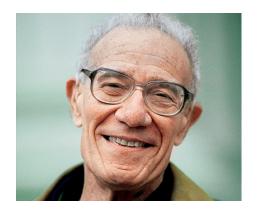


The Solow model





Solow growth model

Key premises:

- neoclassical production function
- Say's law: full employment at all times.

Main implications:

- ▶ stable steady-state with $g_Y = n + g$
- saving rate determines output level but not growth rate
- K accumulation cannot explain long-run growth or cross-country income differences.



Production function

- One-good economy
- ▶ 4 variables: *Y*, *K*, *L*, *A*.
- ► Say's law: full employment of *L* & *K* at each *t*.
- Neoclassical aggregate production function

$$Y(t) = F[K(t), A(t)L(t)]$$

o AL: labor-augmenting technological progress.



Constant returns to scale (CRS)

$$Y = F[K, AL]$$

 $F(cK, cAL) = cF(K, AL)$



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► *Intensive form* of the production function:

$$\frac{Y}{AL} = F(\frac{K}{AL}, \frac{AL}{AL}) = F(\frac{K}{AL}, 1)$$

$$\downarrow$$

$$y = f(k)$$

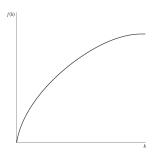
with
$$k = \frac{K}{AL}$$
, $y = \frac{Y}{AL}$ and $f(k) = F(k, 1)$



Other assumptions about the production function

$$f(0) = 0,$$
 $f'(k) > 0,$ $f''(k) < 0$

$$lim_{k\to 0}f'(k) = \infty$$
, $lim_{k\to \infty}f'(k) = 0$





Evolution of production inputs

$$g_L = n$$
 (therefore $\dot{L}(t) = nL(t)$)

$$g_A = g$$
 (therefore $\dot{A}(t) = gA(t)$)

$$\dot{K}(t) = sY(t) - \delta K(t), \qquad 0 < s \le 1$$



The dynamics of the model

- ► Strategy: focus on $k = \frac{K}{AL}$
- ► Take the derivative of k wrt time

$$\dot{K}(t) = \frac{d(K/AL)}{dt} = \frac{\dot{K}}{AL} - \frac{K}{AL}\frac{\dot{L}}{L} - \frac{K}{AL}\frac{\dot{A}}{A}$$

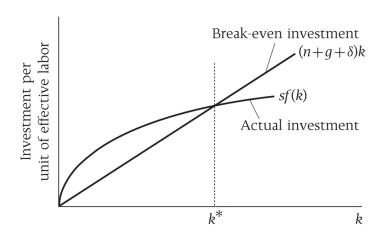
▶ using $k = \frac{K}{AL}$, $y = \frac{Y}{AL}$ & the assumptions about inputs:

$$\dot{k}(t) = sf[k(t)] - (n+g+\delta)k(t)$$

change in k = investment - breakeven investment

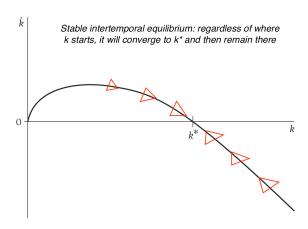


Actual vs. break-even investment





Phase diagram





The steady state

In the intertemporal equilibrium...

- ▶ by assumption, $g_L = n$ and $g_A = g$;
- $ightharpoonup K = ALk
 ightharpoonup g_K = n + g$
- $ightharpoonup Y = ALf(k) \rightarrow g_Y = n + g$
- $\blacktriangleright \frac{K}{L} = Ak \rightarrow g_{\frac{K}{L}} = g$
- $\blacktriangleright \ \frac{Y}{L} = Af(k) \rightarrow g_{\frac{Y}{l}} = g$

balanced growth path: all variables grow at constant rates.



Other things we want to know:

- 1. Qualitative effect of an increase in s (direction)
- 2. What level of k maximizes consumption (golden-rule k^*)
- 3. Speed of convergence: how long does transition take?

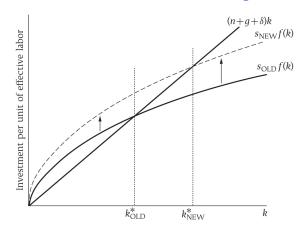


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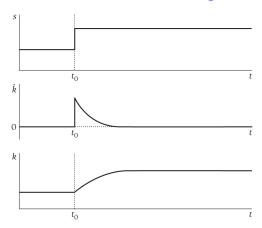


An increase in the saving rate





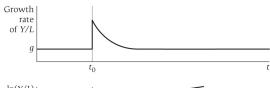
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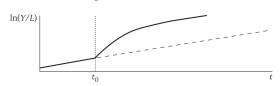




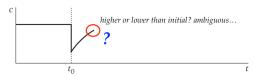
An increase in the saving rate

$$Y/L = Af(k)$$











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Consumption and the golden-rule

- $rac{r}{r} c^* = f(k^*) (n+g+\delta)k^*$
- $\triangleright k^* = k^*(s, n, g, \delta)$

What value of s maximizes c^* ?



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What value of s maximizes c^* ?

- ▶ golden-rule *k**
- ▶ characterized by $MPK = (n + g + \delta)$.
- but no reason for s to be exactly at the level which implies the golden-rule $k^*!$

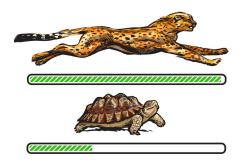


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► How fast will k reach k* when starting out of equilibrium?





Refresher: Taylor approximations

- Taylor's theorem: any (continuously differentiable) function $\phi(x)$ can be approximated, around a point x_0 , by a n-th degree polynomial.
- ightharpoonup n-th degree Taylor approximation around x_0 :

$$\phi(x) = \left[\frac{\phi(x_0)}{0!} + \frac{\phi'(x_0)}{1!}(x - x_0) + \frac{\phi''(x_0)}{2!}(x - x_0)^2 + \dots + \frac{\phi^{(n)}(x_0)}{n!}(x - x_0)^n\right] + R_n$$
(R_n = remainder)

ightharpoonup linear approximation around x_0 :

$$\phi(x) \approx \phi(x_0) + \phi'(x_0)(x - x_0)$$



- $ightharpoonup \dot{k} = \dot{k}(k)$
- ► linear approximation around k*:

$$\dot{k} \approx \left[\frac{\partial \dot{k}(k)}{\partial k} \Big|_{k=k^*} \right] (k-k^*) \quad \Rightarrow \quad \dot{k} \approx -\lambda (k-k^*) \quad \Rightarrow \quad \dot{k} + \lambda k = \lambda k^*$$



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- $k(t) \approx k^* + e^{-\lambda t}(k(0) k^*)$
- ▶ Bottom line: for plausible parameters, convergence is not fast.
- eg: $(n+g+\delta)=6\%$ and $\alpha_K=1/3 \rightarrow \lambda=0.04$



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 - ► $g_Y > n + g$ only during convergence.



- 2. s affects Y but not g_Y (in equilibrium).



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 - BUT implausibly huge differences in s would be needed to produce sizable differences in Y/L.



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- 2. s affects Y but not g_Y (in equilibrium).
- 3. Two sources of cross-country variation in Y/L: s and A.
 - ▶ BUT implausibly huge differences in *s* would be needed to produce sizable differences in *Y/L*.
- 4. Technology (A) is the only possible explanation of vast cross-country differences in Y/L.

Solow model: implications



Solow model: the conventional criticisms

Main driver of growth (A) falls from the sky and has a vague definition;



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- Subsequent developments of neoclassical growth theory address these issues.



Solow model: more radical criticisms

- Overcomes Harrodian instability by assuming it away
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- Overcomes Harrodian instability by assuming it away
 - continuous full employment by assumption.
 - $g = g_W$ is assumed, not demonstrated.
- \triangleright Relies on a fictional aggregate production function Y(K, AL).
 - In reality, many production processes and many types of inputs
 - They do not add up to an aggregate production function with the properties assumed by Solow model (Cambridge capital controversy)
 - One-good economy: 'Venerable Solow may make peculiar assumptions, but he never makes a mistake' (A. Sen, 1974)
 - Recent discussion of the problem: Baqaee & Fahri (2019).
- Subsequent developments of neoclassical growth theory do not address these issues.



Convergence regressions

- Do poor countries catch up?
- ► Solow model suggests convergence, if *A* non-excludable.
- Empirical test:

$$\Delta ln(Y/L)_{i,1} = \alpha + \beta ln(Y/N)_{i,0} + \epsilon_i$$

- with t = 0 and t = 1 usually quite apart in time (40/50 years).
- ▶ $\beta = -1$ = perfect convergence
- ► Evidence from 1960-2000: some convergence among core-OECD countries ($\beta \approx -1$), but little or no convergence overall ($\beta \approx 0$).



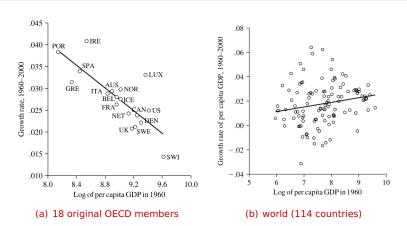


Figure: International evidence on convergence: 1960 income and subsequent growth