

Convex Optimization

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Chapter 1

Minimizers

1.1 Local Minimizers and Global Minimizers

Proposition 1.1.1. *Let f be a proper convex function. Then any local minimizer of f is a global minimizer.*

Proof Approach 1.

Let f be a convex function.

Let x_0 be a local minimizer of f , if any.

Since x_0 is a local minimizer, $\exists \delta > 0$, $\forall x \in \text{ball}(x_0, \delta)$, we have $f(x) \geq f(x_0)$.

Since f is proper, $\text{dom}(f) \neq \emptyset$.

Let y be an arbitrary point in $\text{dom}(f)$.

Case 1. $y \in \text{ball}(x_0, \delta)$.

Since $y \in \text{ball}(x_0, \delta)$, and $\forall x \in \text{ball}(x_0, \delta)$, $f(x) \geq f(x_0)$, we get $f(y) \geq f(x_0)$.

Case 2. $y \notin \text{ball}(x_0, \delta)$.

Define $\lambda := \delta / \|x - y\|$.

Since $y \notin \text{ball}(x_0, \delta)$, $\|x - y\| > 0$.

Since $\delta > 0$ and $\|x - y\| > 0$, we get $\lambda > 0$.

Since $y \notin \text{ball}(x_0, \delta)$, $\|x - y\| > \delta$.

Since $\delta < \|x - y\|$, $\lambda < 1$.

Define a point $z := \lambda y + (1 - \lambda)x$.

Since f is convex, $\text{dom}(f)$ is convex.

Since

■

Proposition 1.1.2. *Any locally optimal point of a convex problem is globally optimal.*

Proposition 1.1.3. *A point x is optimal if and only if it is feasible and for any feasible point y ,*

$$\nabla f_0(x) \cdot (y - x) \geq 0.$$

I forgot where this came from... and I don't know what it's talking about...

1.2 Main Results

Theorem 1. *Let f be a proper function from \mathbb{E} to \mathbb{R}^* . Then*

$$\operatorname{argmin}(f) = \{x \in \mathbb{E} : 0 \in \partial f(x)\}.$$

Proof.

$$\begin{aligned} x &\in \operatorname{argmin}(f) \\ \iff \forall y \in \mathbb{E}, f(x) &\leq f(y) \\ \iff \forall y \in \mathbb{E}, \langle 0, y - x \rangle + f(x) &\leq f(y) \\ \iff 0 \in \partial f(x). \end{aligned}$$

■

Theorem 2. *Let f be a proper, convex, and lower semi-continuous function from \mathbb{R}^d to \mathbb{R} . Let x be a point in \mathbb{R}^d . Then x is a global minimizer of f if and only if x is a fixed point of the proximal operator of f . i.e. $x = \operatorname{prox}_f(x)$.*

Chapter 2

Duality

2.1 Lagrangian Dual

2.1.1 Basics

$$\begin{array}{ll}\text{minimize} & f_0(x) \\ \text{subject to} & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & h_i(x) = 0, \quad i = 1, \dots, p\end{array}$$

where $x \in \mathcal{D} \subseteq \mathbb{R}^n$.

Lagrangian: $L : \mathcal{D} \times \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$.

$$L(x, \lambda, \nu) = f_0(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \nu_i h_i(x).$$

Lagrange Dual Function: $g : \mathbb{R}^m \times \mathbb{R}^p \rightarrow \mathbb{R}$.

$$g(\lambda, \nu) = \inf_{x \in \mathcal{D}} L(x, \lambda, \nu).$$

Proposition 2.1.1. *The Lagrange dual function is concave.*

Proof. The Lagrange dual function is an infimum of an affine function and hence concave. ■

Proposition 2.1.2. *If $\lambda \geq 0$, then $g(\lambda, \nu) \leq p^*$ where p^* denotes the optimal value of the primal problem.*

Proof. Let \bar{x} be an arbitrary feasible solution. Then

$$f_0(\bar{x}) \geq L(\bar{x}, \lambda, \nu) \geq \inf_{x \in \mathcal{D}} L(x, \lambda, \nu) = g(\lambda, \nu).$$

■

2.1.2 Dual of Linear Programming

$$\begin{array}{ll} \text{minimize} & c^T x \\ \text{subject to} & Ax = b, \quad x \geq 0 \end{array}$$

The Lagrangian is

$$L(x, \lambda, \nu) = c^T x - \lambda^T x + \nu^T (Ax - b).$$

The Lagrange dual function is

$$g(\lambda, \nu) = \begin{cases} -b^T \nu, & A^T \nu - \lambda + c = 0 \\ -\infty, & \text{otherwise} \end{cases}.$$

Note 1: g is linear on an affine domain: $\{(\lambda, \nu) : A^T \nu - \lambda + c = 0\}$ and hence concave.

Note 2: The Lower Bound Property says that if $\lambda = A^T \nu + c \geq 0$, then $p^* \geq -b^T \nu$.

Lagrange Dual Problem

$$\begin{array}{ll} \text{maximize} & g(\lambda, \nu) \\ \text{subject to} & \lambda \geq 0 \end{array}$$

Standard form LP and its dual:

$$\begin{array}{ll} \text{(LP)} & \text{minimize} \quad c^T x \\ & \text{subject to} \quad Ax = b, \quad x \geq 0 \end{array}$$

$$\begin{array}{ll} \text{(Dual of LP)} & \text{maximize} \quad -b^T \nu \\ & \text{subject to} \quad A^T \nu + c \geq 0 \end{array}$$

2.2 Weak Dual and Strong Dual

Weak Duality: $d^* \leq p^*$.

String Duality: $d^* = p^*$.

Theorem 3 (Slater). *Consider an optimization problem*

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq 0 \quad i = 1, \dots, m \\ & && Ax = b \end{aligned}$$

where f_0, f_1, \dots, f_m are all convex functions. Then the strong duality holds if there exists a point x^* in $\text{ri}(\mathcal{D})$ where $\mathcal{D} := \text{dom}(f_0) \cap \bigcap_{i=1}^m \text{dom}(f_i)$ such that $f_i(x^*) < 0$ for $i = 1, \dots, m$ and $Ax^* = b$.

Theorem 4 (Complementary Slackness). *Consider an optimization problem and its dual:*

$$\begin{array}{ll} \text{(Primal)} & \begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq 0 \quad i = 1, \dots, m \\ & && h_i(x) = 0 \quad i = 1, \dots, p \end{aligned} \\ \text{(Dual)} & \begin{aligned} & \text{maximize} && g(\lambda, \nu) \\ & \text{subject to} && \lambda \geq 0 \end{aligned} \end{array}$$

Let x be a feasible solution to the primal and (λ, ν) be a feasible solution to the dual. Then x and (λ, ν) are both optimal if and only if

$$\lambda_i f_i(x) = 0$$

for each $i = 1, \dots, m$. i.e.,

$$\lambda_i > 0 \implies f_i(x) = 0, \text{ and } f_i(x) < 0 \implies \lambda_i = 0$$

for each $i = 1, \dots, m$.

2.3 Perturbation

Primal

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq 0, \quad i = 1, \dots, m \\ & && h_i(x) = 0, \quad i = 1, \dots, p \end{aligned}$$

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && f_i(x) \leq u_i \quad i = 1, \dots, m \\ & && h_i(x) = v_i \quad i = 1, \dots, p \end{aligned}$$