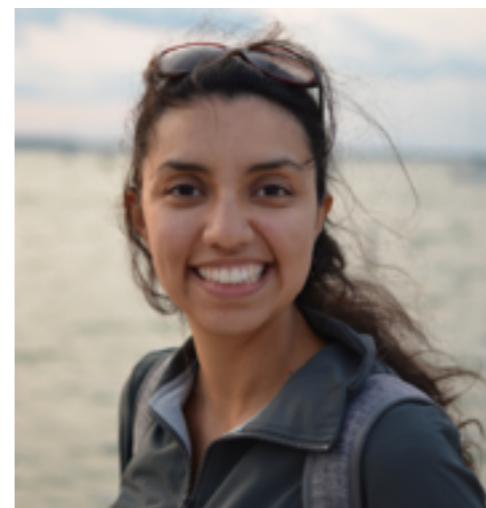


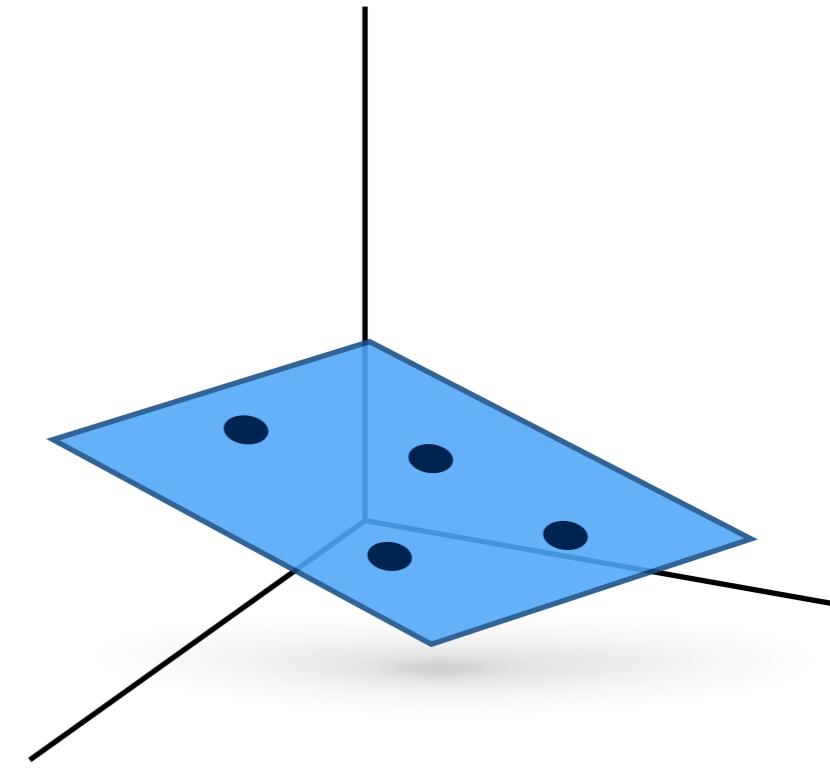
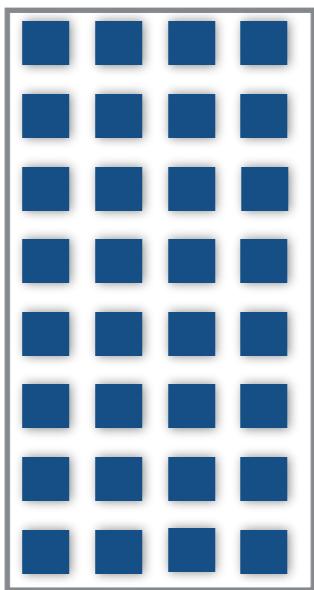
# Adversarial Principal Component Analysis

*Daniel Pimentel-Alarcón,  
Ari Biswas,                    Claudia Solís-Lemus*



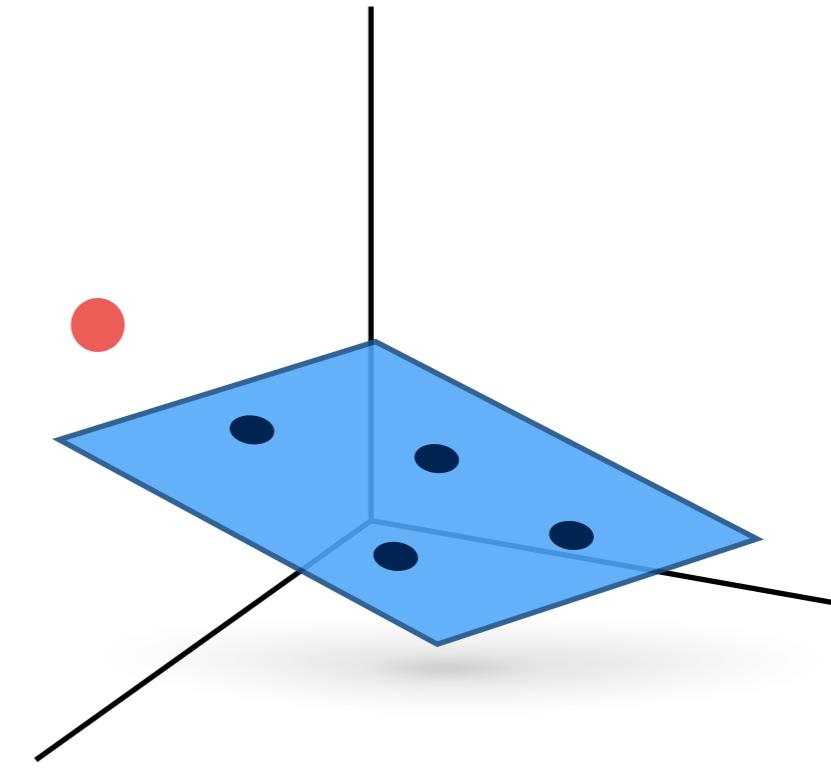
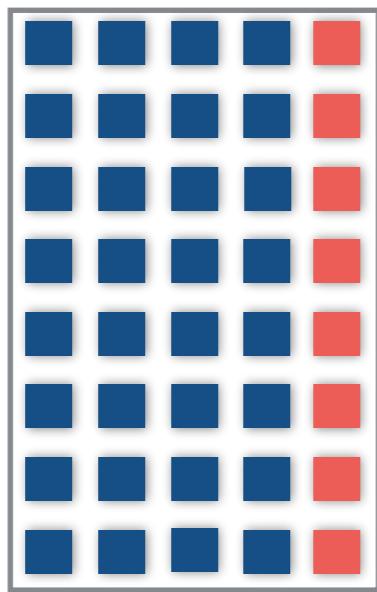
Wisconsin Institute for Discovery  
UNIVERSITY *of* WISCONSIN-MADISON

ISIT 2017



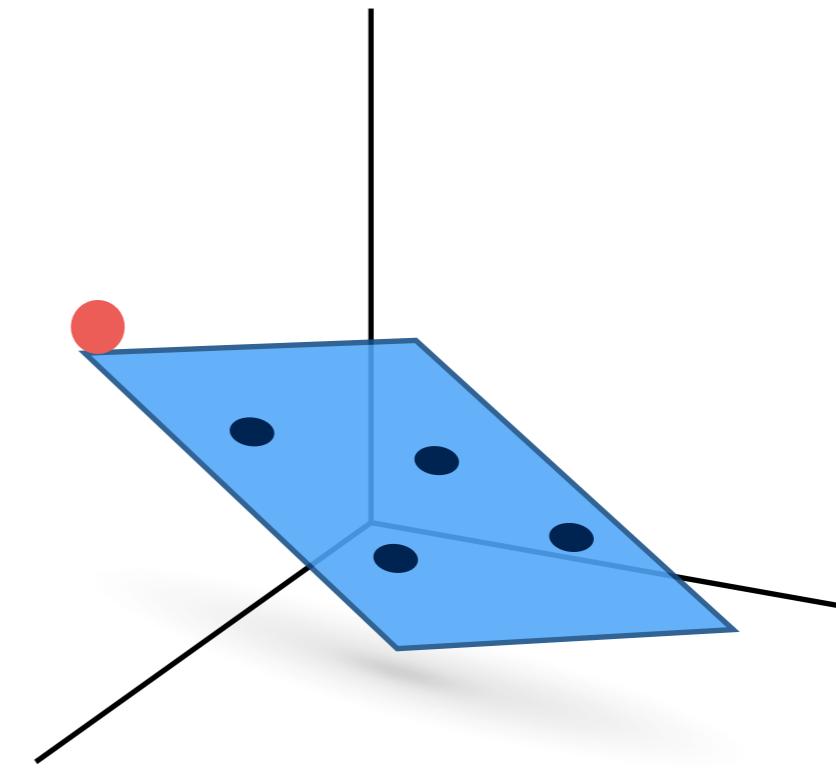
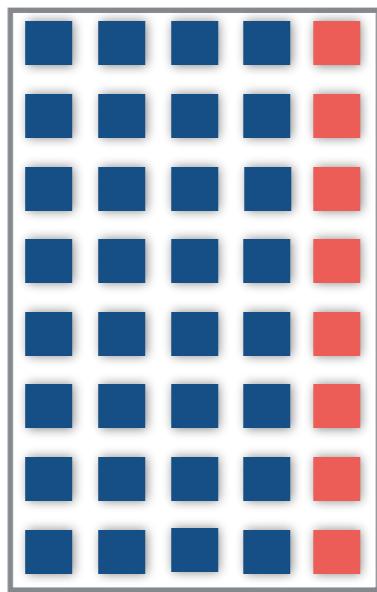
# PCA

Finds a subspace that explains data



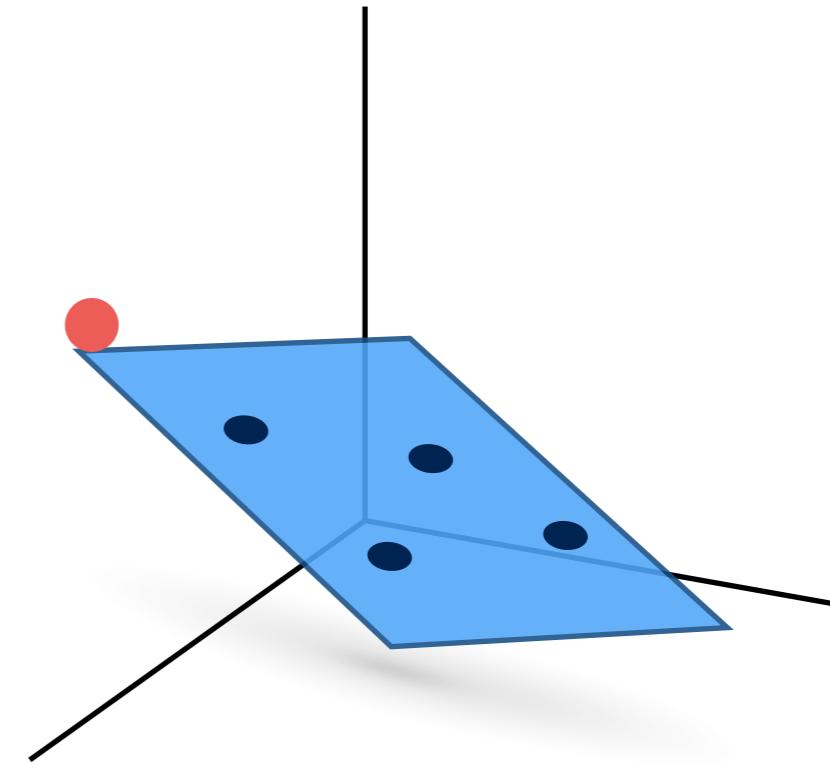
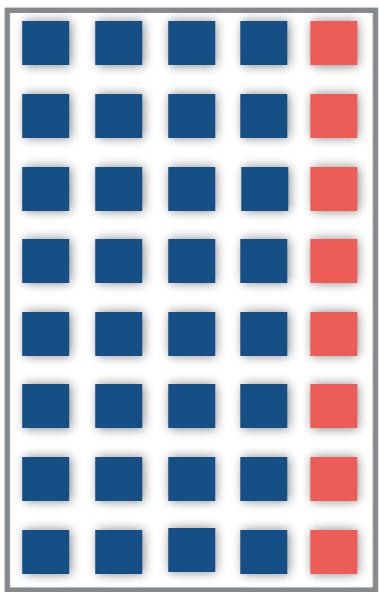
# PCA

An outlier would *tilt* the subspace.



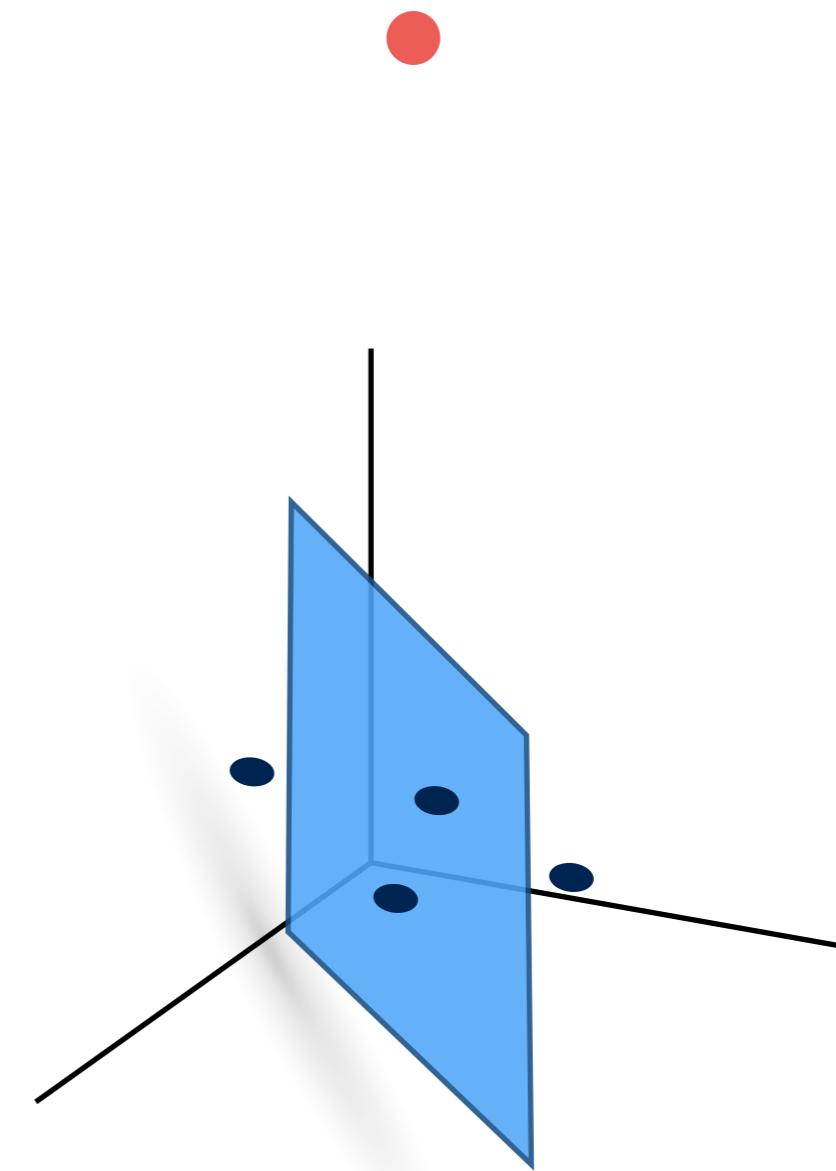
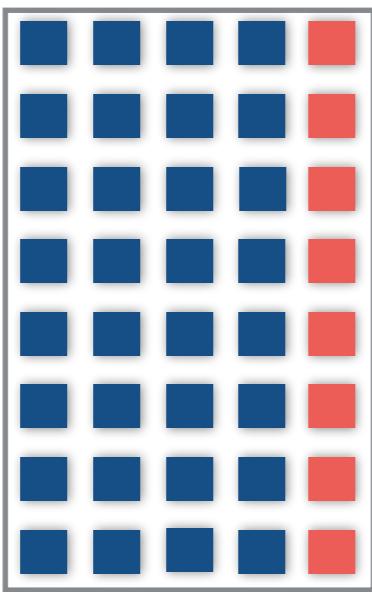
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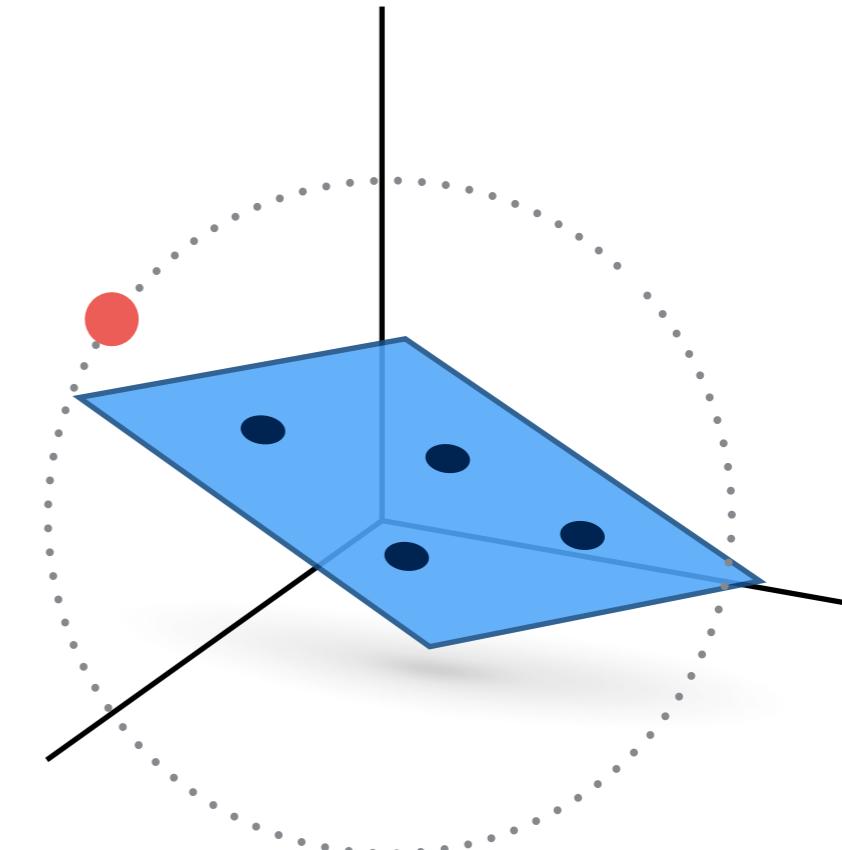
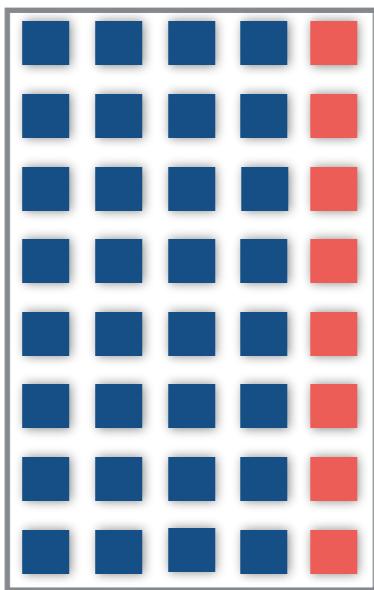
# Adversarial PCA

Where should we put ● so that  
◆ is tilted as much as possible?



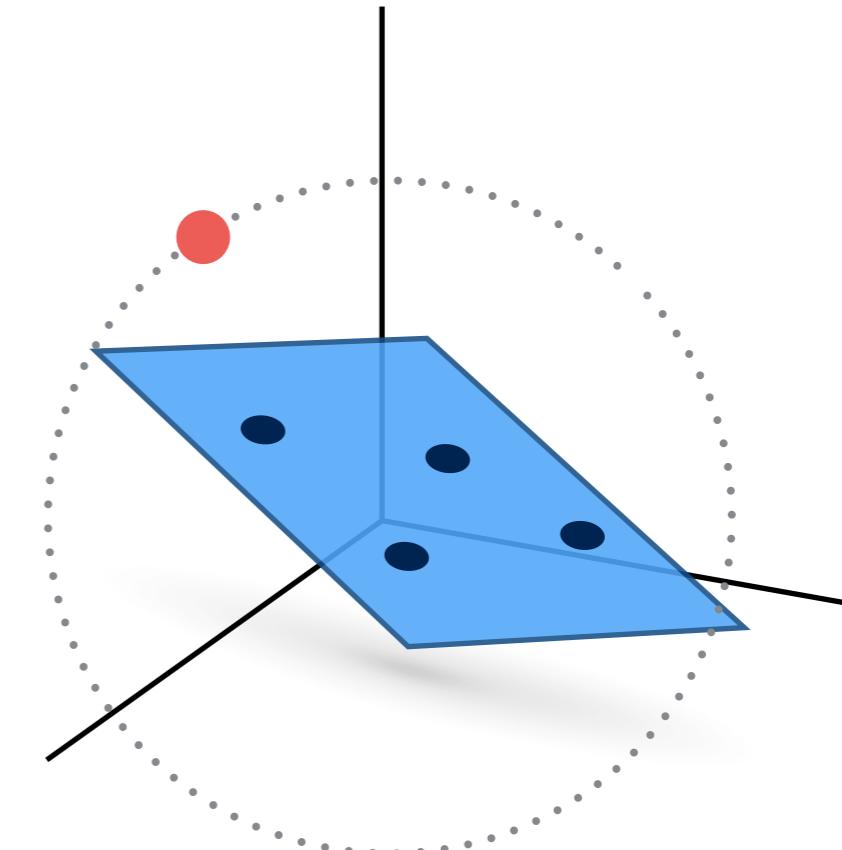
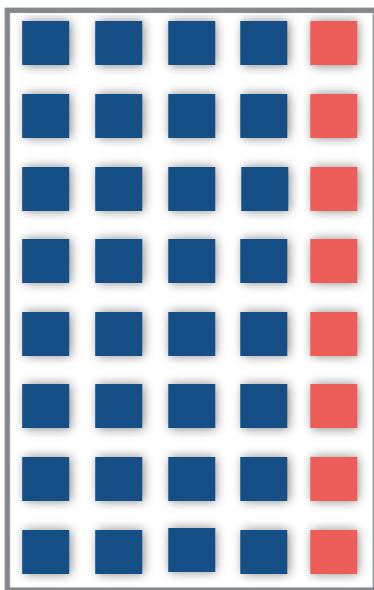
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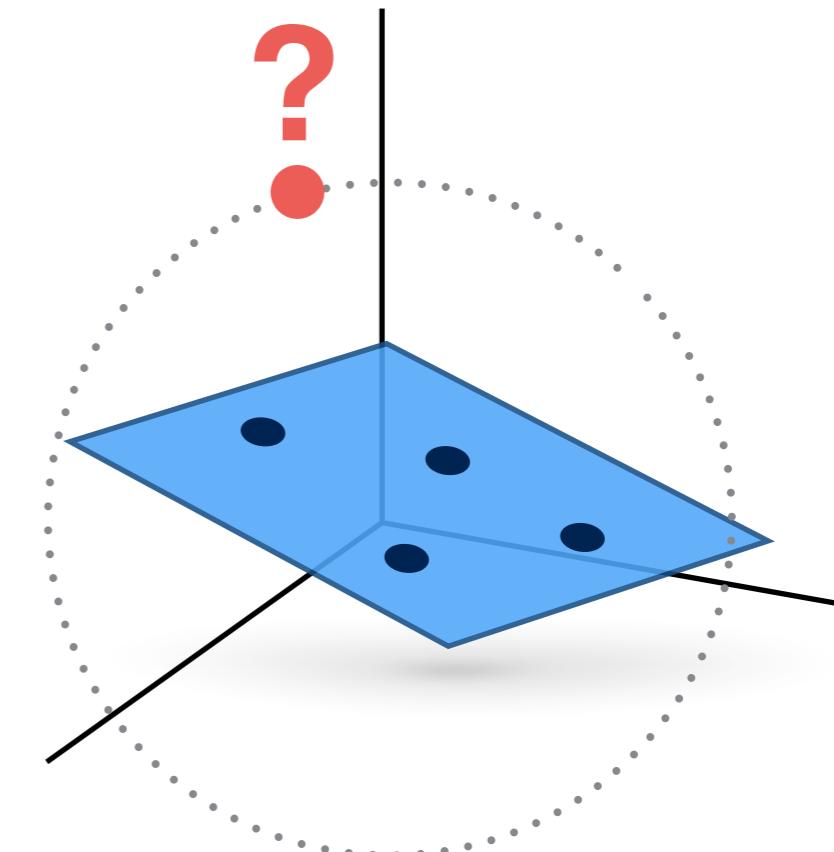
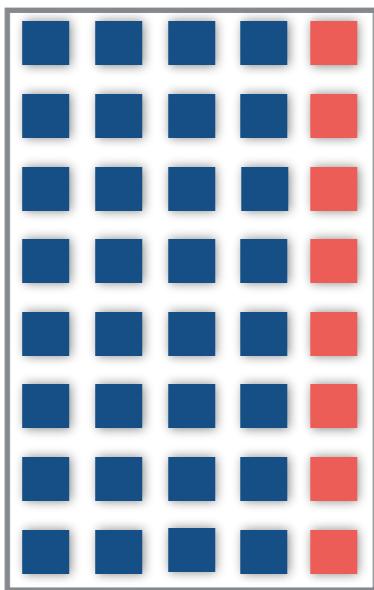
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# Adversarial PCA

Where should we put ● so that  
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# Adversarial PCA

Where should we put ● so that  
◆ is tilted as much as possible?

Isn't that  
already  
known?!



Rob Nowak



Rob Nowak



Rob Nowak



Laura Balzano

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Steve Wright

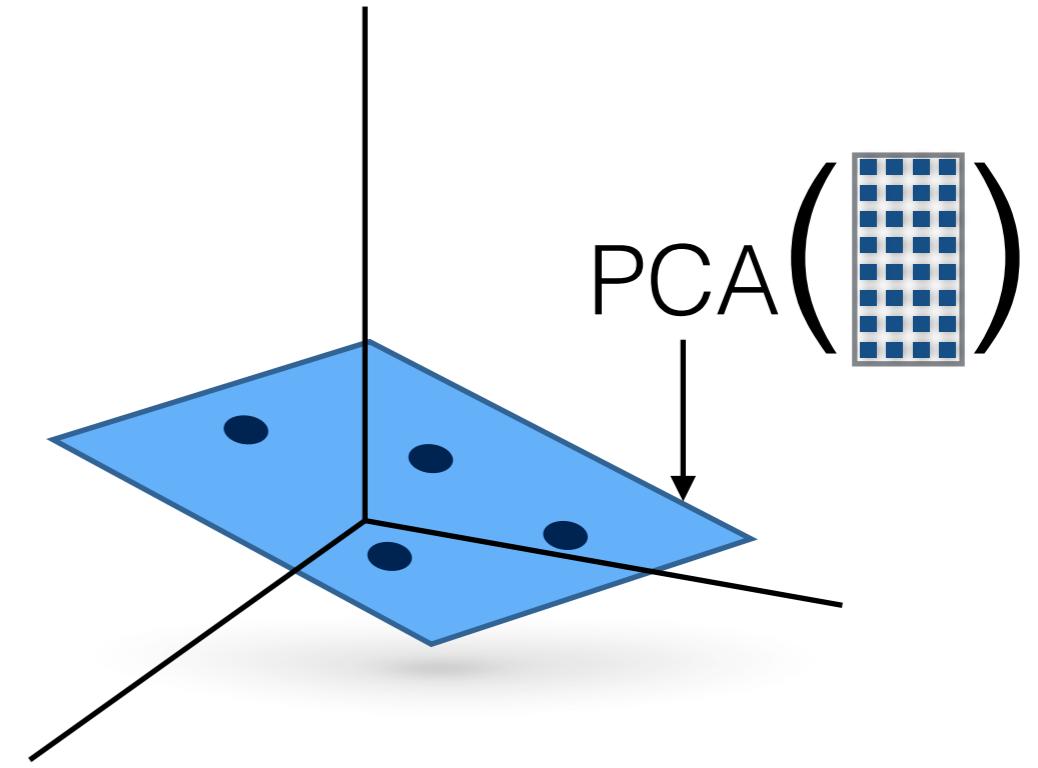
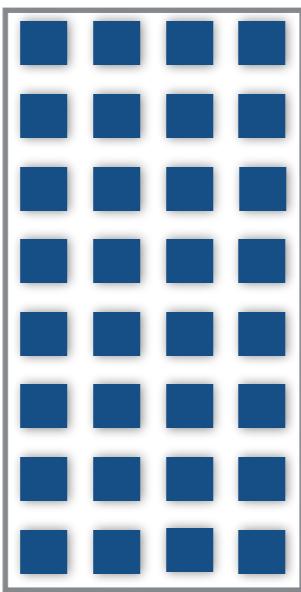
Isn't that  
already  
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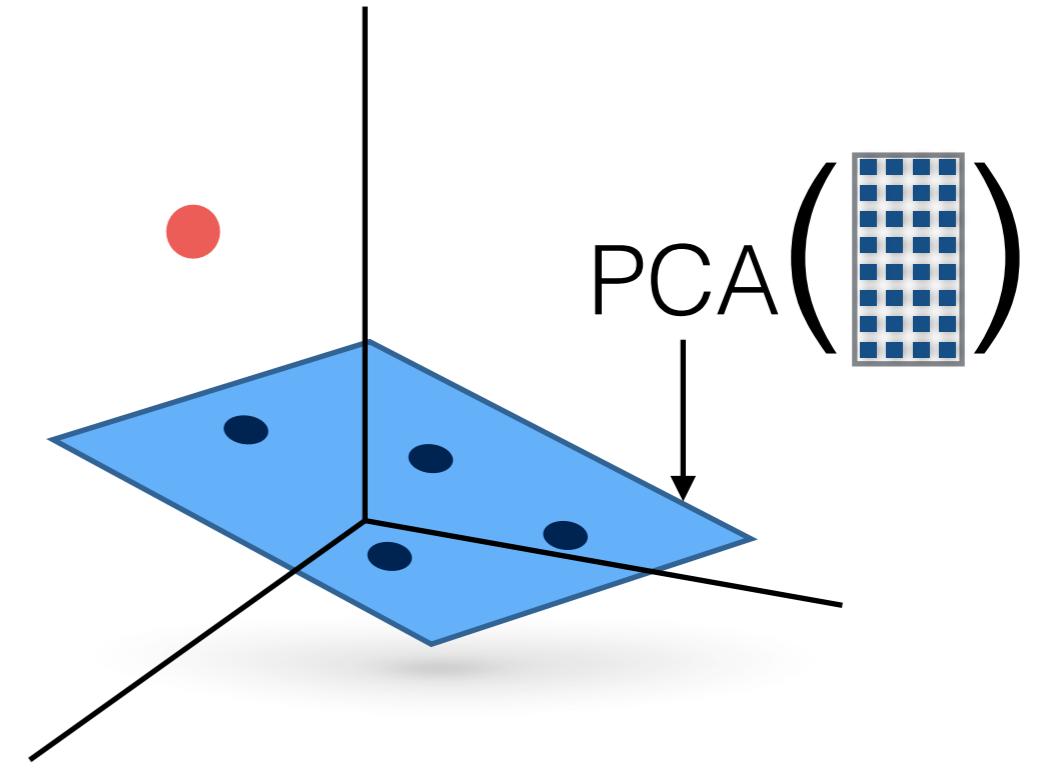
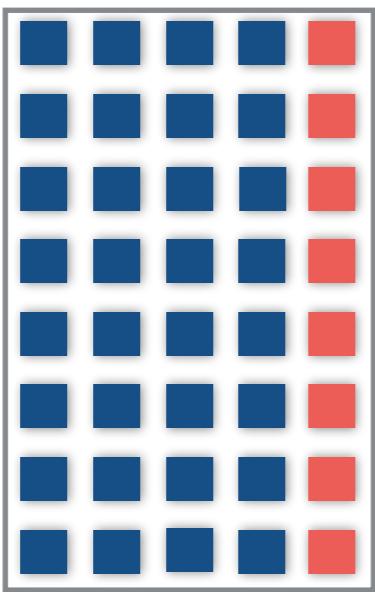
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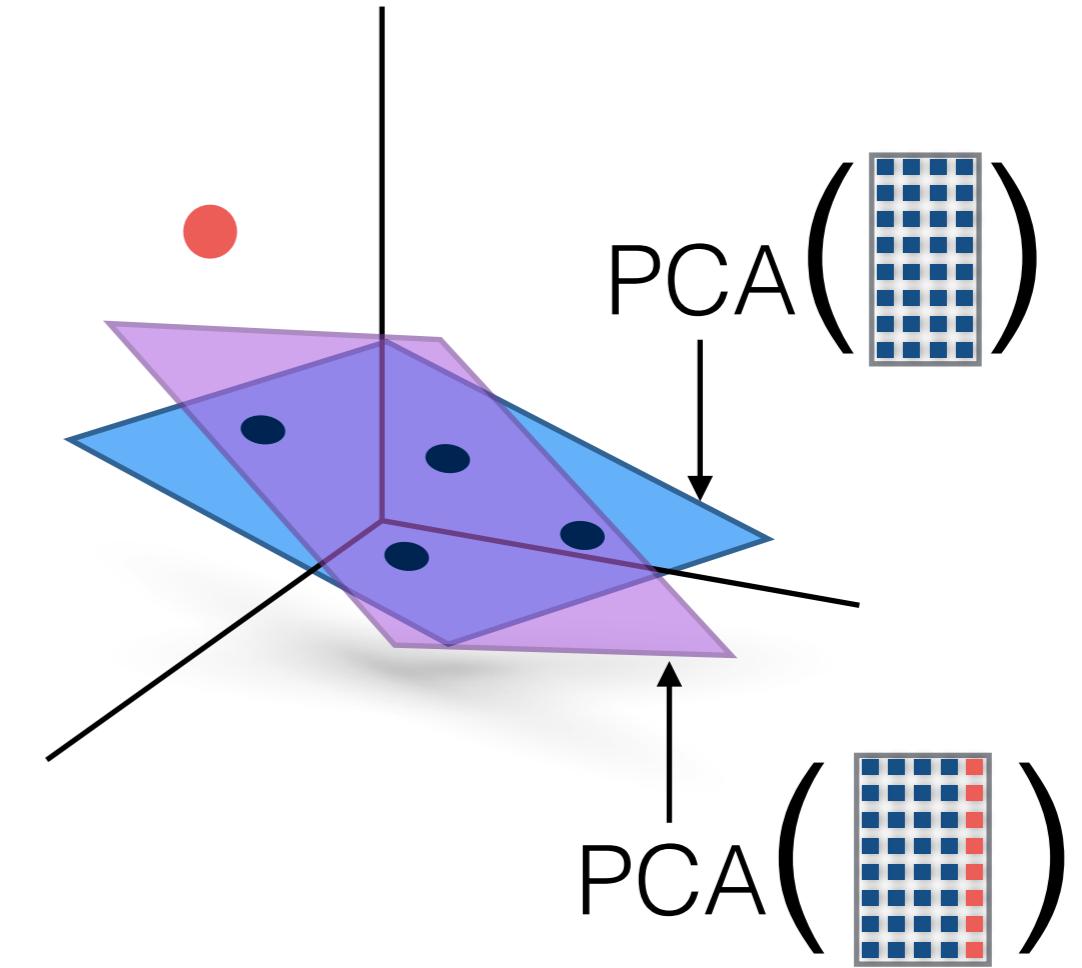
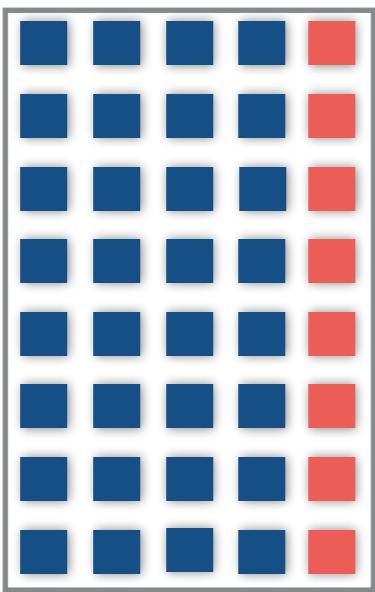
# Rank-One Updates

Given a new point  $\bullet$ , how do we compute new PCA efficiently?



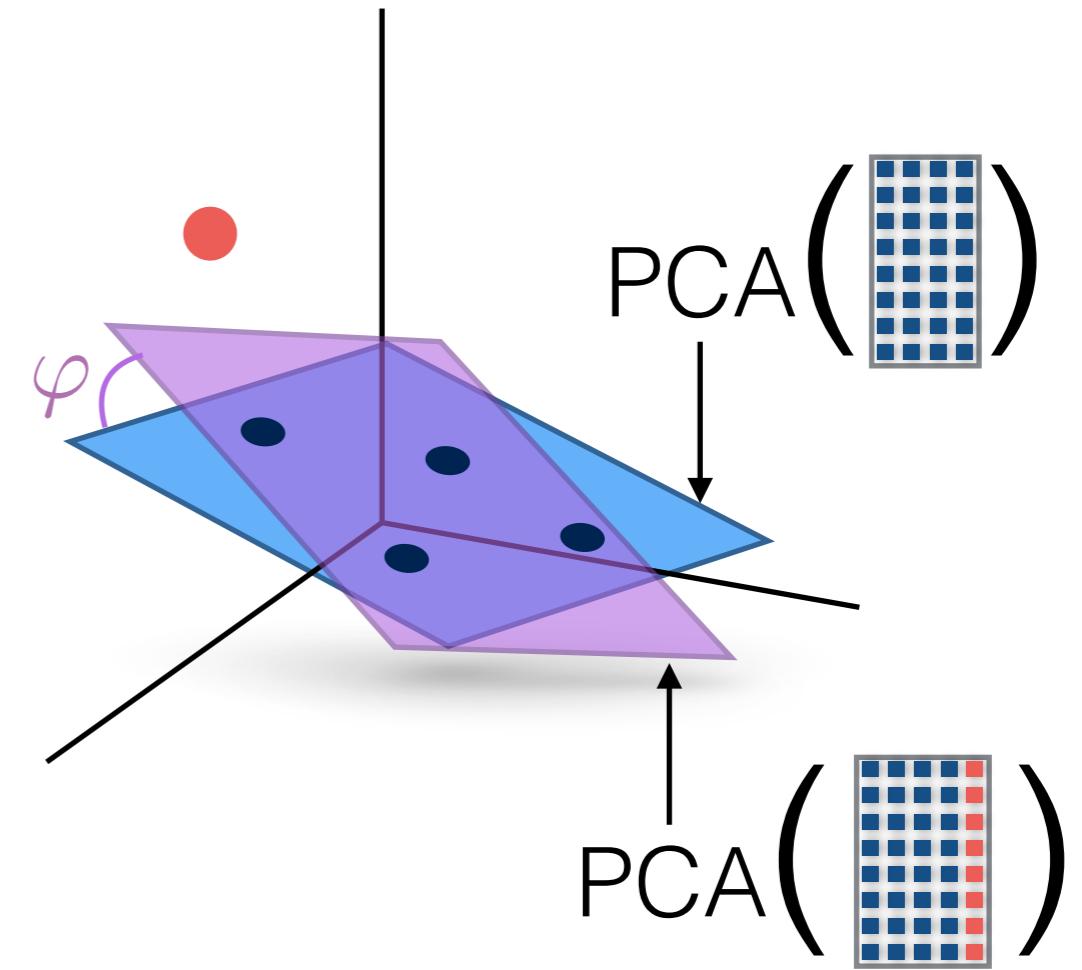
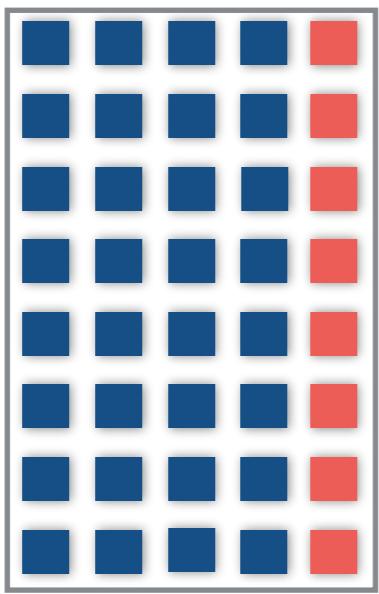
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Given a new point ●, how do we compute new PCA efficiently?



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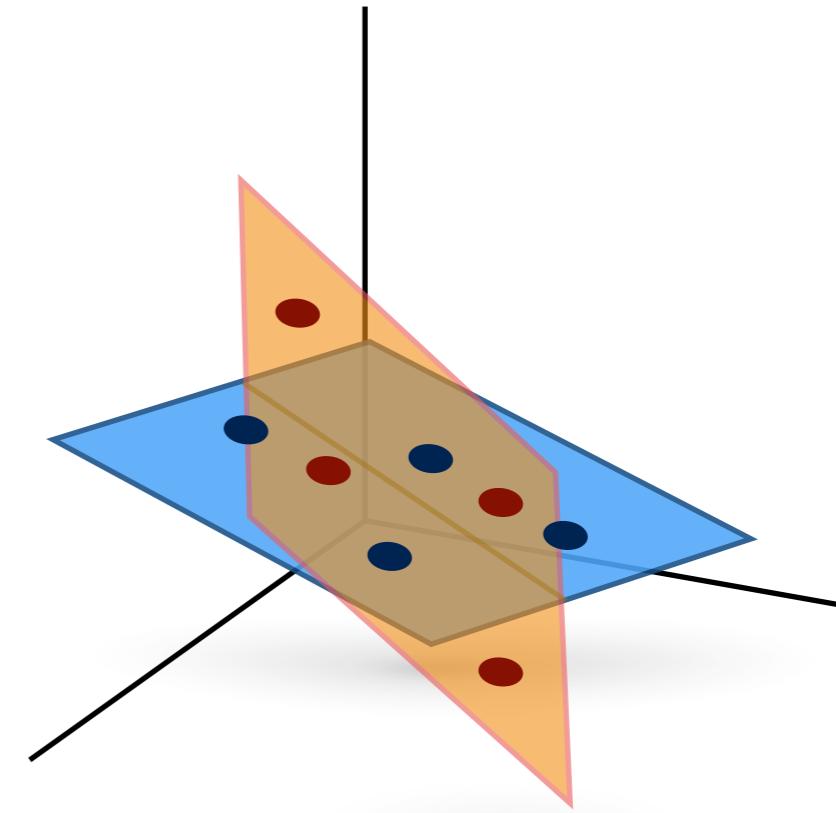
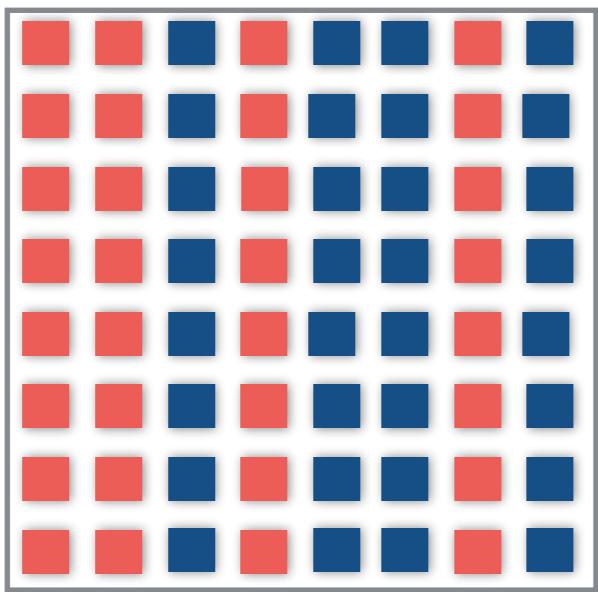


# Adversarial PCA

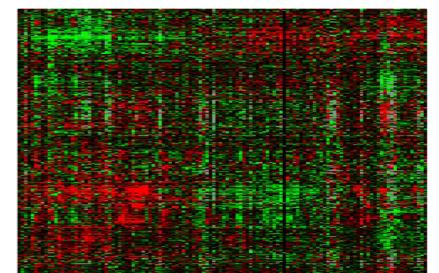
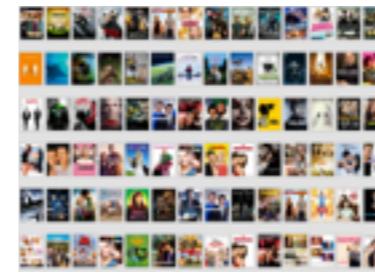
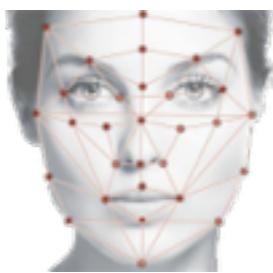
Where should we put ● to maximize  $\varphi$ ?

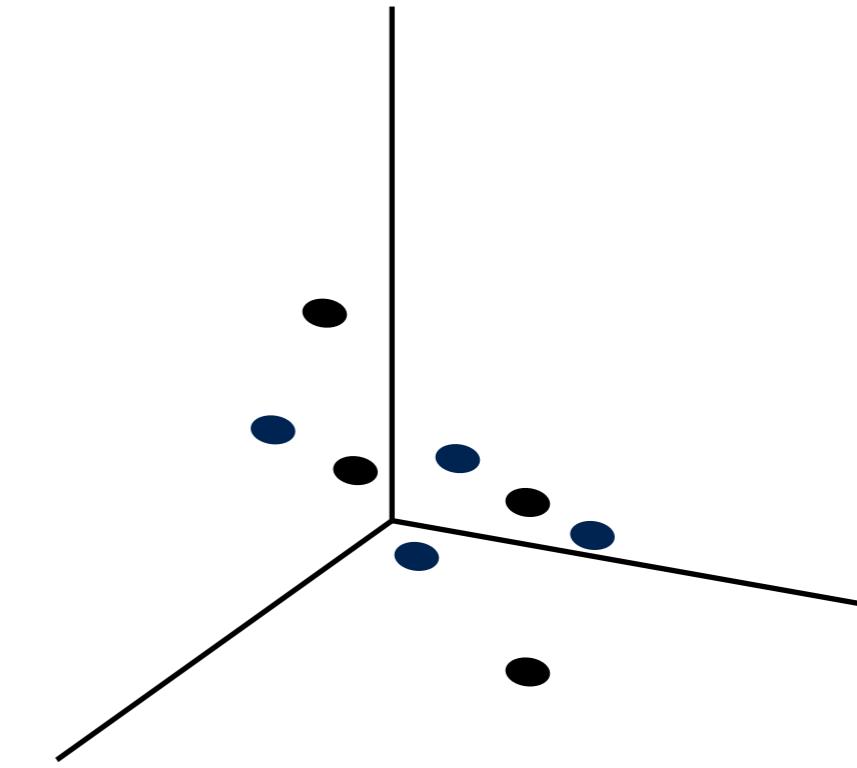
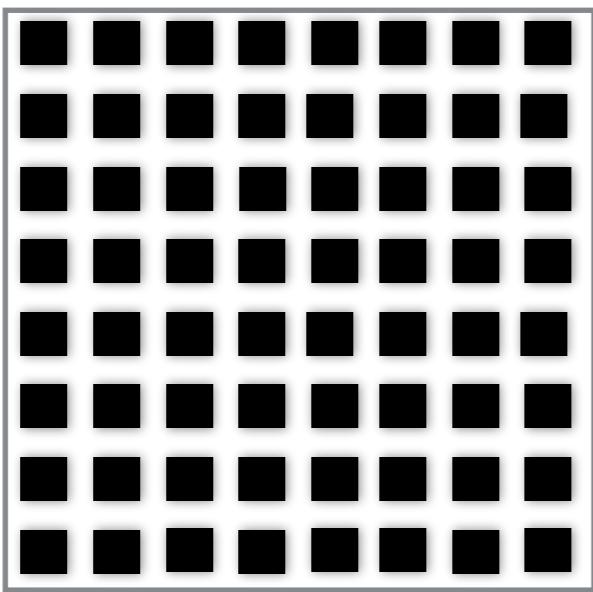
Why do  
you want  
to know?



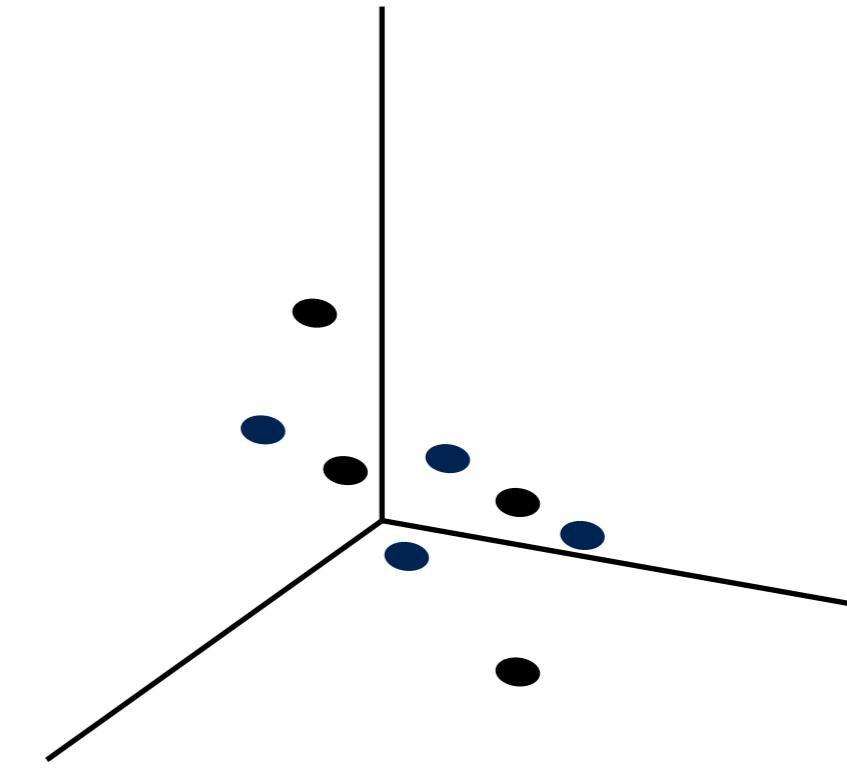
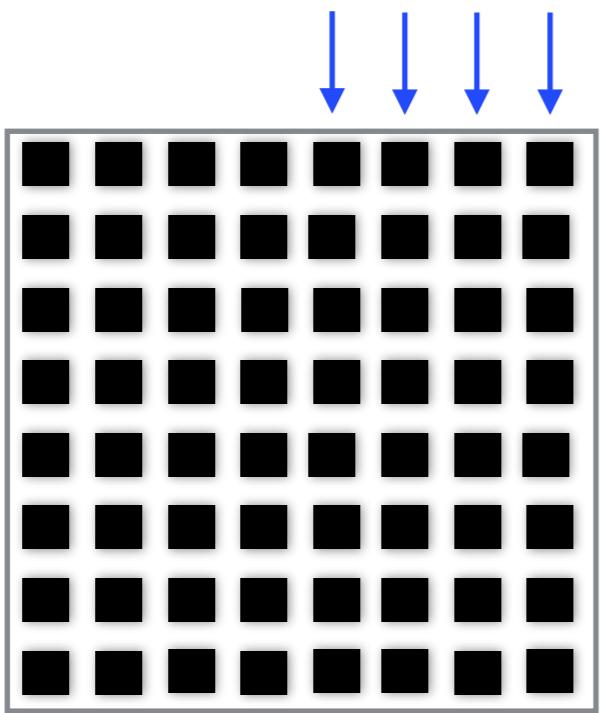


# Subspace Clustering

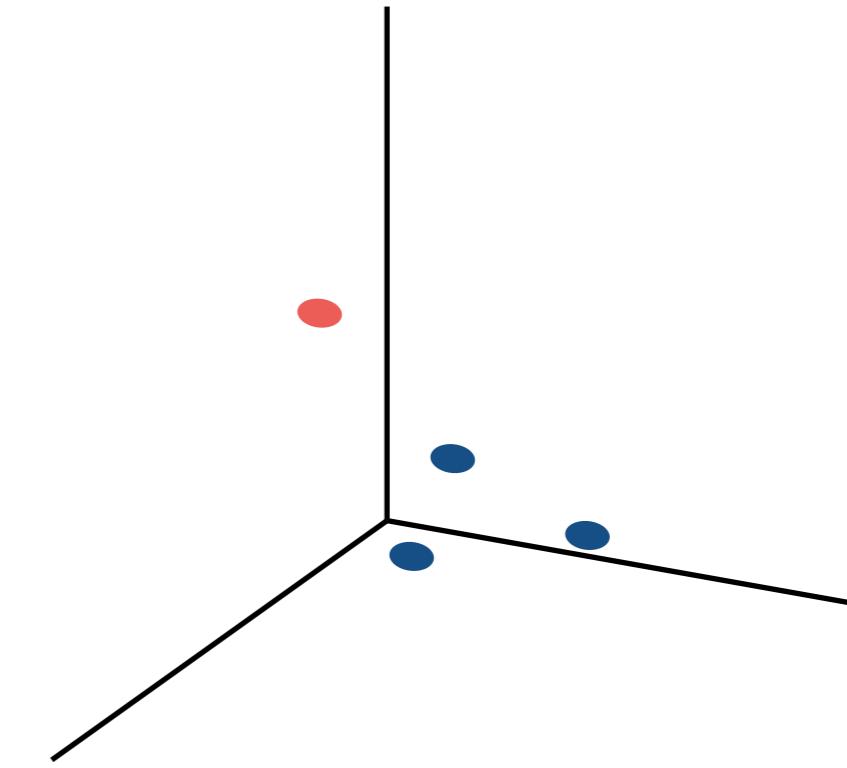
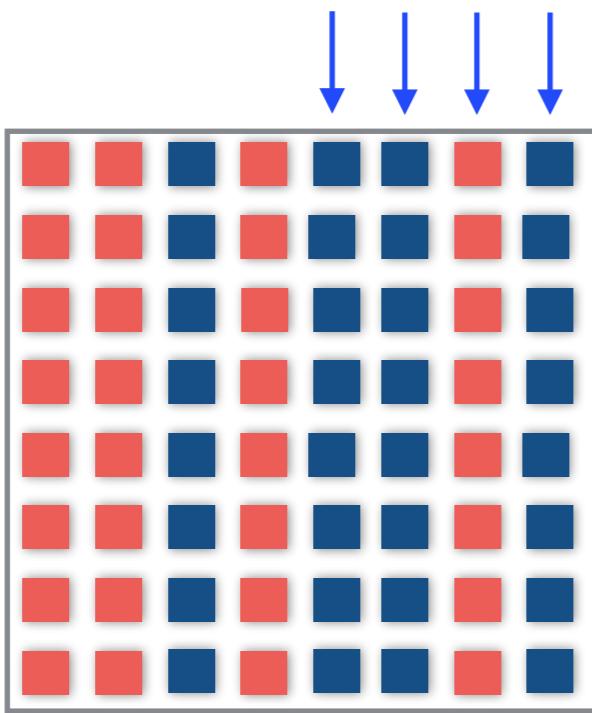




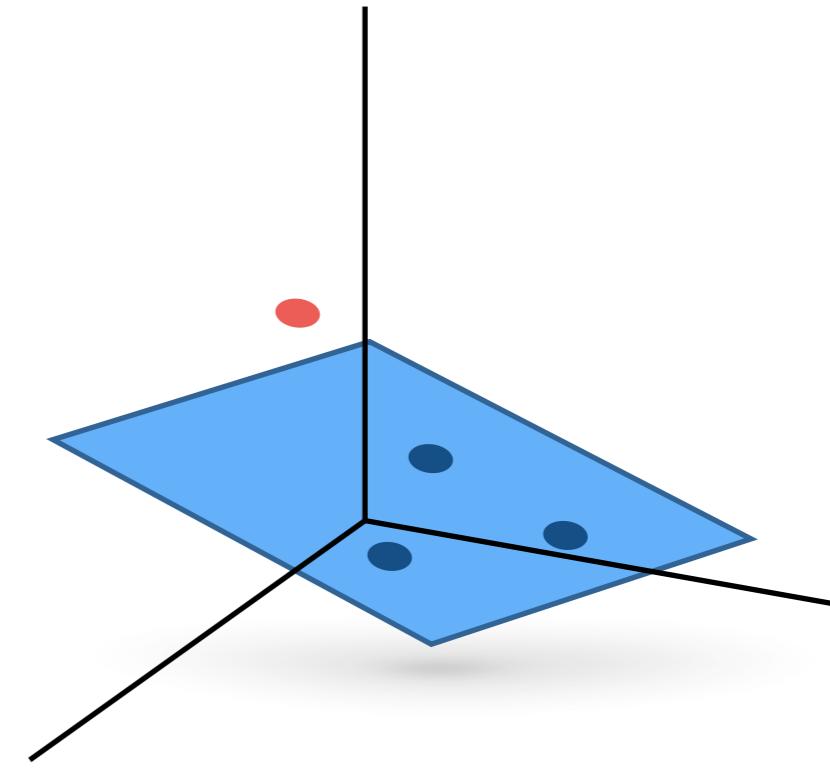
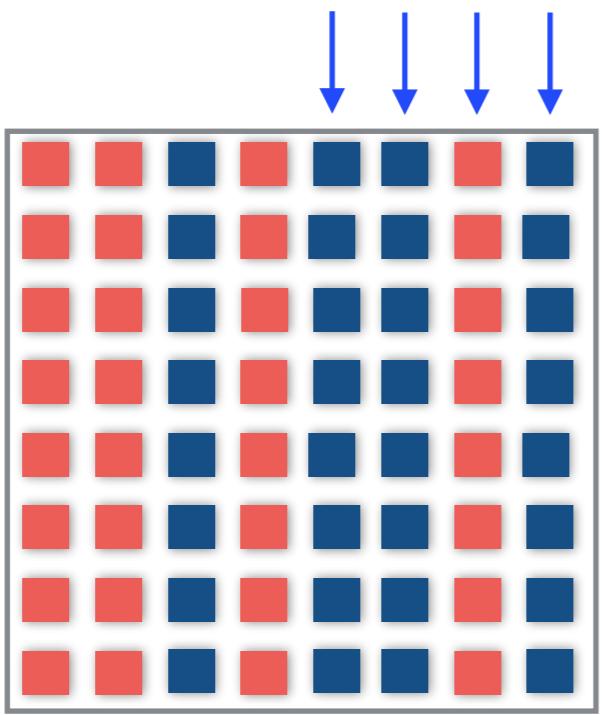
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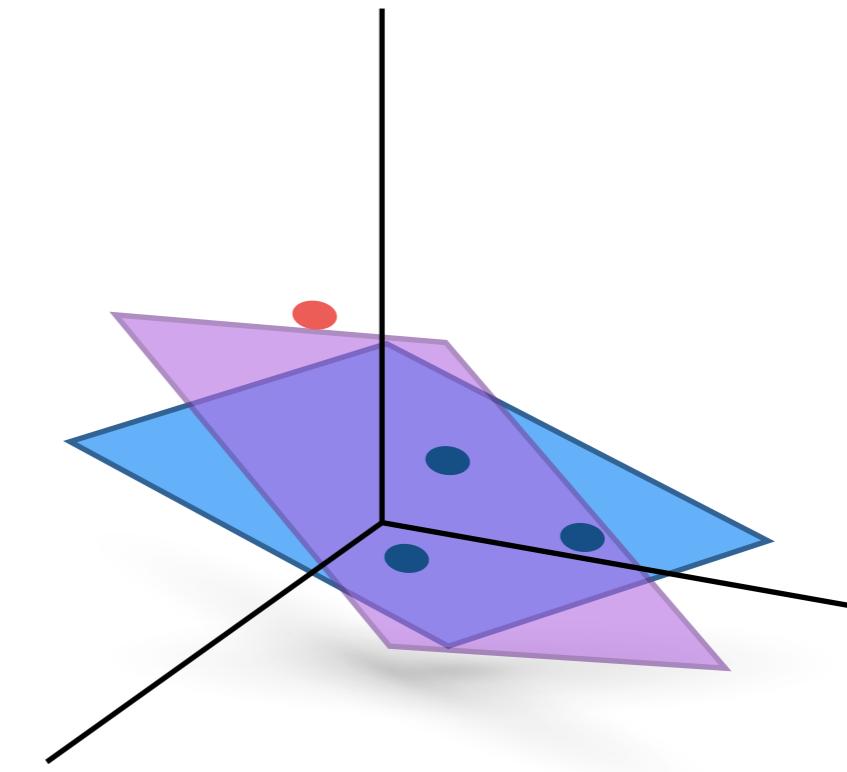
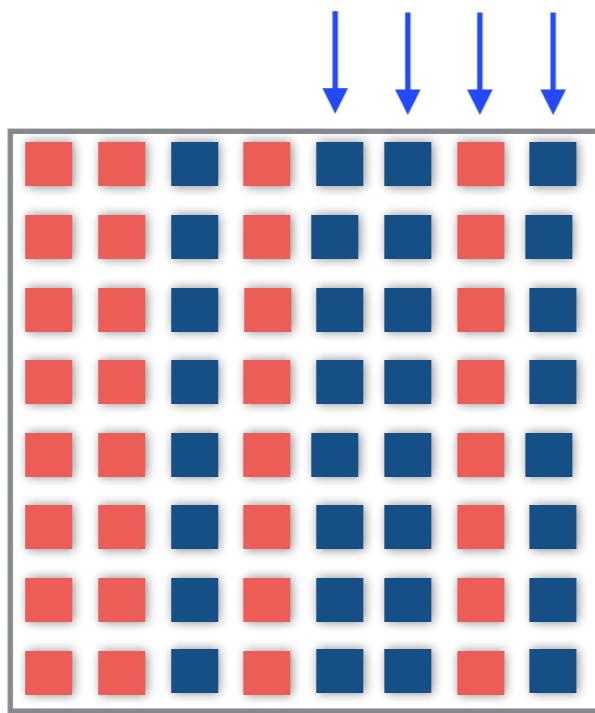
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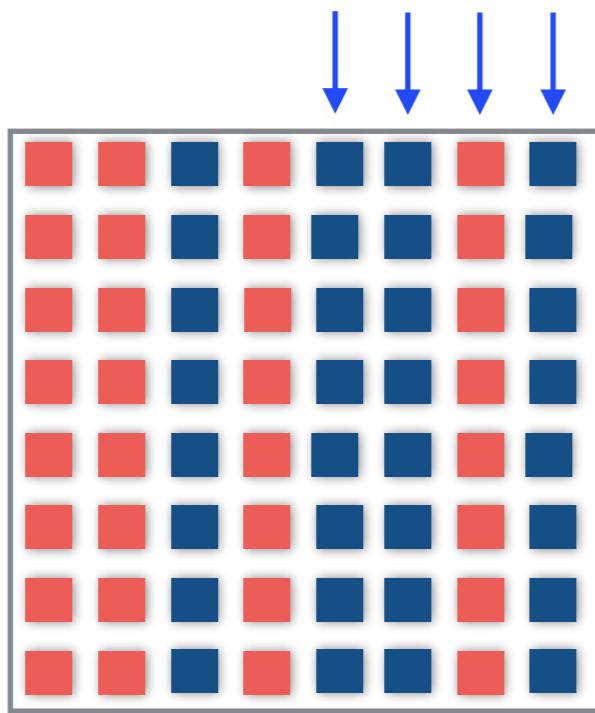
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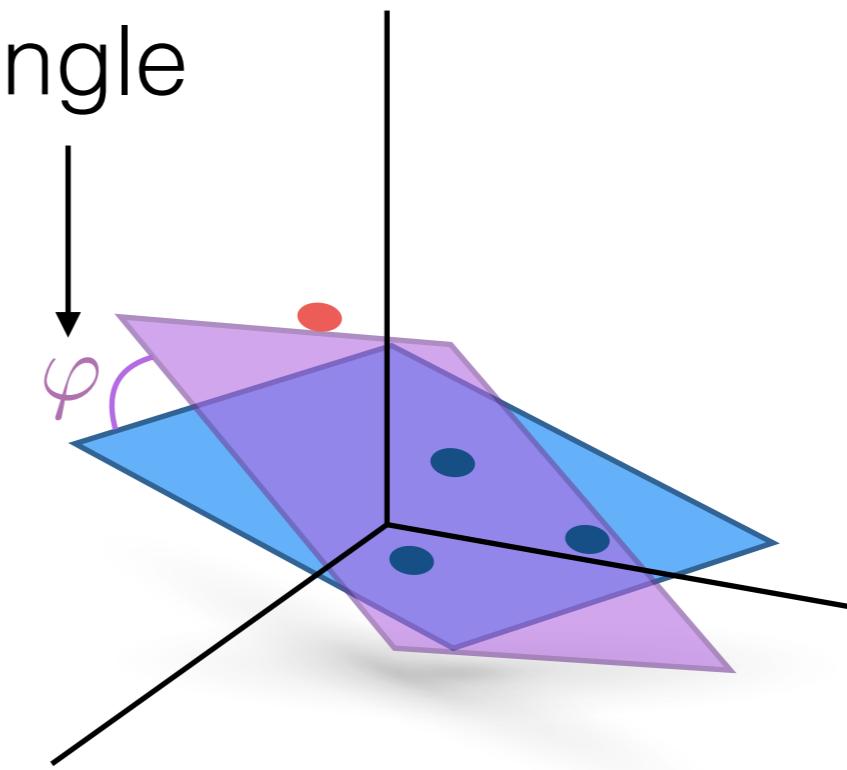
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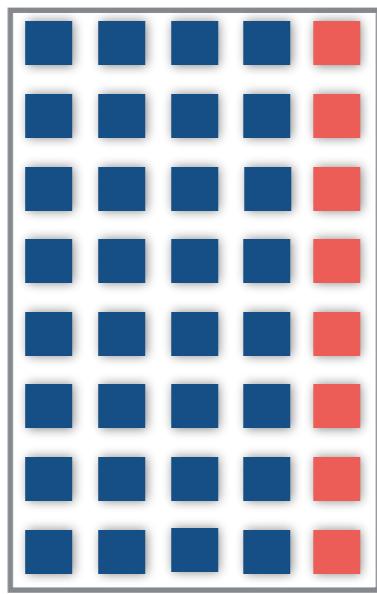


Principal  
angle

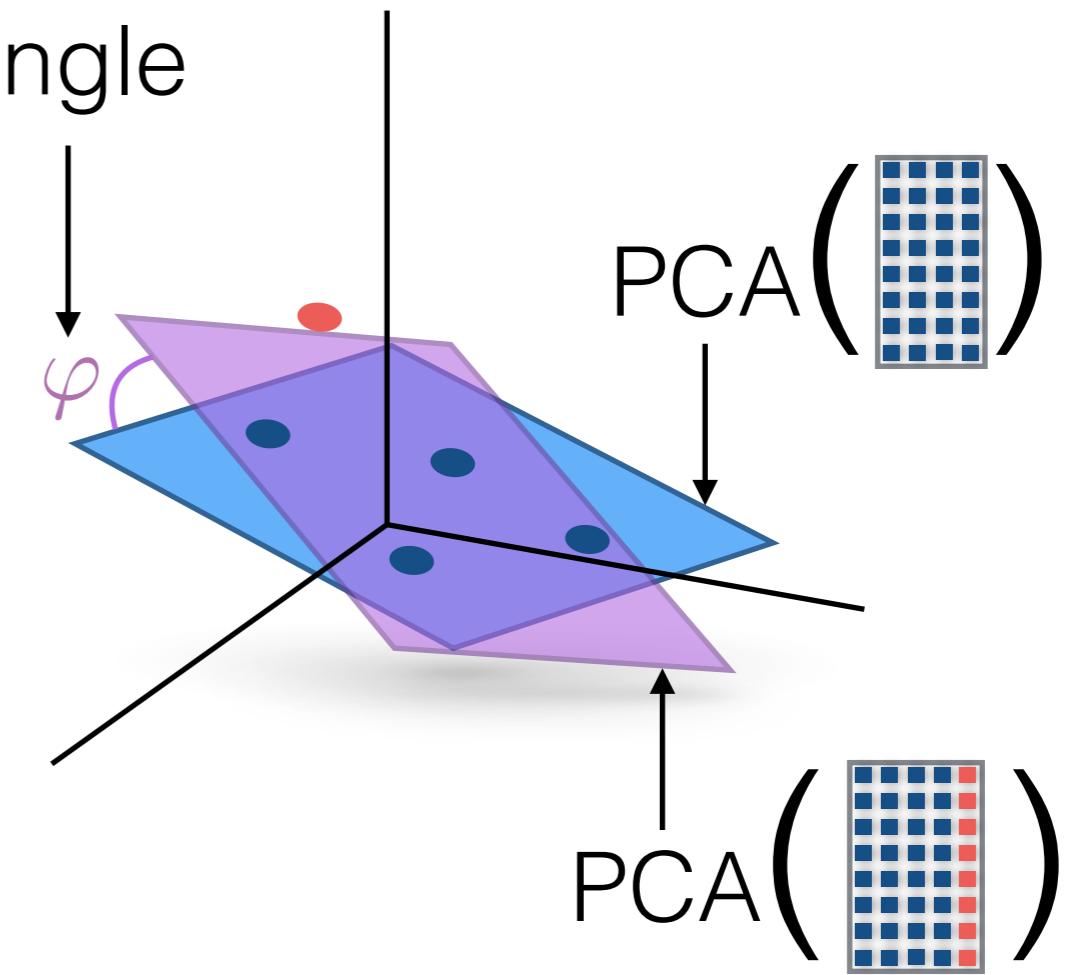


# Subspace Clustering

We want to bound the *error*  $\varphi$



Principal  
angle

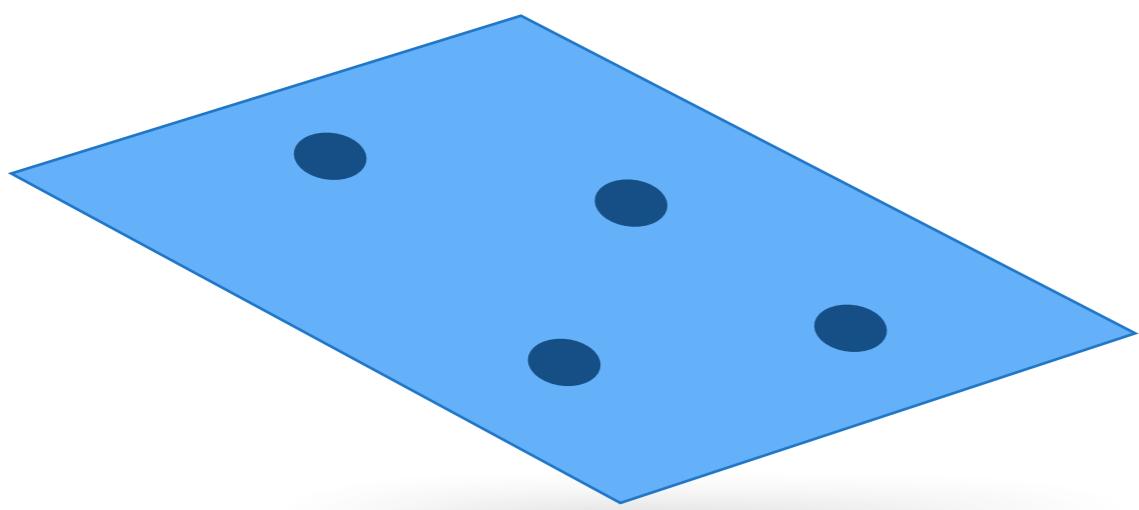


# Adversarial PCA

Where should we put ● to maximize  $\varphi$ ?

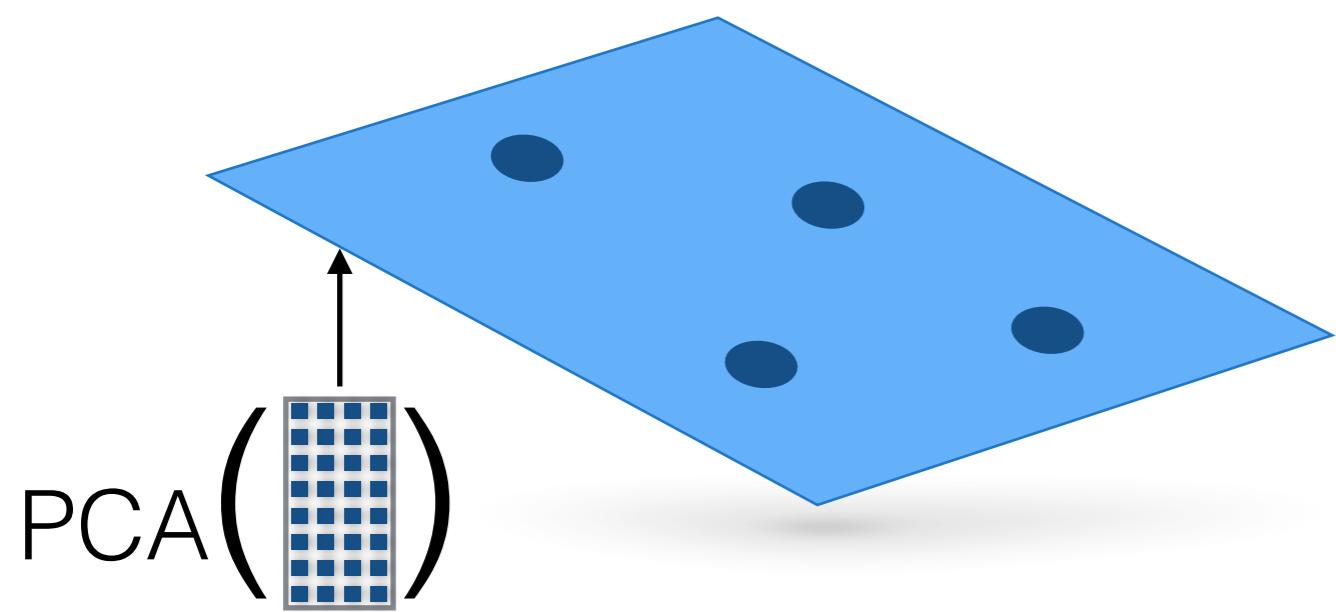
# Our Main Theorem

Closed form solution



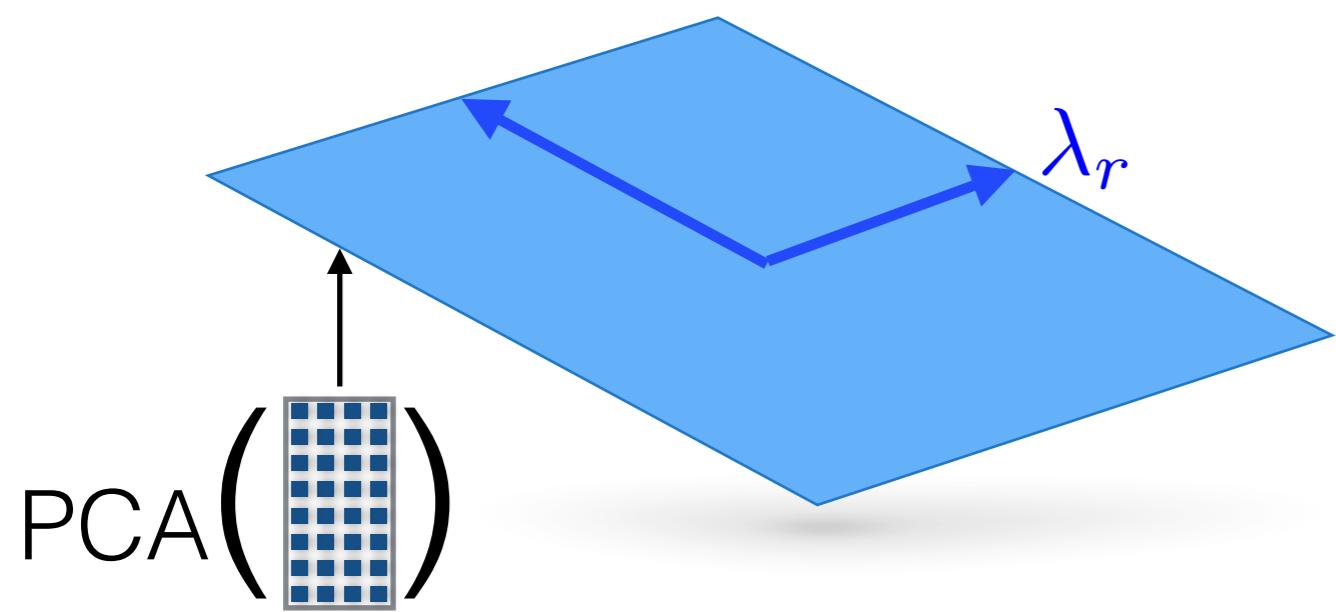
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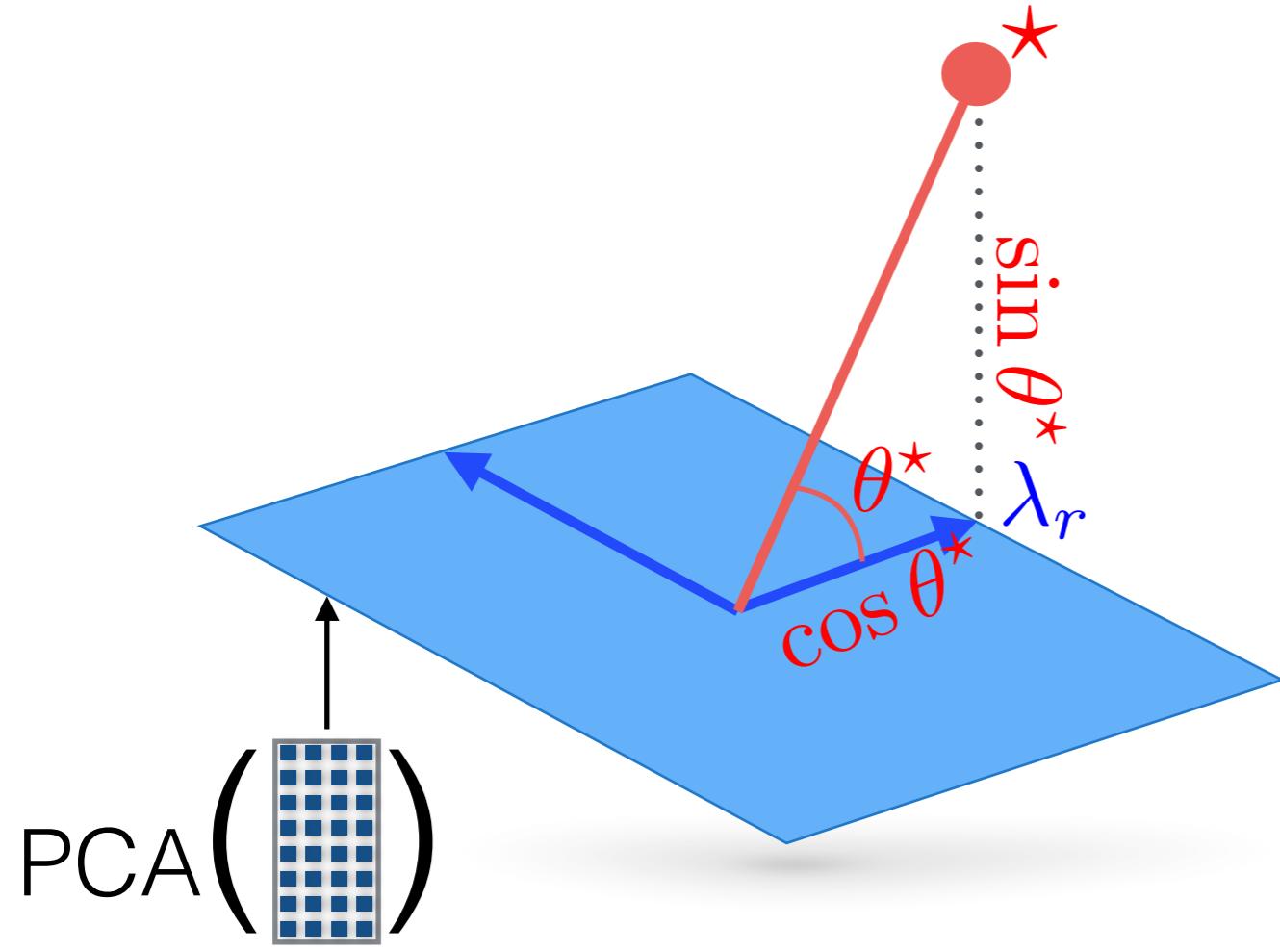
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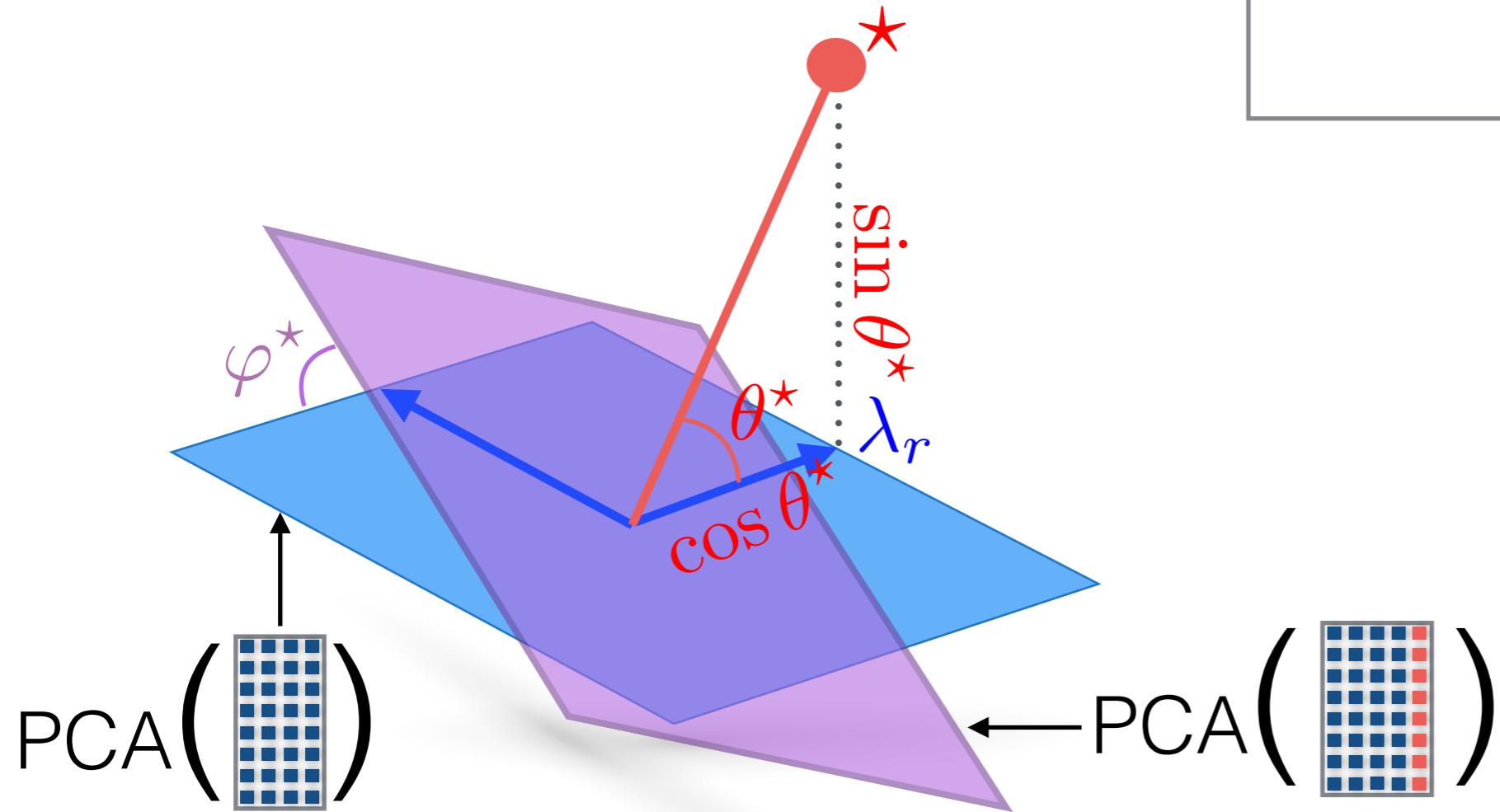


$$\theta^* = \frac{1}{2} \arccos \left( -\frac{1}{\lambda_r^2} \right)$$

# Our Main Theorem

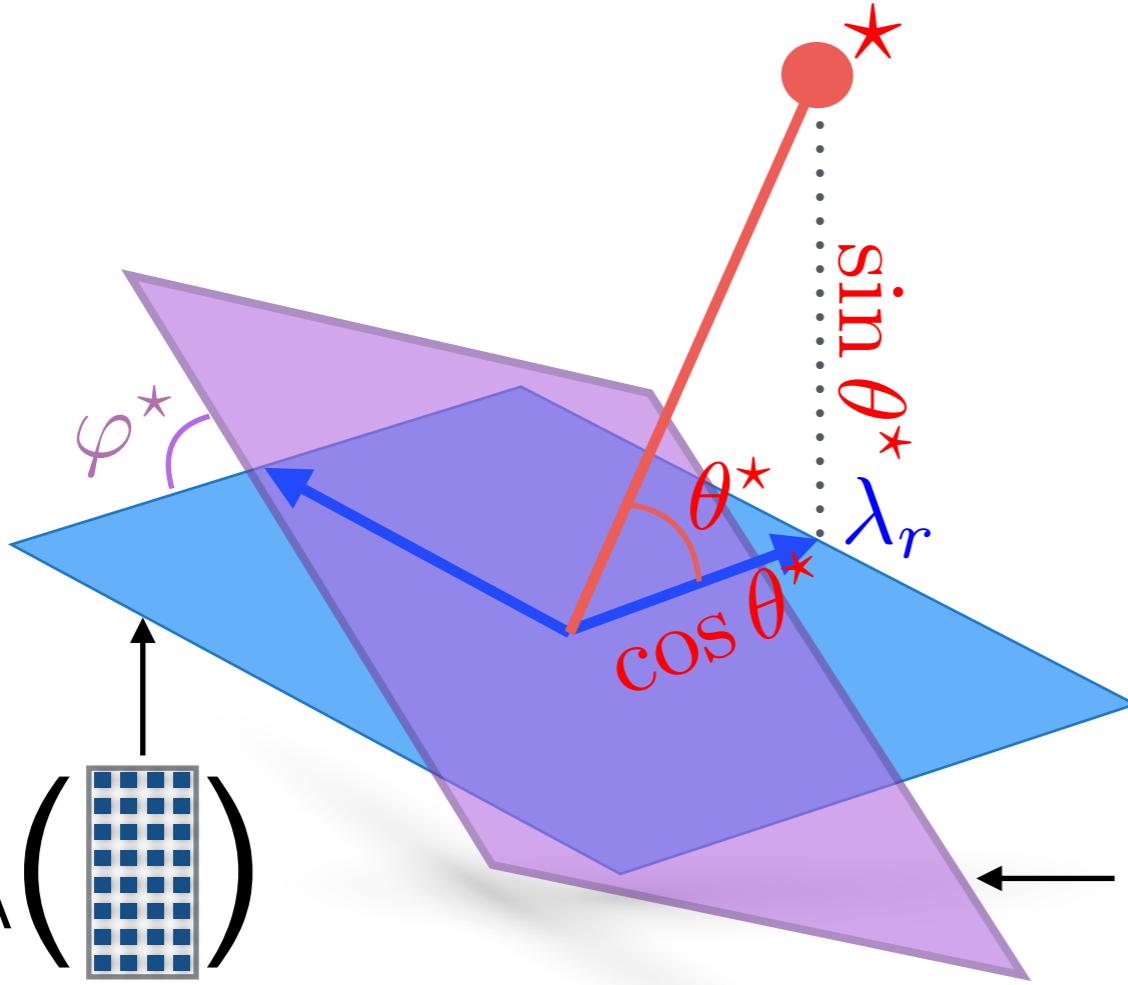
Closed form solution

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# Our Main Theorem

## Closed form solution



PCA( )

PCA( )

$$\theta^* = \frac{1}{2} \arccos \left( -\frac{1}{\lambda_r^2} \right)$$

$$\varphi^* = \arccos \left( \frac{\sin^2 \theta^* - \sigma_*^2}{\sqrt{(\sin^2 \theta^* - \sigma_*^2)^2 + (\sin \theta^* \cos \theta^*)^2}} \right)$$

$$\sigma_*^2 = \frac{(\lambda_r^2 + 1) + \sqrt{(\lambda_r^2 + 1)^2 - 4\lambda_r^2 \sin^2 \theta^*}}{2}.$$

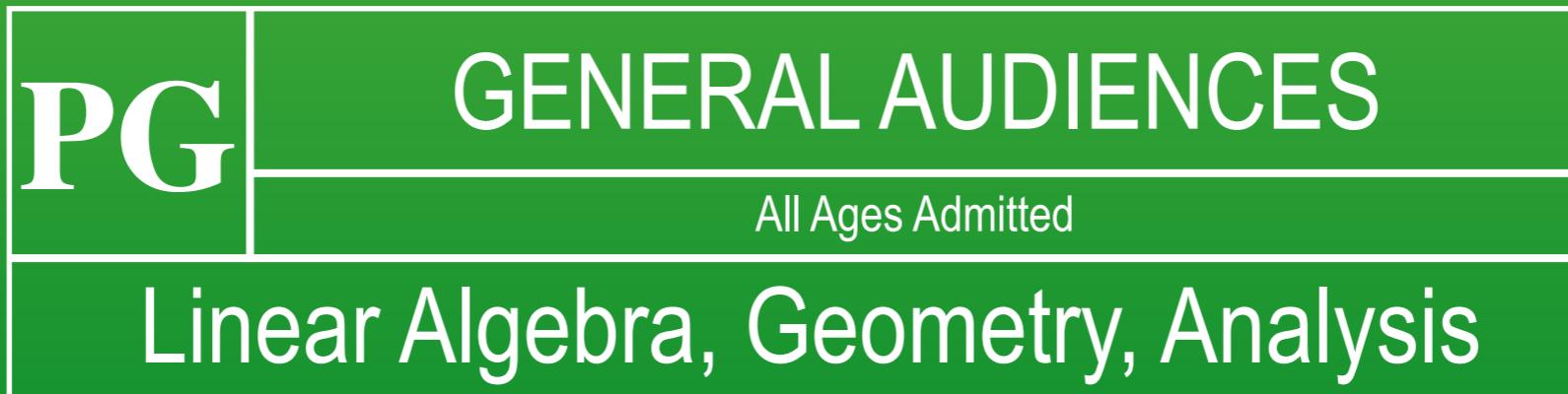
# Our Main Theorem

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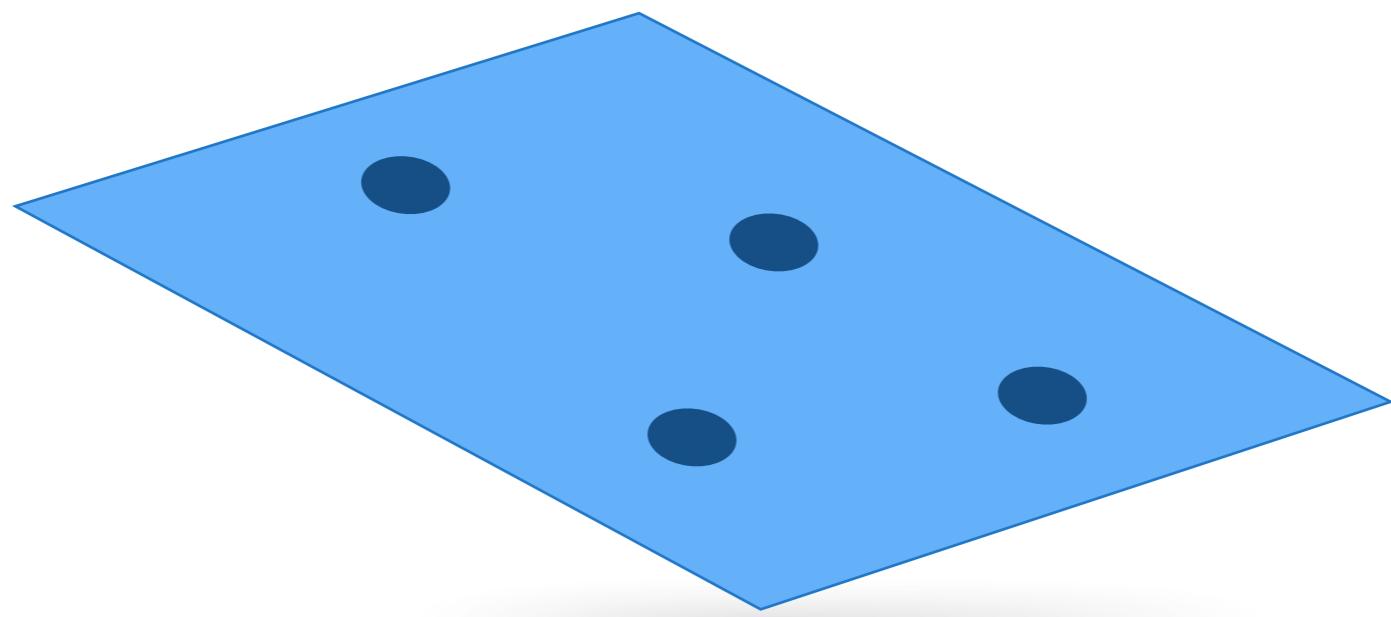
THE FOLLOWING **PREVIEW** HAS BEEN APPROVED FOR  
**ALL AUDIENCES**  
BY THE MOTION PICTURE ASSOCIATION OF AMERICA INC.

THE FILM ADVERTISED HAS BEEN RATED

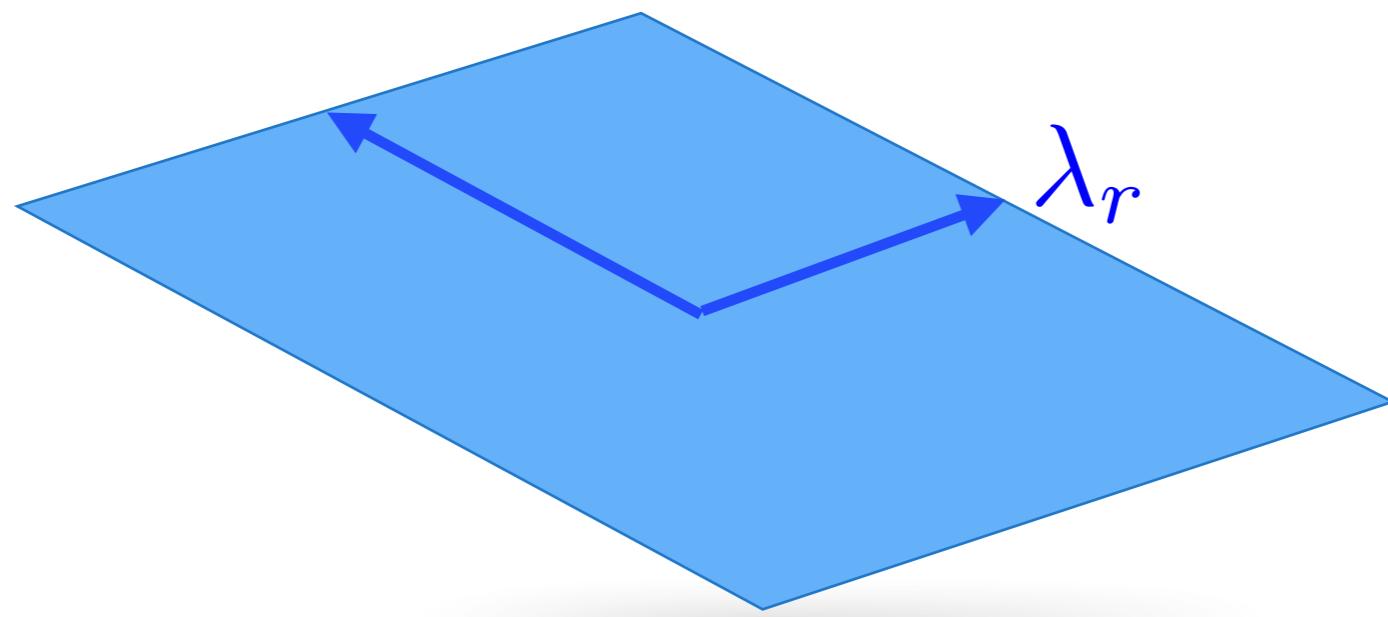


[www.filmratings.com](http://www.filmratings.com)

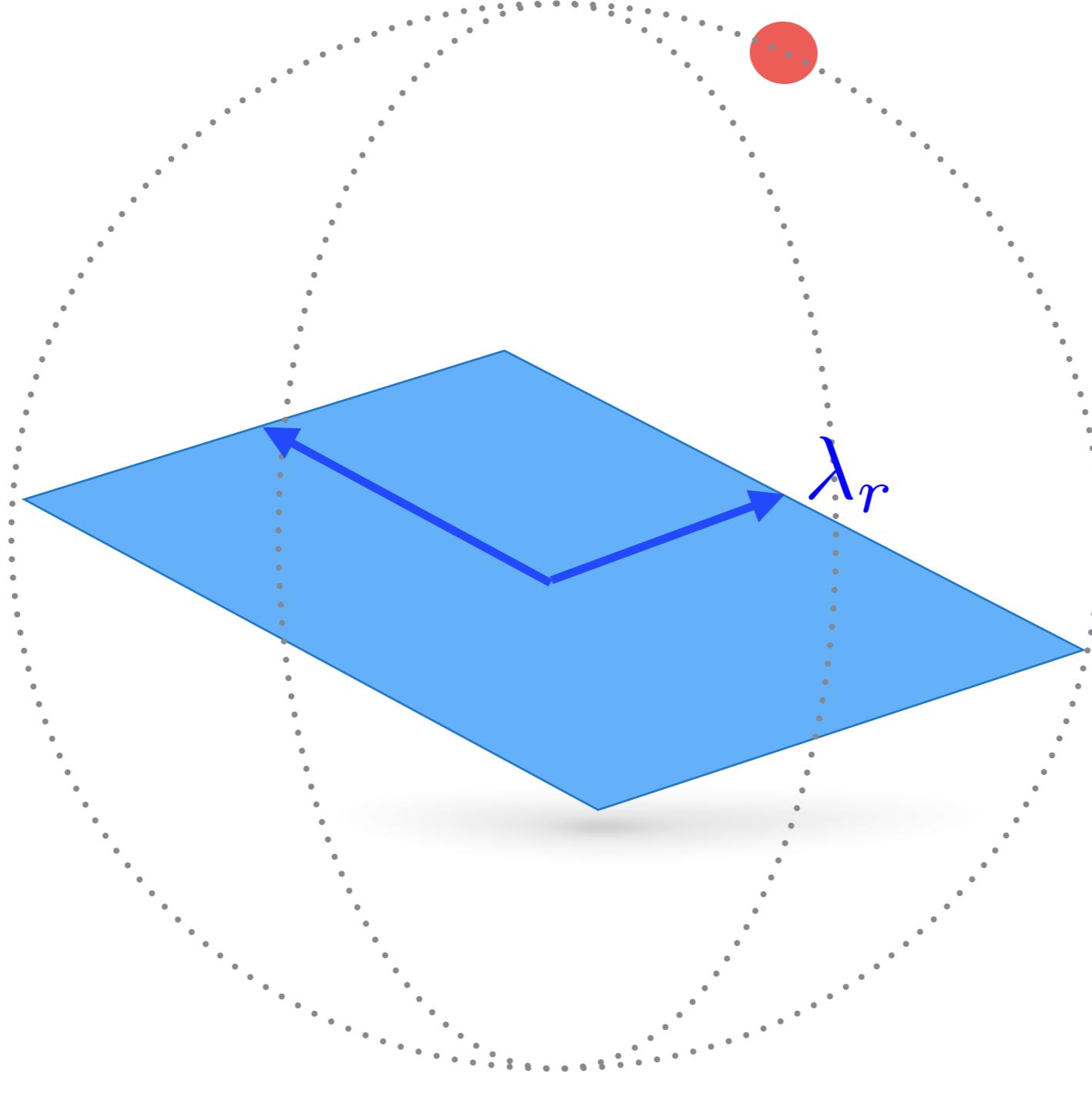
[www.mpaa.org](http://www.mpaa.org)



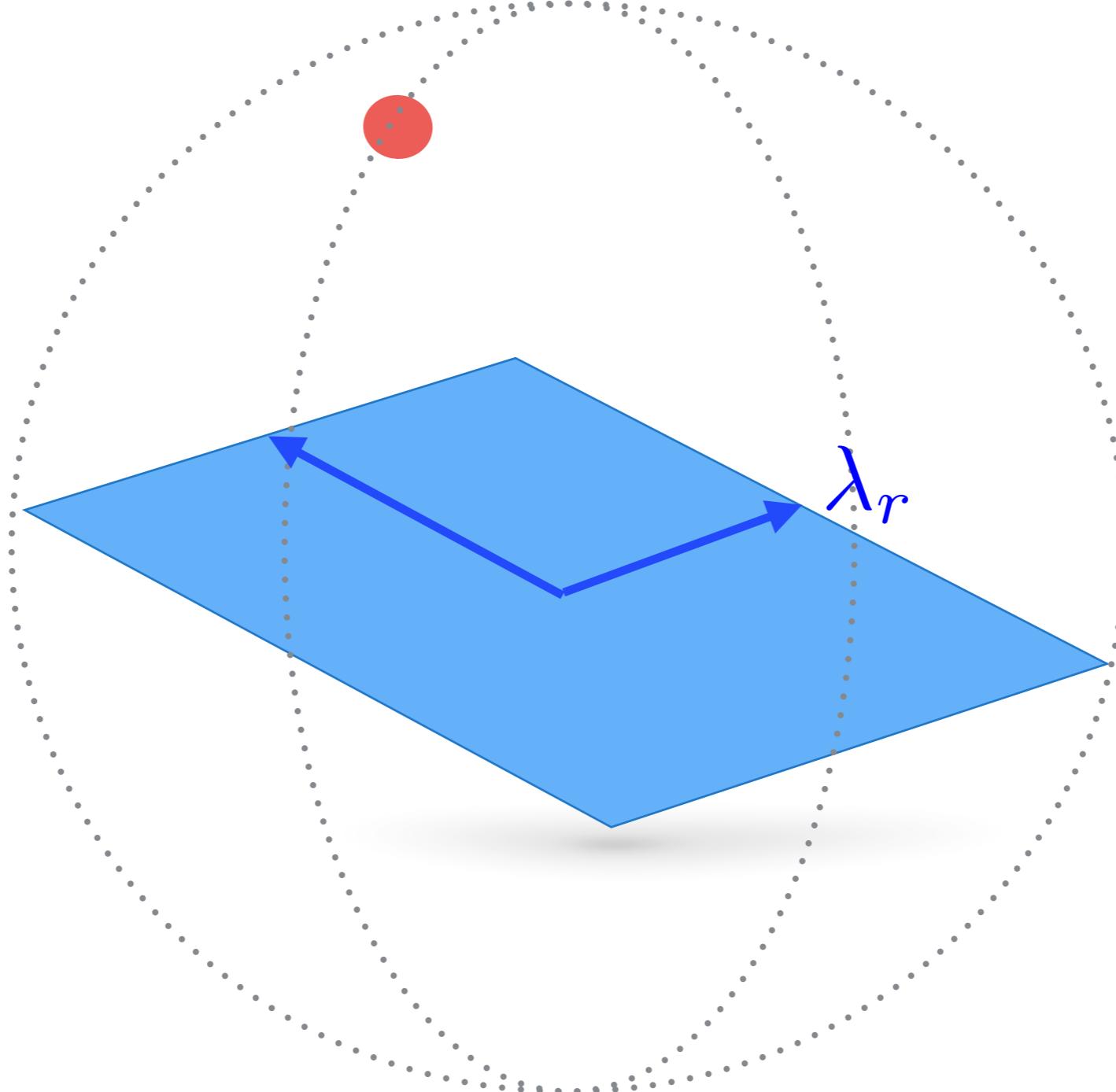
A flavor of the proof



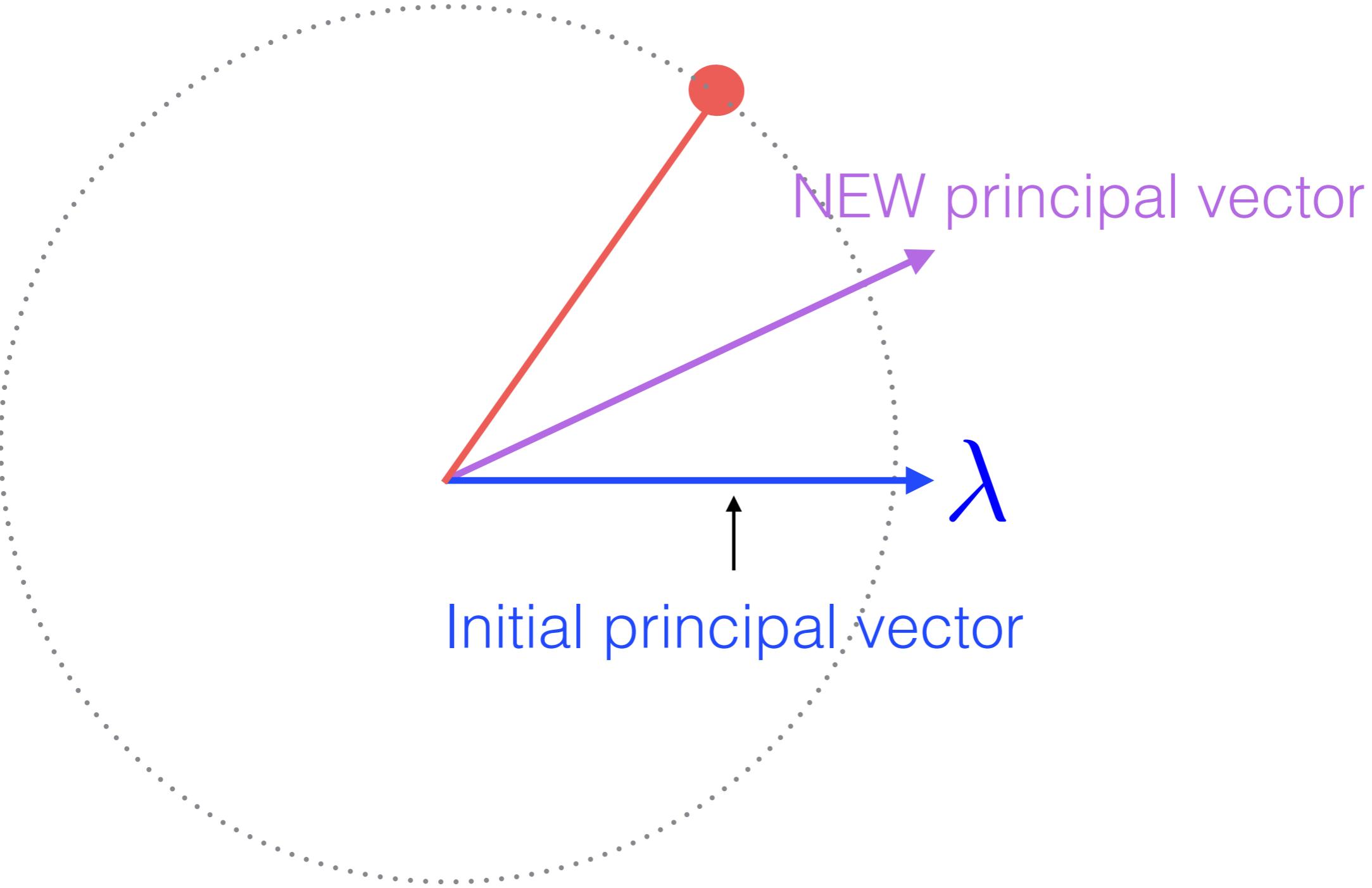
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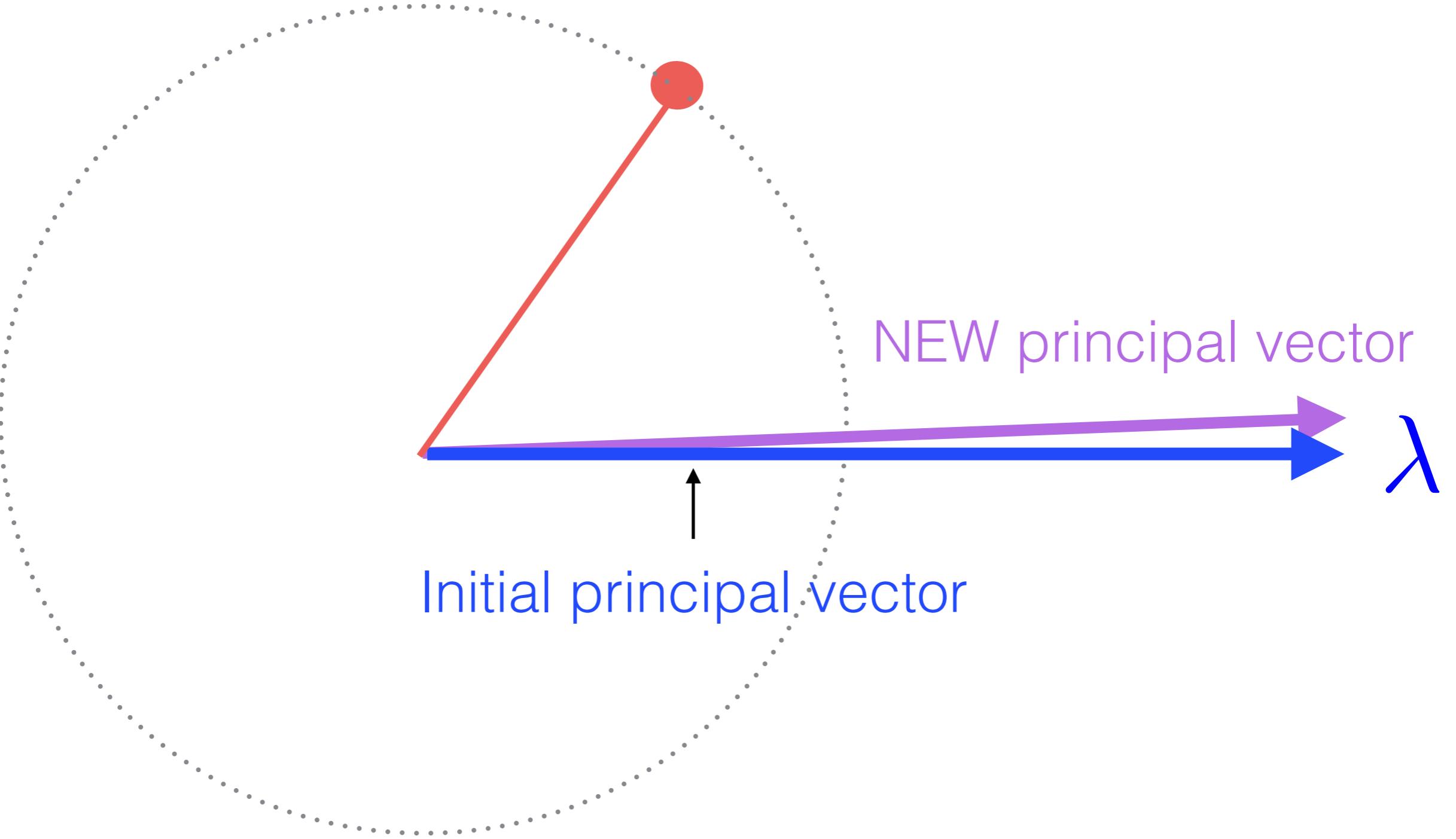
A flavor of the proof  
Fix the magnitude of  $\bullet$



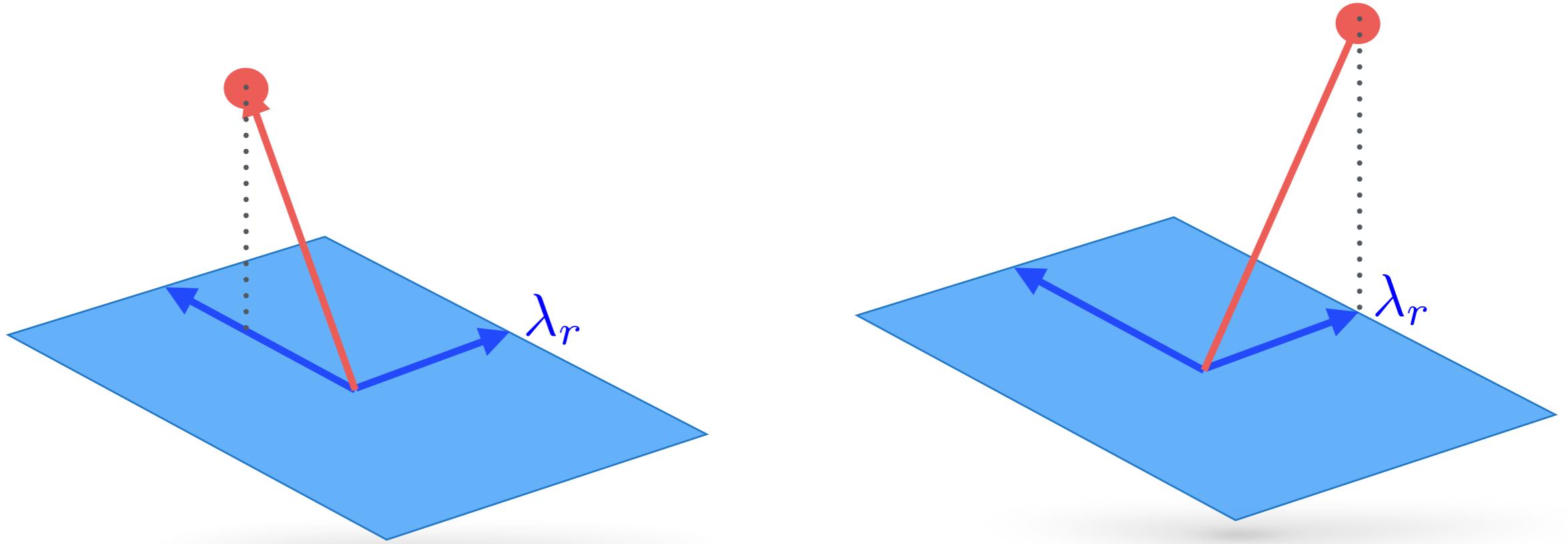
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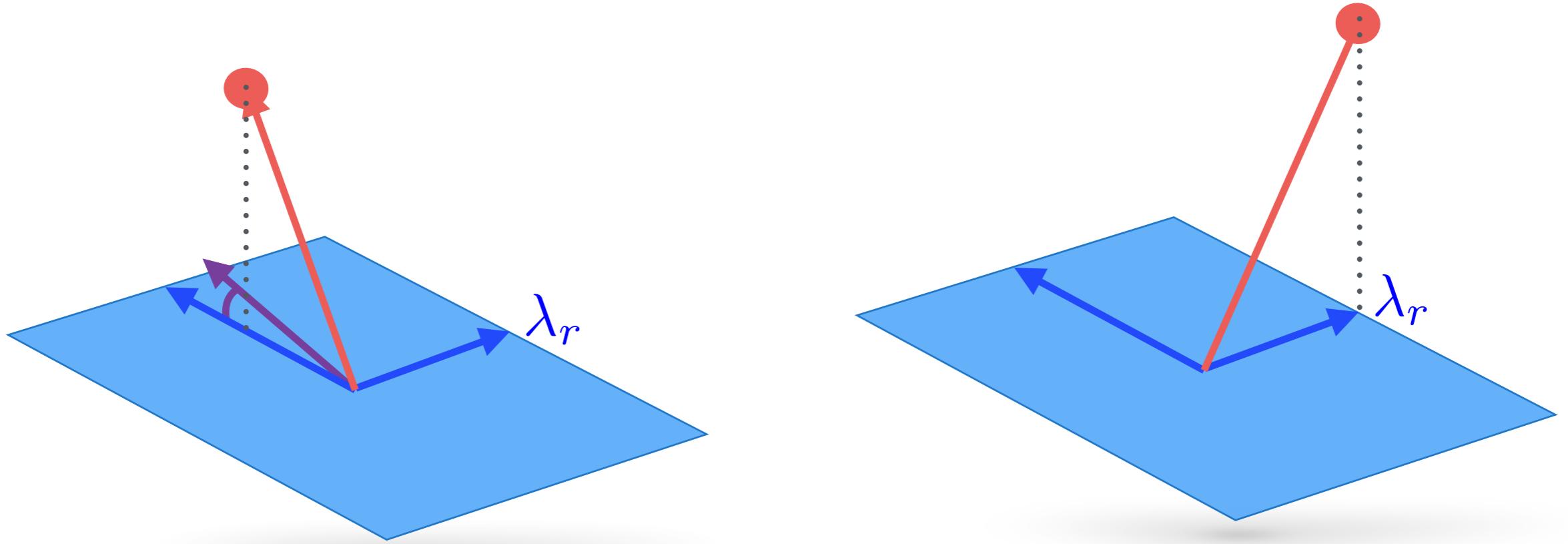
A flavor of the proof  
*Larger vectors are harder to tilt*



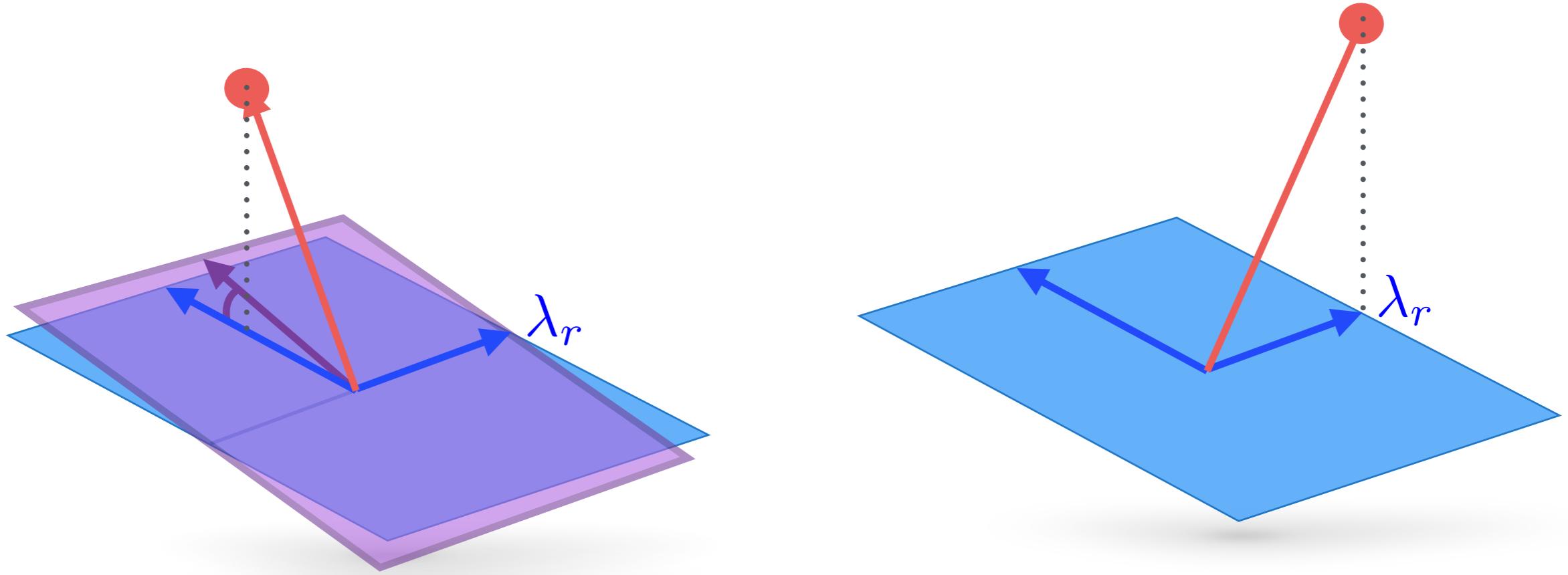
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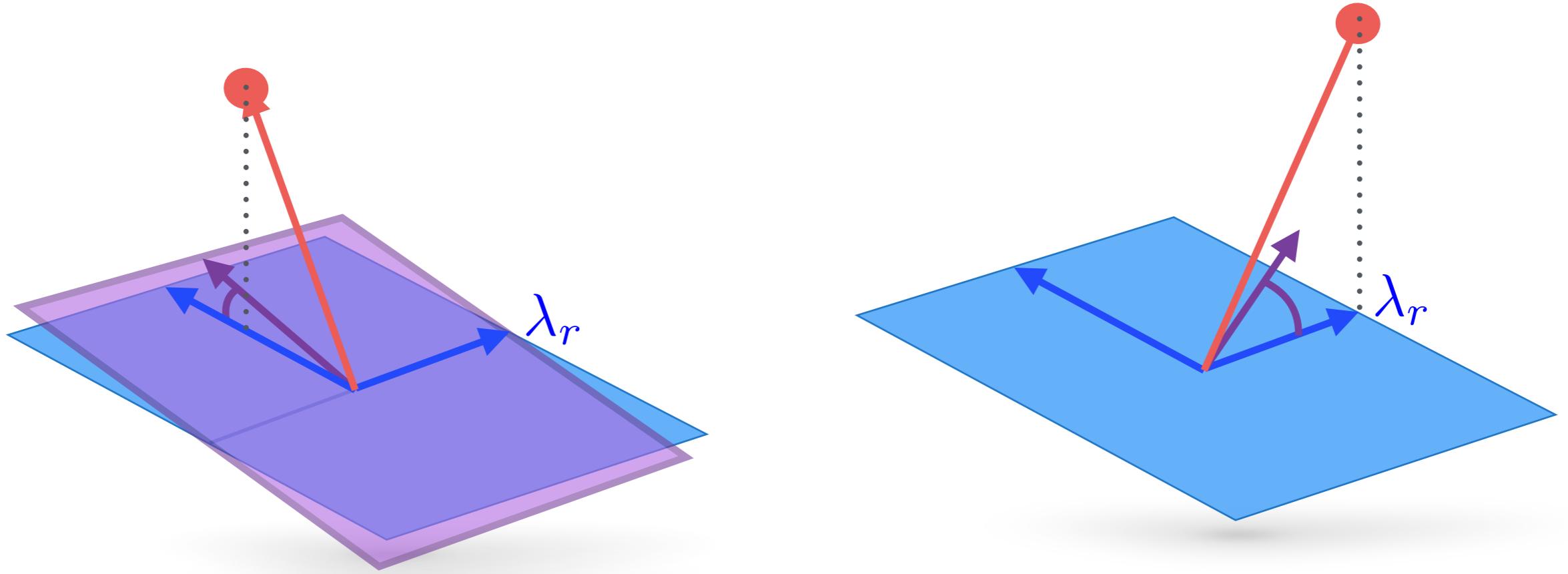
A flavor of the proof  
*Smaller directions can be tilted more*



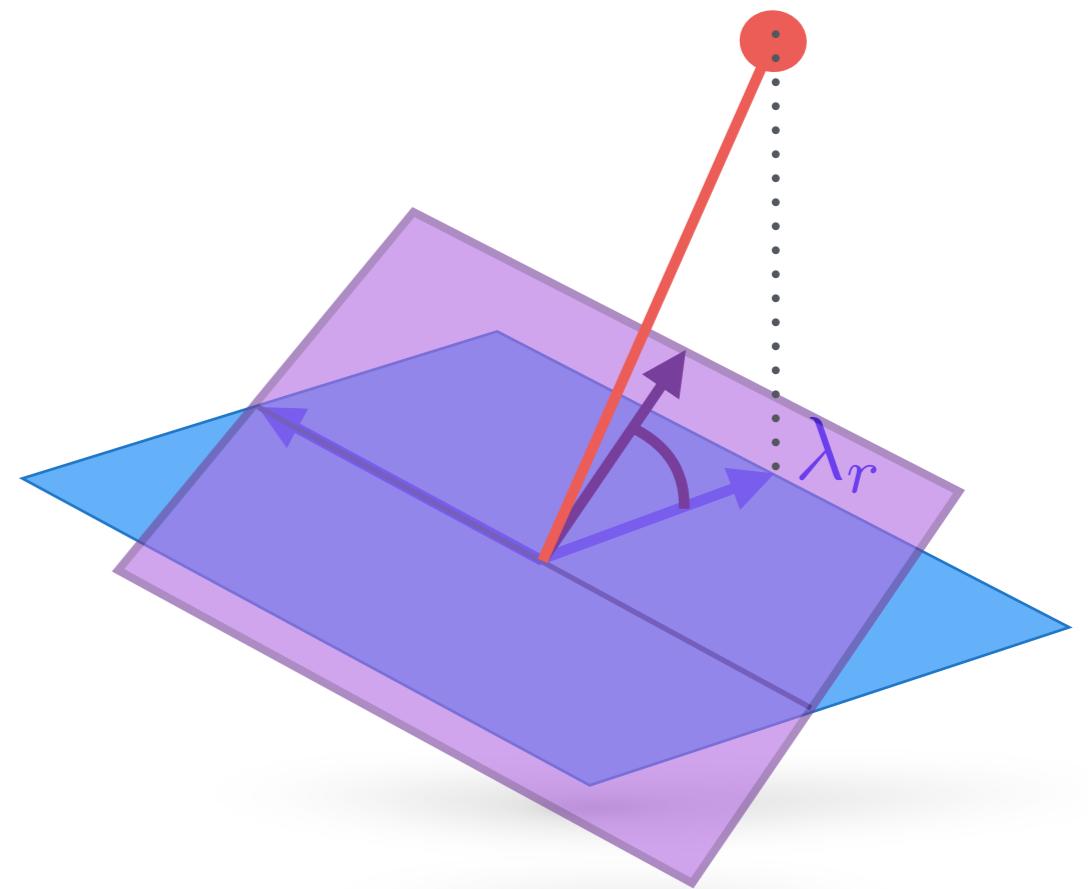
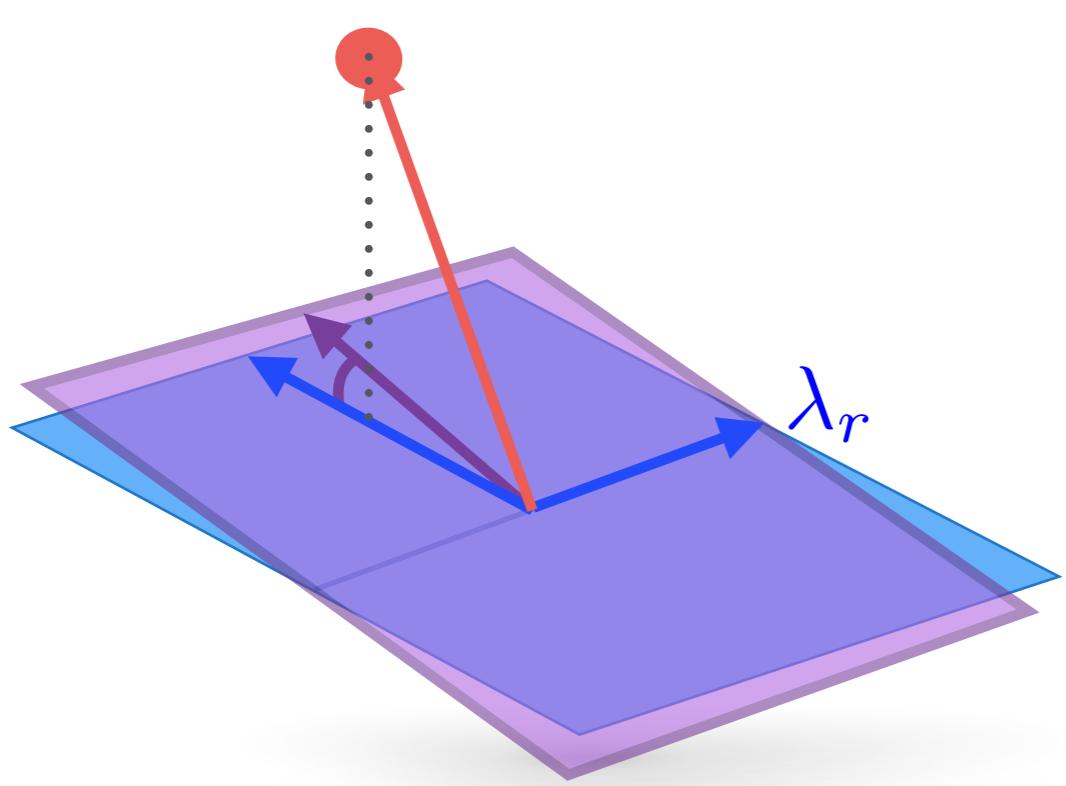
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Smaller directions can be tilted more



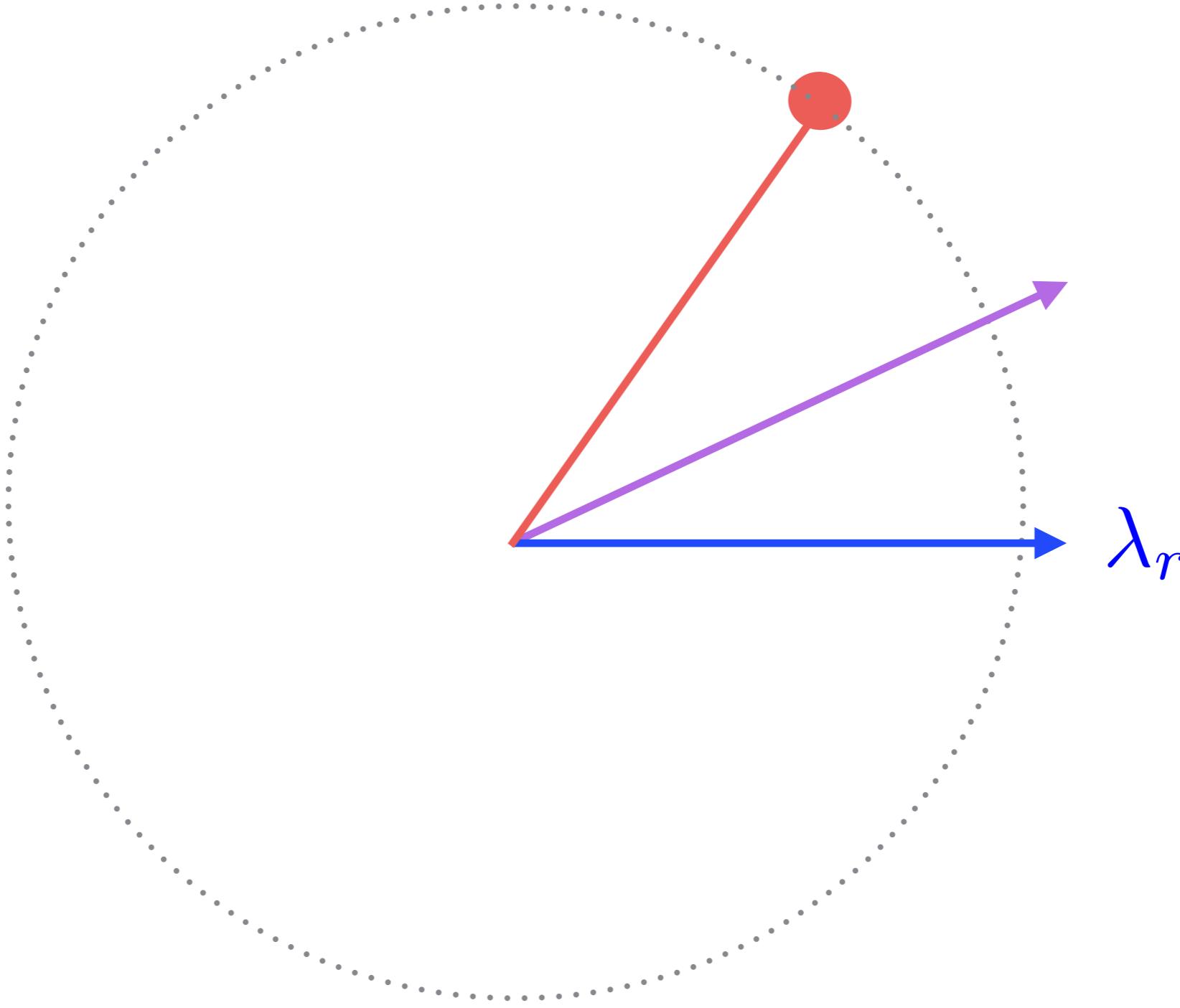
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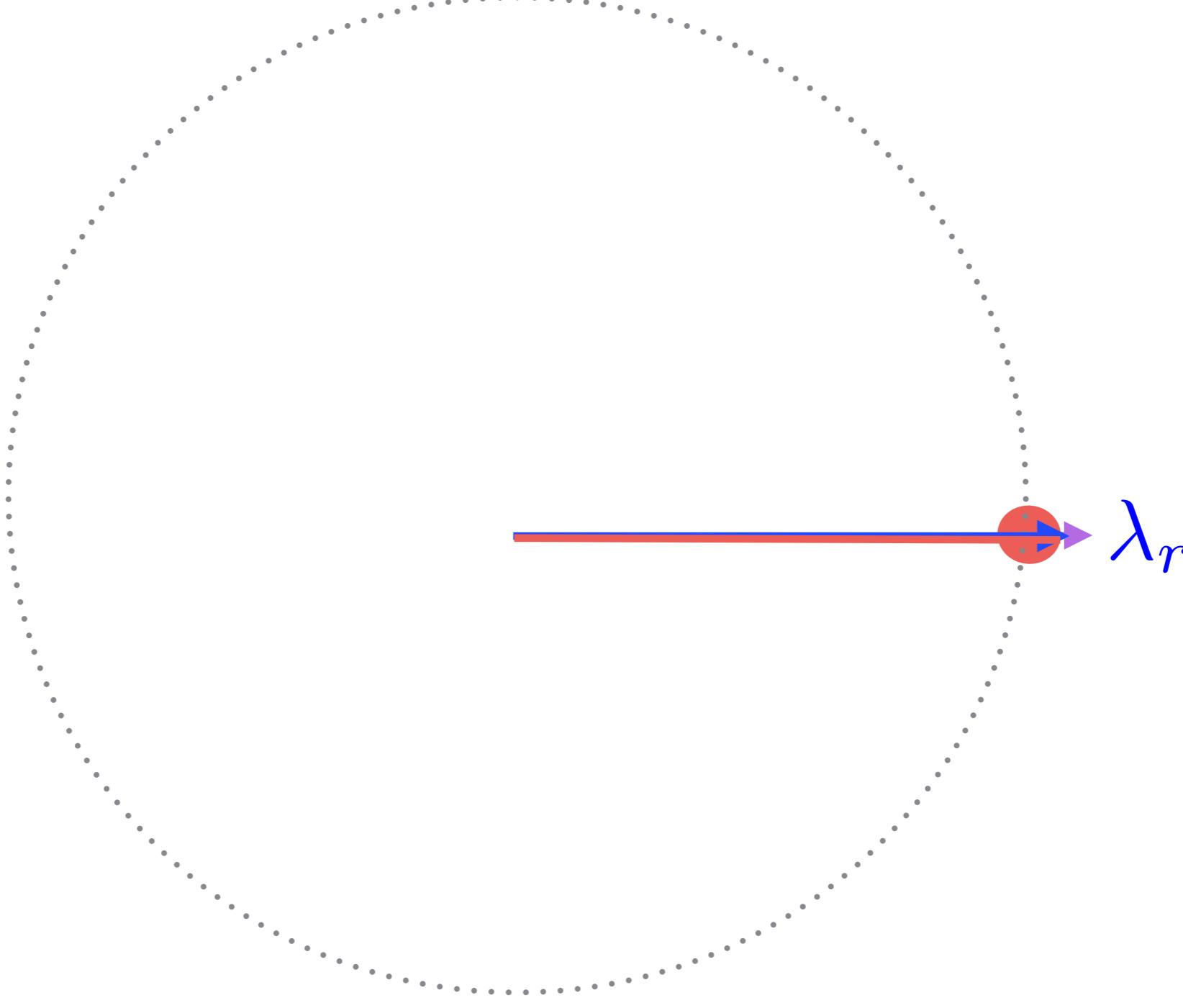


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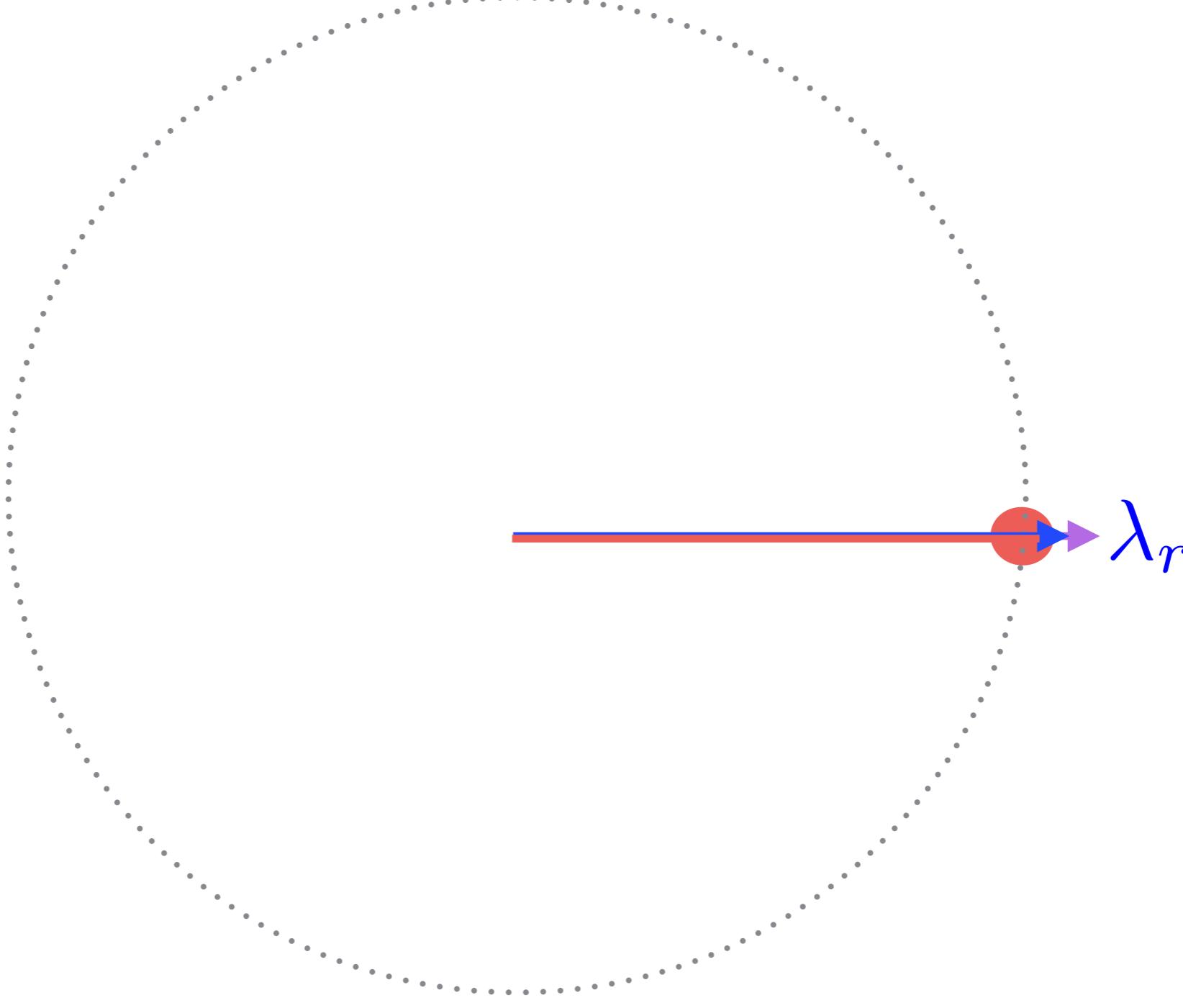
## A flavor of the proof

How do we *tilt* maximally the smallest direction?



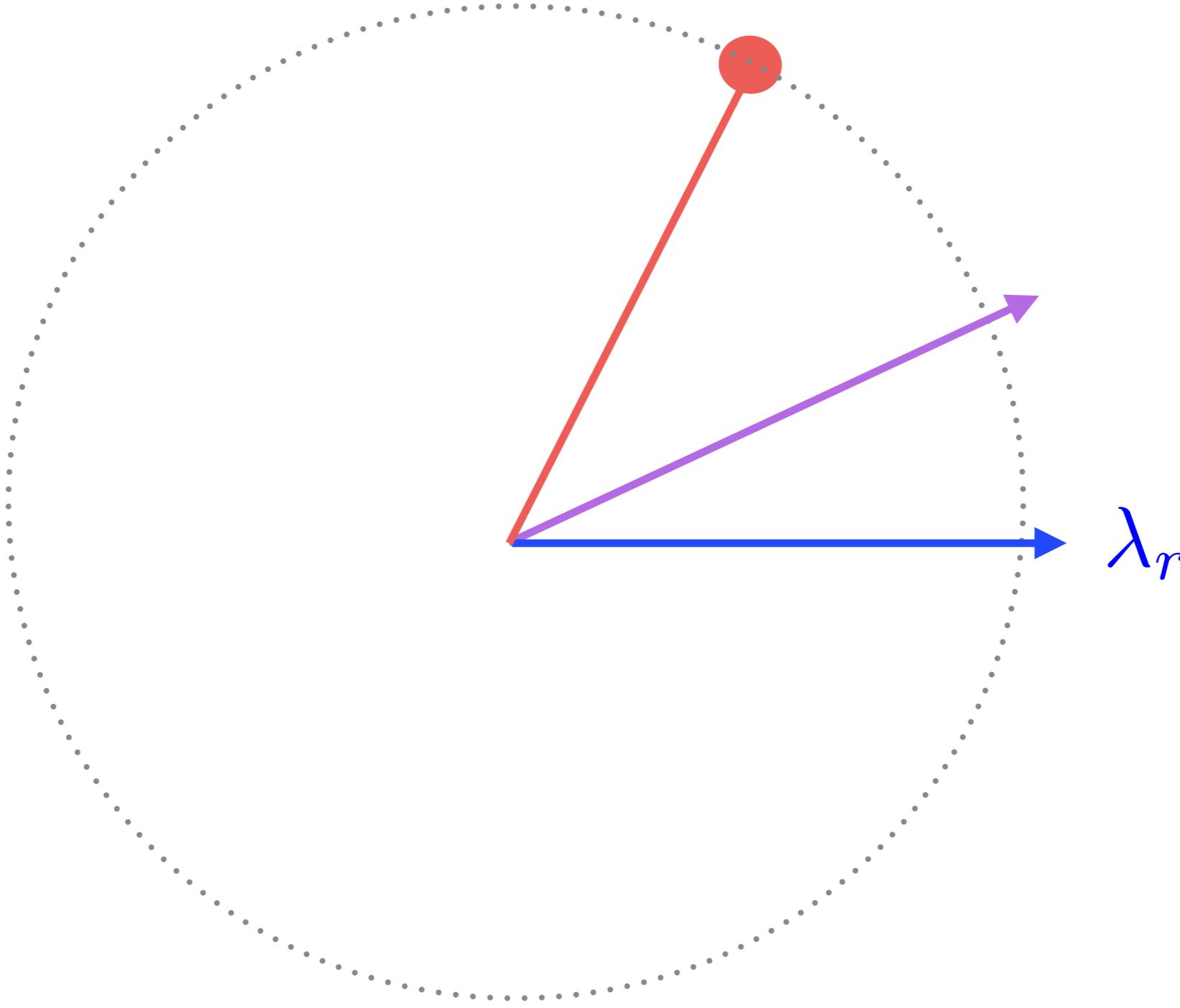
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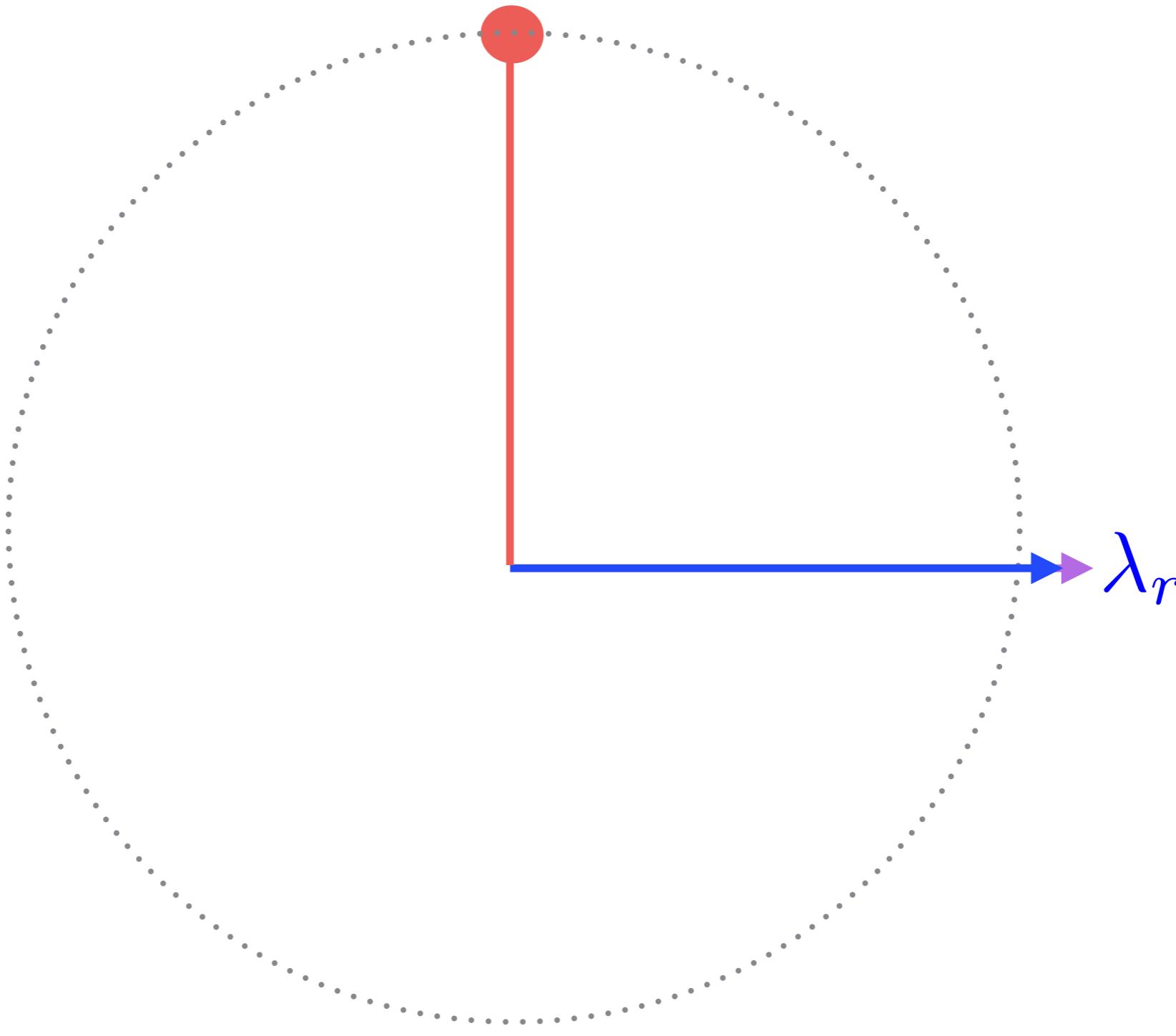
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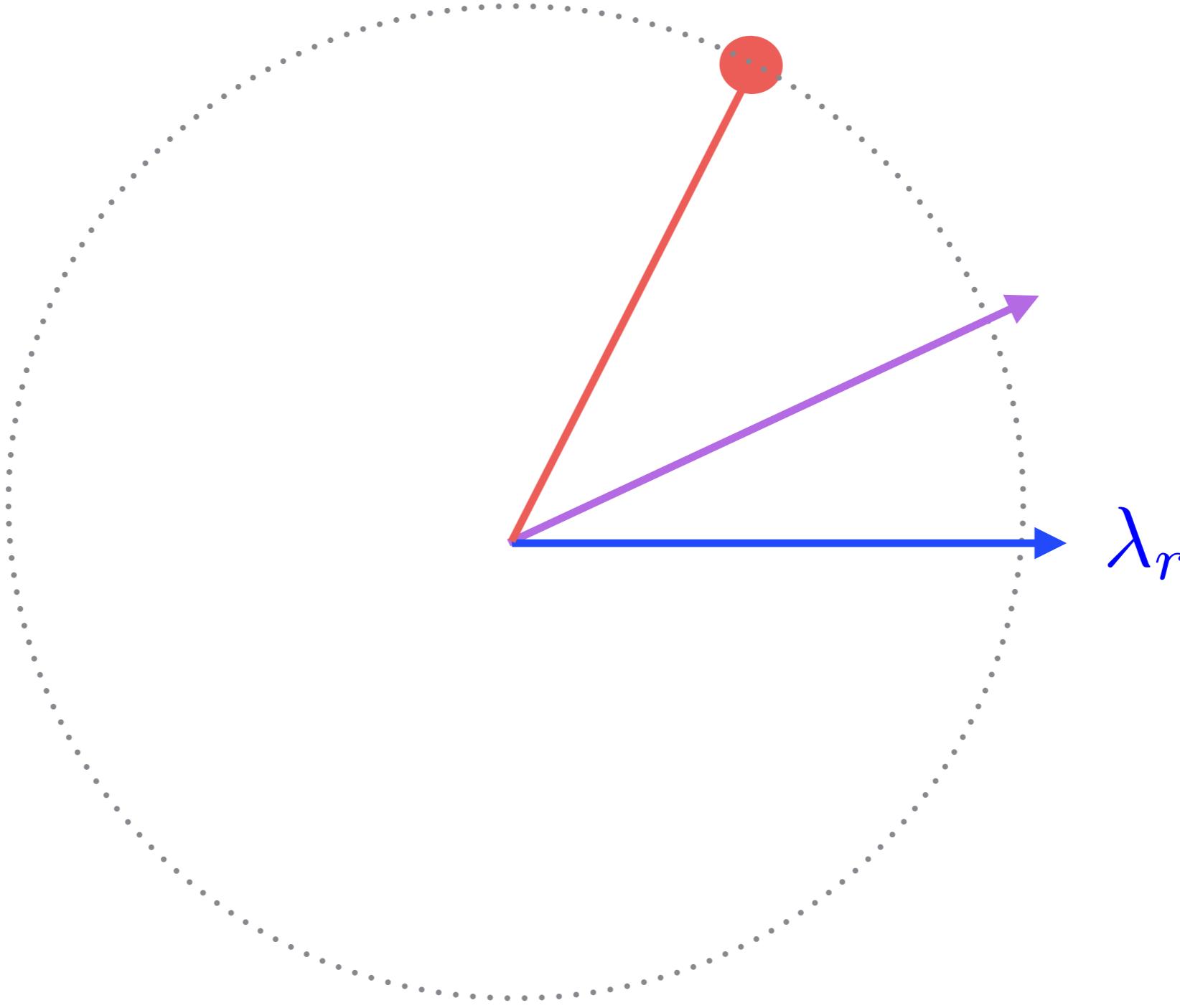
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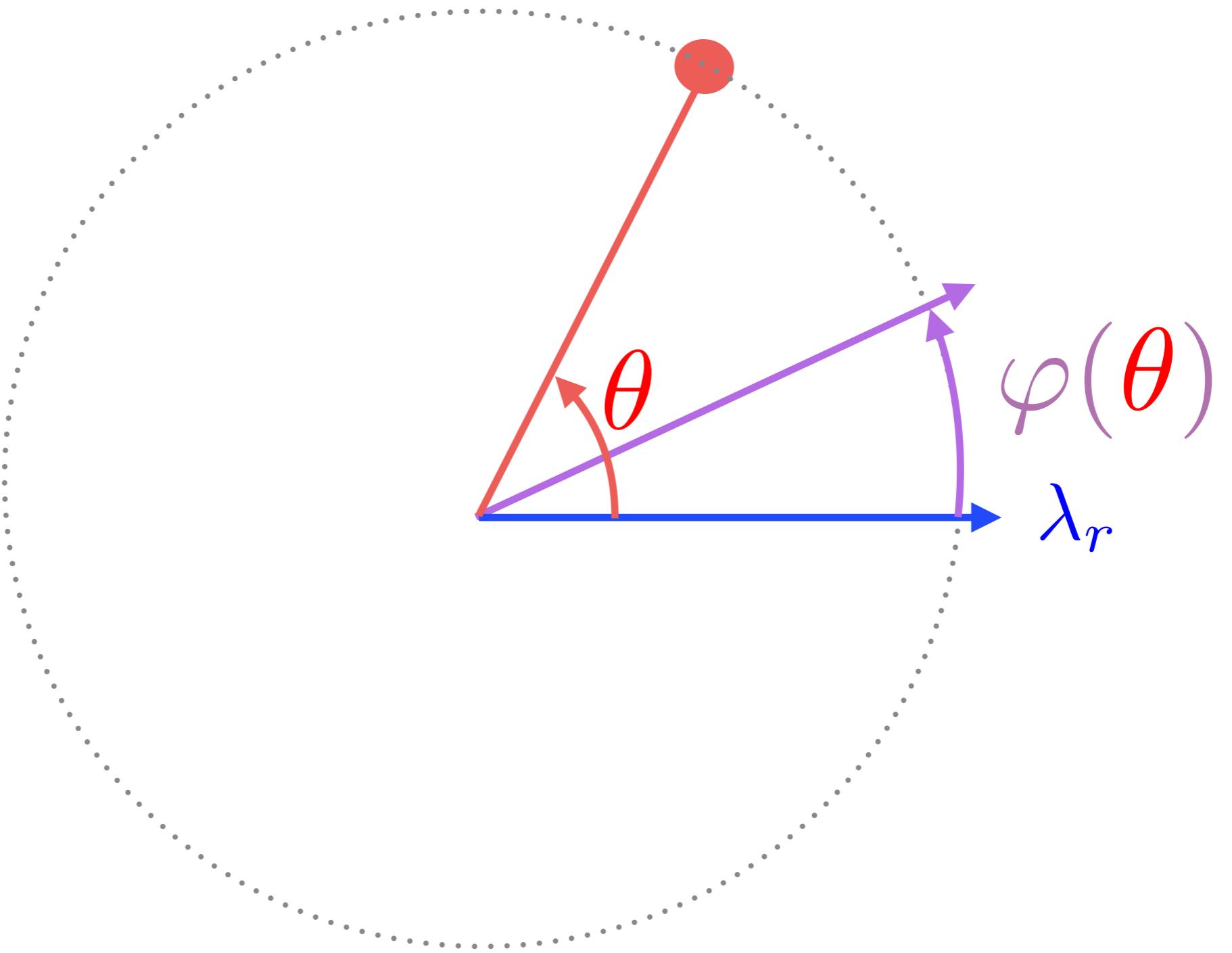
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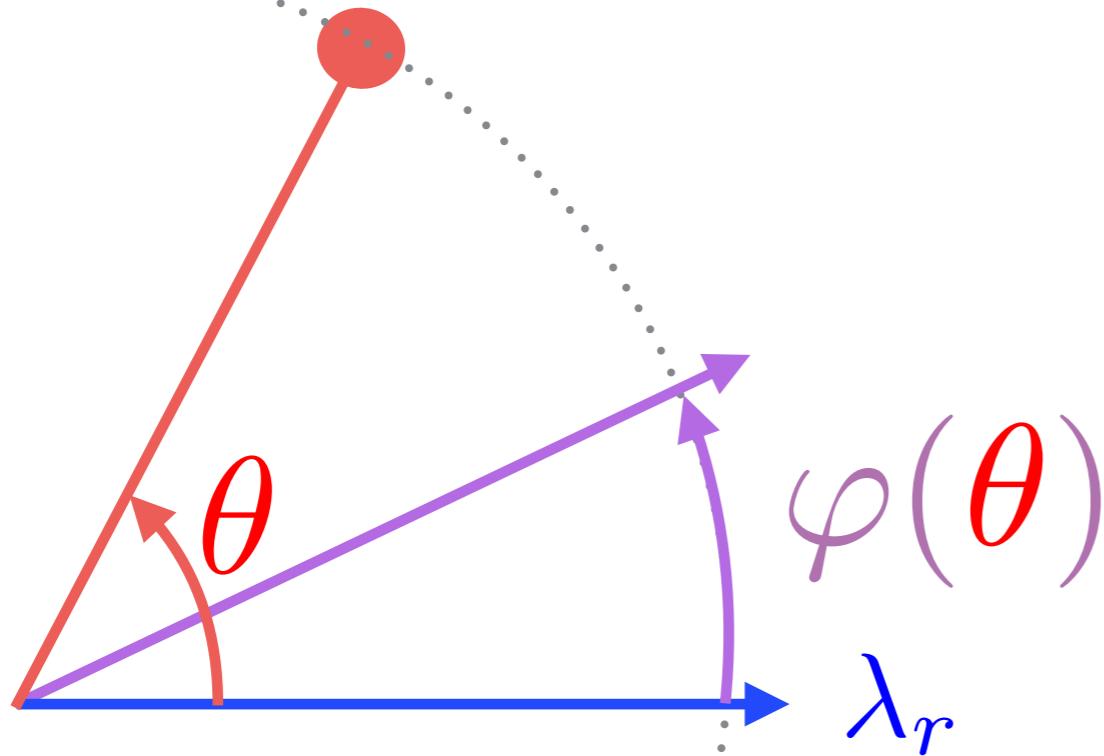
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## A flavor of the proof

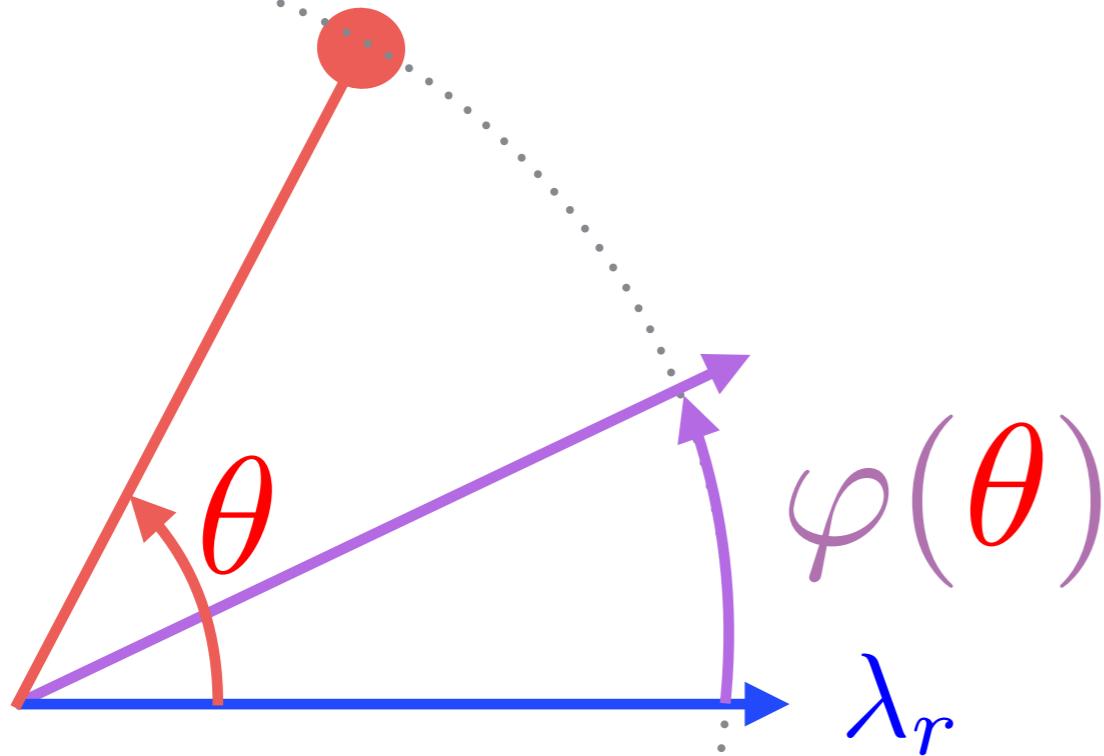
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$$\theta^* = \arg \max_{\theta} \varphi(\theta)$$

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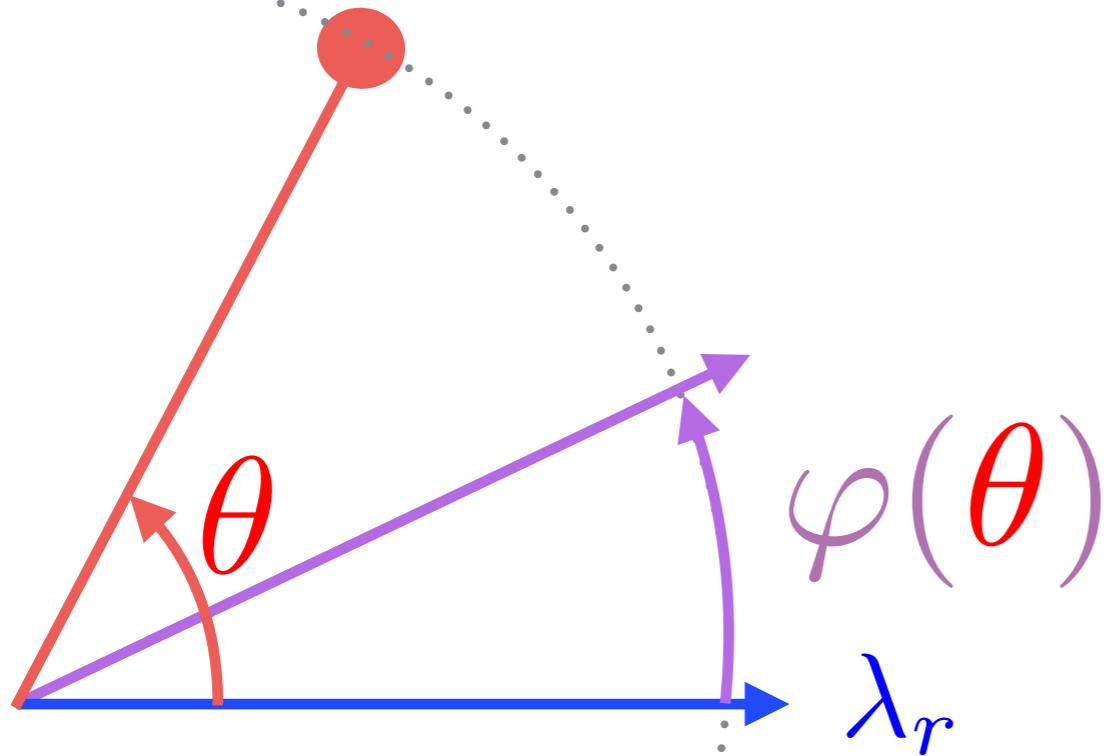
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- Write in closed form.
- Take derivative.
- Set to zero.
- Solve.

(Easier said than done)

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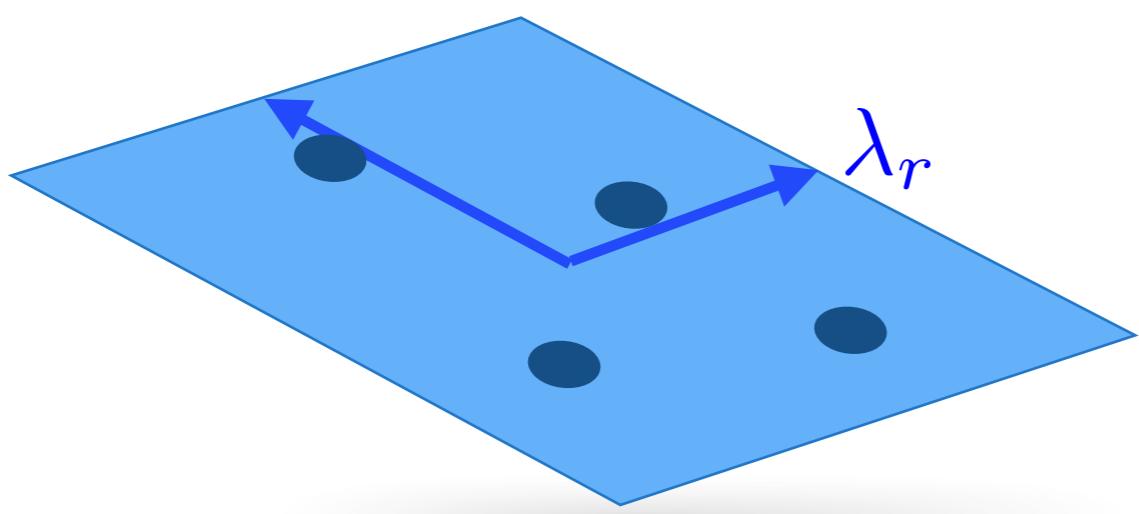
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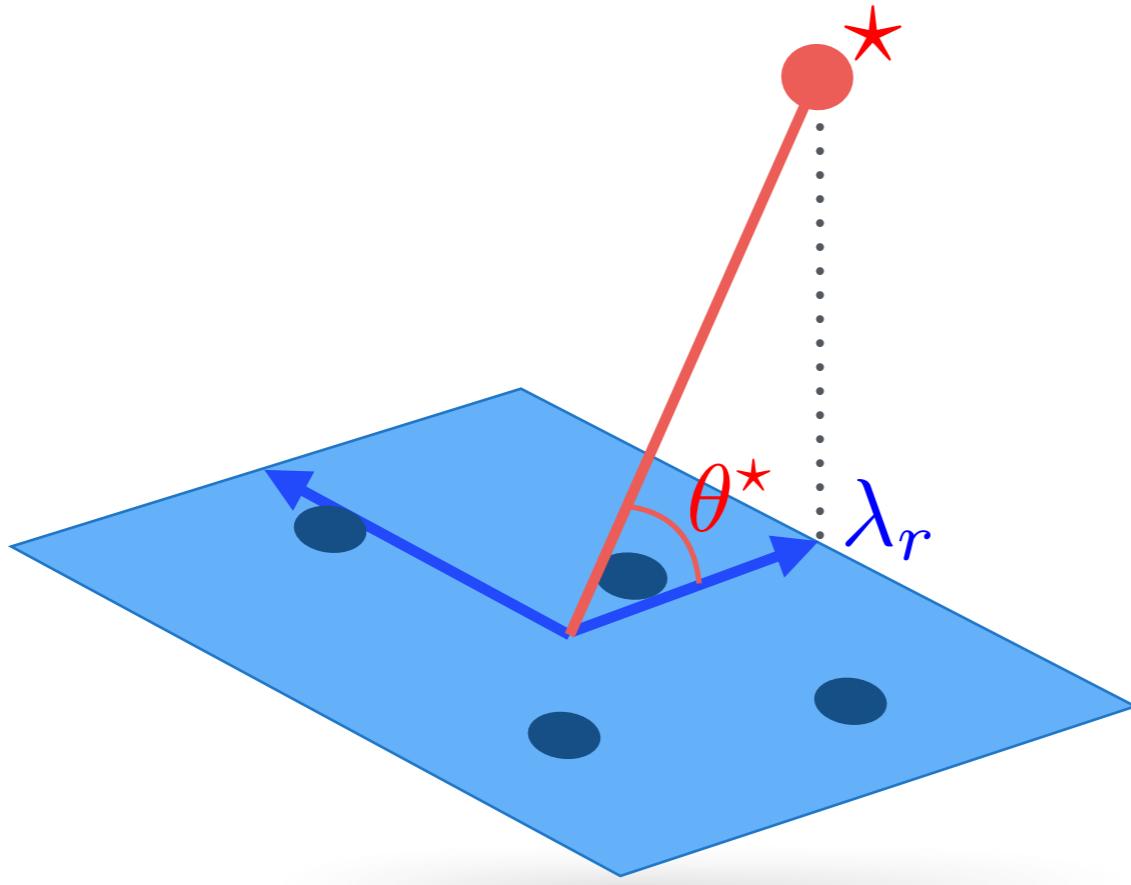
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## A flavor of the proof

How do we maximally *tilt* the smallest direction?

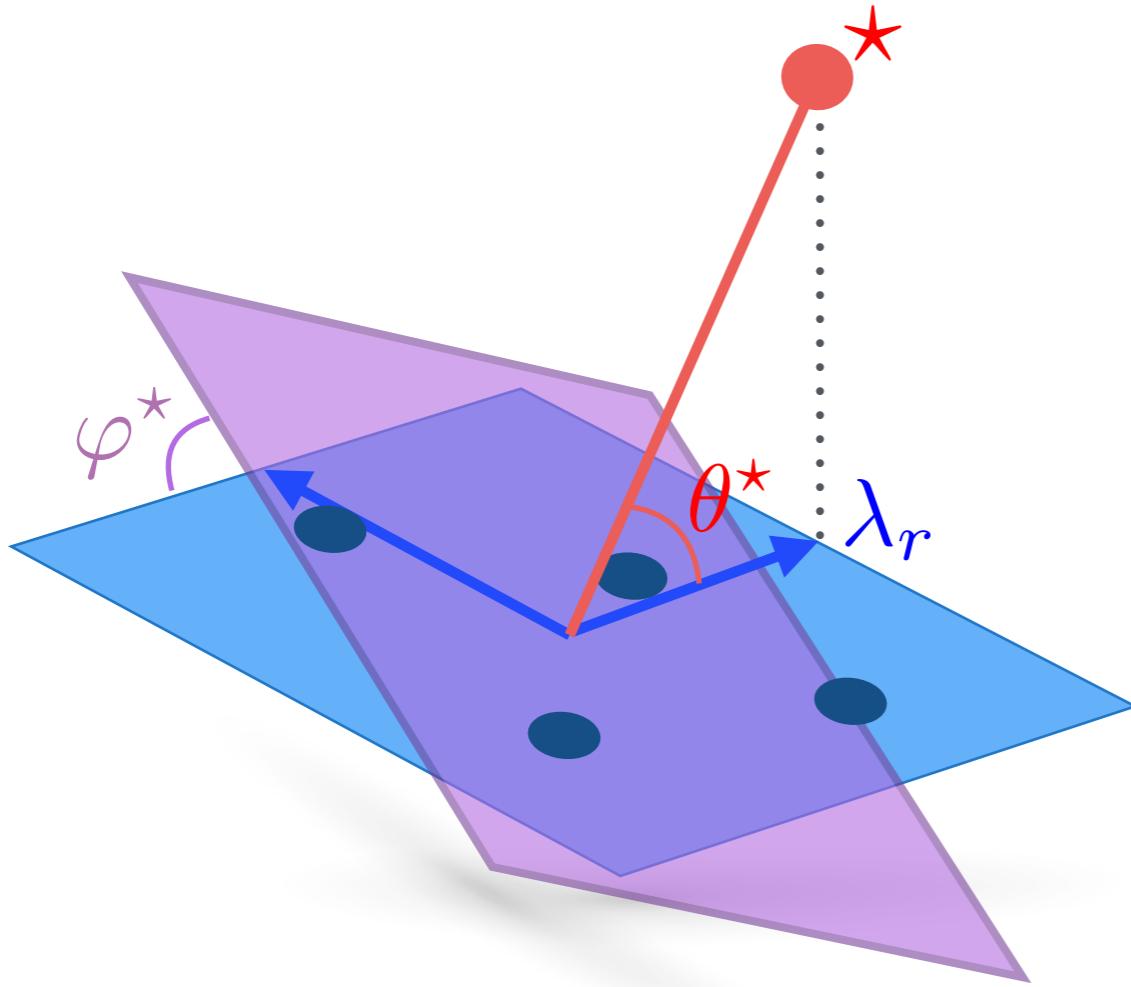


Putting everything together



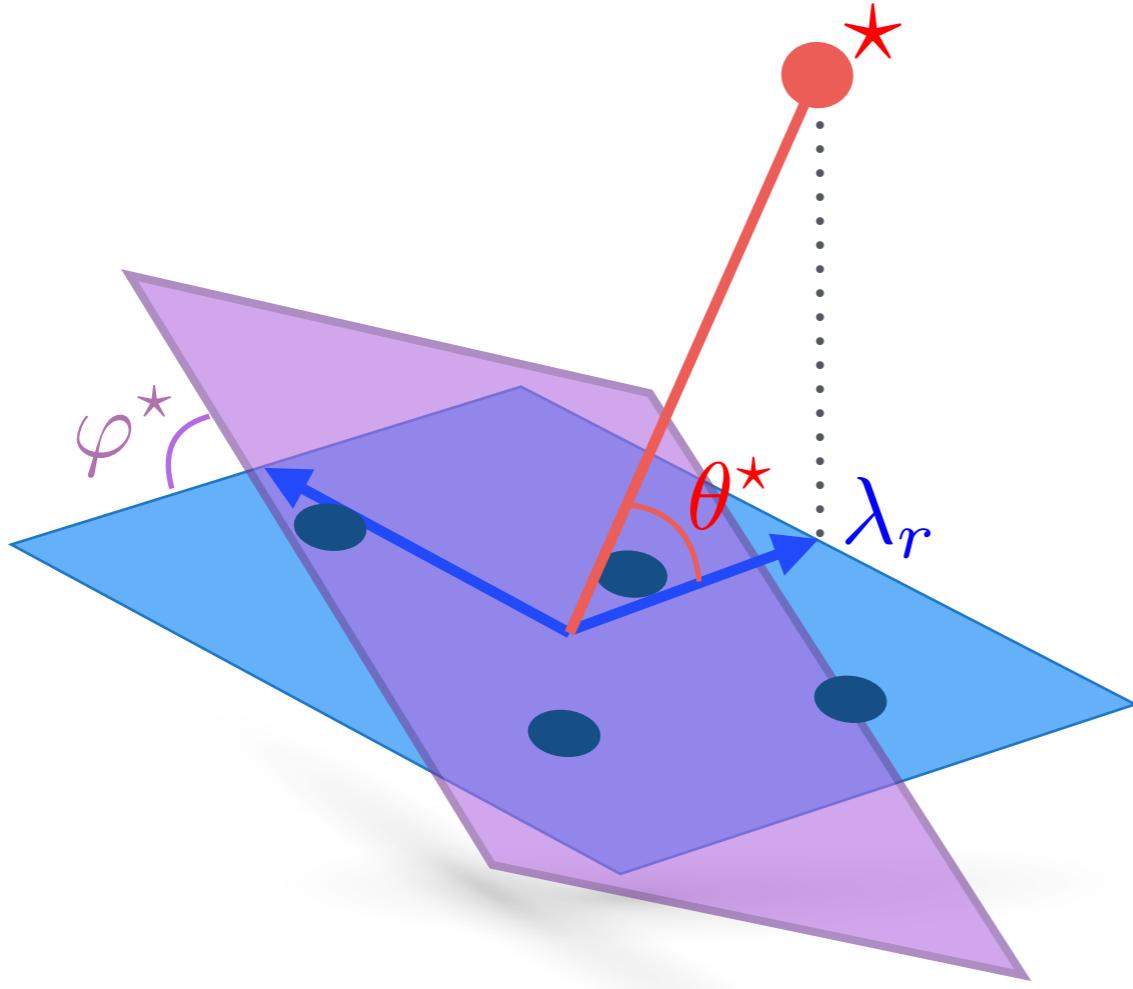
$$\theta^* = \frac{1}{2} \arccos \left( -\frac{1}{\lambda_r^2} \right)$$

Putting everything together



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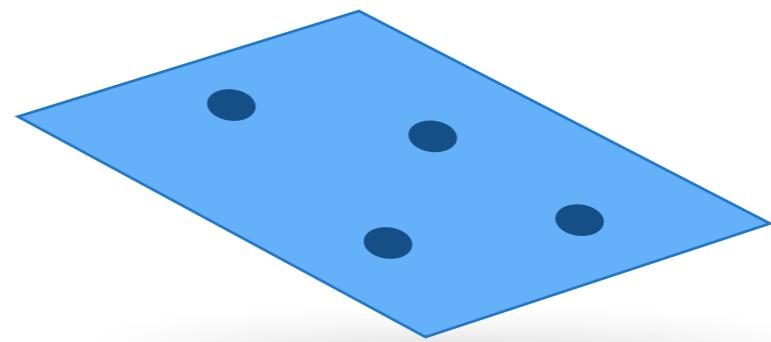
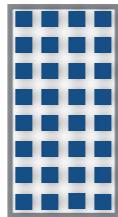
$$\theta^* = \frac{1}{2} \arccos \left( -\frac{1}{\lambda_r^2} \right)$$

$$\varphi^* = \arccos \left( \frac{\sin^2 \theta^* - \sigma_*^2}{\sqrt{(\sin^2 \theta^* - \sigma_*^2)^2 + (\sin \theta^* \cos \theta^*)^2}} \right)$$

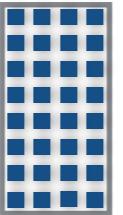
$$\sigma_*^2 = \frac{(\lambda_r^2 + 1) + \sqrt{(\lambda_r^2 + 1)^2 - 4\lambda_r^2 \sin^2 \theta^*}}{2}.$$

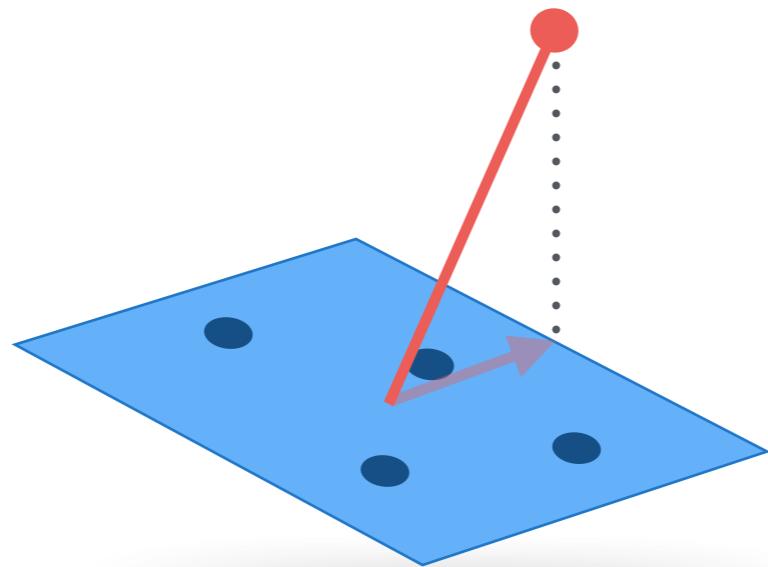
Putting everything together

- Given a dataset

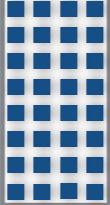


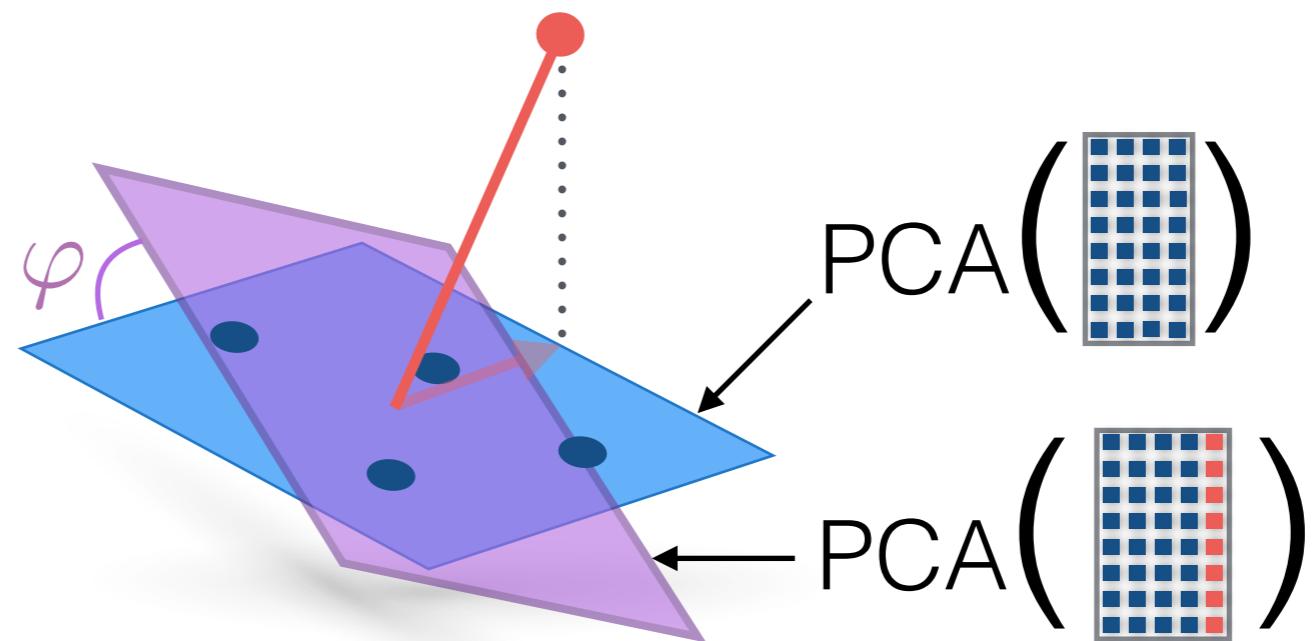
Take home message

- Given a dataset , we know **exactly** what  should be



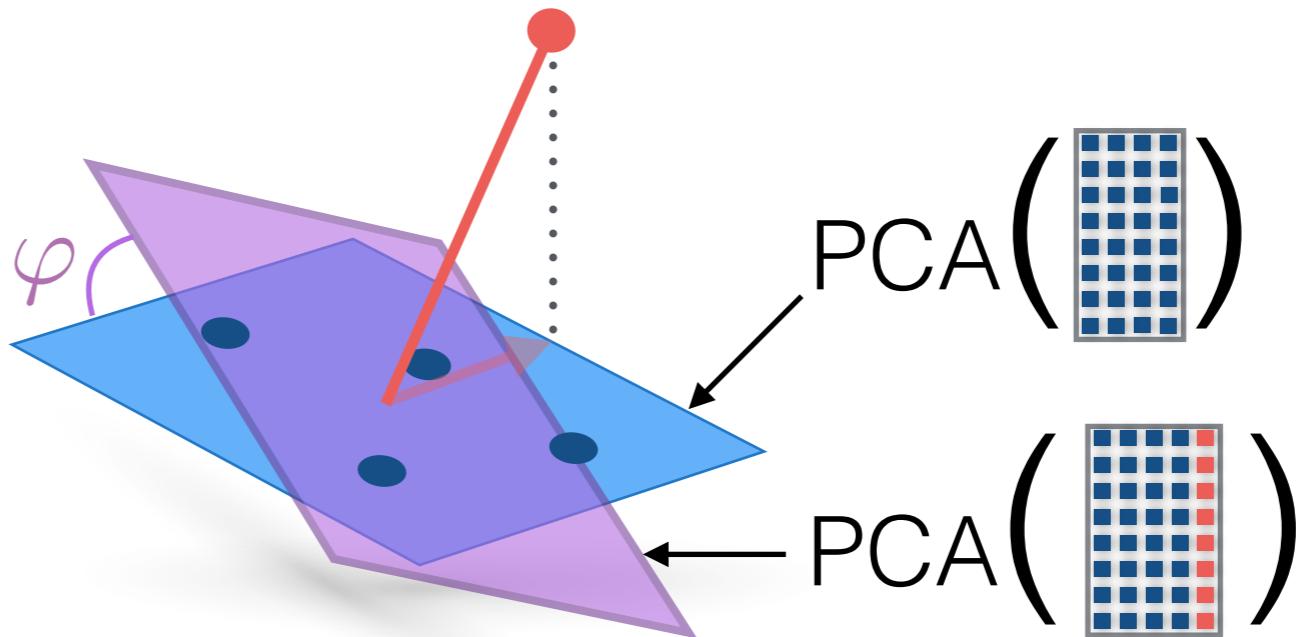
Take home message

- Given a dataset , we know **exactly** what  should be So that  $\varphi$  is maximal.



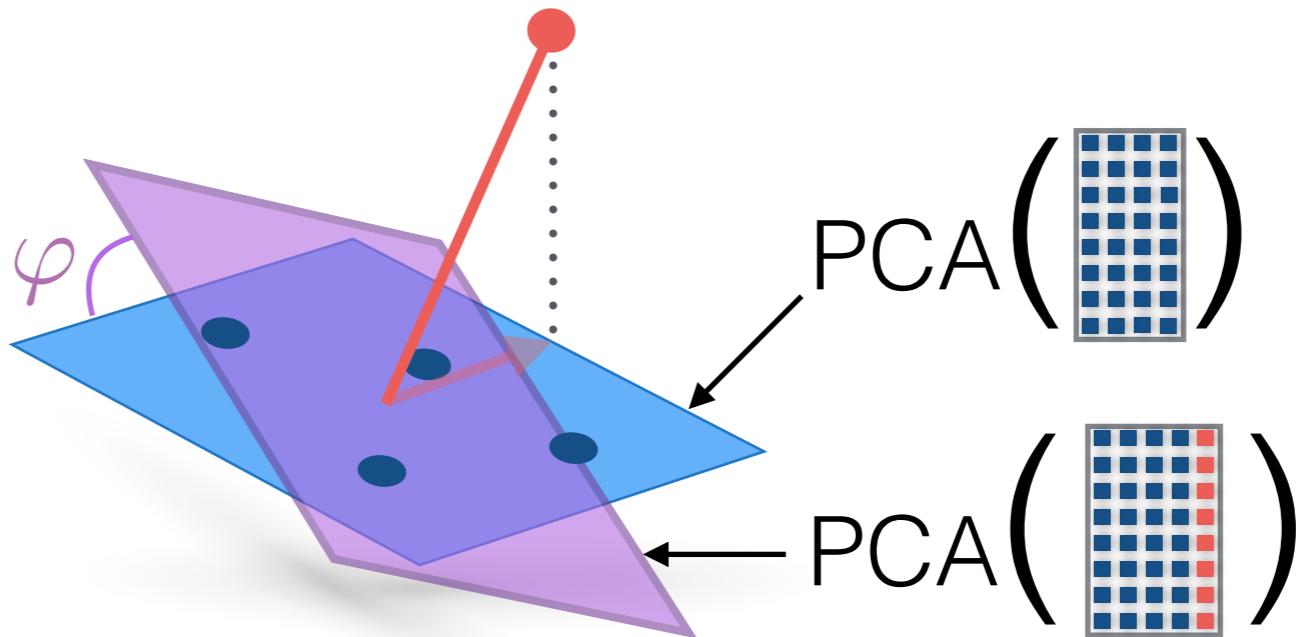
Take home message

- Given a dataset , we know **exactly** what  should be  
So that  $\varphi$  is maximal. (closed form)



# Take home message

- Given a dataset , we know **exactly** what  should be  
So that  $\varphi$  is maximal. (closed form)



- Info-theory bound: how much one can *tilt* a subspace.
- Error bounds for Subspace Clustering.
- Applications in rank-one updates?
- Other applications?

# Take home message

Dankeschön!