

Conditions for eigenvalue configurations of two real symmetric matrices

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Problem

Definition (Eigenvalue configuration)

Let $F \in \mathbb{R}^{m \times m}$ and $G \in \mathbb{R}^{n \times n}$ be symmetric matrices with simple and distinct eigenvalues. Then the “eigenvalue configuration” C is the relative locations of the eigenvalues.

Example ($m = n = 2$)

$$\text{Let } F = \begin{bmatrix} 2 & -1 \\ -1 & 0 \end{bmatrix} \text{ and } G = \begin{bmatrix} 3 & 2 \\ 2 & 9 \end{bmatrix}$$

$$\text{Let } F = \begin{bmatrix} 1 & 3 \\ 3 & 3 \end{bmatrix} \text{ and } G = \begin{bmatrix} -1 & 4 \\ 4 & 3 \end{bmatrix}$$

$$\text{Then } C = \text{---} \bullet \text{---} \bullet \text{---} \bullet \text{---} \bullet \text{---}$$

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Problem (Conditions for eigenvalue configuration)

In : C , eigenvalue configuration

Out: Condition on F and G for C

Example ($m = n = 2$)

$$\text{In : } C = \text{---} \bullet \text{---} \bullet \text{---} \bullet \text{---} \bullet \text{---}$$

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$$\text{Out: } F = \begin{bmatrix} a_{11} & a_{12} \\ a_{12} & a_{22} \end{bmatrix} \text{ and } G = \begin{bmatrix} b_{11} & b_{12} \\ b_{12} & b_{22} \end{bmatrix}$$

$$\text{Out: } F = \begin{bmatrix} a_{11} & a_{12} \\ a_{12} & a_{22} \end{bmatrix} \text{ and } G = \begin{bmatrix} b_{11} & b_{12} \\ b_{12} & b_{22} \end{bmatrix}$$

such that

$$\text{sign}(D) = \begin{bmatrix} + & - & + \\ + & - & + \\ + & - & 0 \\ 0 & 0 & + \end{bmatrix} \vee \begin{bmatrix} + & - & + \\ 0 & 0 & + \\ - & + & + \\ + & - & + \end{bmatrix} \vee \dots$$

such that

$$\text{sign}(D) = \begin{bmatrix} + & - & + \\ + & - & + \\ + & - & 0 \\ 0 & 0 & + \end{bmatrix} \vee \begin{bmatrix} + & - & + \\ + & + & - \\ - & + & + \\ + & - & - \end{bmatrix} \vee \dots$$

where

$$D = \begin{bmatrix} 1 & -2 & 1 \\ 1 & 2(a_{11} + a_{22} - b_{11} - b_{22}) & 1 \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix} \begin{bmatrix} (a_{11} + a_{22})^2 - 2(a_{11} + a_{22})(b_{11} + b_{22}) + 4(b_{11}b_{22} - b_{12}^2) \\ \vdots \\ \vdots \end{bmatrix}$$

We call

- the sign matrices : **sign-configuration transform**,
- the polynomial matrix D : **configuration discriminant**.

Motivation

- Generalization of Descartes’ rule of sign: from $F = [0]$ to arbitrary F .
- Applications to many problems in science and engineering.
- Fundamental importance: specialized quantifier elimination problem.

Result (signature-based)

Theorem 1 (Signature-based)

Sign-configuration transform

We have

$$\text{sign}(D) = S : C = \bigvee H^{-1} \sigma(S)$$

where

$$V = [\delta_{v(s,+),m-t}]_{t,s}$$

$$H = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}^{\otimes m}$$

$$\sigma(S) = \text{signature of } S$$

Configuration discriminant

We have

$$D = \begin{bmatrix} \text{coeffs } h_{0\dots 0} \\ \text{coeffs } h_{0\dots 1} \\ \vdots \\ \text{coeffs } h_{1\dots 1} \end{bmatrix}$$

where

$$h_e = \text{charpoly}(f_e(G))$$

$$f_e = f^{(0)^{e_0}} \dots f^{(m-1)^{e_{m-1}}}$$

$$f = \text{charpoly}(F)$$

Example ($m = n = 2$)

Sign-configuration transform

$$C = \text{---} \bullet \text{---} \bullet \text{---} \bullet \text{---} \bullet \text{---}$$

\Uparrow encoding

$$C = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

\Uparrow

$$C = V H^{-1} \sigma(S)$$

$$\sigma(S) = [4 \ 4 \ 1 \ 2]^T$$

\Uparrow signature

$$S = \begin{bmatrix} + & - & + \\ + & - & + \\ + & - & 0 \\ 0 & 0 & + \end{bmatrix}$$

Configuration discriminant

$$f = (x - \alpha_{11})(x - \alpha_{22}) + \alpha_{12}^2$$

\Downarrow

$$f_{01} = f^{(0)^0} f^{(1)^1} = 2x - a_{11} - a_{22}$$

\Downarrow

$$f_{01}(G) = \begin{bmatrix} -a_{22} - a_{11} + 2b_{11} & 2b_{1,2} \\ 2b_{12} & -a_{22} - a_{11} + 2b_{22} \end{bmatrix}$$

\Downarrow

$$\text{coeffs } h_{01} = \begin{bmatrix} 1 \\ 2(a_{11} + a_{22} - b_{11} - b_{22}) \\ (a_{11} + a_{22})^2 - 2(a_{11} + a_{22})(b_{11} + b_{22}) + 4(b_{11}b_{22} - b_{12}^2) \end{bmatrix}^T$$

Result (symmetric functions-based)

Theorem 2 (Symmetric functions-based)

Sign-configuration transform

We have

$$\text{sign}(D) = S : C = \bigvee T_m^{-1} v(S)$$

where

$$(T_m)_{rs} = (-2)^{r-1} \binom{m-s}{r-s} \binom{s}{r}$$

Configuration discriminant

We have

$$D = \begin{bmatrix} \text{coeffs } p_1 \\ \vdots \\ \text{coeffs } p_m \end{bmatrix}$$

where

$$p_r(a_{ij}, b_{ij}) = \prod_{(i,j) \in Y_r} \left(-x - \prod_{p=1}^r (\alpha_{i_p} - \beta_{j_p}) \right)$$

$$Y_r = \{(i, j) : i_1 < \dots < i_r\}$$

Comparison

	Signature	Symmetric	Descartes
Size of D	$(2^m - 1) \cdot n$	$(2^m - 1) \cdot n$	n

- The size of the configuration discriminant of each approach is the same: $(2^m - 1) \cdot n$
- The above two methods are asymmetric with regard to the sizes of F and G
 - If size of F is fixed, size of discriminant is linear in n
 - In practice, let F be the smaller matrix
- Descartes’ rule of signs is for the special case

$$F = [0] \in \mathbb{R}^{1 \times 1} \text{ and } G \in \mathbb{R}^{n \times n}.$$

Setting $m = 1$, the size of the discriminant D for both approaches is $(2^1 - 1) \cdot n = n$

Future Work

- The outputs of Theorems 1 and 2 grow quickly with m and n . Try to prune the outputs (by removing redundancies, logical inconsistencies, etc.)
- Extend to more than 2 real symmetric matrices
- Extend to matrices with arbitrary eigenvalues

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