# **Stochastic Process**

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### Stochastic Process

#### 1.1 Definitions

**Definition** (Stochastic Process). Let  $\mathcal{T}$  be an index set. Let X(t) be a random variable. We define a **stochastic process** to be the net  $(X(t))_{t\in\mathcal{T}}$ .

**Definition** (Discrete-Time Stochastic Process). Let  $(X(t))_{t\in\mathcal{T}}$  be a stochastic process. We say that it is a **discrete-time stochastic process** if the index set  $\mathcal{T}$  is countable.

**Definition** (Markov Property). Let S be a state space. Let  $(X_n)_{n\in\mathbb{N}}$  be a discrete-time stochastic process. We say that is has the **Markov property** if

$$\forall n \in \mathbb{N}, \forall x_0..x_{n+1} \in \mathcal{S}, \quad \Pr(X_{n+1} = x_{n+1} \mid (X_n)_{n=0}^n = (x_n)_{n=0}^n) = \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n).$$

This property states that the conditional distribution of any future state  $X_{n+1}$  given the past states  $X_0, ..., X_{n-1}$  and the present state  $X_n$  is independent of the past states.

i.e., if we know the value taken by te process at a given time, we will not get any additional information about the future behavior of the process by gathering more knowledge about the past.

**Definition** (Markov Chain). We define a **Markov chain** to be a discrete-time stochastic process with the Markov property.

#### Proposition 1.1.1.

$$\forall n \in \mathbb{N}, \forall j \in \{0..n-1\}, \forall x_0..x_{n+1} \in \mathcal{S}, \quad \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n, (X_i)_{i=1}^{j-1} = (x_i)_{i=1}^{j-1}, (X_i)_{i=j+1}^{n-1} = (x_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1} = (x_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1} = (x_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1} = (x_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1} = (x_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1} = (X_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1} = (X_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1} = (X_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1} = (X_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1} = (X_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1} = (X_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1} = (X_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1} = (X_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1}, (X_i)_{i=1}^{n-1}, (X_i)_{i=j+1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1}, (X_i)_{i=1}^{n-1}, (X_i)_{i=1}^{n-1}, (X_i)_{i=1}^{n-1}) = \Pr(X_i = x_i, (X_i)_{i=1}^{n-1}, (X_i)_{i=1}^$$

Proof.

$$\Pr(X_{n+1} = x_{n+1} \mid X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})$$
(1.1)

$$= \frac{\Pr(X_{n+1} = x_{n+1}, X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}{\Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}$$
(1.2)

$$= \frac{\sum_{x_j=0}^{\infty} \Pr(X_{n+1} = x_{n+1}, X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j}, X_j = x_j)}{\Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}$$
(1.3)

$$=\frac{\sum_{x_{j}=0}^{\infty}\Pr(X_{n+1}=x_{n+1}\mid X_{n}=x_{n},(X_{i})_{i\neq j}=(x_{i})_{i\neq j},X_{j}=x_{j})\Pr(X_{n}=x_{n},(X_{i})_{i\neq j}=(x_{i})_{i\neq j},X_{j}=x_{j})}{\Pr(X_{n}=x_{n},(X_{i})_{i\neq j}=(x_{i})_{i\neq j})}$$

$$(1.4)$$

$$= \frac{\sum_{x_j=0}^{\infty} \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n) \Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j}, X_j = x_j)}{\Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}$$
(1.5)

$$= \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n) \frac{\sum_{x_j=0}^{\infty} \Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j}, X_j = x_j)}{\Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}$$
(1.6)

$$= \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n) \frac{\Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}{\Pr(X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j})}$$
(1.7)

$$= \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n). \tag{1.8}$$

That is,

$$\Pr(X_{n+1} = x_{n+1} \mid X_n = x_n, (X_i)_{i \neq j} = (x_i)_{i \neq j}) = \Pr(X_{n+1} = x_{n+1} \mid X_n = x_n).$$

**Definition** (Transition Probability). Let i and j be a pair of states. Let n be some time step. We define the **transition probability** from state i at time n to state j at time n+1, denoted by  $P_{n,i,j}$ . to be the conditional probability given by

$$P_{n,i,j} = \Pr(X_{n+1} = j \mid X_n = i).$$

**Definition** (Stationary / Homogeneous). We say that a discrete-time Markov chain is stationary or homogeneous if  $\forall i, j \in \mathcal{S}, \ \forall n \in \mathbb{N}, \ P_{n,i,j} = P_{i,j} \ for \ some \ P_{i,j}$ .

**Theorem 1** (Chapman-Kolmogorov Equations).

$$P^{(n)} = P^{(m)}P^{(n-m)}$$

#### 1.2 Accessibility and Communication

**Definition** (Accessible). Let i and j be two states. We say that state j is **accessible** from state i if  $\exists n \in \mathbb{N}$  such that  $P_{i,j}^{(n)} > 0$ .

**Definition** (Communicate). Let i and j be two states. We say that state i and state j communicate if i and j are accessible from each other.

**Proposition 1.2.1.** The communication relation is an equivalence relation. i.e., it is reflexive, symmetric, and transitive.

1.3. PERIODICITY 3

#### Proof. Transitivity:

Let i, j, k be states. Assume that  $i \leftrightarrow j$  and  $j \leftrightarrow k$ . We are to prove that  $i \leftrightarrow k$ . Since  $i \leftrightarrow j$ ,  $\exists n \in \mathbb{N}$  such that  $P_{i,j}^{(n)} > 0$ . Since  $j \leftrightarrow k$ ,  $\exists m \in \mathbb{N}$  such that  $P_{i,j}^{(m)} > 0$ . By the Chapman-Kolmogorov equation, we get

$$P_{i,k}^{(n+m)} = \sum_{l=0}^{\infty} P_{i,l}^{(n)} P_{l,k}^{(m)} \ge P_{i,j}^{(n)} P_{j,k}^{(m)} > 0.$$

That is,  $P_{i,k}^{(n+m)} > 0$ . So  $i \to k$ . Similarly, we can show that  $k \to i$ . So  $i \leftrightarrow k$ .

**Proposition 1.2.2.** Let i and j be two states. If state j is not accessible from state i, then

$$Pr(DTMC \ ever \ exists \ state \ j \mid X_0 = i) = 0.$$

*Proof.* Since state j is not accessible from state i, we have  $\forall n \in \mathbb{N}, P_{i,j}^{(n)} = 0.$ 

 $Pr(DTMC \text{ ever exists state } j \mid X_0 = i)$ 

$$= \Pr(\bigcup_{n=0}^{\infty} \{X_n = j\} \mid X_0 = i) \le \sum_{n=0}^{\infty} \Pr(X_n = j \mid X_0 = i)$$
$$= \sum_{n=0}^{\infty} P_{i,j}^{(n)} = 0.$$

That is,

 $Pr(DTMC \text{ ever exists state } j \mid X_0 = i) = 0.$ 

**Definition** (Communication Class). We define a communication class to the set of states that communicate with each other.

**Definition** (Irreducible, Reducible). We say that a discrete-time Markov chain is irreducible if it has only one communication class; and we say that it is reducible otherwise.

#### 1.3 Periodicity

**Definition** (Period). Let i be a state. We define the **period** of i, denoted by d(i), to be the number given by

$$d(i) := \gcd\{n \in \mathbb{Z}_+ : P_{i,i}^{(n)} > 0\}.$$

**Definition** (Aperiodic). We say that a state i is **aperiodic** if d(i) = 1. We say that a discrete-time Markov chain is **aperiodic** if d(i) = 1 for all state i.

**Proposition 1.3.1.** Let i and j be two states. If  $i \leftrightarrow j$ , then d(i) = d(j).

*Proof.* Since  $i \leftrightarrow j$ ,  $\exists n \in \mathbb{Z}_+$  such that  $P_{i,j}^{(n)} > 0$ ;  $\exists m \in \mathbb{Z}_+$  such that  $P_{j,i}^{(m)} > 0$ ; and  $\exists s \in \mathbb{Z}_+$  such that  $P_{j,j}^{(s)} > 0$ . Note that

$$P_{i,i}^{(n+m)} \ge P_{i,j}^{(n)} P_{j,i}^{(m)} > 0.$$

and

$$P_{i,i}^{(n+s+m)} \ge P_{i,j}^{(n)} P_{j,j}^{(s)} P_{j,i}^{(m)} > 0.$$

So  $d(i) \mid (n+m)$  and  $d(i) \mid (n+s+m)$ . So  $d(i) \mid ((n+s+m)-(n+m)) = s$ . Since  $\forall s \in \mathbb{Z}_+ : P_{j,j}^{(s)} > 0$ ,  $d(i) \mid s$ , we get  $d(i) \mid d(j)$ . Similarly, we have  $d(j) \mid d(i)$ . So d(i) = d(j).

#### 1.4 Transience and Recurrence

# Convergence of Random Variables

#### 2.1 Definitions

**Definition** (Convergence in Distribution). Let  $\{X_n\}_{n\in\mathbb{N}}$  be a sequence of random variables. Let  $F_n$  be the cumulative distribution function of  $X_n$ . Let X be a random variable. Let  $F_X$  be the cumulative distribution function of X. We say that the sequence  $\{X_n\}_{n\in\mathbb{N}}$  converges in distribution to X, denoted by  $X_n \stackrel{d}{\longrightarrow} X$ , if  $\forall x$  at which F is continuous,

$$\lim_{n \to \infty} F_n(x) = F_X(x).$$

In this case, we say  $F_X$  is the asymptotic distribution of  $\{X_n\}_{n\in\mathbb{N}}$ .

**Definition** (Convergence in Probability). Let  $\{X_n\}_{n\in\mathbb{N}}$  be a sequence of random variables. Let X be a random variable. We say that the sequence  $\{X_n\}_{n\in\mathbb{N}}$  converges in probability to X, denoted by  $X_n \stackrel{p}{\longrightarrow}$ , if

$$\forall \varepsilon > 0, \quad \lim_{n \to \infty} P(|X_n - X| \ge \varepsilon) = 0.$$

Or equivalently,

$$\forall \varepsilon > 0, \quad \lim_{n \to \infty} P(|X_n - X| < \varepsilon) = 1.$$

**Definition** (Almost Sure Convergence). Let  $\{X_n\}_{n\in\mathbb{N}}$  be a sequence of random variables. Let X be a random variable. We say that the sequence  $\{X_n\}_{n\in\mathbb{N}}$  converges almost surely to X if

$$P(\lim_{n\to\infty} X_n = X) = 1.$$

**Definition** (Sure Convergence). Let  $\Omega$  be a sample space of the underlying probability space. Let  $\{X_n\}_{n\in\mathbb{N}}$  be a sequence of random variables. Let X be a random variable. We say that the sequence  $\{X_n\}_{n\in\mathbb{N}}$  converges surely to X if

$$\forall \omega \in \Omega, \quad \lim_{n \to \infty} X_n(\omega) = X(\omega).$$

**Definition** (Convergence in Mean). Let  $r \geq 1$ . Let  $\{X_n\}_{n \in \mathbb{N}}$  be a sequence of random variables. Let X be a random variable. We say that the sequence  $\{X_n\}_{n \in \mathbb{N}}$  converges in the  $r^{th}$  mean to X, denoted by  $X_n \xrightarrow{L^r} X$ , if the  $r^{th}$  absolute moments  $\mathbb{E}[|X_n^r|]$  and  $\mathbb{E}[|X|^r]$  of  $X_n$  and X exists and

$$\lim_{n \to \infty} \mathbb{E}[|X_n - X|^r] = 0.$$

#### 2.2 Markov's Inequality

**Theorem 2** (Markov's Inequality). Let X be a random variable. Let k and c be arbitrary positive numbers. Then

$$P(|X| \ge c) \le \frac{\mathbb{E}[|X|^k]}{c^k}.$$

Corollary.

$$P(|X - \mathbb{E}[X]| > k\sqrt{\operatorname{var}[X]}) \le \frac{1}{k^2}.$$

#### 2.3 Properties

**Proposition 2.3.1.** Convergence in probability implies convergence in distribution.

Proposition 2.3.2. Almost sure convergence implies convergence in probability.

**Proposition 2.3.3.** Convergence in the  $r^{th}$  mean for  $r \geq 1$  implies convergence in probability.

**Proposition 2.3.4.** Let  $\{X_i\}_{i\in\mathbb{N}}$  be a sequence of random variables. Let c be a constant. Then  $\{X_i\}_{i\in\mathbb{N}}$  converges to c in distribution if and only if  $\{X_i\}_{i\in\mathbb{N}}$  converges to c in probability.

Sketch Proof.

$$P(|X_i - c| \ge \varepsilon) = P(X_i \ge c + \varepsilon) + P(X_i \le c - \varepsilon)$$

$$= 1 - P(X_i < c + \varepsilon) + F_i(c - \varepsilon)$$

$$\le 1 - P(X_i \le c + \varepsilon/2) + F_i(c - \varepsilon)$$

$$= 1 - F_i(c + \varepsilon/2) + F_i(c - \varepsilon)$$

$$\begin{split} &\lim_{i\to\infty}\left[1-F_i(c+\varepsilon/2)+F_i(c-\varepsilon)\right]\\ &=1-F(c+\varepsilon/2)+F(c-\varepsilon)\\ &=1-1+0\\ &=0. \end{split}$$

**Proposition 2.3.5** (Continuous Map). Let  $\{X_i\}_{i\in\mathbb{N}}$  be a sequence of random variables. Let g be a continuous function on the  $X_i$ 's. Then

- (1) if  $X_i \xrightarrow{d} X$ , we have  $g(X_i) \xrightarrow{d} g(X)$ .
- (2) if  $X_i \xrightarrow{p} c$ , we have  $g(X_i) \xrightarrow{p} g(c)$ .

**Proposition 2.3.6** (Slutsky's Theorem). Let  $\{X_i\}_{i\in\mathbb{N}}$  and  $\{Y_i\}_{i\in\mathbb{N}}$  be sequences of random variables. Suppose  $X_i \stackrel{d}{\longrightarrow} X$  for some random variable X and  $Y_i \stackrel{p}{\longrightarrow} c$  for some constant c. Then

- (1)  $X_i + Y_i \xrightarrow{d} X + c$ .
- (2)  $X_i Y_i \stackrel{d}{\longrightarrow} cX$ .
- (3)  $X_i/Y_i \stackrel{d}{\longrightarrow} X/c$ .

#### 2.4 Law of Large Numbers

**Theorem 3** (Strong Law of Large Nubmers). Let  $\{X_i\}_{i\in\mathbb{N}}$  be a sequence of independent and identically distributed random variables. Suppose that  $\mathbb{E}[X_i] = \mu$  for some  $\mu \in \mathbb{R}$  for all  $i \in \mathbb{N}$ . Then their cumulative average  $\bar{X}_n$  converges almost surely to  $\mu$ . That is,

$$\bar{X}_n := \frac{1}{n} \sum_{i=1}^n X_i \overset{almost surely}{\longrightarrow} \mu.$$

# Markov Decision Process

## Poisson Process

#### 4.1 Homogeneous Poisson Process

#### 4.1.1 Definitions

**Definition** (Homogeneous Poisson Process). We say a counting process is a homogeneous **Poisson counting process** with rate  $\lambda > 0$  if it has the following three properties:

- N(0) = 0;
- it has independent increments; and
- the number of events in any interval of length t is a Poisson random variable with parameter  $\lambda t$ .

**Definition** (Homogeneous Poisson Process). We say a point process is a homogeneous **Poisson point process** with rate  $\lambda > 0$  if the following two conditions hold:

• The probability  $\mathbb{P}\{N(a,b]=n\}$  of the number N(a,b] of points of the process in the interval (a,b] being equal to some counting number n is given by

$$\mathbb{P}\{N(a,b] = n\} = \frac{[\lambda(b-a)]^n}{n!}e^{-\lambda(b-a)}.$$

 $i.e.\ the\ number\ of\ arrivals\ in\ each\ finite\ interval\ has\ a\ Poisson\ distribution.$ 

• For any positive integer k and non-overlapping intervals  $(a_1, b_1], ..., (a_k, b_k],$ 

$$\mathbb{P}\left\{ \bigwedge_{i=1}^{k} N(a_i, b_i] = n_i \right\} = \prod_{i=1}^{k} \mathbb{P}\{N(a_i, b_i] = n_i\}.$$

i.e. the number of arrivals in disjoint intervals are independent random variables.