

Fast egg to chicken transformation - ICPC Library

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1 Data Structures

1.1 Segment Tree

```

#include <vector>
template<class T>
class SegmentTree {
    struct Node {
        T val;
        Node(T x) : val(x) {}
        Node () : val(0) {}
    };
    int N;
    std::vector<T> a;
    std::vector<Node> tr;
    Node neutral;
    inline Node join(const Node &a, const Node &b) {
        return Node(a.val + b.val);
    }
    void build(int node, int l, int r) {
        if (l == r) {
            tr[node] = Node(a[l]);
            return;
        }
        int mid = l+(r-l)/2, lc = (node << 1);
        build(lc, l, mid);
        build(lc+1, mid+1, r);
        tr[node] = join(tr[lc], tr[lc+1]);
    }
    void update(int node, int l, int r, int idx, T x) {
        if (l == r) {
            tr[node] = Node(x);
            return;
        }
        int mid = l+(r-l)/2, lc = (node << 1);
        if(idx <= mid) update(lc, l, mid, idx, x);
        else update(lc+1, mid+1, r, idx, x);
        tr[node] = join(tr[lc], tr[lc+1]);
    }
    Node query(int node, int l, int r, int ql, int qr) {
        if (r < l or qr < l or r < ql) return neutral;
        if (ql <= l and r <= qr) return tr[node];
        int mid = l+(r-l)/2, lc = (node << 1);
        return join(query(lc, l, mid, ql, std::min(qr, mid)),
            query(lc+1, mid+1, r, std::max(mid+1, ql), qr));
    }
    // Searching for the first element greater than a given amount (
    // segtree of max)
    int get_first(int node, int l, int r, int ql, int qr, T x) {
        if (r < l or qr < l or r < ql) return -1;
        if (ql <= l and r <= qr) {
            if (tr[node].val <= x) return -1;
            while (l != r) {
                int mid = l+(r-l)/2, lc = (node << 1);
                if (tr[lc].val > x) {
                    node = lc;
                    r = mid;
                } else {
                    node = lc+1;
                    l = mid+1;
                }
            }
        }
    }
};

```

```

    }
}
return l;
}
int mid = l+(r-1)/2, lc = (node << 1);
int rs = get_first(lc, l, mid, ql, std::min(qr, mid), x);
if (~rs) return rs;
return get_first(lc+1, mid+1, r, std::max(ql, mid+1), qr, x);
}
public:
template<class MyIterator>
SegmentTree (MyIterator begin, MyIterator end) {
    N = end-begin-1;
    tr.assign(4*N, 0);
    a = std::vector<T>(begin, end);
    build(1, 1, N);
}
SegmentTree (int n) : N(n) {
    tr.assign(4*N, 0);
    a.assign(N+1, 0);
}
T query(int l, int r) {
    return query(1, 1, N, l, r).val;
}
void update(int idx, T x) {
    update(1, 1, N, idx, x);
}
};

```

1.2 Segment Tree Lazy Propagation

```

#include <vector>
template<class T>
class SegmentTreeLazy {
    struct Node {
        T val;
        Node(T x) : val(x) {}
        Node () : val(0) {}
    };
    int N;
    std::vector<T> a, lazy;
    std::vector<Node> tr;
    Node neutral;
    inline Node join(const Node &a, const Node &b) {
        return Node(a.val + b.val);
    }
    inline void upLazy(int node, int l, int r) {
        if (lazy[node] == 0) return;
        tr[node].val += lazy[node]*(r-l+1);
        int lc = (node << 1);
        (l != r ? lazy[lc] += lazy[node], lazy[lc+1] += lazy[node] : 0);
        lazy[node] = 0;
    }
    void build(int node, int l, int r) {
        if (l == r) tr[node] = Node(a[l]);
        else {
            int mid = l+(r-1)/2, lc = (node << 1);
            build(lc, l, mid);
            build(lc+1, mid+1, r);
            tr[node] = join(tr[lc], tr[lc+1]);
        }
    }
};

```

```

    }
}
void update(int node, int l, int r, int ul, int ur, T x) {
    upLazy(node, l, r);
    if (r < r or ur < ul or r < l or r < ul) return;
    if (ul <= l and r <= ur) {
        lazy[node] += x;
        upLazy(node, l, r);
    } else {
        int mid = l+(r-1)/2, lc = (node << 1);
        update(lc, l, mid, ul, std::min(ur, mid), x);
        update(lc+1, mid+1, r, std::max(mid+1, ul), ur, x);
        tr[node] = join(tr[lc], tr[lc+1]);
    }
}
Node query(int node, int l, int r, int ql, int qr) {
    upLazy(node, l, r);
    if (r < l or qr < ql or qr < l or r < ql) return neutral;
    if (ql <= l and r <= qr) return tr[node];
    int mid = l+(r-1)/2, lc = (node << 1);
    return join(query(lc, l, mid, ql, std::min(qr, mid)),
               query(lc+1, mid+1, r, std::max(mid+1, ql), qr));
}
public:
template<class MyIterator>
SegmentTreeLazy (MyIterator begin, MyIterator end) {
    N = end-begin-1;
    tr.assign(4*N, 0);
    lazy.assign(4*N, 0);
    a = std::vector<T>(begin, end);
    build(1, 1, N);
}
SegmentTreeLazy (int n) : N(n) {
    tr.assign(4*N, 0);
    lazy.assign(4*N, 0);
    a.assign(N+1, 0);
}
T query(int l, int r) {
    return query(1, 1, N, l, r).val;
}
void update(int l, int r, T x) {
    update(1, 1, N, l, r, x);
}
};

```

1.3 Segment Tree Range Update Point Query

```

#include <vector>
template<class T>
class SegmentTree {
    struct Node {
        T val;
        Node(T x) : val(x) {}
        Node () : val(0) {}
    };
    int N;
    std::vector<T> a;
    std::vector<Node> tr;
    Node neutral;
    inline Node join(const Node &a, const Node &b) {

```

```

    return Node();
}
void build(int node, int l, int r) {
    if (l == r) {
        tr[node] = Node(a[l]);
    } else {
        int mid = l+(r-1)/2, lc = (node << 1);
        build(lc, l, mid);
        build(lc+1, mid+1, r);
    }
}
T query(int node, int l, int r, int idx) {
    if (l == r) return tr[node].val;
    int mid = l+(r-1)/2, lc = (node << 1);
    if (idx <= mid) return tr[node].val + query(lc, l, mid, idx);
    else return tr[node].val + query(lc+1, mid+1, r, idx);
}
void update(int node, int l, int r, int ql, int qr, T x) {
    if (r < l or qr < l or r < ql) return;
    if (ql <= l and r <= qr) {
        int delta = x-tr[node].val;
        tr[node].val += delta;
    } else {
        int mid = l+(r-1)/2, lc = (node << 1);
        update(lc, l, mid, ql, std::min(qr, mid), x);
        update(lc+1, mid+1, r, std::max(mid+1, ql), qr, x);
    }
}
public:
    template<class MyIterator>
    SegmentTree(MyIterator begin, MyIterator end) {
        N = end-begin-1;
        tr.assign(4*N, 0);
        a = std::vector<T>(begin, end);
        build(1, 1, N);
    }
    SegmentTree(int n) : N(n) {
        tr.assign(4*N, 0);
        a.assign(N+1, 0);
    }
    T query(int idx) {
        return query(1, 1, N, idx);
    }
    void update(int l, int r, T x) {
        update(1, 1, N, l, r, x);
    }
};

```

1.4 Merge Sort Tree

```

#include <vector>
#define all(x) (x).begin(), (x).end()
const int64_t INF = 0x3f3f3f3f;
template<class T>
class MergeSortTree {
    typedef std::vector<T> Node;
    inline Node join(const Node &a, const Node &b) {
        Node ans;
        merge(all(a), all(b), std::back_inserter(ans));
        return ans;
    }
};

```

```

}
int N;
std::vector<Node> tr;
std::vector<T> a;
Node neutral;
inline int szEq(int node, int k) {
    return upper_bound(all(tr[node]), k)-lower_bound(all(tr[node]), k)
        ; }
inline int szLe(int node, int k) {
    return upper_bound(all(tr[node]), k)-tr[node].begin(); }
inline int szLt(int node, int k) {
    return lower_bound(all(tr[node]), k)-tr[node].begin(); }
void build(int node, int l, int r) {
    if (l == r) return (void)tr[node].push_back(a[l]);
    int mid = l+(r-1)/2, lc = (node << 1);
    build(lc, l, mid);
    build(lc+1, mid+1, r);
    tr[node] = join(tr[lc], tr[lc+1]);
}
// Find the amount of value (lower, lower or equal, equal) than x
int query(int node, int l, int r, int ql, int qr, int k, int op) {
    if (r < l or qr < l or r < ql) return 0;
    if (ql <= l and r <= qr) return (op == -1 ? szLt(node, k) : op ==
        1 ? szLe(node, k) : szEq(node, k));
    int mid = l+(r-1)/2, lc = (node << 1);
    return query(lc, l, mid, ql, std::min(qr, mid), k, op) +
        query(lc+1, mid+1, r, std::max(ql, mid+1), qr, k, op);
}
//Find the smallest number greater or equal to x
T query(int node, int l, int r, int ql, int qr, T x) {
    if (r < l or qr < l or r < ql) return INF;
    if (ql <= l and r <= qr) {
        auto pos = lower_bound(all(tr[node]), x);
        if (pos != tr[node].end()) return *pos;
        return INF;
    }
    int mid = l+(r-1)/2, lc = (node << 1);
    return std::min(query(lc, l, mid, ql, std::min(mid, qr), x),
        query(lc+1, mid+1, r, std::max(ql, mid+1), qr, x));
}
public:
    template<class MyIterator>
    MergeSortTree(MyIterator begin, MyIterator end) {
        N = end-begin-1;
        a = std::vector<T>(begin, end);
        tr.assign(4*N, std::vector<T>());
        build(1, 1, N);
    }
    int lt(int l, int r, int k) {
        return query(1, 1, N, l, r, k, -1);
    }
    int le(int l, int r, int k) {
        return query(1, 1, N, l, r, k, 1);
    }
    int eq(int l, int r, int k) {
        return query(1, 1, N, l, r, k, 0);
    }
    T query(int l, int r, T x) {
        return query(1, 1, N, l, r, x);
    }
};

```

1.5 Fenwick Tree

```
#include <vector>
template<class T>
class FenwickTree {
    int N;
    std::vector<T> tr, a;
public:
    void add(int idx, T x){
        a[idx] = x;
        for (; idx <= N; idx += (idx & -idx))
            tr[idx] += x;
    }
    void set(int idx, T x){
        T delta = x-a[idx];
        a[idx] = x;
        for (; idx <= N; idx += (idx & -idx))
            tr[idx] += delta;
    }
    T query(int idx){
        T res = 0;
        for (; idx > 0; idx -= (idx & -idx))
            res += tr[idx];
        return res;
    }
    T query(int l, int r){
        return query(r)-query(l-1);
    }
    FenwickTree(int n) : N(n) {
        tr.resize(N+1, 0);
        a.resize(N+1, 0);
    }
};
```

1.6 Disjoint Set Union

```
#include <vector>
#include <numeric>
class DSU {
    int N;
    std::vector<int> link, sz;
public:
    int id(int x) { return link[x] = (link[x] == x ? x : id(link[x])); }
    int same(int x, int y) { return (id(x) == id(y)); }
    void unite(int x, int y) {
        x = id(x); y = id(y);
        if (x == y) return;
        if (sz[x] < sz[y]) std::swap(x,y);
        link[y] = x;
        sz[x] += sz[y];
    }
    int size(int x) { return sz[id(x)]; }
    DSU (int n) : N(n) {
        sz.assign(N+1, 1);
        link.resize(N+1);
        iota(link.begin(), link.end(), 0);
    }
};
```

1.7 Query Queue

```
#include <stack>
template<class T>
class QueryQueue {
    std::stack<std::pair<T, T>> s1, s2;
    inline T cmp(T a, T b) {
        return std::min(a, b);
    }
    void normalize() {
        if (s2.empty()) {
            while (!s1.empty()) {
                T e = s1.top().first; s1.pop();
                T new_e = s2.empty() ? e : cmp(e, s2.top().second);
                s2.push({e, new_e});
            }
        }
    }
public:
    inline void push(T e) {
        T new_e = s1.empty() ? e : cmp(e, s1.top().second);
        s1.push({e, new_e});
    }
    inline T front() {
        normalize();
        return s2.top().first;
    }
    inline T query() {
        if (s1.empty() or s2.empty())
            return (s1.empty() ? s2.top().second : s1.top().second);
        else
            return cmp(s1.top().second, s2.top().second);
    }
    T pop() {
        T e = front();
        s2.pop();
        return e;
    }
    inline int size() {
        return s1.size()+s2.size();
    }
};
```

1.8 Query Stack

```
#include <stack>
template<class T>
class QueryStack {
    std::stack<std::pair<T, T>> st;
    inline T cmp(T a, T b) {
        return std::min(a, b);
    }
public:
    inline void push(T e) {
        T new_e = st.empty() ? e : cmp(e, st.top().second);
        st.push({e, new_e});
    }
    inline T top() {
```

```

    return st.top().first;
}
inline T query() {
    return st.top().second;
}
inline T pop() {
    T e = top();
    st.pop();
    return e;
}
inline int size() {
    return st.size();
}
};

```

1.9 Sparse Table

```

#include <vector>
template<class T>
class SparseTable {
    std::vector<std::vector<T>> st;
    std::vector<int> log2;
    T neutral = 0x3f3f3f3f;
    const int nLog = 20;
    T join(T a, T b) {
        return std::min(a, b);
    }
public:
    template<class MyIterator>
    SparseTable(MyIterator begin, MyIterator end) {
        int n = end - begin;
        log2.resize(n+1);
        log2[1] = 0;
        for (int i = 2; i <= n; ++i)
            log2[i] = log2[i/2] + 1;
        st.resize(n, std::vector<T>(nLog, neutral));
        for (int i = 0; i < n; ++i, ++begin)
            st[i][0] = *begin;
        for (int j = 1; j < nLog; ++j)
            for (int i = 0; i + (1 << (j-1)) < n; ++i)
                st[i][j] = join(st[i][j-1], st[i + (1 << (j-1))][j-1]);
    }
    T query(int l, int r) {
        int sz = r - l + 1;
        T ans = neutral;
        for (int j = nLog - 1; j >= 0; --j) {
            if (sz & (1 << j)) {
                neutral = join(neutral, st[l][j]);
                l += (1 << j);
            }
        }
        return ans;
    }
    T queryRMQ(int l, int r) {
        int j = log2[r - l + 1];
        return join(st[l][j], st[r - (1 << j) + 1][j]);
    }
};

```

2 Graph Algorithms

2.1 Bridges

```

#include <vector>
const int MAXN = 1e5 + 5;
std::vector<int> gr[MAXN];
int used[MAXN], tin[MAXN], low[MAXN];
int n, timer;

void is_bridge(int u, int v) {
    return;
}

void dfs(int u, int p = -1) {
    used[u] = true;
    tin[u] = low[u] = timer++;
    for (int to : gr[u]) if (to != p) {
        if (used[to]) { //Is a back edge
            low[u] = std::min(low[u], tin[to]);
        } else {
            dfs(to, u);
            low[u] = std::min(low[u], low[to]);
            if (low[to] > tin[u]) {
                is_bridge(u, to);
            }
        }
    }
}

void find_bridges() {
    timer = 0;
    for (int i = 0; i < n; ++i) {
        used[i] = false;
        tin[i] = -1;
        low[i] = -1;
    }
    for (int i = 0; i < n; ++i)
        if (!used[i]) dfs(i);
}

```

2.2 Cutpoints

```

#include <vector>
const int MAXN = 1e5 + 5;
std::vector<int> gr[MAXN];
int used[MAXN], tin[MAXN], low[MAXN];
int n, timer;

void is_cutpoint(int u) {
    return;
}

void dfs(int u, int p = -1) {
    used[u] = true;
    tin[u] = low[u] = timer++;
    int children = 0;

```

```

for (int to : gr[u]) if (to != p) {
    if (used[to]) { //Is a back edge
        low[u] = std::min(low[u], tin[to]);
    } else {
        dfs(to, u);
        low[u] = std::min(low[u], low[to]);
        if (low[to] >= tin[u] and p != -1) {
            is_cutpoint(u);
        }
        ++children;
    }
}
if (p == -1 and children > 1)
    is_cutpoint(u);
}

void find_cutpoints() {
    timer = 0;
    for (int i = 0; i < n; ++i) {
        used[i] = false;
        tin[i] = -1;
        low[i] = -1;
    }
    for (int i = 0; i < n; ++i)
        if (!used[i]) dfs(i);
}

```

2.3 Kosaraju

```

#include <vector>
const int MAXN = 1e5+5;
namespace SCC {
    std::vector<int> gr[MAXN], gt[MAXN];
    std::vector<int> order;
    int comp[MAXN], used[MAXN];
    int n, timer, scc;

    void init(int _n) {
        n = _n;
        scc = 0;
        order.clear();
        for (int i = 0; i < n; ++i) {
            used[i] = false;
            comp[i] = 0;
            gr[i].clear();
            gt[i].clear();
        }
    }

    void addEdge(int u, int v) {
        gr[u].push_back(v);
        gt[v].push_back(u);
    }

    void dfs1(int u) {
        used[u] = timer;
        for (int to : gr[u]) if (used[to] != timer) {
            dfs1(to);
        }
        order.push_back(u);
    }
}

```

```

}

void dfs2(int u) {
    used[u] = timer;
    comp[u] = scc;
    for (int to : gt[u]) if (used[to] != timer) {
        dfs2(to);
    }
}

int get_scc() {
    ++timer;
    for (int u = 0; u < n; ++u) {
        if (used[u] != timer) {
            dfs1(u);
        }
    }
    ++timer;
    for (int i = n-1; i >= 0; --i) {
        if (used[order[i]] != timer) {
            dfs2(order[i]);
            ++scc;
        }
    }
    return scc;
}
};

```

2.4 LCA

```

#include <bits/stdc++.h>
using namespace std;
using ii = pair<int, int>;

const int maxn = 1e4+5;
const int L = 21;

namespace LCA {
    int anc[maxn][L], tin[maxn], tout[maxn], deep[maxn], h[maxn];
    vector<ii> gr[maxn];
    int n, timer;

    inline void init(int _n) {
        n = _n;
        timer = 0;
        for (int i = 0; i < n; ++i) {
            deep[i] = 0;
            h[i] = 0;
            tin[i] = tout[i] = 0;
            gr[i].clear();
            for (int j = 0; j < L; ++j) anc[i][j] = 0;
        }
    }

    void dfs(int u, int p) {
        tin[u] = ++timer;
        anc[u][0] = p;
        for (int i = 1; i < L; ++i) anc[u][i] = anc[ anc[u][i-1] ][i-1];
        for (auto [to, w] : gr[u]) if (to != p) {

```

```

    deep[to] = deep[u] + 1;
    h[to] = h[u] + w;
    dfs(to, u);
}
tout[u] = ++timer;
}

inline void addEdge(int u, int v, int w) {
    gr[u].emplace_back(v, w);
}

inline bool is_anc(int u, int v) {
    return (tin[u] <= tin[v] and tout[v] <= tout[u]);
}

inline int lca(int u, int v) {
    if (is_anc(u, v)) return u;
    if (is_anc(v, u)) return v;
    for (int i = L-1; i >= 0; --i) if (!is_anc(anc[u][i], v)) u = anc[u][i];
    return anc[u][0];
}

inline int kth_anc(int u, int k) {
    if (--k == 0) return u;
    for (int i = L-1; i >= 0; --i) {
        if (k - (1 << i) >= 0) {
            u = anc[u][i];
            k -= (1 << i);
        }
    }
    return u;
}

inline int dist_w(int a, int b) {
    return h[a] + h[b] - 2 * h[lca(a, b)];
}

inline int dist(int a, int b) {
    return deep[a] + deep[b] - 2 * deep[lca(a, b)];
}

inline void build() {
    dfs(0, 0);
}
};

```

2.5 Euler Tour

```

#include "../data_structures/fenwick_tree.h"
using namespace std;
const int MAX = 2e5+5;

std::vector<int> gr[MAX];
int n, timer, cost[MAX];
int lf[MAX], rt[MAX];

/*
    Memory: O(2*N)
*/

```

```

void dfs(int u, int par, std::vector<int> &euler) {
    euler[timer++] = u;
    if (lf[u] == -1) lf[u] = timer-1;
    rt[u] = timer-1;
    for (int to : gr[u]) if (to != par) {
        dfs(to, u, euler);
    }
    euler[timer++] = u;
    rt[u] = timer-1;
}

std::vector<int> getEulerTour(int s) {
    std::vector<int> euler(2*n);
    timer = 0;
    for (int i = 0; i < n; ++i) lf[i] = -1;
    dfs(s, -1, euler);
    return euler;
}

/*
    Sum of subtree and add to nodes
    - To add: FT.add(first(v), x)
    - To find sum: FT.query(first(v), last(v))
*/
/*
    Sum of path from ancestor and add to nodes
    - To add: FT.add(first(v), x) and FT.add(last(v), -x)
    - To find sum: FT.query(first(ancestor), first(v))
*/

```

2.6 Eulerian Path

```

#include <algorithm>
#include <vector>
typedef std::pair<int, int> ii;
template<bool dir=false>
struct EulerianPath {
    std::vector<std::vector<ii>> gr;
    std::vector<int> ans, ng;
    std::vector<bool> used;
    int N, m;
    EulerianPath(int n) : N(n) {
        m = 0;
        gr.assign(N, std::vector<ii>());
    }
    inline void addEdge(int a, int b) {
        int eg = m++;
        gr[a].push_back({b, eg});
        if (!dir) gr[b].push_back({a, eg});
    }
    void dfs(int u) {
        while (ng[u] < (int)gr[u].size()) {
            auto [to, id] = gr[u][ng[u]++];
            if (!used[id]) {
                used[id] = true;
                dfs(to);
            }
        }
        ans.push_back(u);
    }
    std::vector<int> getPath(int s) {
        ng.assign(N, 0);
    }
}

```

```

used.assign(m, false);
ans.clear();
dfs(s);
std::reverse(ans.begin(), ans.end());
return ans;
}
};

```

2.7 HLD Edges

```

#include <bits/stdc++.h>
using namespace std;
using i64 = long long int;
using vi64 = vector<i64>;
using ii = pair<int, int>;

#define fi first
#define se second

const int maxn = 1e5+5;

namespace SegmentTree {

    struct Node {
        i64 val;
        Node(i64 x) : val(x) {}
        Node () : val(0LL) {}
    };

    inline Node join(const Node &a, const Node &b) {
        return Node(a.val + b.val);
    }

    int n;
    i64 lazy[4*maxn];
    Node tree[4*maxn];
    Node neutral;
    i64 lazyNeutral = -1LL;

    inline void upLazy(int node, int l, int r) {
        if (lazy[node] == lazyNeutral) return;

        tree[node].val += lazy[node] * (r - l + 1LL); //To increment value
        // tree[node].val = lazy[node] * (r - l + 1LL); //To set value

        if (l != r) {
            int lc = (node << 1);
            // lazy[lc] = lazy[node]; //To set value
            // lazy[lc+1] = lazy[node]; //To set value
            lazy[lc] = (lazy[lc] == lazyNeutral ? lazy[node] : lazy[lc] +
                lazy[node]); //To increment value
            lazy[lc+1] = (lazy[lc+1] == lazyNeutral ? lazy[node] : lazy[lc
                +1] + lazy[node]); //To increment value
        }

        lazy[node] = lazyNeutral;
    }

    void build(int node, int l, int r, int *v) {
        lazy[node] = lazyNeutral;

```

```

        if (l == r) { tree[node].val = v[l]; return; }
        int mid = 1+(r-l)/2, lc = (node << 1);
        build(lc, l, mid, v);
        build(lc+1, mid+1, r, v);
        tree[node] = join(tree[lc], tree[lc+1]);
    }

    void update(int node, int l, int r, int ul, int ur, i64 val) {
        upLazy(node, l, r);
        if (r < l or ur < ul or ur < l or r < ul) return;
        if (ul <= l and r <= ur) {
            lazy[node] = val; // To set value
            lazy[node] = (lazy[node] == lazyNeutral ? val : lazy[node] + val
                ); // To increment value
            upLazy(node, l, r);
            return;
        }
        int mid = 1+(r-l)/2, lc = (node << 1);
        update(lc, l, mid, ul, min(mid, ur), val);
        update(lc+1, mid+1, r, max(mid+1, ul), ur, val);
        tree[node] = join(tree[lc], tree[lc+1]);
    }

    Node query(int node, int l, int r, int ql, int qr) {
        upLazy(node, l, r);
        if (r < l or qr < ql or qr < l or r < ql) return neutral;
        if (ql <= l and r <= qr) return tree[node];
        int mid = 1+(r-l)/2, lc = (node << 1);
        return join(query(lc, l, mid, ql, min(mid, qr)), query(lc+1, mid
            +1, r, max(mid+1, ql), qr));
    }

    void build(int _n, int *v) {
        n = _n;
        build(1, 1, n, v);
    }

    i64 query(int l, int r) {
        return query(1, 1, n, l, r).val;
    }

    void update(int l, int r, i64 val) {
        update(1, 1, n, l, r, val);
    }
};

namespace HLD {
    struct edge {
        int a; i64 w;
        edge () {}
        edge (int to, i64 ww) : a(to), w(ww) {}
    };

    vector<edge> gr[maxn];
    int pos[maxn], st[maxn], pai[maxn];
    int sobe[maxn], h[maxn], v[maxn], timer;
    int hei[maxn], deep[maxn];

    inline void addEdge(int a, int b, i64 w = 1LL) {
        gr[a].push_back(edge(b, w));

```



```

}

//O(n)
void dfs(int u, int p = -1) {
    st[u] = 1;
    for (auto &e : gr[u]) if (e.a != p) {
        sobe[e.a] = e.w;
        dfs(e.a, u);
        st[u] += st[e.a];
        if (st[e.a] > st[gr[u][0].a] or gr[u][0].a == p) swap(e, gr[u][0]);
    }
}

//O(n)
void build_hld(int u, int p = -1) {
    pos[u] = ++timer;
    v[pos[u]] = sobe[u];
    for (auto e : gr[u]) if (e.a != p) {
        pai[e.a] = u;
        h[e.a] = (e.a == gr[u][0].a ? h[u] : e.a);
        build_hld(e.a, u);
    }
}

inline void build(int root = 0) {
    timer = 0;
    h[root] = 0;
    hei[root] = 0;
    deep[root] = 0;
    dfs(root);
    build_hld(root);
    SegmentTree::build(timer, v);
}

//O(log^2(n))
i64 query_path(int a, int b) {
    if (a == b) return 0LL;
    if (pos[a] < pos[b]) swap(a, b);

    if (h[a] == h[b]) return SegmentTree::query(1+pos[b], pos[a]);
    return SegmentTree::query(pos[h[a]], pos[a]) +
        query_path(pai[h[a]], b);
}

//O(log^2(n))
void update_path(int a, int b, int x) {
    if (a == b) return;
    if (pos[a] < pos[b]) swap(a, b);
    if (h[a] == h[b]) return (void) SegmentTree::update(1+pos[b], pos[a], x);
    SegmentTree::update(1, 1, timer, pos[h[a]], pos[a], x);
    update_path(pai[h[a]], b, x);
}

//O(log(n))
inline i64 query_subtree(int a) {
    if (st[a] == 1) return 0LL;
    return SegmentTree::query(1+pos[a], pos[a]+st[a]-1);
}

```

```

//O(log(n))
inline void update_subtree(int a, int x) {
    if (st[a] == 1) return;
    SegmentTree::update(1+pos[a], pos[a]+st[a]-1, x);
}

//O(log(n))
int lca(int a, int b) {
    if (pos[a] < pos[b]) swap(a, b);
    return (h[a] == h[b] ? b : lca(pai[h[a]], b));
}

//O(log(n))
i64 distw(int a, int b) {
    return hei[a] + hei[b] - 2 * hei[lca(a, b)];
}

//O(log(n))
int dist(int a, int b) {
    return deep[a] + deep[b] - 2 * deep[lca(a, b)];
}
};

```

2.8 HLD Nodes

```

#include <bits/stdc++.h>
using namespace std;
using i64 = long long int;
using vi64 = vector<i64>;

const int maxn = 1e5+5;

namespace SegmentTree {

    struct Node {
        i64 val;
        Node(i64 x) : val(x) {}
        Node() : val(0LL) {}
    };

    inline Node join(const Node &a, const Node &b) {
        return Node(a.val + b.val);
    }

    int n;
    i64 lazy[4*maxn];
    Node tree[4*maxn];
    Node neutral;
    i64 lazyNeutral = -1LL;

    inline void upLazy(int node, int l, int r) {
        if (lazy[node] == lazyNeutral) return;

        tree[node].val += lazy[node] * (r - l + 1LL); //To increment value
        // tree[node].val = lazy[node] * (r - l + 1LL); //To set value

        if (l != r) {
            int lc = (node << 1);
            // lazy[lc] = lazy[node]; //To set value
            // lazy[lc+1] = lazy[node]; //To set value

```

```

    lazy[lc] = (lazy[lc] == lazyNeutral ? lazy[node] : lazy[lc] +
        lazy[node]); //To increment value
    lazy[lc+1] = (lazy[lc+1] == lazyNeutral ? lazy[node] : lazy[lc
        +1] + lazy[node]); //To increment value
}

lazy[node] = lazyNeutral;
}

void build(int node, int l, int r, int *v) {
    lazy[node] = lazyNeutral;
    if (l == r) { tree[node].val = v[l]; return; }
    int mid = l+(r-l)/2, lc = (node << 1);
    build(lc, l, mid, v);
    build(lc+1, mid+1, r, v);
    tree[node] = join(tree[lc], tree[lc+1]);
}

void update(int node, int l, int r, int ul, int ur, i64 val) {
    upLazy(node, l, r);
    if (r < l or ur < ul or ur < l or r < ul) return;
    if (ul <= l and r <= ur) {
        // lazy[node] = val; // To set value
        lazy[node] = (lazy[node] == lazyNeutral ? val : lazy[node] + val
            ); // To increment value
        upLazy(node, l, r);
        return;
    }
    int mid = l+(r-l)/2, lc = (node << 1);
    update(lc, l, mid, ul, min(mid, ur), val);
    update(lc+1, mid+1, r, max(mid+1, ul), ur, val);
    tree[node] = join(tree[lc], tree[lc+1]);
}

Node query(int node, int l, int r, int ql, int qr) {
    upLazy(node, l, r);
    if (r < l or qr < ql or qr < l or r < ql) return neutral;
    if (ql <= l and r <= qr) return tree[node];
    int mid = l+(r-l)/2, lc = (node << 1);
    return join(query(lc, l, mid, ql, min(mid, qr)), query(lc+1, mid
        +1, r, max(mid+1, ql), qr));
}

void build(int _n, int *v) {
    n = _n;
    build(1, 1, n, v);
}

i64 query(int l, int r) {
    return query(1, 1, n, l, r).val;
}

void update(int l, int r, i64 val) {
    update(1, 1, n, l, r, val);
}
};

namespace HLD {
    struct edge {
        int a; i64 w;

```

```

        edge () {}
        edge (int to, i64 ww) : a(to), w(ww) {}
    };

    vector<edge> gr[maxn];
    int pos[maxn], st[maxn], pai[maxn];
    int h[maxn], v[maxn], val[maxn], timer;
    int deep[maxn], hei[maxn];

    inline void addEdge(int a, int b, i64 w = 1LL) {
        gr[a].push_back(edge(b, w));
    }

    //O(n)
    void dfs(int u, int p = -1) {
        st[u] = 1;
        for (auto &e : gr[u]) if (e.a != p) {
            pai[e.a] = u;
            deep[e.a] = deep[u] + 1;
            hei[e.a] = hei[u] + e.w;
            dfs(e.a, u);
            st[u] += st[e.a];
            if (st[e.a] > st[gr[u][0].a] or gr[u][0].a == p) swap(e, gr[u
                ][0]);
        }
    }

    //O(n)
    void build_hld(int u, int p = -1) {
        pos[u] = ++timer;
        v[pos[u]] = val[u];
        for (auto e : gr[u]) if (e.a != p) {
            h[e.a] = (e.a == gr[u][0].a ? h[u] : e.a);
            build_hld(e.a, u);
        }
    }

    void build(int root = 0) {
        timer = 0;
        h[root] = 0;
        hei[root] = 0;
        deep[root] = 0;
        dfs(root);
        build_hld(root);
        SegmentTree::build(timer, v);
    }

    //O(log^2 (n))
    i64 query_path(int a, int b) {
        if (pos[a] < pos[b]) swap(a, b);
        if (h[a] == h[b]) return SegmentTree::query(pos[b], pos[a]);
        return SegmentTree::query(pos[h[a]], pos[a]) + query_path(pai[h[a]
            ], b);
    }

    //O(log^2 (n))
    void update_path(int a, int b, i64 x) {
        if (pos[a] < pos[b]) swap(a, b);
        if (h[a] == h[b]) return (void) SegmentTree::update(pos[b], pos[a
            ], x);
        SegmentTree::update(pos[h[a]], pos[a], x);
    }
}

```

```

    update_path(pai[h[a]], b, x);
}

//O(log(n))
inline i64 query_subtree(int a) {
    return SegmentTree::query(pos[a], pos[a]+st[a]-1);
}

//O(log(n))
inline void update_subtree(int a, i64 x) {
    SegmentTree::update(pos[a], pos[a]+st[a]-1, x);
}

//O(log(n))
int lca(int a, int b) {
    if (pos[a] < pos[b]) swap(a, b);
    return (h[a] == h[b] ? b : lca(pai[h[a]], b));
}

//O(log(n))
i64 distw(int a, int b) {
    return hei[a] + hei[b] - 2 * hei[lca(a, b)];
}

//O(log(n))
int dist(int a, int b) {
    return deep[a] + deep[b] - 2 * deep[lca(a, b)];
}
};

```

2.9 SPFA

```

#include <vector>
#include <queue>
typedef std::pair<int, int> ii;
const int INF = 0x3f3f3f3f;
namespace SPFA {
    std::vector<std::vector<ii>> gr;
    std::vector<int> d;
    int N;
    void init(int n) {
        N = n;
        d.assign(N, INF);
        gr.assign(N, std::vector<ii>());
    }
    inline void addEdge(int a, int b, int c) {
        gr[a].push_back({b, c});
    }
    bool spfa(int s) {
        std::vector<int> cnt(N, 0);
        std::vector<bool> inqueue(N, false);
        std::queue<int> q;

        d[s] = 0;
        q.push(s);
        inqueue[s] = true;
        while (!q.empty()) {
            int u = q.front(); q.pop();
            inqueue[u] = false;
            for (auto [to, w] : gr[u]) {

```

```

                if (d[u] + w < d[to]) {
                    d[to] = d[u] + w;
                    if (!inqueue[to]) {
                        inqueue[to] = true;
                        q.push(to);
                        ++cnt[to];
                        if (cnt[to] > N)
                            return false; //Negative cycle
                    }
                }
            }
        }

        return true;
    }
};

```

2.10 Maximum Flow

```

#include <vector>
#include <queue>
const int INF = 0x3f3f3f3f;
namespace MaxFlow {
    std::vector<std::vector<int>> capacity;
    std::vector<std::vector<int>> gr;
    int N;
    void init(int n) { N = n;
        capacity.assign(N, std::vector<int>(N));
        gr.assign(N, std::vector<int>());
    }
    void addEdge(int u, int v, int cap) {
        gr[u].push_back(v);
        gr[v].push_back(u);
        capacity[u][v] += cap;
        capacity[v][u] += 0;
    }
    int bfs(int s, int t, std::vector<int> &parent) {
        fill(parent.begin(), parent.end(), -1);
        parent[s] = -2;
        std::queue<std::pair<int, int>> q;
        q.push({s, INF});
        while (!q.empty()) {
            auto [cur, flow] = q.front(); q.pop();
            for (int next : gr[cur]) {
                if (parent[next] == -1 and capacity[cur][next]) {
                    parent[next] = cur;
                    int new_flow = std::min(flow, capacity[cur][next]);
                    if (next == t)
                        return new_flow;
                    q.push({next, new_flow});
                }
            }
        }
        return 0;
    }
    int maxflow(int s, int t) {
        int flow = 0;
        std::vector<int> parent(N);
        int new_flow;
        while (new_flow = bfs(s, t, parent)) {

```

```

    flow += new_flow;
    int cur = t;
    while (cur != s) {
        int prev = parent[cur];
        capacity[prev][cur] -= new_flow;
        capacity[cur][prev] += new_flow;
        cur = prev;
    }
    return flow;
}
};

```

3 Math

3.1 Basic Math

```

#include <string>
uint64_t modMul(uint64_t a, uint64_t b, uint64_t MOD) {
    return (__uint128_t)a*b%MOD;
}
uint64_t binpow(uint64_t base, uint64_t exp, uint64_t MOD) {
    base %= MOD;
    uint64_t res = 1;
    while (exp > 0) {
        if (exp & 1) res = modMul(res, base, MOD);
        base = modMul(base, base, MOD);
        exp >>= 1;
    }
    return res;
}
uint64_t bigExp(uint64_t base, std::string exp, uint64_t MOD) {
    base %= MOD;
    uint64_t ans = 1LL;
    for (char c : exp) {
        ans = binpow(ans, 10LL, MOD);
        ans = modMul(ans, binpow(base, c-'0', MOD), MOD);
    }
    return ans;
}
uint64_t gcd(uint64_t a, uint64_t b) { return (b == 0 ? a : gcd(b, a%b)); }
uint64_t lcm(uint64_t a, uint64_t b) { return a / gcd(a, b) * b; }
uint64_t binary_gcd(uint64_t a, uint64_t b) {
    if (a == 0 || b == 0)
        return a ^ b;
    int shift = __builtin_ctzll(a | b);
    a >>= __builtin_ctzll(a);
    do {
        b >>= __builtin_ctzll(b);
        if (a > b)
            std::swap(a, b);
        b -= a;
    } while (b);
    return a << shift;
}
namespace ModHash{
    const uint64_t MOD = (1ll<<61) - 1;
}

```

```

uint64_t modmul(uint64_t a, uint64_t b){
    uint64_t l1 = (uint32_t)a, h1 = a>>32, l2 = (uint32_t)b, h2 = b
    >>32;
    uint64_t l = l1*l2, m = l1*h2 + l2*h1, h = h1*h2;
    uint64_t ret = (l&MOD) + (l>>61) + (h << 3) + (m >> 29) + ((m <<
        35) >> 3) + 1;
    ret = (ret & MOD) + (ret>>61);
    ret = (ret & MOD) + (ret>>61);
    return ret-1;
}
};

```

3.2 Modular Arithmetic

```

#include <bits/stdc++.h>
#include "extended_euclidean.h"
using namespace std;

const int64_t MOD = 1e9+7;

inline int64_t modSum(int64_t a, int64_t b, int64_t mod = MOD) {
    return (a+b >= mod ? a+b-mod : a+b);
}
inline int64_t modSub(int64_t a, int64_t b, int64_t mod = MOD) {
    return (a-b < 0 ? a-b+mod : a-b);
}
inline int64_t modMul(int64_t a, int64_t b, int64_t mod = MOD) {
    return (a*b)%mod;
}
int64_t inv_mod(int64_t a, int64_t m = MOD) {
    int64_t x, y;
    extended_gcd(a, m, x, y);
    return (x%m + m)%m;
}
int64_t modDiv(int64_t a, int64_t b, int64_t mod = MOD) {
    return modMul(a, inv_mod(b, mod), mod);
}
//O(log(a))
int64_t bigModMul(int64_t a, int64_t b) {
    int64_t ans = 0LL;
    b %= MOD;
    while (a > 0) {
        if (a & 1) ans = modSum(ans, b);
        b = modMul(b, 2LL);
        a >>= 1;
    }
    return ans;
}
uint64_t bigModMul_2(uint64_t a, uint64_t b) {
    long double x;
    uint64_t c;
    int64_t r;
    if (a >= MOD) a %= MOD;
    if (b >= MOD) b %= MOD;
    x = a;
    c = (x * b) / MOD;
    r = (int64_t) (a * b - c * MOD) % (int64_t)MOD;
    return (r < 0 ? r+MOD : r);
}

```

3.3 Factorial

```
#include "modular.h"
const int MAXV = 1e6+5;

int64_t fat[MAXV], ifat[MAXV];
void init() {
    fat[0] = 1LL;
    for (int64_t i = 1; i < MAXV; ++i) {
        fat[i] = (fat[i-1] * i) % MOD;
    }
    ifat[MAXV-1] = inv_mod(fat[MAXV-1], MOD);
    for (int64_t i = MAXV-1; i >= 1; --i) {
        ifat[i-1] = (ifat[i] * i) % MOD;
    }
}
```

3.4 Prime Number

```
#include <bits/stdc++.h>
#include "basic_math.h"

using namespace std;

bool check_composite(uint64_t n, uint64_t a, uint64_t d, int s) {
    uint64_t x = binpow(a, d, n);
    if (x == 1 or x == n - 1)
        return false;
    for (int r = 1; r < s; ++r) {
        x = modMul(x, x, n);
        if (x == n - 1)
            return false;
    }
    return true;
}

bool MillerRabin(uint64_t n) {
    if (n < 4)
        return (n == 2 or n == 3);

    uint64_t d = n - 1;
    int s = __builtin_ctzll(d);
    d >>= s;

    for (uint64_t a : {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37}) {
        // int a = 2 + rand() % (n - 3); // nondeterministic version
        if (n == a)
            return true;
        if (check_composite(n, a, d, s))
            return false;
    }
    return true;
}

uint64_t pollard(uint64_t n) {
    auto f = [n](uint64_t x) { return (modMul(x, x, n) + 1) % n; };
    uint64_t x = 0, y = 0, t = 30, prd = 2, i = 1, q;
    while (t++ % 40 or binary_gcd(prd, n) == 1) {
```

```
        if (x == y)
            x = ++i, y = f(x);
        if ((q = modMul(prd, max(x, y) - min(x, y), n))
            prd = q;
            x = f(x), y = f(f(y));
        }
    }
    return binary_gcd(prd, n);
}

vector<uint64_t> factor(uint64_t n) {
    if (n == 1)
        return {};
    if (MillerRabin(n))
        return {n};
    uint64_t x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), r.begin(), r.end());
    return l;
}
```

3.5 Matrix Exponentiation

```
#include <vector>
#include <algorithm>

template<typename T>
struct Matrix {
    T MOD = 1e9+7;
    std::vector<std::vector<T>> mat;
    Matrix(int n, int m, bool id = false) {
        mat.resize(n, std::vector<T>(m, 0));
        if (id) for (int i = 0; i < n; ++i)
            mat[i][i] = 1;
    }
    Matrix(std::vector<std::vector<int>> oth) : mat(oth) {}
    Matrix<T> operator +(Matrix<T> oth) {
        int n = (int)mat.size();
        int m = (int)mat[0].size();
        Matrix<T> c(n, m, false);
        for (int i = 0; i < n; ++i) {
            for (int j = 0; j < m; ++j)
                c[i][j] = mat[i][j] + oth.mat[i][j];
        }
        return c;
    }
    Matrix<T> operator *(Matrix<T> oth) {
        int n = (int)mat.size();
        int m = (int)mat[0].size();
        int p = (int)oth.mat[0].size();
        Matrix<T> c(n, p, false);
        std::vector<T> col(m);
        for (int j = 0; j < p; ++j) {
            for (int k = 0; k < m; ++k)
                col[k] = oth.mat[k][j];
            for (int i = 0; i < n; ++i) {
                T sum = 0;
                for (int k = 0; k < m; ++k)
                    sum += mat[i][k] * col[k];
                c.mat[i][j] = sum;
            }
        }
    }
}
```

```

    }
    return c;
}
Matrix<T> operator*(T k) {
    int n = (int)mat.size();
    int m = (int)mat[0].size();
    Matrix<T> a(mat);
    for (int i = 0; i < n; ++i) for (int j = 0; j < m; ++j)
        a[i][j] *= k;
    return a;
}
Matrix<T> operator-(Matrix<T> oth) {
    Matrix<T> a = mat;
    return a + ((-1) * oth);
}
Matrix<T> operator^(T exp) {
    int n = (int)mat.size();
    Matrix<T> res(n, n, true), base(mat);
    while (exp > 0) {
        if (exp & 1)
            res = res * base;
        base = base * base;
        exp >>= 1;
    }
    return res;
}
};

```

3.6 Gauss Elimination

```

#include <iostream>
#include <algorithm>
#include "matrix.h"
typedef long double ld;
const ld EPS = 1e-9;
const int INF = 0x3f3f3f3f;

// Gaussian elimination with partial pivot (avoids propagation of
// rounding errors)
int gaussianElimination(Matrix<ld> a, Matrix<ld> &ans) {
    int n = (int)a.mat.size();
    int m = (int)a.mat[0].size()-1;
    std::vector<int> end(m, -1);

    for (int col = 0, row = 0; col < m and row < n; ++col) {
        int l = row;

        // Which row has largest column value
        for (int i = row; i < n; ++i)
            if (std::abs(a.mat[i][col]) > std::abs(a.mat[l][col]))
                l = i;
        if (std::abs(a.mat[l][col]) < EPS)
            continue;
        for (int i = col; i <= m; ++i)
            std::swap(a.mat[row][i], a.mat[l][i]);
        end[col] = row;

        // Elimination phase
        for (int i = 0; i < n; ++i) if (i != row) {
            ld c = a.mat[i][col] / a.mat[row][col];

```

```

            for (int j = m; j >= col; --j) {
                a.mat[i][j] -= a.mat[row][j] * c;
            }
            ++row;
        }

        // Substitution phase
        for (int i = 0; i < m; ++i)
            if (end[i] != -1)
                ans.mat[i][0] = a.mat[end[i]][m]/a.mat[end[i]][i];

        for (int i = 0; i < n; ++i) {
            ld sum = 0;
            for (int j = 0; j < m; ++j)
                sum += ans.mat[j][0] * a.mat[i][j];
            if (std::abs(sum - a.mat[i][m]) > EPS)
                return 0; // No solution
        }

        for (int i = 0; i < m; ++i)
            if (end[i] == -1)
                return INF; // Infinite solutions

        return 1; // One solution
    }
}

```

3.7 Extended Euclidean

```

#include "basic_math.h"

int64_t extended_gcd(int64_t a, int64_t b, int64_t &x, int64_t &y) {
    if (b == 0) {
        x = 1; y = 0;
        return a;
    }
    int64_t g = extended_gcd(b, a%b, y, x);
    y -= x*(a/b);
    return g;
}

```

4 Dynamic Programming

4.1 Prefix Sum Array

```

#include <bits/stdc++.h>
using namespace std;

const int maxn = 1e5+5;

/*
Answer queries:
Q(L, R) = 1*A[L] + 2*A[L+1] + 3*A[L+2] + ... (R-L+1)*A[R]
*/

int n, a[maxn];

```

```

int psa[maxn], ips[maxn];
int q, l, r, ans;

void computePSA() {
    for (int i = 1; i <= n; ++i) {
        psa[i] = psa[i-1] + a[i];
        ips[i] = ips[i-1] + i * a[i];
    }
    while (q-- > 0) {
        cin >> l >> r;
        ans = ips[r] - ips[l-1] - (l-1) * (psa[r] - psa[l-1]);
        cout << ans << '\n';
    }
}

```

5 Geometry

5.1 Basic Geometry

```

#include <bits/stdc++.h>
using namespace std;

#define eps 1e-9
#define eq(a, b) (abs(a - b) < eps)
#define lt(a, b) (a < b - eps)
#define gt(a, b) (a > b + eps)
#define le(a, b) (a <= b + eps)
#define ge(a, b) (a >= b - eps)
#define ftype long double
/*#define eq(a, b) (a == b)
#define lt(a, b) (a < b)
#define gt(a, b) (a > b)
#define le(a, b) (a <= b)
#define ge(a, b) (a >= b)
#define ftype long long*/

// Begin Point 2D
struct point2d {
    ftype x, y;

    point2d() : x(0.0), y(0.0) {}
    point2d(const ftype& x, const ftype& y) : x(x), y(y) {}

    point2d& operator=(const point2d& oth) {
        x = oth.x; y = oth.y;
        return (*this);
    }
    point2d& operator+=(const point2d& oth) {
        x += oth.x; y += oth.y;
        return (*this);
    }
    point2d& operator-=(const point2d& oth) {
        x -= oth.x; y -= oth.y;
        return (*this);
    }
    point2d& operator*=(const ftype& factor) {
        x *= factor; y *= factor;
        return (*this);
    }
}

```

```

    }
    point2d& operator/=(const ftype& factor) {
        x /= factor; y /= factor;
        return (*this);
    }
};

point2d operator+(const point2d& a, const point2d& b) {
    return point2d(a.x + b.x, a.y + b.y);
}

point2d operator-(const point2d& a, const point2d& b) {
    return point2d(a.x - b.x, a.y - b.y);
}

point2d operator*(const point2d& a, const ftype& factor) {
    return point2d(a.x * factor, a.y * factor);
}

point2d operator*(const ftype& factor, const point2d& a) {
    return point2d(factor * a.x, factor * a.y);
}

point2d operator/(const point2d& a, const ftype& factor) {
    return point2d(a.x / factor, a.y / factor);
}

bool operator==(const point2d& a, const point2d& b) {
    return (eq(a.x, b.x) and eq(a.y, b.y));
}

bool operator!=(const point2d& a, const point2d& b) {
    return !(a==b);
}

bool operator < (const point2d& a, const point2d& b) {
    return (lt(a.x, b.x) or (eq(a.x, b.x) and lt(a.y, b.y)));
}

bool operator > (const point2d& a, const point2d& b) {
    return (b < a);
}

bool operator <= (const point2d& a, const point2d& b) {
    return !(a > b);
}

bool operator >= (const point2d& a, const point2d& b) {
    return !(a < b);
}

// > 0 if |angle| < pi/2
// = 0 if |angle| = pi
// < 0 if |angle| > pi/2
ftype operator*(const point2d& a, const point2d& b) {
    return (a.x * b.x + a.y * b.y);
}

// < 0 if a comes before b in ccw
// = 0 if a is collinear to b
// > 0 if a comes after b in ccw
ftype operator^(const point2d& a, const point2d& b) {
    return (a.x * b.y - a.y * b.x);
}

ftype ccw(const point2d& a, const point2d& b) {
    return (a ^ b);
}

// ccw(a, b, c) : > 0 if a comes before b counterclockwise in origin
// ccw(a, b, c) : < 0 if a comes after b counterclockwise in origin
ftype ccw(const point2d& a, const point2d& b, const point2d& origin) {
    return ccw(a - origin, b - origin);
}

ftype abs(const point2d& a) {
    return (a * a);
}

```

```

}
ftype norm(const point2d& a) {
    return sqrt(abs(a));
}
ftype dist(const point2d& a, const point2d& b) {
    return norm(a - b);
}
ftype dist2(const point2d& a, const point2d& b) {
    return abs(a - b);
}
ftype dist_point_to_line(const point2d& a, const point2d& p1, const
    point2d& p2) {
    return (a-p1)^(p2-p1)/norm(p2-p1);
}
ftype distance_segment_to_point(const point2d& p, const point2d& q,
    const point2d& a) {
    ftype l2 = dist2(p, q);
    if (eq(l2, 0)) return dist(p, a);
    ftype t = max((ftype)0, min((ftype)1, (a-p)*(q-p)/l2));
    point2d proj = p + t * (q-p);
    return dist(a, proj);
}
ftype proj(const point2d& a, const point2d& b) {
    return (a*b)/(b*b);
}
point2d pointProj(const point2d& a, const point2d& b) {
    return proj(a, b)*b;
}
ftype angle(const point2d& a) {
    return atan2(a.y, a.x);
}
ftype angle(const point2d& a, const point2d& b) {
    return atan2(a ^ b, a * b);
}
ftype angle(const point2d& a, const point2d& b, const point2d& origin)
{
    return angle(a - origin, b - origin);
}
// Left rotation. Angle (rad)
point2d rotate(const point2d& a, const ftype& angleSin, const ftype&
    angleCos) {
    return point2d(a.x * angleCos - a.y * angleSin, a.x * angleSin + a
        .y * angleCos);
}
point2d rotate(const point2d& a, const ftype& angle) {
    return rotate(a, sin(angle), cos(angle));
}
// Pi/2 left rotation
point2d perp(const point2d& a) {
    return point2d(-a.y, a.x);
}
// 0 to 1 and 2 quadrant. 1 to 3 and 4
int half(const point2d& p) {
    if (gt(p.y, 0) or (eq(p.y, 0) and ge(p.x, 0))) return 0;
    return 1;
}
// angle(a) < angle(b)
bool cmpByAngle(const point2d& a, const point2d& b) {
    int ha = half(a), hb = half(b);
    if (ha != hb) return ha < hb;
    ftype c = a^b;
    if (eq(c, 0)) return lt(norm(a), norm(b));
    return gt(c, 0);
}
inline int sgn(ftype x) {
    return (ge(x, 0) ? (eq(x, 0) ? 0 : 1) : -1);
}
// Intersection of lines r : a + d1 * t
point2d intersect(const point2d& a1, const point2d& d1, const point2d&
    a2, const point2d& d2) {
    return a1 + ((a2-a1)^d2)/(d1^d2) * d1;
}
ftype area(vector<point2d> &pts){
    ftype ret = 0.0;
    for (int i = 2; i < (int)pts.size(); i++) {
        ret += ccw(pts[i] - pts[0], pts[i - 1] - pts[0]);
    }
    return abs(ret * 0.5);
}
ftype signed_area_parallelogram(const point2d& a, const point2d& b,
    const point2d& c) {
    return ccw(a, b, c);
}
ftype triangle_area(const point2d& a, const point2d& b, const point2d&
    c) {
    return abs(signed_area_parallelogram(a, b, c) * 0.5);
}
bool point_in_triangle(const point2d& a, const point2d& b, const
    point2d& c, const point2d& p) {
    ftype s1 = abs(ccw(b, c, a));
    ftype s2 = abs(ccw(a, b, p)) + abs(ccw(b, c, p)) + abs(ccw(c, a, p
        ));
    return eq(s1, s2);
}
bool pointInSquare(const point2d& A, const point2d& B, const point2d&
    C, const point2d& D, const point2d& P) {
    ftype s1 = 2*abs((B-A)^(D-A));
    ftype s2 = abs((B-P)^(A-P)) + abs((C-P)^(B-P)) + abs((D-P)^(C-P))
        + abs((A-P)^(D-P));
    return eq(s1, s2);
}
bool between(ftype l, ftype r, ftype x) {
    return (le(min(l, r), x) and ge(max(l, r), x));
}
bool pointInSegment(const point2d& a, const point2d& b, const point2d&
    p) {
    if (!eq(ccw(a, b, p), 0.0)) return false;
    return between(a.x, b.x, p.x) and between(a.y, b.y, p.y);
}
ftype up2(ftype a) {
    return (ftype)a * a;
}
// End Point 2D
// Begin Line
ftype det(ftype a, ftype b, ftype c, ftype d){
    return a * d - b * c;
}
struct Line {
    ftype a, b, c;
    Line () {}
    Line (ftype a1, ftype b1, ftype c1) : a(a1), b(b1), c(c1) {}
}

```



```

        normalize();
    }
    Line (const point2d& p1, const point2d& p2) {
        a = p1.y - p2.y;
        b = p2.x - p1.x;
        c = -a * p1.x - b * p1.y;
        normalize();
    }
    void normalize() {
        ftype z = sqrt(up2(a) + up2(b));
        if (!eq(z, 0)) { a /= z, b /= z, c /= z; }
        if (lt(a, 0.0) or (eq(a, 0.0) and lt(b, 0.0))) {
            a = -a;
            b = -b;
            c = -c;
        }
    }
};

bool intersection_point_of_lines(const Line& m, const Line& n, point2d
&res) {
    ftype zn = det(m.a, m.b, n.a, n.b);
    if (eq(zn, 0.0)) return false;
    res.x = -det(m.c, m.b, n.c, n.b) / zn;
    res.y = -det(m.a, m.c, n.a, n.c) / zn;
    return true;
}

bool parallel(const Line& m, const Line& n) {
    return eq(det(m.a, m.b, n.a, n.b), 0.0);
}

bool equivalent(const Line& m, const Line& n) {
    return eq(det(m.a, m.b, n.a, n.b), 0.0) and
        eq(det(m.a, m.c, n.a, n.c), 0.0) and
        eq(det(m.b, m.c, n.b, n.c), 0.0);
}

ftype dist(const Line& m, const point2d& p) {
    return abs(m.a * p.x + m.b * p.y + m.c) /
        sqrt(up2(m.a) + up2(m.b));
}

// End Line
// Begin Segment
struct Segment {
    point2d a, b;
    Segment () {}
    Segment (const point2d& a1, const point2d b1) : a(a1), b(b1) {}
};

bool inter1(ftype a, ftype b, ftype c, ftype d) {
    if (a > b) swap(a, b);
    if (c > d) swap(c, d);
    return le(max(a, c), min(b, d));
}

bool check_intersection(const Segment& s1, const Segment& s2) {
    point2d a = s1.a, b = s1.b, c = s2.a, d = s2.b;
    if (ccw(a, d, c) == 0 and ccw(b, d, c) == 0)
        return (inter1(a.x, b.x, c.x, d.x) and
            inter1(a.y, b.y, c.y, d.y));
    return sgn(ccw(b, c, a) != ccw(b, d, a) and
        ccw(d, a, c) != ccw(d, b, c));
}

bool intersection_point_of_segments(const Segment& s1, const Segment&
s2, Segment &ans) {
    point2d a = s1.a, b = s1.b, c = s2.a, d = s2.b;

```

```

    if (!inter1(a.x, b.x, c.x, d.x) or
        !inter1(a.y, b.y, c.y, d.y)) return false;
    Line m(a, b);
    Line n(c, d);
    if (parallel(m, n)) {
        if (!equivalent(m, n)) return false;
        if (b < a) swap(a, b);
        if (d < c) swap(c, d);
        ans = Segment(max(a, c), min(b, d));
        return true;
    } else {
        point2d p(0, 0);
        intersection_point_of_lines(m, n, p);
        ans = Segment(p, p);
        return between(a.x, b.x, p.x) and between(a.y, b.y, p.y) and
            between(c.x, d.x, p.x) and between(c.y, d.y, p.y);
    }
}

// End Segment

// Begin Circle
struct Circle {
    ftype x, y, r;
    Circle () {}
    Circle(ftype x1, ftype y1, ftype r1) : x(x1), y(y1), r(r1) {}
};

bool pointInCircle(const Circle& c, const point2d& p) {
    return ge(c.r, dist(point2d(c.x, c.y), p));
}

Circle circumCircle(const point2d& a, const point2d& b, const point2d&
c) {
    point2d u((b-a).y, -((b-a).x));
    point2d v((c-a).y, -((c-a).x));
    point2d n = (c-b) * 0.5;
    ftype t = (u^n) / (v^u);
    point2d ct = ((a+c) * 0.5) + (v * t);
    ftype r = dist(ct, a);
    return Circle(ct.x, ct.y, r);
}

Circle inCircle(const point2d& a, const point2d& b, const point2d& c)
{
    ftype m1 = dist(a, b);
    ftype m2 = dist(a, c);
    ftype m3 = dist(b, c);
    point2d ct = ((c * m1) + (b * m2) + a * m3) / (m1 + m2 + m3);
    ftype sp = 0.5 * (m1 + m2 + m3);
    ftype r = sqrt(sp * (sp - m1) * (sp - m2) * (sp - m3)) / sp;
    return Circle(ct.x, ct.y, r);
}

// Minimum enclosing circle
Circle minimumCircle(vector<point2d> p) {
    random_shuffle(p.begin(), p.end());
    Circle c = Circle(p[0].x, p[0].y, 0.0);
    for (int i = 0; i < (int)p.size(); ++i) {
        if (pointInCircle(c, p[i])) continue;
        c = Circle(p[i].x, p[i].y, 0.0);
        for (int j = 0; j < i; ++j) {
            if (pointInCircle(c, p[j])) continue;
            c = Circle((p[j].x + p[i].x)*0.5, (p[j].y + p[i].y)*0.5,
                0.5*dist(p[j], p[i]));
            for (int k = 0; k < j; ++k) {

```

```

        if (pointInCircle(c, p[k])) continue;
        c = circumCicle(p[j], p[i], p[k]);
    }
}
return c;
}
int circle_line_intersection(const Circle& circ, const Line& line,
    point2d& p1, point2d& p2) {
    ftype r = circ.r;
    ftype a = line.a, b = line.b, c = line.c + line.a * circ.x + line.
        b * circ.y; //take a circle to the (0, 0)
    ftype x0 = -a * c / (up2(a) + up2(b)), y0 = -b * c / (up2(a) + up2
        (b));  //(x0, y0) is the shortest distance point of the
        line for (0, 0)
    if (gt(up2(c), up2(r) * (up2(a) + up2(b)))) return 0;
    if (eq(up2(c), up2(r) * (up2(a) + up2(b)))) {
        p1.x = p2.x = x0 + circ.x;
        p1.y = p2.y = y0 + circ.y;
        return 1;
    } else {
        ftype d_2 = up2(r) - up2(c) / (up2(a) + up2(b));
        ftype mult = sqrt(d_2 / (up2(a) + up2(b)));
        p1.x = x0 + b * mult + circ.x;
        p2.x = x0 - b * mult + circ.x;
        p1.y = y0 - a * mult + circ.y;
        p2.y = y0 + a * mult + circ.y;
        return 2;
    }
}
int circle_intersection(const Circle& c1, const Circle& c2, point2d&
    p1, point2d& p2) {
    if (eq(c1.x, c2.x) and eq(c1.y, c2.y)){
        if (eq(c1.r, c2.r)) return -1; //INF
        else return 0;
    } else {
        Circle circ(0, 0, c1.r);
        Line line;
        line.a = -2 * (c2.x - c1.x);
        line.b = -2 * (c2.y - c1.y);
        line.c = up2(c2.x - c1.x) + up2(c2.y - c1.y) + up2(c1.r) - up2
            (c2.r);
        int sz = circle_line_intersection(circ, line, p1, p2);
        p1.x += c1.x;
        p2.x += c1.x;
        p1.y += c1.y;
        p2.y += c1.y;
        return sz;
    }
}
bool check_segment_covered_by_circles(const vector<Circle> &vc, const
    Segment& s) {
    vector<point2d> v = {s.a, s.b};
    Line l(s.a, s.b);
    for (Circle c : vc){
        point2d p1, p2;
        int inter = circle_line_intersection(c, l, p1, p2);
        if (inter >= 1 and between(s.a.x, s.b.x, p1.x) and between(s.a
            .y, s.b.y, p1.y))
            v.push_back(p1);
        if (inter == 2 and between(s.a.x, s.b.x, p2.x) and between(s.a

```

```

            .y, s.b.y, p2.y))
                v.push_back(p2);
    }
    sort(v.begin(), v.end());
    bool ans = true;
    for (int i = 1; i < (int)v.size(); i++){
        bool has = false;
        for (Circle c : vc){
            if (pointInCircle(c, v[i - 1]) and pointInCircle(c, v[i]))
                {
                    has = true;
                    break;
                }
        }
        ans &= has;
    }
    return ans;
}
void tangents(const point2d& c, double r1, double r2, vector<Line> &
    ans) {
    double r = r2 - r1;
    double z = up2(c.x) + up2(c.y);
    double d = z - up2(r);
    if (lt(d, 0)) return;
    d = sqrt(abs(d));
    Line l;
    l.a = (c.x * r + c.y * d) / z;
    l.a = (c.y * r + c.x * d) / z;
    l.c = r1;
    ans.push_back(l);
}
vector<Line> tangents(const Circle& a, const Circle& b) {
    vector<Line> ans;
    for (int i = -1; i <= 1; i += 2)
        for (int j = -1; j <= 1; j += 2)
            tangents(point2d(b.x - a.x, b.y - a.y), a.r * i, b.r * j,
                ans);
    for (int i = 0; i < (int)ans.size(); ++i) {
        ans[i].c -= ans[i].a * a.x + ans[i].b * a.y;
        ans[i].normalize();
    }
    return ans;
}
// End Circle

```

5.2 Convex Hull

```

#include <bits/stdc++.h>
using namespace std;

vector<point2d> convex_hull(vector<point2d> a){
    if (a.size() == 1) return a;
    sort(a.begin(), a.end());
    a.erase(unique(a.begin(), a.end()), a.end());

    vector<point2d> up, down;
    point2d p1 = a[0], p2 = a.back();
    up.push_back(p1);
    down.push_back(p1);

```

```

for (int i = 1; i < (int)a.size(); i++) {
    if ((i == (int)a.size() - 1) or ge(ccw(p2, a[i], p1), 0)) { //
        Accept collinear points
    }
    // if ((i == (int)a.size() - 1) or gt(ccw(p2, a[i], p1), 0)) {
    // Don't accept collinear points
    while (up.size() >= 2 and lt(ccw(a[i], up.back(), up[up.
        size()-2]), 0)) up.pop_back(); // Accept collinear
        points
    // while (up.size() >= 2 and le(ccw(a[i], up.back(), up[up.
        size()-2]), 0)) up.pop_back(); // Don't accept
        collinear points
    up.push_back(a[i]);
}
if ((i == (int)a.size() - 1) or ge(ccw(a[i], p2, p1), 0)) { //
    Accept collinear points
}
// if ((i == (int)a.size() - 1) or gt(ccw(a[i], p2, p1), 0)) {
// Don't accept collinear points
while (down.size() >= 2 and gt(ccw(a[i], down.back(), down.
    [down.size()-2]), 0)) down.pop_back(); // Accept
    collinear points
// while (down.size() >= 2 and ge(ccw(a[i], down.back(),
    down[down.size()-2]), 0)) down.pop_back(); // Don't
    accept collinear points
down.push_back(a[i]);
}
}

a.clear();
for (int i = 0; i < (int)up.size(); i++) a.push_back(up[i]);
for (int i = (int)down.size()-2; i >= 1; i--) a.push_back(down[i])
;
return a;
}

```

5.3 Convex Polygon

```

#include <bits/stdc++.h>
using namespace std;

namespace ConvexPolygon {
    vector<point2d> vp;
    void init(const vector<point2d>& aux) {
        vp = convex_hull(aux);
    }
    bool pointInPolygon(const point2d& point) {
        if (vp.size() < 3) return pointInSegment(vp[0], vp[1], point);

        if (!eq(ccw(vp[1], point, vp[0]), 0.0) and
            sgn(ccw(vp[1], point, vp[0])) != sgn(ccw(vp[1], vp.back(),
                , vp[0]))) return false;

        if (!eq(ccw(vp.back(), point, vp[0]), 0.0) and
            sgn(ccw(vp.back(), point, vp[0])) != sgn(ccw(vp.back(),
                vp[1], vp[0]))) return false;

        if (eq(ccw(vp[1], point, vp[0]), 0.0)) return ge(norm(vp[1]-vp
            [0]), norm(point-vp[0]));

        int pos = 1, l = 1, r = vp.size() - 2;
        while (l <= r) {

```

```

            int mid = (l + r) / 2;
            if (le(ccw(vp[mid], point, vp[0]), 0.0)) {
                pos = mid;
                l = mid + 1;
            } else {
                r = mid - 1;
            }
        }

        return point_in_triangle(vp[0], vp[pos], vp[pos+1], point);
    }
};

```

6 String Algorithms

6.1 Prefix Function

```

#include <bits/stdc++.h>
using namespace std;

/*
    p[i] is the length of the longest proper prefix of s[0..i]
    which is also a suffix of this string
    Run in O(|s|)
*/
vector<int> prefix_function(const string &s) {
    int n = s.size();
    vector<int> pi(n);
    for (int i = 1, j = 0; i < n; ++i) {
        while (j > 0 and s[i] != s[j]) j = pi[j-1];
        if (s[i] == s[j]) ++j;
        pi[i] = j;
    }
    return pi;
}

/*
    Returns a vector with the initial positions of
    all occurrences of s in t
    Using O(|s|) memory
    Run in O(|s|+|t|)
*/
vector<int> kmp(const string &s, const string &t) {
    vector<int> p = prefix_function(s+'$'), match;
    for (int i = 0, j = 0; i < (int)t.size(); ++i) {
        while (j > 0 and s[j] != t[i]) j = p[j-1];
        if (s[j] == t[i]) ++j;
        if (j == (int)s.size()) match.push_back(i-j+1);
    }
    return match;
}

/*
    ans[i] is the amount of occurrences of the prefix s[0..i] in s
*/
vector<int> prefix_occurrences(const string &s) {
    vector<int> pi = prefix_function(s);
    int n = pi.size();

```

```

vector<int> ans(n+1);
for (int i = 0; i < n; i++)
    ans[pi[i]]++;
for (int i = n-1; i > 0; i--)
    ans[pi[i-1]] += ans[i];
for (int i = 0; i <= n; i++)
    ans[i]++;
return ans;
}

inline int getId(char c) {
    return c-'a';
}

/*
    Run in O(26*|s|)
*/
struct autKMP {
    vector<vector<int>> nxt;
    autKMP (const string &s) : nxt(26, vector<int>(s.size()+1)) {
        vector<int> p = prefix_function(s);
        nxt[getId(s[0])][0] = 1;
        for (char c = 0; c < 26; ++c) {
            for (int i = 1; i <= (int)s.size(); ++i) {
                nxt[c][i] = (getId(s[i-1]) == c ? i+1 : nxt[c][p[i-1]]);
            }
        }
    };

    /*
        Returns a vector with the initial positions of
        all occurrences of s in t
        Run in O(|t|)
    */
    vector<int> matching_aut(const string& s, const string& t) {
        auto aut = autKMP(s);
        vector<int> match;
        int at = 0;
        for (int i = 0; i < (int)t.size(); ++i) {
            at = aut.nxt[getId(t[i])][at];
            if (at == (int)s.size()) match.push_back(i-at+1);
        }
        return match;
    }
}

```

6.2 Z Function

```

#include <bits/stdc++.h>
using namespace std;

/*
    z[i] is the length of the largest common prefix
    between s[0..n-1] and s[i..n-1]
*/
vector<int> z_function(const string &s) {
    int n = (int)s.size();
    vector<int> z(n);
    for (int i = 1, l = 0, r = 0; i < n; ++i) {
        if (i <= r)

```

```

        z[i] = min(r - i + 1, z[i - l]);
        while (i + z[i] < n and s[z[i]] == s[i + z[i]])
            ++z[i];
        if (i + z[i] - 1 > r)
            l = i, r = i + z[i] - 1;
    }
    return z;
}

```

6.3 String Hashing

```

#include <bits/stdc++.h>
using namespace std;

/*
    Small Primes:
    31, 53
    Large Primes:
    (1e6+3), (1e8+7), 100003621, (1e9+7), (1e9+9), (1LL<<61)-1
*/

struct StringHashing {
    const uint64_t MOD = (1LL<<61)-1;
    const int base = 31;
    uint64_t modMul(uint64_t a, uint64_t b) {
        uint64_t l1 = (uint32_t)a, h1 = a>>32, l2 = (uint32_t)b, h2 = b
            >>32;
        uint64_t l = l1*l2, m = l1*h2 + l2*h1, h = h1*h2;
        uint64_t ret = (l&MOD) + (l>>61) + (h << 3) + (m >> 29) + ((m <<
            35) >> 3) + 1;
        ret = (ret & MOD) + (ret>>61);
        ret = (ret & MOD) + (ret>>61);
        return ret-1;
    }
    inline int getInt(char c) {
        return (c-'a'+1);
    }

    /*
        hs[i] = s[0]*p^(i) + s[1]*p^(i-1) + ... + s[i-1]*p + s[i]
    */
    vector<uint64_t> hs, p;
    StringHashing(const string &s) {
        int n = s.size();
        hs.resize(n); p.resize(n);
        p[0] = 1;
        hs[0] = getInt(s[0]);
        for (int i = 1; i < n; ++i) {
            p[i] = modMul(p[i-1], base);
            hs[i] = (modMul(hs[i-1], base) + getInt(s[i]))%MOD;
        }
    }

    /*
        hs[i..j] = hs[j] - hs[i-1] * p^(j-i+1)
    */
    uint64_t getValue(int l, int r) {
        if (l > r) return -1;
        uint64_t res = hs[r];
        if (l > 0) res = (res + MOD - modMul(p[r-l+1], hs[l-1]))%MOD;
        return res;
    }
}

```

```

};

struct StringHashingDoubleMod {
    const uint64_t MOD1 = 1e6+3;
    const uint64_t MOD2 = 1e8+7;
    const int base = 31;
    uint64_t modMul(uint64_t a, uint64_t b, const uint64_t &MOD) {
        uint64_t l1 = (uint32_t)a, h1 = a>>32, l2 = (uint32_t)b, h2 = b
            >>32;
        uint64_t l = l1*l2, m = l1*h2 + l2*h1, h = h1*h2;
        uint64_t ret = (l&MOD) + (l>>61) + (h << 3) + (m >> 29) + ((m <<
            35) >> 3) + 1;
        ret = (ret & MOD) + (ret>>61);
        ret = (ret & MOD) + (ret>>61);
        return ret-1;
    }
    int getInt(char c) {
        return (c-'a'+1);
    }
    vector<uint64_t> h1, h2, p1, p2;
    StringHashingDoubleMod(const string &s) {
        int n = s.size();
        h1.resize(n); h2.resize(n); p1.resize(n); p2.resize(n);
        p1[0] = 1;
        p2[0] = 1;
        h1[0] = getInt(s[0]);
        h2[0] = getInt(s[0]);
        for (int i = 1; i < n; ++i) {
            p1[i] = modMul(p1[i-1], base, MOD1);
            p2[i] = modMul(p2[i-1], base, MOD2);
            h1[i] = (modMul(h1[i-1], base, MOD1) + getInt(s[i]))%MOD1;
            h2[i] = (modMul(h2[i-1], base, MOD2) + getInt(s[i]))%MOD2;
        }
    }
    pair<uint64_t, uint64_t> getValue(int l, int r) {
        if (l > r) return {-1, -1};
        pair<uint64_t, uint64_t> res;
        res.first = h1[r];
        if (l > 0) res.first = (res.first + MOD1 - modMul(p1[r-l+1], h1[l-1], MOD1))%MOD1;
        res.second = h2[r];
        if (l > 0) res.second = (res.second + MOD2 - modMul(p2[r-l+1], h2[l-1], MOD2))%MOD2;
        return res;
    }
};

```

6.4 Trie

```

#include <bits/stdc++.h>
using namespace std;
const int K = 26;
inline int getId(char c) {
    return c-'a';
}
namespace Trie {
    struct Vertex {
        int next[K];
        int leaf, count;
        Vertex () {

```

```

            fill(begin(next), end(next), -1);
            leaf = count = 0;
        }
    };
    vector<Vertex> trie;
    void init() {
        trie.clear();
        trie.emplace_back();
    }
    /*
    Insert a string in O(|s|)
    */
    void add(const string &s) {
        int v = 0;
        ++trie[v].count;
        for (char ch : s) {
            int c = getId(ch);
            if (trie[v].next[c] == -1) {
                trie[v].next[c] = trie.size();
                trie.emplace_back();
            }
            v = trie[v].next[c];
            ++trie[v].count;
        }
        ++trie[v].leaf;
    }
    /*
    Get amount of occurrences of s in O(|s|)
    */
    int countStr(const string &s) {
        int v = 0;
        for (char ch : s) {
            int c = getId(ch);
            if (trie[v].next[c] == -1) return 0;
            v = trie[v].next[c];
        }
        return trie[v].leaf;
    }
    /*
    Get amount of occurrences of prefix s in O(|s|)
    */
    int countPre(const string &s) {
        int v = 0;
        for (char ch : s) {
            int c = getId(ch);
            if (trie[v].next[c] == -1) return 0;
            v = trie[v].next[c];
        }
        return trie[v].count;
    }
    /*
    Remove a string s in O(|s|) and returns true if it's removed
    */
    bool remove(const string &s) {
        vector<int> rm;
        int v = 0;
        rm.push_back(v);
        for (char ch : s) {
            int c = getId(ch);
            if (trie[v].next[c] == -1) return false;
            v = trie[v].next[c];

```

```

    rm.push_back(v);
}
if (trie[v].leaf > 0) {
    --trie[v].leaf;
    for (int x : rm) --trie[x].count;
    return true;
}
return false;
}
};

```

6.5 Trie Int

```

#include <bits/stdc++.h>
using namespace std;
const int K = 2;
const int SZ = 32;
namespace Trie {
    struct Vertex {
        int next[K];
        int val, pre;
        Vertex () {
            fill(begin(next), end(next), -1);
            pre = val = 0;
        }
    };
    vector<Vertex> trie;
    void build() {
        trie.clear();
        trie.emplace_back();
    }
    void add(int val) {
        int v = 0;
        ++trie[v].pre;
        for (int i = SZ-1; i >= 0; --i) {
            bool b = val & (1 << i);
            if (trie[v].next[b] == -1) {
                trie[v].next[b] = trie.size();
                trie.emplace_back();
            }
            v = trie[v].next[b];
            ++trie[v].pre;
        }
        trie[v].val = val;
    }
    int min_xor(int val) {
        int v = 0;
        for (int i = SZ-1; i >= 0; --i) {
            bool b = val & (1 << i);
            if (trie[v].next[b] != -1) {
                v = trie[v].next[b];
            } else {
                v = trie[v].next[b^1];
            }
        }
        return val ^ trie[v].val;
    }
    int max_xor(int val) {
        int v = 0;
        for (int i = SZ-1; i >= 0; --i) {

```

```

        bool b = val & (1 << i);
        if (trie[v].next[b^1] != -1) {
            v = trie[v].next[b^1];
        } else {
            v = trie[v].next[b];
        }
    }
    return val ^ trie[v].val;
}
};

```

6.6 Aho Corasick

```

#include <bits/stdc++.h>
using namespace std;
#define fi first
#define se second

typedef pair<int, int> ii;

const int K = 26;
inline int getId(char c) {
    return c-'a';
}
namespace Aho {
    struct Vertex {
        int next[K], go[K];
        int suff_link = -1, end_link = -1;
        int leaf = -1, p = -1, sz, match = -1;
        char pch;
        Vertex(int p1 = -1, char ch = '$', int sz1 = 0) : p(p1), pch(ch),
            sz(sz1) {
            fill(begin(next), end(next), -1);
            fill(begin(go), end(go), -1);
        }
    };
    vector<Vertex> trie;
    inline void init() {
        trie.clear();
        trie.emplace_back();
    }
    int add_string(const string &s, int id = 1) {
        int v = 0;
        for (char ch : s) {
            int c = getId(ch);
            if (trie[v].next[c] == -1) {
                trie[v].next[c] = trie.size();
                trie.emplace_back(v, ch, trie[v].sz + 1);
            }
            v = trie[v].next[c];
        }
        trie[v].leaf = id;
        return v;
    }
    int go(int v, char ch);
    int get_suff_link(int v) {
        if (trie[v].suff_link == -1) {
            if (v == 0 or trie[v].p == 0) {
                trie[v].suff_link = 0;
            } else {

```

```

        trie[v].suff_link = go(get_suff_link(trie[v].p), trie[v].pch);
    }
}
return trie[v].suff_link;
}
int get_end_link(int v) {
    if (trie[v].end_link == -1) {
        if (v == 0 or trie[v].p == 0) {
            trie[v].end_link = 0;
        } else {
            int suff_link = get_suff_link(v);
            if (trie[suff_link].leaf != -1) {
                trie[v].end_link = suff_link;
            } else {
                trie[v].end_link = get_end_link(suff_link);
            }
        }
    }
    return trie[v].end_link;
}
int go(int v, char ch) {
    int c = getId(ch);
    if (trie[v].go[c] == -1) {
        if (trie[v].next[c] != -1) {
            trie[v].go[c] = trie[v].next[c];
        } else {
            trie[v].go[c] = (v == 0 ? 0 : go(get_suff_link(v), ch));
        }
    }
    return trie[v].go[c];
}
};

/*
    Get match positions in O(|t| * sqrt(|t|))
    Answer: {i, j} -> Range of match
*/
vector<ii> getMatch(const string &t) {
    auto addMatch = [] (vector<ii> &ans, int v, int i) {
        while (v != 0) {
            ans.emplace_back(i - Aho::trie[v].sz + 1, i);
            v = Aho::get_end_link(v);
        }
    };
    int v = 0;
    vector<ii> ans;
    for (int i = 0; i < (int)t.size(); ++i) {
        v = Aho::go(v, t[i]);
        if (Aho::trie[v].leaf != -1) {
            addMatch(ans, v, i);
        } else {
            addMatch(ans, Aho::get_end_link(v), i);
        }
    }
    sort(ans.begin(), ans.end());
    return ans;
}

int countMatch(int v) {
    if (Aho::trie[v].match == -1) {
        if (v == 0 or Aho::trie[v].p == 0) {

```

```

            Aho::trie[v].match = (Aho::trie[v].leaf != -1 ? 1 : 0);
        } else {
            Aho::trie[v].match = (Aho::trie[v].leaf != -1 ? 1 : 0) +
                countMatch(Aho::get_end_link(v));
        }
    }
    return Aho::trie[v].match;
}

/*
    Get match amount in O(|t|)
    Answer: Amount of matches
*/
int64_t matchAmount(const string &t) {
    int v = 0;
    int64_t ans = 0;
    for (char ch : t) {
        v = Aho::go(v, ch);
        ans += countMatch(v);
    }
    return ans;
}

```

6.7 Suffix Array

```

#include <numeric>
#include <vector>
#include <string>
typedef std::pair<int, int> ii;
class SuffixArray {
    std::vector<int> RA, SA, tempRA, tempSA, c;
    std::vector<int> LCP, Phi, PLCP;
    std::string S;
    int N;
    void countingSort(int k) {
        int sum = 0, maxi = std::max(256, N);
        c.assign(maxi, 0);
        for (int i = 0; i < N; ++i)
            c[RA[(i+k)%N]]++;
        for (int i = 1; i < maxi; ++i)
            c[i] += c[i-1];
        for (int i = N-1; i >= 0; --i)
            tempSA[--c[RA[(SA[i]+k)%N]]] = SA[i];
        SA = tempSA;
    }
    void constructSA() {
        iota(SA.begin(), SA.end(), 0);
        for (int i = 0; i < N; ++i) RA[i] = S[i];
        for (int k = 1; k < N; k <= 1) {
            countingSort(k);
            countingSort(0);
            int r = 0;
            tempRA[SA[0]] = 0;
            for (int i = 1; i < N; ++i) {
                tempRA[SA[i]] =
                    (ii(RA[SA[i]], RA[(SA[i]+k)%N]) == ii(RA[SA[i-1]], RA[(SA[i-1]+k)%N])) ? r : ++r;
            }
            RA = tempRA;
            if (RA[SA[N-1]] == N-1) break;

```

```

    }
}
void constructLCP() {
    Phi[SA[0]] = -1;
    for (int i = 1; i < N; ++i) {
        Phi[SA[i]] = SA[i-1];
    }
    for (int i = 0, k = 0; i < N; ++i) {
        if (Phi[i] == -1) { PLCP[i] = 0; continue; }
        while (S[i+k] == S[Phi[i]+k]) ++k;
        PLCP[i] = k;
        k = std::max(k-1, 0);
    }
    for (int i = 0; i < N; ++i)
        LCP[i] = PLCP[SA[i]];
}
ii stringMatching(const std::string &s) {
    int m = s.size();
    int lo = 0, hi = N-2, mid;
    while (lo < hi) { /*Find the lower bound*/
        mid = lo+(hi-lo)/2;
        if (S.substr(SA[mid], m) >= s) hi = mid;
        else lo = mid + 1;
    }
    if (S.substr(SA[lo], m) != s) return {-1, -1};
    ii ans = {lo, lo};
    lo = 0, hi = N-2;
    while (lo < hi) { /*Find the upper bound*/
        mid = lo+(hi-lo)/2;
        if (S.substr(SA[mid], m) > s) hi = mid;
        else lo = mid + 1;
    }
    if (S.substr(SA[lo], m) != s) --hi;
    ans.second = hi;
    return ans;
}
public:
    SuffixArray (const std::string &s) : S(s) {
        S += '$';
        N = S.size();
        RA.assign(N, 0);
        SA.assign(N, 0);
        tempSA.assign(N, 0);
        tempRA.assign(N, 0);
        LCP.assign(N, 0);
        PLCP.assign(N, 0);
        Phi.assign(N, 0);
        constructSA();
        constructLCP();
        SA.erase(SA.begin());
        LCP.erase(LCP.begin());
    }
    std::vector<int> getSA() {
        return SA;
    }
    std::vector<int> getLCP() {
        return LCP;
    }
    ii getStringMatching(const std::string &s) {
        return stringMatching(s);
    }
}

```

```

/*
    Number of different substrings:
    (n^2+n)/2 - sum_{i=0 to n-2} lcp[i]
*/
};

```

6.8 Manacher

```

#include <vector>
#include <string>
struct Palindrome {
    std::vector<int> d1, d2;
    int N;
    void manacher(const std::string &s) {
        int l, r = -1;
        N = s.size();
        d1.resize(N), d2.resize(N);
        for (int i = 0; i < N; ++i) {
            int k = i > r ? 1 : std::min(d1[l+(r-i)], r-i+1);
            while (k <= i and i + k < N and s[i-k] == s[i+k])
                ++k;
            d1[i] = k--;
            if (i+k>r) l = i-k, r=i+k;
        }
        l = 0, r = -1;
        for (int i = 0; i < N; ++i) {
            int k = i > r ? 0 : std::min(d2[l+(r-i)+1], r-i+1);
            while (k+1 <= i and i + k < N and s[i-k-1] == s[i+k])
                ++k;
            d2[i] = k--;
            if (i+k>r) l = i-k-1, r=i+k;
        }
    }
    Palindrome (const std::string &s) {
        manacher(s);
    }
    bool isPalindrome(int i, int j) {
        int sz = j-i+1;
        return (sz & 1 ? d1[i+sz/2] >= sz : d2[i+sz/2+1] >= sz);
    }
};

```

6.9 Lyndon Factorization

```

#include <string>
#include <vector>
std::vector<std::string> duval(const std::string &s) {
    int n = s.size();
    std::vector<std::string> fac;
    for (int i = 0; i < n; i++) {
        int j = i + 1, k = i;
        while (j < n and s[k] <= s[j]) {
            if (s[k] < s[j])
                k = i;
            else
                ++k;
            ++j;
        }
    }
}

```



```

        while (i <= k) {
            fac.push_back(s.substr(i, j-k));
            i += j-k;
        }
    }
    return fac;
}

std::string min_cyclic_string(std::string s) {
    s += s;
    int n = s.size();
    int ans = 0;
    for (int i = 0; i < n/2; i) {
        ans = i;
        int j = i+1, k = i;
        while (s[k] <= s[j]) {
            if (s[k] < s[j])
                k = i;
            else
                ++k;
            ++j;
        }
        while (i <= k)
            i += j-k;
    }
    return s.substr(ans, n/2);
}

```

7 Miscellaneous

7.1 Ternary Search

```

#include <bits/stdc++.h>
using namespace std;

#define ftype long double
#define f(x) x

const int inf = 0x3f3f3f3f;

void ternary_search_of_min(ftype top) {
    ftype lo = 0.0, hi = top, m1, m2, ans;
    for (int i = 0; i < 100; ++i) {
        m1 = (lo * 2 + hi) / 3.0;
        m2 = (lo + 2 * hi) / 3.0;
        if (f(m1) > f(m2)) {
            lo = m1;
            ans = m2;
        } else {
            hi = m2;
            ans = m1;
        }
    }
    cout << f(ans) << " = " << ans << '\n';
}

void ternary_search_of_max(ftype top) {
    ftype lo = 0.0, hi = top, m1, m2, ans;
    for (int i = 0; i < 100; ++i) {

```

```

        m1 = (lo * 2 + hi) / 3.0;
        m2 = (lo + 2 * hi) / 3.0;
        if (f(m1) < f(m2)) {
            lo = m1;
            ans = m2;
        } else {
            hi = m2;
            ans = m1;
        }
    }
    cout << f(ans) << " = " << ans << '\n';
}

```

```

void ternary_search_of_min_on_integers(int top) {
    int lo = 0, hi = top, ans = inf, m1, m2;
    while (hi - lo > 4) {
        int m1 = (lo + hi) / 2;
        int m2 = m1 + 1;
        if (f(m1) > f(m2)) {
            lo = m1;
        } else {
            hi = m2;
        }
    }
    for (int i = lo; i <= hi; ++i) {
        ans = min(ans, f(i));
    }
}

```

```

void ternary_search_of_max_on_integers(int top) {
    int lo = 0, hi = top, ans = -inf, m1, m2;
    while (hi - lo > 4) {
        int m1 = (lo + hi) / 2;
        int m2 = m1 + 1;
        if (f(m1) < f(m2)) {
            lo = m1;
        } else {
            hi = m2;
        }
    }
    for (int i = lo; i <= hi; ++i) {
        ans = max(ans, f(i));
    }
}

```

7.2 Longest Increasing Subsequence

```

#include <vector>
int lis(std::vector<int> &aux) {
    std::vector<int> d;
    for (int &x : aux) {
        auto it = std::lower_bound(d.begin(), d.end(), x);
        if (it == d.end()) d.push_back(x);
        else *it = x;
    }
    return (int)d.size();
}

```

7.3 Mo Algorithm

```
#include <bits/stdc++.h>
using namespace std;

typedef vector<int> vi;

const int BLOCK_SIZE = 800;
const int maxn = 5e5+5;

int v[maxn], f[maxn];
int ans;

void remove(int idx) {
    --f[v[idx]];
    if (f[v[idx]] == 0) --ans;
}

void add(int idx) {
    ++f[v[idx]];
    if (f[v[idx]] == 1) ++ans;
}

int get_answer() {
    return ans;
}

struct Query {
    int l, r, idx;
    bool operator < (const Query oth) const {
        if (l / BLOCK_SIZE != oth.l / BLOCK_SIZE) return l < oth.l;
        return (l / BLOCK_SIZE & 1) ? (r < oth.r) : (r > oth.r);
    }
};

vi mo_s_algorithm(vector<Query> queries) {
    vi answers(queries.size());
    sort(queries.begin(), queries.end());
    int l = 0, r = 0;
    for (Query q : queries) {
        while (q.l < l) add(--l);
```

```
        while (r < q.r) add(++r);
        while (l < q.l) remove(l++);
        while (q.r < r) remove(r--);
        answers[q.idx] = get_answer();
    }
    return answers;
}
```

7.4 Inversions Count

```
#include <vector>
int mergeSort(std::vector<int> &a) {
    int n = a.size();
    if (n <= 1) return 0;
    int mid = n/2;
    std::vector<int> b, c;
    for (int i = 0; i < mid; ++i)
        b.push_back(a[i]);
    for (int i = mid; i < n; ++i)
        c.push_back(a[i]);
    int inv = 0;
    inv += mergeSort(b);
    inv += mergeSort(c);
    int i = 0, j = 0;
    for (int k = 0; k < n; ++k) {
        if (i == mid) {
            a[k] = c[j++];
        } else if (j == n-mid) {
            a[k] = b[i++];
        } else if (b[i] <= c[j]) {
            a[k] = b[i++];
        } else {
            a[k] = c[j++];
            inv += mid-i;
        }
    }
    return inv;
}
```