# Daniel Li

https://danielsqli.vercel.app Computer Science, Co-op (+1) 647 996 6232 li.danielsq@gmail.com d363li@uwaterloo.ca

### **SKILLS**

Languages
Frameworks and Tools

C++, Python, Java, HTML/CSS, Java/TypeScript, SQL Node.is, React.js, TensorFlow, Springboot, GraphQL, Git, Next.js

### WORK EXPERIENCE

# Full Stack Developer at DST Systems

May 2020 - August 2020

- Developed a Server Inventorying Tool that scans cloud servers for VM instances and records all installed packages and executables.
- Stores gathered data in a GraphQL database, and created queries and mutations to fetch data using REST api calls from an Express server.
- Displayed all data on a web app created with React and Relay, packaged together with the Express server using Webpack.
- Also worked on Developer Portal, a portal used by companies to retrieve APIs they created.
- Created new pages on the site using Angular and Bootstrap to manage different resources
- Abstracted Java Springboot backend to not be reliant on Kong, and allow client choice of API management service
- Created new REST endpoints to store and retrieve resource configurations with a PostgreSQL database, secured with OAuth 2.0

## **PROJECTS**

### Flower Identification Android App

github.com/danielsqli/FlowerID-App

- Created an app in team of 2 that identifies flower species from a taken picture.
- Used TensorFlow and Keras to create a Convolutional Neural Network, and optimized it with help of visualisation using MatPlotLib.
- Developed app with React Native, integrating the machine learning model into the app locally with TensorflowJS
- Deployed release build of the app to the Play Store

### **EDUCATION**

University of Waterloo (Waterloo, Ontario) Candidate for Bachelors of Computer Science  $September~2019-Present \\ Cumulative~Average:~88.20\%$ 

### **EXTRA-CURRICULAR ACTIVITIES**

#### Team 4001 Robotics – Lead Programmer

2015 - 2019

- Directed programming of robot, and designed teleoperated component, using Object Oriented Programming in Java in an agile environment.
- Brainstormed potential autonomous paths using PID technologies (Proportional Integral Derivative) and optimized with Bézier curves
- Participated in competition and qualified for provincials.