## **Operating Systems (2INC0)**

Condition Synchronization (07)
Condition variables and signals

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Interconnected Resource-aware Intelligent Systems



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150

Where innovation starts

## Recall: action synchronization

- **Cooperation** → Synchronization
  - N concurrent processes working for a common goal
  - Goal 1: avoid program traces that may violate a certain invariant
  - Goal 2: steer the execution to maintain some property
    - e.g., enforce an execution order
  - Typically, by blocking the task execution until an assertion becomes true
- **Competition** → Mutual exclusion
  - N concurrent processes competing for a resource
  - Tasks define critical sections (CS)
  - Introduce extra synchronization requirements to access the CS.





# **Condition** synchronization: motivation

- Action synchronization
  - the invariant refers to ordering of actions:
  - - enforced by counting how many times actions is performed
- Problem: just counting may not be enough to solve all synchronization problems
  - Examples:
    - x := y+z; or x := 2\*y; Value of a variable may not be inferred by simply counting the actions on that variable
    - wait until  $x=0 \lor y=0$ : condition contains a disjunctions (OR operations)
- Solution: Condition synchronization
  - the invariant refers to a (combination of) execution state(s)
  - requires explicit communication (signalling) between processes





# **Condition** synchronization: motivation

- Needed when just counting is not enough to solve a synchronization problem
- Allows to simplify otherwise complex sequences of semaphore operations
  - *P*(*a*); *P*(*a*); *P*(*b*); *P*(*m*); ......

#### Two principles:

Where a condition may be violated: **check and block**Where a condition <u>may have become true</u>: **signal waiters** 





# **Condition** synchronization: building blocks

var cv : Condition; (often associated with a condition: a Boolean expression B in terms of program variables;)

4 basic operations on variable cv.

• Wait(..., cv) suspend execution of caller

Signal(cv) free <u>one</u> process/thread suspended on Wait(cv)

(void if there is none)

Sigall(cv) free <u>all</u> processes suspended on Wait(cv)

• *Empty(cv)* Check if "there is no process suspended on

*Wait(cv)*" (returns true or false)

Extra operations in specific implementations.





Maintain x≥0 in a program with arbitrary assignments to x

```
Proc P2
|[
    while( true) {
        x := x + 50;
        x := 2*x;
    }
}
```





Maintain  $x \ge 0$  in a program with arbitrary assignments to x

```
var cv: condition;
    m: binary semaphore (initially := 1)
```

```
Proc P1
 while( true) {
    x := x-10;
```

```
Proc P2
 while( true) {
    x := x + 50;
    x := 2 *x;
```





Maintain x≥0 in a program with arbitrary assignments to x

```
var cv: condition;
m: binary semaphore (initially := 1)
```

Define the critical sections

```
Proc P2
|[
    while( true) {
        x := x + 50;
        x := 2*x;
    }
]
```





Maintain x≥0 in a program with arbitrary assignments to x

```
var cv: condition;
m: binary semaphore (initially := 1)
```

Define the **critical sections** 

```
Proc P1
|[
    while( true) {
        P(m);
        x := x-10;
        V(m);
    }
]
```





Maintain x≥0 in a program with arbitrary assignments to x

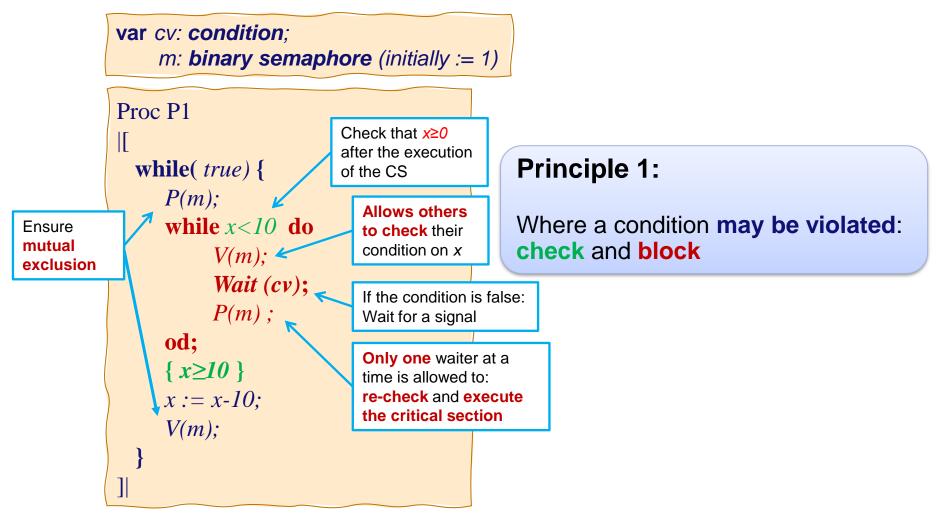
```
var cv: condition;
m: binary semaphore (initially := 1)
```

```
Proc P2
|[
while(true) {
    P(m);
    x := x + 50;
    x := 2*x;
    V(m);
}
```

#### **Principle 1:**

Where a condition may be violated: check and block

Maintain x≥0 in a program with arbitrary assignments to x



Maintain x≥0 in a program with arbitrary assignments to x

```
var cv: condition;
m: binary semaphore (initially := 1)
```

```
Proc P1

|[
| while (true) {
| P(m);
| while x < 10 do
| V(m);
| Wait (cv);
| P(m);
| od;
| {x \ge 10}
| x := x-10;
| V(m);
| Principle 2:
```

```
Proc P2
|[
while(true) {
    P(m);
    x := x + 50;
    x := 2*x;
    V(m);
}
```

Where a condition may have become true: signal the waiters

Maintain x≥0 in a program with arbitrary assignments to x

```
var cv: condition;
m: binary semaphore (initially := 1)
```

```
Proc P1
 while( true) {
    P(m);
     while x < 10 do
          V(m);
          Wait (cv);
          P(m);
     od;
     \{x\geq 10\}
     x := x-10;
               Principle 2:
     V(m);
```

```
Proc P2

|[
    while( true) {
        P(m);
        x := x + 50;
        x := 2*x;
        Sigall (cv);
        V(m);
    }

]|
```

Where a condition may have become true: signal the waiters

Maintain x≥0 in a program with arbitrary assignments to x

```
var cv: condition;
    m: binary semaphore (initially := 1)
Proc P1
  while( true) {
     P(m);
     while x < 10 do
                           Beware!! Not atomic!!!
          V(m); Wait (cv);
                           Sigall(cv) may be called
                           before Wait(cv)
                            \rightarrow P1 is never woken up!
          P(m);
     od;
     \{x \ge 10\}
     x := x-10;
     V(m);
```

```
Proc P2

|[

while( true) {

P(m);

x := x + 50;

x := 2*x;

Sigall (cv);

V(m);

}
```

## Combine: condition variable & semaphore

- Need to combine "V(m); Wait(cv)" atomically:
- define Wait(m,cv): <V(m); Wait(cv)>; P(m)

```
var cv: condition;
m: binary semaphore (initially := 1)
```

```
Proc P1
 while( true) {
     P(m);
     while x < 10 do
          Wait (m, cv);
     od;
     \{x \ge 10\}
     x := x-10;
     V(m);
```

```
Proc P2
|[
while(true) {
    P(m);
    x := x + 50;
    x := 2*x;
    Sigall (cv);
    V(m);
}
```

#### **Using condition variables**

- cv is sometimes extended with a timeout mechanism.
  - recheck the condition even though there is no signal.
- Each condition variable cv is associated with a condition B(cv)
  - Signaling means B(cv) may have become true.
  - B(cv) can be a simple condition such as (x≥10)...
  - ...or a combined condition such as  $B(cv)=(x\geq 10 \lor y\geq 5 \lor x+y\geq 12)$ 
    - alternatively, use 3 condition vars  $B(cv1)=(x\geq 10)$ ,  $B(cv2)=(y\geq 5)$ ,  $B(cv3)=(x+y\geq 12)$
    - ...using a **single semaphore** associated with all critical sections (e.g. POSIX).
  - Depending on the context, a single or multiple condition variables is used for all conditions
    - using more than one is an efficiency choice
    - For example: JAVA allows a single implicit condition variable per object (actually, JAVA provides a *Monitor* mechanism)





17

# POSIX: condition variables (1003.1c)

```
pthread_cond_t cond = PTHREAD_COND_INITIALIZER;
                                                /* should return 0
status = pthread_cond_init (&cond, attr);
                                                                         */
status = pthread_cond_destroy (&cond);
                                                /* idem
status = pthread_cond_wait (&cond, m);
                                                /* semaphore m is associated with
                                                 * all critical sections
                                                                         */
status = pthread_cond_timedwait (&cond, m, exp); /* exp: max. waiting time; returns
                                                 * ETIMEDOUT after exp.*/
                                                /* signal one waiter
status = pthread_cond_signal (&cond);
status = pthread_cond_broadcast (&cond);
                                                /* signal all waiters
                                                                          */
```



