CS4224/CS5424 Lecture 6 Review of Concurrency Control

Transactions

- A transaction is an abstraction representing a logical unit of work
- Example: Transfer (x, y, amount)
 - transaction to transfer amount from account x to account y

```
BEGIN TRANSACTION;
SELECT balance INTO :Balx FROM Account WHERE accountld = :x;

SELECT balance INTO :Baly FROM Account WHERE accountld = :y;

If (:Balx < amount) then ABORT;

UPDATE Account SET balance = :Baly + :amount WHERE accountld = :y;

UPDATE Account SET balance = :Balx - :amount WHERE accountld = :x;

COMMIT;
```

Transaction Management

- Ensures four properties of transactions (Xacts) to maintain data in the face of concurrent access and system failures
 - 1. Atomicity: Either all or none of the actions in Xact happen
 - 2. **Consistency**: If each Xact is consistent, and the DB starts consistent, the DB ends up consistent
 - 3. **Isolation**: Execution of one Xact is isolated from other Xacts
 - 4. **Durability**: If a Xact commits, its effects persist
- The concurrency control manager component ensures isolation
- The recovery manager component ensures atomicity and durability

Transactions

- \triangleright A transaction (Xact) T_i can be viewed as a sequence of actions:
 - $ightharpoonup R_i(O) = T_i$ reads an object O
 - $W_i(O) = T_i$ writes an object O
 - $ightharpoonup Commit_i = T_i$ terminates successfully
 - $ightharpoonup Abort_i = T_i$ terminates unsuccessfully
- Each Xact must end with either a commit or an abort action
- ► An active Xact is a Xact that is still in progress (i.e., has not yet terminated)

Transactions

- ightharpoonup R(x), R(y), W(y), W(x), Commit
- ightharpoonup R(x), R(y), Abort

```
BEGIN TRANSACTION;
SELECT balance INTO :Balx FROM Account WHERE accountId = :x;

SELECT balance INTO :Baly FROM Account WHERE accountId = :y;

If (:Balx < amount) then ABORT;

UPDATE Account SET balance = :Baly + :amount WHERE accountId = :y;

UPDATE Account SET balance = :Balx - :amount WHERE accountId = :x;

COMMIT;
```

Transaction Schedules

- Schedule = a list of actions from a set of Xacts, where the order of the actions within each Xact is preserved
- **Example**: Consider two Xacts T_1 and T_2 :
 - ► T_1 : $R_1(A)$, $W_1(A)$, $R_1(B)$, $W_1(B)$, Commit
 - $ightharpoonup T_2$: $R_2(A)$, $W_2(A)$, $R_2(B)$, $W_2(B)$, $Commit_2$
- \triangleright Some schedules of T_1 and T_2 :
 - S_1 : $R_1(A), W_1(A), R_1(B), W_1(B), Commit_1, R_2(A), W_2(A), R_2(B), W_2(B), Commit_2$
 - S_2 : $R_2(A), W_2(A), R_2(B), W_2(B), Commit_2, R_1(A), W_1(A), R_1(B), W_1(B), Commit_1$
 - S_3 : $R_1(A), W_1(A), R_2(A), W_2(A), R_1(B), W_1(B), Commit_1, R_2(B), W_2(B), Commit_2$
- ► A serial schedule is a schedule where the actions of Xacts are not interleaved

Read From & Final Write

- We say that T_j reads O from T_i in a schedule S if the last write action on O before $R_i(O)$ in S is $W_i(O)$
- ightharpoonup We say that T_i reads from T_i if T_i has read some object from T_i
- We say that T_i performs the final write on O in a schedule S if the last write action on O in S is $W_i(O)$
- Example: Consider the following schedule:

```
R_1(A), W_1(A), R_2(A), W_2(A), R_1(B), W_1(B), Commit_1, R_2(B), W_2(B), Commit_2
```

- $ightharpoonup T_1$ reads A from the initial database (or T_1 reads A from T_0)
 - \star Assume that initial database was created by dummy Xact T_0
- $ightharpoonup T_2$ reads A from T_1
- $ightharpoonup T_1$ reads *B* from T_0
- $ightharpoonup T_2$ reads B from T_1
- ► T₂ performs the final write on A
- ► T₂ performs the final write on B

View Serializable Schedules

- Two schedules S and S' (over the same set of Xacts) are view equivalent (denoted by $S \equiv_V S'$) if they satisfy all the following conditions:
 - 1. If T_i reads A from T_j in S, then T_i must also read A from T_j in S'
 - 2. For each data object A, the Xact (if any) that performs the final write on A in S must also perform the final write on A in S'

Example:

- \triangleright S_3 : $R_1(x)$, $R_1(y)$, $W_1(y)$, $R_2(y)$, $R_2(x)$, $W_1(x)$, $W_2(x)$, $W_2(y)$
- $ightharpoonup S_5$: $R_1(x)$, $R_2(y)$, $R_1(y)$, $W_1(y)$, $R_2(x)$, $W_2(x)$, $W_2(y)$, $W_1(x)$
- $ightharpoonup S_6$: $R_1(x)$, $R_2(y)$, $R_1(y)$, $R_2(x)$, $W_1(y)$, $W_2(x)$, $W_1(x)$, $W_2(y)$
- ▶ $S_3 \not\equiv_V S_5$ as T_2 reads y from T_1 in S_3 but T_2 reads y from T_0 in S_5
- Similarly, $S_3 \not\equiv_{\nu} S_6$
- \triangleright $S_5 \equiv_V S_6$

View Serializable Schedules (cont.)

➤ A schedule *S* is a view serializable schedule (VSS) if *S* is view equivalent to some serial schedule over the same set of Xacts

Example:

▶ Consider two Xacts T_1 and T_2 :

```
* T_1: R_1(x), R_1(y), W_1(y), W_1(x)
```

- * T_2 : $R_2(y)$, $R_2(x)$, $W_2(x)$, $W_2(y)$
- ▶ Serial schedules over $\{T_1, T_2\}$:

```
\star S<sub>1</sub>: R<sub>1</sub>(x), R<sub>1</sub>(y), W<sub>1</sub>(y), W<sub>1</sub>(x), R<sub>2</sub>(y), R<sub>2</sub>(x), W<sub>2</sub>(x), W<sub>2</sub>(y)
```

*
$$S_2$$
: $R_2(y)$, $R_2(x)$, $W_2(x)$, $W_2(y)$, $R_1(x)$, $R_1(y)$, $W_1(y)$, $W_1(x)$

 \triangleright S_3 is not view serializable; S_4 is view serializable

```
\star S<sub>3</sub>: R_1(x), R_1(y), W_1(y), R_2(y), R_2(x), W_1(x), W_2(x), W_2(y)
```

* S_4 : $R_1(x)$, $R_1(y)$, $W_1(y)$, $R_2(y)$, $W_1(x)$, $R_2(x)$, $W_2(x)$, $W_2(y)$

Conflicting Actions

- Two actions on the same object conflict if
 - 1. at least one of them is a write action, and
 - 2. the actions are from different Xacts

Examples:

- $ightharpoonup R_1(x)$ and $R_2(x)$ do not conflict
- $ightharpoonup R_1(x)$ and $W_1(x)$ do not conflict
- $W_1(x)$ and $R_2(y)$ do not conflict
- $W_1(x)$ and $R_2(x)$ conflict
- $W_1(x)$ and $W_2(x)$ conflict

Conflict Serializable Schedules

Two schedules S & S' (over the same set of Xacts) are said to be conflict equivalent (denoted by $S \equiv_c S'$) if they order every pair of conflicting actions of two committed Xacts in the same way

Example:

- $ightharpoonup S_3$: $R_1(x)$, $R_1(y)$, $W_1(y)$, $R_2(y)$, $R_2(x)$, $W_1(x)$, $W_2(x)$, $W_2(y)$
- $ightharpoonup S_5$: $R_1(x)$, $R_2(y)$, $R_1(y)$, $W_1(y)$, $R_2(x)$, $W_2(x)$, $W_2(y)$, $W_1(x)$
- $ightharpoonup S_6$: $R_1(x)$, $R_2(y)$, $R_1(y)$, $R_2(x)$, $W_1(y)$, $W_2(x)$, $W_1(x)$, $W_2(y)$
- ▶ $S_3 \not\equiv_c S_5$ as $W_1(y)$ precedes $R_2(y)$ in S_3 but not in S_5
- ► Similarly, $S_3 \not\equiv_c S_6$
- \triangleright $S_5 \equiv_c S_6$

Conflict Serializable Schedules (cont.)

➤ A schedule is a conflict serializable schedule (CSS) if it is conflict equivalent to a serial schedule over the same set of Xacts

Example:

▶ Consider two Xacts T_1 and T_2 :

```
\star T_1: R_1(x), R_1(y), W_1(y), W_1(x)
```

- * T_2 : $R_2(y)$, $R_2(x)$, $W_2(x)$, $W_2(y)$
- ▶ Serial schedules over $\{T_1, T_2\}$:

```
\star S<sub>1</sub>: R<sub>1</sub>(x), R<sub>1</sub>(y), W<sub>1</sub>(y), W<sub>1</sub>(x), R<sub>2</sub>(y), R<sub>2</sub>(x), W<sub>2</sub>(x), W<sub>2</sub>(y)
```

*
$$S_2$$
: $R_2(y)$, $R_2(x)$, $W_2(x)$, $W_2(y)$, $R_1(x)$, $R_1(y)$, $W_1(y)$, $W_1(x)$

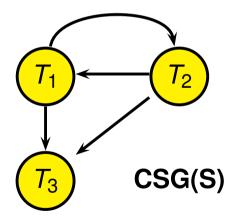
 \triangleright S_3 is not conflict serializable; S_4 is conflict serializable

```
\star S<sub>3</sub>: R_1(x), R_1(y), W_1(y), R_2(y), R_2(x), W_1(x), W_2(x), W_2(y)
```

*
$$S_4$$
: $R_1(x)$, $R_1(y)$, $W_1(y)$, $R_2(y)$, $W_1(x)$, $R_2(x)$, $W_2(x)$, $W_2(y)$

Testing for Conflict Serializability

- A conflict serializability graph for a schedule S (denoted by CSG(S)) is a directed graph G = (V, E) such that
 - V contains a node for each committed Xact in S
 - ► E contains (T_i, T_j) if an action in T_i precedes and conflicts with one of T_j 's actions
- **Example**: Conflict serializability graph for schedule $R_1(A)$, $W_2(A)$, $Commit_2$, $W_1(A)$, $Commit_1$, $W_3(A)$, $Commit_3$



- ► Theorem 1: A schedule is conflict serializable iff its conflict serializability graph is acyclic
- Theorem 2: A schedule that is conflict serializable is also view serializable

Blind Writes

- A write on object O by T_i is call a blind write if T_i did not read O prior to the write
 - ► Consider the schedule: $R_1(x)$, $W_2(y)$, $W_1(x)$
 - $W_2(y)$ is a blind write
 - $W_1(x)$ is a non-blind write
- ► **Theorem 3**: If S is view serializable and S has no blind writes, then S is also conflict serializable

Recoverable Schedules

$$\begin{array}{c|c} \mathbf{T_1} & \mathbf{T_2} \\ \hline W_1(x) & \\ R_2(x) \\ W_2(y) \\ \hline Commit_2 \end{array}$$

Non-Recoverable Schedule

➤ A schedule *S* is said to be a recoverable schedule if for every Xact *T* that commits in *S*, *T* must commit after *T'* if *T* reads from *T'*

Lock-Based Concurrency Control

- Each Xact needs to request for an appropriate lock on an object before the Xact can access the object
- Locking modes
 - Shared (S) locks for reading objects
 - Exclusive (X) locks for writing objects
- ► Lock compatibility:

Lock	Lock Held		
Requested	-	S	X
S			×
X		×	×

√: Compatible
Lock request is granted

IncompatibleLock request is blocked

Lock-Based Concurrency Control (cont.)

- To read an object O, a Xact must request for a shared/exclusive lock on
- 2. To **update an object** O, a Xact must request for an exclusive lock on O
- 3. A **lock request is granted** on *O* if the requesting lock mode is compatible with the lock modes of existing locks on *O*
- 4. If *T*'s **lock request is not granted** on *O*, *T* becomes **blocked**: its execution is suspended & *T* is added to *O*'s request queue
- 5. When a **lock is released** on *O*, the lock manager checks the request of the first Xact *T* in the request queue for *O*. If *T*'s request can be granted, *T* acquires its lock on *O* and resumes execution after its removal from the queue
- 6. When a Xact **commits/aborts**, all its locks are released & T is removed from any request queue it's in

Two Phase Locking (2PL) Protocol

► 2PL Protocol:

- 1. To read an object O, a Xact must hold a S-lock or X-lock on O
- 2. To write to an object O, a Xact must hold a X-lock on O
- 3. Once a Xact releases a lock, the Xact can't request any more locks
- Xacts using 2PL can be characterized into two phases:
 - ► Growing phase: before releasing 1st lock
 - ► Shrinking phase: after releasing 1st lock
- ► Theorem 4: 2PL schedules are conflict serializable

Strict Two Phase Locking (strict 2PL) Protocol

► 2PL Protocol:

- 1. To read an object O, a Xact must hold a S-lock or X-lock on O
- 2. To write to an object O, a Xact must hold a X-lock on O
- 3. Once a Xact releases a lock, the Xact can't request any more locks
- Theorem 4: 2PL schedules are conflict serializable
- Strict 2PL Protocol:
 - 1. To read an object O, a Xact must hold a S-lock or X-lock on O
 - 2. To write to an object O, a Xact must hold a X-lock on O
 - 3. A Xact must hold on to locks until Xact commits or aborts
- Theorem 5: Strict 2PL schedules are strict & conflict serializable

Lock Management

- Handling deadlocks
- Lock conversion

Deadlocks

- Deadlock: cycle of Xacts waiting for locks to be released by each other
- Example:

```
T_1 requests X-lock on A and is granted;
```

 T_2 requests X-lock on B and is granted;

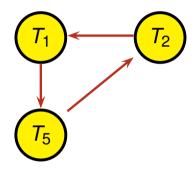
 T_1 requests X-lock on B and is blocked;

 T_2 requests X-lock on A and is blocked;

- Dealing with deadlocks:
 - deadlock detection
 - deadlock prevention

How to Detect Deadlocks?

- Waits-for graph (WFG)
 - Nodes represent active Xacts
 - ▶ Add an edge $T_i \rightarrow T_j$ if T_i is waiting for T_j to release a lock



- Lock manager
 - adds an edge when it queues a lock request
 - updates edges when it grants a lock request
- Deadlock is detected if WFG has a cycle
- Breaks a deadlock by aborting a Xact in cycle
- Alternative to WFG: timeout mechanism

How to Prevent Deadlocks?

- Assume older Xacts have higher priority than younger Xacts
 - Each Xact is assigned a timestamp when it starts
 - An older Xact has a smaller timestamp
- ightharpoonup Suppose T_i requests for a lock that conflicts with a lock held by T_i
- Two possible deadlock prevention policies:
 - Wait-die policy: lower-priority Xacts never wait for higher-priority Xacts
 - Wound-wait policy: higher-priority Xacts never wait for lower-priority Xacts

Prevention Policy	T_i has higher priority	T_i has lower priority
Wait-die	T_i waits for T_i	T_i aborts
Wound-wait	T_j aborts	T_i waits for T_j

- Wait-die policy
 - non-preemptive: only a Xact requesting for a lock can get aborted
 - a younger Xact may get repeatedly aborted
 - a Xact that has all the locks it needs is never aborted
- Wound-wait policy

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- preemptive
- To avoid starvation, a restarted Xact must use its original timestamp!

Lock Conversion

Consider two Xacts:

```
T_1: R_1(A), R_1(B), W_1(A)
T_2: R_2(A), R_2(B)
```

- Since T_1 needs to both read & update A, T_1 acquires an exclusive lock to read A
- All possible schedules are serial

```
S_1: R_1(A), R_1(B), W_1(A), R_2(A), R_2(B)
S_2: R_2(A), R_2(B), R_1(A), R_1(B), W_1(A)
```

- Increase concurrency by allowing lock conversions
- Two types of lock conversions
 - ► *T_i* upgrades its S-lock on object A to X-lock
 - ► *T_i* downgrades its X-lock on object A to S-lock

Lock Conversion (cont.)

Interleaved executions become possible with lock upgrading:

```
S_3: R_1(A), R_2(A), R_2(B), R_1(B), W_1(A)

S_4: R_1(A), R_1(B), R_2(A), R_2(B), W_1(A)

S_5: R_1(A), R_2(A), R_1(B), R_2(B), W_1(A)
```

- Lock upgrade on object A
 - Upgrade request is blocked if another Xact is holding a shared lock on A
 - ▶ Upgrade request is allowed if T_i has not released any lock
- Lock downgrade on object A
 - Downgrade request is allowed if
 - 1. T_i has not modified A, and
 - 2. T_i has not released any lock

Multiversion Concurrency Control (MVCC)

Schedule S

T ₁	T ₂	_	T ₁	T ₂
$R_1(x)$			$R_1(x)$	
$W_1(x)$			$W_1(x)$	
	$R_2(x)$		$R_1(y)$	
	$W_2(y)$		ζ.,	$R_2(x)$
$R_1(y)$	(-)			$W_2(y)$
$W_1(z)$			$W_1(z)$	

Schedule S'

Multiversion Concurrency Control (MVCC)

- Key idea: maintain multiple versions of each object
 - \triangleright $W_i(O)$ creates a new version of object O
 - $ightharpoonup R_i(O)$ reads an appropriate version of O
- Advantages:
 - Read-only Xacts are not blocked by update Xacts
 - Update Xacts are not blocked by read-only Xacts
 - Read-only Xacts are never aborted
- Notation:
 - $\bigvee W_i(x)$ creates a new version of x denoted by x_i
 - For each object x, its initial version is denoted by x_0

MVCC: Example 1

T ₁	T ₂	Comments
		$x_0 = 10$
	$R_2(x)$	10
$W_1(x)$?

- ► In **2PL**, $W_1(x)$ will be blocked
- ► In MVCC,
 - $ightharpoonup T_1$ creates a new version of x
 - Update Xacts are not blocked by read-only Xacts

MVCC: Example 2

T ₁	T ₂	Comments
		$x_0 = 10, y_0 = 20$
	$R_2(x)$	10
$W_1(y)$		$y_1 = 100$
	$R_2(y)$?

- ► In **2PL**, $R_2(y)$ will be blocked
- ► In MVCC,
 - $W_1(y)$ creates a new version of y (with a value of 100)
 - $ightharpoonup R_2(y)$ is not blocked
 - $ightharpoonup R_2(y)$ returns 20 (the value of the version before $W_1(y)$)
 - Read-only Xacts are never blocked/aborted

Multiversion Schedules

- If there are multiple versions of an object x, a read action on x could return any version
- ► Thus, an interleaved execution could correspond to different multiversion schedules depending on the MVCC protocol
- **Example**: $R_1(x)$, $W_1(x)$, $R_2(x)$, $W_2(y)$, $R_1(y)$, $W_1(z)$ S_1 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_0)$, $W_2(y_2)$, $R_1(y_0)$, $W_1(z_1)$ S_2 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_0)$, $W_2(y_2)$, $R_1(y_2)$, $W_1(z_1)$ S_3 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_1)$, $W_2(y_2)$, $R_1(y_0)$, $W_1(z_1)$ S_4 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_1)$, $W_2(y_2)$, $R_1(y_2)$, $W_1(z_1)$
 - $ightharpoonup R_1(x)$ returns x_0
 - $ightharpoonup R_2(x)$ could return x_0 or x_1
 - $ightharpoonup R_1(y)$ could return y_0 or y_2

Multiversion View Equivalence

- Two schedules, S and S', over the same set of transactions, are defined to be multiversion view equivalent ($S \equiv_{mv} S'$) if they have the same set of read-from relationships
 - i.e. $R_i(x_i)$ occurs in S iff $R_i(x_i)$ occurs in S'

Example:

```
S_1: R_3(x_0), W_3(x_3), Commit_3, W_1(x_1), Commit_1, R_2(x_1), W_2(y_2), Commit_2

S_2: R_3(x_0), W_3(x_3), Commit_3, W_1(x_1), R_2(x_3), Commit_1, W_2(y_2), Commit_2

S_3: W_1(x_1), Commit_1, R_2(x_1), R_3(x_0), W_2(y_2), W_3(x_3), Commit_3, Commit_2
```

- ▶ $S_1 \not\equiv_{mv} S_2$ because $R_2(x_1) \in S_1$ and $R_2(x_3) \in S_2$
- $ightharpoonup S_1 \equiv_{mv} S_3$

Monoversion Schedules

- A multiversion schedule *S* is called a monoversion schedule if each read action in *S* returns the most recently created object version
- ► Example: $R_1(x)$, $W_1(x)$, $R_2(x)$, $W_2(y)$, $R_1(y)$, $W_1(z)$ S_1 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_0)$, $W_2(y_2)$, $R_1(y_0)$, $W_1(z_1)$ S_2 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_0)$, $W_2(y_2)$, $R_1(y_2)$, $W_1(z_1)$
 - S_3 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_1)$, $W_2(y_2)$, $R_1(y_0)$, $W_1(z_1)$
 - S_4 : $R_1(x_0)$, $W_1(x_1)$, $R_2(x_1)$, $W_2(y_2)$, $R_1(y_2)$, $W_1(z_1)$
 - \triangleright S_4 is a monoversion schedule
 - \triangleright S_1 , S_2 , and S_3 are not monoversion schedules

Serial Monoversion Schedules

- A monoversion schedule is defined to be a serial monoversion schedule if it is also a serial schedule
- Example:

```
S_1: R_1(x_0), W_1(x_1), R_2(x_1), W_2(y_2), R_1(y_2), W_1(z_1)
S_2: R_1(x_0), W_1(x_1), R_1(y_0), W_1(z_1), R_2(x_1), W_2(y_2)
```

- \triangleright S_1 is a non-serial monoversion schedule
- \triangleright S_2 is a serial monoversion schedule

Multiversion View Serializability

A multiversion schedule *S* is defined to be multiversion view serializable schedule (MVSS) if there exists a **serial monoversion schedule** (over the same set of Xacts) that is multiversion view equivalent to *S*

MVSS: Example 1

Consider schedule S:

$$W_1(x_1)$$
, Commit₁, $R_2(x_1)$, $R_3(x_0)$, $W_2(y_2)$, $W_3(x_3)$, Commit₂, Commit₂

▶ S is multiversion view serializable as $S \equiv_{mv} (T_3, T_1, T_2)$:

 $R_3(x_0)$, $W_3(x_3)$, Commit₃, $W_1(x_1)$, Commit₁, $R_2(x_1)$, $W_2(y_2)$, Commit₂

MVSS: Example 2

Consider the following schedule S:

T_1	T_2
$R_1(x_0)$	
	$R_2(x_0)$
$R_1(y_0)$	
	$R_{2}(y_{0})$
$W_1(x_1)$	
Commit ₁	
	$W_2(y_2)$
	Commit ₂

- S is not multiversion view serializable
- S is not multiversion view equivalent to any serial monoversion schedule
 - $ightharpoonup R_1(x_0), R_1(y_0), W_1(x_1), C_1, R_2(x_1), R_2(y_0), W_2(y_2), C_2$
 - Arr $R_2(x_0), R_2(y_0), W_2(y_2), C_2, R_1(x_0), R_1(y_2), W_1(x_1), C_1$

MVSS: Example 3

Consider the following schedule S:

<i>T</i> ₁	T_2	T_3
$R_1(y_0)$		
	$R_2(x_0)$	
$W_1(y_1)$		
Commit ₁		
	$R_2(y_0)$	
	$W_2(x_2)$	
		$R_3(x_0)$
		$R_3(y_1)$
		Commit ₃
	Commit ₂	

- S is not multiversion view serializable
 - ▶ Suppose S' is a serial monoversion schedule where $S' \equiv_{mv} S$
 - ► T_3 must precede T_2 in S' due to $R_3(x_0)$ & $W_2(x_2)$
 - ► T_2 must precede T_1 in S' due to $R_2(y_0)$ & $W_1(y_1)$
 - ► T_1 must precede T_3 in S' due to $W_1(y_1) \& R_3(y_1)$

Multiversion View Serializability

- ► Theorem 6: A view serializable schedule (VSS) is also a multiversion view serializable schedule (MVSS)
- A MVSS is not necessarily VSS
- Example:

```
T_1: R_1(x_0), R_1(y_0), Commit_1

T_2: W_2(x_2), W_2(y_2), Commit_2,
```

- ▶ The above schedule is multiversion view equivalent to the serial monoversion schedule (T_1, T_2)
- ► However, the schedule is not a valid monoversion schedule (due to $W_2(y_2)$ & $R_1(y_0)$) and is therefore not VSS

MVCC Protocols

- Multiversion two-phase locking
- Multiversion timestamp ordering
- Snapshot isolation

Snapshot Isolation (SI)

- Widely used (e.g., Oracle, PostgreSQL, SQL Server, Sybase IQ)
- Each Xact T sees a snapshot of DB that consists of updates by Xacts that committed before T starts
- ► Each Xact *T* is associated with two timestamps:
 - ► start(T): the time that T starts
 - ightharpoonup commit(T): the time that T commits

Concurrent Transactions

ightharpoonup Two Xacts T and T' are defined to be concurrent if they overlap

▶ i.e., $[start(T), commit(T)] \cap [start(T'), commit(T')] \neq \emptyset$

Example:

Timestamp	T_1	T_2	T_3
1	$R_1(B)$		
2		$R_2(A)$	
3	$W_1(B)$		
4	Commit ₁		
5		$R_2(B)$	
6		$W_2(A)$	
7			$R_3(A)$
8			$R_3(B)$
9			Commit ₃
10		Commit ₂	

Snapshot Isolation (SI)

- $ightharpoonup W_i(O)$ creates a version of O denoted by O_i
- ► O_i is a more recent (or newer) version compared to O_j if $commit(T_i) > commit(T_j)$
- ▶ $\mathbf{R_i}(\mathbf{O})$ reads either its own update (if $W_i(O)$ precedes $R_i(O)$) or the latest version of O that is created by a Xact that committed before T_i started; i.e., If $R_i(O)$ returns O_i , then
 - 1. Either j = i if $W_i(O)$ precedes $R_i(O)$;
 - 2. Or
 - 2.1 $commit(T_i) < start(T_i)$, and
 - 2.2 For every Xact T_k , $k \neq j$, that has created a version O_k of O_k , if $commit(T_k) < start(T_i)$, then $commit(T_k) < commit(T_i)$

Example

T_1	T_2	T_3	Comments
$R_1(x)$			<i>x</i> ₀
$W_1(x)$			<i>X</i> ₁
$R_1(y)$			y 0
	$R_2(x)$		<i>x</i> ₀
$W_1(y)$			<i>y</i> ₁
Commit ₁			
	$R_2(y)$		y 0
	$W_2(x)$		X ₂
		$R_3(x)$	<i>X</i> ₁
		$R_3(y)$	<i>y</i> ₁
		$W_3(y)$	У 3
		$R_3(y)$	У 3
		Commit ₃	

Snapshot Isolation

- Concurrent Update Property: If multiple concurrent Xacts updated the same object, only one of Xacts is allowed to commit
- If not, the schedule may not be serializable
- **Example**: Consider the following schedule *S*

```
T_1: R_1(x_0) W_1(x_1) Commit_1

T_2: R_2(x_0) W_2(x_2) Commit_2
```

S is not serializable!

- Two approaches to enforce the concurrent update property:
 - First Committer Wins (FCW) Rule
 - First Updater Wins (FUW) Rule

First Committer Wins (FCW) Rule

- Before committing a Xact T, the system checks if there exists a committed concurrent Xact T' that has updated some object that T has also updated
- ightharpoonup If T' exists, then T aborts
- Otherwise, T commits
- **Example 1**:

$$T_1$$
: $R_1(x)$ $W_1(x)$ Abort₁
 T_2 : $R_2(x)$ $W_2(x)$ Commit₂

Example 2:

```
T_1: R_1(x) W_1(x) Commit<sub>1</sub>
T_2: R_2(x) W_2(x) Abort<sub>2</sub>
```

First Updater Wins (FUW) Rule

- Whenever a Xact T needs to update an object O, T requests for a X-lock on O
- If the X-lock is not held by any concurrent Xact, then
 - ► *T* is granted the X-lock on *O*
 - ▶ If *O* has been updated by any concurrent Xact, then *T* aborts
 - Otherwise, T proceeds with its execution
- ▶ Otherwise, if the X-lock is being held by some concurrent Xact T', then T waits until T' aborts or commits
 - ▶ If T' aborts, then
 - ★ Assume that *T* is granted the X-lock on *O*
 - ★ If O has been updated by any concurrent Xact, then T aborts
 - ★ Otherwise, *T* proceeds with its execution
 - ▶ If T' commits, then T is aborted
- When a Xact commits/aborts, it releases its X-lock(s)

Write Skew Anomaly

$$T_1$$
 T_2
 $R_1(x_0)$ $R_2(x_0)$
 $R_1(y_0)$ $R_2(y_0)$
 $W_1(x_1)$ $W_2(y_2)$
 $Commit_2$

The above is a SI schedule that is not a MVSS

Read-Only Transaction Anomaly

T ₁	T_2	T_3
$R_1(y_0)$		
	$R_2(x_0)$	
$W_1(y_1)$		
Commit ₁		
	$R_2(y_0)$	
	$W_2(x_2)$	
		$R_3(x_0)$
		$R_3(y_1)$
		Commit ₃
	Commit ₂	

The above is a SI schedule that is not a MVSS

Serializable Snapshot Isolation (SSI) Protocol

- This is a stronger protocol that guarantees serializable SI schedules
- ➤ A schedule S is defined to be a serializable snapshot isolation (SSI) schedule if S is produced by the snapshot isolation protocol (i.e., S is a SI schedule) and S is MVSS

Garbage Collection

A version O_i of object O may be deleted if there exists a newer version O_j (i.e., $commit(T_i) < commit(T_j)$) such that for every active Xact T_k that started after the commit of T_i (i.e., $commit(T_i) < start(T_k)$), we have $commit(T_i) < start(T_k)$

Example:

```
W_1(x_1), C_1,
W_2(x_2), C_2,
W_4(x_4), C_4,
R_3(y_0),
W_5(x_5), C_5,
R_6(z_0)
```

- ightharpoonup Active transactions: $T_3 \& T_6$
- Versions that can be deleted: x₁ & x₄