

Module 4
Lecture: Amplifier design

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Where innovation starts

Outline

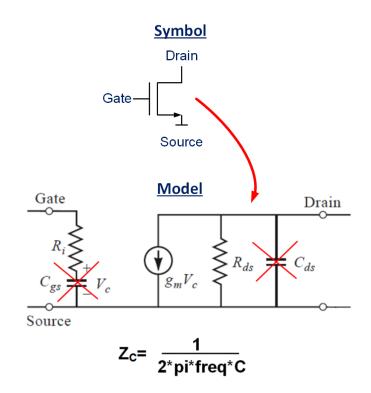
- Design methods
- Two-port network descriptions
- Introduction of S-parameters
- Definitions
 - Reflection coefficient
 - Power
 - Power gain
- Gain circles
- Stability
- Stability circles

Learning Objectives

- Understand design methods at low and high frequency
- Understand S-parameters definition
- Calculate and understand the <u>different gains</u> of an amplifier
- Know the <u>basic amplifier architecture</u>
- Understand gain circles
- Understand the concept of stability
- Be able to evaluate whether an amplifier is unconditionally stable
- Be able to evaluate the stability of an amplifier by calculating the <u>stability circles</u>

Design methods: low versus high frequency

Example: single MOS transistor



Most analog circuit have more than one transistor !!!

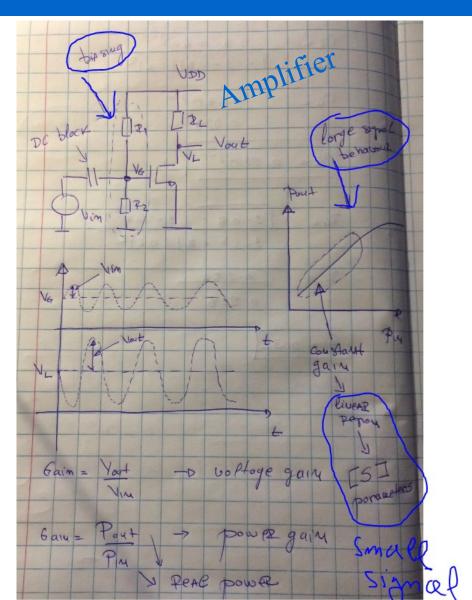
Low frequency method

- Capacitors can be neglected
- Circuit complexity reduced
- Working with gm and Rds is sufficient
- Complexity is manageable

High frequency method

- Capacitors most be included
- Circuit complexity increases
- Black box approach
- In general, every circuit can be described with N-port element
- Most of circuits have 2 ports
- Z, Y, S parameters used for N- port description

Design methods: large vs small signal

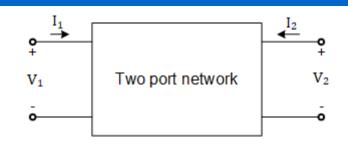


2-port network description: Z,Y parameters

Z parameters

$$V_1 = Z_{11}I_1 + Z_{22}I_2$$

 $V_2 = Z_{21}I_1 + Z_{22}I_2$



Y parameters

$$I_1 = Y_{11}V_1 + Y_{12}V_2 \ I_2 = Y_{21}V_1 + Y_{22}V_2$$

$$Z_{11} = \frac{V_1}{I_1} \Big|_{I_2 = 0} \qquad Z_{12} = \frac{V_1}{I_2} \Big|_{I_1 = 0}$$

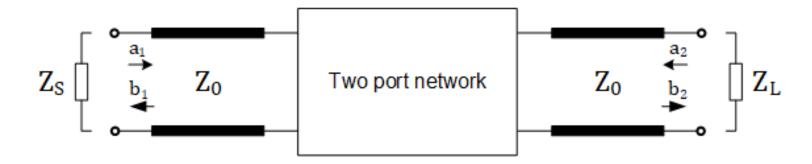
$$\left. egin{array}{c|c} I_1 \ \hline V_1 \end{array} \right| \ V_2 = 0 = Y_{11} & \left. egin{array}{c|c} I_1 \ \hline V_2 \end{array} \right| \ V_1 = 0 \end{array} = Y_{12}$$

$$Z_{21} = rac{V_2}{I_1}igg|_{I_2 \,=\, 0} \qquad Z_{22} = rac{V_2}{I_2}igg|_{I_1 \,=\, 0}$$

$$\left. rac{I_2}{V_1} \, \right|_{V_2 \, = \, 0} \, = Y_{21} \quad \left. rac{I_2}{V_2} \, \right|_{V_1 \, = \, 0} \, = Y_{22}$$

- I=0 means open, V=0 means short
- To measure Z and Y parameters open and short terminations are required
- At high frequencies there are no perfect open and short terminations

2-port network description: S parameters



$$S_{11} = \frac{b_1}{a_1} \bigg|_{a_2 = 0}$$

$$S_{21} = \frac{b_2}{a_1}\Big|_{a_2=0}$$

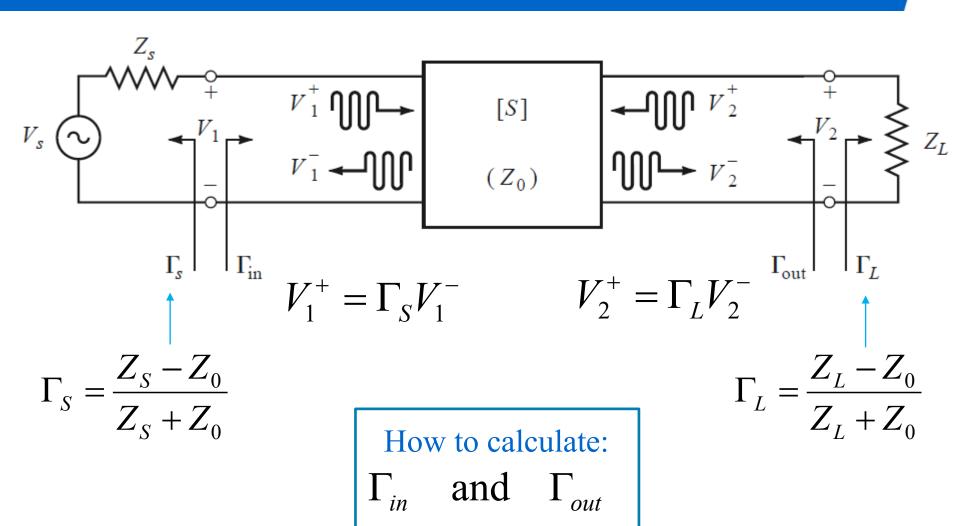
$$S_{22} = \frac{b_2}{a_2}\bigg|_{a_1=0}$$

$$S_{12} = \frac{b_1}{a_2}\Big|_{a_1=0}$$

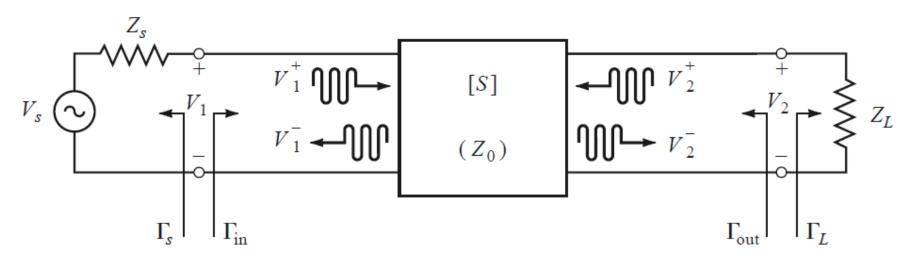
(input reflection coefficient with output properly terminated) (forward transmission coefficient with output properly terminated) (output reflection coefficient with input properly terminated) (reverse transmission coefficient with input properly terminated)

- To measure S parameters matched terminations are required: Z_L=Z₀ and Z_S=Z₀
- At high frequencies matched terminations could be realized much easier compared to short and open terminations

2-port network with source and load



Derivation of the input/output reflection coefficient



$$\Gamma_{in} = \frac{V_1^-}{V_1^+} = S_{11} + \frac{S_{12}S_{21}\Gamma_L}{1 - S_{22}\Gamma_L}$$

$$\Gamma_{out} = \frac{V_2^-}{V_2^+} = S_{22} + \frac{S_{12}S_{21}\Gamma_S}{1 - S_{11}\Gamma_S}$$

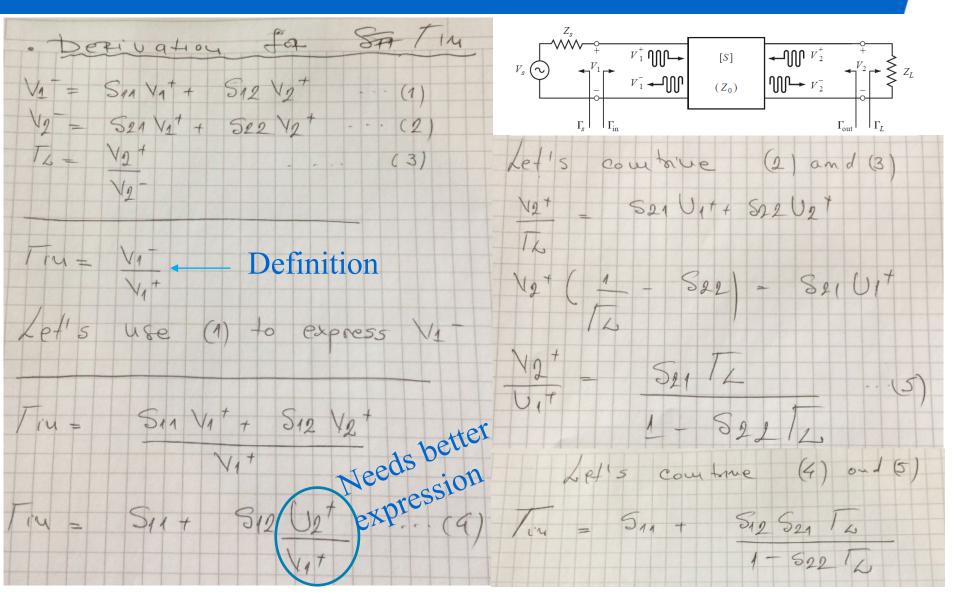
Unilaterial case: $S_{12} = 0$

$$\Gamma_{in} = \frac{V_1^-}{V_1^+} = S_{11}$$

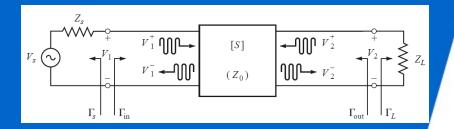
$$\Gamma_{out} = \frac{V_2^-}{V_2^+} = S_{22}$$

More info: book of Pozar, page 607

Derivation of the input reflection coefficient – guidelines



Power definitions



Power delivered to the load:

$$P_{L} = \frac{\left|V_{2}^{-}\right|^{2}}{2Z_{0}} \left(1 - \left|\Gamma_{L}\right|^{2}\right)$$

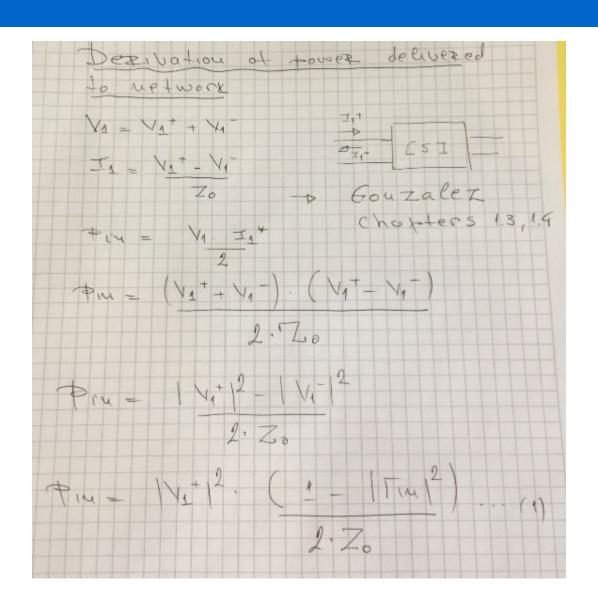
• Input power to the network:

$$P_{in} = \frac{|V_1^+|^2}{2Z_0} \left(1 - |\Gamma_{in}|^2\right)$$

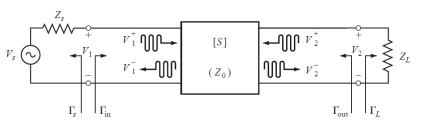
• Power available from the source: P_{avs} P_{in} when the source impedance is conjugately matched to the input impedance $Z_{in} = Z_s^*$

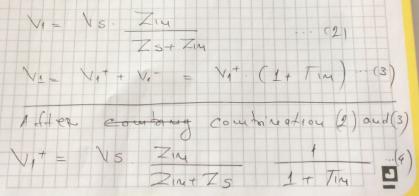
• Power available from the network: P_{avn} P_L when the load impedance is conjugately matched to the output impedance $Z_{out} = Z_{load}^*$

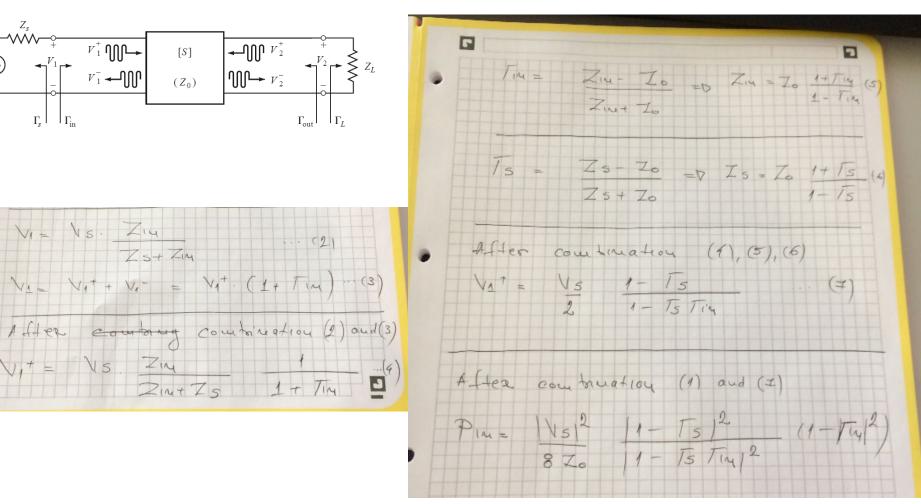
Power definitions – derivation guidelines (1/2)



Power definitions – derivation guidelines (2/2)



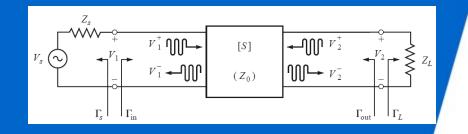




Meaning of the word gain

- Requires additional specifications:
 - What is the load / source impedance
 - Voltage, current or power gain
 - Which power gain?
- Analog designers often use voltage gain.
- RF / microwave designers often use power gain.

Gain definitions



Power gain G: Ratio of the power dissipated in the load Z_L to the power delivered to the input of the two-port network

Available power gain G_A : Ratio of the power available from the two-port network to the power available from the source. Assumes conjugate matching of source and load impedance.

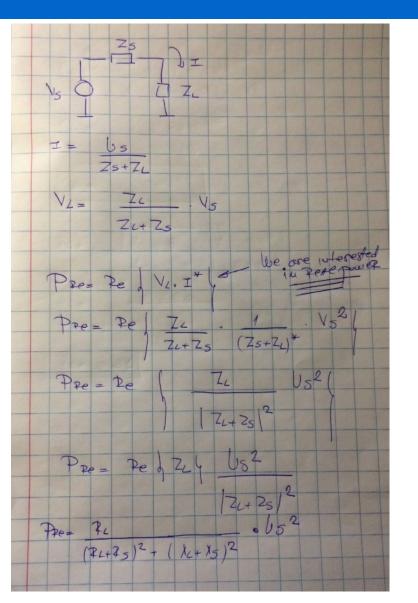
Transducer power gain G_T: Ratio of the power delivered to the load to the power available from the source. Assumes a matched source impedance.

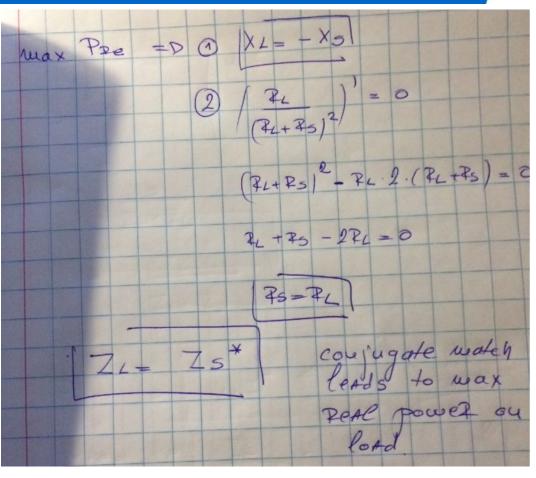
Unilateral transducer power gain G_{TU}:

Transducer power gain for a device with $S_{12}=0$

More info: book of Gonzalez, page 92

Load condition for max real power





Amplifier gains: Equations

Power gain:

$$G = \frac{P_L}{P_{\text{in}}} = \frac{|S_{21}|^2 (1 - |\Gamma_L|^2)}{(1 - |\Gamma_{\text{in}}|^2) |1 - S_{22}\Gamma_L|^2}$$

Available power gain:
$$G_A = \frac{P_{\text{avn}}}{P_{\text{avs}}} = \frac{|S_{21}|^2 (1 - |\Gamma_S|^2)}{|1 - S_{11}\Gamma_S|^2 (1 - |\Gamma_{\text{out}}|^2)}$$

Transducer power gain:
$$G_T = \frac{P_L}{P_{\text{avs}}} = \frac{|S_{21}|^2 (1 - |\Gamma_S|^2) (1 - |\Gamma_L|^2)}{|1 - \Gamma_S \Gamma_{\text{in}}|^2 |1 - S_{22} \Gamma_L|^2}$$

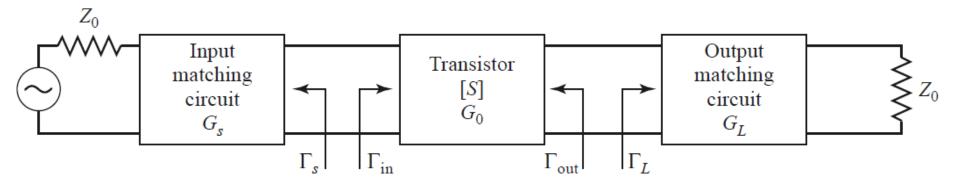
Unilateral transducer power gain:

$$G_{TU} = \frac{1 - |\Gamma_{S}|^{2}}{|1 - \Gamma_{\text{in}}\Gamma_{S}|^{2}} |S_{21}|^{2} \frac{1 - |\Gamma_{L}|^{2}}{|1 - S_{22}\Gamma_{L}|^{2}}$$

$$\Gamma_{\text{in}} = \frac{V_{1}^{-}}{V^{+}} = S_{11}$$
More info: book of Gonzalez, page 92

More info: book of Gonzalez, page 92

General transistor amplifier circuit



$$G_S = \frac{1 - |\Gamma_S|^2}{|1 - \Gamma_{\text{in}} \Gamma_S|^2}$$
 $G_0 = |S_{21}|^2$ $G_L = \frac{1 - |\Gamma_L|^2}{|1 - S_{22} \Gamma_L|^2}$ Unilaterial case

$$G_T = G_S G_0 G_L$$

$$G_{T,dB} = G_{S,dB} + G_{0,dB} + G_{L,dB}$$

Remark: If $S_{12}=0$ then: $\Gamma_{out}=S_{22}$ and $\Gamma_{in}=S_{11}$

Circles of constant power gain

Unilateral transducer power gain G_{TU}:

$$\begin{split} G_{TU} &= \frac{P_L}{P_{AVS}} \bigg|_{\underline{S}_{12}=0} \\ &= \frac{1 - \big|\underline{\Gamma}_S\big|^2}{\big|1 - \underline{\Gamma}_S \underline{S}_{11}\big|^2} \big|\underline{S}_{21}\big|^2 \frac{1 - \big|\underline{\Gamma}_L\big|^2}{\big|1 - \underline{\Gamma}_L \underline{S}_{22}\big|^2} \\ &= G_S \quad \cdot \quad G_0 \quad \cdot \quad G_L \\ &\downarrow \qquad \qquad \qquad \\ \text{Impact of the input matching network on the gain} \quad \text{Impact of the output matching network on the gain} \end{split}$$

For which values of Γ_S do we achieve the desired value of G_S ?

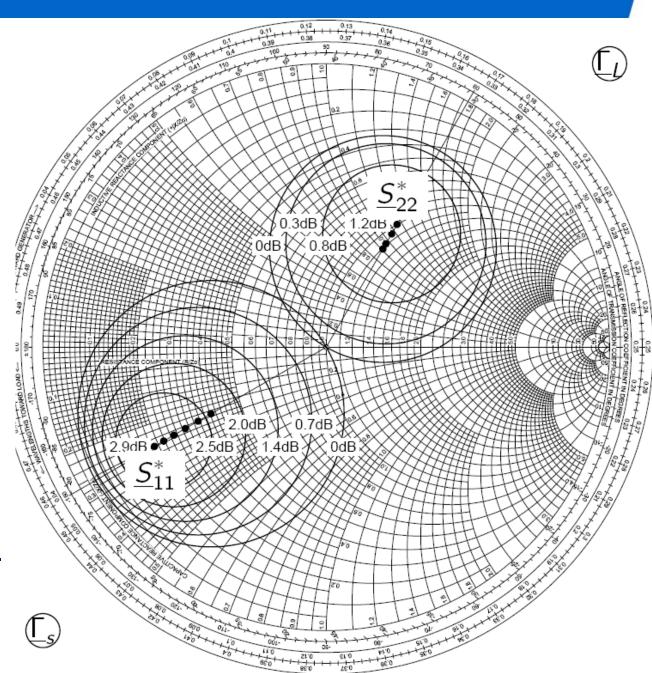
For which values of Γ_L do we achieve the desired value of G_L ?

The values of Γ_S that lead to a constant G_S are situated on circles in the complex Γ plane.

The values of Γ_L that lead to a constant G_L are situated on circles in the complex Γ plane.

These circles are called: Constant gain circles

For $\Gamma_S = S^*_{11}$ maximum G_S is obtained. For $\Gamma_L = S^*_{22}$ maximum G_L is obtained.



Circles of constant power gain

Maximum gain of the input and output matching networks

$$G_{S_{\text{max}}} = \frac{1}{1 - |S_{11}|^2}, \text{ for } \Gamma_{S} = S^*_{11}$$

$$G_{L_{\text{max}}} = \frac{1}{1 - |S_{22}|^2}$$
 for $\Gamma_L = S_{22}^*$

Normalized gain factors g_s and g_L

$$g_S = \frac{G_S}{G_{S_{\text{max}}}} = \frac{1 - |\Gamma_S|^2}{|1 - S_{11}\Gamma_S|^2} (1 - |S_{11}|^2),$$

$$g_L = \frac{G_L}{G_{L_{\text{max}}}} = \frac{1 - |\Gamma_L|^2}{|1 - S_{22}\Gamma_L|^2} (1 - |S_{22}|^2).$$

Center and radius of the constant gain circle for the input and output matching network

$$C_S = \frac{g_S S_{11}^*}{1 - (1 - g_S)|S_{11}|^2},$$

$$R_S = \frac{\sqrt{1 - g_S} \left(1 - |S_{11}|^2 \right)}{1 - (1 - g_S)|S_{11}|^2}$$

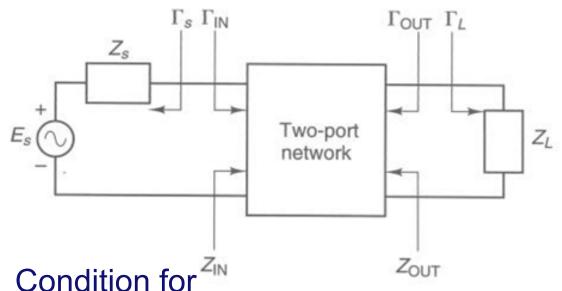
$$C_L = \frac{g_L S_{22}^*}{1 - (1 - g_L)|S_{22}|^2},$$

$$R_L = \frac{\sqrt{1 - g_L} \left(1 - |S_{22}|^2 \right)}{1 - (1 - g_L)|S_{22}|^2}$$

More info: book of Pozar, page 624, book of Gonzalez, page 103



Stability discussion of 2-port circuits



Stability analysis of an amplfier means: Investigation whether there can be oscillations

"unconditionally stable" device:

for all
$$|\underline{\Gamma}_L| < 1$$
 and $|\underline{\Gamma}_S| < 1$

$$\Rightarrow \begin{cases} \left| \Gamma_{in} \right| = \left| S_{11} + \frac{S_{12} S_{21} \Gamma_L}{1 - S_{22} \Gamma_L} \right| < 1 \\ \left| \Gamma_{out} \right| = \left| S_{22} + \frac{S_{12} S_{21} \Gamma_S}{1 - S_{11} \Gamma_S} \right| < 1 \end{cases}$$

If at a given frequency there are source and load reflection coefficients, for which this condition does not hold the device is called "potentially unstable".

Simplification: Unilateral case

for all $|\underline{\Gamma}_L| < 1$ and $|\underline{\Gamma}_S| < 1$

General case:

$$S_{12} \neq 0$$

$$\Rightarrow \begin{cases} \left| \Gamma_{in} \right| = \left| S_{11} + \frac{S_{12} S_{21} \Gamma_{L}}{1 - S_{22} \Gamma_{L}} \right| < 1 \\ \left| \Gamma_{out} \right| = \left| S_{22} + \frac{S_{12} S_{21} \Gamma_{S}}{1 - S_{11} \Gamma_{S}} \right| < 1 \end{cases}$$

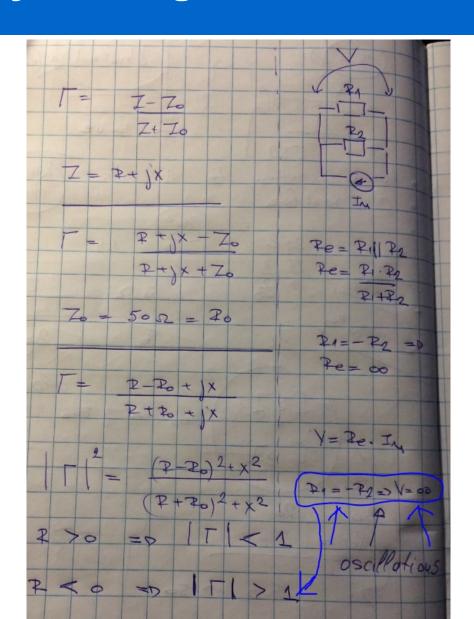
Unilateral case:

$$S_{12} = 0$$

$$\Rightarrow \begin{cases} \left| \Gamma_{in} \right| = \left| S_{11} \right| < 1 \\ \left| \Gamma_{out} \right| = \left| S_{22} \right| < 1 \end{cases}$$



Stability - background





Input stability circles

Boundary between stability and instability is given by:

$$|\Gamma_{\text{OUT}}| = 1$$

$$|\Gamma_{\text{OUT}}| = \left| S_{22} + \frac{S_{12} S_{21} \Gamma_s}{1 - S_{11} \Gamma_s} \right| = 1$$

$$\left| \Gamma_s - \frac{(S_{11} - \Delta S_{22}^*)^*}{|S_{11}|^2 - |\Delta|^2} \right| = \left| \frac{S_{12} S_{21}}{|S_{11}|^2 - |\Delta|^2} \right|$$

Circle equation in the complex Γ-plane

$$r_s = \left| \frac{S_{12} S_{21}}{|S_{11}|^2 - |\Delta|^2} \right|$$
 (radius)

$$C_s = \frac{(S_{11} - \Delta S_{22}^*)^*}{|S_{11}|^2 - |\Delta|^2}$$
 (center)

This circle is called the **output stability circle**. It is the boundary between the region Γ_S that lead to a stable or an unstable reflection amplifier.

 $\Delta = S_{11}S_{22} - S_{12}S_{21}$ ref

Output stability circles

Boundary between stability and instability is given by:

$$\left|\underline{\Gamma}_{in}\right| = 1$$

$$\Leftrightarrow \left| \underline{S}_{11} + \frac{\underline{S}_{12}\underline{S}_{21}\underline{\Gamma}_L}{1 - \underline{S}_{22}\underline{\Gamma}_L} \right| = 1$$

$$\left|\underline{\Gamma}_{L} - \frac{\underline{S}_{22}^{*} - \underline{\Delta}^{*}\underline{S}_{11}}{\left|\underline{S}_{22}\right|^{2} - \left|\underline{\Delta}\right|^{2}}\right|^{2} = \left|\underline{\frac{S}_{12}\underline{S}_{21}}{\left|\underline{S}_{22}\right|^{2} - \left|\underline{\Delta}\right|^{2}}\right|^{2}$$
 Circle equation in the complex

$$\left|\underline{\Gamma}_L - \underline{C}_L\right|^2 = \left|R_L\right|^2$$

$$C_L = \frac{\left(S_{22} - \Delta S_{11}^*\right)^*}{|S_{22}|^2 - |\Delta|^2}$$
 (center),

$$R_L = \left| \frac{S_{12} S_{21}}{|S_{22}|^2 - |\Delta|^2} \right|$$
 (radius).

$$\Delta = S_{11}S_{22} - S_{12}S_{21}$$

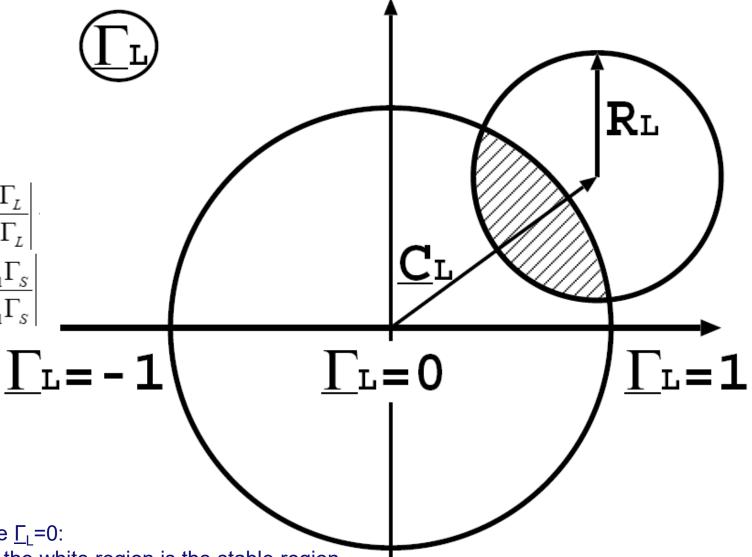
in the complex Γ-plane

This circle is called the **output stability circle**. It is the boundary between the region Γ_{l} that lead to a stable or an unstable reflection amplifier.

> An equivalent derivation of the output reflection coefficient leads to the input stability circle.

Construction Of the Output Stability circle

$$\begin{aligned} \left| \Gamma_{in} \right| &= \left| S_{11} + \frac{S_{12} S_{21} \Gamma_L}{1 - S_{22} \Gamma_L} \right| \\ \left| \Gamma_{out} \right| &= \left| S_{22} + \frac{S_{12} S_{21} \Gamma_S}{1 - S_{11} \Gamma_S} \right| \end{aligned}$$



- 1) Consider the case $\underline{\Gamma}_L$ =0:
- if $|\underline{\Gamma}_{in}| = |\underline{S}_{11}| < 1$, then the white region is the stable region
- if $|\underline{\Gamma}_{in}| = |\underline{S}_{11}| > 1$, then the white region is the unstable region
- 2) If $|S_{11}| < 1$ and $|C_L| R_L| > 1$ the 2-port is unconditionally stable

Tests for unconditional stability

If
$$|\Delta| = |S_{11}S_{22} - S_{12}S_{21}| < 1$$

Rollet stability factor K

and
$$K = \frac{1 - |S_{11}|^2 - |S_{22}|^2 + \Delta^2}{2|S_{12}S_{21}|} > 1$$

than the 2-port is unconditionally stable.

Unilateral case: $S_{12}=0$

Conditions for $|\underline{S}_{11}| < 1$ unconditional stability:

