Real Analysis

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Limit Theory for the Real Numbers

Proposition 1.0.1. Let $(x_n)_{n\in\mathbb{N}}$ be a sequence of real numbers. Suppose that $\lim_{n\in\mathbb{N}} x_n = x_{\bullet}$ for some $x_{\bullet} \in \mathbb{R}$. Then

$$\lim_{n\in\mathbb{N}} \overline{x}_n := \lim_{n\in\mathbb{N}} \frac{1}{n} \sum_{i=1}^n x_i = x_{\bullet}.$$

Differentiation

2.1 Differentiability

Definition (Directional Derivative). Let f be a proper function from \mathbb{R}^n to \mathbb{R}^* . Let x_0 be a point in dom(f). Let d be a point in \mathbb{R}^n . We define the **directional derivative** of f at point x_0 in the direction of d, denoted by $f'(x_0; d)$, to be a number given by

$$f'(x_0; d) := \lim_{t \to 0} \frac{f(x + td) - f(x)}{t}.$$

Definition (Differentiable). Let f be a proper function from \mathbb{R}^n to \mathbb{R}^* . Let x_0 be a point in dom(f). We say that f is **differentiable** at point x_0 if there exists a linear operator ∇ from \mathbb{R}^n to \mathbb{R}^n such that

$$\lim_{\|y\| \to 0} \frac{\left| f(x_0 + y) - f(x_0) - \langle \nabla f(x_0), y \rangle \right|}{\|y\|} = 0.$$

2.2 Properties

Proposition 2.2.1. Let f be a proper function from \mathbb{R}^n to \mathbb{R}^* . Let x_0 be a point in dom(f). Let d be a point in \mathbb{R}^n . Assume that f is differentiable at point x_0 . Then we have

$$f'(x_0; d) = \langle \nabla f(x), d \rangle.$$

2.3 Examples

Example 2.3.1.

$$f(x,y) = (x^2 + y^2)\sin(\frac{1}{\sqrt{x^2 + y^2}})$$

for $(x, y) \neq 0$ and f(0, 0) = 0.

2.4 Higher Order Differentiation

Theorem 1 (Hermann Schwarz and Alexis Clairaut). Let f be a function from some subset Ω of \mathbb{R}^n to \mathbb{R}^n . Let p be an interior point of Ω . Then if f has continuous second order partial derivatives at point p, we get

$$\forall i, j \in \{1, ..., n\}, \frac{\partial^2 f}{\partial x_i \partial x_j}(p) = \frac{\partial^2 f}{\partial x_j \partial x_i}(p).$$

2.5 Differentiation w.r.t. Vectors

Definition. Let $\vec{x} = (x_1, ..., x_n)$ be a vector. Let $y = f(\vec{x})$. We define

$$\frac{\partial y}{\partial \vec{x}} := \begin{bmatrix} \frac{\partial y}{\partial x_1} \\ \vdots \\ \frac{\partial y}{\partial x_n} \end{bmatrix}.$$

Proposition 2.5.1. Quick results:

$$(1) \ \frac{\partial \left[\vec{a} \cdot \vec{x}\right]}{\partial \vec{x}} = \vec{a}.$$

(2)
$$\frac{\partial \left[\vec{x}^T A \vec{x}\right]}{\partial \vec{x}} = Ax + A^T x.$$

2.6 Inverse Function Theorem

Theorem 2. Let F be a C^1 function from Ω to \mathbb{R}^n where Ω is some open subset of \mathbb{R}^n . Let x be some point in Ω . Then if $|J_F(p)| \neq 0$, F is invertible near x. Further, F^{-1} is C^1 at F(x) and

$$J_{F^{-1}}(F(x)) = (J_F(x))^{-1}.$$

Scalar Series

3.1 Convergence

Definition (Convergence). Let $S = \sum_{i=1}^{\infty} a_i$ be an infinite series. We say that S converges if the limit $\lim_{n\to\infty} \sum_{i=1}^{n} a_i$ exists.

Definition (Absolute Convergence). Let $S = \sum_{i=1}^{\infty} a_i$ be an infinite series. We say that S converges absolutely if the series $\sum_{i=1}^{\infty} |a_i|$ converges.

Definition (Conditional Convergence). Let $S = \sum_{i=1}^{\infty} a_i$ be an infinite series. We say that S converges conditionally if it converges but does not converge absolutely.

3.2 Properties

Theorem 3 (Bernhard Riemann). If an infinite series of real numbers is conditionally convergent, then its terms can be arranged in a permutation so that the new series converges to an arbitrary real number, or diverges. i.e., if $S = \sum_{i=1}^{\infty} a_i$ where $a_i \in \mathbb{R}$ converges conditionally, then for any real number l, there exists some permutation σ such that $S_{\sigma} := \sum_{i=1}^{\infty} a_{\sigma(i)} = l$; and there exists some permutation τ such that $S_{\tau} := \sum_{i=1}^{\infty} a_{\tau(i)}$ diverges.

Proposition 3.2.1. Let $\{x_n\}_{n\in\mathbb{N}}$ be a sequence of real numbers. Suppose that the partial sum sequence $\{S_n\}_{n\in\mathbb{N}}$ is bounded. Then $\{x_n\}_{n\in\mathbb{N}}$ must be bounded.

Proof. Assume for the sake of contradiction that the sequence $\{x_n\}_{n\in\mathbb{N}}$ is unbounded. Since the partial sum sequence $\{S_n\}_{n\in\mathbb{N}}$ is bounded, $\exists M\in\mathbb{R}$ such that $\forall n\in\mathbb{N}, |S_n|\leq M$.

3.3 Convergence Tests

Theorem 4 (Ernst Kummer). Let $\{a_n\}_{n\in\mathbb{N}}$ be a sequence of scalars. Consider the series $\sum_{n=1}^{\infty} a_n$. Let ζ_n be an auxiliary sequence of positive constants. Define

$$\rho_n := \zeta_n \frac{a_n}{a_{n+1}} - \zeta_{n+1}.$$

 $Then\ the\ series$

- (1) converges if $\liminf_{n\to\infty} \rho_n > 0$, and
- (2) diverges if $\limsup_{n\to\infty} \rho_n < 0$ and $\sum 1/\zeta_n$ diverges.

Series of Functions

4.1 Power Series

Definition. A power series (in one variable) is an infinite series S of the form

$$S = \sum_{i=0}^{\infty} a_i (x - c)^i.$$

Proposition 4.1.1. Every power series is the Taylor series of some smooth function.

Riemann Integration

5.1 Definitions

Definition (Riemann Sum). Let $(X, \|\cdot\|)$ be a Banach space. Let a and b be real numbers with a < b. Let f be a function from [a,b] to X. Let $P = \{a = p_0 < p_1 < ... < p_{N-1} < p_N = b\}$ be a partition of the interval [a,b]. Let $P^* = \{\xi_i : i = 1..N\}$ be a set of choices of sample points where $\forall i = 1..N$, $\xi_i \in [p_{i-1}, p_i]$. We define the **Riemann sum** of f w.r.t. partition P and sample points P^* , denoted by $S(f, P, P^*)$, to be the vector given by

$$S(f, P, P^*) := \sum_{i=1}^{N} f(\xi_i)(p_i - p_{i-1}).$$

Definition (Riemann Integrable). Let $(X, \|\cdot\|)$ be a Banach space. Let a and b be real numbers with a < b. Let f be a function from [a, b] to X. We say that f is **Riemann Integrable** if

$$\exists x_0 \in X, \forall \varepsilon > 0, \exists P \in \mathcal{P}[a, b], \forall Q \supseteq P, \forall Q^*, \quad ||x_0 - S(f, Q, Q^*)|| < \varepsilon.$$

Proposition 5.1.1. The vector x_0 in the definition is unique, if it exists.

Definition (Riemann Integral). Let $(X, \|\cdot\|)$ be a Banach space. Let a and b be real numbers with a < b. Let f be a Riemann integrable function from [a, b] to X. We define the **Riemann Integral** of f, denoted by $\int_a^b f$, to be the unique vector x_0 . i.e.

$$x_0 = \int_a^b f.$$

5.2 Cauchy Criterion

Proposition 5.2.1 (Cauchy Criterion). Let $(X, \|\cdot\|)$ be a Banach space. Let a and b be real numbers with a < b. Let f be a function from [a, b] to X. Then f is integrable if and

 $only\ if$

$$\forall \varepsilon > 0, \ \exists P \in \mathcal{P}[a,b], \ \forall R_1, R_2 \supseteq P, \ \forall R_1^*, R_2^*, \quad \|S(f,R_1,R_1^*) - S(f,R_2,R_2^*)\| < \varepsilon.$$

5.3 Properties

Proposition 5.3.1. Continuous functions are Riemann integrable.