Functional Analysis

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Balanced Sets

1.1 Definitions

Definition (Balanced Sets). Let X be a vector space over field \mathbb{F} . Let S be a subset of X. We say that S is **balanced** if

$$\forall a \in \mathbb{F} : |a| \le 1, \quad aS \subseteq S.$$

Definition (Balanced Hull). Let X be a vector space over field \mathbb{F} . Let S be a subset of X. We define the **balanced hull** of S, denoted by $\operatorname{balhull}(S)$, to be the smallest balanced set containing S.

Definition (Balanced Core). Let X be a vector space over field \mathbb{F} . Let S be a subset of X. We define the **balanced core** of S, denoted by $\operatorname{balcore}(S)$, to be the largest balanced set contained in S.

1.2 Properties

Proposition 1.2.1. Let X be a vector space over field \mathbb{F} . Let B be a balanced subset of X. Then

$$\forall a,b \in \mathbb{F}: |a| \leq |b|, \quad aB \subseteq bB.$$

Proposition 1.2.2. Balanced sets are path connected.

Proposition 1.2.3 (Act on Other Properties). • The balanced hull of a compact set is compact.

- The balanced hull of a totally bounded set is totally bounded.
- The balanced hull of a bounded set is bounded.

Proposition 1.2.4 (Act on Other Properties). • The balanced core of a closed set is closed.

Proposition 1.2.5. Let X be a vector space over field \mathbb{F} . Let a be a scalar in field \mathbb{F} . Then

$$a \text{ balhull}(S) = \text{balhull}(aS).$$

1.3 Stability of Balance

Proposition 1.3.1 (Set Operations). • The union of balanced sets is also balanced.

• The intersection of balanced sets is also balanced.

Proposition 1.3.2 (Linear Mappings). • The scalar multiple of a balanced set is also balanced.

- The (Minkowski) sum of two balanced sets is also balanced.
- The image of a balanced set under a linear operator is also balanced.
- The inverse image of a balanced set under a linear operator is also balanced.

Proposition 1.3.3 (Topological Operations). The closure of a balanced set is also balanced.

Proposition 1.3.4. The convex hull of a balanced set is also balanced (and also convex).

1.4 Absorbing Sets

Definition (Absorbing Sets). Let \mathfrak{X} be a vector space over field \mathbb{F} . Let S be a subset of X. We say that S is **absorbing** if

$$\forall x \in \mathfrak{X}, \quad \exists r \in \mathbb{R} : r > 0, \quad \forall c \in \mathbb{F} : |c| \ge r, \quad x \in cS.$$

i.e.,

$$\bigcup_{n\in\mathbb{N}} nS = \mathfrak{X}.$$

Proposition 1.4.1. Every absorbing set contains the origin.

Normed Linear Spaces

2.1 Definitions

Definition (Seminorm). Let \mathfrak{X} be a vector space over field \mathbb{F} . We define a **seminorm** on \mathfrak{X} , denoted by ν , to be a map from \mathfrak{X} to \mathbb{R} that satisfies the following conditions.

- (1) $\forall x \in \mathfrak{X}, \quad \nu(x) \ge 0.$
- (2) $\forall \lambda \in \mathbb{F}, \forall x \in \mathfrak{X}, \quad \nu(\lambda x) = \lambda \nu(x).$
- (3) Triangle Inequality.

$$\forall x, y \in \mathfrak{X}, \quad \nu(x+y) \le \nu(x) + \nu(y).$$

The idea behind the seminorm is that we are trying to give our vector space a notion of "length" of vectors.

Definition (Norm). Let \mathfrak{X} be a vector space over field \mathbb{F} . We define a **norm** on \mathfrak{X} , denoted by ν , to be a seminorm on \mathfrak{X} that satisfies the additional condition:

$$\forall x \in \mathfrak{X}, \quad \mu(x) = 0 \iff x = 0.$$

2.2 Properties

Proposition 2.2.1. Let $(V, \|\cdot\|_V)$ be a normed vector space over field \mathbb{F} . Then $(V, \|\cdot\|)$ is complete if and only if $(\overline{B(0,1)}, \|\cdot\|_V)$ is complete.

Proof.

For one direction, assume that $(V, \|\cdot\|)$ is complete.

We are to prove that $(\overline{B(0,1)}, \|\cdot\|_V)$ is complete.

Since $(\overline{B(0,1)}, \|\cdot\|_V)$ is a closed subspace of $(V, \|\cdot\|)$ and $(V, \|\cdot\|)$ is complete, $(\overline{B(0,1)}, \|\cdot\|_V)$ is also complete.

For the reverse direction, assume that $(\overline{B(0,1)}, \|\cdot\|_V)$ is complete.

We are to prove that $(V, \|\cdot\|_V)$ is complete.

Let $\{x_i\}_{i\in\mathbb{N}}$ be an arbitrary Cauchy sequence in $(V, \|\cdot\|_V)$.

Since $\{x_i\}_{i\in\mathbb{N}}$ is Cauchy in $(V, \|\cdot\|_V)$, $\{x_i\}_{i\in\mathbb{N}}$ is bounded in $(V, \|\cdot\|_V)$.

Let λ be a positive upper bound for $\{\|x_i\|_V\}_{i\in\mathbb{N}}$.

Since $\{x_i\}_{i\in\mathbb{N}}$ is Cauchy in $(V, \|\cdot\|_V)$, $\{x_i/\lambda\}_{i\in\mathbb{N}}$ is Cauchy in $(B(0,1), \|\cdot\|_V)$.

Since $\{x_i/\lambda\}_{i\in\mathbb{N}}$ is Cauchy in $(\overline{B(0,1)},\|\cdot\|_V)$ and $(\overline{B(0,1)},\|\cdot\|_V)$ is complete, $\{x_i/\lambda\}_{i\in\mathbb{N}}$ converges in $(\overline{B(0,1)},\|\cdot\|_V)$.

Since $\{x_i/\lambda\}_{i\in\mathbb{N}}$ converges in $(B(0,1),\|\cdot\|_V), \{x_i\}_{i\in\mathbb{N}}$ converges in $(V,\|\cdot\|_V)$.

Since any Cauchy sequence in $(V, \|\cdot\|_V)$ converges in $(V, \|\cdot\|_V)$, $(V, \|\cdot\|_V)$ is complete.

Proposition 2.2.2. Proper subspaces of a normed linear space has empty interior.

Proof. Let \mathfrak{X} be a normed linear space. Let \mathcal{M} be a proper subspace of \mathfrak{X} . Assume for the sake of contradiction that \mathcal{M} has non-empty interior. Then $\exists x_0 \in \mathcal{M}$ and $\exists r > 0$ such that $\operatorname{ball}(x_0, r) \subseteq \mathcal{M}$ where $\operatorname{ball}(x_0, r)$ denotes the open ball centered at point x_0 with radius r. Let x be an arbitrary point in \mathfrak{X} . Define a point y(x) as $y(x) := x_0 + \frac{r}{2\|x\|} x$. Then $x = \frac{2\|x\|}{r}(y - x_0)$. It is easy to verify that $\|y - x_0\| = \frac{r}{2} < r$. So $y \in \operatorname{ball}(x_0, r)$. So $y \in \mathcal{M}$. Since $y, x_0 \in \mathcal{M}$ and \mathcal{M} is a subspace, we get $\frac{2\|x\|}{r}(y - x_0) \in \mathcal{M}$. That is, $x \in \mathcal{M}$. So $\forall x \in \mathfrak{X}, x \in \mathcal{M}$. So $\mathcal{M} = \mathfrak{X}$. This contradicts to the assumption that \mathcal{M} is a proper subspace of \mathfrak{X} . So \mathcal{M} has empty interior.

Proposition 2.2.3. Closed proper subspaces of a normed linear space are nowhere dense.

Proof. Let \mathfrak{X} be a normed linear space. Let \mathcal{M} be a closed proper subspace of \mathfrak{X} . Since \mathcal{M} is closed, $cl(\mathcal{M}) = \mathcal{M}$. So $cl(\mathcal{M}) = \mathcal{M}$ is a closed proper subspace of \mathfrak{X} . Since $cl(\mathcal{M})$ is a proper subspace of \mathfrak{X} , $int(cl(\mathcal{M})) = \emptyset$. So \mathcal{M} is nowhere dense.

Proposition 2.2.4. Finite dimensional subspace of a normed linear space is closed.

Proposition 2.2.5. Finite-dimensional normed linear spaces are complete.

2.3 Equivalence of Norms

Definition (Equivalence of Norms). Let \mathfrak{X} be a vector space over field \mathbb{F} . Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be two norms on V. We say that $\|\cdot\|_1$ and $\|\cdot\|_2$ are **equivalent** if

$$\exists c_1, c_2 > 0, \quad \forall v \in \mathfrak{X}, \quad c_1 \|v\|_1 \le \|v\|_2 \le c_2 \|v\|_2.$$

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Or equivalently,

$$c_1||v||_2 \le ||v||_1 \le c_2||v||_2.$$

Proposition 2.3.1. The equivalence of norms is an equivalence relation.

Theorem 1. Let V be a finite dimensional vector space over field $\mathbb{F} = \{\mathbb{R}, \mathbb{C}\}$. Then any two norms on V are equivalent.

Proof.

Let $\|\cdot\|_p$ be an arbitrary p-norm on V and $\|\cdot\|$ be an arbitrary norm on V. Let \mathcal{B} be the standard basis for V. Say $\mathcal{B} = \{e_1, e_2, \dots, e_n\}$.

Let v be an arbitrary vector in V.

$$||v|| = ||\sum_{i=1}^{n} v_i e_i||$$

$$\leq \sum_{i=1}^{n} |v_i| ||e_i||$$

$$\leq \left(\sum_{i=1}^{n} |v_i|^p\right)^{\frac{1}{p}} \left(\sum_{i=1}^{n} ||e_i||^{\frac{p}{p-1}}\right)^{1-\frac{1}{p}}$$

$$= \left(\sum_{i=1}^{n} ||e_i||^{\frac{p}{p-1}}\right)^{1-\frac{1}{p}} ||v||_p$$

$$:= c_1 ||v||_p.$$

Proposition 2.3.2. Let X be a vector space. Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be two norms on X. Then $\|\cdot\|_1$ and $\|\cdot\|_2$ are equivalent if and only if they generate the same metric topology.

Proof. Convergence to 0 is equivalent under either $\|\cdot\|_1$ or $\|\cdot\|_2$. i.e., equivalent norms give rise to the same set of sequences that are convergent. Convergence of sequences defines the topology.

Proposition 2.3.3. Let \mathfrak{X} be a vector space. Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be two norms on \mathfrak{X} . Let ι be the identity map from $(\mathfrak{X}, \|\cdot\|_1)$ to $(\mathfrak{X}, \|\cdot\|_2)$. Then if $\|\cdot\|_1$ and $\|\cdot\|_2$ are equivalent, ι is continuous, and in fact, a homeomorphism between $(\mathfrak{X}, \|\cdot\|_1)$ and $(\mathfrak{X}, \|\cdot\|_2)$.

2.4 Dual Norms

Definition (Dual Norm). Let $(V, \|\cdot\|)$ be an normed vector space. We define the **dual** norm of $\|\cdot\|$, denoted by $\|\cdot\|_{\circ}$, to be a function given by

$$||v||_{\circ} := \max_{||w||=1} v \cdot w = \max_{||w||\neq 0} \frac{|v \cdot w|}{||w||}.$$

Proposition 2.4.1. Dual norms of norms are indeed norms.

Proposition 2.4.2. Let $(V, \|\cdot\|)$ be a normed vector space. Let v, w be vectors in the space. Then

$$|v \cdot w| \le ||v|| \cdot ||w||_{\circ}.$$

2.5 p-norms

Definition (p-norm). Let V be a finite-dimensional normed vector space over field \mathcal{F} . Let $\mathcal{B} = \{b_1, ..., b_n\}$ be a basis for V where $n = \dim(V)$. Let v be a vector in a normed vector space. For $p \in [1, +\infty)$, we define the p-norm of v, denoted by $||v||_p$, to be the number given by

$$||v||_p = \left(\sum_{i=1}^n |(v_{\mathcal{B}})_i|^p\right)^{\frac{1}{p}}.$$

Definition (Infinity Norm - 1). Let $\mathfrak{X} = \mathbb{K}^n$ where \mathbb{K} is a field and $n \in \mathbb{N}$. We define the infinity norm on \mathfrak{X} , denoted by $\|\cdot\|_{\infty}$, to be a function given by

$$||v||_{\infty} := \max\{|v_i|\}_{i=1}^n.$$

Definition (Infinity Norm - 2). Let $\mathfrak{X} = \mathbb{K}^{\mathbb{N}}$. We define the **infinity norm** on \mathfrak{X} , denoted by $\|\cdot\|_{\infty}$, to be a function given by

$$||v||_{\infty} := \sup_{i \in \mathbb{N}} |v_i|.$$

Definition (Infinity Norm - 3). Let $\mathfrak{X} = \mathcal{C}([0,1],\mathbb{C})$. We define the **infinity norm** on \mathfrak{X} , denoted by $\|\cdot\|_{\infty}$, to be a function given by

$$\nu(f) := \sup_{x \in [0,1]} |f(x)|.$$

Proposition 2.5.1. Let $\mathfrak{X} := \mathcal{C}([0,1],\mathbb{C})$. Let x be an arbitrary number in [0,1]. Define a function ν_x on \mathfrak{X} by $\nu_x(f) := |f(x)|$. Define a function ν on \mathfrak{X} by $\nu(f) := \sup_{x \in [0,1]} |f(x)|$. Then ν_x is a seminorm on \mathfrak{X} for each x and ν is a norm on \mathfrak{X} and we have $\nu = \sup_{x \in [0,1]} \nu$.

Proposition 2.5.2. *p-norms are indeed norms.*

Proposition 2.5.3. For any vector v in \mathbb{R}^n , we have

$$\lim_{p \to \infty} ||v||_p = ||v||_{\infty}.$$

i.e.,

$$\lim_{p \to \infty} \left(\sum_{i=1}^{n} |v_i|^p \right)^{\frac{1}{p}} = \max\{|v_i|\}_{i=1}^n.$$

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Proof. Let p be an arbitrary number in $[1, +\infty)$. Let k be an arbitrary index in $\{1, ..., n\}$. Then

$$|v_k| \le (\sum_{k=1}^n |v_k|^p)^{1/p} = ||v||_p.$$

So

$$\max\{|v_k|\} = ||v||_{\infty} \le ||v||_p.$$

So

$$\lim_{p \to \infty} \|v\|_p \ge \|v\|_{\infty}. \tag{1}$$

On the other hand, note that

$$(\sum_{i=1}^{n} |v_i|^p) / \|v\|_{\infty}^p = \sum_{i=1}^{n} (\frac{|v_i|}{\|v\|_{\infty}})^p$$

decreases as p increases. So it is bounded above. Say

$$(\sum_{i=1}^{n} |v_i|^p) / \|v\|_{\infty}^p \le C$$

for some $C \in \mathbb{R}$. Then

$$\left(\sum_{i=1}^{n} |v_i|^p\right)^{1/p} = ||v||_p \le C^{1/p} ||v||_{\infty}.$$

So

$$\lim_{p \to \infty} \|v\|_p \le \lim_{p \to \infty} C^{1/p} \|v\|_{\infty} = \|v\|_{\infty}.$$
 (2)

From (1) and (2) we get

$$\lim_{p \to \infty} \|v\|_p = \|v\|_{\infty}.$$

Proposition 2.5.4. Let p be an arbitrary number in $[1, +\infty)$. Then the dual norm of the p-norm $\|\cdot\|_p$ is the q-norm $\|\cdot\|_q$ where q is such that satisfies

$$\frac{1}{p} + \frac{1}{q} = 1.$$

Proposition 2.5.5. Let p and q be numbers in $[1, +\infty]$. Let v be a vector in \mathbb{R}^n . Then if $p \leq q$,

$$||x||_q \le ||x||_p \le n^{\frac{1}{p} - \frac{1}{q}} \cdot ||x||_q.$$

Proposition 2.5.6. Let w and z be vectors in \mathbb{E}^d . Then

$$||w + z||_2^2 + ||w - z||_2^2 = 2(||w||_2^2 + ||z||_2^2).$$

Inner Product Spaces

3.1 Inner Products

3.1.1 Definitions

Definition (Inner Product). Let V be a vector space over field \mathbb{F} . We define an inner **product** on V, denoted by $\langle \cdot, \cdot \rangle$, to be a scalar-valued function defined on $V \times V$ such that

(1) Positive Definiteness:

$$\forall x \in V, \langle x, x \rangle > 0 \text{ and } \langle x, x \rangle = 0 \iff x = 0.$$

(2) Sesqui-Linearity:

$$\forall x, y, z, w \in V, \quad \langle x + y, z + w \rangle = \langle x, z \rangle + \langle y, z \rangle + \langle x, w \rangle + \langle y, w \rangle, \text{ and}$$
$$\forall a, b \in \mathbb{F}, \forall x, y \in V, \quad \langle ax, by \rangle = a\overline{b}\langle x, y \rangle.$$

(3) Conjugate Symmetry:

$$\forall x, y \in V, \quad \langle x, y \rangle = \overline{\langle y, x \rangle}.$$

Definition (Induced Norm). Let \mathfrak{X} be an inner product space over field \mathbb{K} . We define the **norm induced by** $\langle \cdot, \cdot \rangle$, denoted by $\| \cdot \|$, to be a function from \mathfrak{X} to \mathbb{R}_+ given by

$$||x|| := \sqrt{\langle x, x \rangle}$$

3.1.2 Examples of Inner Products

Definition (Standard Inner Product). For $V = \mathbb{F}^n$, we define the **standard inner product** by

$$\langle x, y \rangle := \sum_{i=1}^{n} x_i \overline{y_i}.$$

Definition (Frobenius Inner Product). For $V = \mathbb{F}^{n \times n}$, we define the **Frobenius inner** product by

$$\langle M_1, M_2 \rangle := \operatorname{tr}(M_2^* M_1).$$

Definition. Let V be the space of continuous scalar-valued functions on $[0, 2\pi]$. We define the inner product on V by

$$\langle f, g \rangle := \frac{1}{2\pi} \int_0^{2\pi} f(x) \overline{g(x)} dx.$$

3.1.3 Properties

Proposition 3.1.1. Let V be a finite dimensional inner product space. Let \mathcal{B} be a basis for V. Let x and y be vectors in V. Then

$$x = y \iff \forall b \in \mathcal{B}, \quad \langle x, b \rangle = \langle y, b \rangle.$$

3.2 Inner Product Space

Definition (Inner Product Space). Let \mathfrak{X} be a vector space over field \mathbb{F} . Let $\langle \cdot, \cdot \rangle$ be an inner product on \mathfrak{X} . We define an **inner product space** to be the pair $(\mathfrak{X}, \langle \cdot, \cdot \rangle)$.

3.3 Inequalities

Theorem 2 (Minkowski).

$$\left(\sum_{i=1}^{n} |x_i + y_i|^p\right)^{\frac{1}{p}} \le \left(\sum_{i=1}^{n} |x_i|^p\right)^{\frac{1}{p}} + \left(\sum_{i=1}^{n} |y_i|^p\right)^{\frac{1}{p}}$$

Proposition 3.3.1 (Cauchy-Schwarz Inequality). Let V be an inner product space. Then

$$\forall x, y \in V, \quad |\langle x, y \rangle| < ||x|| \cdot ||y||$$

Proposition 3.3.2 (Triangle Inequality). Let V be an inner product space. Then

$$\forall x, y \in V, \quad ||x + y|| < ||x|| + ||y||$$

Proposition 3.3.3 (Parallelogram Law). Let \mathfrak{X} be an inner product space. Then

$$\forall x, y \in \mathfrak{X}, \quad \|x+y\|^2 + \|x-y\|^2 = 2\|x\|^2 + 2\|y\|^2.$$

Proof.

$$||x + y||^2 + ||x - y||^2 = \langle x + y, x + y \rangle + \langle x - y, x - y \rangle$$

$$= \langle x, x \rangle + \langle x, y \rangle + \langle y, x \rangle + \langle y, y \rangle$$
$$+ \langle x, x \rangle - \langle x, y \rangle - \langle y, x \rangle + \langle y, y \rangle$$
$$= 2\langle x, x \rangle + 2\langle y, y \rangle$$
$$= 2\|x\|^2 + 2\|y\|^2.$$

That is,

$$||x + y||^2 + ||x - y||^2 = 2||x||^2 + 2||y||^2.$$

Orthogonality

4.1 Orthogonal Sets

Definition (Orthogonality). Let V be an inner product space. We say that points x and y in V are **orthogonal** if $\langle x, y \rangle = 0$.

Definition (Orthogonal Set). Let \mathfrak{X} be an inner product space. Let S be a subset of \mathfrak{X} . We say that S is **orthogonal** if

$$\forall x, y \in S : x \neq y, \quad \langle x, y \rangle = 0.$$

i.e., if any two distinct vectors are orthogonal.

Definition (Orthonormal Set). Let \mathfrak{X} be an inner product space. Let S be a set in the space. We say that S is **orthonormal** if S is orthogonal and $\forall x \in S$, ||x|| = 1 where $||\cdot||$ is the norm induced by the inner product.

Proposition 4.1.1. Orthogonal sets are linearly independent.

4.2 Orthogonal Bases

Definition (Orthogonal Basis). Let V be an inner product space. Let S be a set in the space. We say that S is an **orthogonal basis** for V if it is an ordered basis for V and orthogonal.

Definition (Orthonormal Basis). Let \mathfrak{X} be an inner product space. Let S be a set in the space. We say that S is an **orthonormal basis** for \mathfrak{X} if it is the maximal, with respect to inclusion, in the collection of all orthonormal sets in the space.

Proposition 4.2.1. Let V be an inner product space. Let $S = \{v_1, ..., v_n\}$ be an orthogonal subset of V where each v_i is non-zero. Then

$$\forall y \in \text{span}(S), \quad y = \sum_{i=1}^{n} \frac{\langle y, v_i \rangle}{\|v_i\|^2} v_i.$$

Theorem 3 (Gram-Schmidt Process). Let V be an inner product space. Let $S = \{x_0, ..., x_n\}$ be a linearly independent subset of V. Then the set $T = \{y_0, ..., y_n\}$ given by $y_0 := x_0$ and

$$\forall i \in \{1, ..., n\}, \quad y_i := x_i - \sum_{j=1}^{i-1} \frac{\langle x_i, y_j \rangle}{\|y_j\|} y_j$$

is an orthogonal subset of V consisting of non-zero vectors such that $\operatorname{span}(S) = \operatorname{span}(S')$.

Proposition 4.2.2. Let V be an inner product space and $S = \{v_0, v_1, \ldots, v_n\}$ be an orthogonal subset of V. Then the set S' derived from the Gram-Schmidt process is exactly S.

Theorem 4 (Parseval's Identity). Let V be a finite-dimensional inner product space. Let $\mathcal{B} = \{v_1, ..., v_n\}$ be an orthogonal basis for V. Then

$$\forall x, y \in V, \quad \langle x, y \rangle = \sum_{i=1}^{n} \langle x, v_i \rangle \overline{\langle y, v_i \rangle}.$$

Proposition 4.2.3. Let \mathcal{H} be a Hilbert space. Let \mathcal{E} be an orthonormal set in \mathcal{H} . Then \mathcal{E} is an orthonormal basis for \mathcal{H} if and only if

$$\forall x \in \mathcal{H}, \quad x = \sum_{e \in \mathcal{E}} \langle x, e \rangle e.$$

4.3 Orthogonal Complements

Definition (Orthogonal Complement). Let \mathfrak{X} be an inner product space. Let S be a non-empty subset of V. We define the **orthogonal complement** of S, denoted by S^{\perp} , to be a set given by

$$S^{\perp} := \{ x \in \mathfrak{X} : \forall s \in S, \langle x, s \rangle = 0 \}.$$

i.e., the set of all points in $\mathfrak X$ that are orthogonal to all vectors in S.

Proposition 4.3.1. Let V be a finite-dimensional inner product space. Then

(1)
$$V^{\perp} = \{O_V\}$$

(2)
$$\{O_V\}^{\perp} = V$$

Proposition 4.3.2. Orthogonal complements are always linear subspaces.

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Proposition 4.3.3. Let V be an inner product space and W be a subspace of V with basis β . Then a vector in V is also in W^{\perp} if and only if it is orthogonal to all vectors in β .

Proposition 4.3.4 (Extension). Let V be an n-dimensional inner product space and $S = \{v_1, v_2, \ldots, v_k\}$ be an orthogonal subset of V. Then S can be extended to an orthogonal basis $B = \{v_1, v_2, \ldots, v_k, v_{k+1}, \ldots, v_n\}$ for V.

Proposition 4.3.5. Let V be an inner product space. Then

- (1) $S \subseteq T$ implies $T^{\perp} \subseteq S^{\perp}$ for any subsets S and T of V.
- (2) $S \subseteq (S^{\perp})^{\perp}$ for any subset S of V.

Proposition 4.3.6. Let V be a finite-dimensional inner product space and W be a subspace of V. Then

- (1) $W = (W^{\perp})^{\perp}$
- (2) $V = W \oplus W^{\perp}$

Proposition 4.3.7. Let V be a finite-dimensional inner product space and W_1 and W_2 be subspaces of V. Then

- (1) $(W_1 + W_2)^{\perp} = W_1^{\perp} \cap W_2^{\perp}$
- (2) $(W_1 \cap W_2)^{\perp} = W_1^{\perp} + W_2^{\perp}$

4.4 Orthogonal Projection

Definition (Orthogonal Projection). Let V be a vector space. Let W be a finite-dimensional subspace of V. Let x be a vector in V. We define the **orthogonal projection** of x on W, denoted by (x), to be the vector u in W such that x = u + v where v is another vector in W^{\perp} .

4.5 Inequalities in Hilbert Spaces

Theorem 5 (Bessel's Inequality). Let \mathcal{H} be a Hilbert space. Let \mathcal{E} be an orthonormal set in the space. Then

$$\forall x \in \mathcal{H}, \quad \sum_{e \in \mathcal{E}} |\langle x, e_i \rangle|^2 \le ||x||^2.$$

Proposition 4.5.1. Let \mathcal{H} be a Hilbert space. Let \mathcal{E} be an orthonormal set in \mathcal{H} . Let x be a point in the space. Then the net $\sum_{e \in \mathcal{E}} \langle x, e \rangle e$ converges in \mathcal{H} .

Proof. Let \mathcal{F} be the collection of all finite subsets of \mathcal{E} , partially ordered by inclusion. Define for each $F \in \mathcal{F}$ a vector y_F as $y_F := \sum_{e \in F} \langle x, e \rangle e$. Let ε be an arbitrary positive number. Since \mathcal{E} is an orthonormal set, the set $\{e \in \mathcal{E} : \langle x, e \rangle \neq 0\}$ is countable. Let $\{e_i\}_{i \in \mathbb{N}}$ denote the set. By the Bessel's inequality, $\exists N \in \mathbb{N}$ such that $\sum_{i=N+1}^{\infty} |\langle x, e_i \rangle|^2 < \varepsilon^2$. Define a set F_0 as $F_0 := \{e_1, ..., e_N\}$. Let F and G be arbitrary elements in \mathcal{F} such that $F_0 \leq F$ and $F_0 \leq G$. Then

$$||y_F - y_G||^2 = \left\| \sum_{e \in F \setminus G} \langle x, e \rangle e - \sum_{e \in G \setminus F} \langle x, e \rangle e \right\|^2$$

$$= \sum_{e \in F \cup G \setminus F \cap G} |\langle x, e \rangle|^2$$

$$= \sum_{e \in F \cup G} |\langle x, e \rangle|^2 - \sum_{e \in F \cap G} |\langle x, e \rangle|^2$$

$$\leq \sum_{i=N+1}^{\infty} |\langle x, e_i \rangle|^2$$

$$< \varepsilon^2.$$

So $\{y_F\}_{F\in\mathcal{F}}$ is Cauchy. Since \mathcal{H} is complete and $\{y_F\}_{F\in\mathcal{F}}$ is Cauchy, $\{y_F\}_{F\in\mathcal{F}}$ converges.

Sequence Spaces

5.1 ℓ^p Space

Definition (ℓ^p Space). We define the ℓ^p space to be the set of all sequences x such that $||x||_p$ is finite, equipped with the p-norm $||\cdot||_p$.

Definition (Weighted ℓ^p Space). Let $(r_i)_{i\in\mathbb{N}}$ be a sequence of positive integers. We define the weighted ℓ^p space to be the set given by

$$\ell^p := \{(x_i)_{i \in \mathbb{N}} \in \mathbb{K}^{\mathbb{N}} : \sum_{i \in \mathbb{N}} r_i |x_i|^p < +\infty.$$

Proposition 5.1.1. For $p \in [1, +\infty)$, $(\ell^p, ||\cdot||_p)$ is complete.

Proof.

Let $\{x_n\}_{n\in\mathbb{N}}$ be an arbitrary Cauchy sequence in ℓ^p .

Since $\{x_n\}_{n\in\mathbb{N}}$ is Cauchy in ℓ^p , $\forall \varepsilon > 0$, $\exists N(\varepsilon) \in \mathbb{N}$ such that $\forall m, n > N$, we have $\|x_m - x_n\|_p < \varepsilon$.

Since $||x_m - x_n||_p < \varepsilon$ and $|x_m^{(i)} - x_n^{(i)}| \le ||x_m - x_n||_p$ for any $i \in \mathbb{N}$, $|x_m^{(i)} - x_n^{(i)}| < \varepsilon$ for any $i \in \mathbb{N}$.

Since for any $i \in \mathbb{N}$ and any positive number ε , there exists an integer $N(\varepsilon)$ such that for any indices m, n > N, we have $|x_m^{(i)} - x_n^{(i)}| < \varepsilon$, by definition, $\{x_n^{(i)}\}_{n \in \mathbb{N}}$ is Cauchy in \mathbb{F} .

Since $\{x_n^{(i)}\}_{n\in\mathbb{N}}$ is Cauchy in \mathbb{F} and \mathbb{F} is complete, $\{x_n^{(i)}\}_{n\in\mathbb{N}}$ converges.

Let $x_0^{(i)} = x_n^{(i)}$. Let $x_0 = \{x_0^{(i)}\}_{i \in \mathbb{N}}$.

$$||x_0||_p = (\sum_{i=1}^{\infty} |x_0^{(i)}|^p)^{\frac{1}{p}}$$

5.2 c_0 Space and c_{00} Space

Definition (c_0 Space). We define c_0 to be

$$c_0 := \big\{ \{x_n\}_{n \in \mathbb{N}} \in \mathbb{R}^{\mathbb{N}} : \lim_{n \to \infty} x_n = 0 \big\}.$$

Definition (c_{00} Space). We define c_{00} to be

$$c_{00} := \{(x_n)_{n \in \mathbb{N}} \in \mathbb{R}^{\mathbb{N}} : \exists N \in \mathbb{N}, \forall n > N, x_n = 0\}.$$

i.e., the set of all eventually zero sequences of real numbers. i.e., the set of all sequences with finite support.

Proposition 5.2.1. The c_{00} is not complete in $(\ell_1, \|\cdot\|_1)$.

Proof. Define a sequence of vectors $(\mathfrak{x}_i)_{i\in\mathbb{N}}$ by $\mathfrak{x}_i^j:=\frac{1}{j^2}$ for $j\in\{1..i\}$ and $\mathfrak{x}_i^j:=0$ for j>i. Then $(\mathfrak{x}_i)_{i\in\mathbb{N}}$ converges to something that is not in c_{00} .

Proposition 5.2.2. The closure of c_{00} in the space $(\mathbb{R}^{\omega}, d_1)$ is ℓ_1 .

Proof. For one direction, we are to prove that $\operatorname{cl}(c_{00}) \subseteq \ell_1$. Let x be an arbitrary element in $\operatorname{cl}(c_{00})$. Since $x \in \operatorname{cl}(c_{00})$, there exists another element $y \in c_{00}$ such that $d_1(x,y) < 1$. Let $N \in \mathbb{N}$ be such that $\forall n > N, y_n = 0$. Then

$$\begin{aligned} d_1(x,y) &< 1 \\ \iff & \sum_{n \in \mathbb{N}} |x_n - y_n| < 1 \\ \iff & \sum_{n=1}^N |x_n - y_n| + \sum_{n > N} |x_n - y_n| < 1 \\ \iff & \sum_{n=1}^N |x_n - y_n| + \sum_{n > N} |x_n| < 1 \\ \iff & \sum_{n=1}^N ||x_n| - |y_n|| + \sum_{n > N} |x_n| < 1 \\ \iff & \sum_{n=1}^N \left(|x_n| - |y_n| \right) + \sum_{n > N} |x_n| < 1 \\ \iff & \sum_{n=1}^N |x_n| - \sum_{n=1}^N |y_n| + \sum_{n > N} |x_n| < 1 \\ \iff & \sum_{n \in \mathbb{N}} |x_n| - \sum_{n=1}^N |y_n| < 1 \\ \iff & \sum_{n \in \mathbb{N}} |x_n| < 1 + \sum_{n=1}^N |y_n|. \end{aligned}$$

Since $\sum_{n\in\mathbb{N}} |x_n|$ is bounded, $x\in\ell_1$.

For the reverse direction, we are to prove that $\ell_1 \subseteq \operatorname{cl}(c_{00})$. Let x be an arbitrary element in ℓ_1 . For $i \in \mathbb{N}$, define $x^i = \{x^i_j\}_{j \in \mathbb{N}}$ as $x^i_j = x_j$ for $j \leq i$ and $x^i_j = 0$ for j > i. Then $\forall i \in \mathbb{N}, x^i \in c_{00}$. Then

$$\lim_{i \in \mathbb{N}} d_1(x^i, x)$$

$$= \lim_{i \in \mathbb{N}} \sum_{j \in \mathbb{N}} |x_j^i - x_j|$$

$$= \lim_{i \in \mathbb{N}} \sum_{j > i} |x_j^i - x_j|$$

$$= \lim_{i \in \mathbb{N}} \sum_{j > i} |x_j|$$

$$= 0$$

That is, $\lim_{i\in\mathbb{N}} d_1(x^i, x) = 0$. So $\lim_{i\in\mathbb{N}} x^i = x$. So $x \in cl(c_{00})$.

Proposition 5.2.3. The closure of c_{00} in the space $(\mathbb{R}^{\omega}, d_{\infty})$ is c_0 .

Proof. For one direction, we are to prove that $\operatorname{cl}(c_{00}) \subseteq c_0$. Let x be an arbitrary element in $\operatorname{cl}(c_{00})$. Let ε be an arbitrary positive real number. Since $x \in \operatorname{cl}(c_{00})$, there exists another element y in c_{00} such that $d_{\infty}(x,y) < \varepsilon$. That is, $\forall j \in \mathbb{N}, |x_j - y_j| < \varepsilon$. Since $y \in c_{00}$, $\exists N \in \mathbb{N}$ such that $\forall j > N, y_j = 0$. So $\forall j > N, |x_j| < \varepsilon$. That is,

$$\forall \varepsilon > 0, \quad \exists N \in \mathbb{N}, \quad \forall j > N, \quad |x_j| < \varepsilon.$$

By definition of convergence of limits, $\lim_{j\in\mathbb{N}} x_j = 0$. So $x \in c_0$.

For the reverse direction, we are to prove that $c_0 \subseteq \operatorname{cl}(c_{00})$. Let x be an arbitrary element in c_0 . For $i \in \mathbb{N}$, define x^i as $x^i_j = x_j$ for $j \leq i$ and $x^i_j = 0$ for j > i. Then $\forall i \in \mathbb{N}$, $x^i \in c_{00}$. Let ε be an arbitrary positive real number. Since $x \in c_0$,

$$\exists N \in \mathbb{N}, \quad \forall j > N, \quad |x_j| < \varepsilon/2.$$

Let i > N. Then

$$d_{\infty}(x^{i}, x)$$

$$= \sup_{j \in \mathbb{N}} |x_{j}^{i} - x_{j}|$$

$$= \sup_{j > i} |x_{j}^{i} - x_{j}|$$

$$= \sup_{j > i} |x_{j}|$$

$$\leq \varepsilon/2 < \varepsilon.$$

That is,

$$\forall \varepsilon > 0, \quad \exists N \in \mathbb{N}, \quad \forall i > N, \quad d_{\infty}(x^{i}, x) < \varepsilon.$$

By definition of convergence of sequences, $\lim_{i \in \mathbb{N}} x^i = x$. So $x \in cl(c_{00})$.

Proposition 5.2.4. Let $A := \{ \{x_n\}_{n \in \mathbb{N}} \in c_{00} : \sum_{n \in \mathbb{N}} x_n = 0 \}$. Then A is a subset of ℓ^1 and is closed in (ℓ^1, d_1) . i.e. cl(A) = A in (ℓ^1, d_1) .

Proof. Let $x = \{x^i\}_{i \in \mathbb{N}}$ be a sequence in ℓ^1 , where each $x^i = \{x^i_j\}_{j \in \mathbb{N}}$ is an element in A, that converges in (ℓ^1, d_1) . Say $\lim_{i \to \infty} x^i = x^{\infty}$.

First I claim that $x^{\infty} \in c_{00}$.

Now I claim that $\sum_{j\in\mathbb{N}} x_j^{\infty} = 0$. i.e. $x^{\infty} \in A$. Since $x^{\infty} \in c_{00}$,

$$\exists N \in \mathbb{N}, \quad \forall j > N, \quad x_i^{\infty} = 0.$$

Define $y_i := \sum_{j=1}^N x_j^i$. Define $y_\infty := \sum_{j=1}^N x_j^\infty$. It is easy to see that $\lim_{i \in \mathbb{N}} y_i = y_\infty$. Assume for the sake of contradiction that $y_\infty \neq 0$. i.e. $\{y_i\}_{i \in \mathbb{N}}$ does not converge to 0. Then

$$\exists \varepsilon_0 > 0, \quad \forall M \in \mathbb{N}, \quad \exists i_0 > M, \quad |y_{i_0} - 0| = |y_{i_0}| \ge \varepsilon_0.$$
 (1)

Since $\lim_{i\to\infty} x^i = x^\infty$,

$$\exists M_0 \in \mathbb{N}, \quad \forall i > M_0, \quad d_1(x^i, x^\infty) < \varepsilon_0.$$
 (2)

Consider statement (1) for a particular M, M_0 , we have

$$\exists i_0 > M_0, \quad |y_{i_0}| \ge \varepsilon_0. \tag{3}$$

That is,

$$\left|\sum_{j=1}^{N} x_j^{i_0}\right| \ge \varepsilon_0. \tag{3'}$$

Consider statement (2) for a particular i, i_0 , we have

$$d_1(x^{i_0}, x^{\infty}) < \varepsilon_0. \tag{4}$$

From statement (4) we can derive:

$$d_1(x^{i_0}, x^{\infty}) < \varepsilon_0$$

$$\iff \sum_{j \in \mathbb{N}} |x_j^{i_0} - x_j^{\infty}| < \varepsilon_0$$

$$\iff \sum_{j=1}^N |x_j^{i_0} - x_j^{\infty}| + \sum_{j>N} |x_j^{i_0} - x_j^{\infty}| < \varepsilon_0$$

5.3. HÖLDER'S INEQUALITY

$$\implies \sum_{j>N} |x_j^{i_0} - x_j^{\infty}| < \varepsilon_0$$

$$\iff \sum_{j>N} |x_j^{i_0} - 0| < \varepsilon_0$$

$$\iff \sum_{j>N} |x_j^{i_0}| < \varepsilon_0$$

$$\implies |\sum_{j>N} x_j^{i_0}| < \varepsilon_0$$

$$\implies |\sum_{j>N} x_j^{i_0}| < \varepsilon_0$$

$$\iff |\sum_{j\in\mathbb{N}} x_j^{i_0} - \sum_{j=1}^N x_j^{i_0}| < \varepsilon_0$$

$$\iff |0 - \sum_{j=1}^N x_j^{i_0}| < \varepsilon_0$$

$$\iff |\sum_{j=1}^N x_j^{i_0}| < \varepsilon_0$$

$$\iff |\sum_{j=1}^N x_j^{i_0}| < \varepsilon_0$$

This contradicts to statement (3'). So the original assumption that $y_{\infty} \neq 0$ is false. i.e. $y_{\infty} = 0$. It follows that $\sum_{j \in \mathbb{N}} x_j^{\infty} = 0$. This completes the proof.

5.3 Hölder's Inequality

Theorem 6 (Hölder's Inequality). Let $\mathfrak{X} = \mathbb{R}^n$ for some $n \in \mathbb{N}$. Let $x = (x_i)_{i=1}^n$ and $y = (y_i)_{i=1}^n$ be vectors in \mathfrak{X} . Then $\forall p, q \in (1, +\infty) : 1/p + 1/q = 1$, $||xy||_1 \le ||x||_p ||y||_q$. i.e.,

$$\sum_{i=1}^{n} |x_i y_i| \le \left(\sum_{i=1}^{n} |x_i|^p\right)^{1/p} \left(\sum_{i=1}^{n} |y_i|^q\right)^{1/q}.$$

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Function Spaces

6.1 The \mathcal{L}^p Norm

$$||f||_p = \left(\int_a^b |f(x)|^p dx\right)^{\frac{1}{p}}.$$



Banach Space

7.1 Definition

Definition (Banach Space). Let $(\mathfrak{X}, \|\cdot\|)$ be a normed linear space. Let d be the metric induced by $\|\cdot\|$. We say that \mathfrak{X} is a **Banach space** if (\mathfrak{X}, d) is a complete metric space. i.e., we define a Banach space to be a complete normed linear space.

7.2 Properties

Proposition 7.2.1. Let $(\mathfrak{X}, \|\cdot\|)$ be a normed vector space over field \mathbb{F} . Then $(\mathfrak{X}, \|\cdot\|)$ is a Banach space if and only if every absolutely summable series in X is summable.

Proposition 7.2.2. Any Banach space with a Schauder basis has to be separable.

7.3 Examples of Banach Space

Example 7.3.1. $(\mathcal{C}([0,1],\mathbb{F}),\|\cdot\|_{\infty})$ is a Banach space.

Example 7.3.2 (Disc Algebra). Define $\mathbb{D}:=\{z\in\mathbb{C}:|z|<1\}$. Define $\mathcal{A}(\mathbb{D}):=\{f\in\mathcal{C}(\overline{\mathbb{D}}):f|_{\mathbb{D}}\text{ is holomorphic }\}$. Define $\|\cdot\|_{\infty}$ by $\|f\|_{\infty}:=\sup_{z\in\overline{\mathbb{D}}}|f(z)|$. Then $(\mathcal{A}(\mathbb{D}),\|\cdot\|_{\infty})$ is a Banach space.

Example 7.3.3. Let (X, Ω, μ) be a measure space. Let p be a number in $[1, +\infty)$. Define

$$\mathcal{L}^p(X,\mu) := \operatorname{span}\{f: X \to [0,+\infty] \mid f \text{ is measurable and } \int_X |f|^p < +\infty\}.$$

Define an equivalence relation on $\mathcal{L}^p(X,\mu)$ by $f \equiv g$ if and only if

$$\mu(\{x \in X : f(x) \neq g(x)\}) = 0.$$

Define a space $L^p(X,\mu) := \mathcal{L}^p(X,\mu)/\equiv$. Then $L^p(X,\mu)$ is a Banach space when equipped with the norm

$$||[f]||_p := \left(\int_X |f|^p\right)^{1/p}.$$

Example 7.3.4. Let $\mathcal{P}_{\mathbb{C}}[0,1]$ denote the set of all polynomials with complex coefficients. For each $p \in [1,+\infty)$, define a norm

$$||f||_p := \left(\int_0^1 |f|^p\right)^{1/p}.$$

For $p = +\infty$, define a norm

$$||f||_{\infty} := \sup_{x \in [0,1]} |f(z)|.$$

7.4 Construction of Banach Spaces

Definition. Let $(\mathfrak{X}, \|\cdot\|_{\mathfrak{X}})$ and $(\mathfrak{Y}, \|\cdot\|_{\mathfrak{Y}})$ be two Banach spaces over field \mathbb{K} . Let $p \in [1, +\infty)$. We define

$$\mathfrak{X} \oplus_p \mathfrak{Y} := \{(x,y) : x \in \mathfrak{X}, y \in \mathfrak{Y}\}$$

and

$$\|(x,y)\|_p := (\|x\|_{\mathfrak{X}}^p + \|y\|_{\mathfrak{Y}}^p)^{1/p}.$$

For $p = +\infty$, we define

$$\mathfrak{X} \oplus_{\infty} \mathfrak{Y} := \{(x,y) : x \in \mathfrak{X}, y \in \mathfrak{Y}\}$$

and

$$||(x,y)||_{\infty} := \max(||x||_{\mathfrak{X}}, ||y||_{\mathfrak{Y}}).$$

- Note that the norms behave similarly to what the p norm would do.
- We can similarly define the direct sum of finitely many Banach spaces.

Proposition 7.4.1. $\|\cdot,\cdot\|_p$ is a norm on $\mathfrak{X} \oplus_p \mathfrak{Y}$.

Proposition 7.4.2. $\mathfrak{X} \oplus_p \mathfrak{Y}$ is complete with respect to $\|\cdot, \cdot\|_p$.

Hilbert Space

8.1 Definition

Definition (Hilbert Space). We define a **Hilbert space**, denoted by \mathcal{H} , to be a complete inner product space.

8.2 Examples of Hilbert Space

Example 8.2.1. Let (X, μ) be a measure space. Then $L^2(X, \mu)$ is a Hilbert space with inner product given by

$$\langle f, g \rangle := \int_X f(x) \overline{g(x)} d\mu(x).$$

Example 8.2.2. $\ell^2(\mathbb{K}) = \{(x_i)_{i \in \mathbb{N}} \in \mathbb{K}^{\infty} : \sum_{i \in \mathbb{N}} |x_i|^2 < +\infty \}$ is a Hilbert space with inner product given by

$$\langle (x_i)i \in \mathbb{N}, (y_i)_{i \in \mathbb{N}} \rangle := \sum_{i \in \mathbb{N}} x_n \overline{y_n}.$$

8.3 Properties of Hilbert Space

Proposition 8.3.1. Let \mathcal{H} be a Hilbert space. Let S be a non-empty set in the space. Then $S^{\perp\perp} = \text{clspan}(S)$.

Proof. For one direction, we are to prove that $\operatorname{clspan}(S) \subseteq S^{\perp \perp}$.

For the reverse direction, we are to prove that $S^{\perp\perp}\subseteq \operatorname{clspan}(S)$. Assume for the sake of contradiction that $\exists x\in S^{\perp\perp}$ with $x\neq 0$ such that $x\notin \operatorname{clspan}(S)$. Say $x=m_1+m_2$ for some $m_1\in\operatorname{clspan}(S)$ and some $m_2\in\operatorname{clspan}(S)^{\perp}$. Note that $\operatorname{clspan}(S)^{\perp}=S^{\perp}$. So $m_2\in S^{\perp}$. Since $x\in S^{\perp\perp}$ and $m_2\in S^{\perp}$, we should have $\langle x,m_2\rangle=0$. However,

$$\langle x, m_2 \rangle = \langle m_1 + m_2, m_2 \rangle$$

$$= \langle m_1, m_2 \rangle + \langle m_2, m_2 \rangle$$
$$= 0 + \langle m_2, m_2 \rangle$$
$$> 0, \text{ since } m_2 \neq 0.$$

This leads to a contradiction. So $S^{\perp\perp} \subseteq \text{clspan}(S)$.

Theorem 7 (The Riesz Representation Theorem). Let \mathcal{H} be a Hilbert space over field $\mathbb{K} \in \{\mathbb{R}, \mathbb{C}\}$. Suppose that $\mathcal{H} \neq \{0\}$. Then for any $\varphi \in \mathcal{H}^*$, $\exists y \in \mathcal{H}$ such that

$$\forall x \in \mathcal{H}, \quad \varphi(x) = \langle x, y \rangle.$$

Proof. Define for each $y \in \mathcal{H}$ a function $\beta_y \in \mathcal{H}^*$ by $\beta_y(x) := \langle x, y \rangle$. We are to prove that $\mathcal{H}^* = \{\beta_y : y \in \mathcal{H}\}$. It is easy to verify that each β_y is linear and bounded. So $\forall y \in \mathcal{H}$, $\beta_y \in \mathcal{H}^*$. i.e., $\{\beta_y : y \in \mathcal{H}\} \subseteq \mathcal{H}^*$. Define a map Θ from \mathcal{H} to \mathcal{H}^* as $\Theta(y) := \beta_y$. It is easy to verify that Θ is linear.

$$\|\Theta(y)\| = \|\beta_y\| = \sup\{\beta_y(x) : \|x\| = 1\}$$

$$= \sup\{\langle x, y \rangle : \|x\| = 1\}$$

$$\leq \sup\{\|x\| \|y\| : \|x\| = 1\}$$

$$= \|y\|.$$

That is, $\|\Theta(y)\| \le \|y\|$. So $\|\Theta\| \le 1$. On the other hand, consider an arbitrary point $y_0 \in \mathcal{H}$ with $y_0 \ne 0$:

$$\|\Theta\| = \sup \left\{ \frac{\|\Theta(y)\|}{\|y\|} : y \neq 0 \right\}$$

$$\geq \frac{\|\Theta(y)\|}{\|y\|} \Big|_{y=y_0}$$

$$= \frac{\|\Theta(y_0)\|}{\|y_0\|}$$

$$= \frac{\|\beta_{y_0}\|}{\|y_0\|}$$

$$= \frac{1}{\|y_0\|} \sup \left\{ \frac{\|\beta_{y_0}(y)\|}{\|y\|} : y \neq 0 \right\}$$

$$\geq \frac{1}{\|y_0\|} \frac{\|\beta_{y_0}(y_0)\|}{\|y_0\|}$$

$$\geq \frac{1}{\|y_0\|} \frac{\|y_0\|^2}{\|y_0\|}$$

$$= \frac{1}{\|y_0\|} \frac{\|y_0\|^2}{\|y_0\|}$$

That is, $\|\Theta\| \ge 1$. So $\|\Theta\| = 1$. So Θ is isometric. It immediately follows that Θ is injective. Now it remains to prove that Θ is surjective. Let $\varphi \in \mathcal{H}^*$. If $\varphi = 0$, then $\varphi = \Theta(0)$ and we are done. Otherwise, let $\mathcal{M} := \ker(\varphi)$. Then we have $\operatorname{codim} \mathcal{M} = \dim \mathcal{M}^{\perp} = 1$. Take $e \in \mathcal{M}^{\perp}$ such that ||e|| = 1. Let P denote the orthogonal projection onto \mathcal{M} . Then 1 - P is the orthogonal projection onto \mathcal{M}^{\perp} .

$$x = Px + (1 - P)x = Px + \langle x, e \rangle e.$$

So for $x \in \mathcal{H}$,

$$\varphi(x) = \varphi(Px) + \langle x, e \rangle \varphi(e) = \langle x, \overline{\varphi(e)}e \rangle = \beta_y(x)$$

where $y := \overline{\varphi(e)}e$. Hence $\varphi = \beta_y$. So Θ is surjective. This completes the proof.

Operators

9.1 Bounded Operators

Definition (Bounded Operator). Let \mathfrak{X} and \mathfrak{Y} be normed linear spaces. Let T be a linear map from \mathfrak{X} to \mathfrak{Y} . We say that T is a **bounded operator** if

$$\exists k \in \mathbb{R}, \quad \forall x \in \mathfrak{X}, \quad ||Tx||_{\mathfrak{Y}} \le k||x||_{\mathfrak{X}}.$$

Definition (Operator Norm). Let \mathfrak{X} and \mathfrak{Y} be normed linear spaces. Let T be a bounded operator from \mathfrak{X} to \mathfrak{Y} . We define the **operator norm** of T, denoted by ||T||, to be the number given by

$$||T|| := \inf\{k \in \mathbb{R} : \forall x \in \mathfrak{X}, ||Tx||_{\mathfrak{Y}} \le k||x||_{\mathfrak{X}}\}.$$

Proposition 9.1.1.

$$||T|| = \sup\{||Tx||_{\mathfrak{D}} : x \in \mathfrak{X}, ||x||_{\mathfrak{X}} = 1\}.$$

Proposition 9.1.2. Let X and Y be normed linear spaces. Let T be a linear map from X to Y. Then T is bounded if and only if T is continuous.

9.2 Examples of Bounded Operators

Example 9.2.1 (The Multiplication Operator). Let $\mathfrak{X} = (\mathcal{C}([0,1],\mathbb{C}), \|\cdot\|_{\infty})$. Let f be a function in \mathfrak{X} . We define the **multiplication operator** on \mathfrak{X} , w.r.t. f, denoted by M_f , as

$$M_f(g) = fg.$$

Then M_f is bounded and $||M_f|| = ||f||_{\infty}$.

Proof. Let g be an arbitrary function in \mathfrak{X} . Then

$$||M_f g||_{\infty} = ||fg||_{\infty}$$

$$\begin{split} &= \sup_{x \in [0,1]} |f(x)g(x)| \\ &= \sup_{x \in [0,1]} |f(x)||g(x)| \\ &\leq \sup_{x \in [0,1]} |f(x)| \sup_{x \in [0,1]} |g(x)| \\ &= \|f\|_{\infty} \|g\|_{\infty}. \end{split}$$

That is, $||M_f g||_{\infty} \leq ||f||_{\infty} ||g||_{\infty}$. So $||f||_{\infty}$ is an element of the set $S = \{k \in \mathbb{R} : \forall g \in \mathfrak{X}, ||M_f g||_{\mathfrak{Y}} \leq k ||g||_{\mathfrak{X}}\}$. So $||M_f|| = \inf(S) \leq ||f||_{\infty}$. Consider g_0 given by $g_0(x) = 1$. Then g_0 in \mathfrak{X} . Then

$$||M_f g_0||_{\infty} = ||f g_0||_{\infty} = ||f||_{\infty} = ||f||_{\infty} ||g_0||_{\infty}.$$

Let k be an arbitrary element in S. Assume for the sake of contradiction that $k < ||f||_{\infty}$. Then

$$||f||_{\infty} ||g_0||_{\infty} = ||M_f g_0||_{\infty}$$

 $\leq k ||g_0||_{\infty}$
 $< ||f||_{\infty} ||g_0||_{\infty}.$

This leads to a contradiction. So $\forall k \in S, \ k \geq \|f\|_{\infty}$. So $\|f\|_{\infty}$ is a lower bound for the set S. So $\|M_f\| = \inf(S) \geq \|f\|_{\infty}$. Since $\|M_f\| \leq \|f\|_{\infty}$ and $\|M_f\| \geq \|f\|_{\infty}$, we get $\|M_f\| = \|f\|_{\infty}$.

Example 9.2.2 (The Volterra Operator). Let $\mathfrak{X} = (\mathcal{C}([0,1],\mathbb{C}), \|\cdot\|_{\infty})$. Define

$$Vf := x \mapsto \int_0^x f(t)dt.$$

Then the Volterra Operator is bounded and $||V|| \leq 1$.

Proof. Let f be an arbitrary function in \mathfrak{X} with $||f||_{\infty} = 1$. Then $\forall x \in [0,1]$,

$$|Vf(x)| = \left| \int_0^x f(t)dt \right|$$

$$\leq \int_0^x |f(t)|dt$$

$$\leq \int_0^x \sup_{t \in [0,1]} |f(t)|dt$$

$$= \int_0^x ||f||_{\infty} dt$$

$$= \int_0^x 1dt$$

$$= x.$$

That is, $\forall x \in [0,1], |Vf(x)| \le 1$. So $||Vf||_{\infty} \le 1$. Since $\forall f \in \mathfrak{X} : ||f||_{\infty} = 1, ||Vf||_{\infty} \le 1$, we get $||V|| \le 1$.

Example 9.2.3 (The Diagonal Operator). Let $\mathfrak{X} = \ell^2(\mathbb{N})$. Let

$$D = \begin{bmatrix} d_1 & & & \\ & d_2 & & \\ & & d_3 & \\ & & & \ddots \end{bmatrix}.$$

Then D is bounded if and only if $(d_i)_{i\in\mathbb{N}}$ is bounded and $||D|| = ||(d_i)_{i\in\mathbb{N}}||_{\infty}$.

Proof. Case 1.

$$||Dx||_{2}^{2} = \sum_{i \in \mathbb{N}} |d_{i}x_{i}|^{2}$$

$$= \leq \sum_{i \in \mathbb{N}} ||(d_{j})_{j \in \mathbb{N}}||_{\infty} |x_{i}|^{2}$$

$$= ||(d_{j})_{j \in \mathbb{N}}||_{\infty} \sum_{i \in \mathbb{N}} |x_{i}|^{2}$$

$$= ||(d_{j})_{j \in \mathbb{N}}||_{\infty} ||x||_{2}^{2}.$$

Case 2.

If $(d_i)_{i\in\mathbb{N}} \notin \ell^{\infty}$, $\exists (d_{n_i})_{i\in\mathbb{N}} \to \infty$.

$$||De_{n_i}||_2 = ||d_{n_i}e_{n_i}||_2$$
$$= |d_{n_i}|||e_{n_i}||_2$$
$$= |d_{n_i}|.$$

So $||D|| \ge ||De_{n_i}||_2 \to \infty$.

Example 9.2.4 (Weighted Shifts).

• Let $\mathcal{H} = \ell_{\mathbb{N}}^2$. Let $(w_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{N}}^{\infty}$. We define an unilateral forward weighted shift W on \mathcal{H} as

$$W(x_n) := (0, w_1x_1, w_2x_2, w_3x_3, \dots).$$

i.e.,

$$W = \begin{bmatrix} 0 & & & & & \\ w_1 & 0 & & & & \\ & w_2 & 0 & & & \\ & & w_3 & 0 & & \\ & & & \ddots & \ddots \end{bmatrix}.$$

Then W is bounded and $||W|| = \sup\{|w_n| : n \in \mathbb{N}\}.$

• Let $\mathcal{H} = \ell_{\mathbb{N}}^2$. Let $(v_n)_{n \in \mathbb{N}} \in \ell_{\mathbb{N}}^{\infty}$. We define an unilateral backward weighted shift V on \mathcal{H} as

$$V(x_n) := (v_1 x_2, v_2 x_3, v_3 x_4, \dots).$$

Then V is bounded and $||V|| = \sup\{|v_n| : n \in \mathbb{N}\}.$

• Let $\mathcal{H} = \ell_{\mathbb{Z}}^2$. Let $(u_n)_{n \in \mathbb{Z}} \in \ell_{\mathbb{Z}}^{\infty}$. We define a bilateral weighted shift U on \mathcal{H} as

$$U(x_n) := (u_{n-1}x_{n-1})_{n \in \mathbb{Z}}.$$

Then U is bounded and $||U|| = \sup\{|u_n| : n \in \mathbb{Z}\}.$

Example 9.2.5 (The Composition Operators). Let $\mathfrak{X} = \mathcal{C}([0,1],\mathbb{C})$. Let $\varphi \in \mathcal{C}([0,1],[0,1])$. We define the **composition operator** on \mathfrak{X} , denoted by C_{φ} as

$$C_{\varphi}(f) := f \circ \varphi.$$

Then C_{φ} is contractive.

Proof.

$$||C_{\varphi}(f)|| = \sup_{x \in [0,1]} |(f \circ \varphi)(x)|$$

$$\leq ||f||_{\infty}.$$

9.3 The Space of Bounded Operators

Proposition 9.3.1. Let \mathfrak{X} and \mathfrak{Y} be normed linear spaces. Then $\mathcal{B}(\mathfrak{X},\mathfrak{Y})$ is a vector space and the operator norm is a norm on $\mathcal{B}(\mathfrak{X},\mathfrak{Y})$.

Proposition 9.3.2. Let \mathfrak{X} and \mathfrak{Y} be normed linear spaces. Let $\mathcal{B}(\mathfrak{X},\mathfrak{Y})$ be the space of bounded linear operators from \mathfrak{X} to \mathfrak{Y} . Then if \mathfrak{Y} is complete, $\mathcal{B}(\mathfrak{X},\mathfrak{Y})$ is complete.

Proposition 9.3.3. Let \mathfrak{X} and \mathfrak{Y} be normed linear spaces. Let $\|\cdot\|_1$ and $\|\cdot\|_2$ be two equivalent norms on $\mathcal{B}(\mathfrak{X},\mathfrak{Y})$. Then $T \in \mathcal{B}(\mathfrak{X},\mathfrak{Y}), \|\cdot\|_1$ if and only if $T \in \mathcal{B}(\mathfrak{X},\mathfrak{Y}), \|\cdot\|_2$.

9.4 Invertible Bounded Operators

Proposition 9.4.1. Let $(\mathfrak{X}, \|\cdot\|_1)$ be a Banach space. Let $S \in \mathcal{B}(\mathfrak{X})$ be a bounded linear map that is invertible. Define a norm $\|\cdot\|_2$ on \mathfrak{X} as

$$||x||_2 := ||Sx||_1.$$

Then $\|\cdot\|_1$ and $\|\cdot\|_2$ are equivalent.

Proof. On one hand, since S is bounded, $\exists c_1$ such that $\forall x \in \mathfrak{X}$, $||Sx||_1 \leq c_1 ||x||_1$. That is, $||x||_2 \leq c_1 ||x||_1$.

On the other hand, since S is invertible, S^{-1} exists and is also bounded. Since S^{-1} is bounded, $\exists c_2$ such that $\forall x \in \mathfrak{X}, \|S^{-1}x\|_1 \leq c_2\|x\|_1$. Consider x = Sx, we get $\forall x \in \mathfrak{X}, \|S^{-1}Sx\|_1 \leq c_2\|Sx\|_1$. That is, $\|x\|_1 \leq c_2\|x\|_2$.

So $\|\cdot\|_1$ and $\|\cdot\|_2$ are equivalent.

Proposition 9.4.2. Let $(\mathfrak{X}, \|\cdot\|)$ be a Banach space. Let S be a map in $\mathcal{B}(\mathfrak{X})$ that is invertible. Then

$$||S^{-1}|| = (\inf\{||Sx|| : ||x|| = 1\})^{-1}.$$

Proof.

$$\begin{split} \|S^{-1}\| &= \sup\{\|S^{-1}x\| : \|x\| = 1\} \\ &= \sup\left\{\frac{\|S^{-1}x\|}{\|x\|} : \|x\| \neq 0\right\} \\ &= \sup\left\{\frac{\|S^{-1}Sx\|}{\|Sx\|} : \|x\| \neq 0\right\} \\ &= \sup\left\{\frac{\|x\|}{\|Sx\|} : \|x\| \neq 0\right\} \\ &= \sup\left\{\frac{1}{\|Sx\|} : \|x\| = 1\right\} \\ &= (\inf\{\|Sx\| : \|x\| = 1\})^{-1}. \end{split}$$

That is,

$$||S^{-1}|| = (\inf\{||Sx|| : ||x|| = 1\})^{-1}.$$

Dual Space

10.1 Definition

Definition ((Topological) Dual Space). Let \mathfrak{X} be a normed linear space over field \mathbb{K} . We define the (topological) dual space of \mathfrak{X} , denoted by \mathfrak{X}^* , to be the space $\mathcal{B}(\mathfrak{X}, \mathbb{K})$.

Definition (Linear Functionals). We call the elements of \mathfrak{X}^* linear functionals.

Proposition 10.1.1. Let X be a normed linear space. Then there exists a contractive map from X to its double dual X^{**} .

10.2 Properties

10.3 Examples of Dual Space

Example 10.3.1. $c_0(\mathbb{N})^*$ is isometrically isomorphic to $\ell^1(\mathbb{N})$.

Example 10.3.2. $c_0(\mathbb{N})^*$ is isometrically isomorphic to $\ell^{\infty}(\mathbb{N})$.

Quotient Spaces

11.1 Definitions

Definition. Let \mathfrak{V} be a vector space. Let \mathfrak{W} be a subspace of \mathfrak{V} . We define a **quotient** space, denoted by $\mathfrak{V}/\mathfrak{W}$, to be a set $\{v + \mathfrak{W} : v \in \mathfrak{V}\}$ with operations

$$(v_1 + \mathfrak{W}) + (v_2 + \mathfrak{W}) := (v_1 + v_2) + \mathfrak{W}$$
 and
$$\kappa(v + \mathfrak{W}) := (\kappa v) + \mathfrak{W}.$$

Definition (Quotient Map). Let $(\mathfrak{X}, \|\cdot\|)$ be a normed linear space. Let \mathfrak{M} be a linear manifold in \mathfrak{X} . We define the **quotient map** on \mathfrak{X} with respect to \mathfrak{M} , denoted by $q_{\mathfrak{M}}$, to be a function from \mathfrak{X} to $\mathfrak{X}/\mathfrak{M}$ given by

$$q_{\mathfrak{M}}(x) := x + \mathfrak{M}$$

Proposition 11.1.1. Quotient maps are contractive. i.e.,

$$\forall x \in \mathfrak{X}, \quad \|x + \mathfrak{M}\|_{\mathfrak{X}/\mathfrak{M}} \le \|x\|_{\mathfrak{X}}.$$

Proposition 11.1.2. Let \mathfrak{X} be a normed linear space. Let \mathfrak{M} be a closed subspace of \mathfrak{X} . Let q be the canonical quotient map from \mathfrak{X} to $\mathfrak{X}/\mathfrak{M}$. Then

• q is a continuous map. i.e.,

$$\forall$$
 open set $W \subseteq \mathfrak{X}/\mathfrak{M}$, $q^{-1}(W)$ is open in \mathfrak{X} .

• q is an open map. i.e.,

$$\forall open \ set \ G \subseteq \mathfrak{X}, \quad q(G) \ is \ open \ in \ \mathfrak{X}/\mathfrak{M}.$$

Proof. Since q is contractive, q is continuous and hence (1).

Definition (Seminorm on Quotient Spaces). Let $(\mathfrak{X}, \|\cdot\|)$ be a normed linear space. Let \mathfrak{M} be a linear manifold in \mathfrak{X} . We define a **seminorm** on $\mathfrak{X}/\mathfrak{M}$ to be a function from $\mathfrak{X}/\mathfrak{M}$ to \mathbb{R} given by

$$p(x+\mathfrak{M}) := \inf\{\|x+m\| : m \in \mathfrak{M}\}.$$

Proposition 11.1.3. Seminorms on quotient spaces are indeed seminorms.

Proposition 11.1.4. A seminorm on a quotient space $\mathfrak{X}/\mathfrak{M}$ is a norm if and only if \mathfrak{M} is closed.

Topological Vector Space

12.1 Definitions

Definition (Compatible). Let W be a vector space over field K. Let T be a topology on W. We say that T is **compatible** with the vector space structure on W if the addition and scalar multiplication operations on W are continuous.

Definition (Topological Vector Space). We define a topological vector space to be a vector space with a compatible Hausdorff topology.

Proposition 12.1.1 (Stability under Linear Combinations). Let X be a normed vector space over \mathbb{F} . Let K be a compact set in the space. Let C be a closed set in the space. Then $\forall \alpha, \beta \in \mathbb{F}$, the set S given by $S := \alpha K + \beta C$ is closed.

Proof. The case where $\beta=0$ is trivial. I will assume $\beta\neq 0$. Let $\alpha,\beta\in\mathbb{F}$ be arbitrary. Let $\{s_i\}_{i\in\mathbb{N}}$ be an arbitrary sequence in S that converges. Say the limit is s_∞ . Since $s_i\in S$ for any $i\in\mathbb{N}$ and $S=\alpha K+\beta C$, $s_i=\alpha k_i+\beta c_i$ for some $k_i\in K$ and some $c_i\in C$, for any $i\in\mathbb{N}$. Since $\{k_i\}_{i\in\mathbb{N}}$ is a sequence in K and K is compact, there exists a convergent subsequence $\{k_i\}_{i\in I}$ of $\{k_i\}_{i\in\mathbb{N}}$ in K. Say $\{k_i\}_{i\in I}$ converges to $k_\infty\in K$. Since $\{s_i\}_{i\in\mathbb{N}}$ converges to s_∞ , $\{s_i\}_{i\in I}$ also converges to s_∞ . Since $s_i=\alpha k_i+\beta c_i$, $s_i=\beta^{-1}(s_i-\alpha k_i)$. Define $s_i=\beta^{-1}(s_i-\alpha k_i)$. Since $\{s_i\}_{i\in I}$ converges to s_∞ and $\{k_i\}_{i\in I}$ converges to k_∞ and $k_i=\beta^{-1}(s_i-\alpha k_i)$, $\{s_i\}_{i\in I}$ converges to s_∞ . Since $\{s_i\}_{i\in I}$ is a sequence in S and converges to S_∞ and S_∞

Remark. The sum of two closed sets may not be closed.

Proof. Counter-example 1

Consider $A := \{n : n \in \mathbb{N}\}$ and $B := \{n + \frac{1}{n} : n \in \mathbb{N}\}.$

(https://math.stackexchange.com/questions/124130/sum-of-two-closed-sets-in-mathbb-r-is-closed) Their sum contains the sequence $\{\frac{1}{n}\}_{n\in\mathbb{N}}$ but does not contain 0.

Counter-example 2

Consider
$$A:=\mathbb{R}\times\{0\}$$
 and $B:=\{(x,y)\in\mathbb{R}^2:x,y>0,xy\geq 1\}.$ Their sum is $\mathbb{R}\times\mathbb{R}_{++}.$

12.2 Examples

Example 12.2.1. Let \mathfrak{X} be a normed linear space. Then \mathfrak{X} is a topological vector space with the topology induced by the norm.

Proposition 12.2.1. Normed linear spaces are Hausdorff.

Example 12.2.2. Let \mathfrak{X} be a Banach space. Let \mathfrak{X}^* denote the dual space of \mathfrak{X} . Let τ_* denote the weak topology on \mathfrak{X}^* induced by elements of \mathfrak{X} as

$$\lim_{\alpha} x_{\alpha}^* = x^* \iff \forall x \in \mathfrak{X}, \lim_{\alpha} x_{\alpha}^*(x) = x^*(x).$$

Then (\mathfrak{X}^*, τ_*) is a topological vector space.

12.3 Neighborhood Improvements

Proposition 12.3.1. Let (V, τ) be a topological vector space. Let $U \in \mathcal{U}_0$ be a neighborhood of 0 in V. Then

- $\exists N \in \mathcal{U}_0 \text{ such that } N + N \subseteq U.$
- $\exists M \in \mathcal{U}_0 \text{ and } \exists \varepsilon > 0 \text{ such that } \forall 0 < |k| < \varepsilon, \text{ we have } kM \subseteq U.$

•

Equicontinuity in Metric Spaces

13.1 Definitions

Definition ((Pointwise) Equicontinuity). Let (X, d_X) and (Y, d_Y) be metric spaces. Let \mathcal{F} be a collection of functions from X to Y. Let x_0 be a point in X. We say that \mathcal{F} is (pointwise) equicontinuous at point x_0 if for any positive number ε , there exists some number $\delta(x_0, \varepsilon)$ such that for any function f in \mathcal{F} and any point x in X, we have

$$d_{Y}(f(x), f(x_{0})) < \varepsilon$$

whenever $d_X(x, x_0) < \delta(x_0, \varepsilon)$ is satisfied.

Definition (Uniform Equicontinuity). Let (X, d_X) and (Y, d_Y) be metric spaces. Let \mathcal{F} be a collection of functions from X to Y. We say that \mathcal{F} is uniformly equicontinuous if for any positive number ε , there exists some number $\delta(\varepsilon)$ such that for any function f in \mathcal{F} and any points x_1 and x_2 in X, we have

$$d_Y(f(x_1), f(x_2)) < \varepsilon$$

whenever $d_X(x_1, x_2) < \delta(\varepsilon)$ is satisfied.

13.2 Sufficient Conditions

Proposition 13.2.1. The closure of an equicontinuous family of functions is equicontinuous.

Proof.

Let (X, d_X) and (Y, d_Y) be metric spaces.

Let \mathcal{F} be an equicontinuous family of functions from X to Y.

We are to prove that $cl(\mathcal{F})$ is equicontinuous.

Let x_0 be an arbitrary point in X.

Let ε be an arbitrary positive number.

Since \mathcal{F} is equicontinuous at point x_0 , there exists some $\delta(x_0, \varepsilon)$ such that for any function f in \mathcal{F} and any point x in X such that $d_X(x, x_0) < \delta(x_0, \varepsilon)$, we have $d_Y(f(x), f(x_0)) < \varepsilon/3$.

Let f be an arbitrary function in $cl(\mathcal{F})$.

Let x be an arbitrary point in X such that $d_X(x, x_0) < \delta(x_0, \varepsilon)$.

Since $f \in cl(\mathcal{F})$, there exists some function $f_0 \in \mathcal{F}$ such that $d_{\infty}(f, f_0) < \varepsilon/3$.

Since $d_{\infty}(f, f_0) < \varepsilon/3$, $d_Y(f(x), f_0(x)) < \varepsilon/3$ and $d_Y(f(x_0), f_0(x_0)) < \varepsilon/3$.

Since $f_0 \in \mathcal{F}$ and $d_X(x, x_0) < \delta(x_0, \varepsilon), d_Y(f_0(x), f_0(x_0)) < \varepsilon/3$.

Since $d_Y(f(x), f_0(x)) < \varepsilon/3$ and $d_Y(f(x_0), f_0(x_0)) < \varepsilon/3$ and $d_Y(f_0(x), f_0(x_0)) < \varepsilon/3$, $d_Y(f(x), f(x_0)) < \varepsilon$.

Since for any positive number ε , there exists some $\delta(x_0,\varepsilon)$ such that for any function f in $cl(\mathcal{F})$ and any point x in X such that $d_X(x,x_0) < \delta(x_0,\varepsilon)$, we have $d_Y(f(x),f(x_0)) < \varepsilon$, by definition of equicontinuous, $cl(\mathcal{F})$ is equicontinuous at point x_0 .

Since $cl(\mathcal{F})$ is equicontinuous at point x_0 for any point x_0 in X, $cl(\mathcal{F})$ is equicontinuous.

Adjoint Operator

14.1 Definitions

Definition (Adjoint Matrix). Let A be an $m \times n$ matrix. We define the **adjoint** of A, denoted by A^* , to be an $n \times m$ matrix given by

$$(A^*)_{ij} := \overline{(A)_{ji}}.$$

Definition (Adjoint Operator). Let V and W be inner product spaces. Let T be a linear map from V to W. We define the **adjoint** of T, denoted by T^* , to be a map from W to V such that

$$\forall x \in V, \forall y \in W, \quad \langle T(x), y \rangle_W = \langle x, T^*(y) \rangle_V.$$

Proposition 14.1.1 (Existence). Let V be a finite-dimensional inner product space and T be a linear operator on V. Then the adjoint of T exists.

Proposition 14.1.2 (Uniqueness). Let V be an inner product space and T be a linear operator on V. Then the adjoint of T is unique, provided that it exists.

14.2 Properties of the Adjoint Operator

Proposition 14.2.1. Let V be an inner product space. Then

- (1) $(I_V)^* = I_V$ where I_V is the identity operator on V.
- (2) $T^{**} = T$ for any linear operator T on V.

Proposition 14.2.2. Let V be an inner product space and T be a linear operator on V. Then T^* is also linear.

Proposition 14.2.3. Let V be an inner product space. Then

(1) For any linear operators T and U,

$$(T+U)^* = T^* + U^*.$$

(2) For any linear operator T,

$$(cT)^* = \overline{c} \cdot T^*.$$

(3) For any linear operator T and U,

$$(TU)^* = U^*T^*.$$

Proposition 14.2.4. Let V be a finite-dimensional inner product space and T be a linear operator on V. Then if T is invertible, T^* is also invertible.

Proposition 14.2.5. Let V be an inner product space and T be an invertible linear operator on V. Then $(T^{-1})^* = (T^*)^{-1}$.

14.3 Normal Operators

Definition (Normal). Let V be an inner product space and T be a linear operator on V. We say that T is **normal** if $TT^* = T^*T$.

14.4 Self-adjoint

Convolution

Definition (Convolution). Let f and g be functions from \mathbb{R} to \mathbb{R} . We define the **convolution** of f and g, denoted by f * g, to be a function on \mathbb{R} given by

$$(f*g)(t) := \int_{-\infty}^{+\infty} f(\tau)g(t-\tau)dt.$$

Coercive Functions

16.1 Definitions

Definition (Coercive). Let f be a function from \mathbb{R}^d to \mathbb{R}^* . We say that f is coercive if $\lim_{\|x\|\to\infty} f(x) = +\infty$.

16.2 Properties

Proposition 16.2.1. Let f be a proper lower semi-continuous function from \mathbb{R}^d to \mathbb{R}^* . Let K be a compact set in \mathbb{R}^d . Assume $K \cap \text{dom}(f) \neq \emptyset$. Then f attains its minimum over K.

Proof.

Define $m := \inf_{x \in K} f(x)$.

Since $m = \inf_{x \in K} f(x)$, there exists a sequence $\{x_i\}_{i \in \mathbb{N}}$ in K such that $\lim_{i \to \infty} f(x_i) = m$

Since K is compact and $\{x_i\}_{i\in\mathbb{N}}\subseteq K$, there exists a convergent subsequence $\{x_i\}_{i\in I}$ in K where I is an infinite subset of \mathbb{N} .

Say the limit is x_{∞} where $x_{\infty} \in K$.

Since $\lim_{i\to\infty} f(x_i) = m$, we get $\lim_{i\in I, i\to\infty} f(x_i) = m$.

Since $\lim_{i \in I, i \to \infty} f(x_i) = m$, we get $\lim \inf_{i \in I, i \to \infty} f(x_i) = m$.

Since f is lower semi-continuous and $\lim_{i \in I, i \to \infty} x_i = x_\infty$, we get $f(x_\infty) \leq \liminf_{i \in I, i \to \infty} x_i$.

That is, $f(x_{\infty}) \leq m$.

Since $m = \inf_{x \in K} f(x)$, we have $\forall x \in K, f(x) \ge m$.

In particular, $f(x_{\infty}) \geq m$.

Since $f(x_{\infty}) \geq m$ and $f(x_{\infty}) \leq m$, $f(x_{\infty}) = m$.

Since f is proper, $f(x_{\infty}) = m \neq -\infty$.

So f attains its minimum at point x_{∞} .

Proposition 16.2.2. Let f be a proper, lower semi-continuous, and coercive function from \mathbb{R}^d to \mathbb{R}^* . Let C be a closed subset of \mathbb{R}^d . Assume $C \cap \text{dom}(f) \neq \emptyset$. Then f attains its minimum over C.

Proof.

Since $C \cap \text{dom}(f) \neq \emptyset$, take $x \in C \cap \text{dom}(f)$.

Since f is coercive, $\exists R$ such that $\forall y, ||y|| > R$, we have $f(y) \ge f(x)$.

Since $x \in C \cap \text{dom}(f)$ and $\forall y, ||y|| > R$, we have $f(y) \geq f(x)$, the set of minimizers of f over C is the same as the set of minimizers of f over $C \cap \text{ball}[0, R]$.

Since C and ball [0, R] are both closed, $C \cap \text{ball}[0, R]$ is closed.

Since ball[0, R] is bounded, $C \cap \text{ball}[0, R]$ is bounded.

Since $C \cap \text{ball}[0, R]$ is closed and bounded, by the Heine-Borel Theorem, $C \cap \text{ball}[0, R]$ is compact.

Since f is proper and lower semi-continuous and $C \cap \text{ball}[0, R]$ is compact, f attains its minimum over $C \cap \text{ball}[0, R]$.

So f attains its minimum over C.

Unclassified Results

Proposition 17.0.1. Let (X,d) be a compact metric space. Let L(X) be the set of all Lipschitz functions from X to \mathbb{R} . Let C(X) be the set of all continuous functions from X to \mathbb{R} . Then L(X) is dense in C(X).

Proposition 17.0.2. Let $(V, \|\cdot\|)$ be a normed vector space. Let S be a subset of V. Let p be a vector in V. Then we have the followings.

(1)
$$p + int(S) = int(p + S)$$
,

(2)
$$p + cl(S) = cl(p + S)$$
.

Proof.

Proof of (1).

For one direction, let x be an arbitrary point in the set (p + int(S)).

We are to prove that $x \in int(p+S)$.

Since $x \in (p + int(S)), (x - p) \in int(S)$.

Since $(x-p) \in int(S)$, by definition of interior, there exists a radius r such that

$$B(x-p,r) \subseteq S$$
.

It follows that $B(x,r) \subseteq p + S$.

Since there exists a radius r such that $B(x,r) \subseteq p+S$, by definition of interior,

$$x \in int(p+S)$$
.

For the reverse direction, let x be an arbitrary point in int(p+S).

We are to prove that $x \in p + int(S)$.

Since $x \in int(p+S)$, by definition of interior, there exists a radius r such that

$$B(x,r) \subseteq (p+S)$$
.

It follows that $B(x-p,r) \subseteq S$.

Since there exists a radius r such that $B(x-p,r) \subseteq S$, by definition of interior,

$$(x-p) \in int(S)$$
.

Since $(x - p) \in int(S)$, we get $x \in (p + int(S))$.

Proof of (2).

For one direction, let x be an arbitrary point in the set (p + cl(S)).

We are to prove that $x \in cl(p+S)$.

Since $x \in (p + cl(S))$, we get $(x - p) \in cl(S)$.

Since $(x-p) \in cl(S)$, by definition of closure, for any radius r, we have

$$B(x-p,r) \cap S \neq \emptyset$$
.

It follows that $B(x,r) \cap (p+S) \neq \emptyset$.

Since for any radius r, $B(x,r) \cap (p+S) \neq \emptyset$, by definition of closure, we get

$$x \in cl(p+S)$$
.

For the reverse direction, let x be an arbitrary point in cl(p+S).

We are to prove that $x \in (p + cl(S))$.

Since $x \in cl(p+S)$, by definition of closure, for any radius r, we have

$$B(x,r) \cap (p+S) \neq \emptyset$$
.

It follows that $B(x-p,r) \cap S \neq \emptyset$.

Since for any radius r, $B(x-p,r) \cap S \neq \emptyset$, by definition of closure, we get

$$(x-p) \in cl(S)$$
.

Since $(x - p) \in cl(S)$, we get $x \in (p + cl(S))$.

Proposition 17.0.3. Let $(V, \|\cdot\|)$ be a normed vector space. Let S be a subset of V. Let λ be a non-zero real number. Then

- (1) $\lambda int(S) = int(\lambda S)$.
- (2) $\lambda \operatorname{cl}(S) = \operatorname{cl}(\lambda S)$.

Proof.

Proof of (1).

For one direction, let x be an arbitrary point in $\lambda int(S)$.

We are to prove that $x \in int(\lambda S)$.

Since $x \in \lambda int(S)$, we get $x/\lambda \in int(S)$.

Since $x/\lambda \in int(S)$, by definition of interior, there exists a radius r such that

$$B(x/\lambda, r) \subseteq S$$
.

Let y be an arbitrary point in $B(x, \lambda r)$.

Since $y \in B(x, \lambda r)$, we get $||y - x|| \le \lambda r$.

Since $||y - x|| \le \lambda r$, we get $||y/\lambda - x/\lambda|| \le r$.

Since $||y/\lambda - x/\lambda|| \le r$, we get $y/\lambda \in B(x/\lambda, r)$.

Since $y/\lambda \in B(x/\lambda, r)$ and $B(x/\lambda, r) \subseteq S$, we get $y/\lambda \in S$.

Since $y/\lambda \in S$, we get $y \in \lambda S$.

Since any point in $B(x, \lambda r)$ is also in λS , we get $B(x, \lambda r) \subseteq \lambda S$.

Since there exists a radius r such that $B(x, \lambda r) \subseteq \lambda S$, by definition of interior, we get

$$x \in int(\lambda S)$$
.

For the reverse direction,