

Computer Vision

Jupyter Notebooks and Google Colab for Exercise 2

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Environment Setup

You have two choices to complete our exercises:

1. Setup jupyter notebook locally on your machine
2. Use google colab in your browser

1. Local Environment Setup

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- ▶ Follow the instructions for your OS to install the Python package manager `conda`:
`https://docs.conda.io/projects/conda/en/latest/user-guide/install/`
- ▶ Download the archive for exercise 1 and open a terminal in the `code` directory
- ▶ Create the new environment `lecturecv` with required packages (numpy, etc.):
`conda env create -f environment.yml`
- ▶ Before launching your notebook you need to activate the environment:
`conda activate lecturecv-ex02`
- ▶ Run this command from the directory where the jupyter notebooks are located:
`jupyter-notebook`

1. Local Environment Setup

You can then navigate to the respective notebook and edit it in the browser

Computer Vision Lecture - Exercise 1 - Image Formation

In this exercise, you will gain hands-on experience regarding the image formation process and geometric transformations. More specifically, we will develop our own simple renderer and play around with focal lengths, BRDF-based shading, rotations, translations, and much more! In the second part of the notebook, we will have a look at homographies and how they can be used to stitch together images to form panoramas.

This notebook guides you through the relevant steps. When you see helper functions, you don't need to do anything - they are already implemented. The functions you need to implement are indicated as Exercise Function. Sometimes, you can find Hints - these are written upside-down so you can first try to find the solution without reading them.

Good luck and let's have fun!

Preliminaries

Let's first import relevant libraries and define hyperparameters. For the latter, we set the image height H and width W to 128 pixels.

```
In [ ]: import numpy as np
import itertools
import matplotlib
import matplotlib.pyplot as plt
from scipy.spatial.transform import Rotation as R
from IPython.display import HTML
from matplotlib import animation
from matplotlib.patches import Polygon
import cv2

# Let's first define hyperparameters. In our case, we set the image height  $H$  and width  $W$  to 128 pixels.
H, W = 128, 128
```

We need an object in our scene in order to render more than an empty image! For this, we define a helper function which returns the faces (and optionally the face normals) of a cube.

```
In [ ]: #####
##### Helper Function #####
#####
def get_cube(center=(0, 0, 2), rotation_angles=[0., 0., 0.], with_normals=False, scale=1.):
    """Returns an array containing the faces of a cube.

    Args:
        center (tuple): center of the cube
        rotation_angles (tuple): Euler angles describing the rotation of the cube
        with_normals (bool): whether to return the normal vectors of the faces
        scale (float): scale of cube

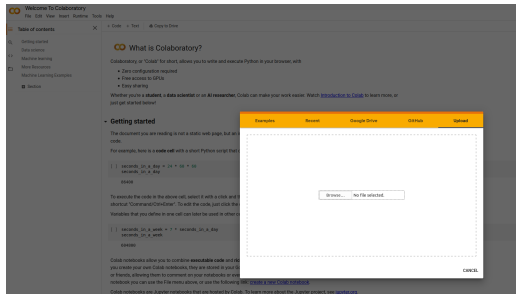
    """
    # A cube consists of 6 faces and 8 corners:
    #
    #   +-----+
    #   |         |
    #   |         |
    #   |         |
    #   |         |
    #   |         |
    #   |         |
    #   +-----+
    #
    # Let's first consider the unit cube. The corners are:
```

2. Online Environment Setup: Google Colab

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Alternatively, you can use Google Colab online

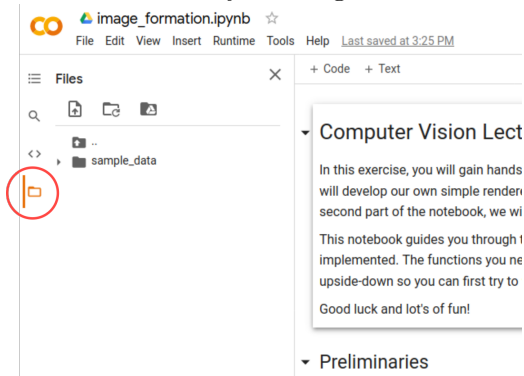
- ▶ Create a free Google account at: <https://google.com>
- ▶ Navigate to <https://colab.research.google.com/> in your browser
- ▶ Click on File → Upload notebook and upload the respective notebook



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- ▶ Click on File → Upload notebook and upload the respective notebook
- ▶ You can also upload additional files by clicking on the folder symbol on the left:



Coding Exercises - Structure-From-Motion

3. Setup for the Structure-From-Motion Exercise

Running the structure-from-motion notebook in Colab requires some setup

- ▶ Colab comes with an old version of `opencv-python` that does not have SIFT
- ▶ We can install newer version directly from the notebook running in colab
- ▶ Additionally we need to install `ipympl`
- ▶ To do that, simply uncomment the first lines of the notebook

```
[ ] !pip install opencv-python==4.5.1.48
    !pip install ipympl

import cv2
import json

import numpy as np
import matplotlib.pyplot as plt
```

3. Setup for the Structure-From-Motion Exercise

Besides the dependencies we also need a few files...

- ▶ `code/sfm/img1.png`
- ▶ `code/sfm/img2.png`
- ▶ `code/sfm/cameras.npz`

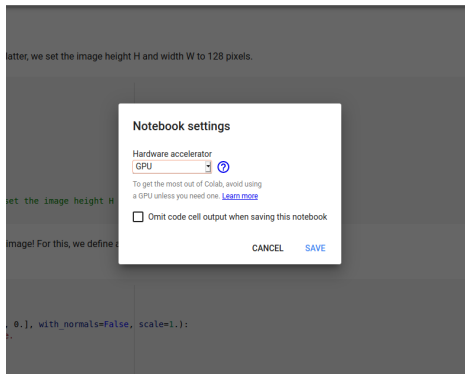
You can simply upload these from the colab environment (see prev. slides)

Coding Exercises - Stereo

3. Setup for the Stereo Exercise

If you don't have a GPU, we recommend running this notebook in Colab

- Click on Runtime → Change runtime type and select “GPU” and click “Save”:



3. Setup for the Structure-From-Motion Exercise

For this we need a few files aswell:

- ▶ `code/stereo/stereo_batch_provider.py`
- ▶ `code/stereo/KITTI_2015_subset`

You can simply upload these from the colab environment (see prev. slides)

3. Setup for the Structure-From-Motion Exercise

Can't upload folders - but there is a workaround

- ▶ Create a .zip archive of `code/stereo/KITTI_2015_subset`
- ▶ Upload the .zip (might take a bit)
- ▶ Uncomment the first line of the notebook to unzip the archive

```
[ ] !unzip KITTI_2015_subset.zip  
  
import os  
import sys  
import argparse  
import torch
```

Questions?