

---

**EDUCATION**


**NASA Jet Propulsion Laboratory & Autonomous Systems Lab, ETH Zurich** 05/2018  
*MSc Thesis:* Disturbance Estimation and Rejection for High-Precision Multirotor Position Control. Supervision: Dr. Roland Brockers (JPL), Prof. Roland Siegwart (ASL ETH). - 12/2018

- Developed nonlinear Kalman Filters to estimate external wrench and a disturbance-aware MPC controller to improve multirotor position control accuracy in the presence of strong external disturbances by up to 80% compared to a baseline PID controller [3];
- Applied the controller to enable precision landing despite ground effect and severe wind.



**ETH Zurich** 2012-2018  
*BSc & MSc Mech. Eng.* Focus on control systems, state estimation, autonomous systems.

---

**WORK EXPERIENCE**

**Autonomous Systems Lab, ETH Zurich** 04/2019  
 Research Assistant. - 07/2019

- Improved accuracy and efficiency of evaluating visual-inertial odometry state estimation algorithms by developing an automated benchmarking pipeline and by integrating RTK-GPS state estimation to collect precise ground truth measurements (C++, Python, ROS);
- Enabled Swiss air rescue personnel to monitor live outputs of a deep-learning human detection pipeline running onboard a search-and-rescue UAV by developing a full-stack web UI (front end using vue.js, back end using express/node.js);



**NASA Jet Propulsion Laboratory, California Institute of Technology** 11/2017  
 Visiting Researcher. Mobility and Robotic Systems, Computer Vision (347H). - 04/2018

- Developed and tested guidance, control and autonomy software for long-duration, fully autonomous operation of rotorcraft UAVs (C++, ROS);
- Enabled the first autonomous outdoor flights by improving the robustness of the flight controllers and of the autonomy logic, resulting in up to 4-hour fully autonomous missions;
- Quantified performance of vision-based pose estimation of recharging platform.



**Automatic Control Laboratory, ETH Zurich** 02/2017  
 Student Researcher. Supervision: Prof. Maryam Kamgarpour. - 07/2017

- Developed a novel stochastic motion planning algorithm to generate safety-optimal aircraft trajectories in the presence of hazardous thunderstorms (MATLAB) [2].
- 

**PROJECT EXPERIENCE**

**AMZ Racing, ETH Formula Student Electric Team** 2015-16  
 Team Leader.

- Led ETH's world-record-breaking Formula Student team in the development of a state-of-the-art electric racecar, competing in the world's largest engineering competition;
- Team won *Formula Student Austria* and achieved 3 Engineering Design wins in 4 major European competitions; AMZ set WR for fastest-accelerating EV.

Battery Engineer. 2014-15

- Responsible for packaging, structural analysis and thermal management of the high voltage accumulator, using CAD, FEA and CFD software tools;
  - Team won 2 out of 4 competitions, becoming Formula Student Electric World Champions.
- 

**SKILLS**

(\*\*\* proficient, \*\* intermediate, \* basic knowledge)  
 Languages: C/C++\*\*\*, Python\*\*, JavaScript\*\*, MATLAB/Simulink\*\*\*, Bash\*\*.  
 Frameworks: ROS\*\*\*, Vue.js\*, Express.js\*.  
 Libraries: STL\*\*\*, Eigen\*\*, OpenCV\*.  
 CAD/CAE: Siemens NX, Ansys, CD Adapco StarCCM+.  
 Spoken languages: English, French, German (all high proficiency), Luxembourgish (native).

---

## PUBLICATIONS

### JOURNALS

1. D. Malyuta, C. Brommer, **D. Hentzen**, T. Stastny, R. Siegwart, and R. Brockers, “Long-Duration Fully Autonomous Operation of Rotorcraft UAS for Remote-Sensing Data Acquisition,” *Journal of Field Robotics*, 2019
2. **D. Hentzen**, M. Kamgarpour, M. Soler, and D. Gonzalez-Arribas, “On maximizing safety in stochastic aircraft trajectory planning with uncertain thunderstorm development”, *Aerospace Science and Technology*, vol. 79, pp. 543-553, 2018

### CONFERENCE PROCEEDINGS

3. **D. Hentzen**, T. Stastny, R. Siegwart, R. Brockers, “Disturbance Estimation and Rejection for High-Precision Multirotor Position Control,” in *IEEE Intelligent Robots and Systems (IROS)*, Macao, China, 2019
4. C. Brommer, D. Malyuta, **D. Hentzen**, and R. Brockers, “Long-Duration Autonomy for Small Rotorcraft UAS including Recharging,” in *IEEE Intelligent Robots and Systems (IROS)*, Madrid, Spain, 2018
5. D. Gonzalez-Arribas, **D. Hentzen**, M. Sanjurjo-Rivo, M. Kamgarpour, and M. Soler, “Optimal Aircraft Trajectory Planning in the Presence of Stochastic Convective Weather Cells,” in *17th AIAA Aviation Technology, Integration, and Operations Conference*, Denver, CO, 2017