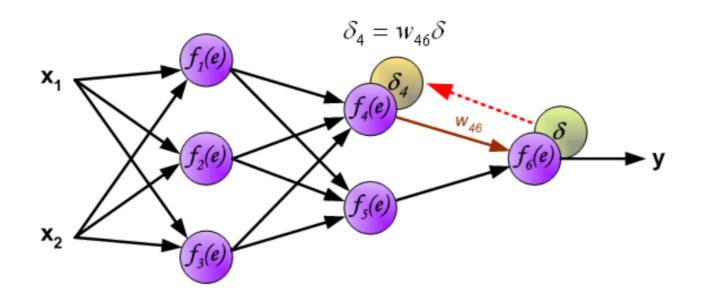


Computer Vision: Insight of object detection algorithms:

### Lesson4 Basic Neutral Network



By Daniel

Research Scientist danielshaving@gmail.com



- Neutral Network
- Loss Function
- Gradient descent
- Forward Propagation
- Backward Propagation

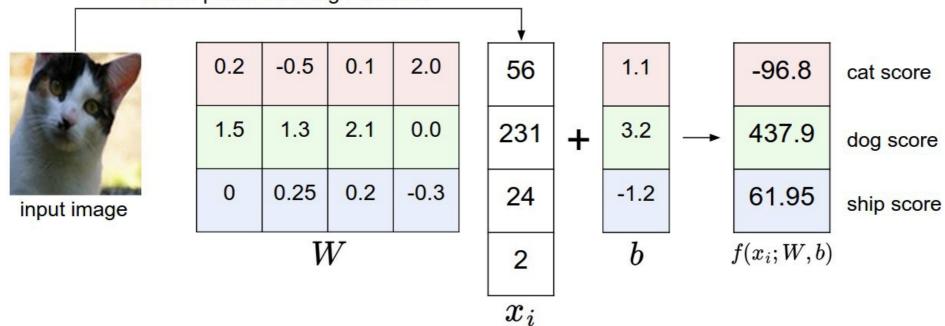
## An NN model



Suppose we have a weights matrix  $W \in \mathbb{R}^{K \times D}$ , a bias vector  $b \in \mathbb{R}^{K \times 1}$  where K is number of classes and D is feature dimensionality, then given an input  $x_i \in \mathbb{R}^{D \times 1}$ , the score funtion  $f : \mathbb{R}^D \to \mathbb{R}^K$  is:

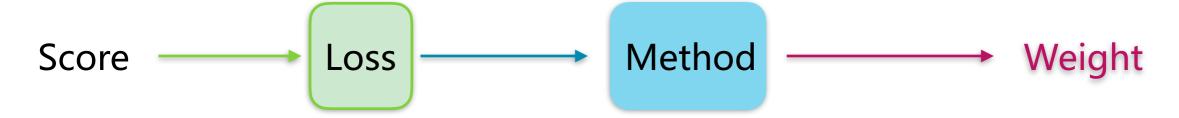
$$f(x_i, W, b) = Wx_i + b$$

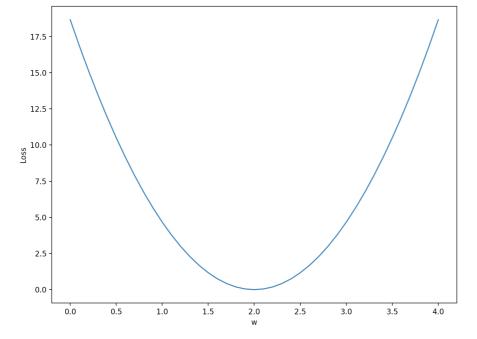
#### stretch pixels into single column



# Using score to correct weights (supervising)





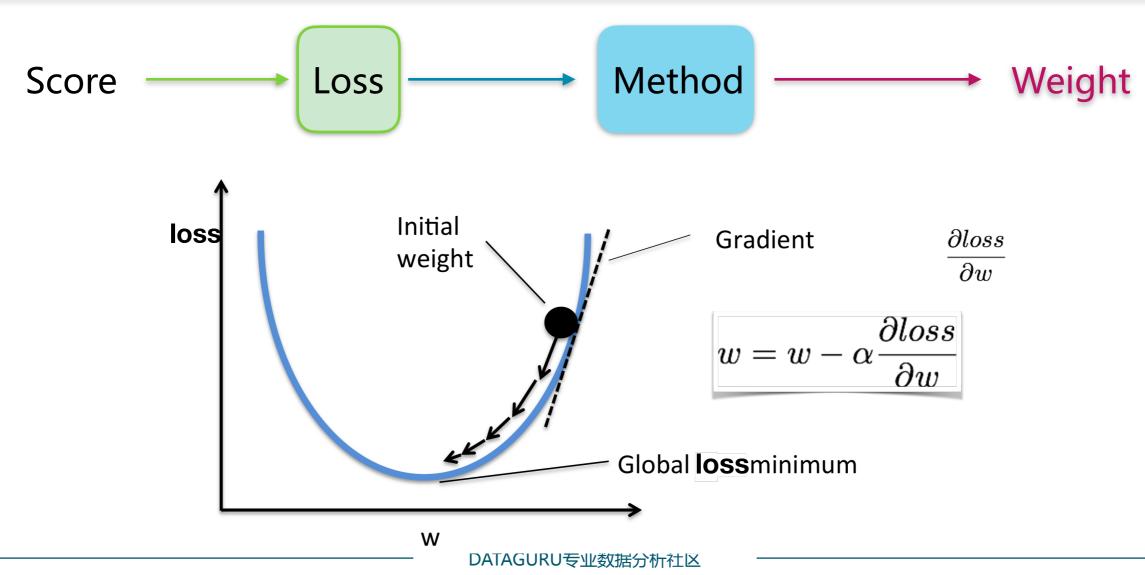


$$loss(w) = rac{1}{N} \sum_{n=1}^N (\hat{y_n} - y_n)^2$$

 $rg \min_{w} loss(w)$ 

# Example: UNet $(x \times w - y)^2$





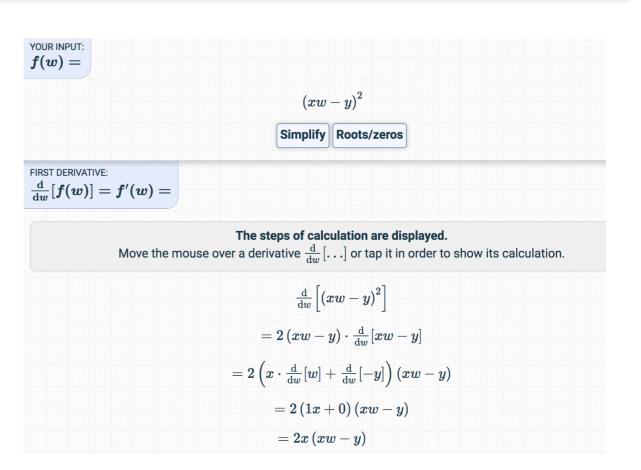
# Derivative $(x \times w - y)^2$



$$loss = (\hat{y} - y)^2 = (x * w - y)^2$$

$$w = w - \alpha \frac{\partial loss}{\partial w}$$

$$\frac{\partial loss}{\partial w} = ?$$

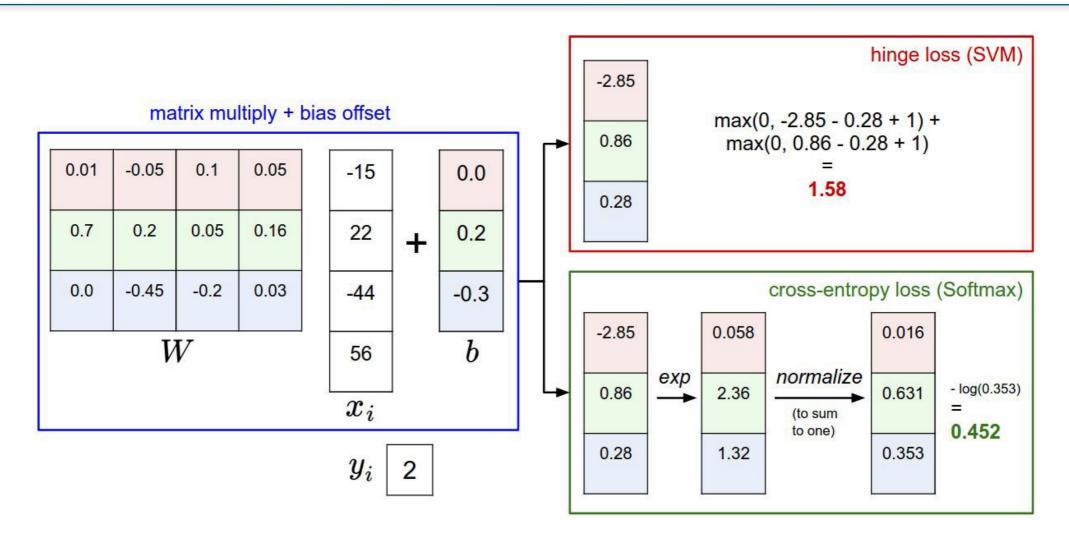




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  - Softmax + Cross Entropy loss
  - Hinge Loss
  - Overall Loss
  - Loss summary
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- Backward Propagation

### Loss Function to calculate the errors





# Loss Function (Cross-Entropy and Hinge (SVM Loss))



#### Cross-Entropy-Loss (after Softmax)

Let  $(x_i, y_i)$  be a pair of training example, where  $x_i \in R^D$  is training data and  $y_i \in R^K$  is a one-hot vector with all zeros except for its true class index is one. Assume the prediction  $\hat{y_i} \in R^K$  is computed after Softmax, then the cross-entropy loss is:

$$L_i = -y_i \cdot \log(\hat{y})$$

#### Hinge Loss (SVM Loss)

Note that the exponential computing in cross-entropy loss is expensive and sometimes we do not need a probability. Thus, the hinge loss function is:

$$L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + \Delta)$$



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# Softmax Classifier (Multinomial Logistic Regression)





scores = unnormalized log probabilities of the classes.

$$P(Y=k|X=x_i)=rac{e^{s_k}}{\sum_j e^{s_j}}$$
 where

 $s=f(x_i;W)$ 

cat **3.2** 

car 5.1

frog -1.7

Want to maximize the log likelihood, or (for a loss function) to minimize the negative log likelihood of the correct class:

$$L_i = -\log P(Y = y_i | X = x_i)$$

in summary: 
$$L_i = -\log(rac{e^{sy_i}}{\sum_i e^{s_j}})$$

# Softmax Classifier





cat

car

frog

3.2

5.1

-1.7

$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$

unnormalized log probabilities

## Softmax Classifier





$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$

unnormalized probabilities

unnormalized log probabilities

# Softmax Classifier





$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$

#### unnormalized probabilities

unnormalized log probabilities

probabilities

# Softmax + Cross entropy





$$L_i = -y_i \cdot \log(\hat{y})$$

#### unnormalized probabilities

$$L_i = -log(0.13)$$
  
= **0.89**

unnormalized log probabilities

probabilities



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# Hinge Loss



Suppose: 3 training examples, 3 classes. With some W the scores f(x, W) = Wx are:







cat

3.2

1.3

2.2

car

5.1

4.9

2.5

frog

-1.7

2.0

-3.1

#### **Multiclass SVM loss:**

Given an example  $(x_i, y_i)$  where  $x_i$  is the image and where  $y_i$  is the (integer) label,

and using the shorthand for the scores vector:  $s = f(x_i, W)$ 

the SVM loss has the form:

$$L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$$

# Hinge Loss



Suppose: 3 training examples, 3 classes. With some W the scores f(x, W) = Wx are:





2.0



cat	3.2	
car	5.1	
frog	-1.7	
Losses:	2.9	

# 1.32.24.92.5

#### **Multiclass SVM loss:**

Given an example  $(x_i, y_i)$  where  $x_i$  is the image and where  $y_i$  is the (integer) label,

and using the shorthand for the scores vector:  $s = f(x_i, W)$ 

the SVM loss has the form:

$$L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$$

 $= \max(0, 5.1 - 3.2 + 1)$ 

 $+\max(0, -1.7 - 3.2 + 1)$ 

= max(0, 2.9) + max(0, -3.9)

= 2.9 + 0

= 2.9

# Hinge Loss



Suppose: 3 training examples, 3 classes. With some W the scores f(x, W) = Wx are:







cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1
Losses:	2.9	0	10.9

#### **Multiclass SVM loss:**

Given an example  $(x_i, y_i)$  where  $x_i$  is the image and where  $y_i$  is the (integer) label,

and using the shorthand for the scores vector:  $s = f(x_i, W)$ 

the SVM loss has the form:

$$L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$$

 $= \max(0, 2.2 - (-3.1) + 1)$ 

 $+\max(0, 2.5 - (-3.1) + 1)$ 

 $= \max(0, 5.3) + \max(0, 5.6)$ 

= 5.3 + 5.6

= 10.9



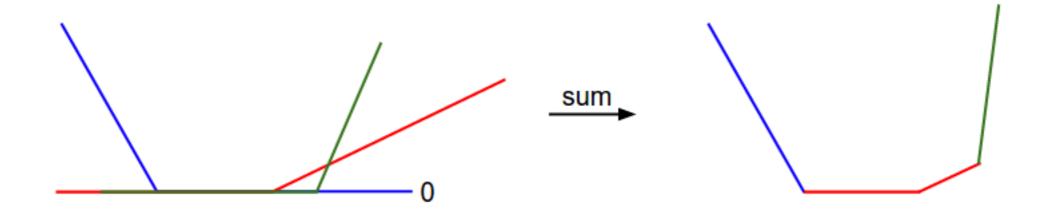
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# Overall Loss



The overall loss consists of two items, namely data loss and regularization loss.

$$L = \frac{1}{N} \sum_{i} L_{i} + \lambda R(W)$$





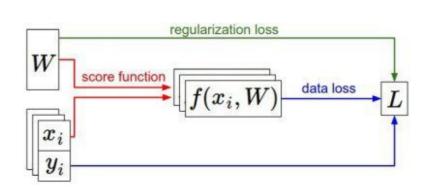
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### Summary of loss function



- We have some dataset of (x,y)
- We have a **score function**:  $s=f(x;W)\stackrel{\text{e.g.}}{=}Wx$
- We have a **loss function**:

$$L_i = -\log(rac{e^{sy_i}}{\sum_j e^{s_j}})$$
 SVM $L_i = \sum_{j 
eq y_i} \max(0, s_j - s_{y_i} + 1)$  $L = rac{1}{N} \sum_{i=1}^N L_i + R(W)$  Full loss





- Neutral Network
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# Follow the slope



In 1-dimension, the derivative of a function:

$$rac{df(x)}{dx} = \lim_{h o 0} rac{f(x+h) - f(x)}{h}$$

In multiple dimensions, the **gradient** is the vector of (partial derivatives).

# Follow the slope



#### current W:

### gradient dW:

[0.34, -1.11,
0.78,
0.12,
0.55,
2.81,
-3.1,
-1.5,
0.33,]
loss 1.25347

```
[0.34 + 0.0001,
-1.11,
0.78,
0.12,
0.55,
2.81,
-3.1,
-1.5,
0.33,...]
loss 1.25322
```

```
[?,
?,
?,
?,
?,
?,...]
```

# Follow the slope



#### current W:

### W + h (first dim):

#### gradient dW:

[-2.5, ?, ?, ?, ...]
$$(1.25322 - 1.25347)/0.0001$$

$$= -2.5$$

$$\frac{df(x)}{dx} = \lim_{h \to 0} \frac{f(x+h) - f(x)}{h}$$
?, ?,...]

### **Gradient Decent**



```
# Vanilla Gradient Descent

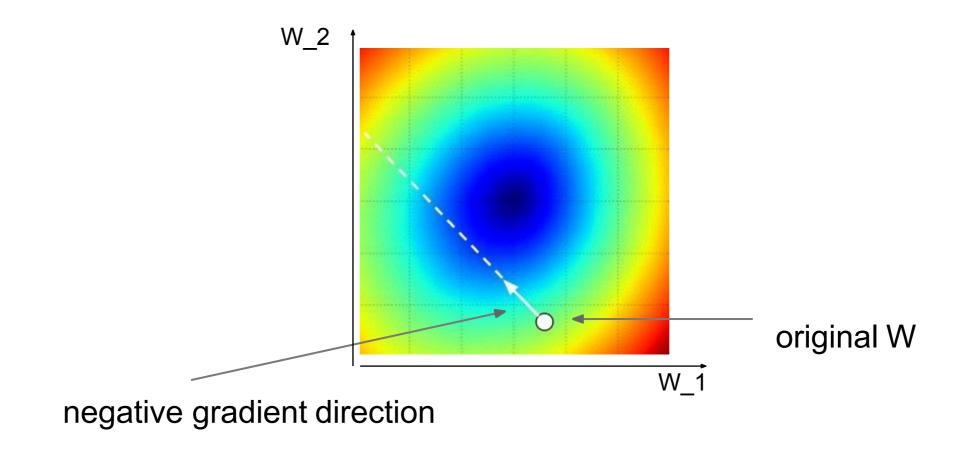
while True:
    weights_grad = evaluate_gradient(loss_fun, data, weights)
    weights += - step_size * weights_grad # perform parameter update
```

```
# Vanilla Minibatch Gradient Descent

while True:
    data_batch = sample_training_data(data, 256) # sample 256 examples
    weights_grad = evaluate_gradient(loss_fun, data_batch, weights)
    weights += - step_size * weights_grad # perform parameter update
```

# Gradient Decent

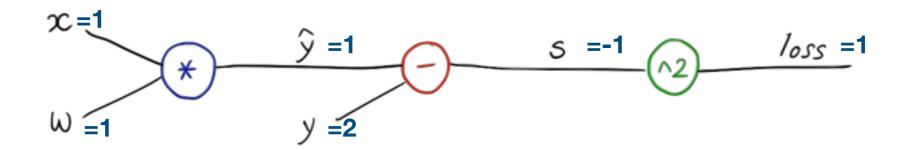






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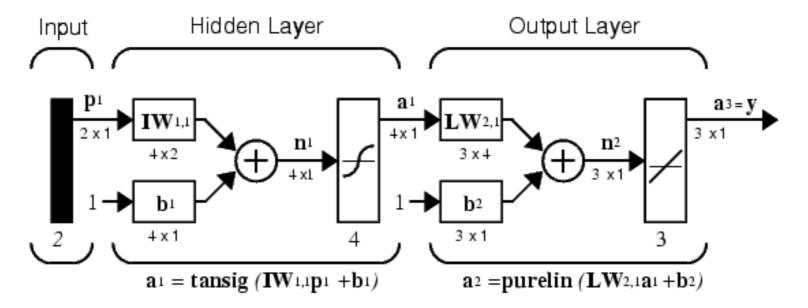




Feedforward networks often have one or more hidden layers of sigmoid neurons followed by an output layer of linear neurons.

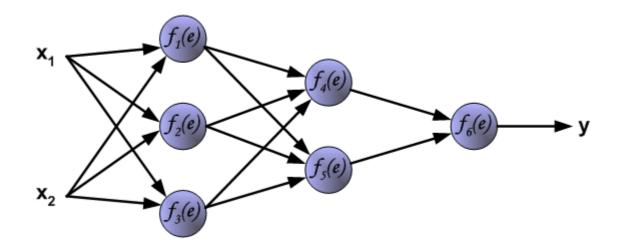
Multiple layers of neurons with nonlinear transfer functions allow the network to learn nonlinear and linear relationships between input and output vectors.

The linear output layer lets the network produce values outside the range -1 to +1. On the other hand, if you want to constrain the outputs of a network (such as between 0 and 1), then the output layer should use a sigmoid transfer function (such as logsig).





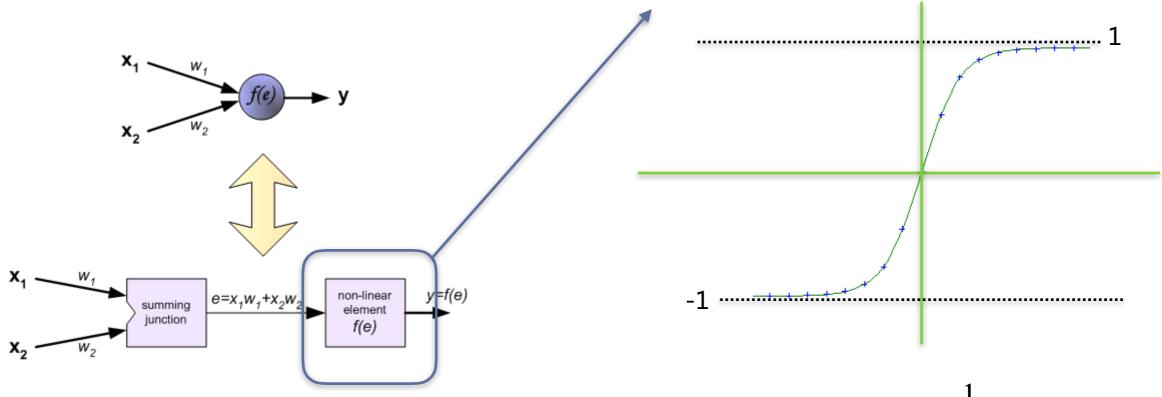
The following slides describes **teaching process** of multi-layer neural network employing **backpropagation** algorithm. To illustrate this process the three layer neural network with two inputs and one output, which is shown in the picture below, is used:



### Active Function



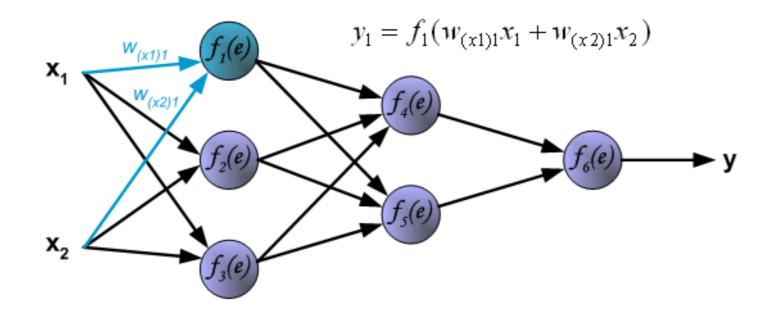
#### **Active Function: Sigmoid**



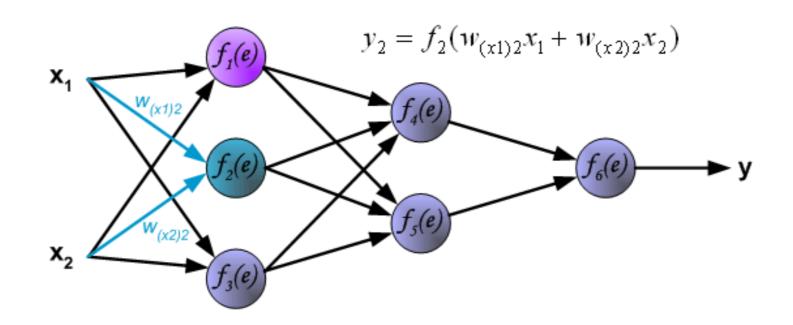
$$f(x) = \frac{1}{1 + e^{-\lambda x}}$$



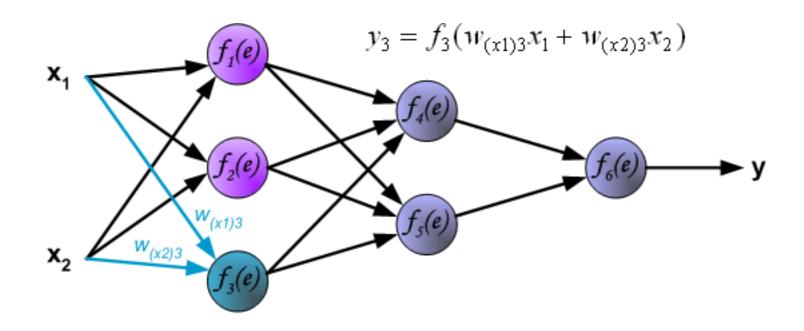
Pictures below illustrate how signal is propagating through the network, Symbols  $w_{(xm)n}$  represent weights of connections between network input  $x_m$  and neuron n in input layer. Symbols  $y_n$  represents output signal of neuron n.





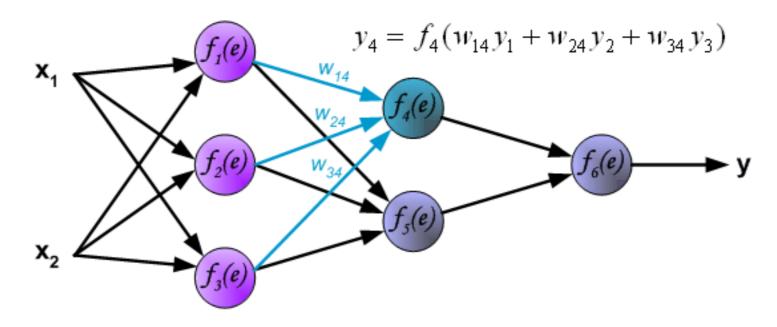




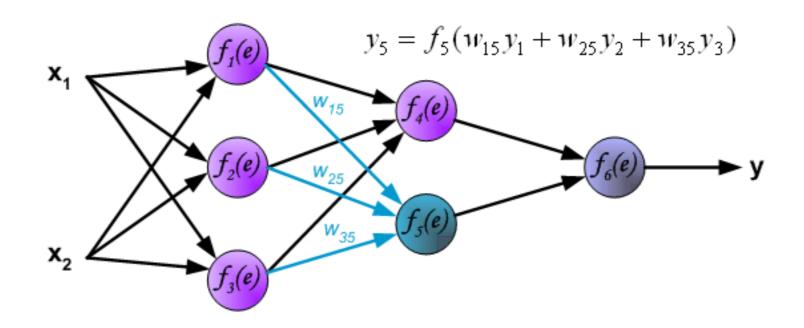




Propagation of signals through the hidden layer. Symbols  $w_{mn}$  represent weights of connections between output of neuron *m* and input of neuron *n* in the next layer.

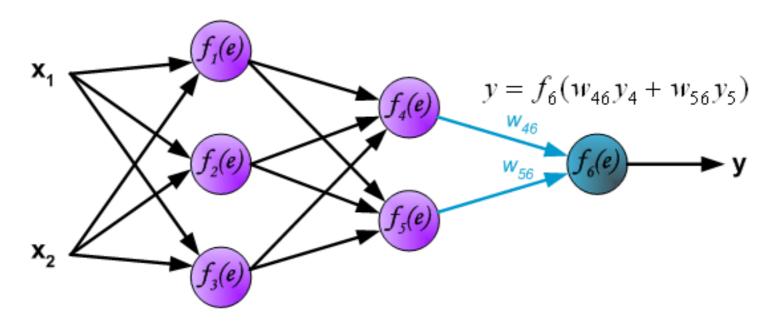








Propagation of signals through the output layer.



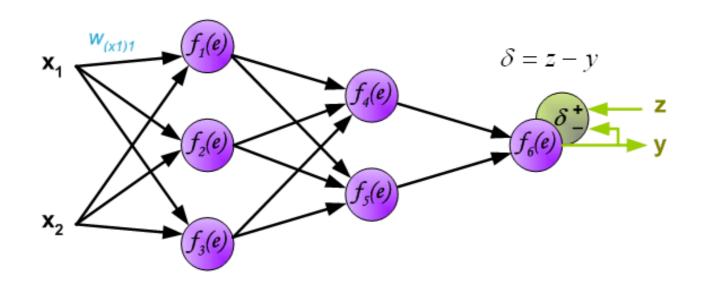
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### Back Propogation





 $\partial loss$ Gradient of loss with respect to  $\boldsymbol{w}$  $\partial w$ 

$$\frac{\partial \delta}{\partial W} = ?$$

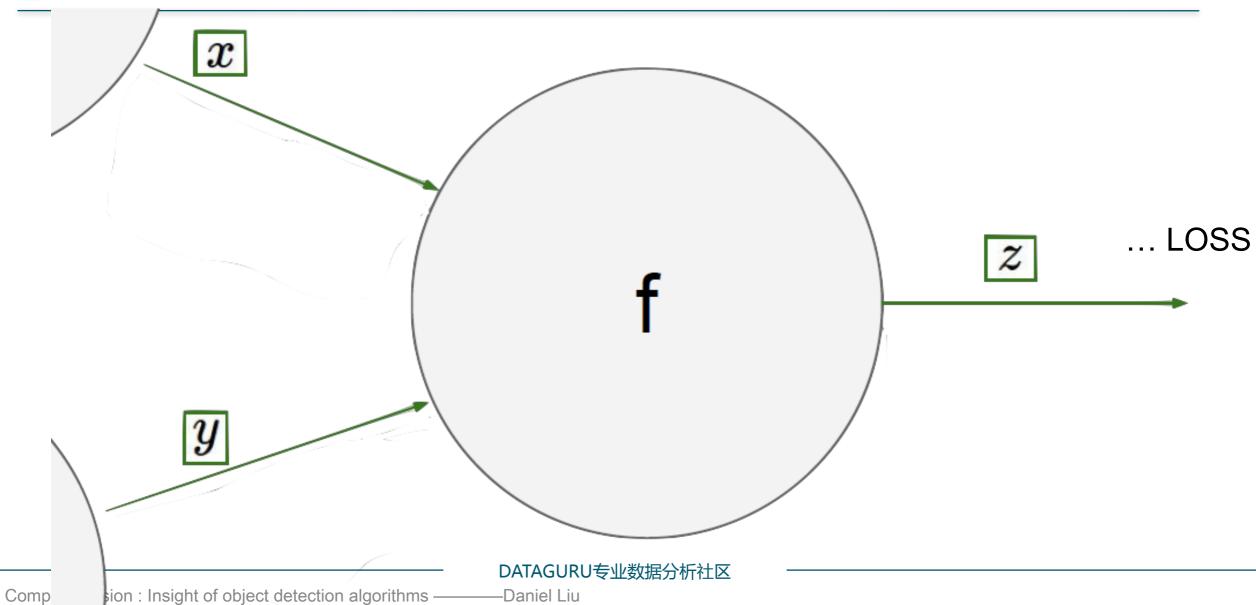
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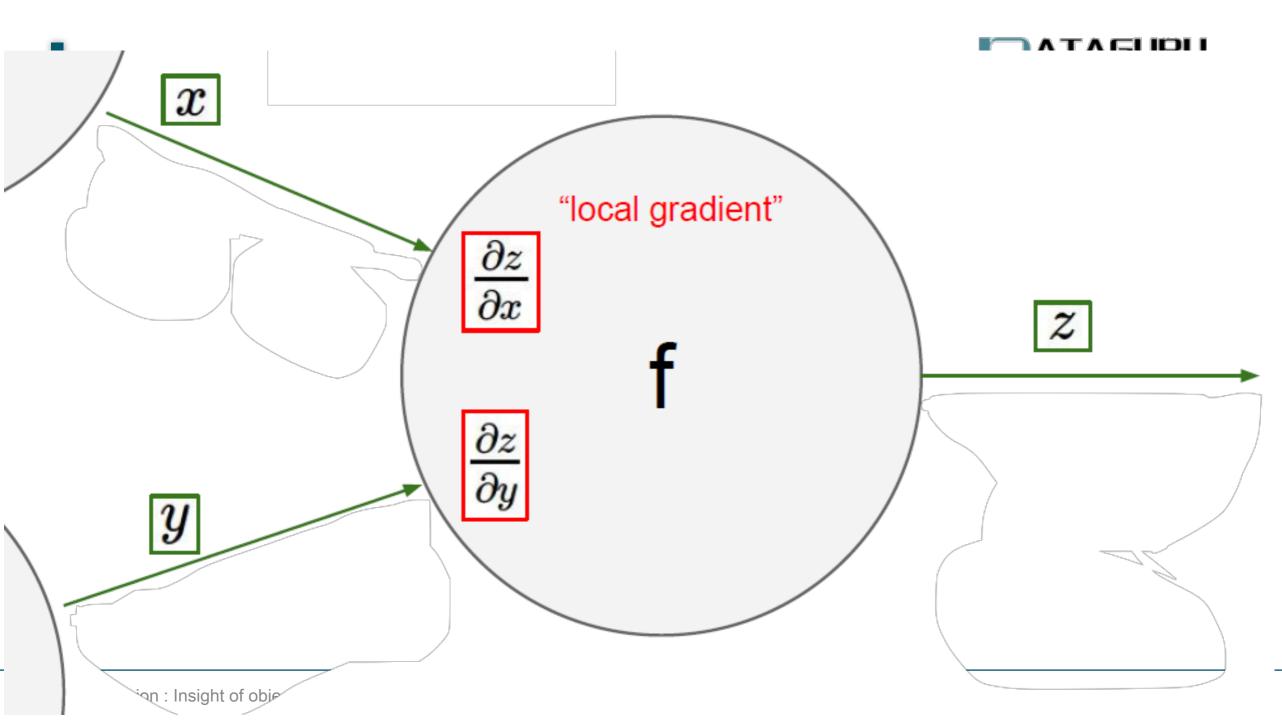


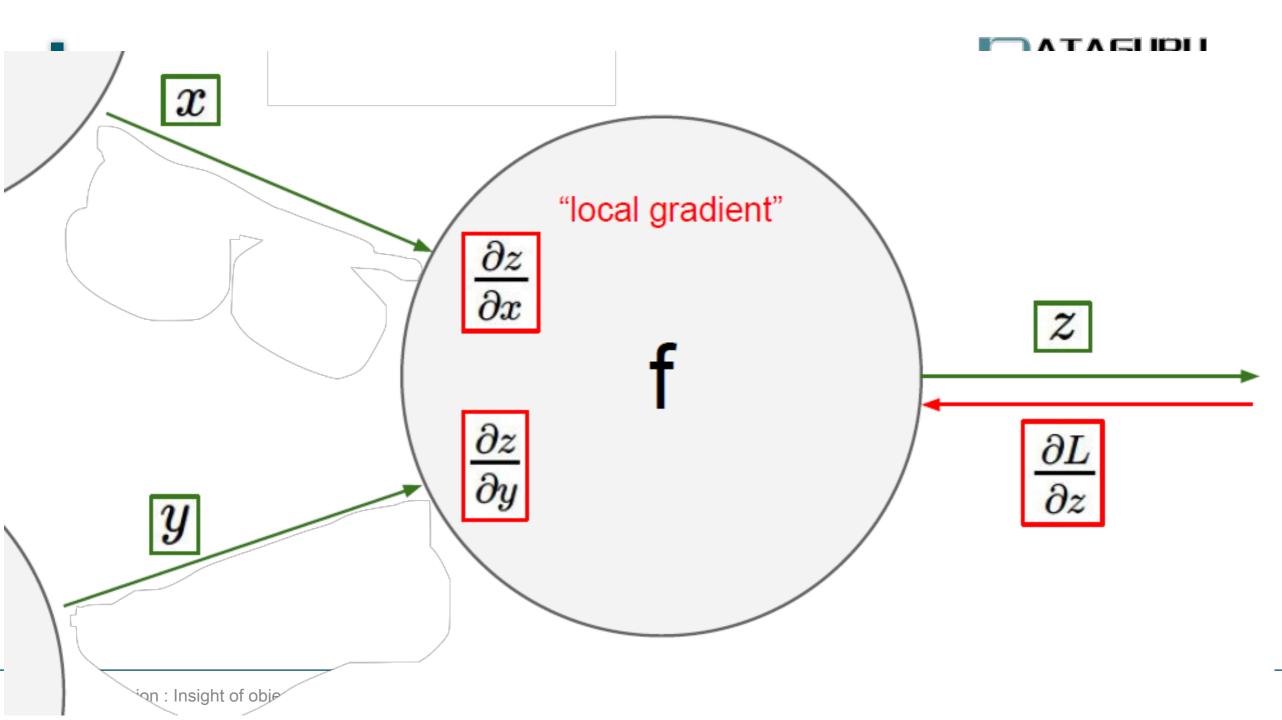
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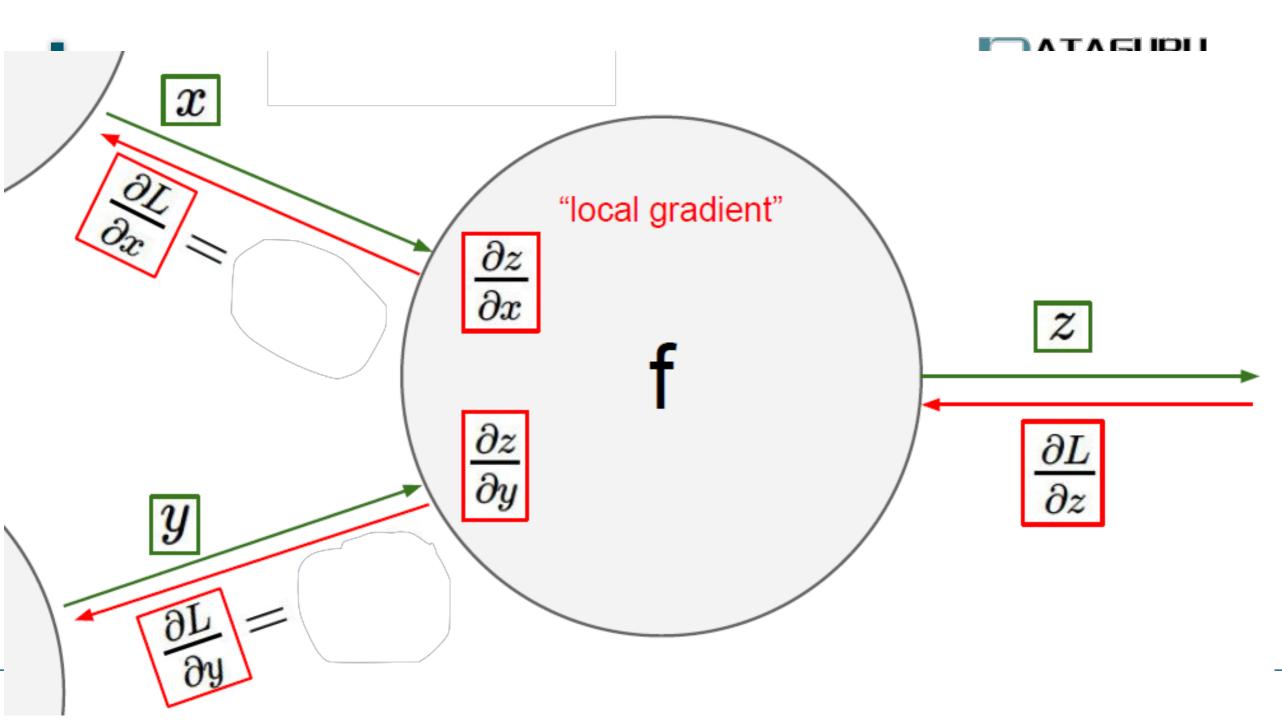
### Chain rule

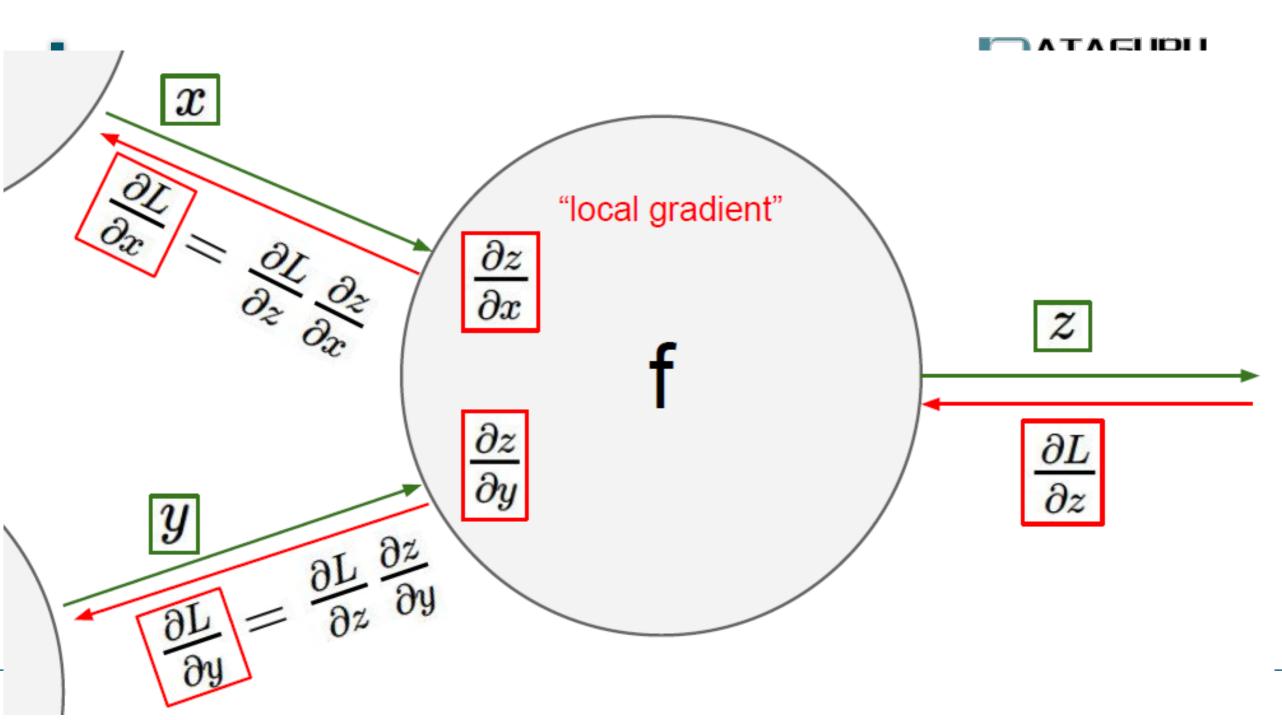


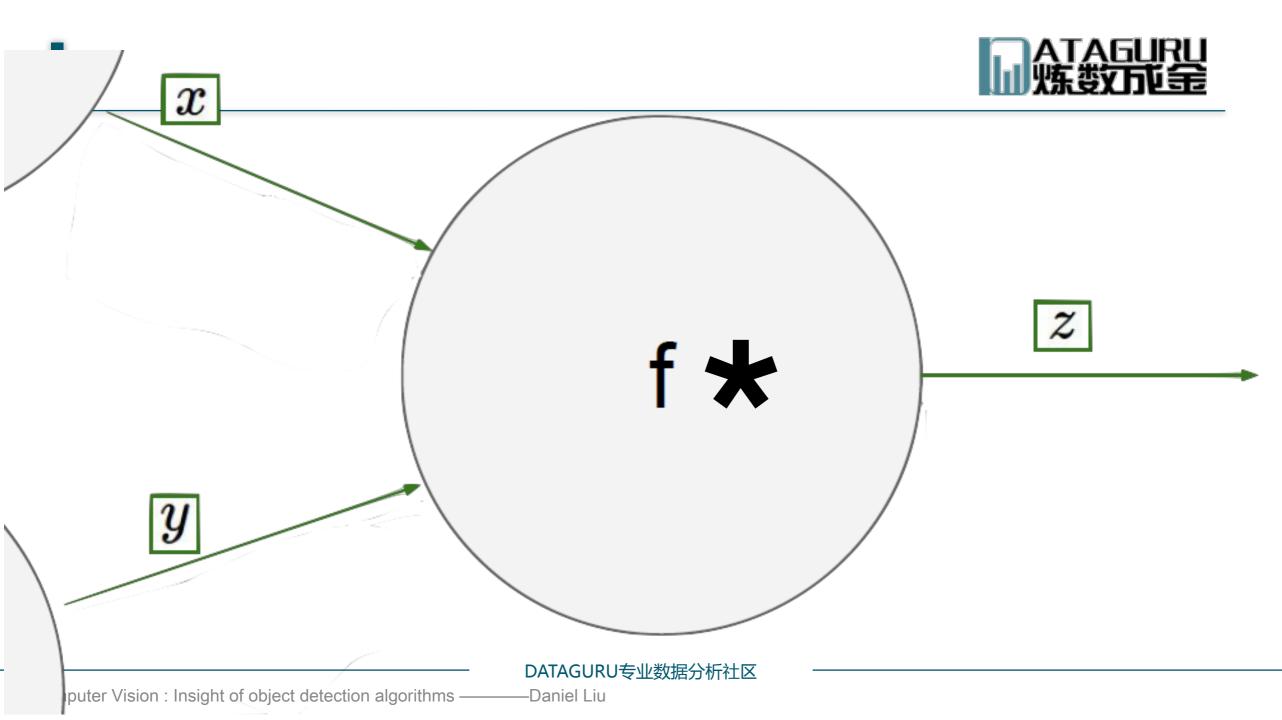


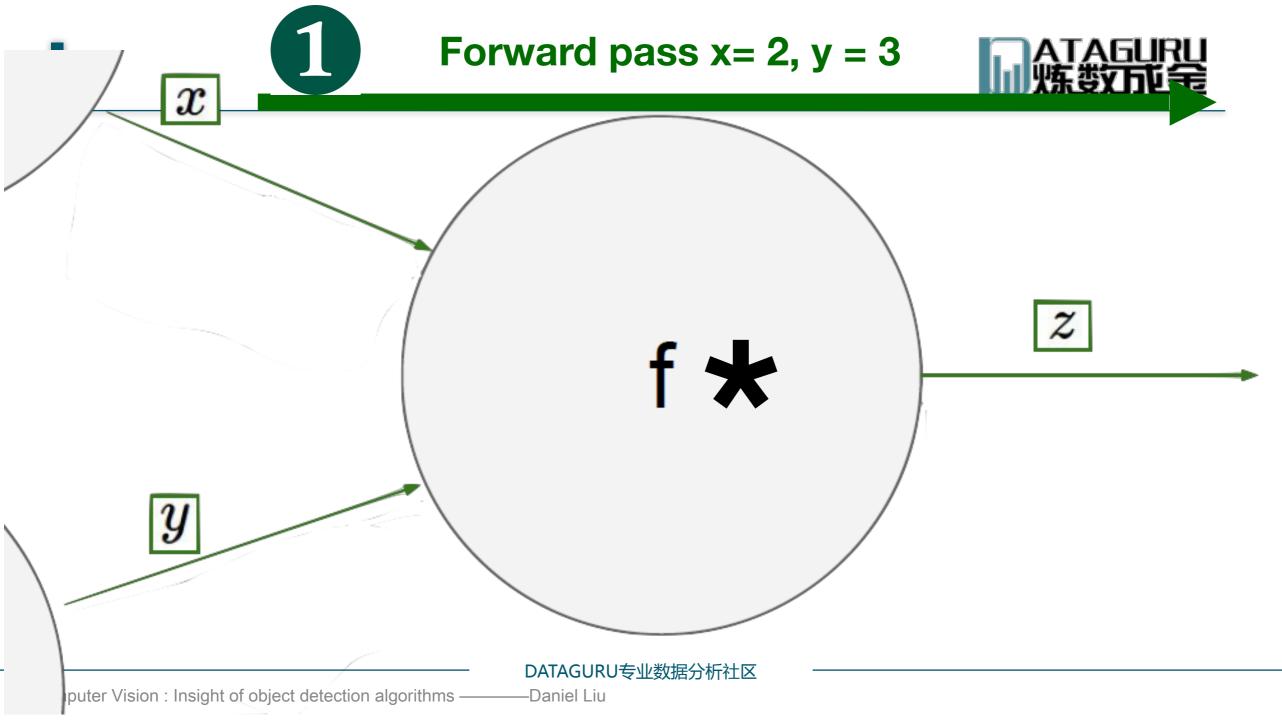


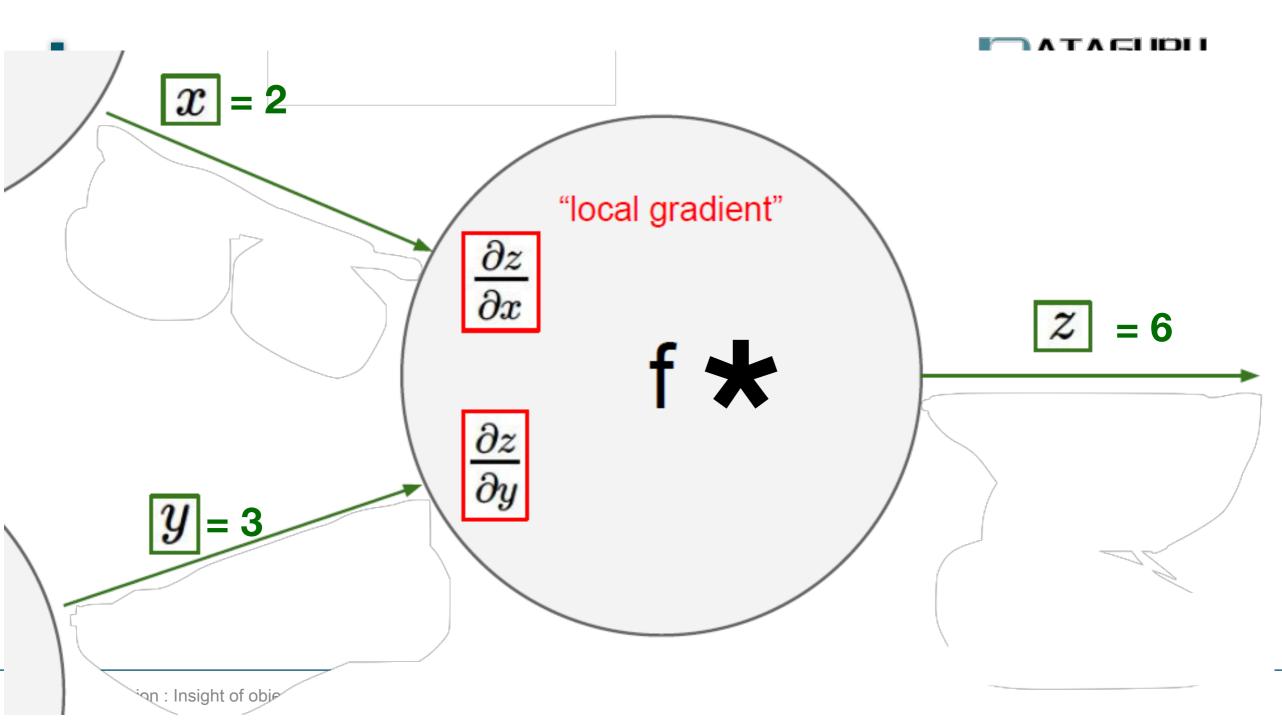


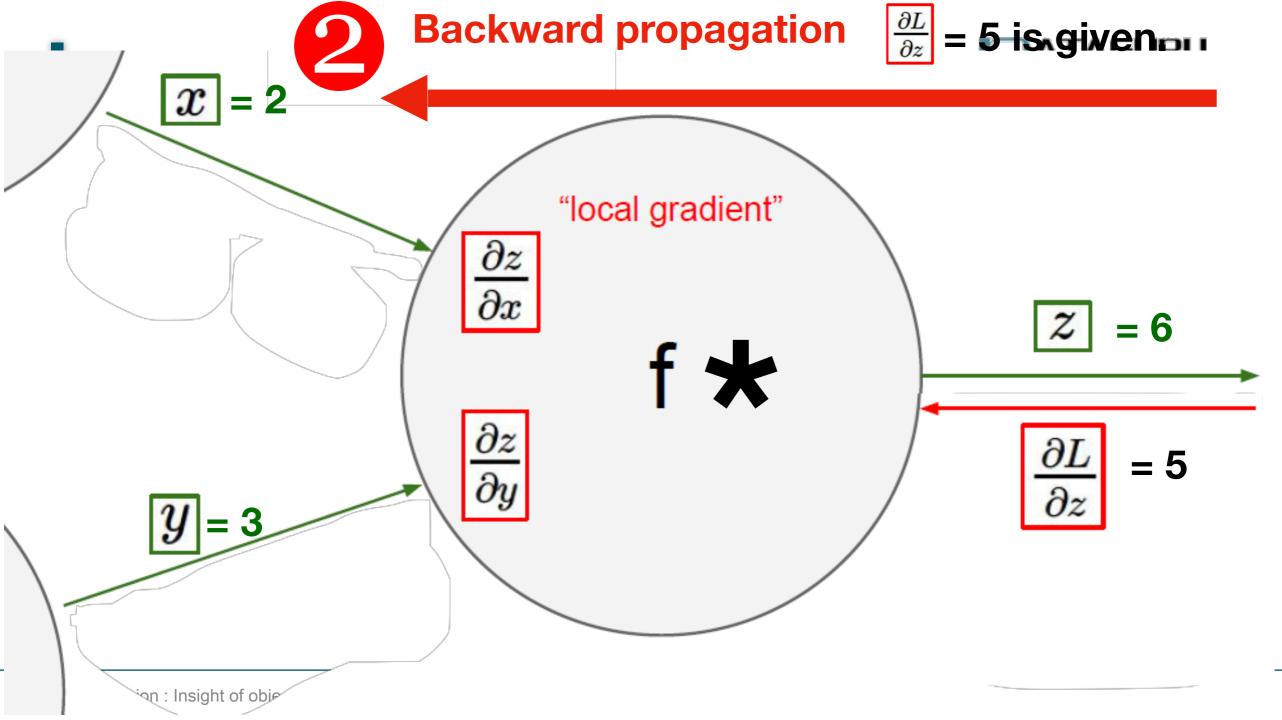


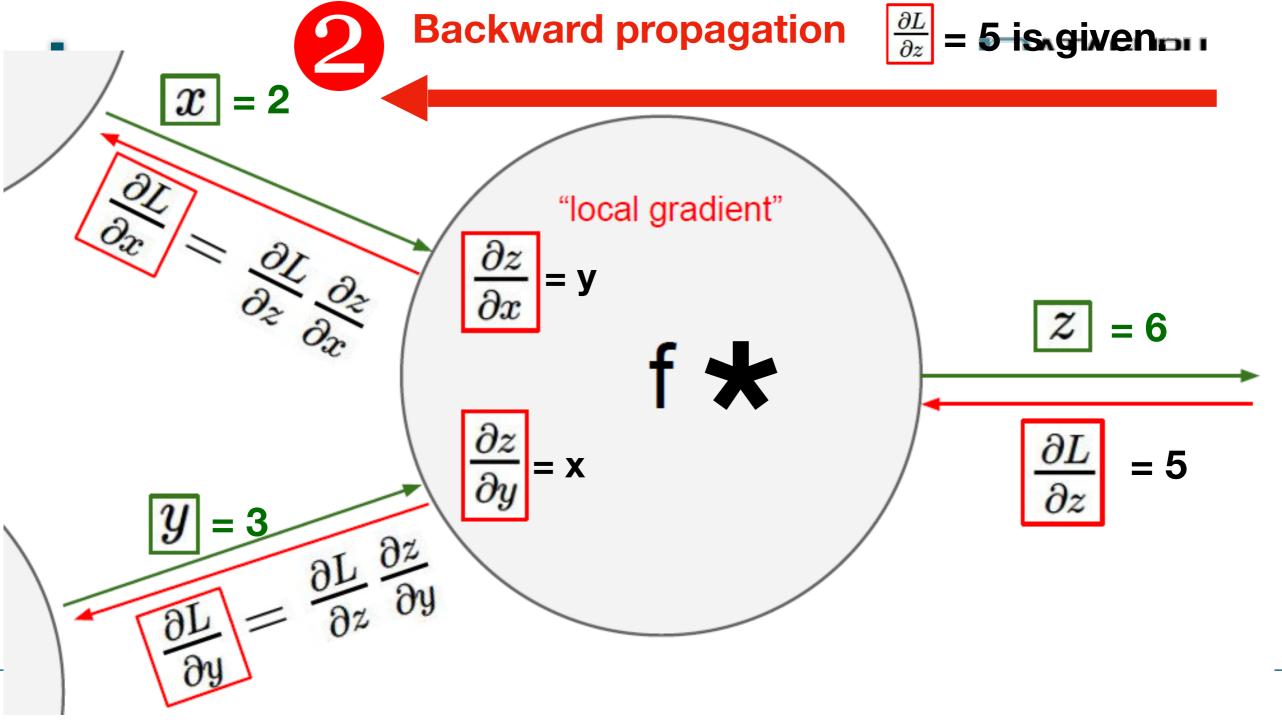


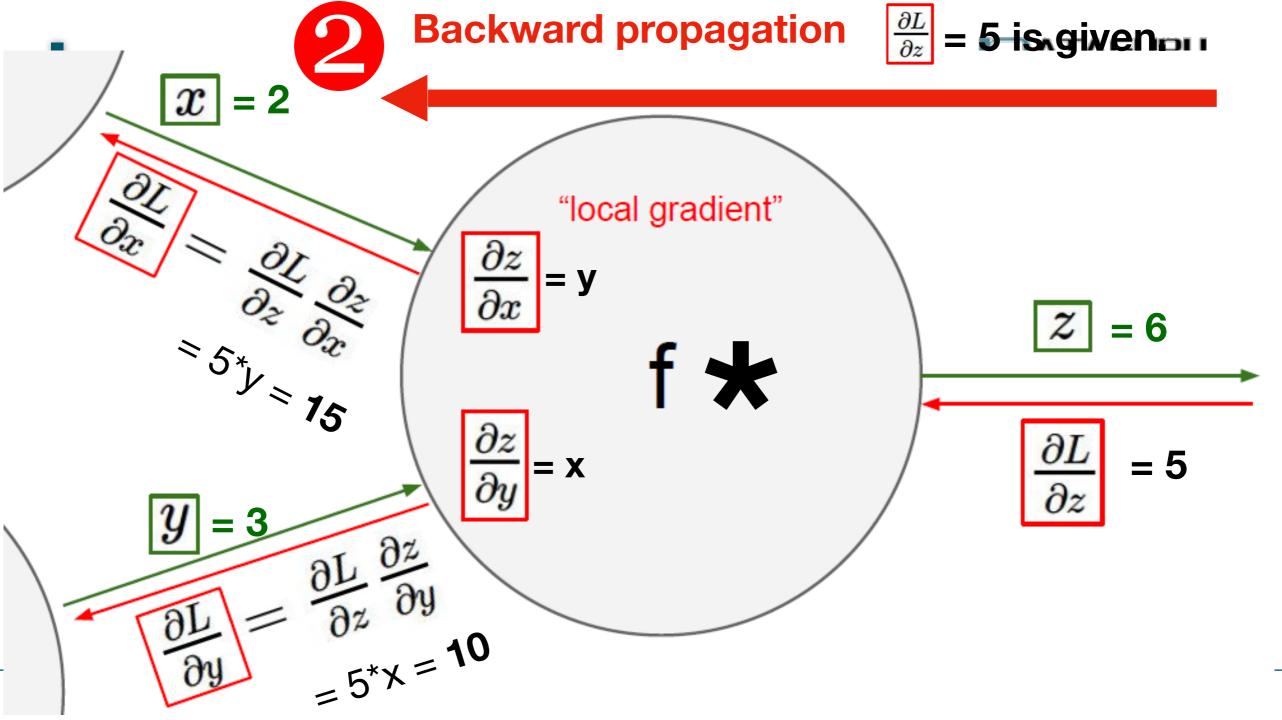












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### Computational graph

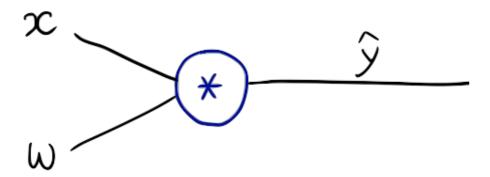


$$\hat{y} = x * w$$





$$\hat{y} = x * w$$

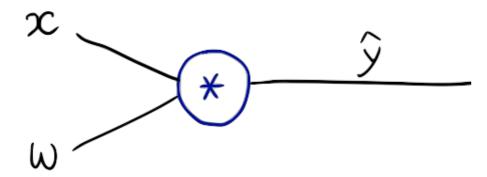


### Computational graph



$$\hat{y} = x * w$$

$$loss = (\hat{y} - y)^2 = (x * w - y)^2$$

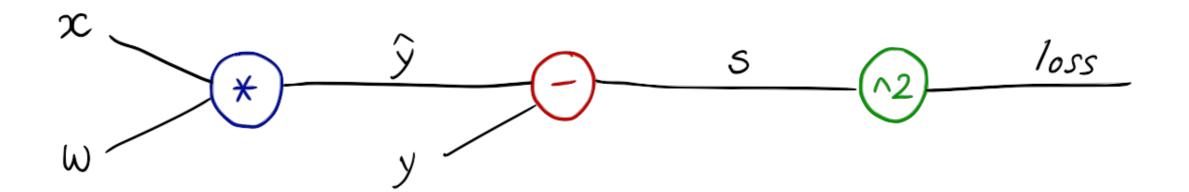


### Computational graph



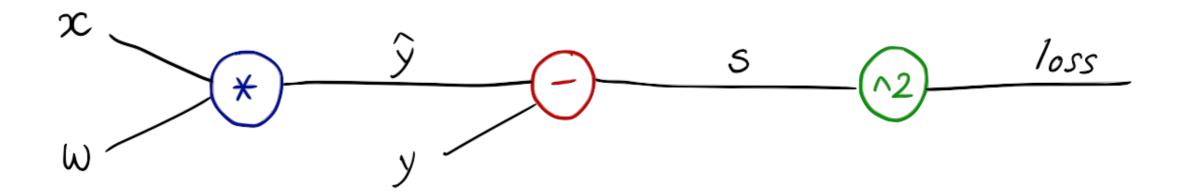
$$\hat{y} = x * w$$

$$loss = (\hat{y} - y)^2 = (x * w - y)^2$$





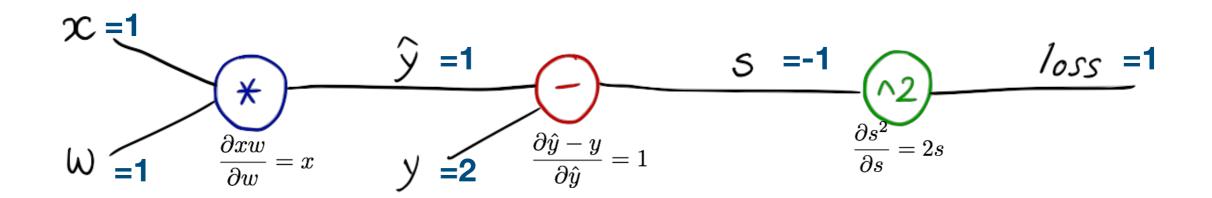
### Forward pass x=1, y = 2 where





 $\partial loss$ 

### Backward propagation 地類



## Backward propagation 地域等

$$\mathcal{X} = 1$$

$$\mathcal{Y} = 1$$

$$\mathcal{Y} = 1$$

$$\mathcal{Y} = 1$$

$$\mathcal{Y} = 2$$

$$\mathcal{Y} = 2$$

$$\mathcal{Y} = 2$$

$$\mathcal{Y} = 3$$

 $\frac{\partial loss}{\partial \hat{y}} = \frac{\partial loss}{\partial s} \frac{\partial s}{\partial \hat{y}} = -2 * 1 = -2$ 

$$\frac{\partial loss}{\partial w} = \frac{\partial loss}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial w} = -2*x = -2*1 = -2$$
 DATAGURU专业数据分析社区 Computer Vision : Insight of object detection algorithms ————Daniel Liu

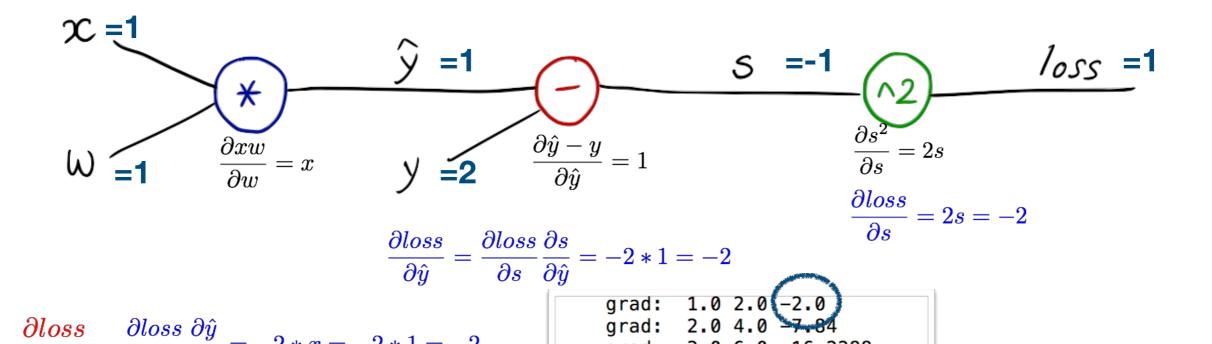
----Daniel Liu



 $\partial w$   $\partial \hat{y}$   $\partial w$  Computer Vision : Insight of object detection algorithms -

 $\partial loss$ 

## Backward propagation 地域等



DATA(

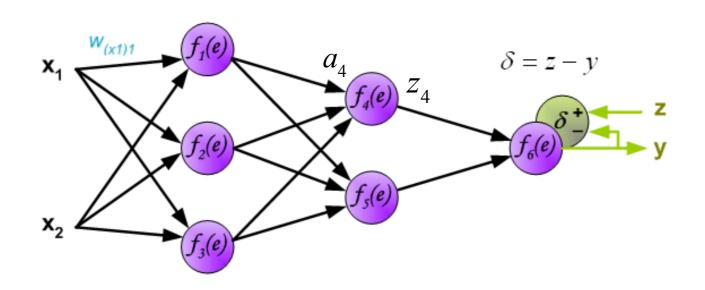
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### Backward propagation

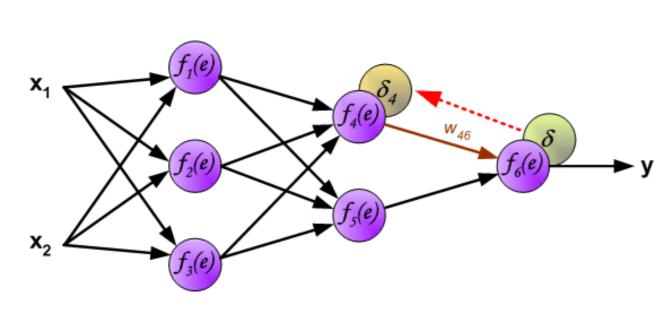




$$\frac{\partial \delta}{\partial z_4} = ?$$

### Backward propagation to the 2nd layer

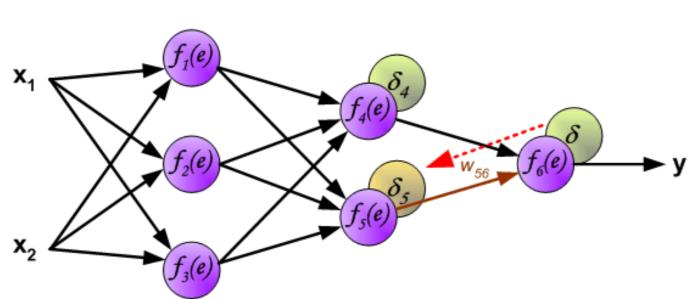




$$\delta_{4} = \delta \frac{\partial \delta}{\partial z_{4}} = \delta \frac{\partial (W_{46}z_{4} + b_{46})}{\partial z_{4}} \cdot f_{6}'$$
$$= \delta W_{46}f_{6}'$$

### Backward propagation to the 2nd layer



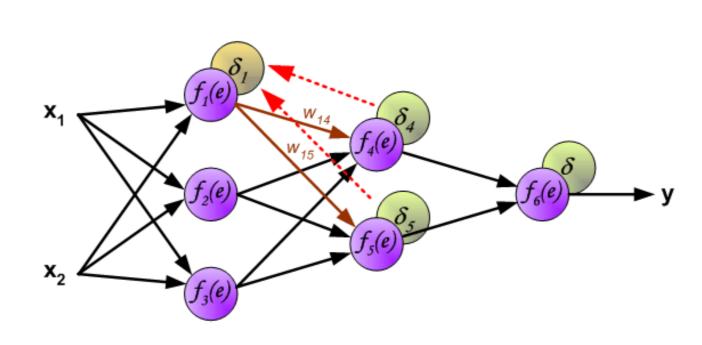


$$\delta_{4} = \delta \frac{\partial \delta}{\partial z_{4}} = \delta \frac{\partial \left(W_{46}z_{4} + b_{46}\right)}{\partial z_{4}} \cdot f_{6}'$$
$$= \delta W_{46}f_{6}'$$

$$\delta_{5} = \delta W_{56} f_{6}^{'}$$

### Backward propagation to the 1st layer





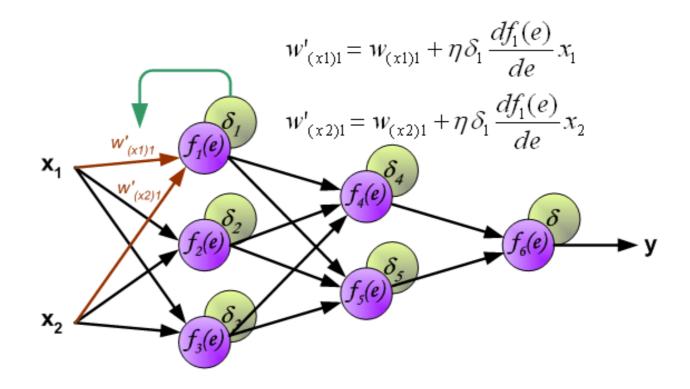
$$\delta_{1} = \delta_{4} W_{14} f_{4}^{'} + \delta_{5} W_{15} f_{5}^{'}$$

$$= \delta f_{6}^{'} (W_{14} W_{46} f_{4}^{'} + W_{56} W_{15} f_{5}^{'})$$

### 1st Layer Refresh

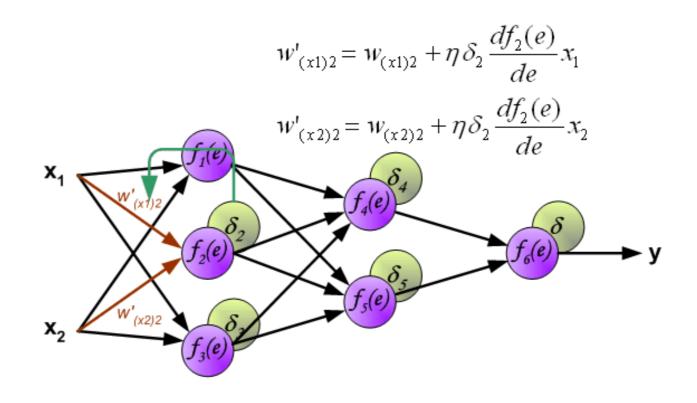


When the error signal for each neuron is computed, the weights coefficients of each neuron input node may be modified. In formulas below df(e)/de represents derivative of neuron activation function (which weights are modified).



### 1st Layer Refresh

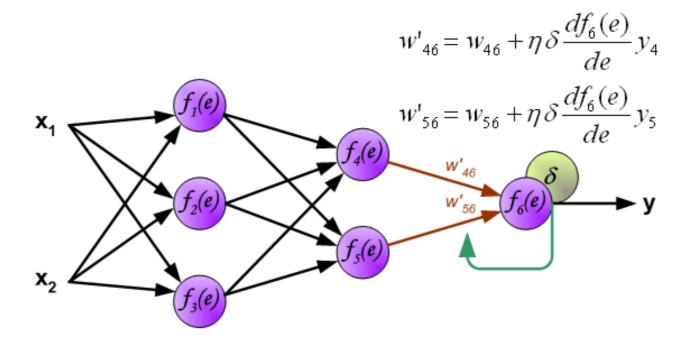




### 2nd Layer Refresh



When the error signal for each neuron is computed, the weights coefficients of each neuron input node may be modified. In formulas below df(e)/de represents derivative of neuron activation function (which weights are modified).



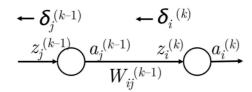
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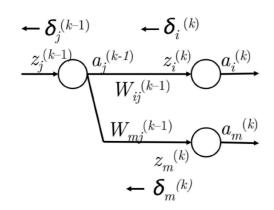


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### Backpropagation from $\delta^k$ to $\delta^{k-1}$







We have error  $\delta_i^{(k)}$  propagating backwards from  $z_j^{(k)}$ , i.e. neuron i at layer k.

We propagate this error backwards to  $a_j^{(k-1)}$  by multiplying  $\delta_i^{(k)}$  by the path weight  $W_{ij}^{(k-1)}$ .

Thus, the error received at  $a_j^{(k-1)}$  is  $\delta_i^{(k)} W_{ij}^{(k-1)}$ .

However,  $a_j^{(k-1)}$  may have been forwarded to multiple nodes in the next layer(i.e. node m in layer k).

Thus, the total error received at  $a_j^{(k-1)}$  is  $\delta_i^{(k)}W_{ij}^{(k-1)}+\delta_m^{(k)}W_{mj}^{(k-1)}$ .

In fact, we can generalize this to be  $\sum_{i} \delta_{i}^{(k)} W_{ij}^{(k-1)}$ .

Now, we can have the correct error at  $a_j^{(k-1)}$ , we move it across neuron j at layer k-1 by multiplying with the local gradient  $\sigma'(z_j^{(k-1)})$ .

Finally, the error that reaches at  $z_j^{(k-1)}$ , called  $\delta_j^{(k-1)}$  is  $\sigma'(z_j^{(k-1)}) \sum_i \delta_i^{(k)} W_{ij}^{(k-1)}$ .





# Thanks

### FAQ时间

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