

# Digital Signal Processing Fundamentals (5ESC0)

## Introduction

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## Books

- \* The course is based on the book:

*Schaum's Outline of Theory and Problems*  
*"Digital Signal Processing"; Monson H. Hayes*  
ISBN13: 97890071635097

- \* Stochastic Signal Processing is based on:

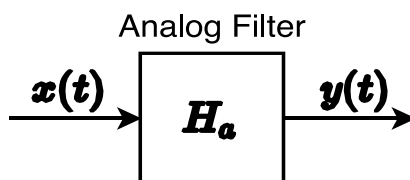
*Chapter 3 from the book*  
*"Statistical and Adaptive Signal Processing"*  
*Dimitris G. Manolakis, Vinay K. Ingle and Stephan M. Kogon*  
ISBN: 1-58053-610-7

## Introduction Content

- \* Global course content
- \* Organization
- \* Preknowledge

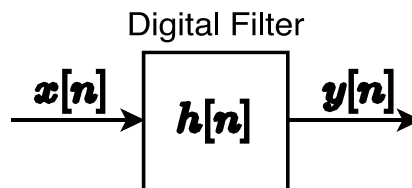
## Global Content

- \* In practice, many signals are analog signals
- \* Analog signals are continuous time signals and in this course we denote them by using round brackets:  $x(t)$
- \* In the figure below, an analog filter is used to obtain output signal  $y(t)$  from input signal  $x(t)$
- \* A filter with an in- and output signal is an example of what we cover under [Systems and Signals](#)



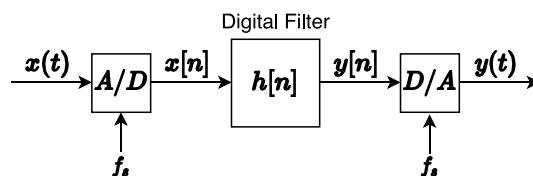
## Global Content

- \* Manipulating signals is mainly done in the digital domain, where we talk about discrete time signals
- \* In this course, we denote discrete time signals by using square brackets:  $x[n]$
- \* In the figure below, a digital filter is used to obtain output signal  $y[n]$  from input signal  $x[n]$

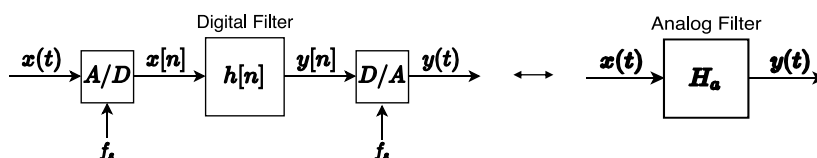


## Global Content

- \* There are benefits to using the digital domain, but this implies we have to convert an analog signal to a digital signal, which we do by [Sampling](#)
- \* Sampling was treated in Signals I for periodic signals. In this course, we will look at what is happening in these blocks in detail
- \* The block scheme below shows the same digital filter, but now with conversion from and to analog

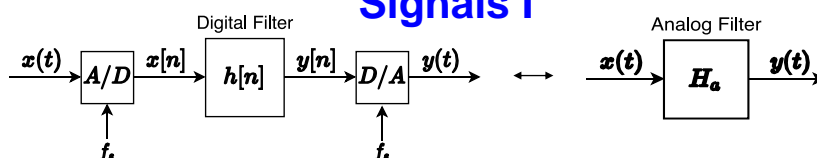


## Content Outline



- \* To explain **Signals & Systems** and **Sampling**, we need **mathematical analysis tools** which are often in the form of **Transforms**
- \* Many transforms are related to Fourier: Fourier Series (FS), Fourier Transform for Continuous time signals (FTC), Fourier Transform for Discrete time signals (FTD), Discrete Fourier Transform (DFT), Fast Fourier Transform (FFT), Z-Transform (ZT)
- \* On the next slide, the outline of the chapters that we will cover is shown

## Content Outline: **red** means new w.r.t. Signals I



- \* **Signals & Systems**
  - Periodic vs a-periodic signals : Ch 1
  - Deterministic vs Stochastic signals : Ch 1 + **Ch 10**
  - LTI systems (Linear Time Invariant) : Ch 1
  - System function : **Ch 5**
  - Filter structures : **Ch 8**
  - Filter design : **Ch 9**
- \* **Sampling**
  - A/D, D/A and multirate : **Ch 3**
- \* **Mathematical analysis tools, Transforms**
  - FS, FTC, FTD, DFT/FFT, ZT : **Ch 2 + Ch 4 + Ch 6/7**

# Organization

- \* **Course hours:** 8 hours per week

- 4 hours lectures
- 4 hours instructions/ labs

We strongly advise you to prepare at home and use the contact hours for assistance. You learn most from your own efforts and mistakes.

- \* **Grading:**

1. Written exam (70%)
2. Labs (30%)

- \* **All relevant information on Canvas**

- \* **Register in Canvas for a lab group (maximum 2 members per group)**

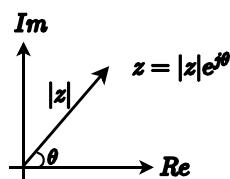
- \* **If previous year average lab grade was at least a 6 → exemption**

# Preknowledge: Complex numbers

- \* **Polar notation:**

$$z = |z|e^{j\theta}$$

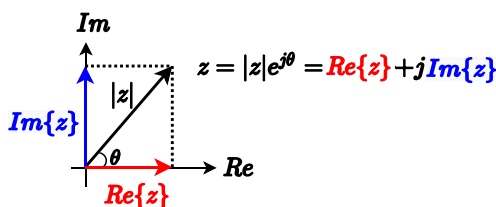
- $|z|$  is the length of the vector and  $\theta$  is the angle



- \* **Cartesian notation:**

$$z = \text{Re}\{z\} + j \cdot \text{Im}\{z\}$$

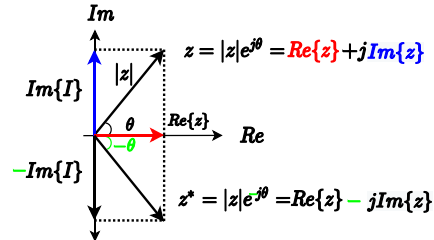
- There is a real part and an imaginary part, the imaginary part is indicated by  $j$ ,  $j = \sqrt{-1}$



# Preknowledge: Complex numbers

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- \* Complex conjugation:  $j \rightarrow -j$



- \* Euler:

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

# Preknowledge: Important geometric series

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- \* With  $z_0$  some (possibly complex) number:

$$\sum_{n=0}^{\infty} (z_0)^n = \frac{1}{1 - z_0}$$

iff  $|z_0| < 1$

- \* If  $|z_0| \geq 1$ , the series will not hold as divergence instead of convergence will occur

## Preknowledge: Important geometric series

- \* Proof:
- \*  $\sum_{n=0}^{\infty} (z_0)^n = \frac{1}{1-z_0}$  (Multiply both sides with  $(1 - z_0)$ )
- \*  $\sum_{n=0}^{\infty} (z_0)^n - z_0 \sum_{n=0}^{\infty} (z_0)^n = 1$  (If the series holds then the left hand side has to equal 1. Now we expand the summations)
- \*  $(1 + z_0 + z_0^2 + z_0^3 + \dots) - z_0(1 + z_0 + z_0^2 + \dots) = 1$
- \*  $1 + z_0 - z_0 + z_0^2 - z_0^2 + z_0^3 - z_0^3 + \dots = 1$
- \* All terms after the 1 cancel each other out, so the series holds.

## Preknowledge: Important geometric series

- \* With  $z_0$  some (possibly complex) number:

$$\sum_{n=0}^{M-1} (z_0)^n = \frac{1 - z_0^M}{1 - z_0}$$

- \* Note that there is no restriction on the magnitude of  $z_0$

## Preknowledge: Important geometric series

- \* Proof using  $\sum_{n=0}^{\infty} (z_0)^n = \frac{1}{1-z_0}$ :
- \*  $\sum_{n=0}^{M-1} (z_0)^n = \sum_{n=0}^{\infty} (z_0)^n - \sum_{n=M}^{\infty} (z_0)^n$  (The series can be split in two series, mind the bounds)
- \*  $= \sum_{n=0}^{\infty} (z_0)^n - \sum_{n=M}^{\infty} (z_0)^n = \frac{1}{1-z_0} - \sum_{n=M}^{\infty} (z_0)^n$  (now we expand the remaining summation)
- \*  $= \frac{1}{1-z_0} - (z_0^M + z_0^{M+1} + \dots)$  (now we can take  $z_0^M$  out of the brackets)
- \*  $= \frac{1}{1-z_0} - z_0^M (1 + z_0^1 + \dots) = \frac{1}{1-z_0} - z_0^M \sum_{p=0}^{\infty} (z_0)^p$
- \*  $\frac{1}{1-z_0} - \frac{z_0^M}{1-z_0} = \frac{1-z_0^M}{1-z_0}$

## Preknowledge: Zeros of a complex equation

- \* With  $a$  some (complex) number, find the zeros of:  $z^N - a = 0$
- \* We move  $a$  to the other side and then take the Nth root of both sides

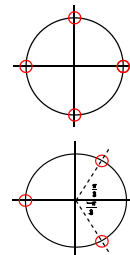
$$z^N = a = a e^{jk \cdot 2\pi} \rightarrow z_k = a^{\frac{1}{N}} \cdot e^{jk \cdot \frac{2\pi}{N}} \text{ for } k = 0, 1, \dots, N-1$$

- \* Example:  $a = 1$ ,  $N = 4$ . We fill in the equation:

$$\rightarrow z_k = e^{jk \cdot \frac{\pi}{2}}$$

- \* Example:  $a = -1$ ,  $N = 3$

$$\begin{aligned} \rightarrow z_k &= (-1)^{\frac{1}{3}} \cdot e^{jk \cdot \frac{2\pi}{3}} \\ &= (e^{j\pi})^{\frac{1}{3}} \cdot e^{jk \cdot \frac{2\pi}{3}} \\ &= e^{j\frac{\pi}{3} + k \cdot \frac{2\pi}{3}} \end{aligned}$$



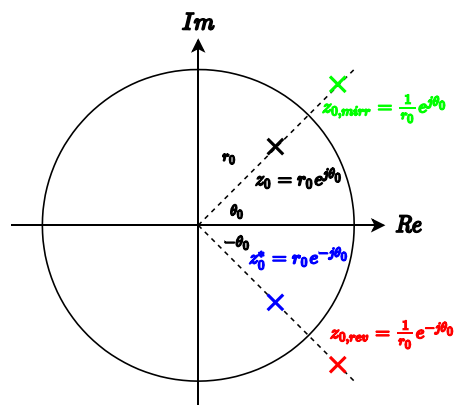


## Preknowledge: Mirroring and conjugation

- \* Take a point  $z_0 = r_0 e^{j\theta_0}$
- \* *Complex conjugation* is done by replacing  $j$  with  $-j$ :  $z_0^* = r_0 e^{-j\theta_0}$
- \* *Mirroring*  $z_0$  is done by taking the inverse of  $z_0$  and then the complex conjugate:  $z_{0,mirr} = \left(\frac{1}{z_0}\right)^* = \frac{1}{r_0} e^{j\theta_0}$   
This is called mirroring because the point is mirrored with respect to the unit circle.
- \* *Reversing*  $z_0$  is done by both mirroring and taking the complex conjugate:  $z_{0,rev} = z_{0,mirr}^* = \frac{1}{r_0} e^{-j\theta_0} = \frac{1}{z_0}$

## Preknowledge: Mirroring and conjugation

- \* Take a point  $z_0 = r_0 e^{j\theta_0}$
- \* *Complex conjugation*:  $z_0^* = r_0 e^{-j\theta_0}$
- \* *Mirroring*:  $z_{0,mirr} = \left(\frac{1}{z_0}\right)^* = \frac{1}{r_0} e^{j\theta_0}$
- \* *Reversing*:  $z_{0,rev} = z_{0,mirr}^* = \frac{1}{r_0} e^{-j\theta_0}$



## Summary

- \* We discussed the global content of the course
- \* We divided the global content in [Signals and Systems](#), [Sampling](#) and the [Mathematical analysis tools/ Transforms](#): the subjects we will cover in this course
- \* We looked at the preknowledge needed to follow the course:
  - Complex numbers
  - Geometric series
  - Finding the zeros of a complex equation
  - Mirroring, conjugation and reversal