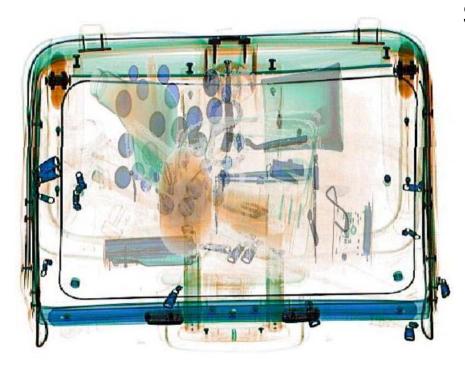
Perceptual decisions tournament

Casimir Ludwig c.ludwig@bristol.ac.uk

Perceptual decisions tournament

- Introduction to perceptual decision-making (~
 1.5 hrs)
- Tournament introduction (~ 1 hr)
- Lunch
- Model implementation (1.5 hrs)
- Model evaluation

Perceptual decision-making?



P(state of the world | sensory data)

$$P(S|x) = \frac{P(x|S)P(S)}{P(x)}$$



Hallmark characteristics

- Noisy sensory information (external noise)
- Processed by a noisy brain (internal noise)
- Typically: sampling or integrating across space and time (on a variety of spatial and temporal scales; e.g. neuronal to attentional)
- Often: combine sensory information with stored knowledge (i.e. prior beliefs)

Inference problem: what real-world event gave rise to these noisy sensory data?

Models of (perceptual) decisionmaking

2-AFC:

$$\frac{P(S_1|x)}{P(S_2|x)} = \frac{P(x|S_1)}{P(x|S_2)} \frac{P(S_1)}{P(S_2)}$$

When both options are equally likely:

$$\frac{P(S_1|x)}{P(S_2|x)} = \frac{P(x|S_1)}{P(x|S_2)}$$

Models of (perceptual) decisionmaking

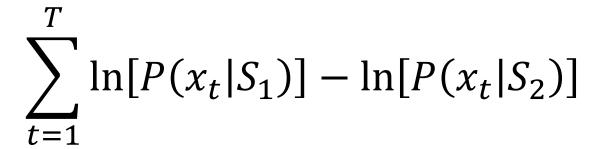
When the evidence comes in over time

$$\frac{P(S_1|\mathbf{x})}{P(S_2|\mathbf{x})} = \frac{\prod_{t=1}^T P(x_t|S_1)}{\prod_{t=1}^T P(x_t|S_2)} = \prod_{t=1}^T \frac{P(x_t|S_1)}{P(x_t|S_2)} = LR$$

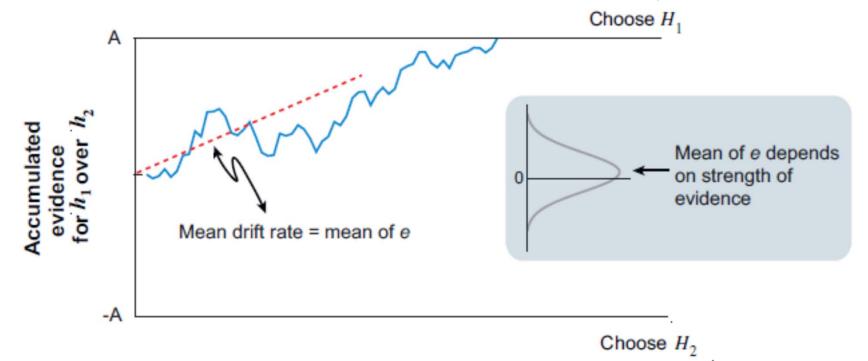
LLR

$$= \sum_{t=1}^{T} \ln \left[\frac{P(x_t|S_1)}{P(x_t|S_2)} \right] = \sum_{t=1}^{T} \ln[P(x_t|S_1)] - \ln[P(x_t|S_2)]$$

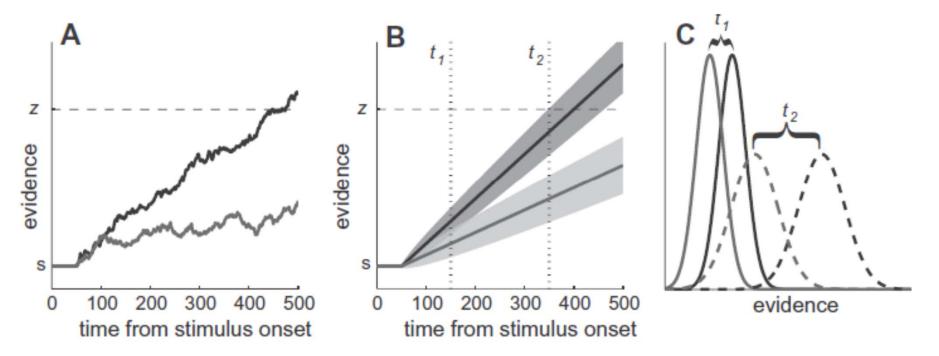
Choose S_1 if LLR > 0, S_2 if LLR < 0



b Symmetric random walk



Gold & Shadlen (2007) Ann Rev Neurosci.



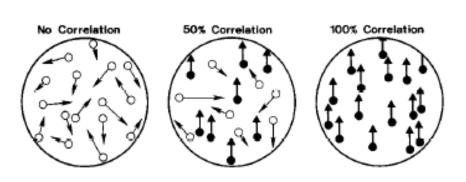
Ludwig & Davies (2011) Cognitive Psychology.

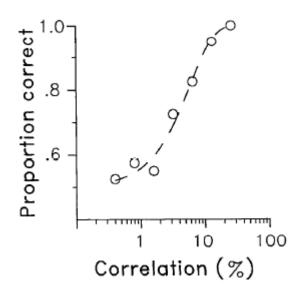
- Sequential sampling is a form of dynamic signal detection theory
- SDT is a useful starting point
- For more details on sequential sampling:
 Chris on Thursday

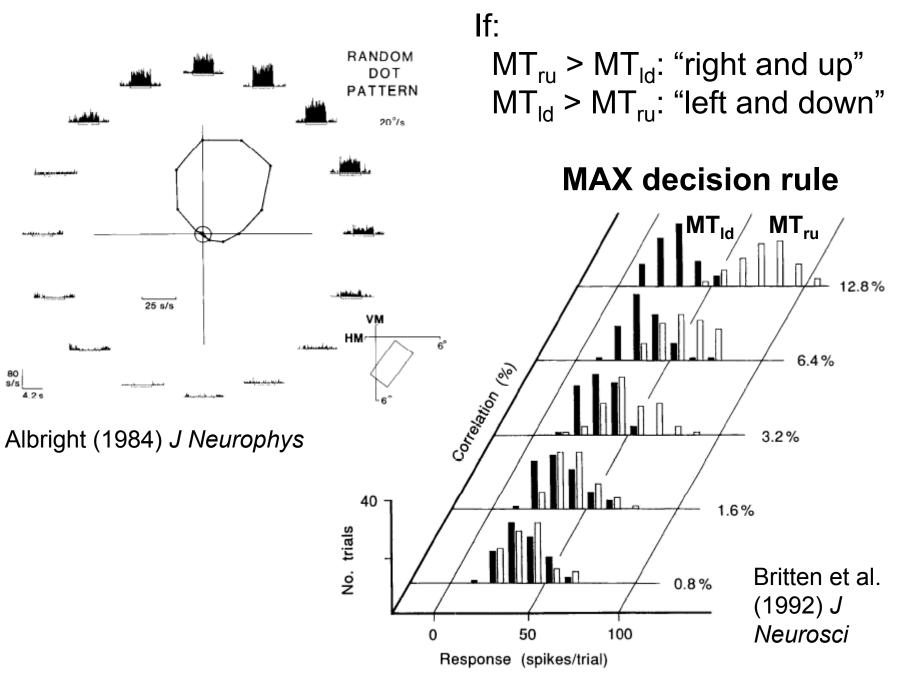
Signal Detection Theory account of choice accuracy

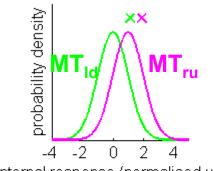
The Analysis of Visual Motion: A Comparison of Neuronal and Psychophysical Performance

Kenneth H. Britten, Michael N. Shadlen, William T. Newsome, and J. Anthony Movshon

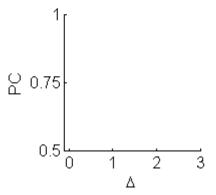


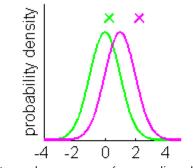




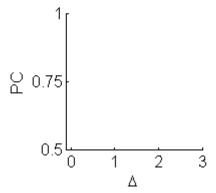


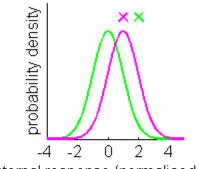
internal response (normalised units)

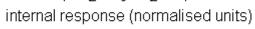


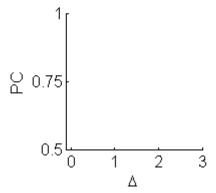


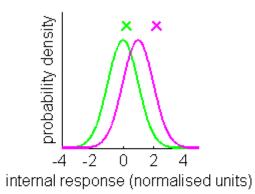
internal response (normalised units)

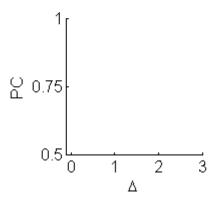


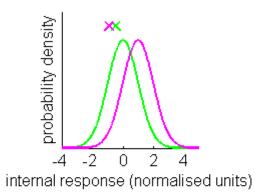


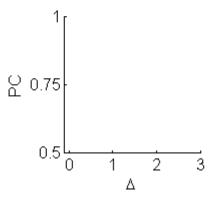


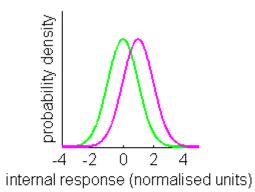


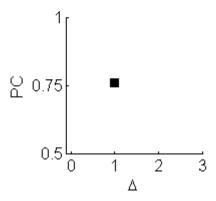












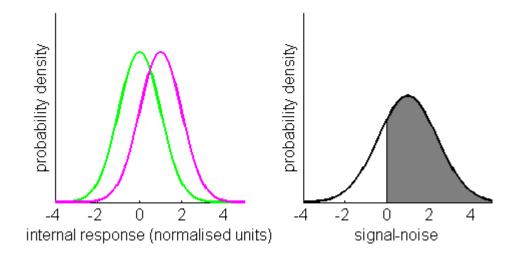
Play time...

- Simulate pairs of responses: one from the "preferred direction" (signal) distribution, one from the "non-preferred direction" (noise) distribution
- If signal > noise, response is correct
- Fix noise arbitrarily (e.g. set to 1)
- Vary the separation between the two distributions at a number of values (e.g. motion coherence): e.g. 0, 0.5, 1, etc.
- Plot PC as a function of separation

Method 1: simulation

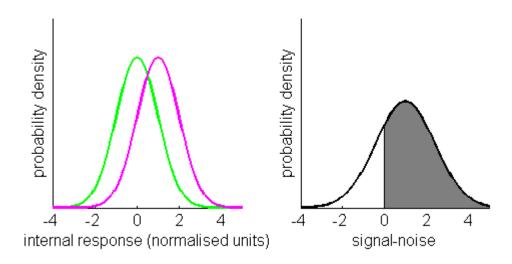
- Draw N pairs of responses, one response from signal and noise distributions (N = large)
- \circ Evaluate # trials on which $X_{signal} > X_{noise}$
- o For ties, flip a coin − I use: rbinom
- \circ PC = #/N
- Generally not needed for parametric models (i.e. where we assume some known distributional form)
- For example, where we have *measured* two distributions of noisy responses (like in Britten et al., 1992)

- Method 2: difference-of-Gaussians
 - o MAX rule corresponds to evaluating whether $(X_{signal} X_{noise}) > 0$



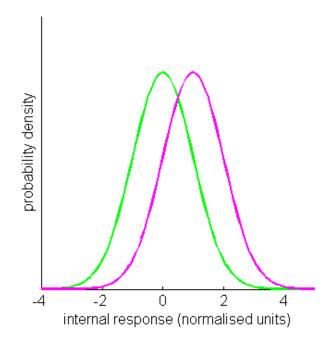
$$\mu_{difference} = \mu_{signal} - \mu_{noise}$$
 $\sigma_{difference} = \sqrt{\sigma_{signal}^2 + \sigma_{noise}^2}$

- Method 2: difference-of-Gaussians
 - Compute area under curve > 0
 - \circ = 1 area up to 0
 - o In R this is easy: 1-pnorm(0, mean= $\mu_{\text{difference}}$, sd= $\sigma_{\text{difference}}$)



- Method 3: direct evaluation
 - o For a given noise value $u = X_{noise}$, compute $P(X_{signal} > u)$
 - Weigh P(X_{signal} > u) by the probability of observing u under the noise distribution
 - Do this for all possible values for u and add up, i.e. integrate across u
 - Think of this as the "average probability that the signal response was greater than the noise response"
 - For 2-AFC this is equivalent to difference-of-Gaussian method
 - Direct evaluation is necessary for M-AFC (M > 2)

- Method 3: direct evaluation
 - o Signal and noise probability density: $f_s(x) = f_n(x)$



$$P(X_{signal} > u) = \int_{u}^{\infty} f_s(x) dx = H(u)$$

$$PC = \int_{-\infty}^{\infty} f_n(u)H(u)du$$

Method 3: direct evaluation

 $PC = \int_{-\infty}^{\infty} f_n(u)H(u)du$

- PC cannot be directly evaluated
- Gaussian distributions have to be integrated numerically (i.e. approximated with a discrete

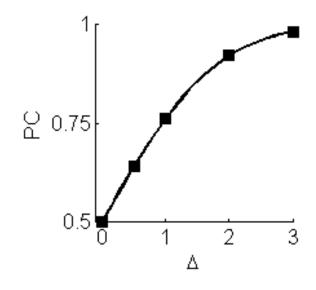
```
sum)
```

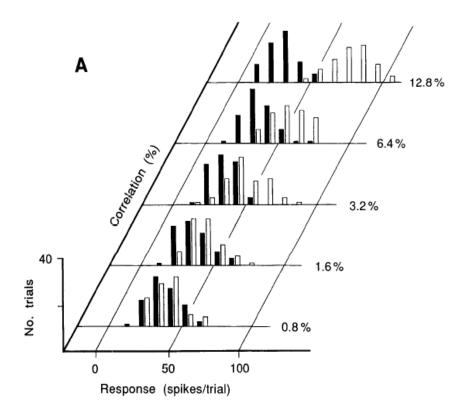
o In R:

```
# Method 3: Integrate across all possible noise responses and evaluate the
# probability that the signal response was greater. This results in a more
# complex expression to integrate, but the result should be identical to
# the difference distribution. The advantage of this approach is that it
# scales up for designs with more than two alternatives.
# First, set up the function to integrate
TwoAFCmax=function(x,mean1=0,mean2=0,sd1=1,sd2=1){
 v=dnorm(x.mean=mean1.sd=sd1)*(1-pnorm(x.mean=mean2.sd=sd2))
  return(y)
# This function can only be numerically integrated. You can be more or less
# sophisticated about this. I'm using the built-in 'integrate'
# function. Other functions to explore would be 'quadgk' or, the simplest
# of all, 'trapz'.
lowlim=mu_noise-5*sigma_noise # Set some sensible integration limits
uplim=mu_signal+5*sigma_signal # Assumes: mu_noise <= mu_signal</pre>
PC=integrate(TwoAFCmax,
             lowlim.
             uplim.
             mean1=mu_noise,
             mean2=mu_signal,
             sd1=sigma_noise.
             sd2=sigma_signal)
PCint=PC$value
```

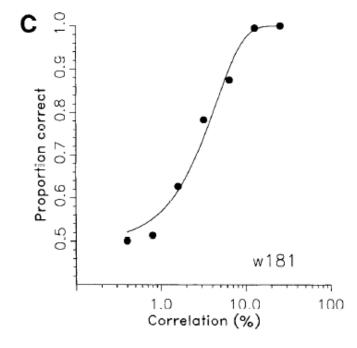
R script: TwoAFC_accuracy_demo

(Run with mu_signal = e.g. 0, 0.5, 1, 2, 3—plot in one window)

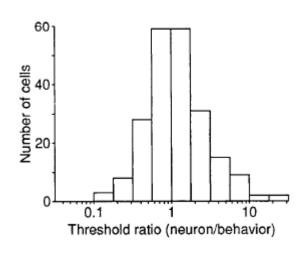


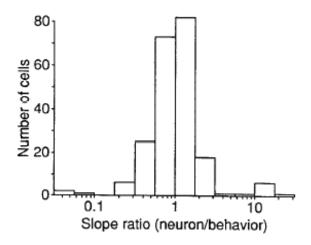


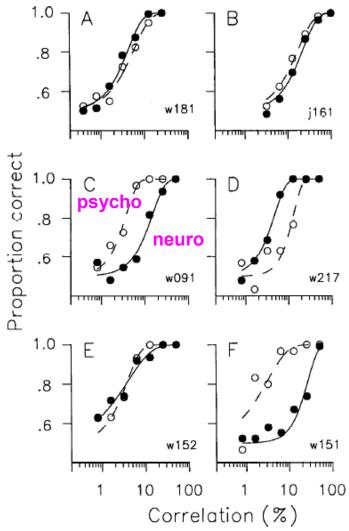
Britten et al. (1992) J Neurosci



Psychometric – neurometric comparison







Aim

- Develop a mechanistic model of the psychometric function
- Fit model to behavioural data using MLE
- or use Bayes if you like :-)
- Fit data on a training set
- Outcome metric: predictive generalisation to test set (i.e. likelihood of the "un-seen" test data)
- It may be instructive to compute other metrics for model selection (e.g. AIC, BIC)

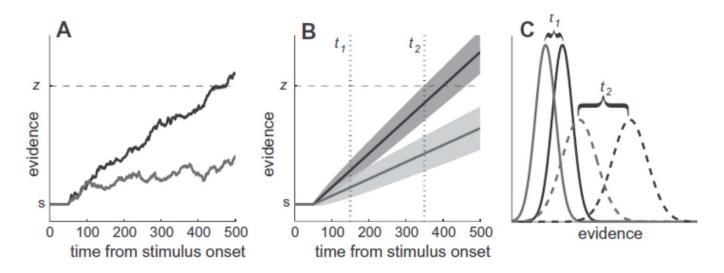
The data set

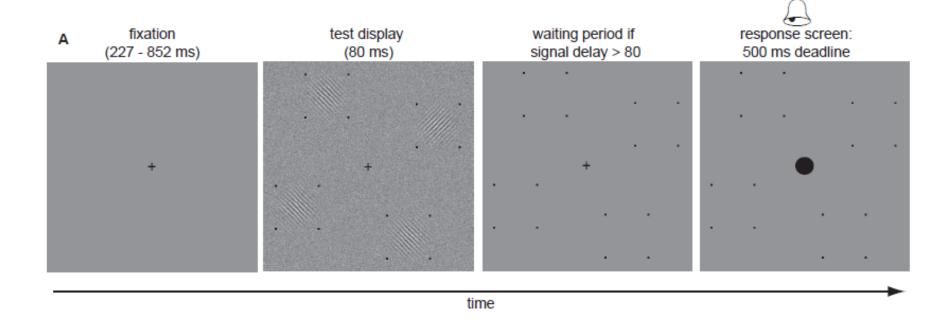
Cognitive Psychology 63 (2011) 61-92



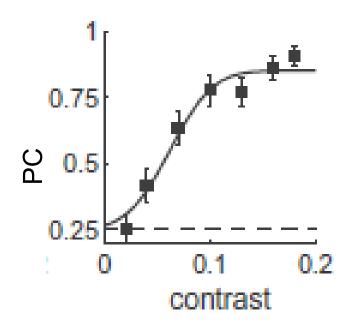
Estimating the growth of internal evidence guiding perceptual decisions

Casimir J.H. Ludwig*, J. Rhys Davies





- Search for oriented target among 3 distractors (orthogonal orientation)
- Manual localisation response
- Vary luminance contrast of all four patterns (energy)



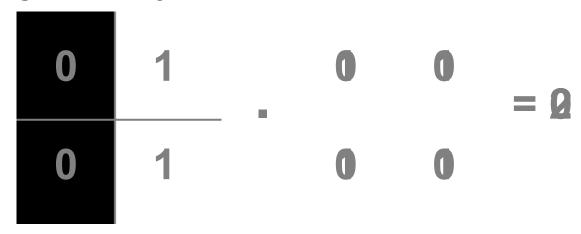
- PC(c) = F(c; θ), where θ is a vector of model parameters
- In this case: F = cumulative Gaussian, θ = {μ, σ}
- Function fitting

Aim: fit a "process" model

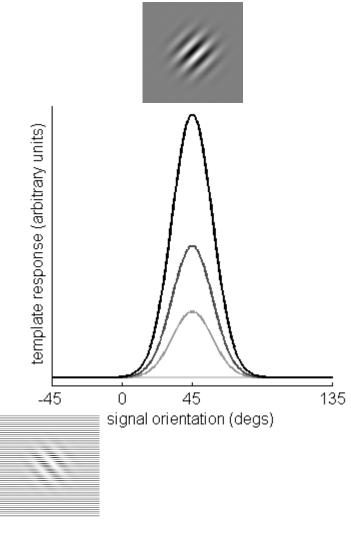
- Template matching!
- Implemented as 2-D "correlation" between a "target template" T and pattern S on screen

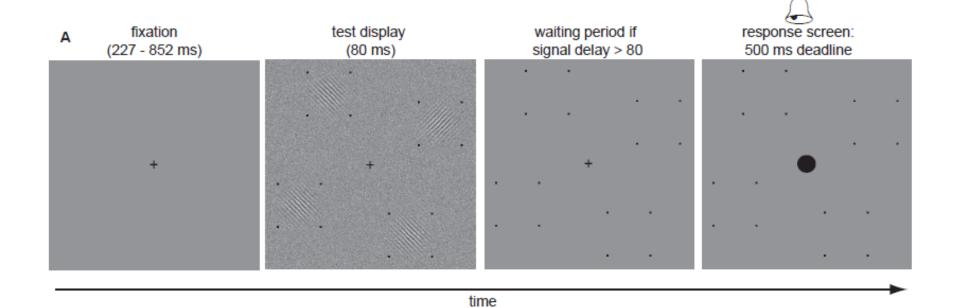
$$r = \sum_{x,y} T(x,y) \times S(x,y) = T(x,y) \cdot S(x,y)$$

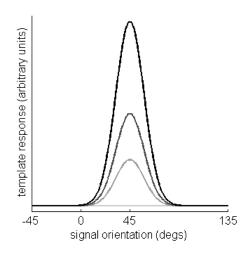
Images are just numbers!

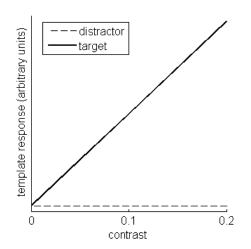


Best template matches the signal exactly ("matched filter")



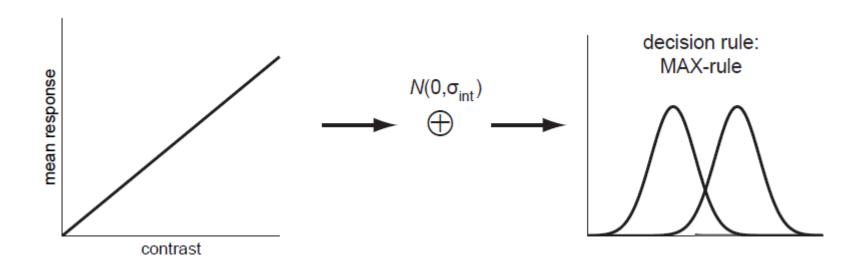






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A minimal model



- Template matched at all 4 locations
- Distractor response = 0
- Target response > 0
- Internal noise corrupts internal responses
- MAX response = most likely target location

- Similar to model used for random dot motion
- Except:
- 4 alternatives, rather than 2
- Continuous link function between signal strength (contrast here) and mean internal response

M-AFC

- Difference-of-Gaussian method cannot be applied when M > 2
- Direct evaluation:
 - For a given target response u = X_{signal}, compute probability that *all* (M-1) distractor responses are less than u:

$$P(X_{n1} < u) \times P(X_{n2} < u) \times K \times P(X_{nM-1} < u) = \left[\int_{-\infty}^{u} f_n(x) dx\right]^{M-1}$$

- Weigh P(all X_{noise} < u) by the likelihood of observing u under the target response distribution
- Do this for all possible values for u and add up, i.e.
 integrate across u

dnorm(
$$u$$
,mean= μ_{signal}) $PC = \int_{-\infty}^{\infty} (f_s(u)) \int_{-\infty}^{u} f_n(x) dx$

 Think of this as the "average probability that the target response was greater than all three distractor responses"

pnorm(
$$u$$
,mean= μ_{noise} ,sd= σ_{noise})

$$P(X_{n1} < u) \times P(X_{n2} < u) \times K \times P(X_{nM-1} < u) = \left[\int_{-\infty}^{u} f_n(x) dx\right]^{M-1}$$

Model in a nutshell

- Matched filtering:
 - o Linear transducer

$$\mu_{\text{target}}(c) = \beta c$$

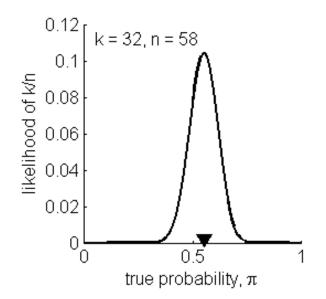
Zero response to distractors

$$\mu_{\text{nontarget}}(c) = 0$$

- We cannot separate out signal/noise, so fix noise arbitrarily: $\sigma_{\rm nontarget} = \sigma_{\rm target} = 1$
- Free parameters: β

- In R, load 'TrainData.csv'
- Dataframe with 5 variables: participant, contrast, square root signal energy, number correct responses, total number of trials
- Number of contrast levels and trials may vary across participants

- For each signal level: *n* bernoulli trials (i.e. binary outcome), with *k* out of *n* successes
- E.g. k = 32, n = 58
- Binomial likelihood function:



• Observed data are *frequencies* and the model predicts the "true" probability, π , from which those frequencies were generated

$$L(\pi; n, k) = \frac{n!}{k!(n-k)!} \pi^{k} (1-\pi)^{n-k}$$

- Or, in R: dbinom (k, n, π)
- Look at your SIMPLE code from last week

- Fit model to each participant separately
 - \circ For each signal: $eta E o \pi o$ likelihood
 - Across signals multiply likelihoods or, rather, sum log-likelihoods
 - Multiply by -2 (Deviance)
 - Minimise (e.g. optim or whatever optimisation routine you want) to find best fitting parameter(s)
- Overall goodness-of-fit: sum Deviance measures across participants

Improving the model

- Non-linear transducer?
 - o Logarithmic:

$$\mu(c) = \beta \ln c$$

o Power function:

$$\mu(c) = (\beta c)^{\gamma}$$

- Naka-Rushton equation (often used for single neuron response functions—ask me)
- Signal-dependent noise:

$$\sigma^2 = 1 + k\mu$$

• Mixture of visually guided responses and stimulus-independent responses ("finger errors", λ): $PC_i = w\pi_i + (1-w)\lambda$

Model selection

- Winner is determined with a common yard stick:
 - Fix the parameters of your best model fit to the training data
 - Compute total deviance for the test set
- If you have (lots of) time to spare:
 - Play around with other model selection methods: e.g. AIC, BIC, n-fold cross-validation (on the training and test sets combined)
 - Do different fitting and model selection methods give you the same answer?

Tournament!



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- What is the number of data points (for BIC)?
- What model selection method is best?
- Is MAX rule optimal?
- Applications beyond psychophysics?

- What is the number of data points (for BIC)?
 - o Total number of trials for a subject (i.e. 100s in this case per subject)?
 - Number of "proportion" samples (typically <10 per subject)?
- Similar considerations in more "typical" psychology experiments
 - E.g. N subjects doing M trials in K conditions
 - Model average RT in K conditions
 - o N x K?
 - \circ N x M x K?

- What model selection method is best?
- With a bit of luck, all selection methods say the same thing!
- Goals of the modelling:
 - o Best account of one or more benchmark data sets?
 - Generating predictions for future behaviour or experimental effects?
- Cross-validation makes no assumptions about measuring/quantifying complexity
- Very natural assessment of overfitting/generalisation, but no meaningful scale

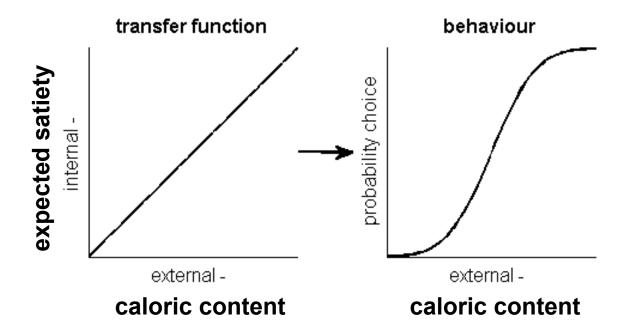
- Is MAX rule optimal?
 - o Given four noisy pattern responses X_i for i=1,...,4
 - At each location i: is the response more likely to have been generated from the "target distribution"?
 - Compute LR Location with greatest LR is most likely to have contained the target

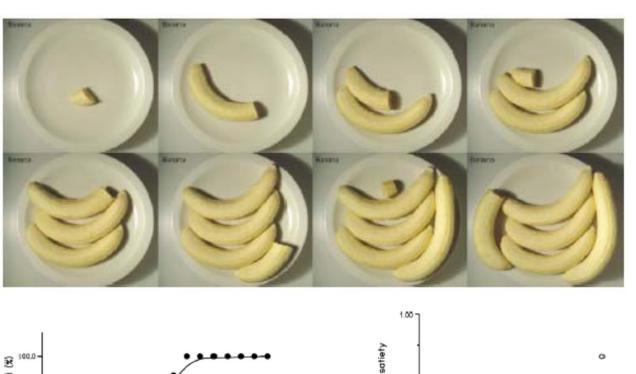
$$LR_{i} = \frac{f(X_{i} | \mu_{\text{target}}, \sigma_{\text{target}})}{f(X_{i} | \mu_{\text{nontarget}}, \sigma_{\text{nontarget}})}$$

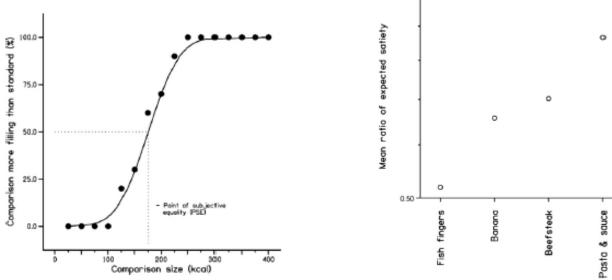
(Recall that $\mu_{\text{target}} \ge \mu_{\text{nontarget}} = 0$, $\sigma_{\text{target}} = \sigma_{\text{nontarget}} = 1$, and assume equal prior probability across locations)

- Applications beyond psychophysics?
- Three key ingredients:
 - Transfer function relating external dimension to an internal variable
 - Noise
 - o Choice rule

• Applications beyond psychophysics?

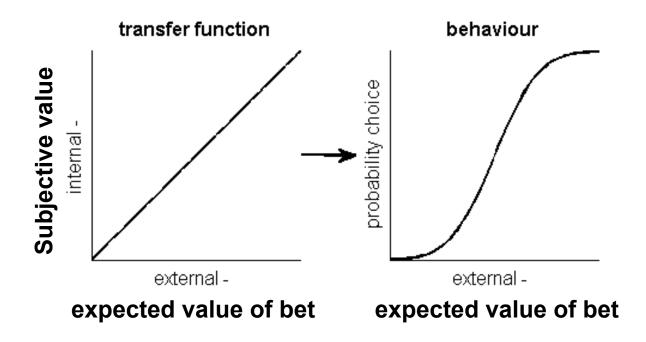






Brunstrom et al. (2008) Appetite

• Applications beyond psychophysics?



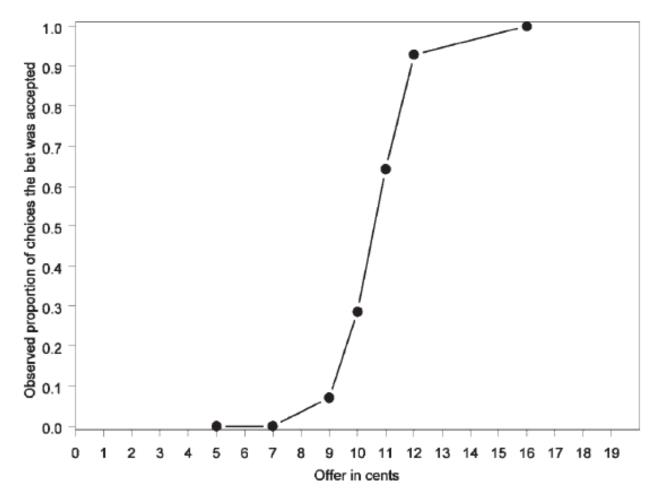
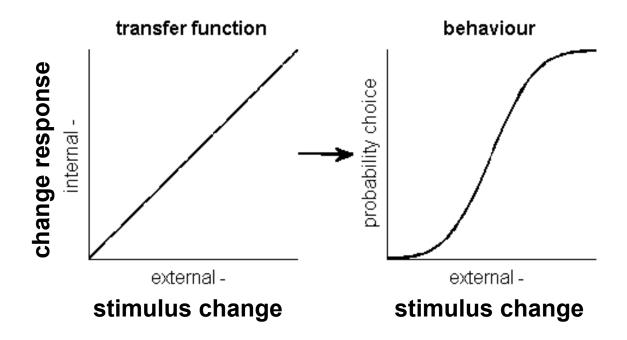
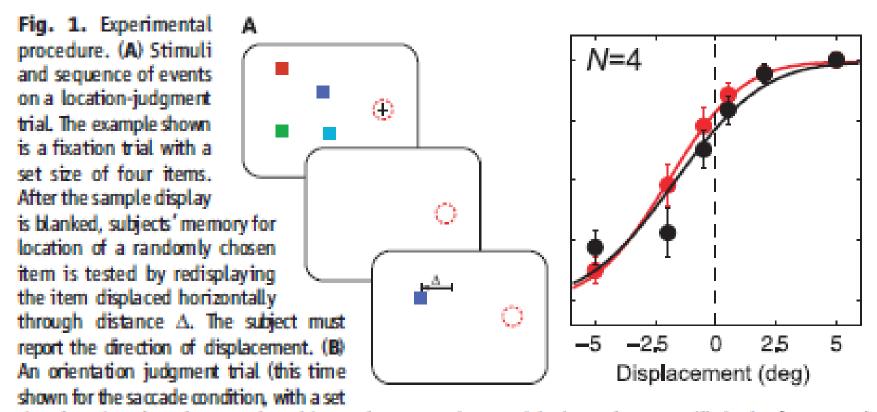


Figure 1. The choice proportions of participant B-I in Mosteller and Nogee (1951) of accepting a bet that led with a probability of .33 to a specific gain represented on the abscissa and with a probability of .67 to a loss of 5 cents. Each bet was offered 14 times, and when the participant rejected the bet, a payoff of zero resulted.

Mosteller & Nogee (1951), from Rieskamp (2008) *JEP: LMC*

• Applications beyond psychophysics?





size of two items). At the tone, the subject makes a saccade toward the item of a prespecified color (here green) with the display being blanked during the eye movement. A randomly chosen item is redisplayed, rotated through an angle Δ , and the subject reports the direction of rotation. Red circles indicate gaze position.

Bays & Husein (2008) Science