



Communication Theory (5ETB0) Module 6.2

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Module 6.2

Presentation Outline

Part I Correlation Receiver

Part II Matched Filter Receiver

Part III Signal to Noise Ratio





Motivation for Correlation Receiver

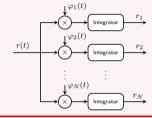
Recovery of Signal Vectors

Gram-Schmidt: $s_m(t) = \sum_{i=1}^{N} s_{mi} \varphi_i(t)$

Components r_i are determined as follows:

$$r_i \stackrel{\Delta}{=} \int_{-\infty}^{\infty} r(t)\varphi_i(t)dt$$

for $i=1,2,\ldots,N$



Optimum Receiver

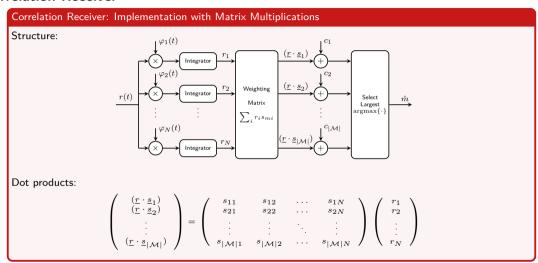
The optimum receiver applies the rule

$$\hat{m}^{\mathsf{MAP}} = \operatorname*{argmax}_{m \in \mathcal{M}} \{ (\underline{r} \cdot \underline{s}_m) + c_m \}, \qquad c_m = \frac{N_0}{2} \ln \Pr\{M = m\} - \frac{E_m}{2}$$





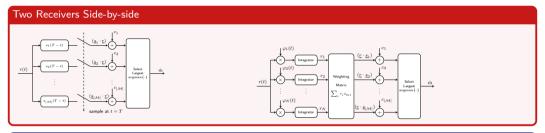
Correlation Receiver







Direct Receiver vs. Correlation Receiver



Three Questions

- Q1: Which receiver is simpler in terms of $argmax\{\cdot\}$?
- Q2: Which receiver is simpler in terms of filters?
- Q3: Can we always guarantee this?

Example: $s_m(t) = m \cdot p(t), \ m=1,2,3,\ldots,128$ and 0 < T < 1 ps (transmission rate is 7 Gbps). In this case, N=1 and $|\mathcal{M}|=128 \Rightarrow \times 100$ simpler





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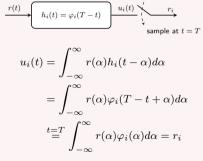


Matched-Filter Receiver

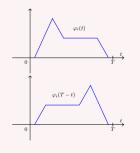
Two Important Concepts

Integral of a multiplication = dot product = Filter+sampling (M6.1) r-values: Integral of multiplication (r(t) and $\varphi_i(t)$)

Matched Filter Receiver



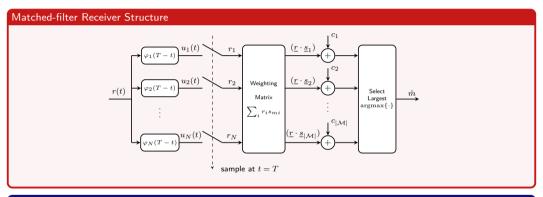
Building-block $\varphi_i(t)$ and impulse response $\varphi_i(T-t)$:







Matched-Filter Receiver



Two Questions

- Q1: Is the matched-filter receiver simpler than the direct receiver?
- Q2: What are differences between the matched-filter and correlation receiver?





Who Cares? We do!

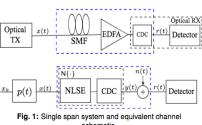
Ecoc 2015 - ID: 0690

Optimum Detection in Presence of Nonlinear Distortions with Memory

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Abstract The performance of nonlinearity-tailored detection for single channel, single span optical fibre systems is studied. Monotonically decreasing bit error rate with transmitted power can be achieved without any nonlinearity compensation.



schematic. A. Alvarado

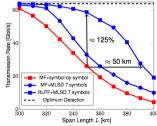


Fig. 4: Achievable transmission rates vs. L for differen detection strategies.





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Presentation Outline

Part I Correlation Receiver

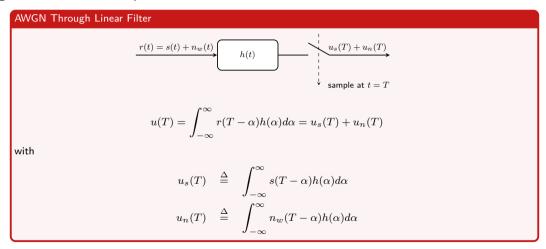
Part II Matched Filter Receiver

Part III Signal to Noise Ratio





Signal and Noise Components







Signal-to-Noise Ratio (SNR)

SNR Definition

We can now define the signal-to-noise ratio as

$$\mathsf{SNR} \stackrel{\Delta}{=} \frac{u_s^2(T)}{E[U_n^2(T)]}$$

Noise variance:

$$\begin{split} E[U_n^2(T)] &= E\left[\int_{-\infty}^{\infty} N_w(T-\alpha)h(\alpha)d\alpha \int_{-\infty}^{\infty} N_w(T-\beta)h(\beta)d\beta\right] \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} E[N_w(T-\alpha)N_w(T-\beta)]h(\alpha)h(\beta)d\alpha d\beta \\ &= \frac{N_0}{2} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \delta(\beta-\alpha)h(\alpha)h(\beta)d\alpha d\beta \\ &= \frac{N_0}{2} \int_{-\infty}^{\infty} h^2(\alpha)d\alpha. \end{split}$$

(1)





Matched Filter Maximizes the SNR

Schwarz Inequality

For two finite-energy waveforms a(t) and b(t) the inequality

$$\left(\int_{-\infty}^{\infty} a(t)b(t)dt\right)^{2} \le \int_{-\infty}^{\infty} a^{2}(t)dt \int_{-\infty}^{\infty} b^{2}(t)dt \tag{2}$$

holds. Equality is obtained only if $b(t) \equiv Ca(t)$ for some constant C.

Result: Maximum Attainable SNR

$$\begin{split} \mathsf{SNR} &= \frac{\left[\int_{-\infty}^{\infty} s(T-\alpha)h(\alpha)d\alpha\right]^2}{\frac{N_0}{2}\int_{-\infty}^{\infty} h^2(\alpha)d\alpha} \leq \frac{\int_{-\infty}^{\infty} s^2(T-\alpha)d\alpha\int_{-\infty}^{\infty} h^2(\alpha)d\alpha}{\frac{N_0}{2}\int_{-\infty}^{\infty} h^2(\alpha)d\alpha} \\ &= \frac{\int_{-\infty}^{\infty} s^2(T-\alpha)d\alpha}{\frac{N_0}{2}} = \frac{E_s}{\frac{N_0}{2}} \end{split}$$

The Matched-filter Receiver not only minimizes $P_{\rm e}$ but it also maximizes the SNR!





Summary Module 6.2

Take Home Messages

- Correlation receiver
- Matched-filter receiver (correlation receiver using filters)
- Comparison of the three receivers: direct, correlation and matched-filer
- SNR and optimality of Matched-filter receiver





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