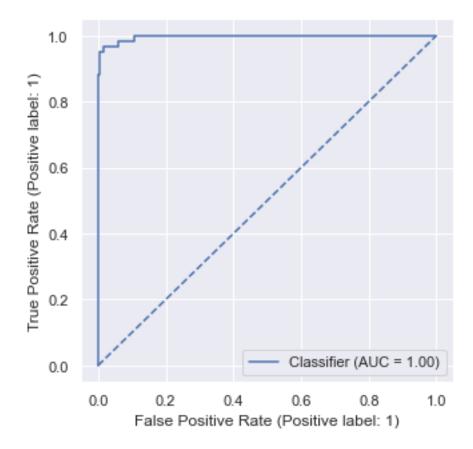
3 1

0]

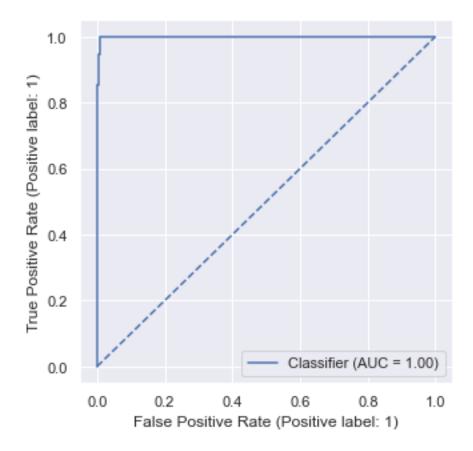




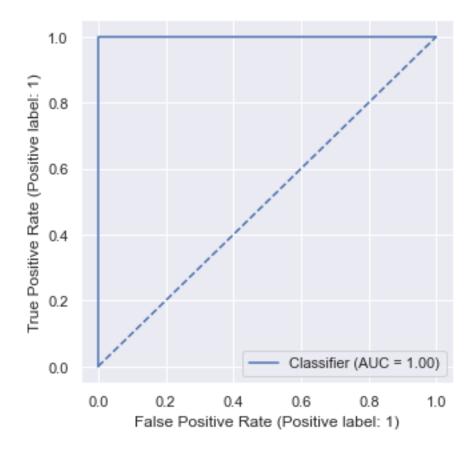
Class drinking water. Sample-Wise Acc: 0.990, Recall: 0.949, Precision: 0.966, F1: 0.957



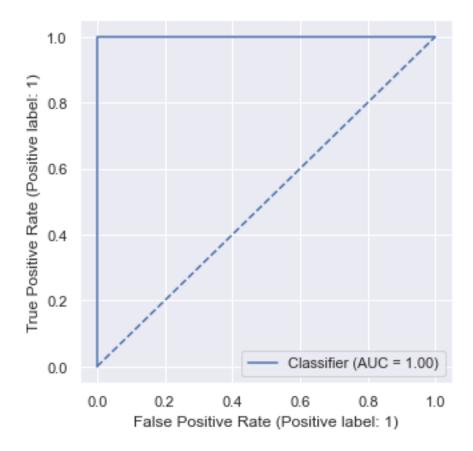
Class smoking. Sample-Wise Acc: 0.994, Recall: 1.000, Precision: 0.948, F1: 0.973



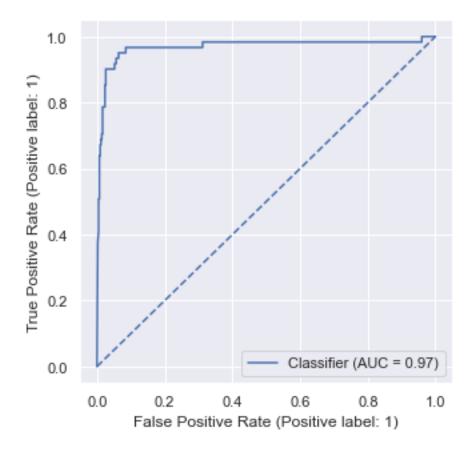
Class standing up. Sample-Wise Acc: 1.000, Recall: 1.000, Precision: 1.000, F1: 1.000



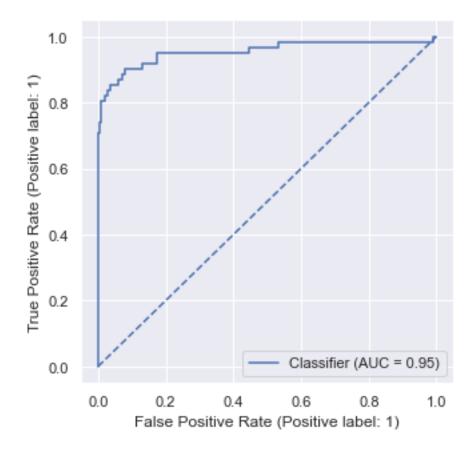
Class sit down. Sample-Wise Acc: 0.996, Recall: 1.000, Precision: 0.958, F1: 0.979



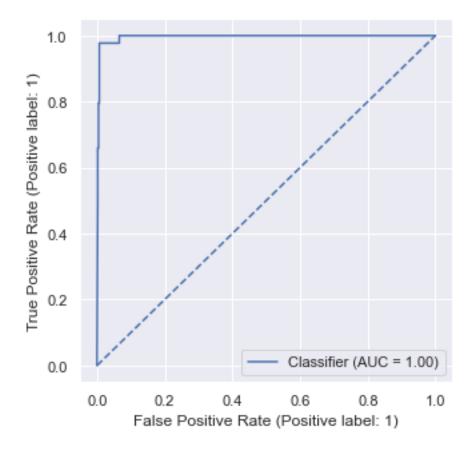
Class mopping the floor. Sample-Wise Acc: 0.961, Recall: 0.902, Precision: 0.809, F1: 0.853



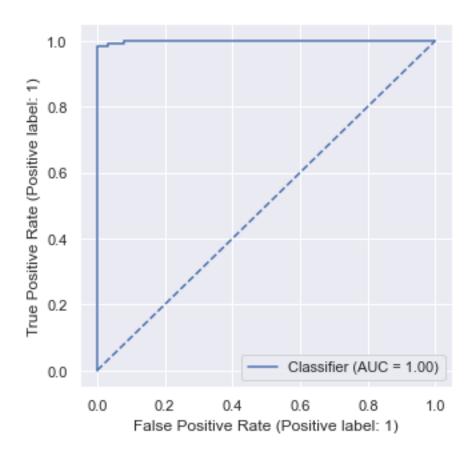
Class sweeping the floor. Sample-Wise Acc: 0.967, Recall: 0.806, Precision: 0.926, F1: 0.862



Class walking. Sample-Wise Acc: 0.981, Recall: 0.864, Precision: 0.927, F1: 0.894



Class unknown. Sample-Wise Acc: 0.992, Recall: 0.982, Precision: 0.982, F1: 0.982



5 Saving the Model

i = 2

```
[]: if isnotebook:
                                i += 1
                                print(i)
                                display(_ih[i])
[102]: if isnotebook:
                                PossibleNetClass = _ih[i]
[172]: ### Saving the Model ###
                    QuoteIfNone = lambda x: f"'{x}'" if x is not None else "None"
                     #Saving the Parameters
                    WriteText(
                                f"#PyTorch v{torch.__version__}\n#CUDA device available:__
                        →{IS_GPU_AVAILABLE}\n{f'#{torch.cuda.device_count()} devices available' if
                         storch.cuda.is_available() else ''}\n#device = {device}\n" +
                                f"#isnotebook = {isnotebook}\n#isgooglecolab = {isgooglecolab}\n#shell =__
                        \hookrightarrow{shell}\n\n" +
                                f"layer_type = {json.dumps(layer_type)}\nSeed = {Seed}\nnum_units = {json.
                         dumps(num units)}\nactivation = {json.dumps(activation)}\ndropout = {json.
                         \rightarrowdumps(dropout)}\nusebias = {usebias}\n" +
                                f"batch size = {batch size} \n" +
                                f''K_Length = {K_Length}\nD_Length = {D_Length}\nH1 = {H1}\nW1 =
                         German Graph Street Stre
                         \rightarrow{input_size}\noutput_size = {output_size}\nhn1 = {hn1}\n\n" +
                                f"12_lamda = {12_lamda}\nmu = {mu}\nbatchnorm_momentum =__
                         ⇔{batchnorm momentum}\nconv_pool_size = {conv_pool_size}\nconv_pool_stride = __
                         f"conv_pool_padding = {conv_pool_padding}\nconv_pool_dilation =_
                         \hookrightarrow {conv pool dilation}\n" +
                                f"\nPrintInfoEverynEpochs = {PrintInfoEverynEpochs}\n" +
                                f"\ntrain_best_loss = {train_best_loss}\nvalid_best_loss =_
                         f"valid metric1 = {valid metric1}\nvalid metric2 =___
                         f"valid_best_metric1 = {valid_best_metric1}\nvalid_best_metric2 =_

¬{valid_best_metric2}\nvalid_best_metric3 = {valid_best_metric3}\n",

                    f"{SaveFolder}/Parameters.py")
                    #Saving the Losses so we can plot them in the future
                    WriteText(json.dumps(train_losses.tolist()) , f"{SaveFolder}/Metrics/
                         ⇔train_losses.json" )
                    WriteText(json.dumps(valid_losses.tolist()) , f"{SaveFolder}/Metrics/
                        ⇔valid_losses.json" )
                    WriteText(json.dumps(train_metric1s.tolist()), f"{SaveFolder}/Metrics/
                         ⇔train metric1s.json")
```

```
WriteText(json.dumps(train_metric2s.tolist()), f"{SaveFolder}/Metrics/
 ⇔train_metric2s.json")
WriteText(json.dumps(train_metric3s.tolist()), f"{SaveFolder}/Metrics/
⇔train metric3s.json")
WriteText(json.dumps(valid_metric1s.tolist()), f"{SaveFolder}/Metrics/
 ⇔valid_metric1s.json")
WriteText(json.dumps(valid_metric2s.tolist()), f"{SaveFolder}/Metrics/
 ⇔valid metric2s.json")
WriteText(json.dumps(valid_metric3s.tolist()), f"{SaveFolder}/Metrics/
 ⇔valid_metric3s.json")
#Saving the Optimiser
WriteText(optimiser, f"{SaveFolder}/Optimiser.txt")
#Saving the optimiser's parameters
torch.save(optimiser.state_dict(), f"{SaveFolder}/optimiser_dict.pt")
#Saving the Criterion
SaveVariable(criterion, f"{SaveFolder}/criterion.pt")
#Saving the Criterion's name (easier to see by looking at the file)
WriteText(criterion, f"{SaveFolder}/criterion.txt")
#Saving the Net() Class
if isnotebook:
   print(PossibleNetClass.partition('\n')[0])
   WriteText(PossibleNetClass, f"{SaveFolder}/Net.py")
else:
   WriteText(f"#Net() not found.\n#Probably not a notebook?\n", f"{SaveFolder}/
 →Net.py")
#Saving Model itself
torch.save(model.state_dict(), f"{SaveFolder}/model_dict.pt")
#Saving Model itself
SaveVariableDill(model, f"{SaveFolder}/model.pt")
#Saving the Scheduler
SaveVariableDill(scheduler, f"{SaveFolder}/scheduler.pt")
print("Done!")
```

#Dynamic with "layer.append()"
Done!

6 Loading the Model

```
[190]: SaveFolder = f"{path_root}/Models/2022-09-11 19-38, Valid Loss 1.36 Acc 0.92, Use Test Acc 0.94 AUC 0.99 F1 0.94"
```

Done!

```
[192]: train_losses = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       valid losses
                     = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔valid losses.json")))
      train_metric1s = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔train_metric1s.json")))
      train_metric2s = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔train_metric2s.json")))
      train_metric3s = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔train_metric3s.json")))
      valid_metric1s = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔valid_metric1s.json")))
      valid_metric2s = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔valid_metric2s.json")))
      valid_metric3s = np.array(json.loads(ReadText(f"{SaveFolder}/Metrics/
       ⇔valid_metric3s.json")))
      print("Done!")
```

Done!

```
[194]: model = Net(K_Length, num_units, activation, dropout, usebias)

if device != "cpu":
    model.load_state_dict(torch.load(f"{SaveFolder}/model_dict.pt"))

# model = nn.DataParallel(model)
```

Done!

7 Predicting on External Data

```
[180]: External_DF = pd.read_csv(f"{path_data}/11-16 (1).csv", header = None).iloc[:,__
      X_External = External_DF.values.astype(np.float32)
      X_External = Scale(X_External, *scaler_mean_sd)
      MYDataset = TensorDataset(torch.from_numpy(X_External))
      MYDataLoader = torch.utils.data.DataLoader(
          MYDataset,
          batch_size = batch_size,
          pin_memory = True
      model.to(device)
      model.eval()
      with torch.no_grad():
          TestPredictions = []
          for inputs in MYDataLoader:
               TestPredictions.append(model(inputs[0].to(device)))
          _, TestPredictions = torch.max(nn.Softmax(dim = 1)(torch.
        ⇒cat(TestPredictions)), 1)
          TestPredictions += 1
          TestResults = pd.DataFrame(TestPredictions.cpu().numpy()).reset_index()
          TestResults.columns = ["Id", "Class"]
      FileExportPath = f"{path_root}/Exports/Results.csv"
      TestResults.to_csv(FileExportPath, sep = ',', header = True, index = False)
      print(f"Results saved on: {FileExportPath}")
      TestResults
```

Results saved on: D:\GiannisM\Downloads\Exercises\Fiver\100. frotribe FFNN Multiclass Classification/Exports/Results.csv

```
[180]: Id Class
      0
             0
                    1
      1
             1
                    1
      2
             2
                    1
      3
              3
                    1
      4
              4
      4830 4830
                    8
      4831 4831
                    8
      4832 4832
                    8
      4833 4833
                    8
      4834 4834
     [4835 rows x 2 columns]
 []:
```