

# CSE 379 Lab 3: Serial Communication with UART

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## 1) Purpose of the Program

### a) Objective

The purpose of this program is to receive two numbers from the user and to output the largest of the two their difference. PuTTY is used for the user to input their two numbers and for the program to display outputs.

### b) Debugging Steps

Whenever we ran into problems, we placed breakpoints wherever a subroutine is called. We stepped into every subroutine and looked at what's in memory and in registers. We continued to step into and resume, u  
ter value into a second register before calling subroutines on the first register which might have very possibly overwritten the data that we need.

### c) How To Run The Program

Go to Start, and type "cmd" and press Enter. Then type "mode" and press Enter. A window will pop up, and at the top of the window, there is a line that says "COMXX." The number, XX, will be important. To open PuTTY, go to Start → All Programs → PuTTY → PuTTY. The PuTTY Configuration window will pop up. Select Serial as the connection type. In the "Serial line" text field, write "COMXX" where XX is the number that you saw in the first step. Change the speed to 115200. To save these settings, type "Tiva-c" in the "Saved Sessions" text field and press "Save," located to the right of it. Then click "Open" at the bottom of the PuTTY Configuration window. Then open Code Composer Studio from the start menu. Now click on debug project, and click on resume. Enter the first number into PuTTY when prompted, click enter, enter the second number then click enter. You should see our program telling you which of your inputs is the largest, and what the difference between the two is.

#### d) Outside References

For reference, please refer to Texas Instruments' Tiva™ TM4C123GH6PM Microcontroller, Chapter 14. This contains information about UARTDR and UARTFR; the UARTDR and UARTFR are used in *read\_character* and *output\_character*.

In addition, please refer to ***Introduction to Microprocessor Based Systems Using the ARM Microprocessor***, Kris Schindler, Second Edition, Pearson, 2013, page 41. This contains information about the division algorithm that is implemented in the *div\_and\_mod* subroutine.

### 2) Division of Work

Daniel wrote *read\_character*, and Motaz wrote *output\_character*. The subroutines *read\_character* and *output\_character* were used to build *read\_string* and *output\_string* which they both developed together. Daniel wrote *convert\_to\_int* and Motaz wrote *convert\_to\_ASCII*. The thought process and the development of the other subroutines were mutually contributed by Daniel and Motaz.

### 3) Logic

#### a) Summary of Flowchart

First, the prompt to enter the first number is outputted to PuTTY. Then, as the user inputs their digit(s), the program stores these values in memory. Then, the prompt to enter the second number is outputted to PuTTY, and, again, the digit(s) are stored in memory. The program then finds and outputs the largest of the two numbers. Finally, the program computes the difference and outputs the difference. The program then loops back to the beginning, allowing the user to re-run the program without exiting.

## b) Summary of Subroutines

### i) *uart\_init*

This subroutine initializes the board. The assembly code is written based on the *serial\_init()* function in the C wrapper.

### ii) *read\_character*

When the user presses a key, the character is stored in UARTDR. This subroutine receives the character and stores it in the register r0.

### iii) *output\_character*

This subroutine stores whatever character/data is in r0 into UARTDR. By doing so, the character is outputted into PuTTY.

### iv) *read\_string*

When the user presses a key, the character is stored in UARTDR. This subroutine receives the character and stores it into memory in r4. It then proceeds to store any character pressed later after it in memory. If the key pressed is the Enter key, then a null character is stored instead and it terminates.

### v) *output\_string*

This subroutine starts at the address held in r4, and outputs the character at that address, traversing through r4. When the character in r4 is a null character, this subroutine stops.

### vi) *output\_newline*

This subroutine simply outputs a new line into PuTTY, by outputting the character represented by ASCII value 10 and 13, which are new line and carriage return, respectively.

### vii) *convert\_to\_int*

When a key is pressed by the user, the computer reads it as the key's ASCII representation. This subroutine converts the key's ASCII representation into its integer representation by subtracting 48 and weighting in terms of 100's 10's and 1's.

### viii) *Calculations*

This subroutine takes the two numbers, entered by the user, as integer representations, and finds the biggest of the two, and the difference. The biggest number and the difference are then moved into different registers for future use.

### ix) *convert\_to\_ASCII*

This subroutine takes an integer stored in register, and starts storing it backwards into memory address by dividing by 10 three times and setting the remainder as the last value in memory slot.

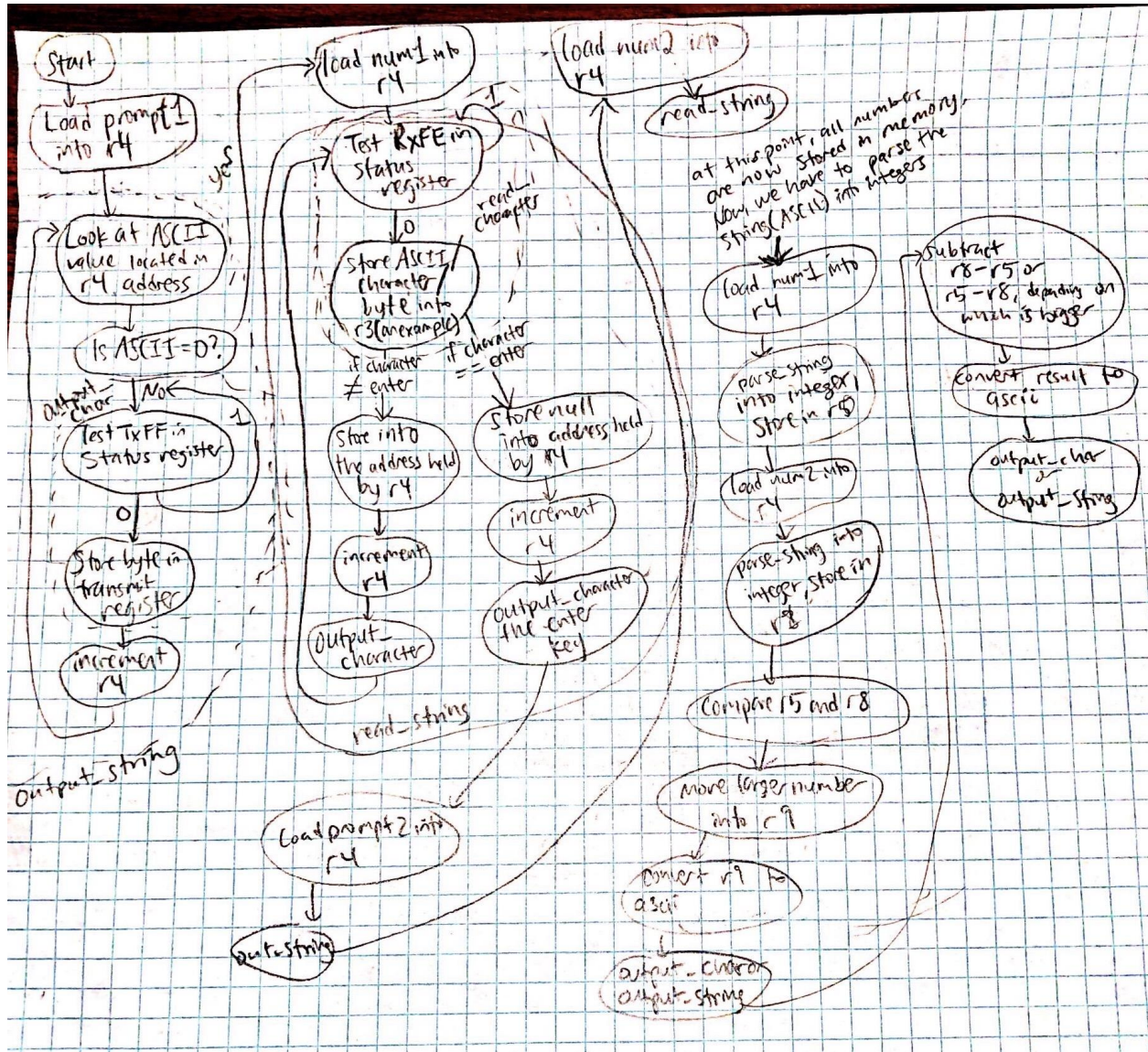
### x) *div\_and\_mod*

Subroutine used from lab2, used to determine the quotient and remainder of an unsigned division.

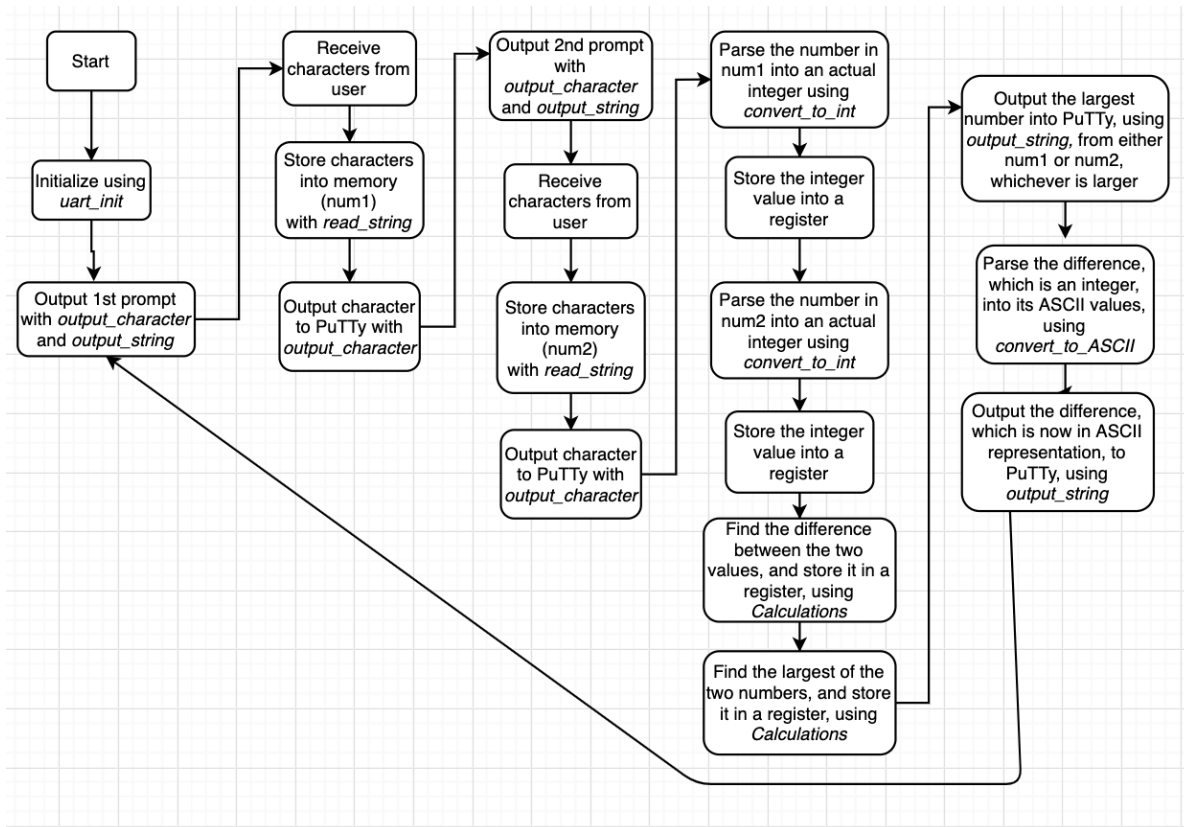
## 4) Flowcharts

All flowcharts are generated in draw.io.

### a) Rough Draft

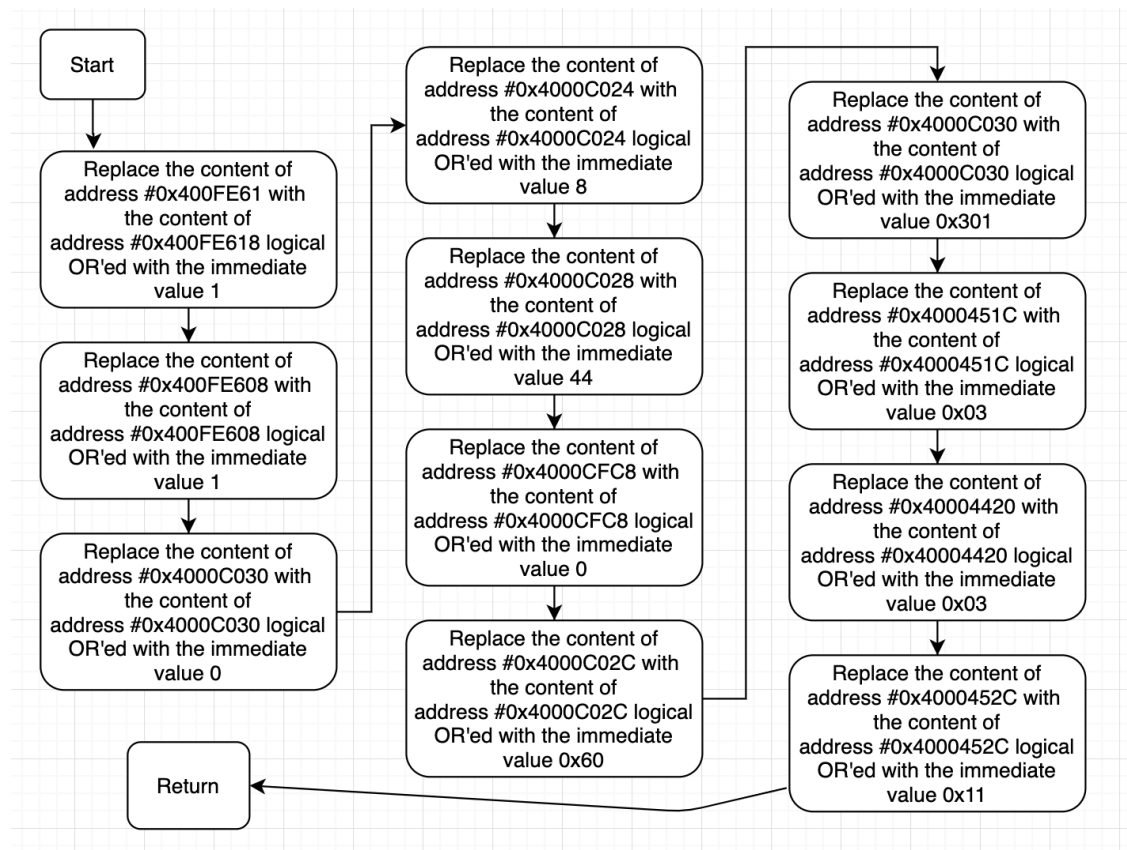


## b) Main Program Final Flowchart

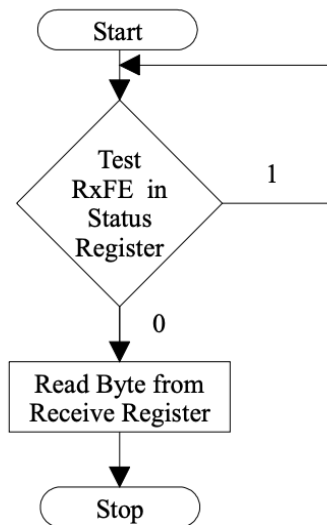


## c) Subroutine Flowcharts

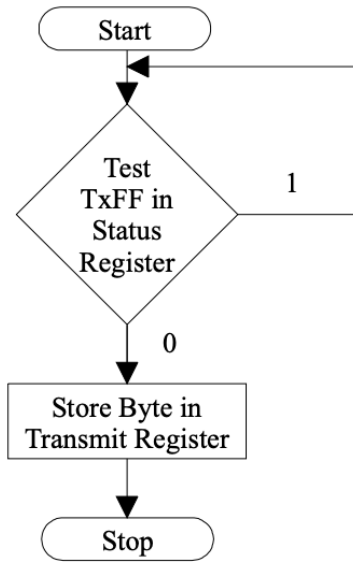
### i) *uart\_init*



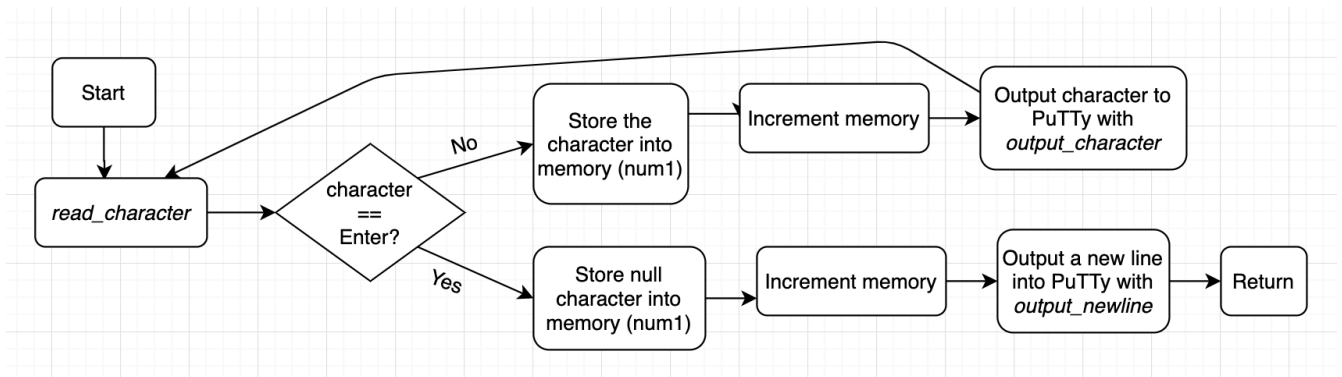
### ii) *read\_character*



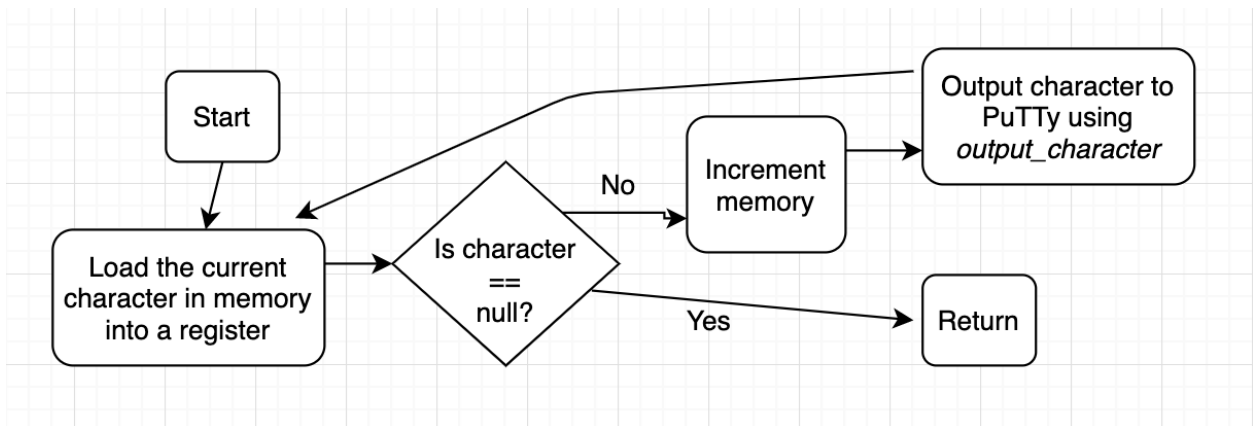
iii) *output\_character*



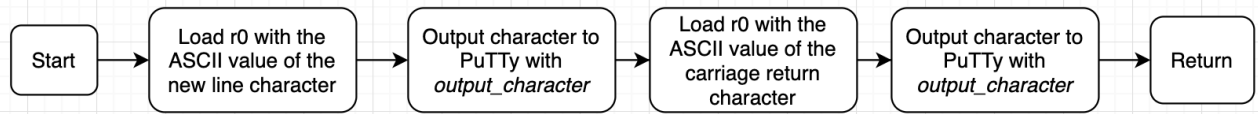
iv) *read\_string*



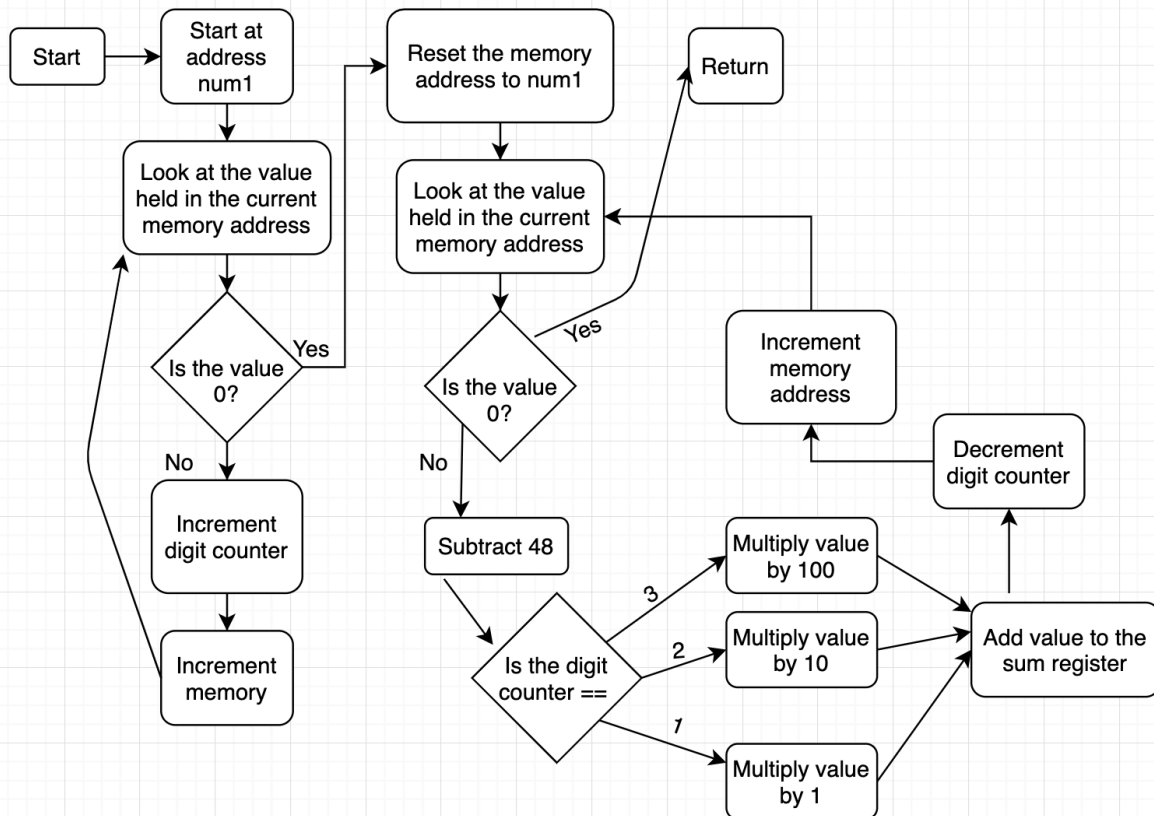
v) *output\_string*



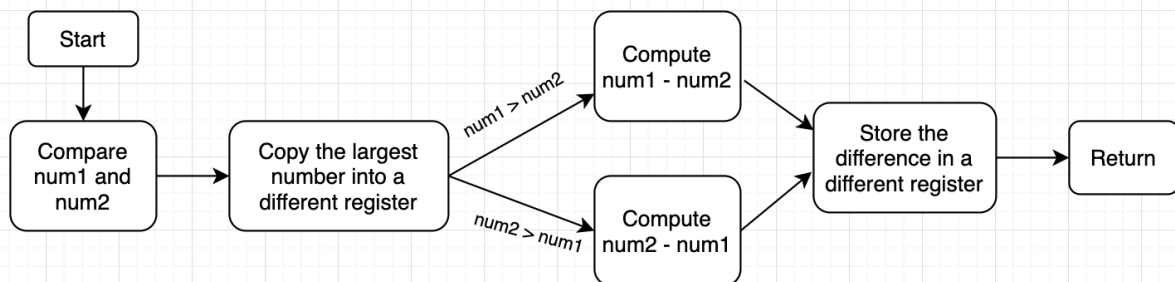
### vi) *output\_newline*



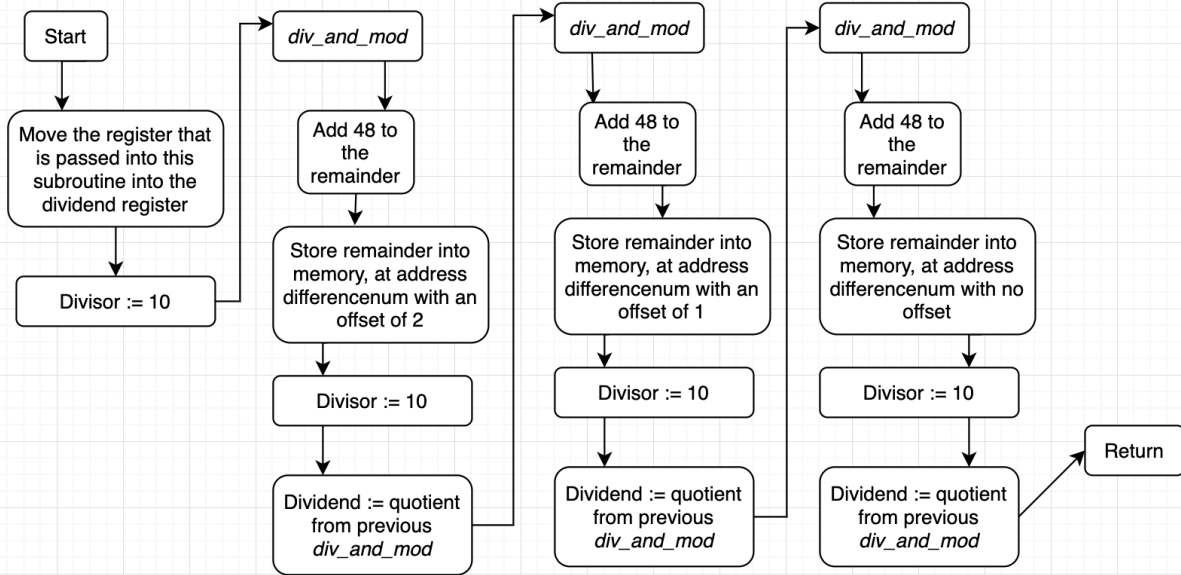
### vii) *convert\_to\_int*



### viii) *Calculations*





ix) convert\_to\_ASCII

x) *div\_and\_mod*

