

$$x_0 \in \mathbb{R}^n$$

$$x(t) = e^{At} x(0) + \int_0^t e^{A(t-\tau)} B u(\tau) d\tau$$

$$\text{Modos: } [0-t_1] : \dot{x} = A_1 x + \underbrace{B_1 u_1}_{dt}$$

$$[t_1-t_2] : \dot{x} = A_2 x + B_2 u_2$$

$$\vdots$$

$$[t_{n-1}-t_n] : \dot{x} = A_n x + B_n u_n$$

$$x(t_1) = \underbrace{e^{A_1 t_1}}_{F_1} x(0) + \underbrace{\left[\int_0^{t_1} e^{A_1(t_1-\tau)} B_1 d\tau \right]}_{G_1} u_1$$

$$[F_1, G_1] = \text{c2dm}(A_1, B_1, [], [], t_1, 'zoh')$$

$$\begin{cases} x(t_1) = F_1 x(0) + G_1 u_1 \\ x(t_2) = F_2 x(t_1) + G_2 u_2 \\ \vdots \\ x(t_n) = F_n x(t_{n-1}) + G_n u_n \end{cases}$$

$$[F_2, G_2] = \text{c2dm}(A_2, B_2, \begin{matrix} C \\ D \end{matrix}, [], t_2-t_1, 'zoh')$$

$$x(t_n) = F_n \cdot F_{n-1} \cdots F_1 x(0) + \underbrace{F_n F_{n-1} \cdots F_2 G_1 u_1 + F_n F_{n-1} \cdots F_3 G_2 u_2 + \cdots + F_n G_{n-1} u_{n-1} + G_n u_n}_{c(t_1, t_2, \dots, t_n)}$$

$$\text{Queremos } x(t_n) = x(0) = ?$$

$$\underbrace{(I - F_n F_{n-1} \cdots F_1)}_{\text{Inversa invertida}} x(0) = c \Leftrightarrow x(0) = \underbrace{(I - F_n F_{n-1} \cdots F_1)^{-1}}_{=}$$