



Advanced Macroeconomics

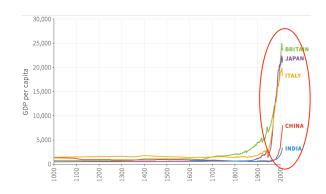
Section 2 - Growth (I): The mechanics of capital accumulation and growth

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The hockey stick of history





Section 2: Growth (I)

The Plan

- 1. Harrod-Domar
- 2. Solow
- 3. Ramsey-Cass-Koopmans
- 4. Diamond's overlapping-generations (OLG)



Key idea: Intertemporal equilibrium

- ► Static analysis: equilibrium condition -> equilibrium relations.
 - I=S
 - supply=demand
 - MRS=MRT
 - ...
- ► Growth theory is *dynamic*: intertemporal equilibria.

Main concepts:

- o Intertemporal equilibrium
- o Steady state
- o Dynamic stability



The Harrod-Domar model







There's an old joke. Two elderly women are at a Catskill restaurant. One of them says, 'Boy, the food at this place is just terrible.' The other one says, 'Yeah I know. And such small portions.'

(Woody Allen, 'Annie Hall')





The Harrod-Domar model

- 'Grandfather' of modern growth theory.
- Premise 1: aggregate investment has a dual effect
 - 1. multiplier effect (demand side)
 - 2. capacity-creating effect (supply side)
- Premise 2: investment depends on output (accelerator)



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- Premise 1: aggregate investment has a dual effect
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- Premise 2: investment depends on output (accelerator)
- ► Main findings:
 - unique equilibrium path: $g_W = sa$ (warranted rate)
 - · warranted rate does not guarantee full (nor stable) employment
 - instability: economy won't converge to g_w , except by a fluke



Harrod-Domar model

Assumptions:

$$Y(t) = C(t) + I(t);$$
 $S(t) = sY(t);$ $Y^*(t) = aK(t);$ $u(t) = \frac{Y(t)}{Y^*(t)}$

$$g_K(t) = \frac{\dot{K}(t)}{K(t)} = \frac{I(t)}{K(t)};$$
 $\dot{g}_K(t) = \alpha(u(t) - 1)$ with $\alpha > 0$



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Actual investment rate:

$$I(t) = S(t) \quad \rightarrow g_K(t) = \frac{S(t)}{K(t)} = s \frac{Y(t)}{K(t)} = s \frac{Y^*(t)}{K(t)} \frac{Y(t)}{Y^*(t)} = sa[u(t)]$$



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Intertemporal equilibrium ('warranted' growth rate):

$$\dot{g}_K(t) = 0 \quad \rightarrow u = 1 \quad \rightarrow g_W = sa$$



The equilibrium ('warranted') rate of growth

Warranted vs natural growth rate:

$$g_Y = sa \neq n$$



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Dynamic instability:

$$g_K = u(sa) > g_W = sa \implies u > 1 \implies \dot{g}_K > 0$$

 $g_K = u(sa) < g_W = sa \implies u < 1 \implies \dot{g}_K < 0$



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► More formally:

$$\dot{g}_K = \frac{\alpha}{sa} (g_K - g_w)$$
 with $\alpha > 0$



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