

IPM²: Towards better understanding and forecasting of population dynamics

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1 Summary

2 Models of population dynamics typically aim to predict demographic rates in re-
3 lation to environmental variation. However, they rarely include the diversity of
4 individual responses facing these environmental pressures. When resources become
5 scarce, the performance of low-quality individuals is often the first to suffer. Here,
6 we develop an new model (“IPM²”) that is the combination of an integrated popula-
7 tion (IPM_{pop}) and an integral projection model (IPM_{ind}). The novel IPM² allows
8 including interaction between environmental and individual variables in models
9 of population dynamics as well as forecasting population size and trait distribu-
10 tion accurately. We illustrated this applying all three models to a population of
11 barn swallows. We also studied bias and precision of all three models using three
12 simulated scenarios with no, a homogeneous, and a heterogeneous environmental
13 influence across individual traits on individual survival and reproduction. When
14 the individual responses to environmental variation were heterogeneous, only IPM²
15 was able to predict unbiased population dynamics according to heterogeneous in-
16 dividual performance.

17 Word count=158 and maxi is 150

18 Introduction

19 Animal and plant populations are governed by deterministic and stochastic effects
20 (Leirs *et al.*, 1997; Bjørnstad *et al.*, 1999; Lande *et al.*, 2003). Yet, populations
21 consist of individuals that are unique and hence each individual may respond differ-
22 entially to competition or environmental conditions (Coulson, 2004). For instance,
23 poor environmental conditions affected the survival of inexperienced but not of ex-
24 perience breeders of blue petrels (*Halobaena caerulea*, Barbraud & Weimerskirch
25 2005). In addition, plastic responses may vary among individuals. For exam-
26 ple, the individual phenological responses to climate change are heterogeneous in
27 great tits (*Parus major*) because some individuals were more plastic than others
28 (Nussey *et al.*, 2005). Thus, predicting population dynamics requires knowledge
29 about interactions between individual behaviour and competition and environmen-
30 tal changes (Lavergne *et al.*, 2010) but common models of population dynamics do
31 not allow accounting for these interactions, despite a very active development of
32 analytical methods to understand and predict population dynamics from empirical
33 data in the recent past (e.g. Caswell 2001; Williams *et al.* 2002; Lande *et al.* 2003;
34 Royle & Dorazio 2008)

35 To account for these interactions, here we focus on analytical methods that es-
36 timate demographic rates and include them in a population model, thus that make
37 an explicit link between the level of individuals and the level of the population.
38 A first class of models is known as integrated population model (IPM_{pop}, Besbeas
39 *et al.* 2002; Schaub & Abadi 2011), where count data are jointly analysed with
40 one or more demographic datasets (typically capture-recapture and productivity
41 data). The link between the individual and the population level is provided by a

42 matrix projection model. Estimates of age- and stage-specific demographic rates
 43 and of population growth rates are obtained from these models allowing to under-
 44 stand the contribution of each demographic rate to population dynamics (Schaub
 45 *et al.*, 2012, 2013). The main advantage of this joint analysis of several datasets is
 46 that information about demographic processes, that the count data contain is ex-
 47 ploited, resulting in increased precision of the estimates and the ability to estimate
 48 demographic parameters for which no explicit data have been collected (Besbeas
 49 *et al.*, 2002; Tavecchia *et al.*, 2009). In the context of geographically open popula-
 50 tions, immigration is a relevant demographic process in many populations (Lieury
 51 *et al.*, 2016; Szostek *et al.*, 2014; Schaub *et al.*, 2013) that can be estimated using
 52 IPM_{pop} (Abadi *et al.*, 2010). A limitation of current IPM_{pop} is that they assume
 53 all individuals in a given age- or stage-class are identical. Individually different
 54 responses to changes in the environment or competition and their effects on pop-
 55 ulation dynamics can therefore not be studied.

56 A second class of models is the integral projection models (IPM_{ind}). Here the
 57 focus is on individual demographic performances and on how they affect popula-
 58 tion dynamics. A population is therefore described by the distribution of one or
 59 several individual continuous traits (Easterling *et al.*, 2000; Rees *et al.*, 2014; Ellner
 60 *et al.*, 2016). Usually four types of individual data are used: survival and repro-
 61 duction data allow the estimation of the influence of individual traits on survival
 62 and reproductive rates. With inheritance data we estimate how individual traits
 63 are inherited from parents to offspring and with transition data we estimate the
 64 change in these traits as individuals get older. If environmental data or population
 65 density are included as well, IPM_{ind} allow an understanding of how environmental
 66 conditions or competition influence the development and inheritance of individ-

67 ual traits and how in turn these traits affect individual survival and reproductive
68 performance under these environmental pressures (Ozgul *et al.*, 2010; Plard *et al.*,
69 2014). A main advantage of IPM_{ind} is therefore that one can study the interac-
70 tion of individual traits and environmental changes affecting demography. A main
71 limitation of current IPM_{ind} is no data at the population level are included. Ac-
72 cordingly, the accuracy of population projections based solely on individual data
73 has been questioned (Ghosh *et al.*, 2012). For example, population predictions can
74 be biased if demographic processes for which no data are available are ignored.

75 Here, we develop a new class of model that represents the combination of an
76 IPM_{pop} and an IPM_{ind}: the integrated integral projection model (IPM²). We show
77 that our new model enjoys the advantages of both individual analytical frame-
78 works while at the same time it overcomes their individual weaknesses. The IPM²
79 enables us to study the mechanisms that operate at the individual level and shape
80 the population dynamics while keeping population predictions close to observed
81 population size, even when individual responses to environmental variation are
82 heterogeneous.

83 Material and Methods

84 To illustrate the difference between models and also as a basis for the simulation
85 (see Appendix S1 and Table S1), we consider a population of an hypothetical
86 passerine bird species with two age classes: fully grown nestlings (juveniles) and
87 adults. First year (juvenile) survival differs from adult survival, first breeding
88 occurs at age 1 and reproductive performance is invariant to age. All individuals
89 are assigned to one heritable, continuous individual trait that is constant with age.

90 In addition, an environmental variable is created. Depending on the scenarios (see
 91 later), the demographic rates may or may not be affected by the individual trait,
 92 by the environmental variable or by an interaction between the two. We assume
 93 that density dependence is absent. We describe the female part of the population
 94 and adopt a model for a post-breeding census.

95 In the following, we denote matrices in capital bold, vectors in bold lowercase,
 96 functions in the form $F()$ and constants by capital letters. Parameters of a function
 97 F are given by the intercept i_F and the slopes linked to the environmental variable
 98 b_F , to the individual trait c_F and to their interaction d_F . We first introduce the
 99 integrated population model (IPM_{pop}), the the integral projection model (IPM_{ind})
 100 and finally develop the new model.

101 What is an Integrated Population Model IPM_{pop}?

102 We define a population model that includes demographic stochasticity and envi-
 103 ronmental variation as

$$\begin{aligned} N_{t+1}^A &\sim Bin(S_t^A, N_t^A) + Bin(S_t^J, N_t^J) \\ N_{t+1}^J &\sim Pois(R_t * N_{t+1}^A) \end{aligned} \tag{1}$$

104 where the number of juveniles in year t is N_t^J and, the number of adults N_t^A ,
 105 juvenile survival is S^J , adult survival S^A and reproductive output is R . One or
 106 several demographic rates can be functions of environmental covariable(s) (Table
 107 1). However, within an age class all individuals are assumed to be identical. The
 108 population model is the process model of a state-space model that we link to the

109 count data (C_t^1).

$$C_t^1 \sim \text{Pois}(N_t^A) \quad (2)$$

110 Three data sets are used for the integrated population model: annual num-
111 ber of breeding females (count data: $\mathbf{C1}$), age-specific survival data and data
112 on reproduction. The annual demographic rates are estimated from the survival
113 and reproductive data, for which we use binomial and Poisson regression models,
114 respectively. The joint analysis requires the formulation of the joint likelihood
115 which is the product of the single data likelihoods, i.e. of the state-space, binomial
116 and Poisson regression models. For more details about constructing integrated
117 population models, see Besbeas *et al.* (2002) and Schaub & Abadi (2011).

118 What is an Integral Projection Model, IPM_{ind} ?

119 In an IPM_{ind} , a population is not described by a single number representing its
120 size but by a frequency distribution of one or several individual traits (Table 1).
121 Moreover, demographic rates are not only age- or stage-specific, but in addition
122 depend on continuous individual traits (z). For the sake of simplicity, we here
123 consider z to be a single, fixed continuous individual trait but it could be replaced
124 by several continuous and time-dependent traits and may represent body mass,
125 laying date or degree of parasitism, for instance. Three datasets (survival, re-
126 productive and inheritance) are used to parameterize a simple IPM_{ind} modeling
127 the influence of the fixed continuous trait on individual survival and reproductive
128 success. The inheritance of this fixed trait from parents to nestlings is estimated
129 from the inheritance data.

IPM_{ind} are implemented in practice using the midpoints rule as a numerical integration method (see e.g. section 8.3.3 in Kéry & Royle 2016). The continuous trait z is divided into M bins and the bin-value midpoints $\mathbf{z} = [Z_1 Z_2 \dots Z_M]$ are the medians of these trait classes. IPM_{ind} use similar matrix projection models as IPM_{pop} but each age class is subdivided into a very large number of trait classes.

Diagonal matrices with survival (\mathbf{S}) and reproductive rates (\mathbf{R}) of individuals in each trait class are constructed based on the available data. Nestlings inherit a value of the individual trait depending on the maternal trait. This process is described by the inheritance matrix (\mathbf{I}). Each entry of \mathbf{I} is the probability for the nestling of a mother with trait z inheriting trait z' . The distribution of all individuals of a given age a is described by the vector \mathbf{n}^a of length M (number of artificial trait classes), and the change of this distribution over time is calculated based on \mathbf{S} , \mathbf{R} and \mathbf{I} .

$$\begin{aligned} \mathbf{n}_{t+1}^{a+1} &= \mathbf{S}_t^a \mathbf{n}_t^{a'}, \quad a \geq 1 \\ \mathbf{n}_{t+1}^1 &= \sum_{a>1} \mathbf{I} \mathbf{R}_t \mathbf{n}_{t+1}^{a'} \end{aligned} \tag{3}$$

where $\mathbf{n}^{a'}$ is the transpose (column vector) of \mathbf{n}^a .

The individual trait and the environmental variable influence survival and reproduction in our hypothetical population. Nestlings inherit a trait depending on the maternal trait but not on the birth environment. Intercepts and slopes for survival and reproductive rates ($S^J(z, t)$, $S^A(z, t)$ and $R(z, t)$) are estimated independently from each other from the survival and the reproductive data. The diagonal vector of \mathbf{S}_t^a is estimated with $S^J(z, t)$ if $a = 1$ and with $S^A(z, t)$ other-

150 wise. In our hypothetical example, we assume linear functions, but others could
 151 be chosen as well.

$$\text{logit}(S^J(z, t)) = i_S + b_S * e_t + c_S * \mathbf{z} + d_S * e_t * \mathbf{z} \quad (4)$$

$$\text{logit}(S^A(z, t)) = i_S + i_{a,S} + b_S * e_t + c_S * \mathbf{z} + d_S * e_t * \mathbf{z} \quad (5)$$

$$\log(R(z, t)) = i_R + b_R * e_t + c_R * \mathbf{z} + d_R * e_t * \mathbf{z} \quad (6)$$

$$I \sim \mathcal{N}(\mu_I(z), \sigma_I) \quad (7)$$

$$\mu_I(z) = i_I + c_I * \mathbf{z} \quad (8)$$

152 where $i_{a,S}$ is the age effect (adult vs. juvenile) in annual survival. For more details
 153 about integral projection models, see Easterling *et al.* (2000); Coulson (2012); Rees
 154 *et al.* (2014) and Ellner *et al.* (2016).

155 Combining IPM_{pop} and IPM_{ind} into IPM²

156 In our new IPM² (Fig. 1), we combine IPM_{ind} and IPM_{pop}. As in IPM_{ind}, the
 157 population is described by the distribution of one or several individual traits.
 158 Thus, the population development is the same as the one described for IPM_{ind}
 159 (Table 1). The population size can also be summarized for each age/stage class by
 160 integration over individual trait distributions. This offers the possibility to include
 161 count data in the model in addition to the datasets used for IPM_{ind}. In contrast
 162 to an IPM_{ind}, the different datasets are now analysed jointly as in an IPM_{pop}. A
 163 state-space model whose state process is given by eq (4) is used for the integration
 164 of the different datasets. The count data consists of the number of counted female

165 adults and can include the distribution of their individual trait in each year. The
 166 observation process of the state-space model includes therefore the fit between the
 167 size of the adult population $\sum_{a>1} \mathbf{n}_t^a$ and the count data \mathbf{y}_t .

$$\text{population size : } \sum_z y_{z,t} \sim \mathcal{P}\left(\sum_{z,a>1} n_{z,t}^a\right) \quad (9)$$

168 If the count data also include information about the individual trait (count data $C2$
 169 or $C3$, see below), the observation process also link the observed to the predicted
 170 distributions of the individual trait in each year:

$$\text{distribution of trait : } \mathbf{y}_t \sim \text{Density}\left(\sum_{a>1} \mathbf{n}_t^a\right) \quad (10)$$

171 The *Density()* function gives the probability for observed and predicted dis-
 172 tributions of being the same independently of population size (fig. S2).

173 We used the Bayesian framework for the analysis because of its ease to propa-
 174 gate uncertainty from each dataset to demographic and population growth rates.
 175 The likelihoods of the four datasets are multiplied to get a joint likelihood on which
 176 inference from the model is based.

177 **Simulation study**

178 To compare the performance of IPM^2 with IPM_{pop} and IPM_{ind} , we simulated data
 179 from our hypothetical population (see fig. S1). The simulation is described in
 180 detail in Appendix S1 (see Fig. S1). We assume that the sampled data are not
 181 subject to imperfect detection. This simplifies the calculations, but is not a gen-
 182 eral assumption of the models, as we will show in the empirical example. Three

different scenarios were included in which: demographic rates were influenced by an individual trait only (I), by the additive effects of an environmental trend and an individual trait (II) or by the interactive effect between an environmental trend and an individual trait (III). We simulated 500 populations (replicas) over 20 years under each of these 3 scenarios and sampled individuals to yield survival, reproduction, inheritance and count datasets. To analyse which amount of additional information is needed at the population level to correctly predict population dynamics, three different types of count datasets were simulated; *C1*: contained the counts of females only without any measures of the individual trait; *C2*: contained the counts of females as well as categorical information about the individual trait of each counted female (e.g., in the form of short, medium or tall female size); *C3*: contained the counts of females and exact measure of the individual trait of each counted female. The percentage of females sampled to get the survival, reproductive and the count data did not influence the results and was thus set to 50%. Inheritance data are often the most challenging data-type to gather in the field. Hence, we investigated the influence of the percentage of inheritance data sampled in our simulation analysis and reported the results for 20% and 2%.

Analysis. Each sampled population was analyzed with 5 different models:

- IPM_{pop} using the number of surviving individuals each year from the survival data-set, the number of recruits per female each year from the reproduction dataset and the number of females counted each year from *C1*.
- IPM_{ind} using the survival, reproduction and inheritance dataset including the individual trait.
- IPM^2_{C1} , IPM^2_{C2} and IPM^2_{C3} using count data (either *C1*, *C2* or *C3*) in

207 addition to the datasets that are used for IPM_{ind} .

208 We scaled individual trait as well as the environmental trend to improve con-
209 vergence. We fitted the models in a Bayesian framework using program NIM-
210 BLE (NIMBLE Development Team, 2016) run from R (R Core Team, 2014). We
211 chose diffuse prior distributions for all parameters and generated 3 chains of length
212 50,000, using the first 25,000 as a burn-in. We used the 10 first years of each sim-
213 ulation to estimate parameters and demographic rates. We then projected the
214 population into the future (10 following years) and compared these predictions
215 with the truth in the simulated data. An assessment of the predictive abilities
216 of the models is important for judging their suitability to predict consequences of
217 future environmental changes.

218 To compare the performance of these five models, we first compared the 95%
219 interval (over the 500 simulations) of posterior means of the demographic rates
220 of the first ten years with the true demographic rates. Second, we compared the
221 predicted demographic rates of the ten following years with the true ones. Finally,
222 we compared the bias ($\text{posterior mean} - \text{truth}$) and precision (using mean squared
223 errors $MSE = \text{bias}^2 + \text{variance}$) of estimators of the slopes of each function used
224 to derive the demographic rates using IPM_{ind} and the three IPM^2 .

225 Application to barn swallows

226 The barn swallow (*Hirundo rustica*) is a short-lived, double breeding and long-
227 distance migratory passerine bird that breeds in Europe in agricultural landscapes
228 (Grüebler *et al.*, 2010). Laying date of the first annual brood was chosen as the in-
229 dividual continuous trait to describe the distribution of females in the population.

230 The laying date has a strong impact on the reproductive output; later first broods
 231 yield lower annual reproductive output (Grüebler & Naef-Daenzer, 2008). More-
 232 over, fledglings from an early brood have longer life expectancy than fledglings
 233 from late broods (Saino *et al.*, 2012). The annual dynamics of the laying-date
 234 distribution is described using five functions:

- 235 • **annual number of successful clutches** and **number of fledglings** per
 236 successful clutch of a pair according to the laying date of the first clutch
 237 ($N = 2605$ pairs).
- 238 • **annual survival** according to individual age (< 1 year old or older), sex
 239 and laying date of the first clutch ($N = 12222$ individuals). Barn swallows
 240 were subject to imperfect detection, hence, we used capture-mark-recapture
 241 models to estimate the recapture probability and the annual survival based
 242 on previous analysis of these populations (Schaub *et al.*, 2015).
- 243 • the **transition** between successive annual laying dates of first clutches (using
 244 $N = 1053$ duos of successive laying date of first clutches). In contrast to the
 245 simulation study we here included a transition function, because laying date
 246 is not a fixed individual trait.
- 247 • the **inheritance**: laying date of first clutches according to birth laying date
 248 ($N = 192$ filiations) and whether the bird as a nestling was born into a first
 249 or a second (including also the rare third broods) brood.

250 We used data sampled in 12 populations located throughout Switzerland from
 251 1997 to 2004 (see Schaub & von Hirschheydt 2009; Schaub *et al.* 2015; Grüebler
 252 *et al.* 2010 for more details) to estimate the intercept and slopes of these functions.

253 Variation among populations was taking into account by including an effect of a
 254 site-specific environmental variable. We used spring precipitations (sum across
 255 March to June) as an index of the environmental conditions influencing the avail-
 256 ability of resources at each site. Using an IPM_{C3}^2 and an IPM_{ind} , we tested the
 257 main and interaction effects of individual laying date and spring precipitation on
 258 the five functions. Using an IPM_{pop} , we investigated the influence of spring precip-
 259 itation only on annual survival, annual number of successful clutches and number
 260 of fledglings per successful clutch. Priors and MCMC settings were set identically
 261 to the ones used in the simulation study. For each model, we conducted vari-
 262 able selection iteratively by use of 95% credible intervals (CRI). If the CRI of the
 263 interaction term included zero, we removed it, refitted the model with the main
 264 effects only and then repeated this for the main effects of individual laying date
 265 and spring precipitation in the different functions.

266 As count data, we summed the number of breeding pairs in four (out of the
 267 12) populations that were surveyed every year from 1997 to 2003. To estimate the
 268 average demographic rates for the global Swiss population, we used the average of
 269 spring precipitation over sites. The Swiss population was geographically open and
 270 thus emigration and immigration has to be addressed. Emigration was already
 271 accounted for, because we used capture-recapture data with which apparent sur-
 272 vival, the probability of surviving and staying in the population was estimated.
 273 Immigration was estimated when possible (using IPM_{pop} and IPM_{C3}^2) with the
 274 assumption that the distribution of laying dates among immigrants was the same
 275 as the distribution of laying dates of residents.

276 We estimated the demographic rates of the Swiss population from 1997 to 2004
 277 under each model (IPM_{pop} , IPM_{ind} and IPM_{C3}^2). Finally, we used the three models

278 to forecast the population development of the barn swallows from 2005 to 2015
279 across Switzerland. We compared these predictions with the annual population
280 index of barn swallows compiled from bird monitoring data sampled at 267 1km²
281 plots across Switzerland (Sattler *et al.*, 2016).

282 Results

283 In most cases, the three models IPM²_{C3}, IPM²_{C2} and IPM²_{C1} yielded very similar
284 estimates that were very close to true values, so we report the results for the three
285 of them together.

286 Estimation of demographic rates

287 In scenarios I and II, the agreement of estimates between all models and true sim-
288 ulated values was particularly good (Fig. 2). Generally, the novel IPM² produced
289 more precise estimates than the two “simple” IPMs. 95% intervals of population
290 growth rate were 83% and 67% larger in IPM_{pop} than in IPM² and 33% and 42%
291 larger in IPM_{ind} than in IPM² on average over the 10 first years of scenarios I and
292 II, respectively.

293 In scenario III, the environmental pressure was stronger on individuals with a
294 large than a small trait value, which results in a faster adaptation of the former
295 to changing environmental conditions. Estimates of demographic rates from the
296 IPM_{pop} were biased in most years (Fig. 2). IPM_{ind} over-estimated all demographic
297 rates (mean of juvenile and adult survival and reproduction were 17%, 1% and 30%
298 higher than true values, on average) and population growth rate (4% higher than
299 true values, on average) at the end of the 10 first years. Moreover 95% intervals of

annual demographic rates were particularly large showing that IPM_{ind} converged far from true values in some of the simulations (fig. 2). These errors were caused by the non linearity of the reproductive function that induced an increase of the mean reproduction and of the size of the individuals recruited in the population over time. The average individual trait value of adults predicted under IPM_{ind} could be 10 times higher than truth at the end of the first 10 years. This never happened under IPM^2 . Estimates of demographic rates under IPM^2 were similar to true values.

Population forecasting

The demographic rates and population growth rate could reliably be predicted by all models under scenarios I and II (fig. 3). In scenario III, however, only predictions under IPM^2 were accurate. IPM_{pop} underestimated most demographic rates and consequently also population growth, the latter up to 64% in the final predicted year. By contrast, IPM_{ind} overestimated most demographic rates and hence population growth rate, the latter up to 106% in the final year.

Parameters of survival and reproductive functions

Mean estimates of the intercept and slope parameters influencing demographic rates were accurate and similar in IPM_{ind} and the three IPM^2 (fig. S3). In all scenarios, standard deviations of the slopes of the survival and the reproductive functions were higher in IPM_{ind} than in IPM^2 , resulting in higher MSE in IPM_{ind} . Thus, estimates were more precise using IPM^2 .

Parameters of the inheritance function

The estimates of the slope of the inheritance function were slightly underestimated but more precise using IPM^2 than IPM_{ind} in all scenarios and particularly in scenario III (fig. 4, on average in this scenario, the slope values were differing from the true value by 11% and 3% using IPM^2 and IPM_{ind} , respectively).

When only 2% of the mother-offspring filiations were sampled to estimate the inheritance function, the benefit in terms of precision from the IPM^2 compared to the IPM_{ind} was even larger (fig. 4). Among the three models of IPM^2 , IPM^2_{C3} and IPM^2_{C2} produced slightly more precise estimates than IPM^2_{C1} (fig. 4).

Population dynamics of Swiss barn swallows

We found a significant negative influence of spring precipitation on annual survival of barn swallows (slope: -0.10 95% CRI:[-0.16;-0.03]) but not on reproductive rates when the data were analysed with the IPM_{pop} (Table S2). However, using IPM^2 , we found that demographic rates were also influenced by individual laying date of the first clutch. Individual laying date influenced negatively annual survival (slope:-0.15 [-0.23;-0.07], Table S2), the annual number of successful clutches and the number of fledglings per successful clutch (figs. S4 and S5). Successive annual laying dates of first clutches were positively correlated and positively related to precipitation (fig. S6). First year laying date was not influenced by maternal laying date ([-0.16;0.16]) but was delayed in years with high precipitation (fig. S7). The results from IPM_{ind} were similar to those under an IPM^2 (Table S2), except that 95% CRI of the effect of precipitation on first year laying date and on annual survival included 0 ([-0.03;0.22] and [-0.08;0.07], respectively, Table S2) and were

thus removed from the model. The annual demographic rates based on the three models were similar in most years (fig. S8). Immigration rate estimated under IPM_{pop} and IPM^2 was substantial (Table S2).

The predictions of the population index of barn swallows during the 12 years following the study period were similar from IPM^2 and IPM_{pop} (fig. 5), but very different from IPM_{ind} . The predictions from IPM^2 and IPM_{pop} were remarkably similar to the population index estimated from independent monitoring birds data. The predictions of IPM^2 including individual laying date were slightly better than the ones of IPM_{pop} (predictions from IPM^2 vs. IPM_{pop} explained 46% vs. 44% of the variation in the Swiss national index, respectively). IPM_{ind} was unsuccessful for prediction and explained only 9% of the variation.

Discussion

We developed a population model that can estimate heterogeneous individual demographic responses in a changing environment and predict the resulting population dynamics. This integrated integral projection model (IPM^2) is a combination of the existing integral projection and integrated population models and shares the key benefits of each of them. Basically, the new model can either be regarded as an extension of an integral projection model that includes count data in addition, or as an extension of an integrated population model that considers individual traits by including additional information about the link of individuals traits on demographic rates and their inheritance. Key benefits are that the influence of individual traits on population dynamics can be assessed, that parameter estimates become more precise, that population dynamics can be estimated including

demographic processes for which no explicit data have been collected, and that a smaller amount of the difficult to gather affiliation data needs to be collected. The model yielded accurate population predictions even if the individuals react differentially to environmental changes.

The simulation study showed that the count data without information about the individual traits (IPM^2_{C1}) is enough to obtain accurate population predictions, unless inheritance data are particularly scarce. In this case it is preferable to include a rough measure (small, medium, large) of each counted individual using IPM^2_{C2} . Thus, the count data that need to be included generally do not require additional capture of individuals.

Model assumptions

Here we used a very simple and specific life cycle model with a single trait and a single environmental covariable, but in principle IPM^2 can be adapted to any life cycle by adapting the model structure and by adding several traits or functions (linear or not) as used in other IPM_{ind} (Ellner *et al.*, 2016). Influence of density as well as intra- or inter-species competition can also easily be included in an IPM^2 . In our simple IPM^2 , we did not include demographic stochasticity but assumed that individual heterogeneity in demographic performance was shaped by individual traits only as usually done in IPM_{ind} . In IPM_{pop} , all individuals in a given age- or stage-class are assumed to be identical and, annual heterogeneity in individual performance is created by demographic stochasticity only. Both demographic stochasticity and individual heterogeneity linked to identified or unidentified individual traits are expected to influence population dynamics (Cam *et al.*, 2016). It

390 is an asset of the new IPM² that demographic stochasticity as well as other sources
391 of individual heterogeneity can easily be included (Coulson, 2012).

392 The joint likelihood of the IPM² is formed as a product of the single-data likeli-
393 hoods and therefore requires the assumption of independence among datasets. The
394 violation of this assumption can affect parameter estimates (Besbeas *et al.*, 2009),
395 but the impact is often non-existent or irrelevant (Abadi *et al.*, 2010; Schaub *et al.*,
396 2015). In the case of our new model, we have not explicitly explored the effects
397 of the violation of the independence assumption, but we note that our simulated
398 data are dependent to some degree because we simulated the data collection to
399 mimic a real field study. Since the performance of the estimators was good, we
400 think that the violation of this assumption is not a serious issue for the specific
401 models that we have used. However, more research should evaluate this issue in
402 the future and possibly develop more general models that can handle dependent
403 datasets.

404 The reproductive function linking reproductive success to individual trait was
405 non-linear in the simulations, increasing exponentially with the individual trait.
406 This has strongly contributed to the large biased predictions of IPM_{ind}. Individual
407 heterogeneity can influence population dynamics twice as much when the functions
408 are not linear as when the functions are linear (Plard *et al.* 2016, Jensen inequality,
409 Ruel & Ayres 1999). Nevertheless, this assumption was justified because repro-
410 ductive output is often modeled with a log link in empirical analyses. Moreover, in
411 some species of plants or oviparous animals, it is common that reproductive out-
412 put increases exponentially with individual size, for instance (Dauer & Jongejans,
413 2013; Miller *et al.*, 2012; Vindenes, 2014).

Application to barn swallow

Forecasting of the size of the Swiss population of barn swallows under IPM² and IPM_{pop} was very similar to the independent population index estimated from monitoring data. The main reason why IPM_{ind} was unsuccessful for forecasting is that this model did not include immigration. This result shows that barn swallow population dynamics was strongly driven by the effect of spring precipitation on annual survival and by immigration.

The benefit of using IPM² instead of IPM_{pop} can be found in our better understanding of the mechanisms linking spring precipitation to demographic rates of the barn swallow. The IPM_{pop} only evidenced that there was a negative effect of spring precipitation on annual survival. However the IPM² allowed us understanding that spring precipitation influenced negatively directly and indirectly annual survival. High spring precipitation had an indirect negative effect on individual survival because it also led to delay individual laying date of the first clutch. The IPM² showed that this phenological delay influenced negatively individual survival but also reproductive outputs. The latter is a well-known result in most birds (Perrins, 1970) but cannot be included in an IPM_{pop}.

Population forecasting in a changing environment needs IPM²

Whenever individual traits affect demographic rates with interacting environmental co-variables (as in scenario III), only IPM² produced adequate predictions. This was to be expected, because IPM_{pop} do not include individual traits and because IPM_{ind} do not make the link between predictions at the population level and observed data.

437 When individual demographic rates are influenced linearly and homogeneously
 438 by annual environmental variables, IPM_{pop} give accurate estimates and predictions
 439 of population size (Johnson *et al.*, 2010; Abadi *et al.*, 2017). However the influ-
 440 ence of any environmental variable is often followed by a heterogeneous individual
 441 adaptive or plastic response that will influence demographic rates in turn. For
 442 instance, individual laying date is often a plastic trait that responds to environ-
 443 mental changes and then has repercussions on reproductive success as shown in
 444 our barn swallow population and in many other bird populations (Charmantier
 445 & Gienapp, 2014). Understanding how individual traits shape demography and
 446 population dynamics cannot be performed using an IPM_{pop} while it is needed to
 447 improve our understanding of the evolution of quantitative traits.

448 In this direction, IPM_{ind} are very useful to address various questions in eco-
 449 evolutionary dynamics (Coulson *et al.*, 2010; Smallegange & Coulson, 2013) at
 450 equilibrium or in constant environment. However, when using an IPM_{ind} to pre-
 451 dict population dynamics over successive years in variable environment, one might
 452 check that the distribution of individual trait (see also detecting individual evic-
 453 tion, Williams *et al.* 2012) as well as population size remain close to what is
 454 observed in the data. IPM^2 corrected for the former possible bias by slightly un-
 455 derestimating the slope of the inheritance function in our simulation analysis. For
 456 the latter bias or when working in open populations, IPM^2 allows estimating de-
 457 mographic processes for which not much data are available. For instance, IPM^2
 458 allowed us to include immigration in the population models for the barn swal-
 459 lows (Abadi *et al.*, 2010). Moreover, IPM^2 helps to get better estimates of the
 460 inheritance function when the inheritance data are scarce. Finally, as a general
 461 benefit, modeling demographic rates in the same framework together with count

462 data allows including easily spatial or temporal covariations between survival and
463 reproductive rates, for instance and investigate their influence on population dy-
464 namics (Elderl & Miller, 2016; Koons *et al.*, 2016).

465 Conclusion

466 Responses to environmental pressures can vary among individuals and are the main
467 drivers of pattern of eco-evolutionary dynamics. To forecast population dynamics,
468 we need to understand the individual drivers of populations and thus to include
469 individual responses to their environment while following the entire population.
470 As a consequence, combining data both at the individual and at the population
471 level which is done in the new IPM² will help our predictions to become more
472 accurate and thus more powerful in science and more relevant in management.

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611 Press, San Diego.
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614 **Table 1:** Comparison between IPM_{pop} , IPM^2 and IPM_{ind} .

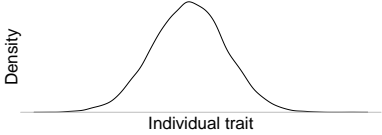
| | IPM_{pop} | IPM^2 | IPM_{ind} |
|-------------------|--|--|---------------------------|
| Population size | N_t^A, N_t^J |  | |
| Model | $\begin{pmatrix} R_t * S_t^J & R_t * S_t^A \\ S_t^J & S_t^A \end{pmatrix}$ | $\begin{pmatrix} I * R_t * S_t^J & I * R_t * S_t^A \\ S_t^J & S_t^A \end{pmatrix}$ | |
| Demographic rates | $\text{logit}(S^J(t)) = i_S + b_S * e_t$ $\text{logit}(S^A(t)) = i_S + i_S^a + b_S * e_t$ $\text{log}(R(t)) = i_R + b_R * e_t$ | $\text{logit}(S^J(z, t)) = i_S + b_S * e_t + c_S * z$ $\text{logit}(S^A(z, t)) = i_S + i_S^a + b_S * e_t + c_S * z$ $\text{log}(R(z, t)) = i_R + b_R * e_t + c_R * z$ $I \sim \mathcal{N}(\mu_I = i_I + c_I * z, \sigma_I)$ | |
| Covariables | Environmental | Environmental and individual | |
| Heterogeneity | Individuals in a given age-class are identical | Individuals in a given age-class differ by their phenotype | |
| Data | Count data | | |
| | Survival pop data | Survival ind data | |
| | Reproduction pop data | Reproduction ind data Inheritance ind data | |
| Advantages | Keep population predictions close to reality | | |
| | Can estimate latent demographic processes | | |
| | More accurate estimates | | |
| | | Eco-evolutionary dynamics Include individual mechanisms Can predict population dynamics including heterogeneous individual responses in a changing environment | |

Figure captions

Figure 1: Conceptual overview of an IPM² describing the dynamics of the distribution of a continuous fixed individual trait (such as wing length) in a population. The survival (Sdata), reproductive (Rdata) and inheritance (Idata) datasets are used to estimate the influence of the individual trait on demographic rates. These estimates are also influenced by the fit between the predicted population size and its distribution each year and the count dataset. *C1* includes only counts, *C2* includes counts and a classification of the individual trait of each counted individual, *C3* includes counts and the precise value of the individual trait of each counted individual. *C1*, *C2* or *C3* are used to fit an IPM²_{*C1*}, an IPM²_{*C2*} or an IPM²_{*C3*}, respectively.

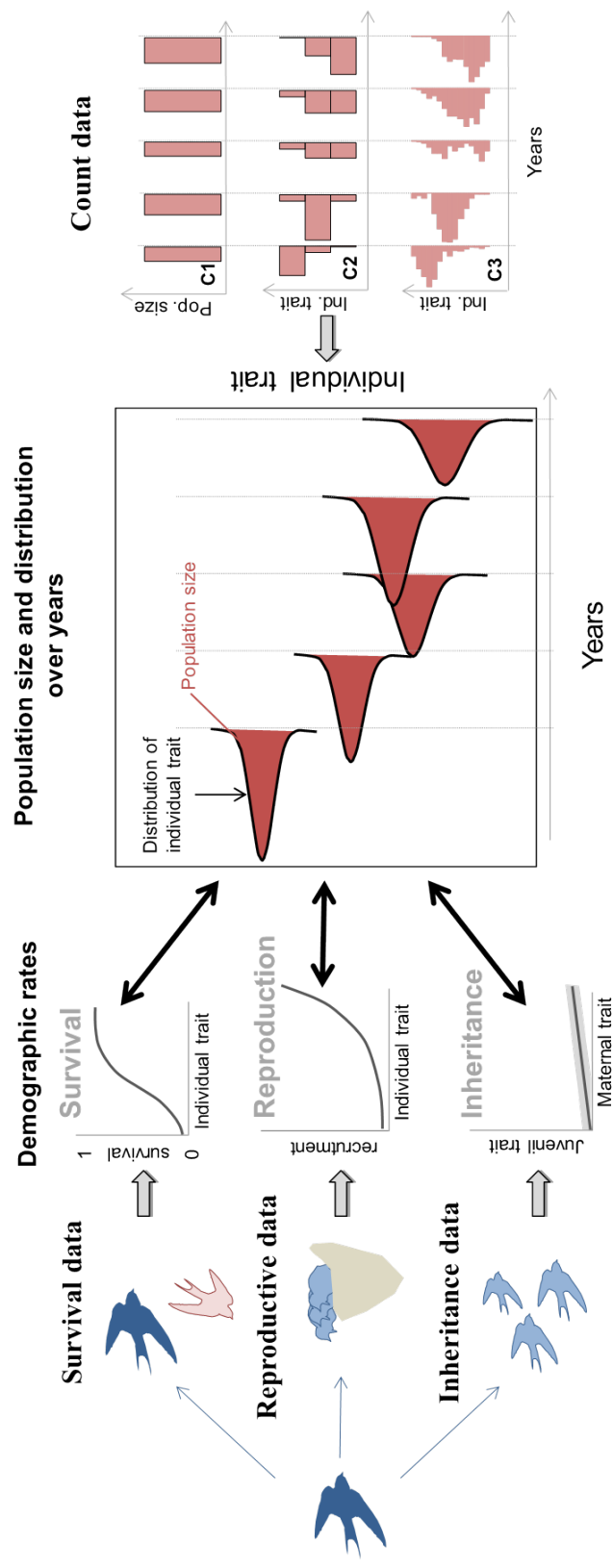
Figure 2: Estimates of demographic rates and population growth rates during years 7 to 10 under scenarios I (including only an effect of the individual trait) and II (including additive effects of the individual and environmental covariables) and during the 10 first years for scenario III (including interactive effects of the individual and environmental covariables) using the 5 different models: IPM²_{*C3*}, IPM²_{*C2*}, IPM²_{*C1*}, IPM_{ind} and IPM_{pop} (in this order from left to right). Average (points) and 95% interval (vertical lines) of posterior means from 500 simulations are represented. Averages and 95% intervals of the true demographic rates estimated over 500 sampled populations are represented using a dashed black line and a grey rectangle, respectively.

Figure 3: Forecasting of demographic rates and population growth rates during the years 11 to 20 under the three scenarios using the 3 different models: IPM²_{*C3*}, IPM_{ind} and IPM_{pop} (in this order from left to right). Average (points) and 95%

interval (vertical lines) of posterior means from 500 simulations are represented. IPM^2_{C1} and IPM^2_{C2} are not presented because they gave the same results as IPM^2_{C3} . Averages and 95% intervals of the true demographic rates estimated over 500 sampled populations are represented using a dashed black line and a grey rectangle, respectively.

Figure 4: Comparison of bias and mean squared errors (MSE) of the slope of the inheritance function estimated under the three different scenarios when 20% or 2% of the filiation data were collected. Boxplots of estimators from IPM_{ind} and IPM^2 are in grey and white respectively. IPM^2_{C3} , IPM^2_{C2} and IPM^2_{C1} are presented in white in this order from the left to the right.

Figure 5: Predictions of the Swiss barn swallow population index and their 95% credible intervals from 2004 to 2015 using model IPM^2_{C3} (solid red lines), IPM_{pop} (dashed blue lines) and IPM_{ind} (dotted green lines). Models were fitted using data collected on 12 populations in Switzerland from 1997 to 2003. The 95% confident interval of the Swiss population index estimated from independent monitoring bird data is represented in grey.



34
Figure 1

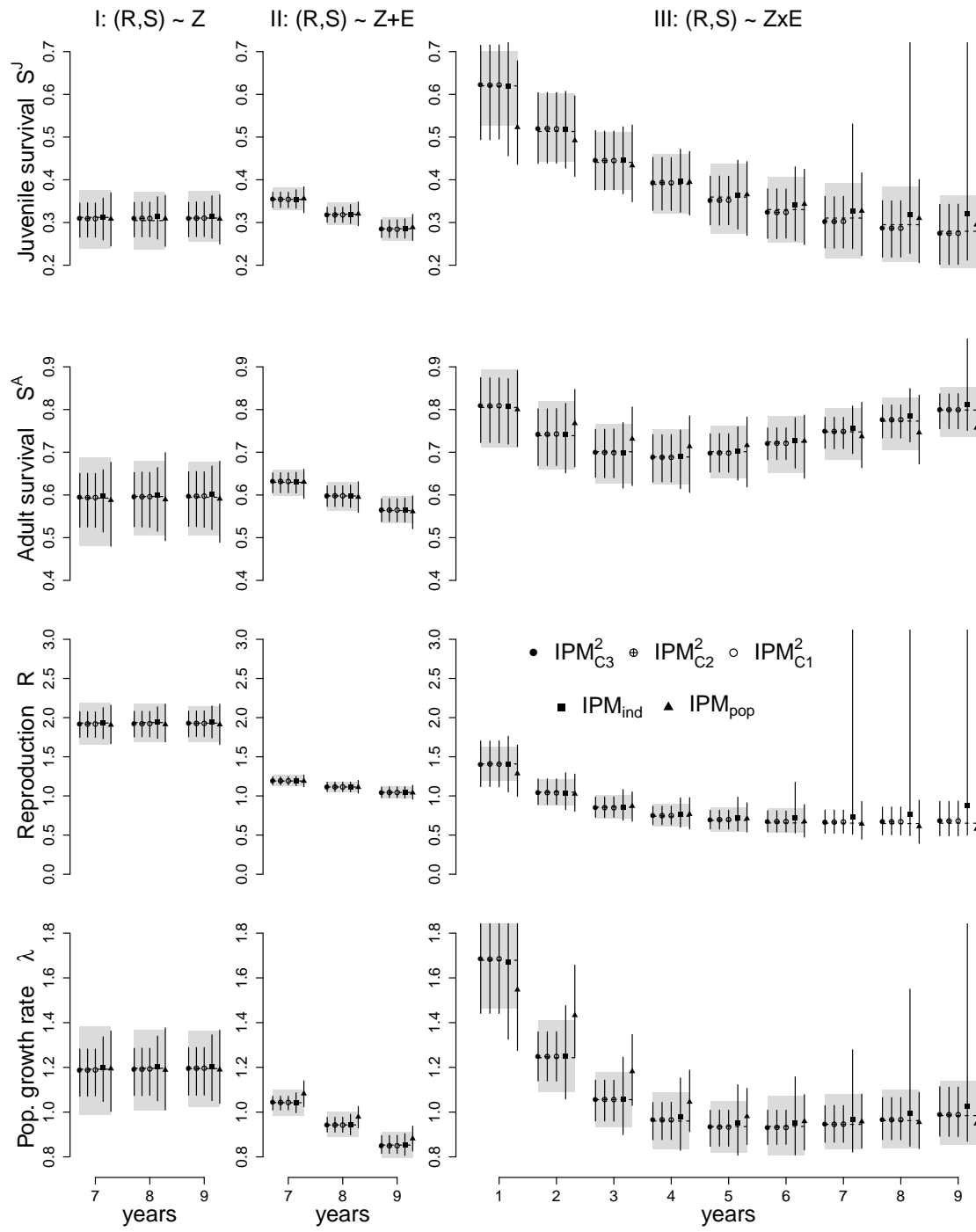


Figure 2

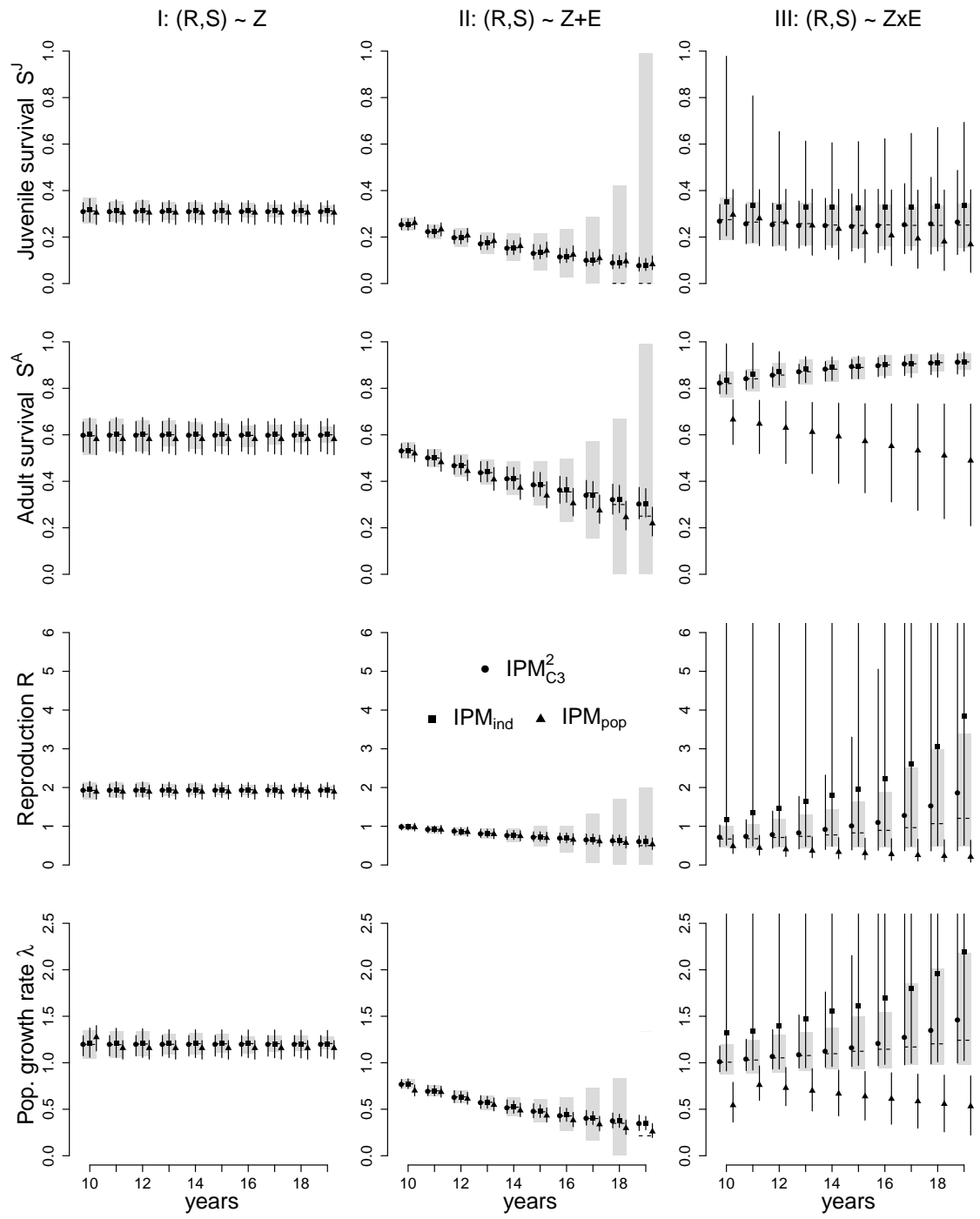


Figure 3

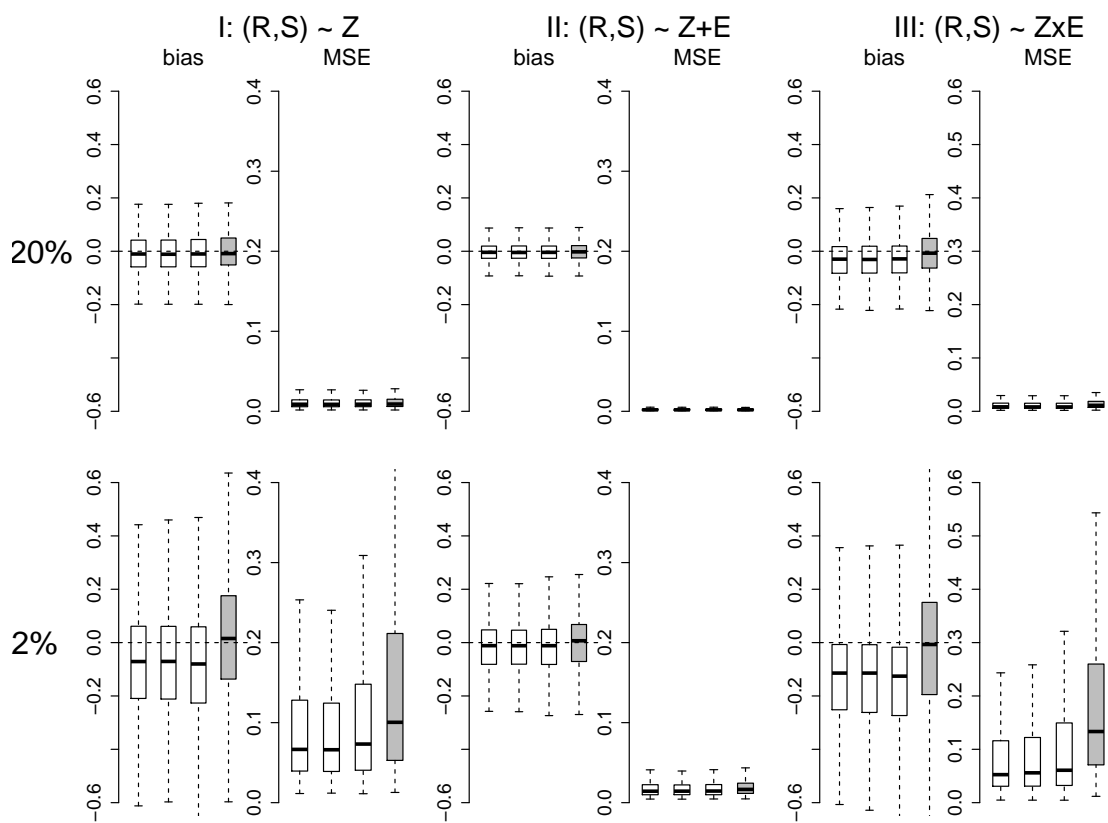


Figure 4

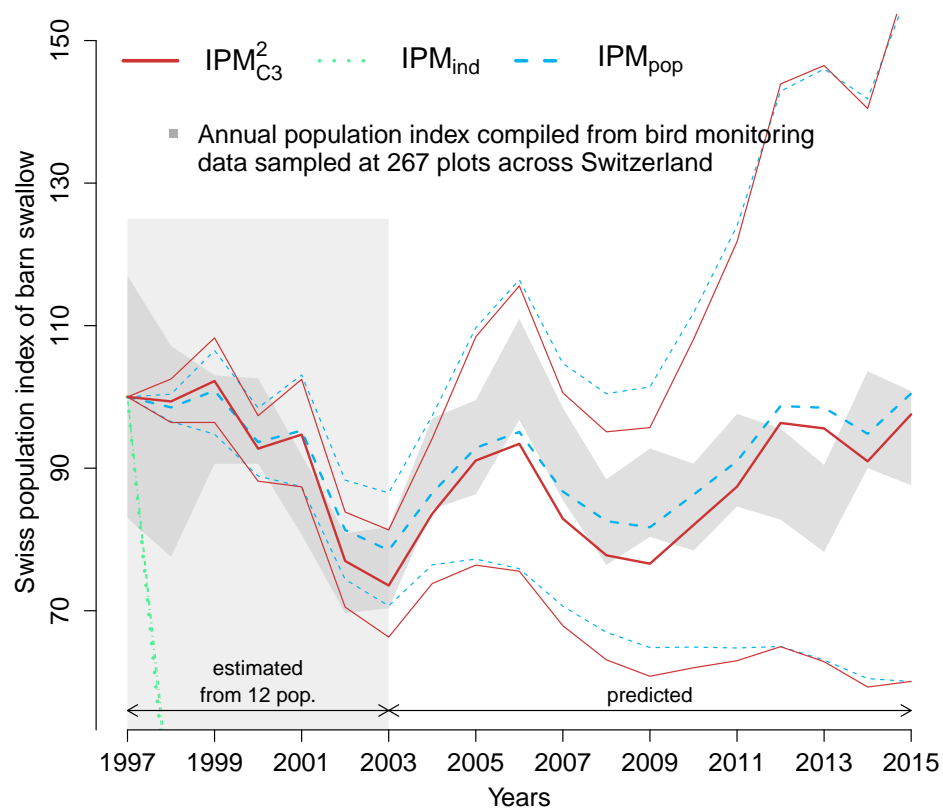


Figure 5

655 Supplementary information

656 Appendix S1: Simulation study

657 Three different scenarios were used to simulate populations:

- (I) Survival and reproductive rates are influenced by an individual trait (z), but not by an environmental trend.

$$\text{logit}(S^J(z, t))_I = i_S + c_S * z \quad (11)$$

$$\text{logit}(S^A(z, t))_I = i_S + i_S^a + c_S * z$$

$$\log(R(z, t))_I = i_R + c_R * z$$

- (II) The individual trait and the environmental trend have additive effects on survival and reproductive rates.

$$\text{logit}(S^J(z, t))_{II} = i_S + c_S * z + b_S * e_t \quad (12)$$

$$\text{logit}(S^A(z, t))_{II} = i_S + i_S^a + c_S * z + b_S * e_t$$

$$\log(R(z, t))_{II} = i_R + c_R * z + b_R * e_t$$

- (III) The individual trait and the environmental trend have interactive effects on survival and reproductive rates.

$$\text{logit}(S^J(z, t))_{III} = i_S + c_S * z + b_S * e_t + d_S * z * e_t \quad (13)$$

$$\text{logit}(S^A(z, t))_{III} = i_S + i_S^a + c_S * z + b_S * e_t + d_S * z * e_t$$

$$\log(R(z, t))_{III} = i_R + c_R * z + b_R * e_t + d_R * z * e_t$$

658 The values used for each parameter are shown in Table S1. They are typical
659 for a short-lived species.

Table S1: Parameters used to simulate the different populations under the three different scenarios. The same inheritance function was used in all scenarios.

| | Inheritance | | | | i | c | σ_I^2 | | | | | |
|--------------|-------------|-------|------|-----|-------|------|--------------|-----|-------|------|-------|------|
| | | | | | 0 | 0.3 | 1 | | | | | |
| | I | | | II | | | | III | | | | |
| | i | i_a | c | i | i_a | c | b | i | i_a | c | b | d |
| Survival | -1 | 1 | 0.5 | 0.5 | 1 | 0.5 | -0.18 | 1 | 1 | 0.5 | -0.55 | 0.25 |
| Reproduction | 0.5 | | 0.17 | 0.6 | | 0.17 | -0.08 | 0.7 | | 0.15 | -0.5 | 0.15 |

To mimic a data collection that would have taken place in the field, we sampled some females from the created population. The sampling process worked in the following way: during the first year, a proportion p_{rs} of the female adults are marked with permanent tracking marks such as radio- or GPS-tracking such that, once an individual is marked, its state (alive or dead) was known each year. The reproductive success (number of female nestlings) of all marked females has been collected by observations. Because we only had a limited number of tracking material, a proportion p_i of these females chicks were marked. In addition, random searches allowed a proportion p_{rs} of new female chicks (for which we did not know the mother) each year to be found and marked. The individual traits of all females were measured without error when they were marked. Independently, an annual survey during the breeding period allowed counting a proportion p_C of the breeding females. For this survey data, we simulated three cases: C1: contains the number of counted females only without measures of the individual trait, C2: contains the number of counted females as well as categorical information about the individual

trait of each counted female (small, medium or tall), C3: contains the number of counted females and exact information about the individual trait of each counted female.

Finally, we obtained four datasets, partially linked:

- survival dataset: binary survival data of each marked female in each year, their individual trait and their age.
- reproduction dataset: reproductive success of a surviving marked female in relation to year and individual trait.
- inheritance dataset: nestling trait according to year and maternal trait including all the nestlings belonging to a clutch that have been marked and measured and produced by a marked female.
- count dataset: number of sampled breeding females in each year (for C1, C2, and C3) along with the distribution of the individual trait (C2: one of the 3 trait classes for each counted female; C3: exact measurement of each counted female).

We used an initial population size of 100 adult females for year 0 in all scenarios. The above defined survival, reproductive and inheritance functions (Table S1) were used to simulate the fate of each individual during 20 years. For each scenario, we simulated 500 times the population and the data collection. We fitted the different population models to the first 10 years to obtain estimates of the different function parameters and demographic rates. We then forecast the demographic rates and population size for the following 10 years and compared the predictions with the true simulated demographic rates and population sizes.

Each sampled population was analyzed with 5 different models. The specific datasets that each model uses are summarized below:

- IPM_{pop} needed 3 datasets: a) the number of surviving females each year from the survival dataset, b) the number of recruits per female each year from the reproduction dataset and c) the number of females counted each year ($C1$)
- IPM_{ind} needed 3 datasets: a) the number of surviving females each year from the survival dataset including the information about the female trait, b) the number of recruits per female each year including the information about the female trait and c) the inheritance dataset.
- IPM^2_{C1} , IPM^2_{C2} , IPM^2_{C3} all needed 4 datasets. All needed the 3 same datasets as the IPM_{ind} , and in addition one count dataset (either $C1$, $C2$ or $C3$).

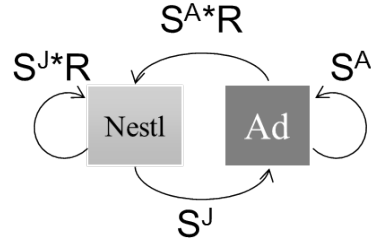
We used 50 mid points to describe the distribution of the individual trait in IPM_{ind} and IPM^2 . Individual as well as environmental covariables were scaled to facilitate convergence. We used normal distributions with mean 0 and variance 10^2 as priors for regression slopes and intercept and uniform distributions over the interval $[0,100]$ as priors for the standard deviations of the inheritance function (Kéry & Schaub, 2012). The parameter values of the simulated populations were used as initial values. To avoid any influence of initial population distribution in first year on the results of IPM^2 and IPM_{ind} , we used the true distribution to initialize first year distribution. The initial population distribution must be a continuous distribution and should not be directly estimated as a “histogram” using the data

to avoid having holes in the distribution due to individual sampling. Convergence of all chains has been checked using the Gelman and Rubin convergence diagnostic ($R < 1.5$, Gelman & Rubin 1992).

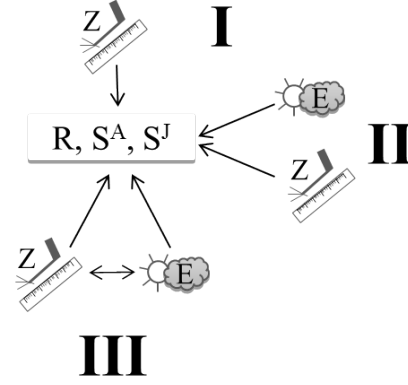
Table S2: Parameter estimates from the IPM_{pop} , IPM^2 and IPM_{ind} of the functions describing the demography of the 12 barn swallow populations from Switzerland. Means, standard deviations and 95% credible intervals of each parameter are presented. The parameters that were not selected under IPM^2_{C3} were also removed when using IPM_{ind} or IPM_{pop} and are not presented here. a : intercepts ($i_{S_{age}}$ and $i_{S_{sex}}$: additional intercept for adult and female survival, respectively, $i_{I_{age}}$: correction for age as first-year individuals often lay eggs later than adults and $i_{I_{clutch}}$: correction for individuals born in a second clutch), b : slope linked to environmental covariable c : slope linked to individual trait, σ : standard deviation.

| | IPM _{pop} | | | | IPM ² | | | | IPM _{ind} | | | |
|---|--------------------|----------------|-------|-------|------------------|-----------|-------|-------|--------------------|-----------|-------|-------|
| | <i>mean</i> | <i>sd</i> | 2.5% | 97.5% | <i>mean</i> | <i>sd</i> | 2.5% | 97.5% | <i>mean</i> | <i>sd</i> | 2.5% | 97.5% |
| Survival | | | | | | | | | | | | |
| <i>i_S</i> | −3.62 | 0.15 | −3.86 | −3.22 | −3.65 | 0.13 | −3.87 | −3.32 | −3.69 | 0.11 | −3.92 | −3.47 |
| <i>i_{Sage}</i> | 2.99 | 0.16 | 2.57 | 3.26 | 2.97 | 0.14 | 2.64 | 3.22 | 3.02 | 0.13 | 2.77 | 3.27 |
| <i>i_{Ssex}</i> | 0.41 | 0.07 | 0.27 | 0.55 | 0.41 | 0.08 | 0.26 | 0.56 | 0.39 | 0.08 | 0.24 | 0.54 |
| <i>c_S</i> | | Not assessable | | | −0.15 | 0.04 | −0.23 | −0.07 | −0.13 | 0.04 | −0.21 | −0.05 |
| <i>b_S</i> | −0.10 | 0.03 | −0.16 | −0.03 | −0.07 | 0.03 | −0.14 | −0.01 | removed | | −0.08 | 0.07 |
| Recapture | | | | | | | | | | | | |
| <i>i_{pO}</i> | −1.35 | 1.01 | −3.40 | 0.71 | −1.38 | 1.09 | −3.81 | 0.70 | −1.15 | 1.30 | −3.83 | 1.39 |
| <i>i_{pA}</i> | 1.75 | 0.28 | 1.23 | 2.31 | 1.81 | 0.26 | 1.31 | 2.32 | 1.73 | 0.26 | 1.23 | 2.24 |
| <i>σ_p</i> | 2.16 | 0.86 | 1.11 | 4.36 | 2.21 | 0.90 | 1.15 | 4.46 | 2.23 | 0.95 | 1.13 | 4.74 |
| <i>σ_{site}</i> | 2.19 | 0.68 | 1.25 | 3.85 | 2.22 | 0.69 | 1.26 | 3.88 | 2.20 | 0.69 | 1.24 | 3.89 |
| Number of successful clutches | | | | | | | | | | | | |
| <i>i_R</i> | 0.36 | 0.02 | 0.32 | 0.39 | 0.34 | 0.02 | 0.31 | 0.37 | 0.34 | 0.02 | 0.31 | 0.37 |
| <i>c_R</i> | | Not assessable | | | −0.22 | 0.02 | −0.25 | −0.18 | −0.22 | 0.02 | −0.25 | −0.18 |
| Number of fledglings/successful clutch | | | | | | | | | | | | |
| <i>i_F</i> | 4.04 | 0.02 | 4.00 | 4.08 | 4.03 | 0.02 | 3.99 | 4.06 | 4.03 | 0.02 | 3.99 | 4.06 |
| <i>c_S</i> | | Not assessable | | | −0.24 | 0.02 | −0.28 | −0.20 | −0.24 | 0.02 | −0.28 | −0.20 |
| <i>σ_F</i> | 0.94 | 0.01 | 0.92 | 0.97 | 0.91 | 0.01 | 0.89 | 0.94 | 0.91 | 0.01 | 0.89 | 0.94 |
| Transitions between annual first laying dates | | | | | | | | | | | | |
| <i>i_T</i> | | Not assessable | | | −0.60 | 0.02 | −0.64 | −0.56 | −0.60 | 0.02 | −0.64 | −0.56 |
| <i>c_T</i> | | | | | 0.19 | 0.02 | 0.15 | 0.23 | 0.19 | 0.02 | 0.15 | 0.23 |
| <i>b_T</i> | | | | | 0.16 | 0.02 | 0.12 | 0.19 | 0.16 | 0.02 | 0.12 | 0.19 |
| <i>σ_T</i> | | | | | 0.62 | 0.01 | 0.60 | 0.65 | 0.62 | 0.01 | 0.60 | 0.65 |
| Inheritance | | | | | | | | | | | | |
| <i>a_I</i> | | Not assessable | | | 0.58 | 0.08 | 0.42 | 0.74 | 0.51 | 0.08 | 0.35 | 0.67 |
| <i>i_{Iage}</i> | | | | | −0.83 | 0.15 | −1.12 | −0.53 | −0.79 | 0.15 | −1.08 | −0.50 |
| <i>i_{Iclutch}</i> | | | | | −0.30 | 0.16 | −0.61 | 0.00 | −0.29 | 0.16 | −0.60 | 0.02 |
| <i>b_I</i> | | | | | 0.13 | 0.06 | 0.01 | 0.26 | removed | | −0.03 | 0.22 |
| <i>σ_I</i> | | | | | 0.90 | 0.05 | 0.81 | 0.99 | 0.90 | 0.05 | 0.82 | 1.00 |
| Immigration | 7.58 | 1.20 | 4.71 | 9.67 | 8.03 | 1.12 | 5.49 | 10.07 | Not assessable | | | |

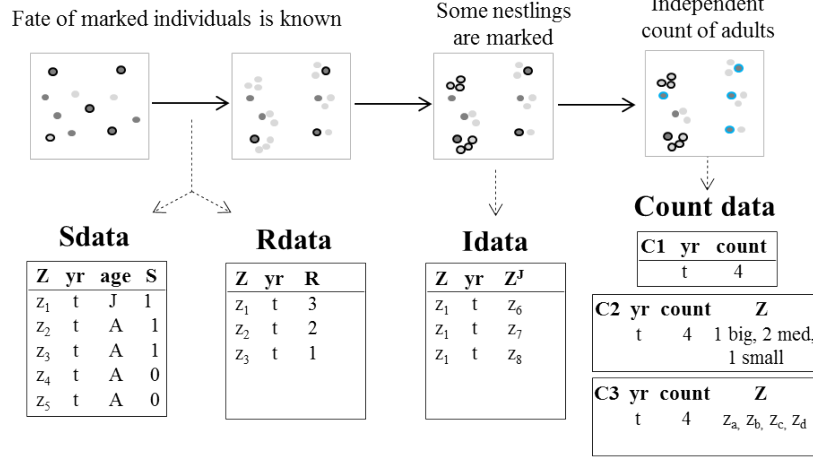
Population



3 scenarios



Sampling: each year



Analysis: 5 models

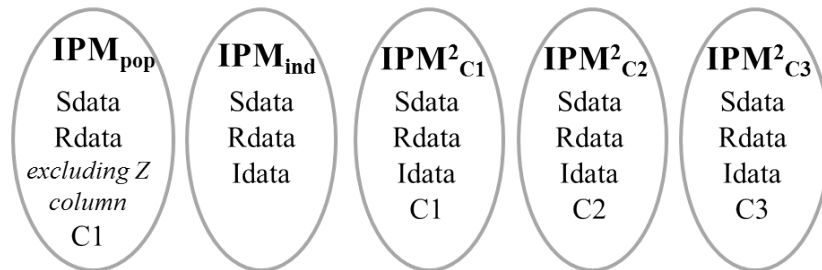


Figure S1: Description of the simulation of the dataset used. The populations were simulated under 3 different scenarios. I: demographic rates are influenced by the individual trait (Z), only (S^J : Juvenile survival, S^A : adult survival and R : reproduction) II: demographic rates are influenced by additive effects of an environmental trend (E) and the individual trait. III: demographic rates are influenced by interactive effects of an environmental trend and the individual trait. Among the females constituting the population, some are marked with permanent tag that can be easily recovered (e.g. GPS collars). The survival and reproduction of these females are known each year⁴⁶. Some nestlings are also captured and marked. Finally, an independent count of breeding females takes place. This sampling allows getting four different datasets that are used to analyze these simulated data with 5 different models. Sdata: Survival data, Rdata: Reproductive data, Idata: Inheritance data.

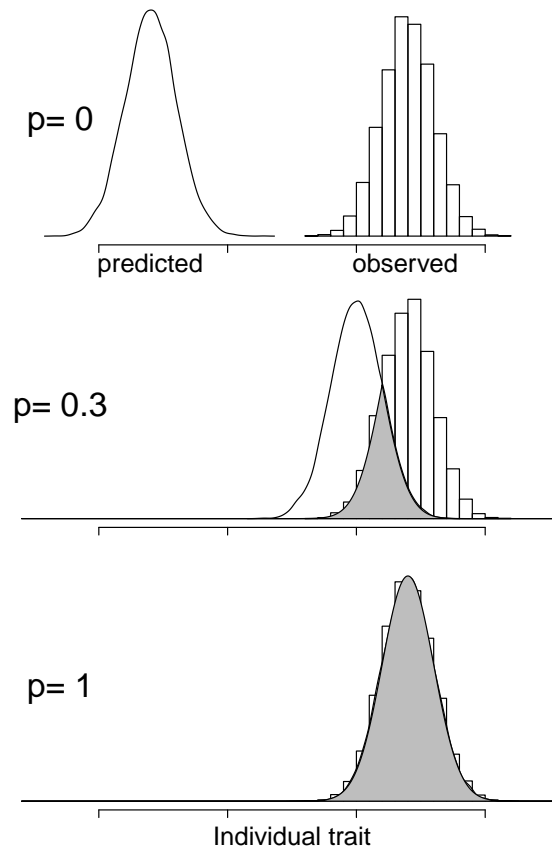


Figure S2: Illustration of the density function that gives the probability that the predicted distribution equals the observed distribution. In practice, this function scales the two distributions such that they can be interpreted as probability density functions. It calculates the area where the two distributions are superimposed on each other. If the observed and predicted distributions are identical, the function returns 1 and if the two distributions are completely different, the function returns 0.

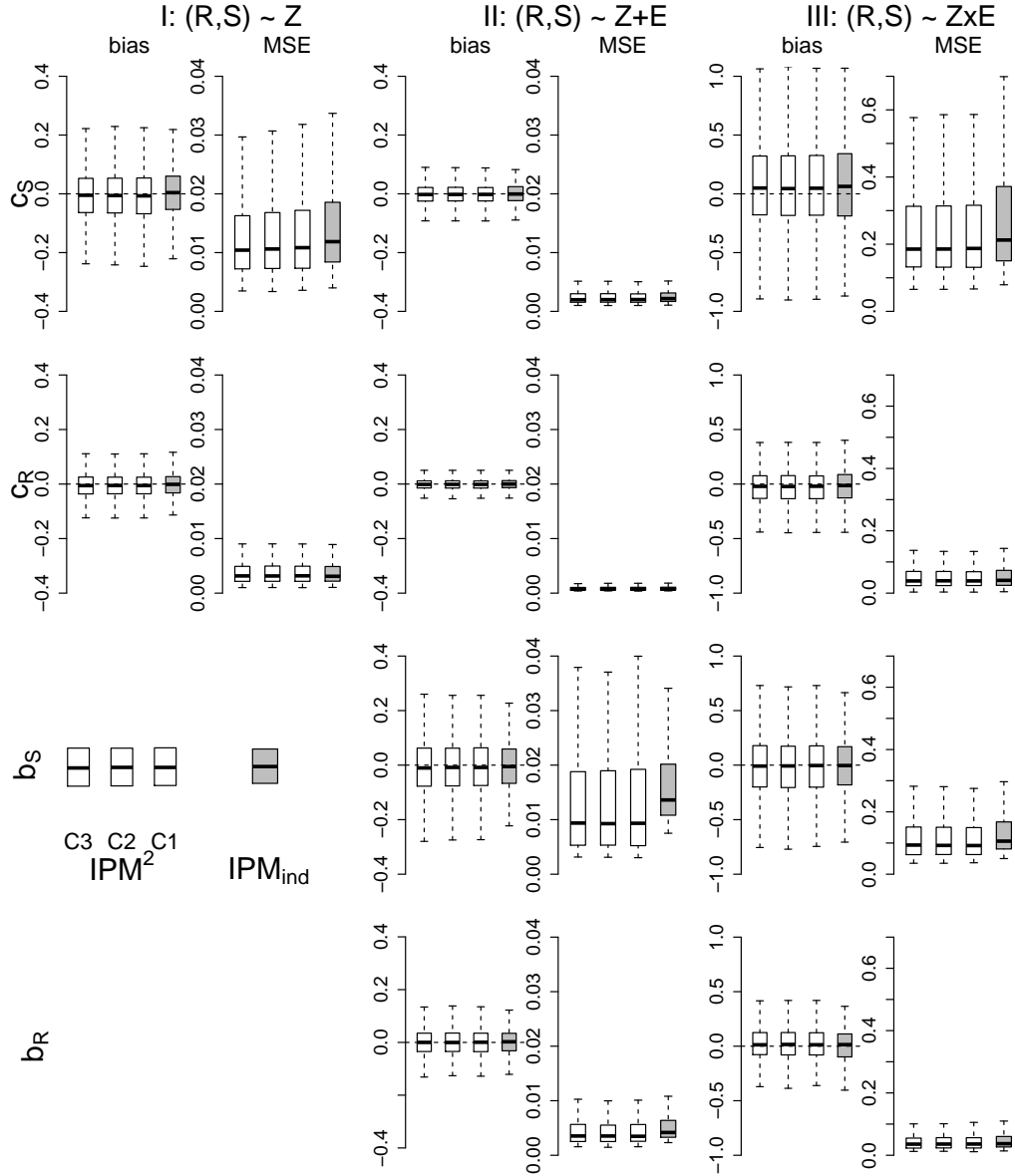


Figure S3: Comparison of bias and mean squared errors (MSE) of the slopes of the survival and reproductive functions estimated from 4 different models under the three different scenarios. Boxplots of estimators from IPM_{ind} and IPM^2 are in grey and white respectively. IPM^2_{C3} , IPM^2_{C2} and IPM^2_{C1} are presented in this order from the left to the right. c_S and c_R are the slopes linking individual trait to the survival (S) and the reproduction (R) functions, respectively. b_S and b_R are the slopes linking the environmental trend to the survival and the reproductive functions, respectively.

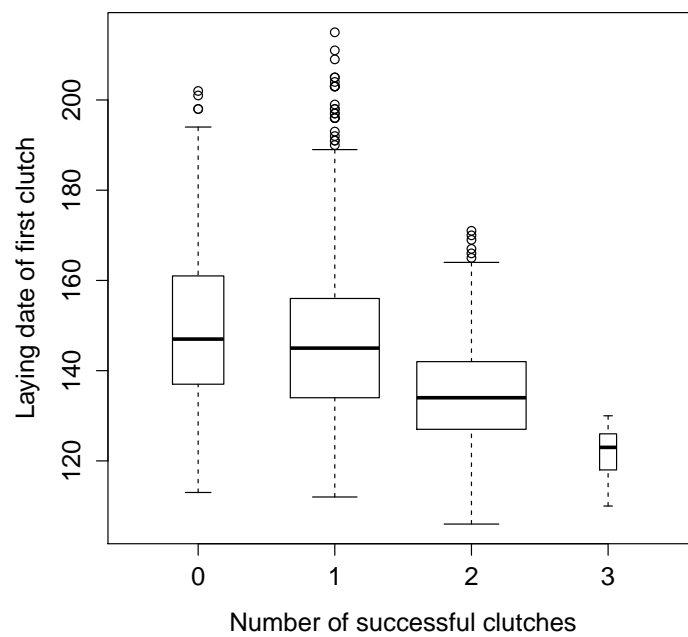


Figure S4: Influence of laying date of the first clutch on the number of successful clutches produced during a breeding season.

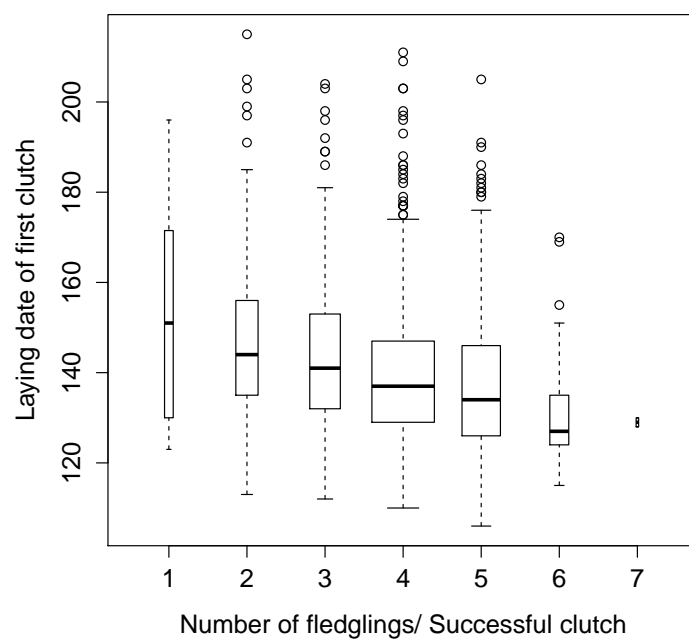


Figure S5: Influence of laying date of the first clutch on the mean number of fledglings (round to the closest integer) per successful clutch.

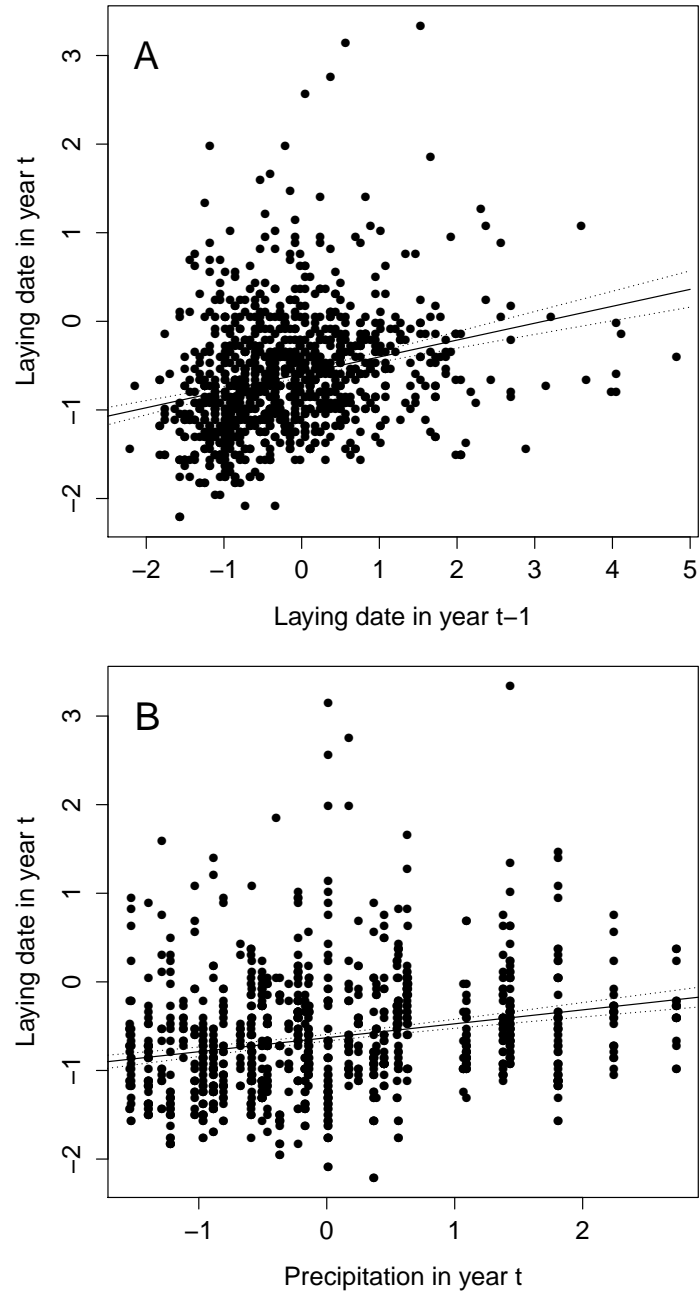


Figure S6: Transitions between annual first laying dates. Influence of laying date of the first clutch laid in year $t-1$ (A) and of precipitation in year t (B) on the laying date of the first clutch laid in year t . The relationships predicted from IPM² are presented with their 95% credible interval.

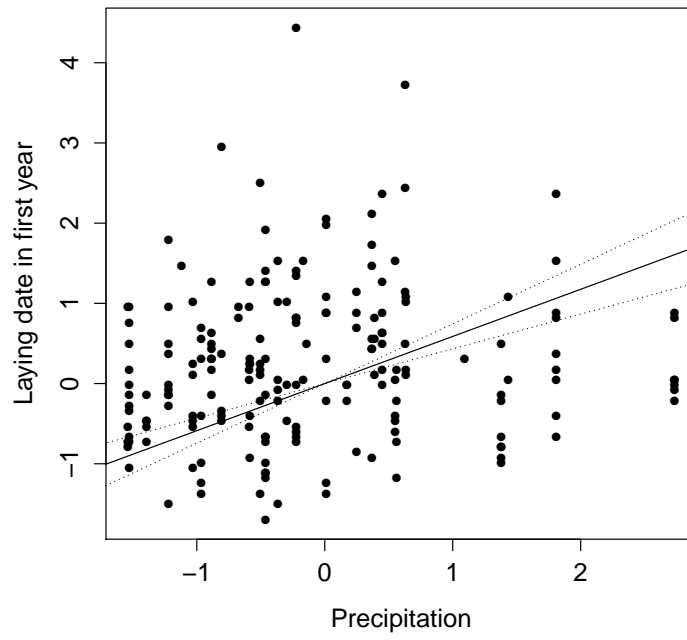


Figure S7: Inheritance of first laying dates. Nestling laying date of the first clutch in the first year was not influenced by maternal laying date but was influenced by annual spring precipitation. The relationship predicted from IPM² is presented with its 95% credible interval.

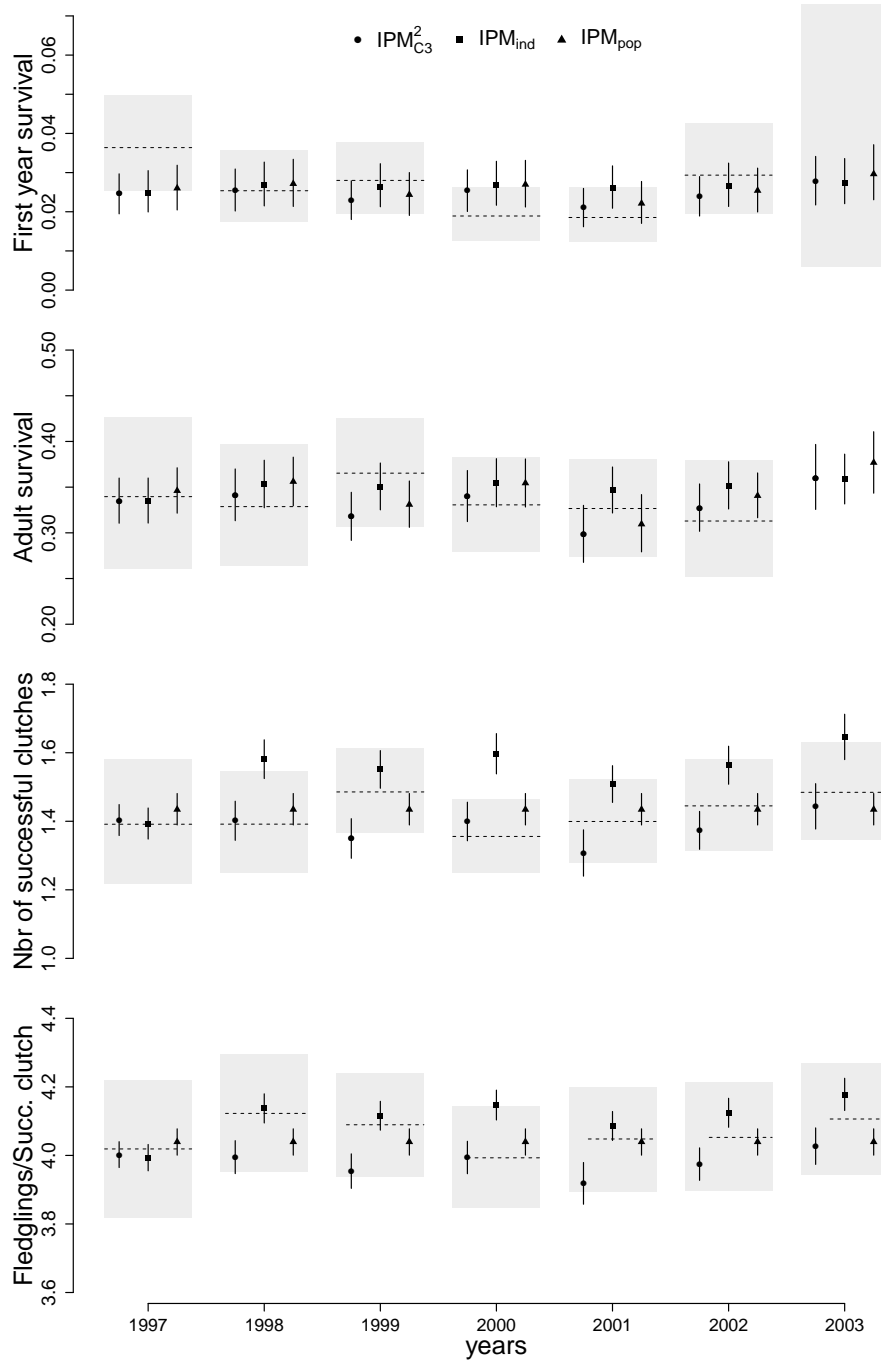


Figure S8: Estimates of the demographic rates of the Swiss barn swallow population under 4 different models. Mean and 95% credible intervals estimated from IPM^2_{C3} , IPM_{pop} and IPM_{ind} are presented with points and vertical lines, respectively. Mean and 95% credible interval of yearly variation in demographic rates estimated using a model including an effect of year as a factor are represented using a dashed black line and a grey rectangle each year.

Appendix S2: Code.R