



## Semester 2 Examinations 2022–2023

<b>Course Instance Codes</b>	2BA1, 2BDS1, 2BME1, 2BMU1, 1OA2, 1OA3, 2BCT1, 2BMS1, 2BPT1, 2BS1, 3BS9, 2FM1
<b>Examinations Module Codes</b>	Second Year Science, Arts, Computer Science & Information Technology MA283
<b>Module Paper No</b>	Mathematics 1
<b>External Examiner</b>	Prof. C. Roney-Dougal
<b>Internal Examiners</b>	Prof. G. Pfeiffer Dr R. Quinlan*

<b><u>Instructions:</u></b>	Answer THREE of the four questions. Within each question, all four parts carry equal marks
<b>Duration</b>	Two hours
<b>No. of Pages</b>	Three (including this cover page)

<b><u>Requirements:</u></b>	
Release in Exam Venue	Yes <input checked="" type="checkbox"/> No <input type="checkbox"/>
MCQ	Yes <input type="checkbox"/> No <input checked="" type="checkbox"/>
Handout	None
Statistical Tables/ Log Tables	None
Cambridge Tables	None
Graph paper	None
Log Graph Paper	None
Other Materials	Non-programmable calculators are permitted

1. (a) Find the general solution of the following system of linear equations.

$$\begin{array}{rrrrrr} x_1 & + & 3x_2 & + & 2x_3 & + & 3x_4 & = & 6 \\ 2x_1 & - & x_2 & + & x_3 & + & 8x_4 & = & -1 \\ 2x_1 & + & 2x_2 & + & 3x_3 & + & 10x_4 & = & 6 \end{array}$$

- (b) Find the unique value of  $k$  for which the following system is consistent.

$$\begin{array}{rrrrrr} x_1 & + & 3x_2 & + & 2x_3 & + & 3x_4 & = & 6 \\ 2x_1 & - & x_2 & + & x_3 & + & 8x_4 & = & -1 \\ 2x_1 & + & 2x_2 & + & 3x_3 & + & 10x_4 & = & 6 \\ x_1 & + & x_2 & - & x_3 & - & 5x_4 & = & k \end{array}$$

- (c) Find the unique solution of the following system of linear equations.

$$\begin{array}{rrrrrr} x_1 & + & 3x_2 & + & 2x_3 & + & 3x_4 & = & 6 \\ 2x_1 & - & x_2 & + & x_3 & + & 8x_4 & = & -1 \\ 2x_1 & + & 2x_2 & + & 3x_3 & + & 10x_4 & = & 6 \\ x_1 & - & 2x_2 & + & x_3 & - & x_4 & = & 9 \end{array}$$

- (d) State, with a short explanation, whether each of the following is TRUE or FALSE.

- i. A system of three linear equations in three variables can have infinitely many solutions.
- ii. A system of three linear equations in four variables can have a unique solution.

2. (a) What is meant by a *spanning set* of a vector space  $V$ ? Exactly one of the following sets is a spanning set of  $\mathbb{R}^3$ . Determine which one, with explanation.

$$S_1 = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right\}, \quad S_2 = \left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

- (b) Let  $V$  be the subset of  $M_3(\mathbb{R})$  consisting of all matrices  $A$  with the property that  $A^T + A$  is diagonal, where  $A^T$  denotes the transpose of  $A$ . Show that  $V$  is a subspace of  $M_3(\mathbb{R})$ , and determine its dimension.
- (c) Let  $V$  be a vector space over  $\mathbb{R}$ , with a spanning set  $S = \{v_1, v_2, v_3\}$ . Show that every set of four elements of  $V$  is linearly dependent.
- (d) Let  $A$  be a  $m \times n$  matrix with real entries. Explain what is meant by the *row rank* and the *column rank* of  $A$ , and show that these are equal.

3. (a) Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the linear transformation defined by

$$T(v) = \begin{bmatrix} 2 & -2 & 0 \\ 2 & -4 & -1 \\ 2 & -4 & 1 \end{bmatrix} v,$$

for a column vector  $v \in \mathbb{R}^3$ . What is  $T\left(\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}\right)$ ?

Determine the matrix of  $T$  with respect to the basis  $\mathcal{B}$  of  $\mathbb{R}^3$  given by

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \right\}.$$

- (b) Suppose that  $v_1, \dots, v_k$  are eigenvectors of a square matrix  $A$ , corresponding respectively to different eigenvalues  $\lambda_1, \dots, \lambda_k$ . Show that  $\{v_1, \dots, v_k\}$  is a linearly independent set.
- (c) Give an example of
- A matrix in  $M_2(\mathbb{R})$  whose characteristic polynomial is  $X^2 + 1$ .
  - A non-zero matrix in  $M_2(\mathbb{R})$ , that has 0 occurring twice as an eigenvalue.
  - A matrix in  $M_2(\mathbb{R})$  that is similar to  $\begin{bmatrix} 1 & 1 \\ 2 & 4 \end{bmatrix}$  and has 2 as its entry in the (1,1)-position.
- (d) Let  $A$  be a square matrix with an eigenvalue  $\lambda$ . What is meant by the *algebraic multiplicity* and *geometric multiplicity* of  $\lambda$  as an eigenvalue of  $A$ ? Explain why the geometric multiplicity cannot exceed the algebraic multiplicity.
4. (a) A scalar product  $\star$  on  $\mathbb{R}^3$  is defined by

$$\begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \star \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} = a_1 b_2 + a_2 b_3 + a_3 b_1.$$

Is  $\star$  an inner product on  $\mathbb{R}^3$ ? Why or why not?

- (b) In  $\mathbb{R}^3$ , calculate the orthogonal projection of  $\begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$  on the subspace  $U$  spanned by  $\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$  and

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

- (c) Consider the following inconsistent system of linear equations.

$$\begin{array}{rcl} x & + & 2y = 3 \\ 3x & + & 7y = 8 \\ 3x & + & 5y = 4 \end{array}$$

What is meant by the *least-squares approximate solution* to this system? By using the concept of projection on a subspace or otherwise, explain why the least-squares approximate solution is given by

$$\hat{x} = (A^T A)^{-1} A^T \begin{bmatrix} 3 \\ 8 \\ 4 \end{bmatrix},$$

where  $A$  is the coefficient matrix of the system.

- (d) Find the least-squares approximate solution of the system of equations in part (c).