



Neural Density Estimation

Introduction into Normalising Flows and Masked Autoregressive Flow

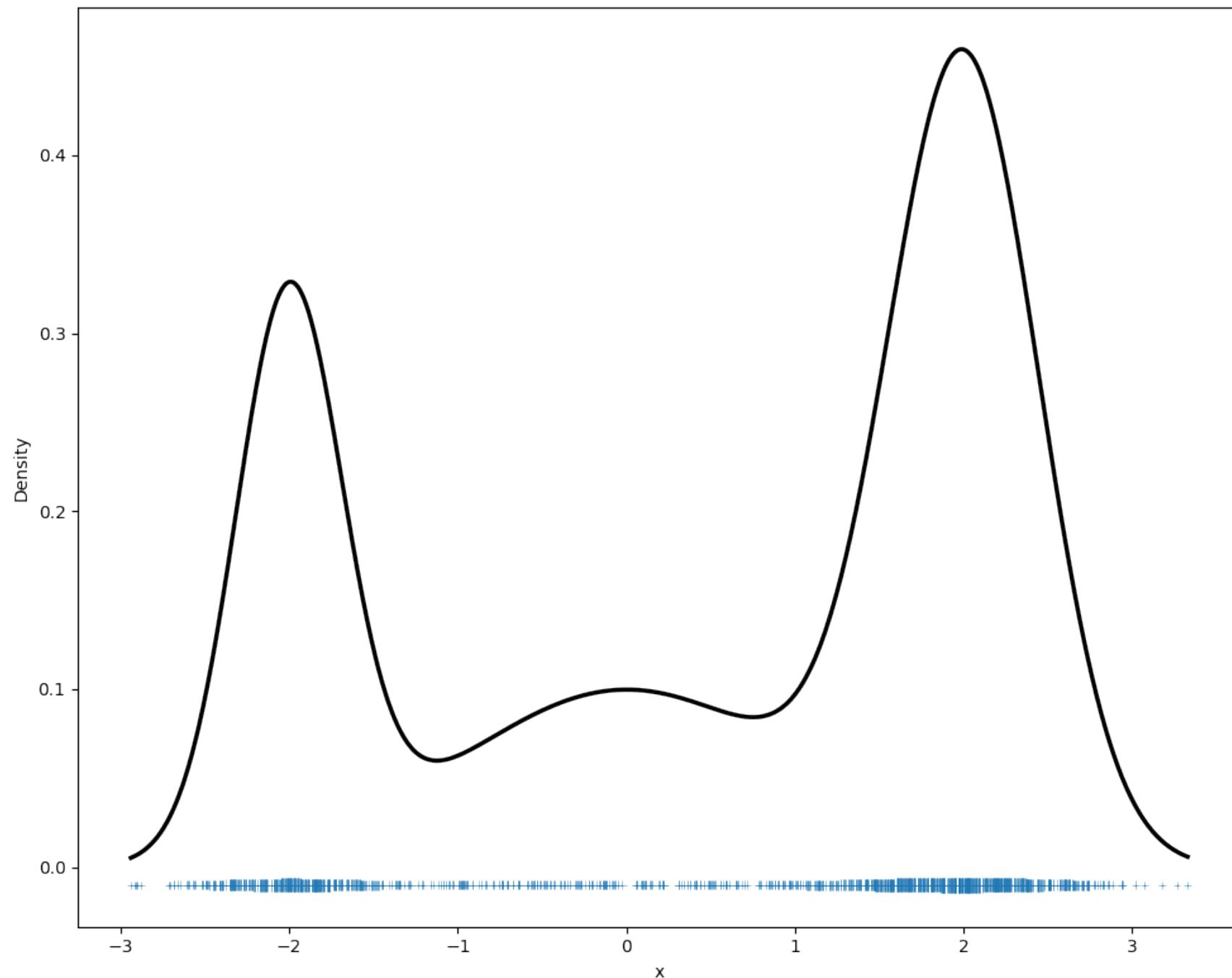
Daniel Decker

University of Rostock

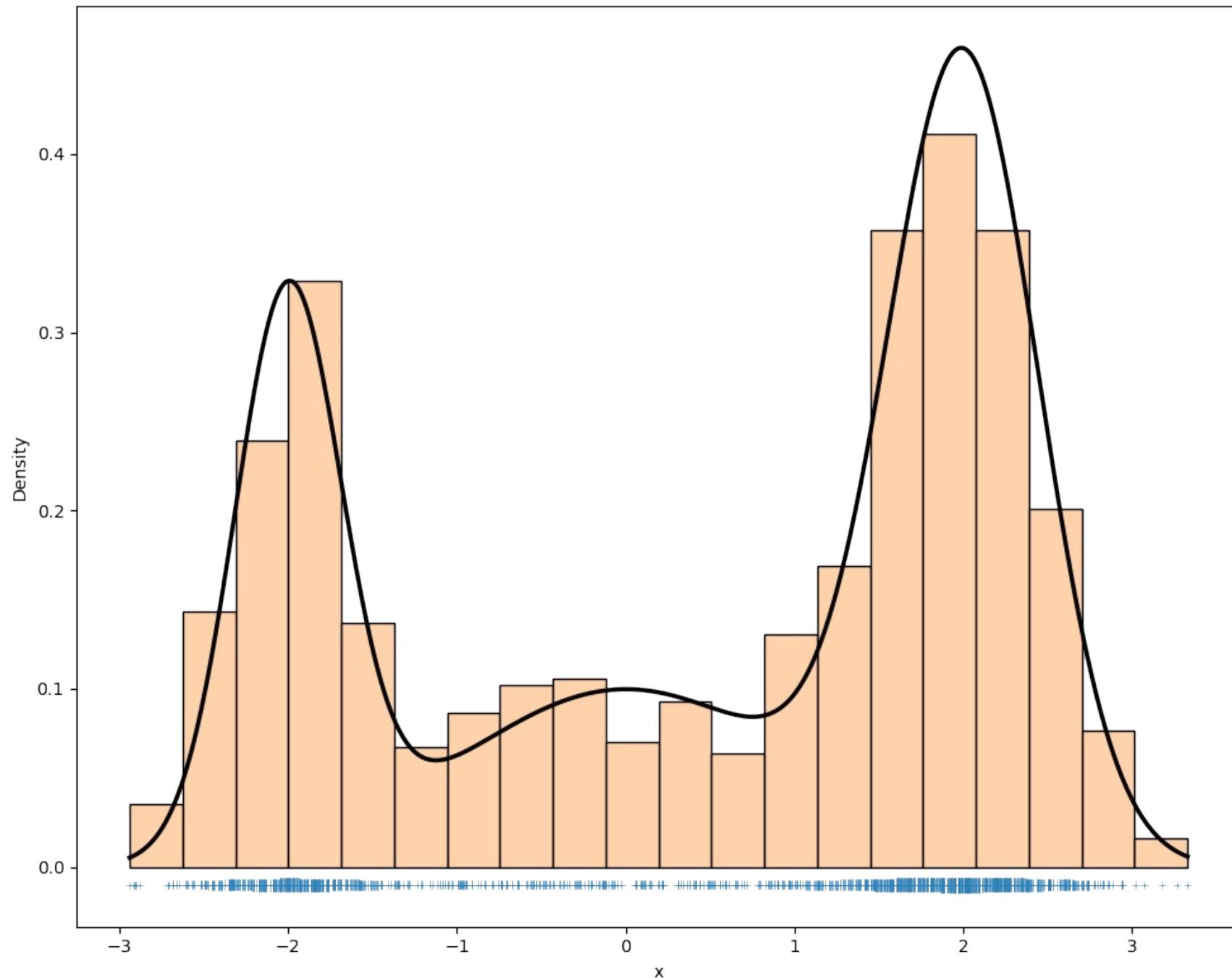
- Density Estimation & Masked Autoregressive Flows
- Evaluation of Masked Autoregressive Flow:
 - Density Estimation with artificial distributions
 - Sampling quality with a real world dataset

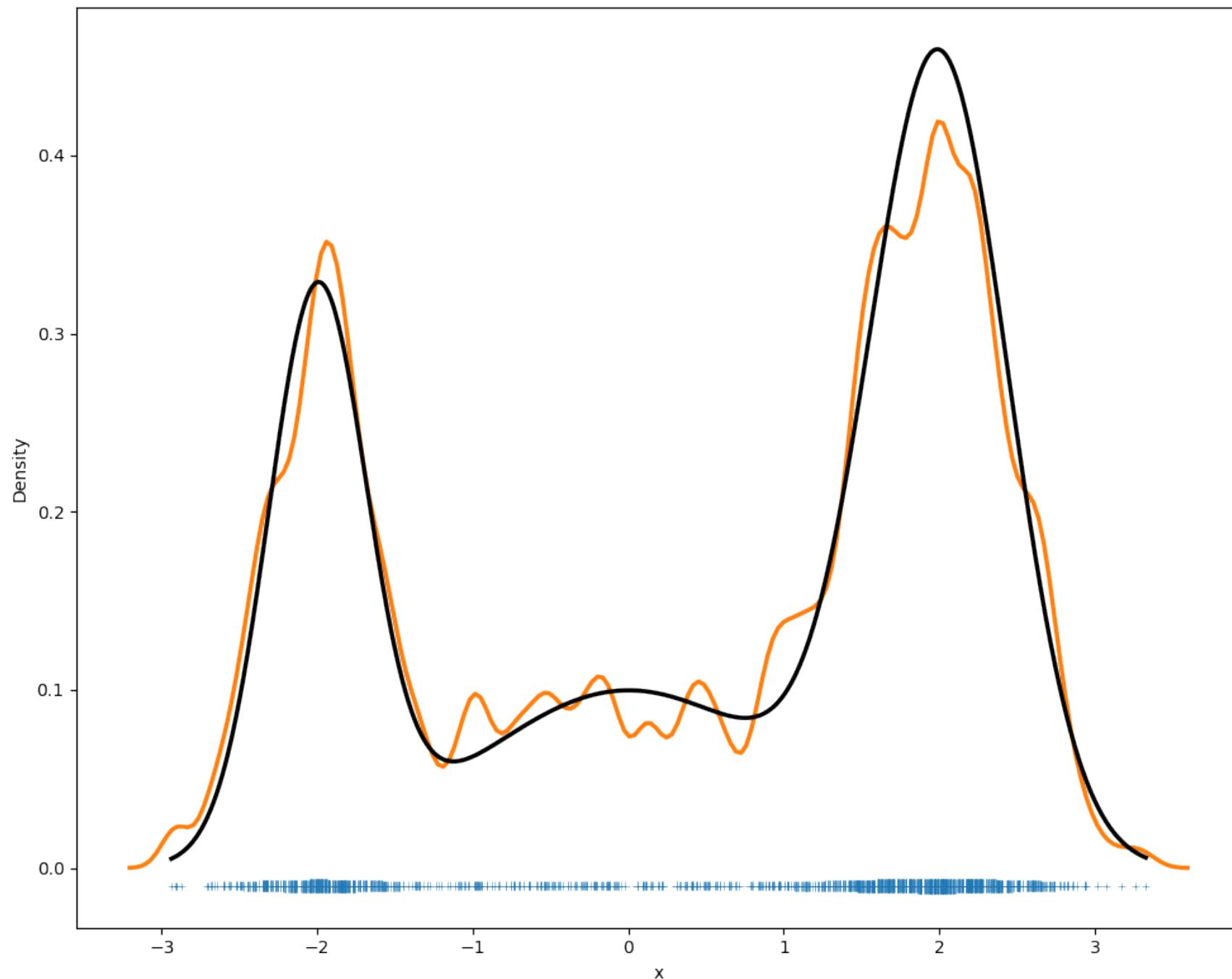


Intro: Density Estimation

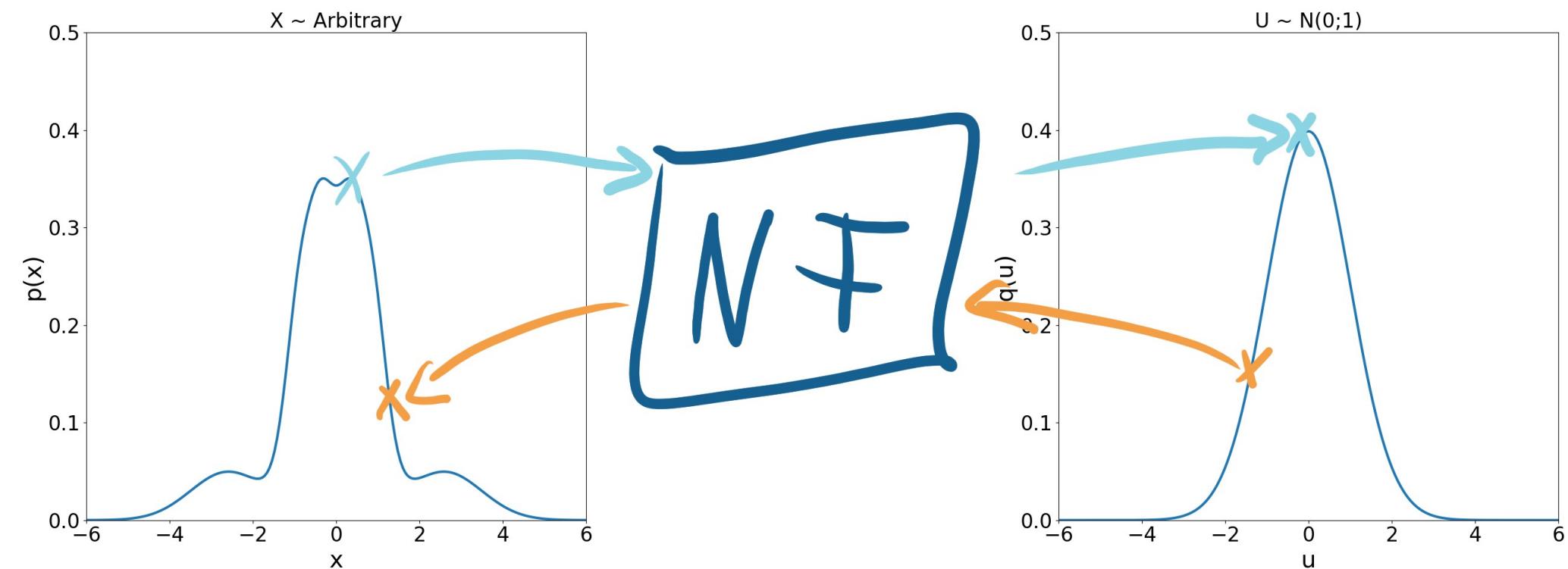


Intro: Density Estimation - Histogram

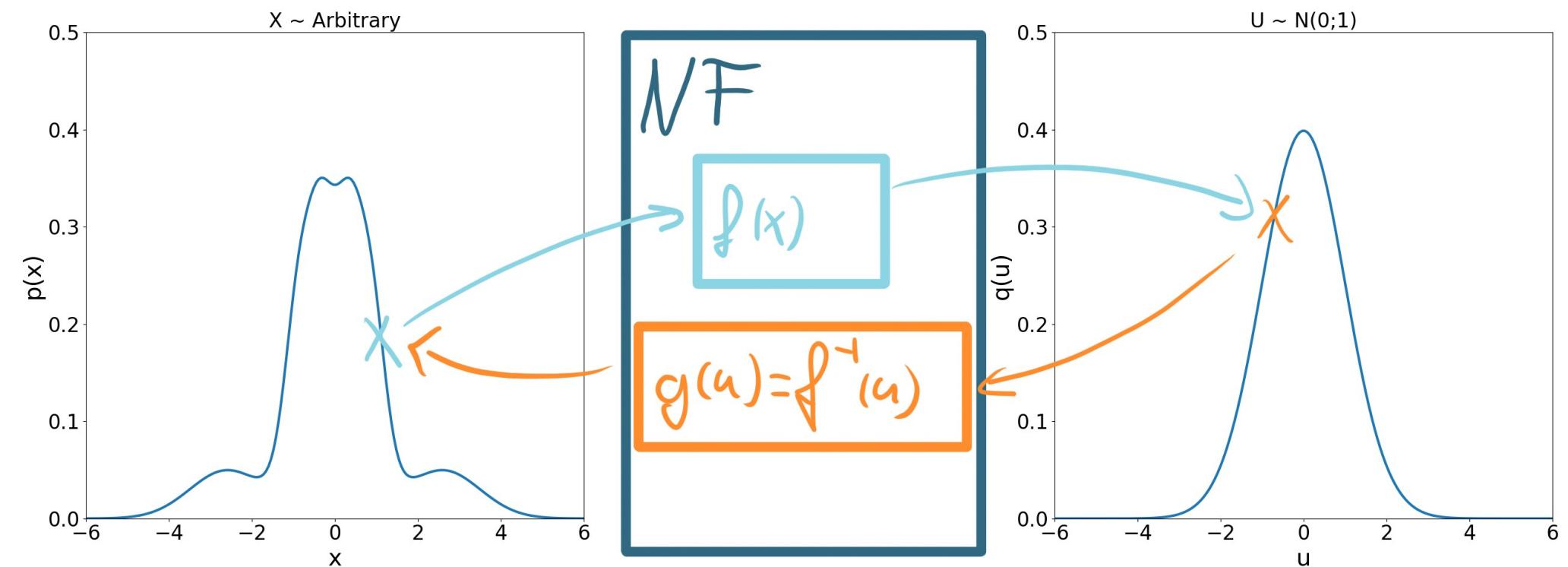




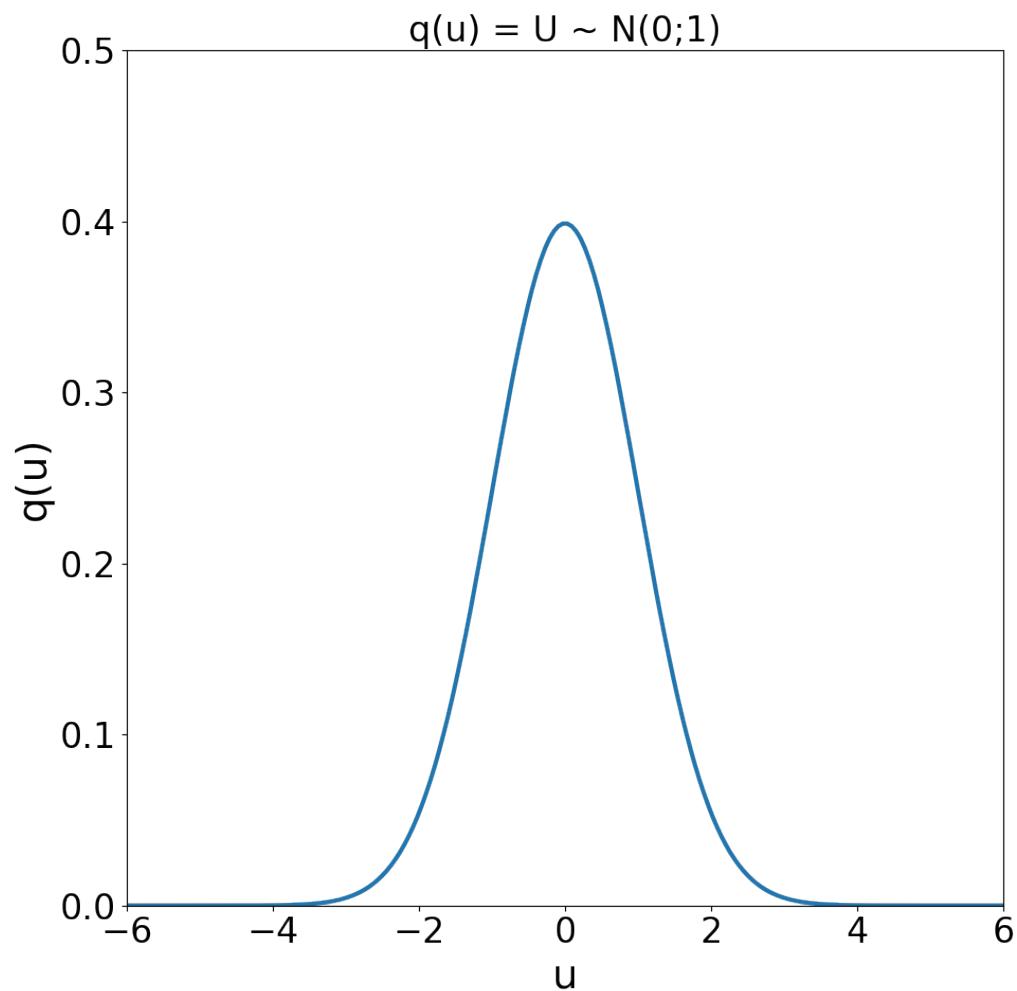
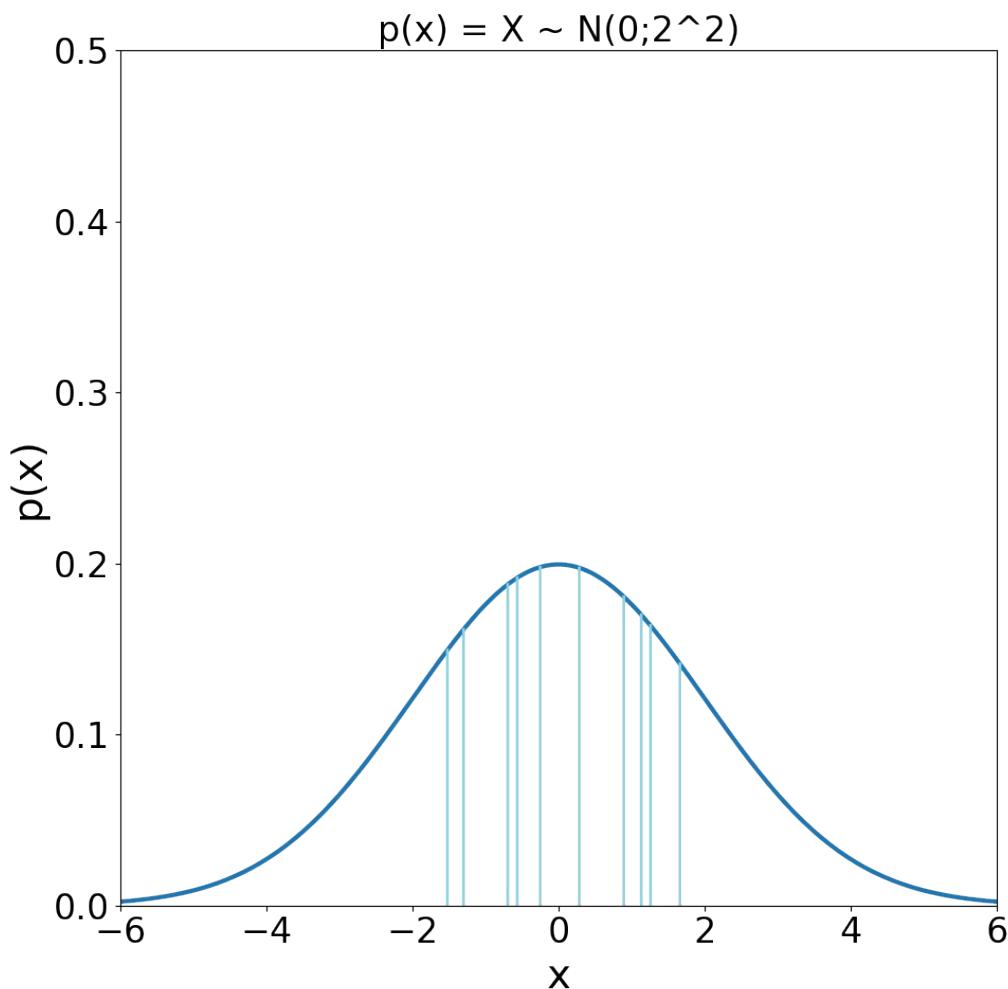
Intro: Normalising Flows



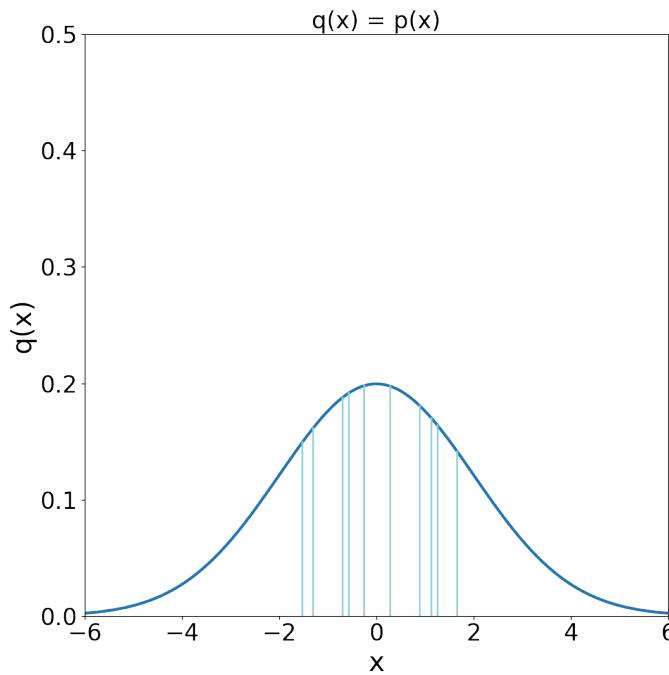
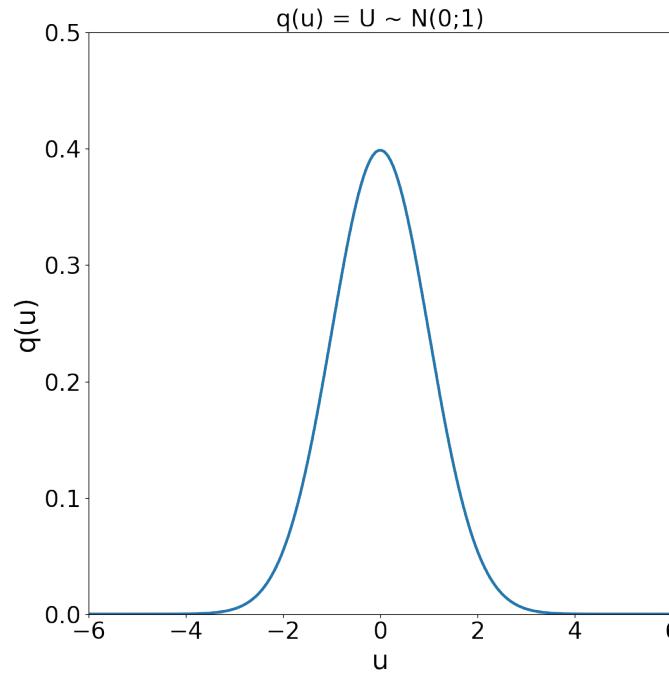
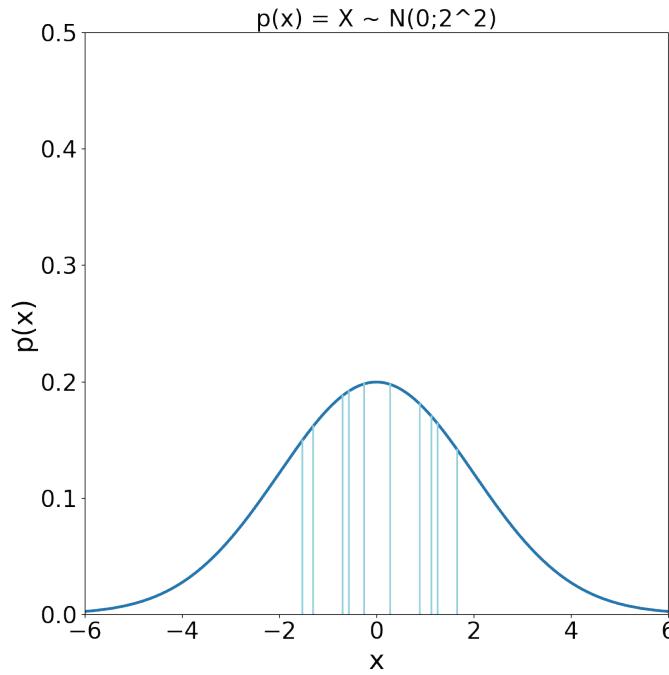
Intro: Normalising Flows



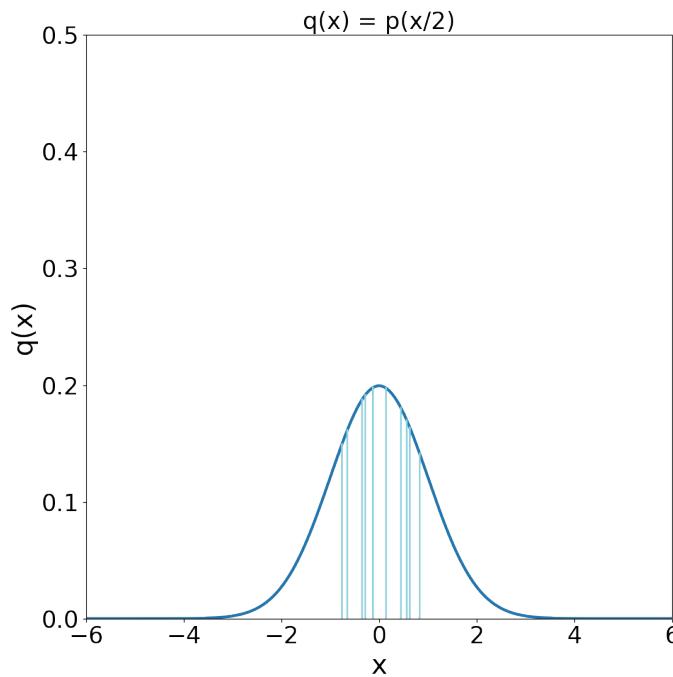
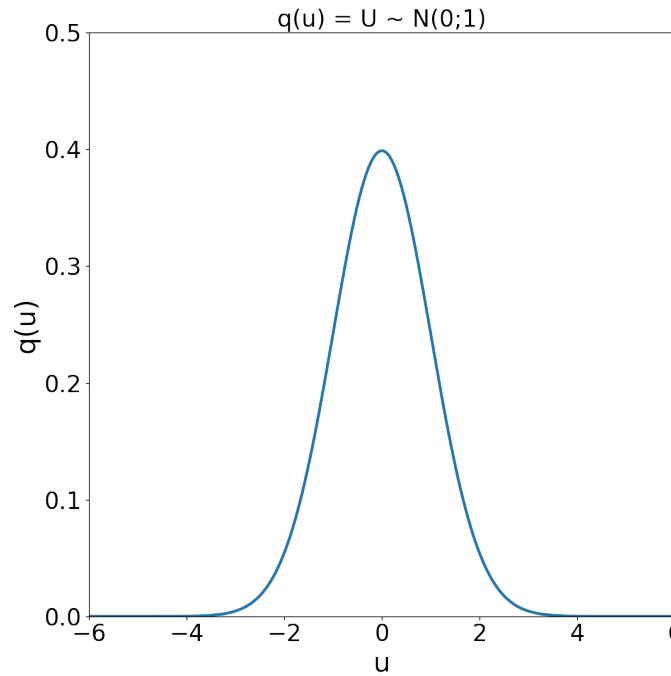
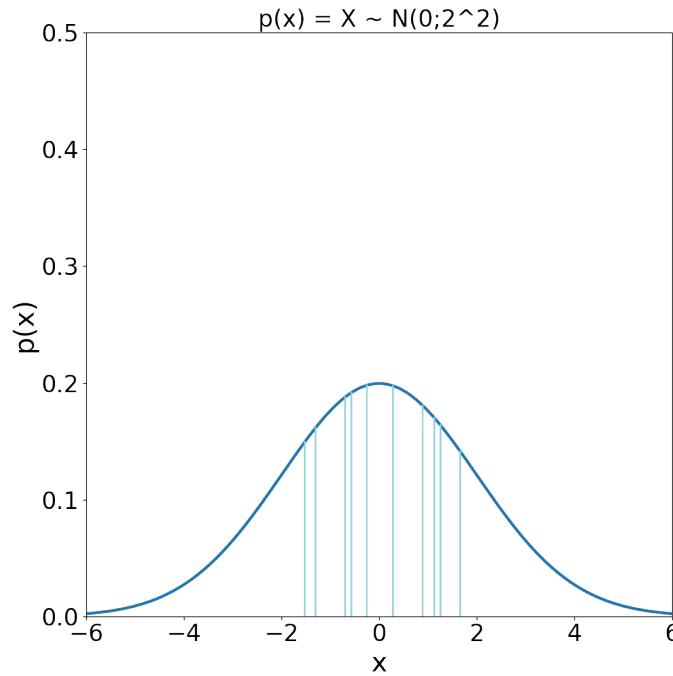
Intro: 1D Transformation



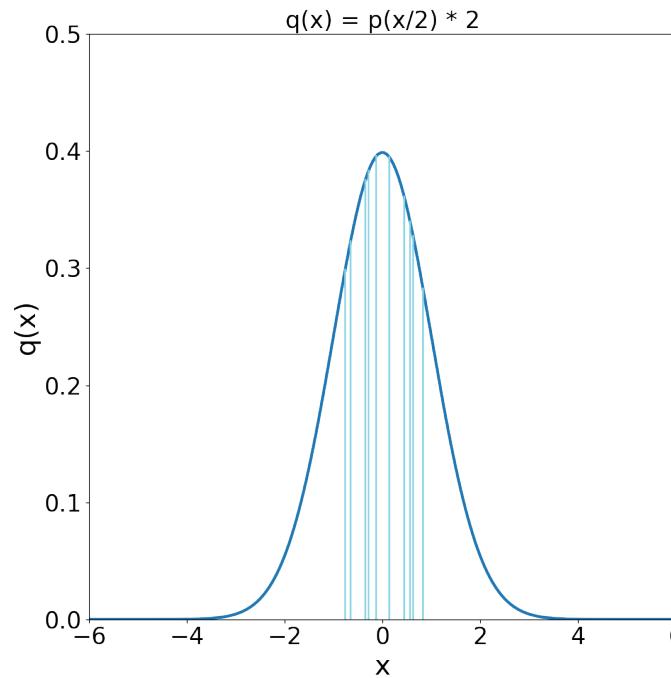
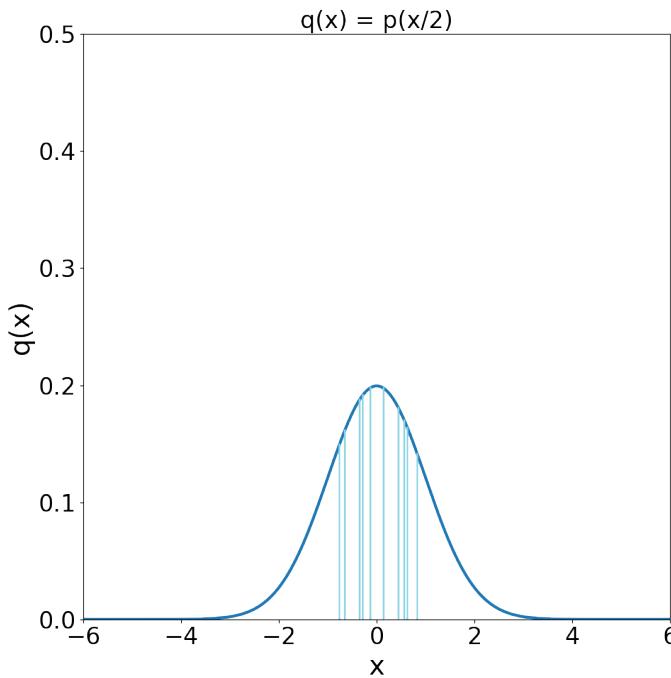
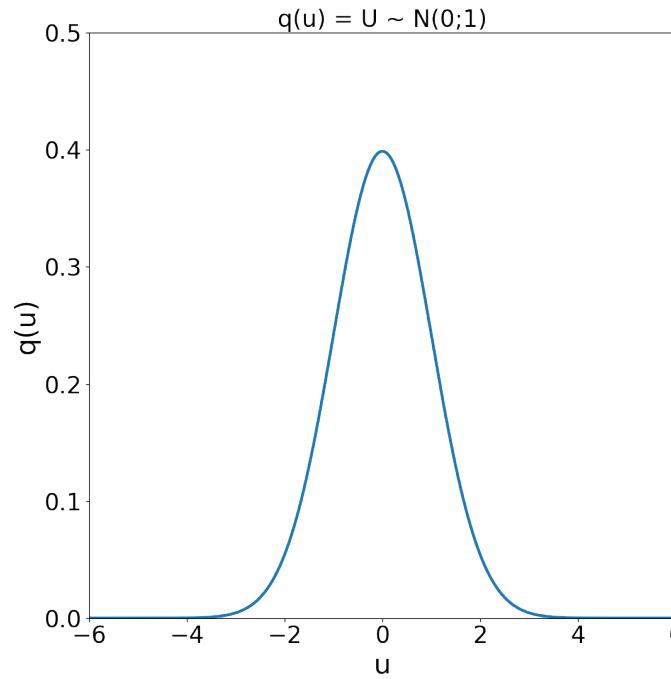
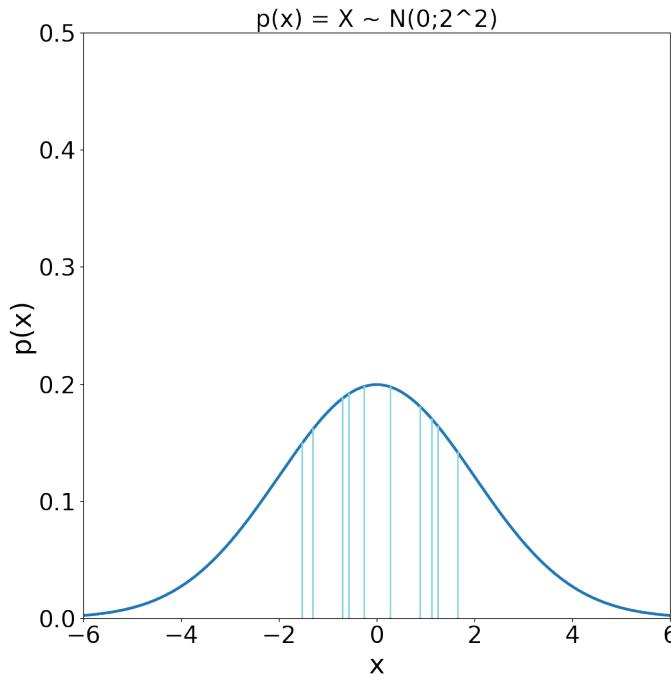
Intro: 1D Transformation



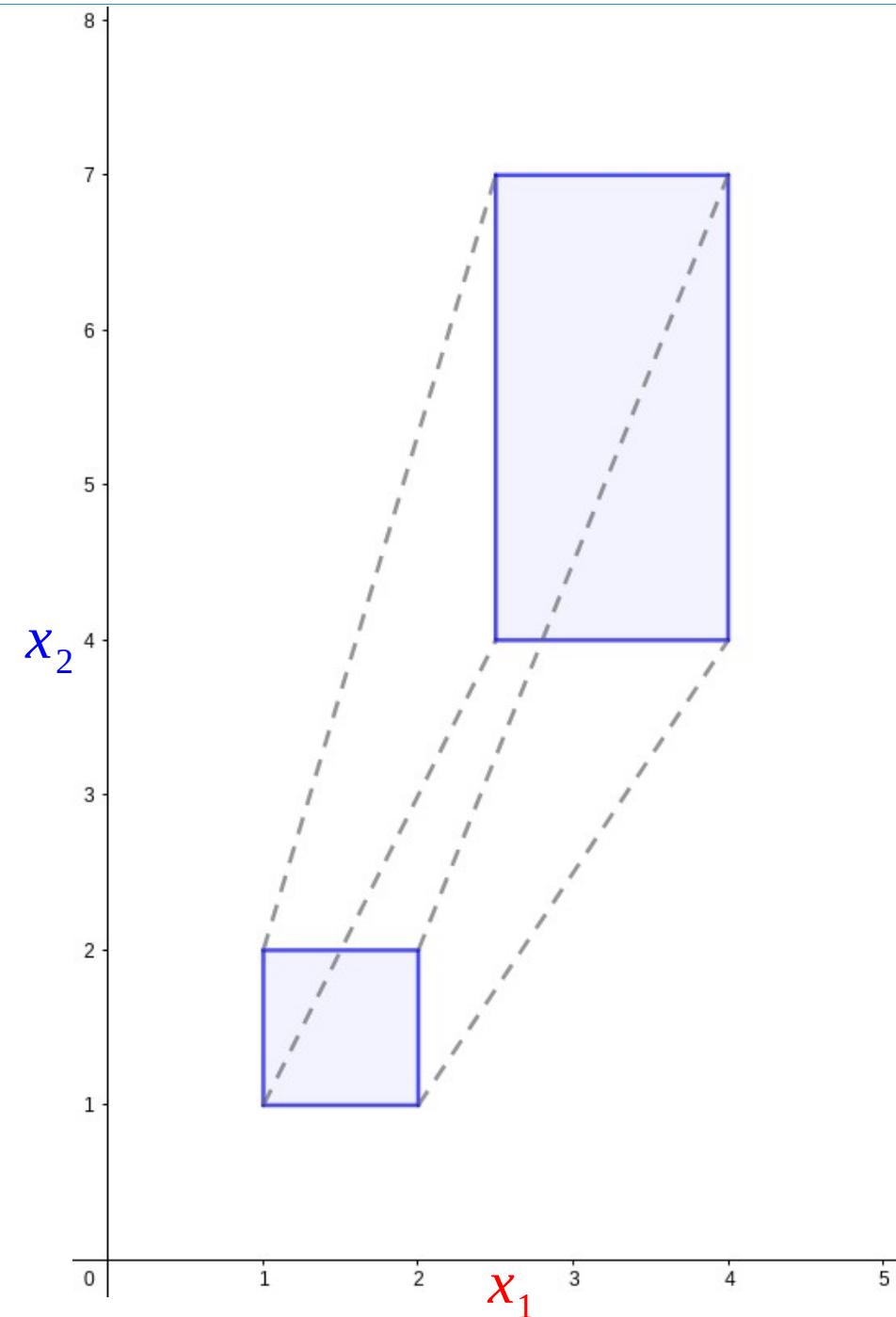
Intro: 1D Transformation



Intro: 1D Transformation



Intro: Jacobian Matrix and Determinant



$$f(x) = \begin{aligned} f_1(x_1) &= \frac{3}{2}x_1 + 1 \\ f_2(x_2) &= 3x_2 + 1 \end{aligned}$$

$$\text{Jacobian}(f(x)) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} \end{bmatrix}$$

$$\text{Jacobian}(f(x)) = \begin{bmatrix} \frac{3}{2} & 0 \\ 0 & 3 \end{bmatrix}$$

$$\det \text{Jacobian}(f(x)) = \frac{9}{2}$$

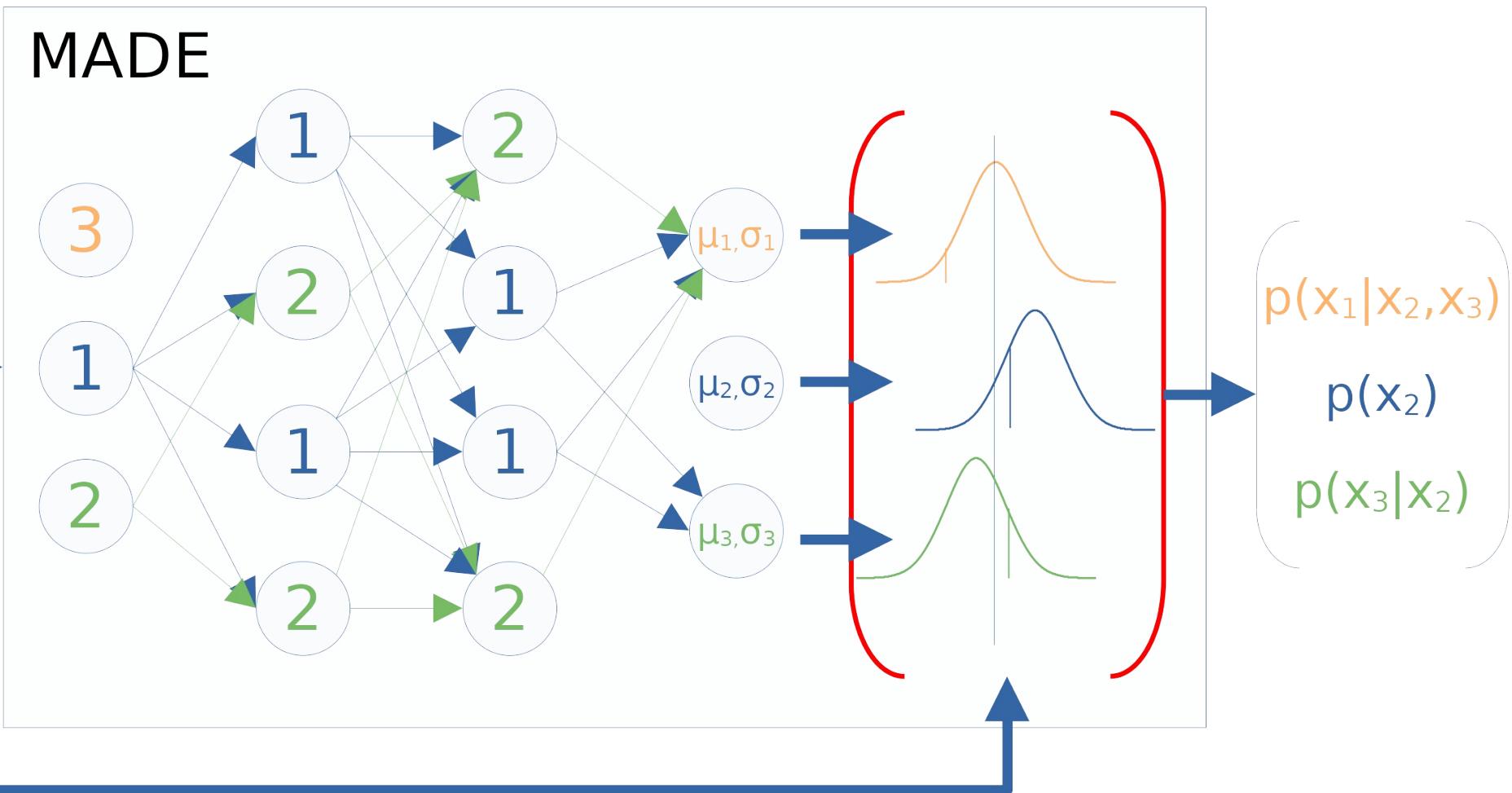
- Normalising Flow formula:

$$p(\mathbf{x}) = q(f(\mathbf{x})) \left| \det\left(\frac{\partial f}{\partial \mathbf{x}}\right) \right|$$

- Optimisation target: maximum likelihood
- Deep models can be build
- Deep models have increased expressiveness

Intro: Autoregression

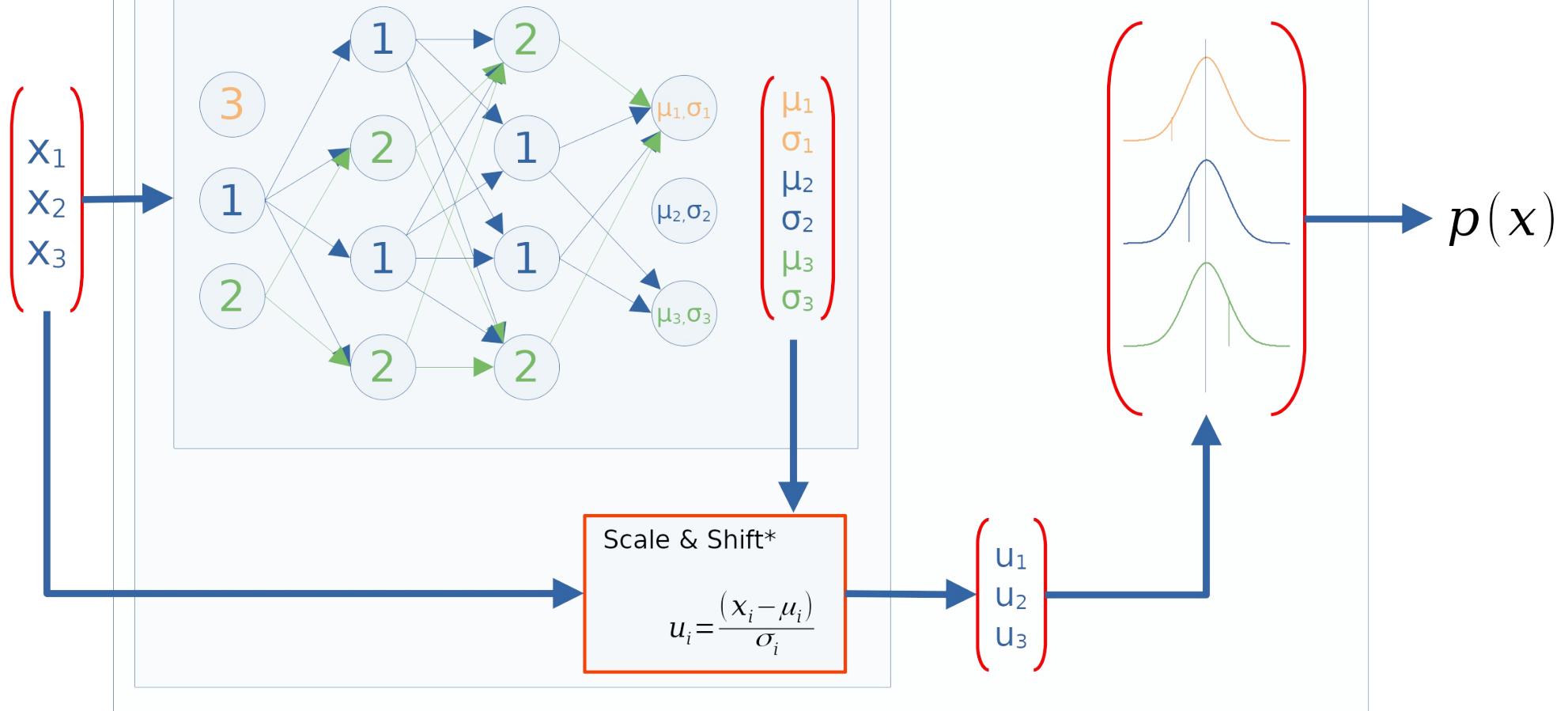
$$p(\mathbf{x}) = \prod_1^D p(x_i | \mathbf{x}_{1:i})$$



Masked Autoregressive Flow - 1 layer

MAF1

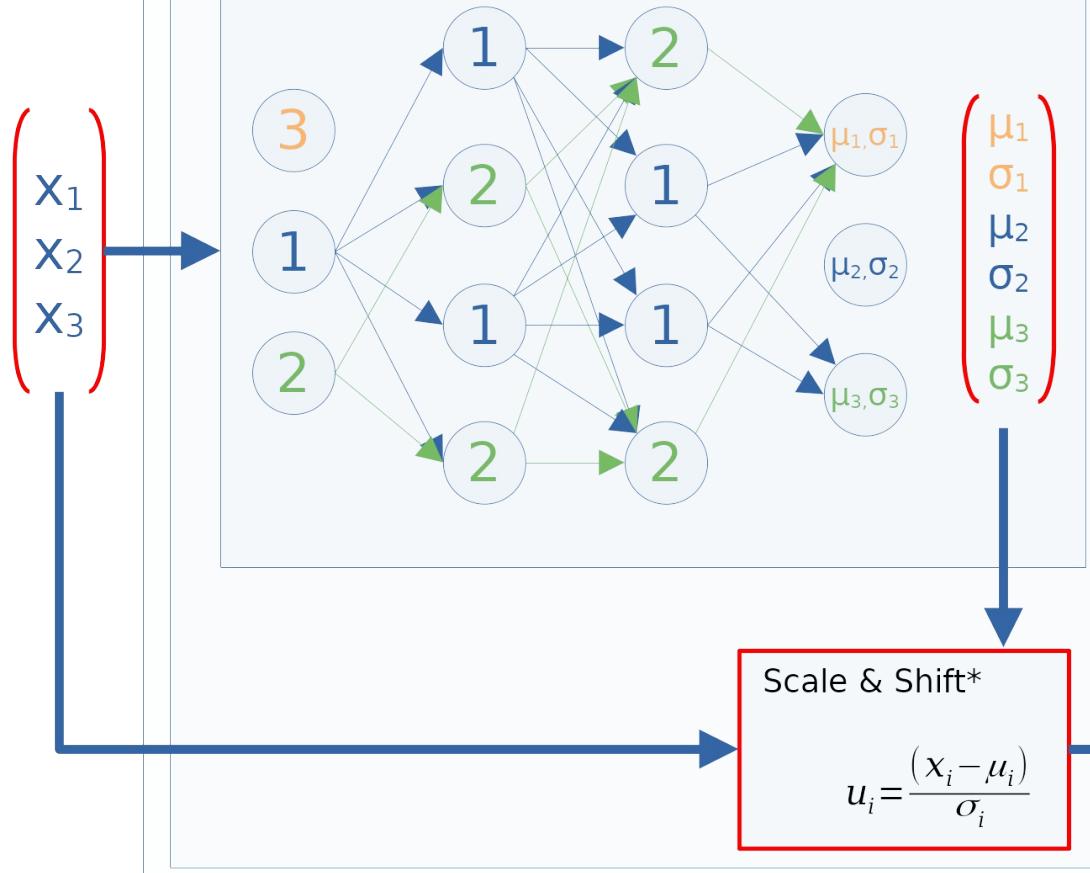
MADE



Masked Autoregressive Flow - 2 layers

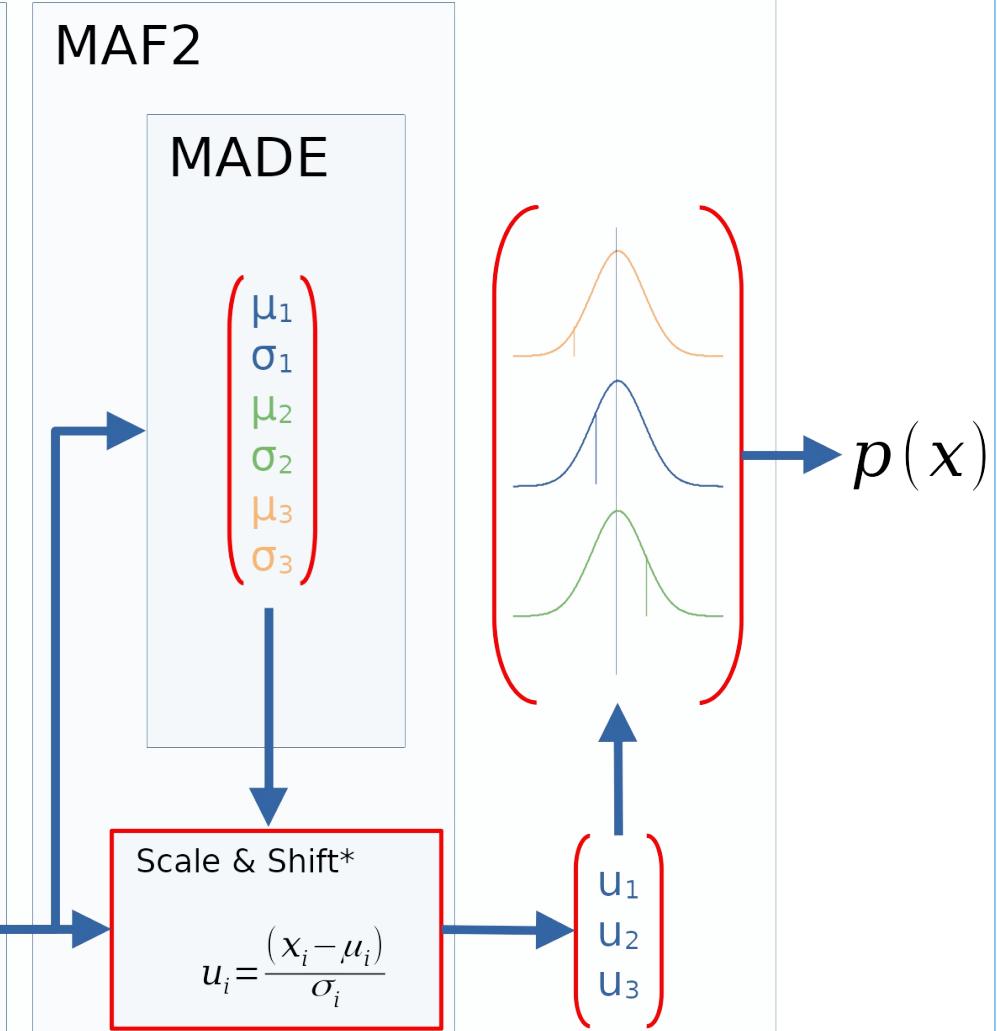
MAF1

MADE



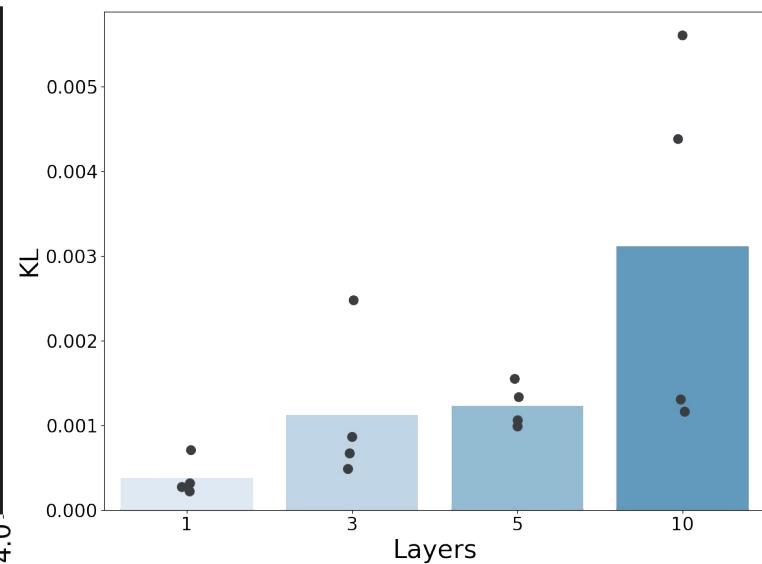
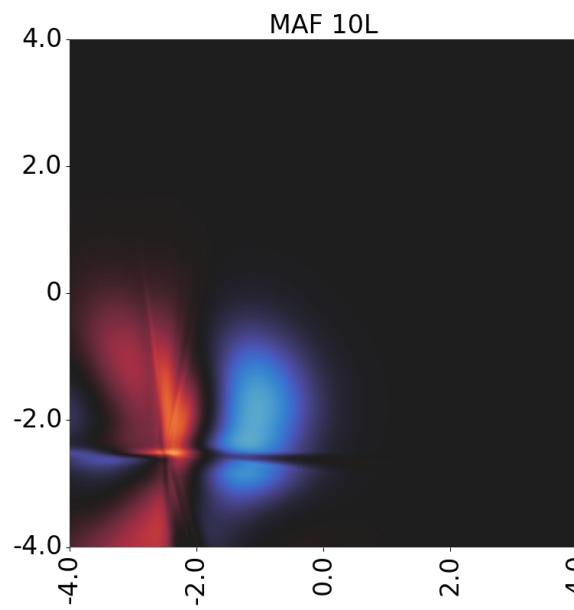
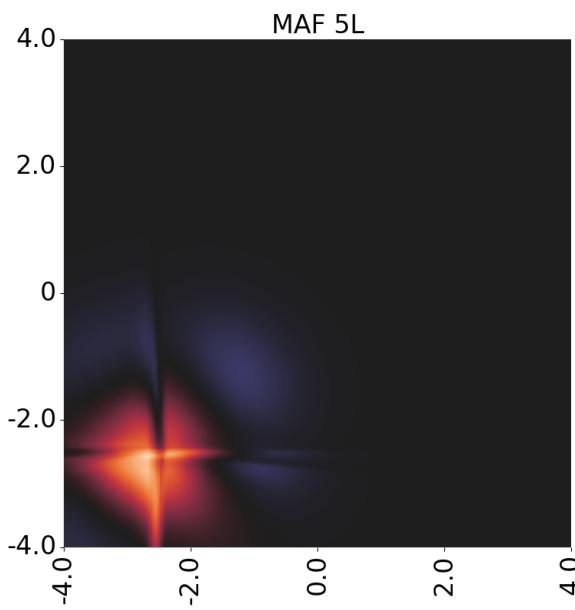
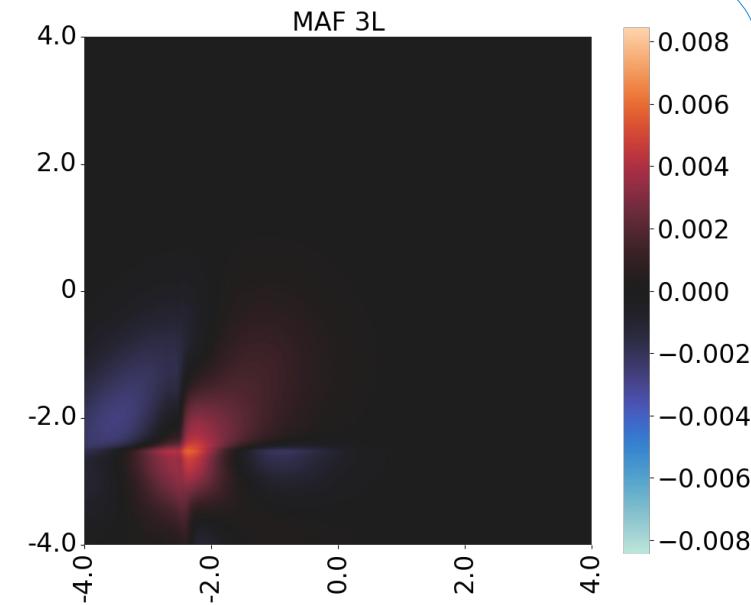
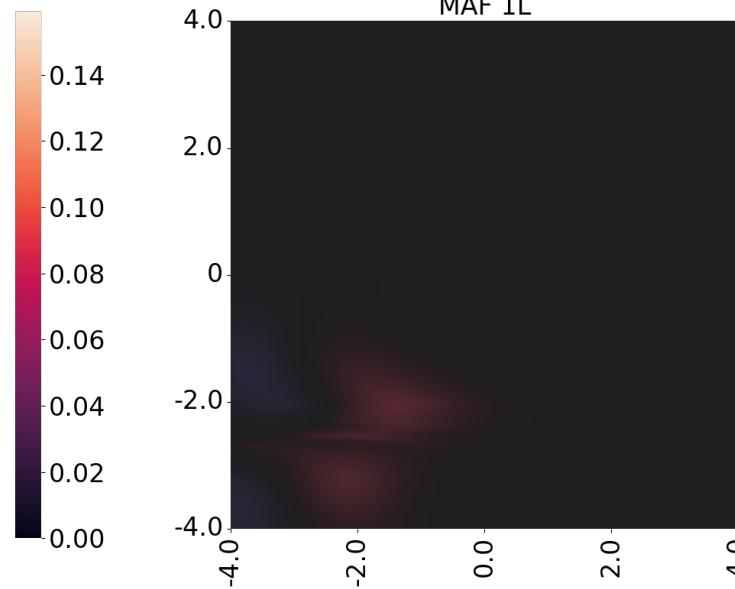
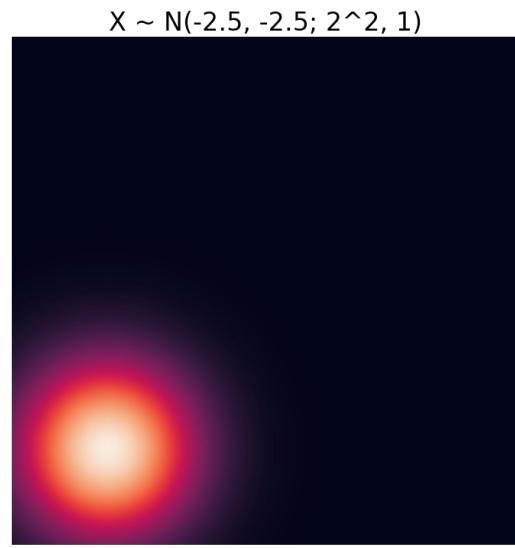
MAF2

MADE



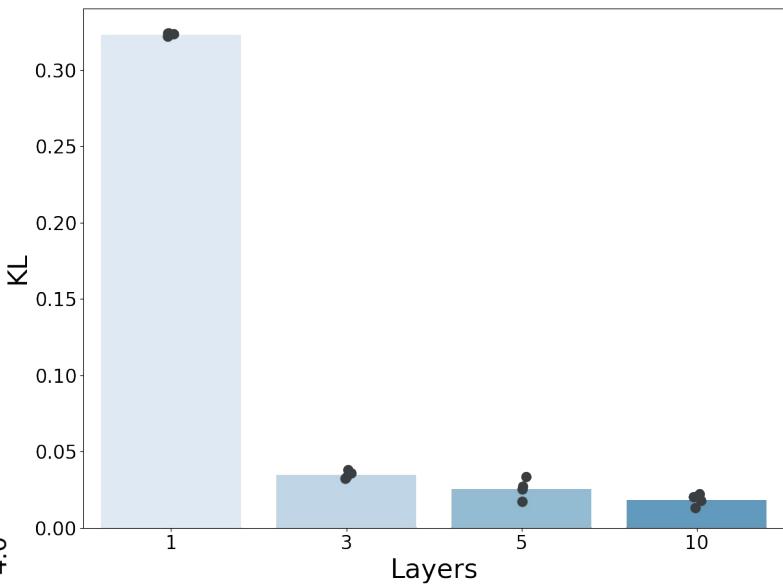
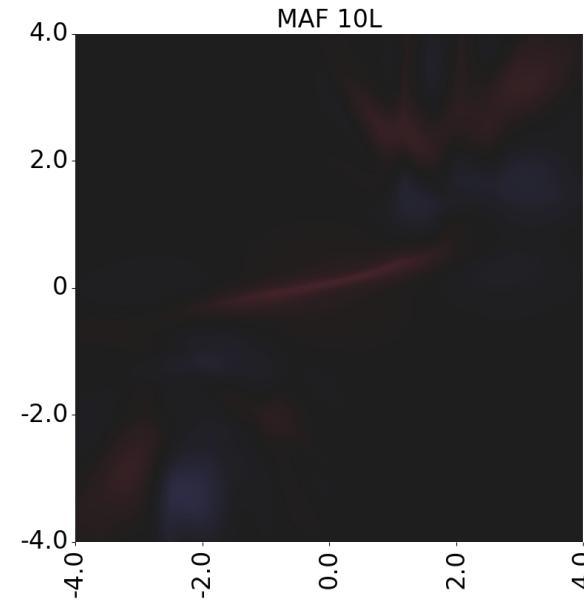
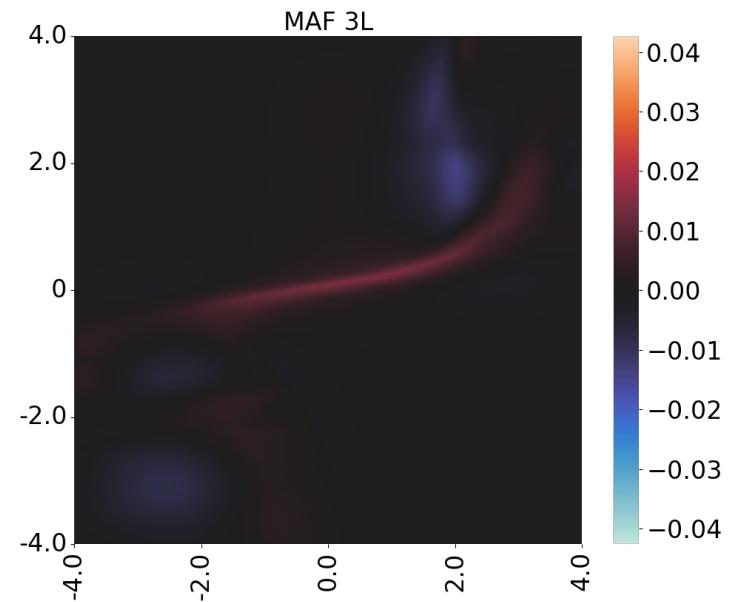
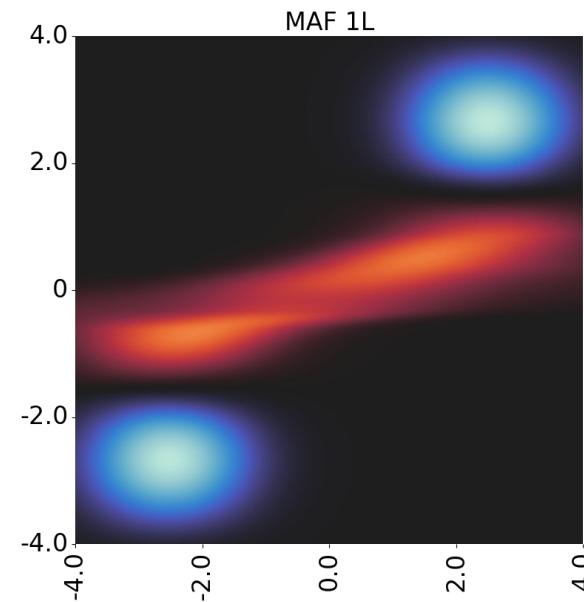
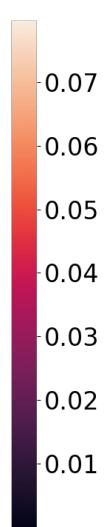
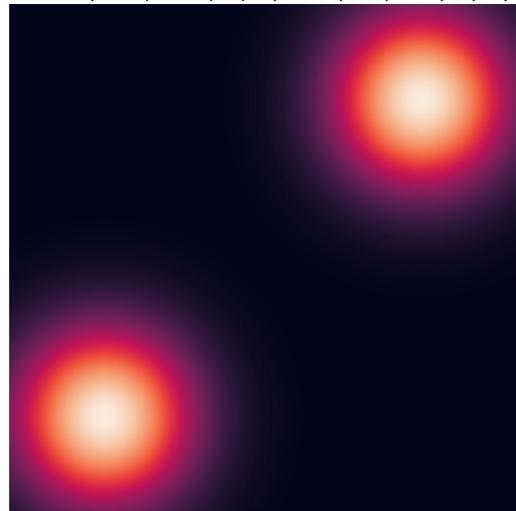
- Density Estimation with artificial distributions
 - Measure: KL-divergence
 - Experiments:
 - Lower dimensions (2D)
 - Higher dimensions (10D)
- Sampling quality with a real world dataset
 - Measure: Accuracy of trained classifiers
 - Experiment:
 - High dimensional (50D)

Density Estimation - 2D: 1 Gaussian

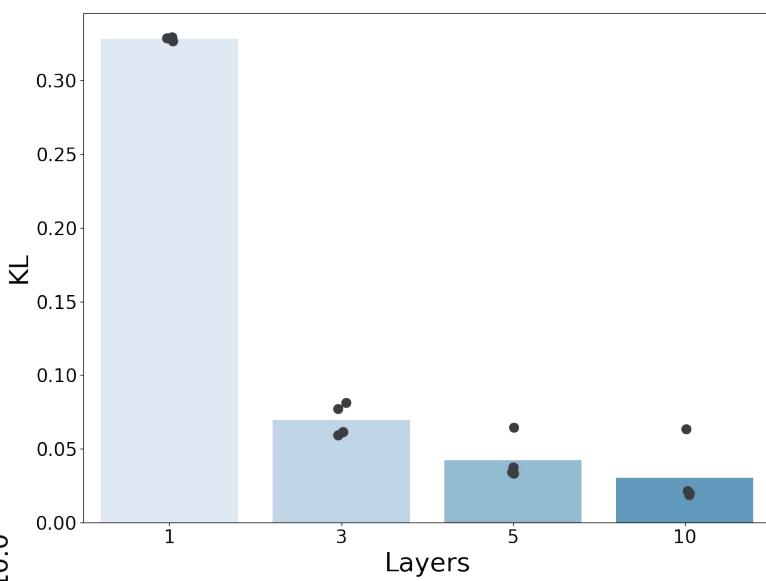
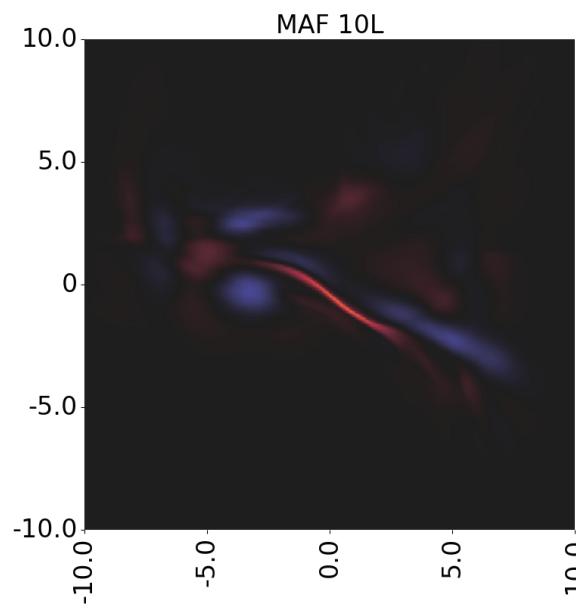
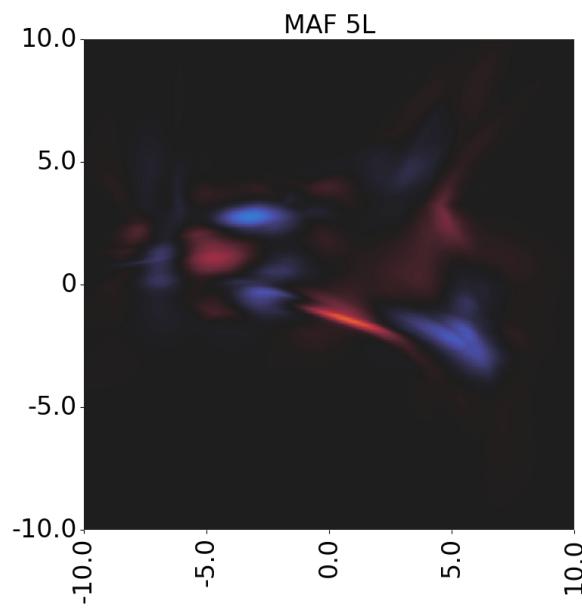
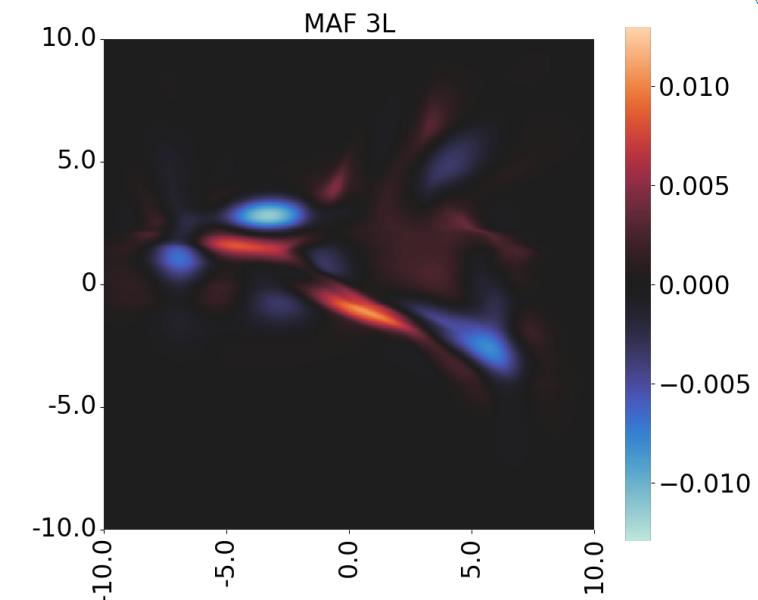
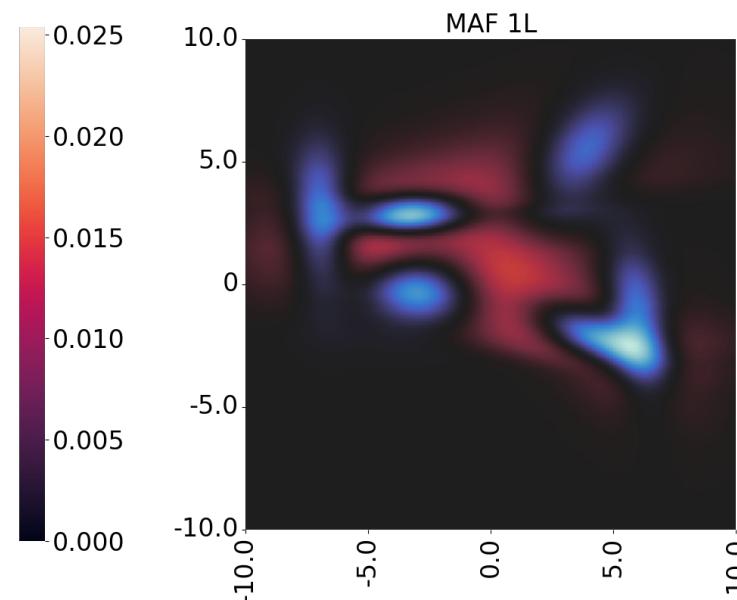
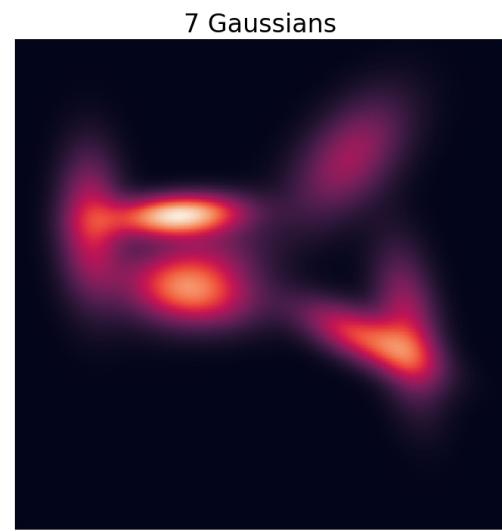


Density Estimation - 2D: 2 Gaussians

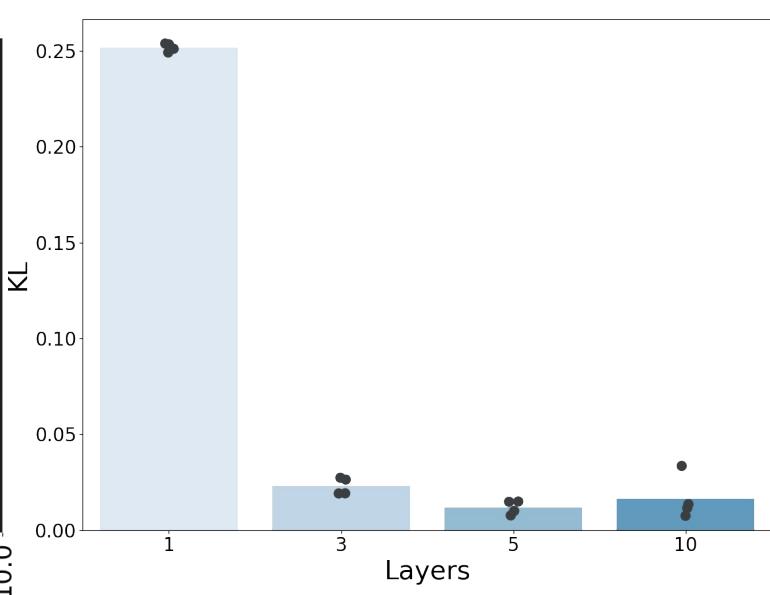
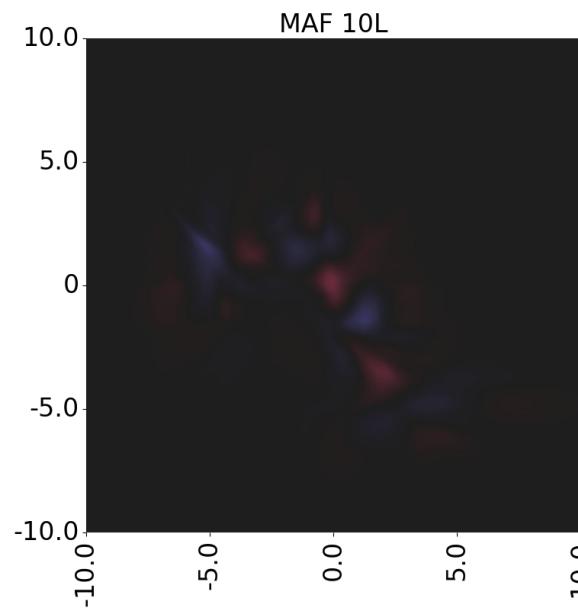
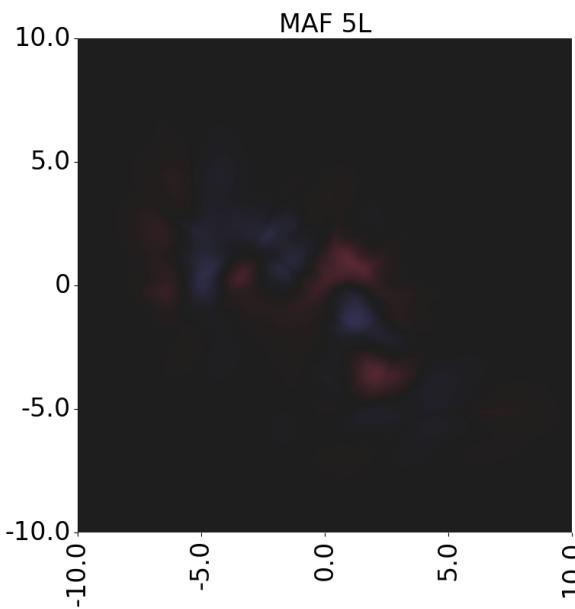
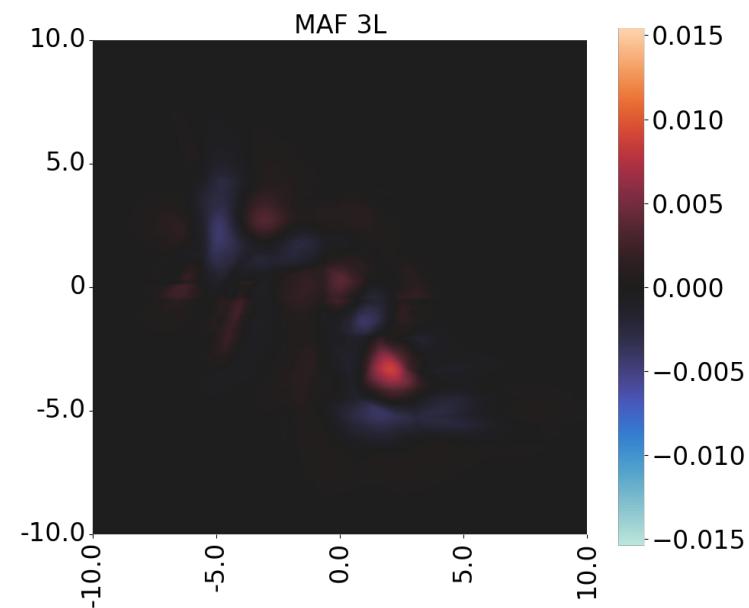
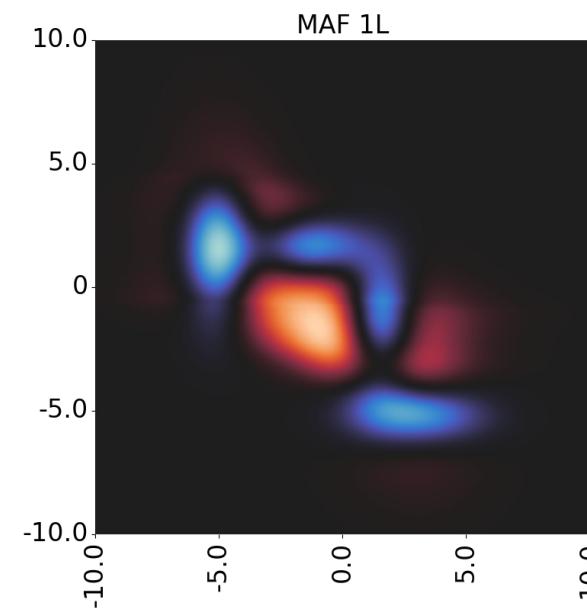
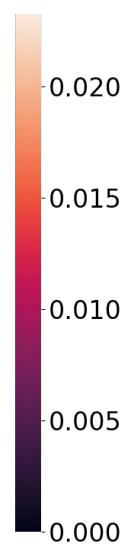
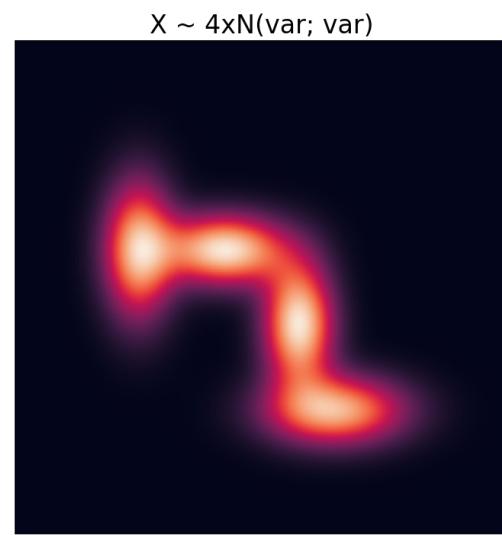
$X \sim N(-2.5, -2.5; 1, 1) \text{ & } N(2.5, 2.5; 1, 1)$



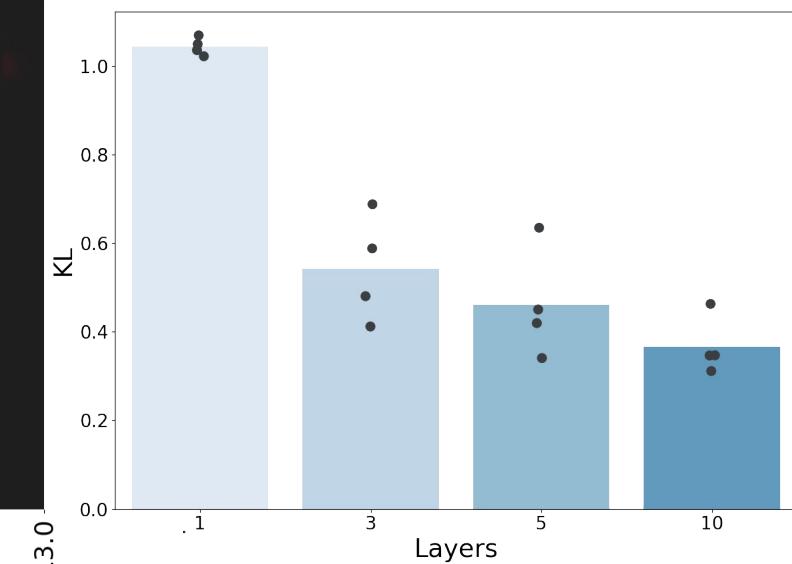
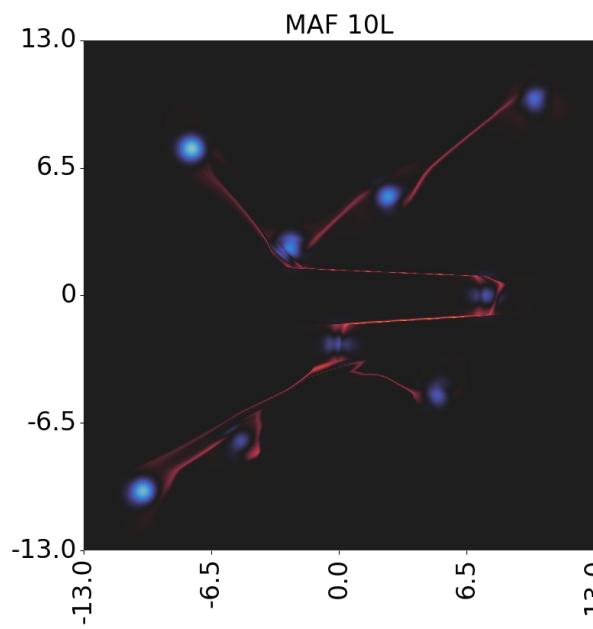
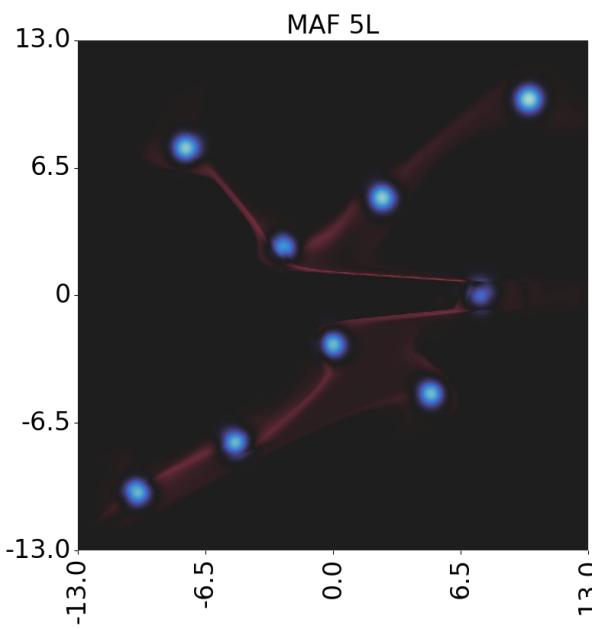
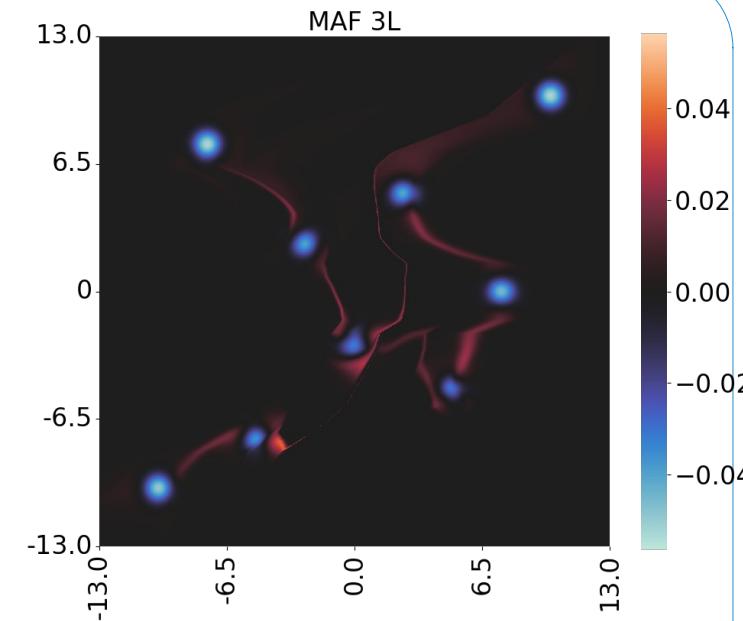
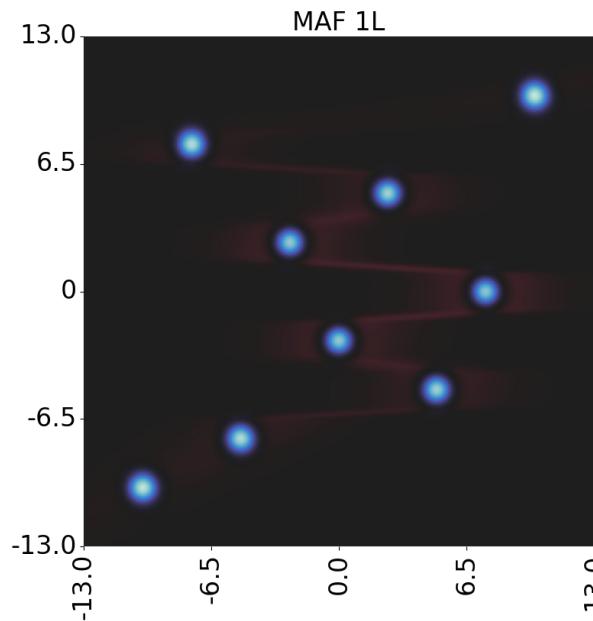
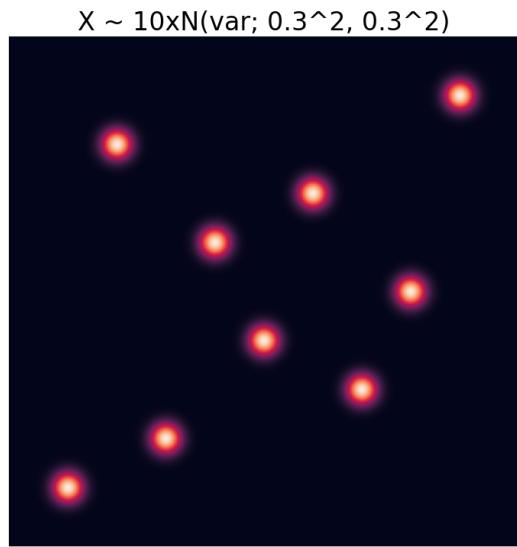
Density Estimation – 2D: 7 Gaussians

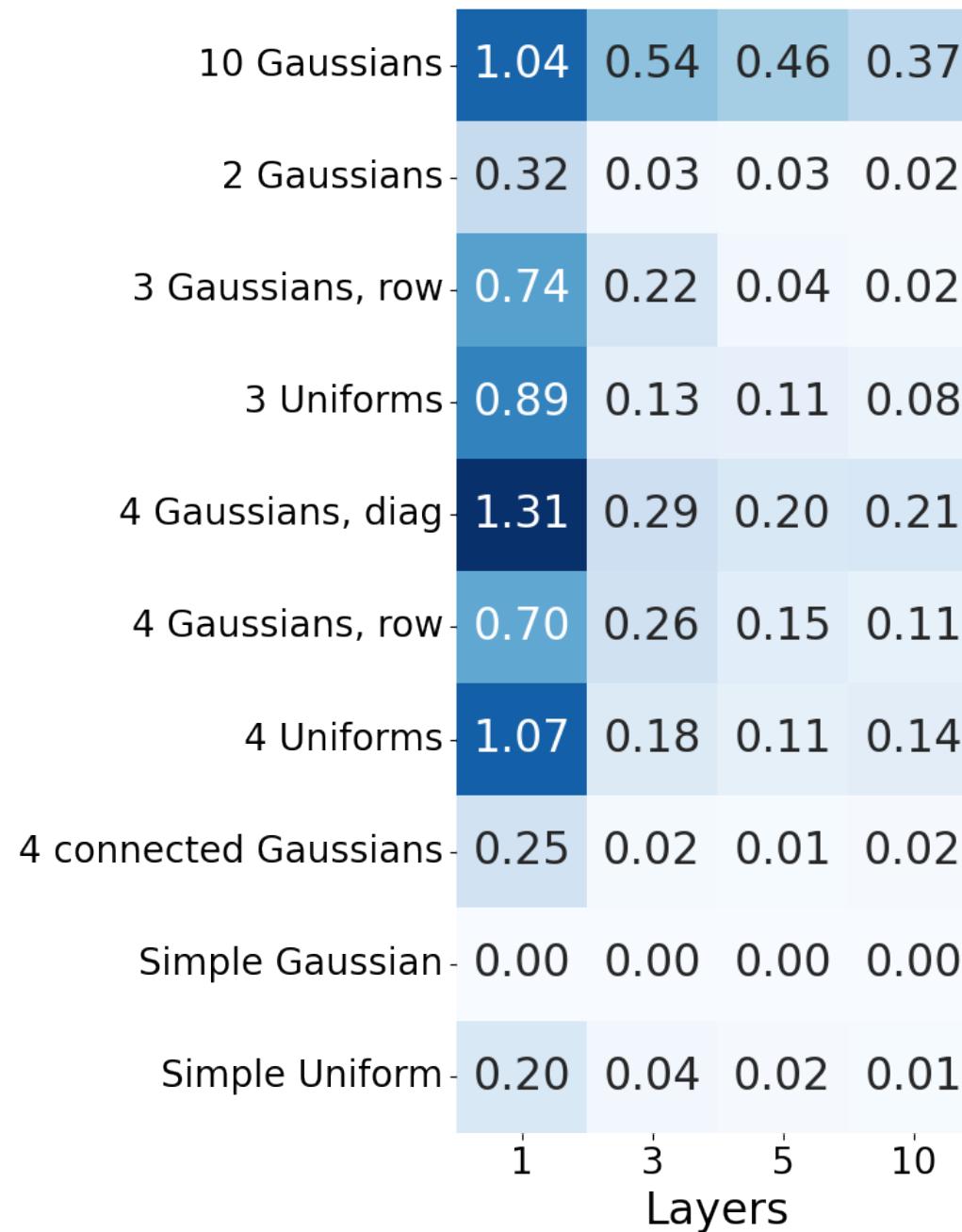


Density Estimation - 2D: 4 Gaussians

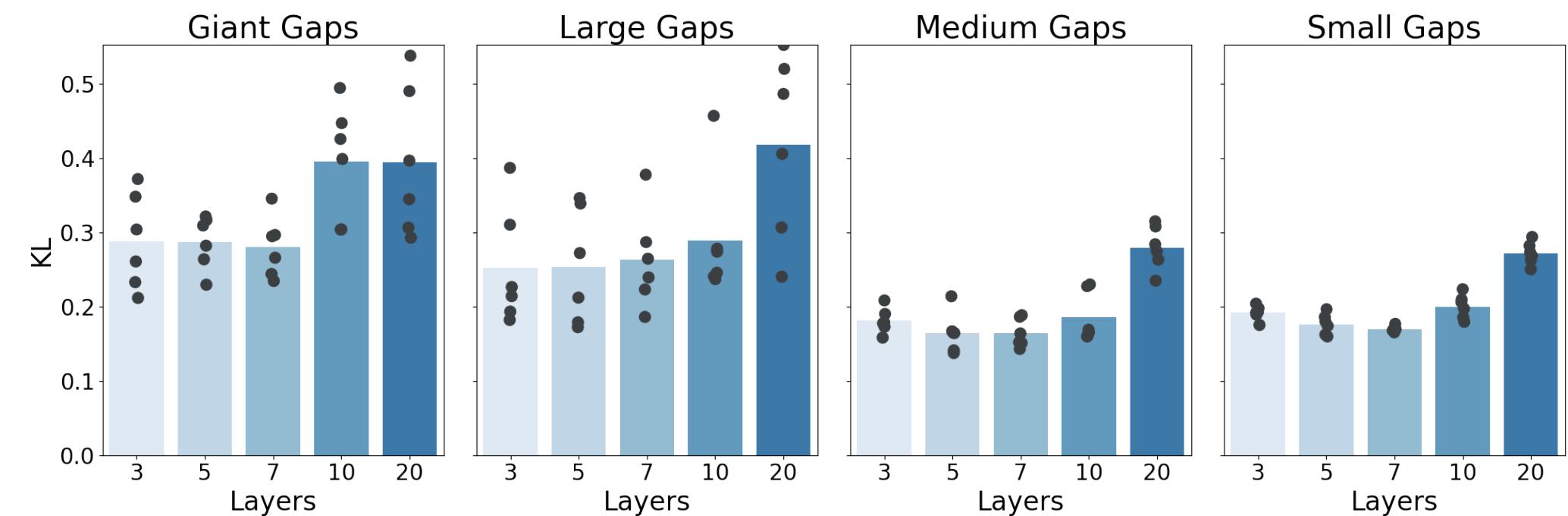


Density Estimation - 2D: 10 Gaussians





- Found:
 - More layers generally improve results
 - Layers >> Dimensions
 - ‘Gaps’ increase divergence
- Does this hold true for higher dimensions?

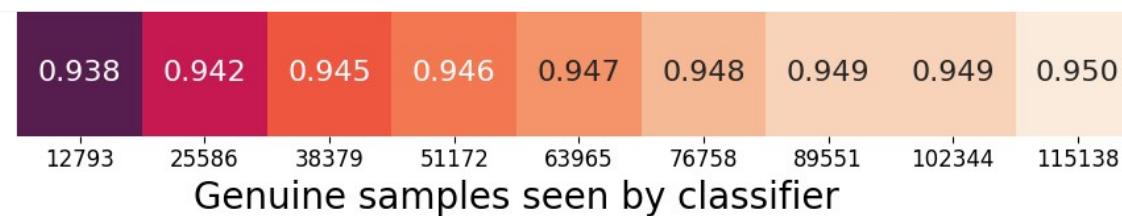


- Found:
 - More layers may make it worse
 - 5 to 7 layers works best
 - Layers < Dimensions
 - ‘Gaps’ increase divergence

- 50 dimensions
- Physical experiment to observe neutrinos
- Binary classification problem: signal and noise
- ~130k samples
 - ~70% noise, ~30% signal
- Balanced and unbalanced experiment
- Experiment
 - Fit individual 30 layer MAFs for noise and signal
 - Sample synthetic dataset from MAFs
 - Fit classifiers with varying amounts of genuine and synthetic samples
 - Measure accuracy on test set

Sampling Quality: MiniBooNE Accuracy

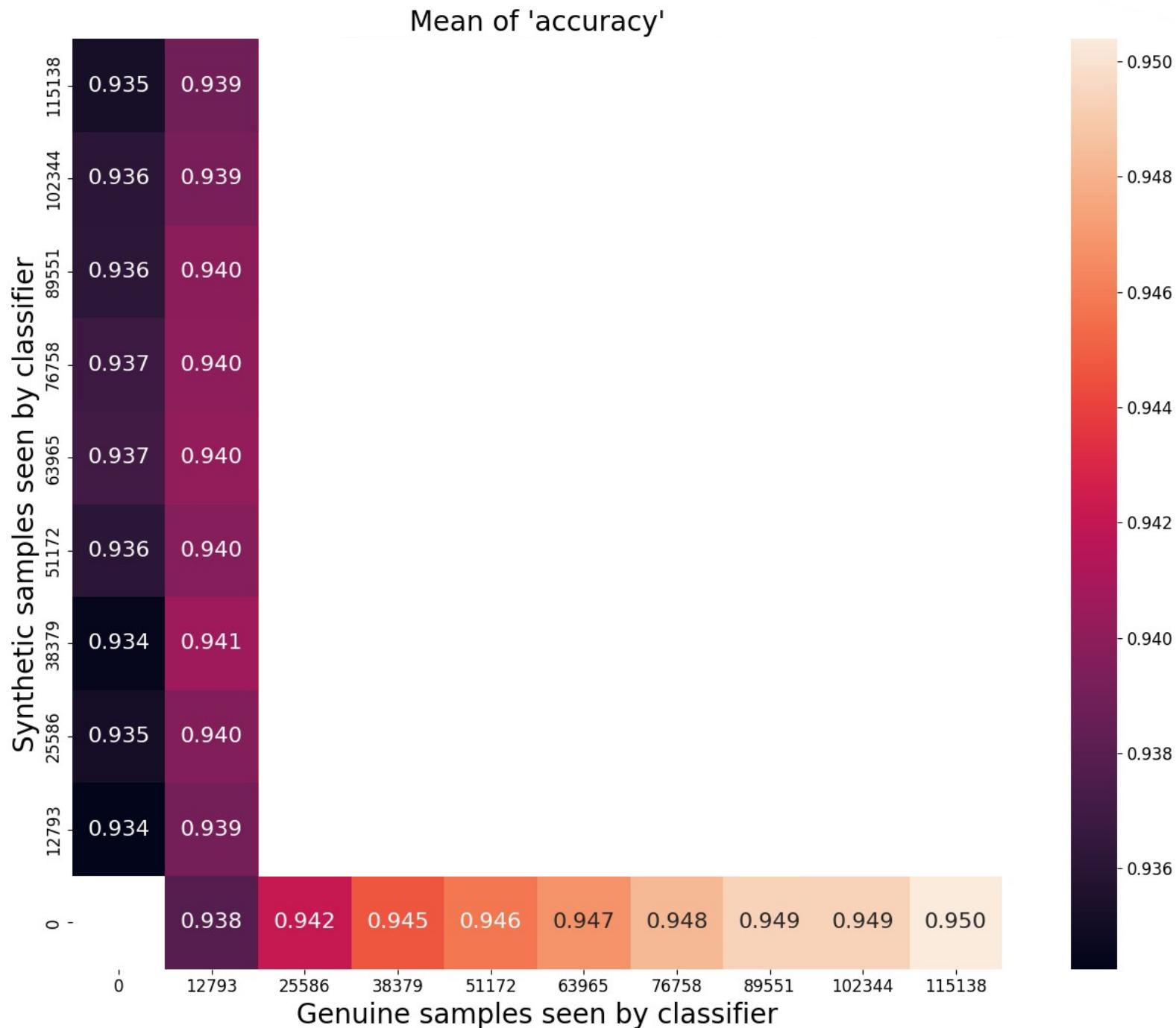
Mean of 'accuracy'



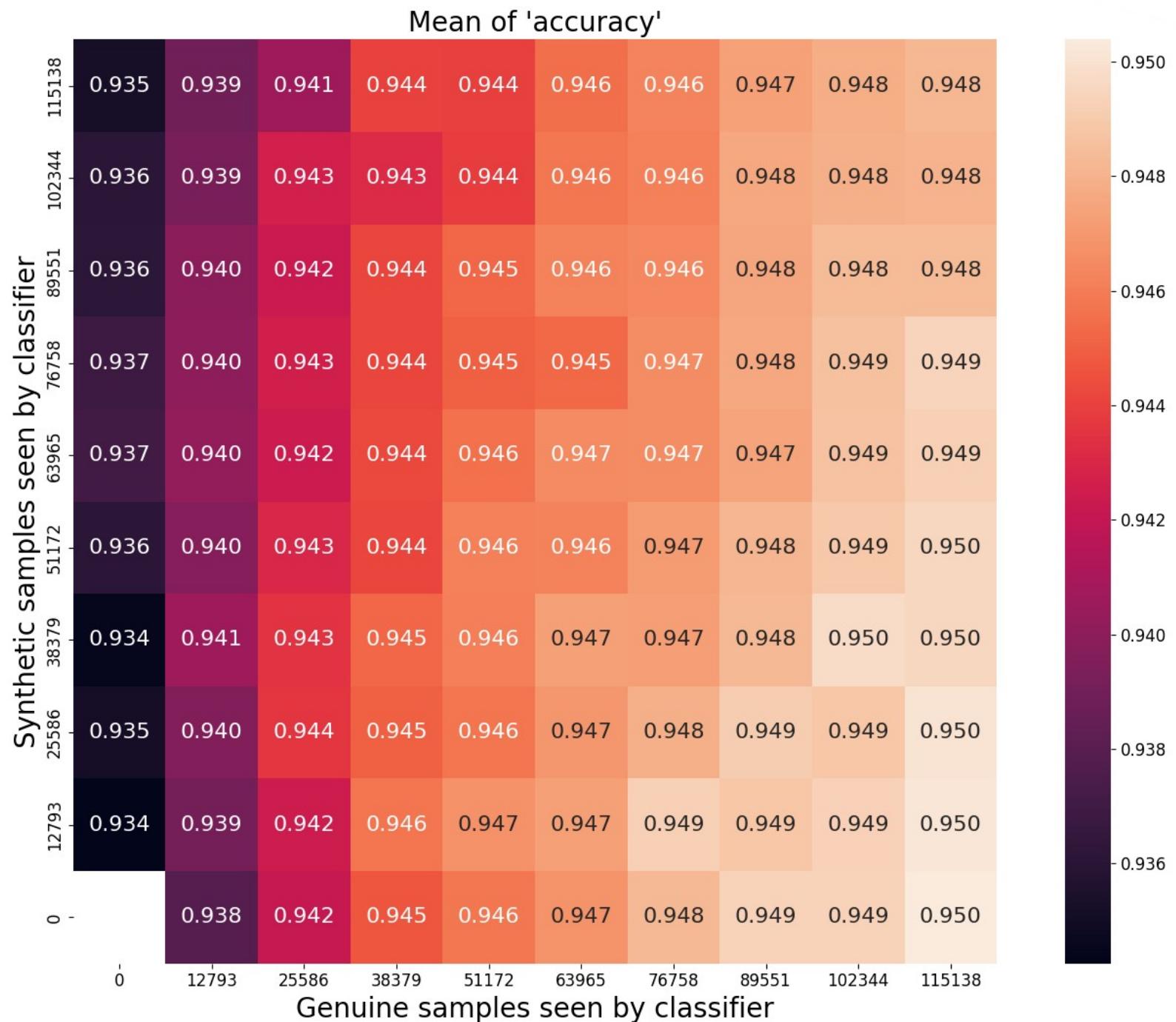
Sampling Quality: MiniBooNE Accuracy



Sampling Quality: MiniBooNE Accuracy

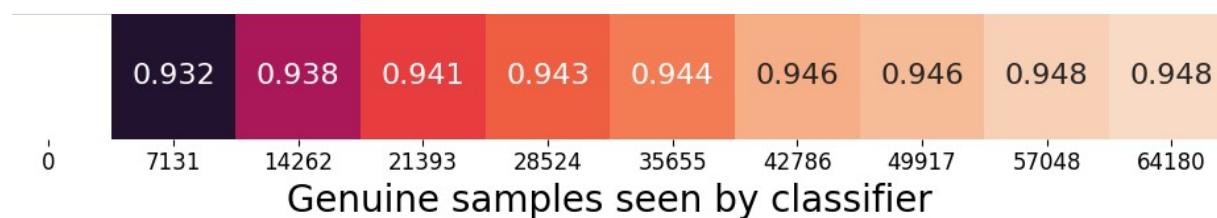


Sampling Quality: MiniBooNE Accuracy

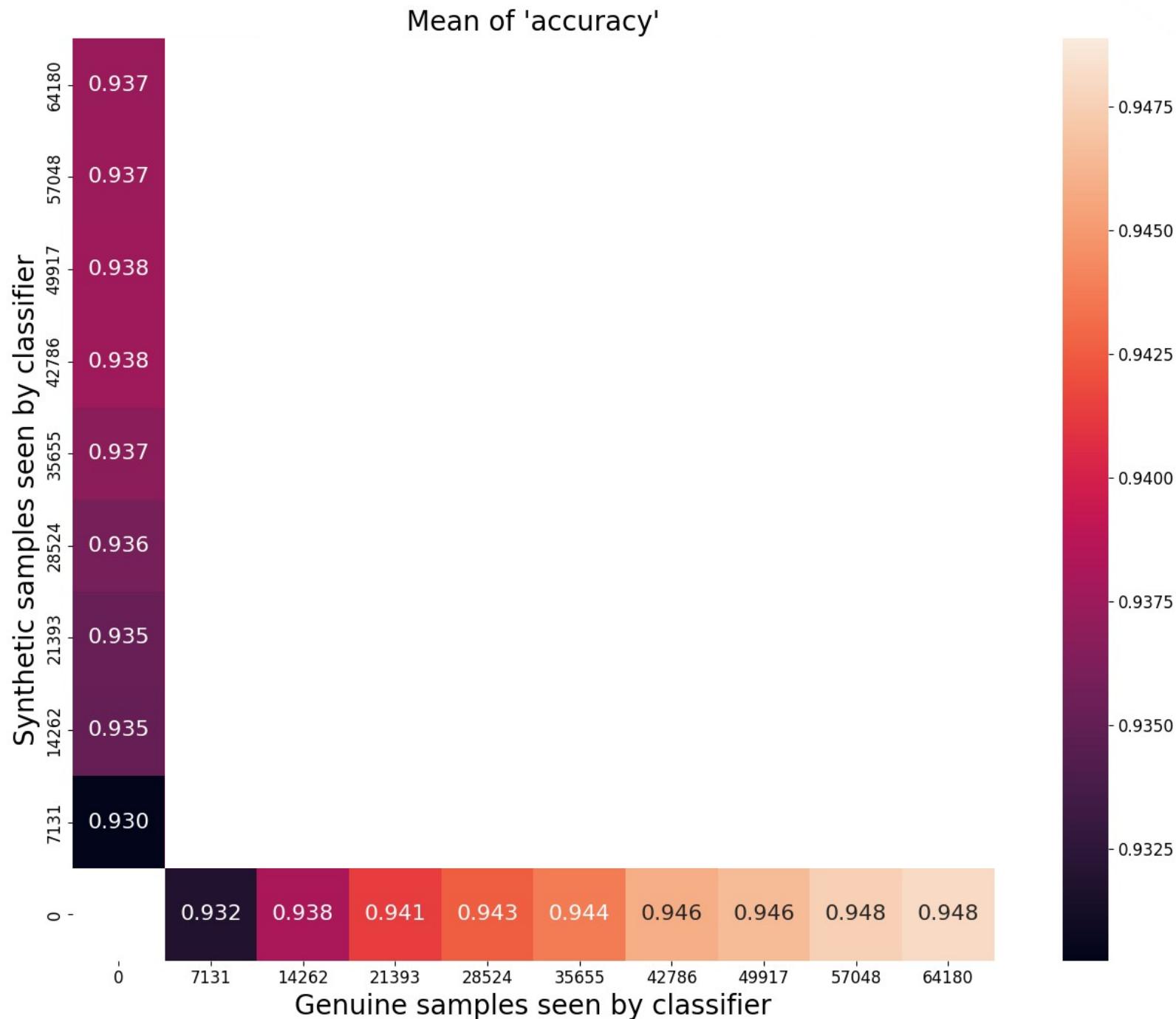


Sampling Quality: MiniBooNE, balanced

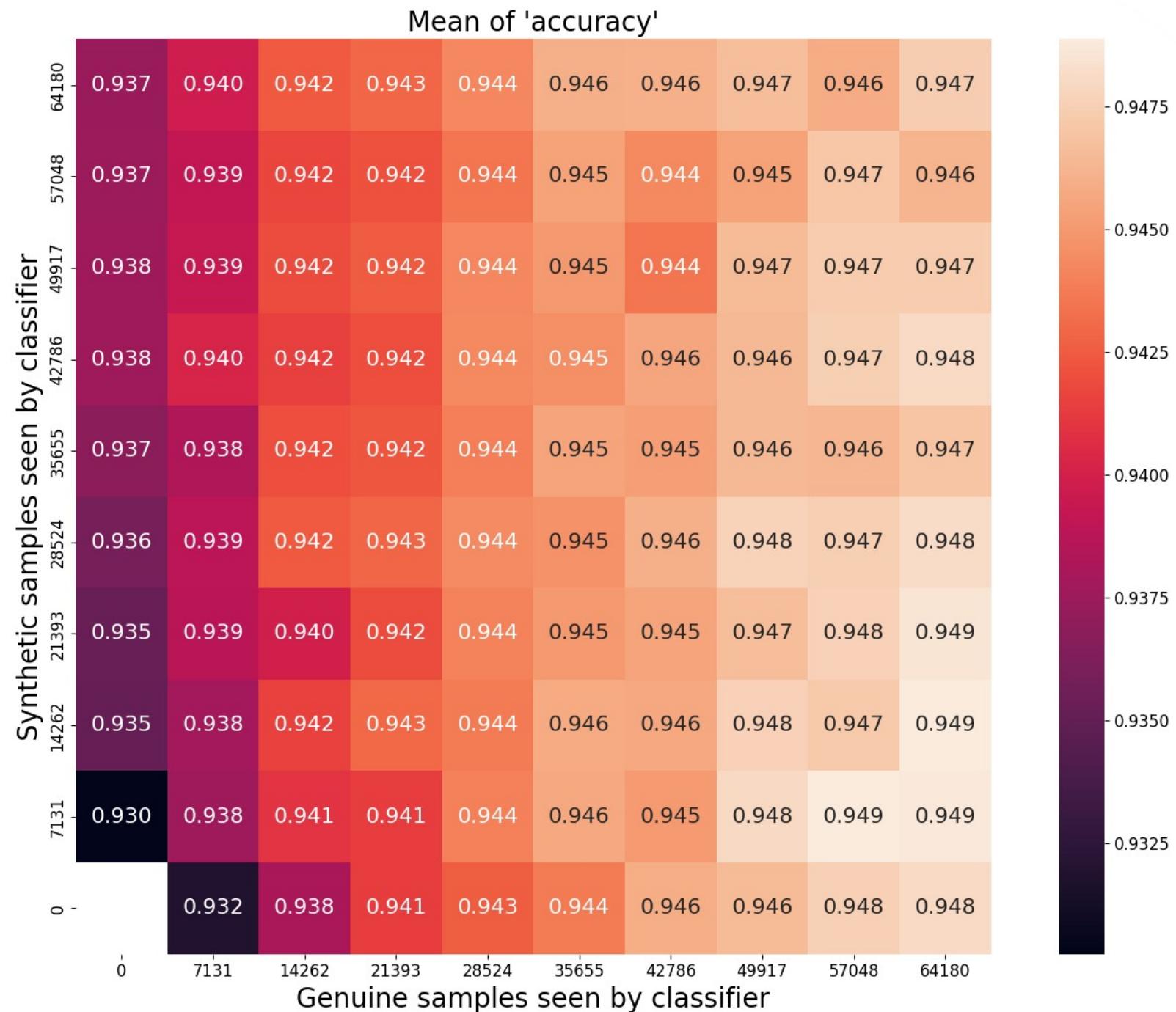
Mean of 'accuracy'



Sampling Quality: MiniBooNE, balanced



Sampling Quality: MiniBooNE, balanced



- Switching to synthetic samples
 - Accuracy drops slightly in all cases
- Augmenting synthetic samples
 - Complete dataset
 - Does not do anything at best
 - Augmenting many samples is harmful
 - Balanced
 - Few additional samples may improve accuracy very slightly
 - Augmenting many samples is harmful

- MAFs can learn arbitrary distributions
- MAFs are easy to tune
- MAFs scale well for higher dimensions



The End