# Comparing the Classical and Nonclassical Symmetries of Nonlinear Partial Differential Equations

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2023

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#### Introduction

Our research objective for this project was to calculate the classical and nonclassical symmetry groups for the reduced Gibbons-Tsarev equation and the Born-Infeld equation and compare them.

#### Definition

A symmetry is a transformation that leaves an object invariant.

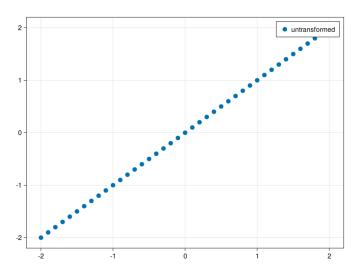
#### Definition

A symmetry is a transformation that leaves an object invariant.

#### Definition

A symmetry is a change that doesn't change anything.

Let's see this in action using the simple linear equation x - y = 0.



### Example (A Non-Example)

- For our first transformation, let's define new variables  $\bar{x} = x + 1$  and  $\bar{y} = y$ .
- Now we rewrite our equation using these new variables.

$$ar x - ar y = 0$$
 by definition  $x+1-y=0$  by substitution  $y=x+1$  by rewriting in slope-intercept form

► This is transformation is not a symmetry:

$$x - y + 1 \neq x - y$$

#### A Transformation that is a Symmetry

### Example (2)

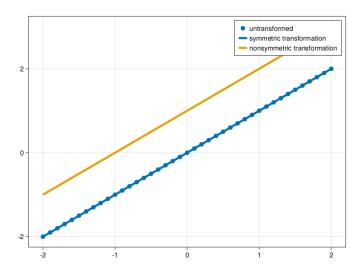
- Let's define some new variables again  $\bar{x} = x + 1$  and  $\bar{y} = y + 1$ .
- Now we rewrite our equation using these new variables.

$$\begin{array}{c} \bar{x}-\bar{y}=0 & \text{by definition} \\ (x+1)-(y+1)=0 & \text{by substitution} \\ (x-y)+(1-1)=0 & \text{by algebra} \\ x-y=0 & \text{by algebra} \\ y=x & \text{by rewriting in slope-intercept form} \end{array}$$

► This transformation is a symmetry:

$$x - y = x - y$$

The graphs of our three equations.



#### Who cares?

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- ► They're cool.

## What is a Differential Equation?

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#### Definition

- ▶ A differential equation is an equation that contains both an unknown function and information about how that function relates to its rates of change.
- ▶ Differential equations show up everywhere we model something using information about how that thing changes over time. This includes everything from population dynamics to the motion of the planets.

# What is a Differential Equation?

As an example, we'll use the equation for a spring.

$$m\ddot{x} + \gamma \dot{x} + \kappa x = 0$$

Here m is the mass,  $\ddot{x}$  is the acceleration,  $\gamma$  is the damping constant (friction),  $\dot{x}$  is the velocity,  $\kappa$  is the spring constant, and x is the position.

# The History of the Born-Infeld and the reduced Gibbons-Tsarev Equations

# The Classical Symmetries of the Born-Infeld and the reduced Gibbons-Tsarev Equations

The Nonclassical Symmetries of the Born-Infeld and the reduced Gibbons-Tsarev Equations

Future Work: Does Integrability Imply Equivalence of Classical and Nonclassical Symmetries?

# Future Work: Does Equivalence of Classical and Nonclassical Symmetries Imply Integrability?