

Questionnaire on

Mobile robots visualization via virtual exocentric vision

The purpose of this questionnaire is to collect your impressions about the experience you just had in visualizing a mobile robot via a virtual exocentric vision system.

Please answer the questions in a candid fashion. All the information you provide is confidential and will remain anonymous. The information you provide will not be used for any other purpose.

1) Did you manage to get the trajectory performed by the robot? If so, describe it below:

2) Did you feel the robot was moving jerkily?
no 0 1 2 3 4 yes

3) If so, when it was such a behaviour particularly disturbing?
☐ during hard turnings
☐ during straight lines
☐ during broken lines

4) Give an overall evaluation of how comfortable did you feel at understanding what was the robot doing:

not comfortable 0 1 2 3 4 very comfortable