

A quick intro to deep learning and PyTorch

A multiclass classification problem

Three species of Iris:

iris setosa



iris versicolor



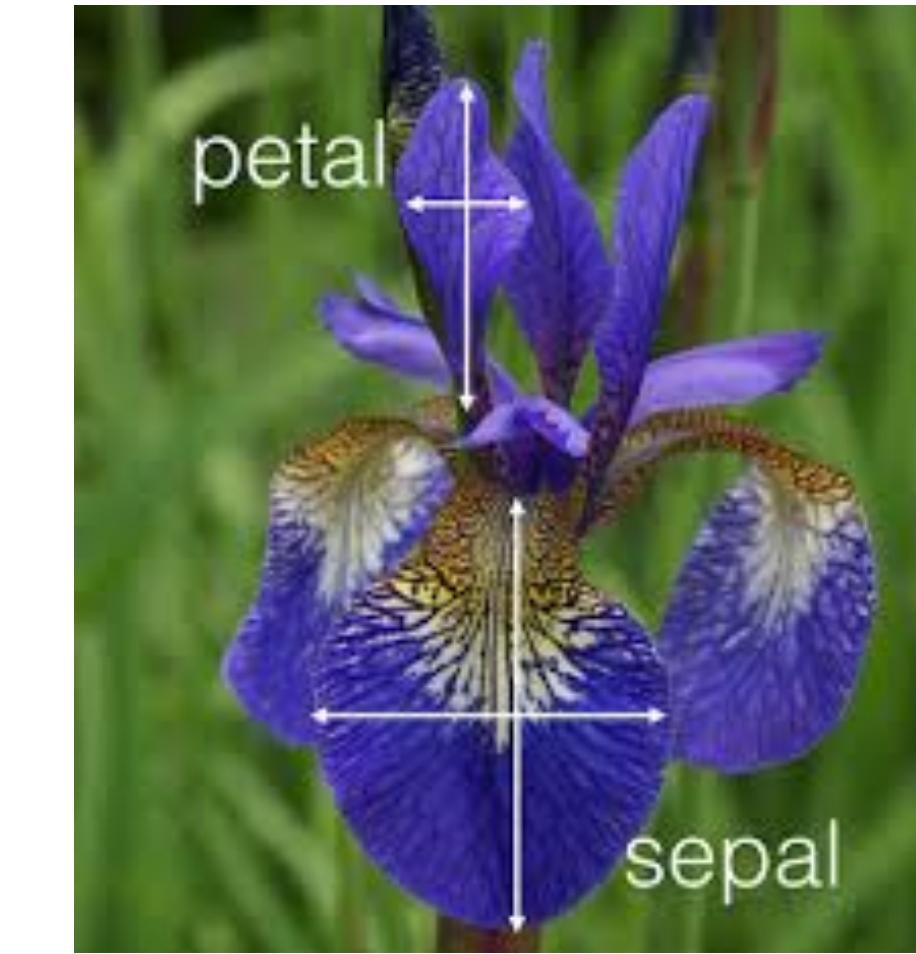
iris virginica



A multiclass classification problem

Our **goal** is to predict the type of Iris based on four measurements:

- petal length
- petal width
- sepal length
- sepal width



These four numbers are called “features”, and combined they form a “feature vector” such as

$$\begin{bmatrix} 5.1 \\ 3.5 \\ 1.4 \\ 0.2 \end{bmatrix}$$

Each Iris is described by its own feature vector

Note: A “vector” is just a finite, ordered list of numbers

Definition of a probability vector

A vector such as

$$p = \begin{bmatrix} .3 \\ .1 \\ .6 \end{bmatrix}$$

whose components are nonnegative and sum to 1 is called a “probability vector”

Application:

Suppose we’re solving a classification problem with 3 possible classes

The probability vector p tells us how likely it is that the example we’re looking at belongs to each class

So the vector p above tells us:

- The probability of belonging to class 1 is 30%
- The probability of belonging to class 2 is 10%
- The probability of belonging to class 3 is 60%

Probability vectors that express certainty

The special probability vectors $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$, and $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ reflect certainty about which class an example belongs to

So, the vector $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ expresses certainty that the example we're looking at belongs to class 1

Likewise, the vector $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ expresses certainty that the example belongs to class 2

And the vector $\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ expresses certainty that the example belongs to class 3

The softmax function

The function $S : \mathbb{R}^K \rightarrow \mathbb{R}^K$ defined by

$$S(u) = \begin{bmatrix} \frac{e^{u_1}}{e^{u_1} + \dots + e^{u_K}} \\ \frac{e^{u_2}}{e^{u_1} + \dots + e^{u_K}} \\ \vdots \\ \frac{e^{u_K}}{e^{u_1} + \dots + e^{u_K}} \end{bmatrix}$$


is called the “softmax” function

The output of S is guaranteed to be a probability vector!

The softmax function is useful in machine learning because it converts a vector into a probability vector

A recipe for a multiclass classification algorithm

Ingredient 1: A training dataset

Our training dataset consists of a collection of feature vectors

$$x_1, x_2, \dots, x_N \in \mathbb{R}^d$$

$$\begin{array}{c} \uparrow \quad \uparrow \quad \uparrow \\ \begin{bmatrix} 5.1 \\ 3.5 \\ 1.4 \\ 0.2 \end{bmatrix} \quad \begin{bmatrix} 7 \\ 3.2 \\ 4.7 \\ 1.4 \end{bmatrix} \quad \begin{bmatrix} 5.9 \\ 3 \\ 5.1 \\ 1.8 \end{bmatrix} \end{array}$$

and corresponding target values

$$y_1, y_2, \dots, y_N \in \mathbb{R}^K$$

$$\begin{array}{c} \uparrow \quad \uparrow \quad \uparrow \\ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \quad \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \end{array}$$

Here y_i is a probability vector that expresses certainty about which class example i belongs to

For example, if $K = 3$ and example i belongs to class 1, then $y_i = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

The position of the 1 tells you which class the example belongs to

A recipe for a multiclass classification algorithm

Ingredient 2: A prediction function $f : \mathbb{R}^d \rightarrow \mathbb{R}^K$

The output of f should be a probability vector, and we hope that

$$f(x_i) \approx y_i \quad \text{for } i = 1, \dots, N$$

This looks complicated, but
you could try to invent a
more concise notation

Big question: What form should we assume for f ?

For example, we might assume that f has the form

$$f(x_i) = S \left(\begin{bmatrix} \beta_{1,0} + \beta_{1,1}x_{i,1} + \cdots + \beta_{1,d}x_{i,d} \\ \beta_{2,0} + \beta_{2,1}x_{i,1} + \cdots + \beta_{2,d}x_{i,d} \\ \vdots \\ \beta_{K,0} + \beta_{K,1}x_{i,1} + \cdots + \beta_{K,d}x_{i,d} \end{bmatrix} \right)$$



$$\begin{bmatrix} x_{i,1} \\ x_{i,2} \\ \vdots \\ x_{i,d} \end{bmatrix}$$

In words, this function f computes a bunch of weighted combinations of the components of x_i , then the softmax function S is applied to ensure that the output is a probability vector

Much of machine learning is just getting creative about what form we assume for f

A recipe for a multiclass classification algorithm

Ingredient 3: A loss function ℓ

We need a way to measure how well a predicted probability vector q agrees with a “ground truth” probability vector p

First idea: $\ell(p, q) = (p_1 - q_1)^2 + (p_2 - q_2)^2 + \cdots + (p_K - q_K)^2$

$$\begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_K \end{bmatrix} \quad \begin{bmatrix} q_1 \\ q_2 \\ \vdots \\ q_K \end{bmatrix}$$



This choice of ℓ is called the “squared error” loss function

If q agrees perfectly with p , then $\ell(p, q) = 0$

On the other hand, if q is not close to p , then $\ell(p, q)$ is large

A recipe for a multiclass classification algorithm

The most beautiful way to measure how well a predicted probability vector q agrees with a “ground truth” probability vector p is to use the “cross-entropy” loss function ℓ defined by

$$\ell(p, q) = -p_1 \log(q_1) - p_2 \log(q_2) - \cdots - p_K \log(q_K)$$

$$\begin{bmatrix} p_1 \\ p_2 \\ \vdots \\ p_K \end{bmatrix} \quad \begin{bmatrix} q_1 \\ q_2 \\ \vdots \\ q_K \end{bmatrix}$$

This strange-looking formula is hard to motivate, but it turns out that in some sense it's the most natural way to compare probability vectors

Exercise: Suppose that $p = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Which probability vector q minimizes $\ell(p, q)$?

A recipe for a multiclass classification algorithm

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Exercise: Suppose that $p = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$. Which probability vector q minimizes $\ell(p, q)$?

Conclusion: $\ell(p, q)$ is small when q agrees with p !

Discovering the cross-entropy loss function

The cross-entropy formula looks weird – how would you discover it?

One approach uses the “maximum likelihood estimation” technique from statistics

We make a modeling assumption that the probability vector

$$f(x_i) = S \begin{pmatrix} \beta_{1,0} + \beta_{1,1}x_{i,1} + \cdots + \beta_{1,d}x_{i,d} \\ \beta_{2,0} + \beta_{2,1}x_{i,1} + \cdots + \beta_{2,d}x_{i,d} \\ \vdots \\ \beta_{K,0} + \beta_{K,1}x_{i,1} + \cdots + \beta_{K,d}x_{i,d} \end{pmatrix}$$

tells us how likely it is that example i belongs to each of the K classes

Then we go through the steps of maximum likelihood estimation to estimate the beta coefficients

and when you work out the details, the cross-entropy formula emerges

Objective function

We hope that $\ell(y_i, f(x_i))$ is small for $i = 1, \dots, N$

In other words, we hope that the average cross-entropy

$$L(\beta) = \frac{1}{N} \sum_{i=1}^N \ell(y_i, f(x_i)) \quad \text{is small}$$



These parameters
are “knobs” that
you can tune

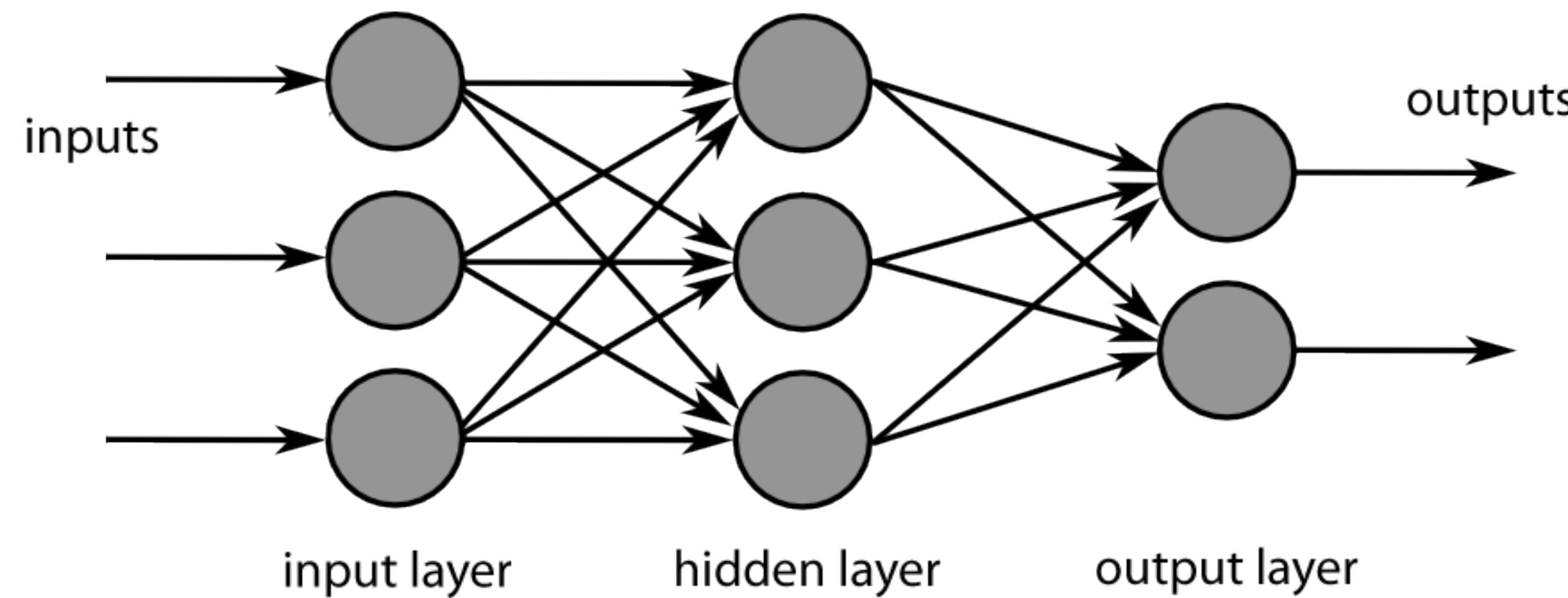
$$\begin{bmatrix} \beta_{10} \\ \vdots \\ \beta_{1d} \\ \vdots \\ \beta_{K0} \\ \vdots \\ \beta_{Kd} \end{bmatrix}$$



We could call this f_β

We select β by solving the optimization problem: minimize $L(\beta)$

Neural networks



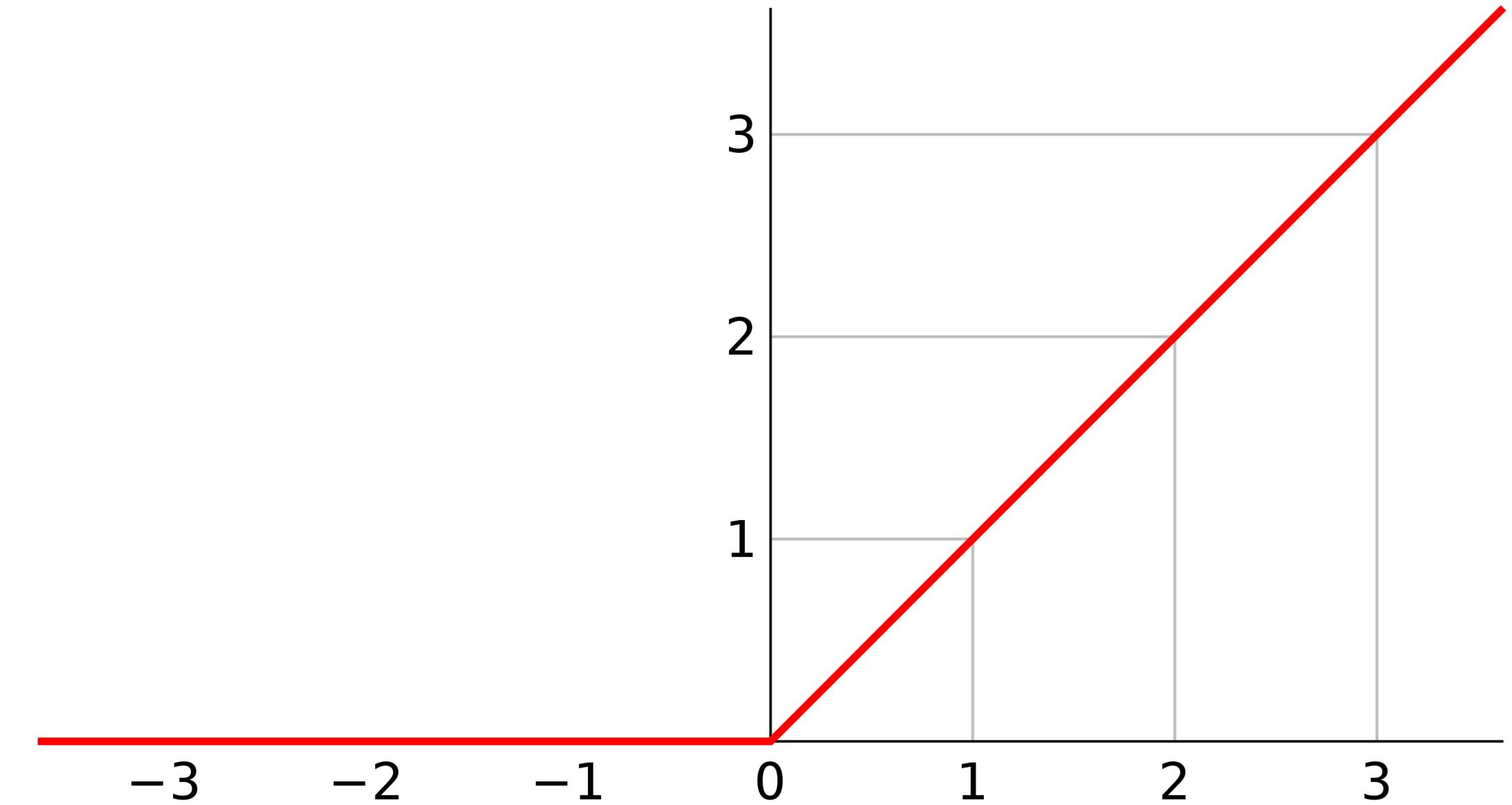
(Getting creative with the prediction function)

A simple nonlinear function

$$r(u) = \begin{cases} u & \text{if } u \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

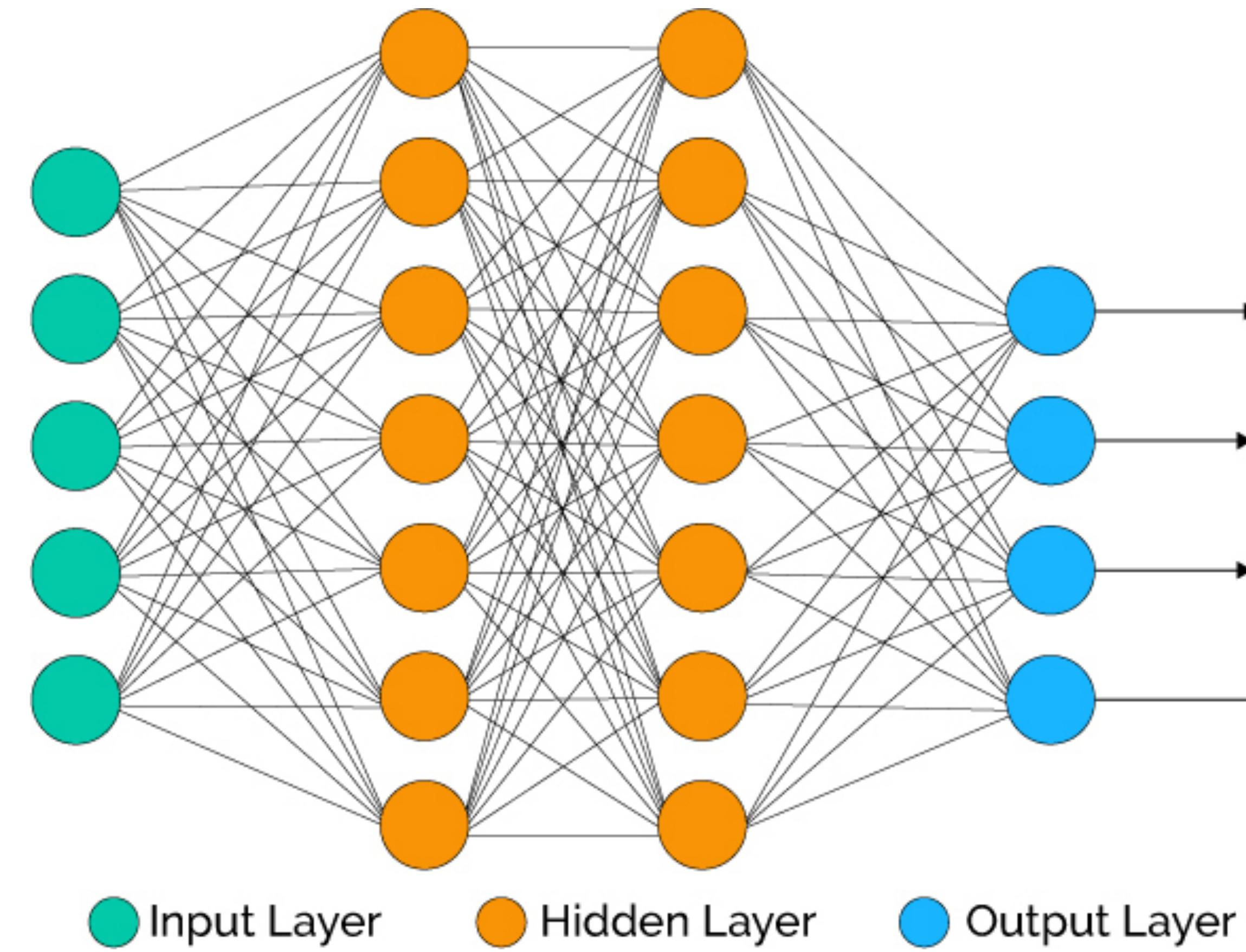
Also called ReLU





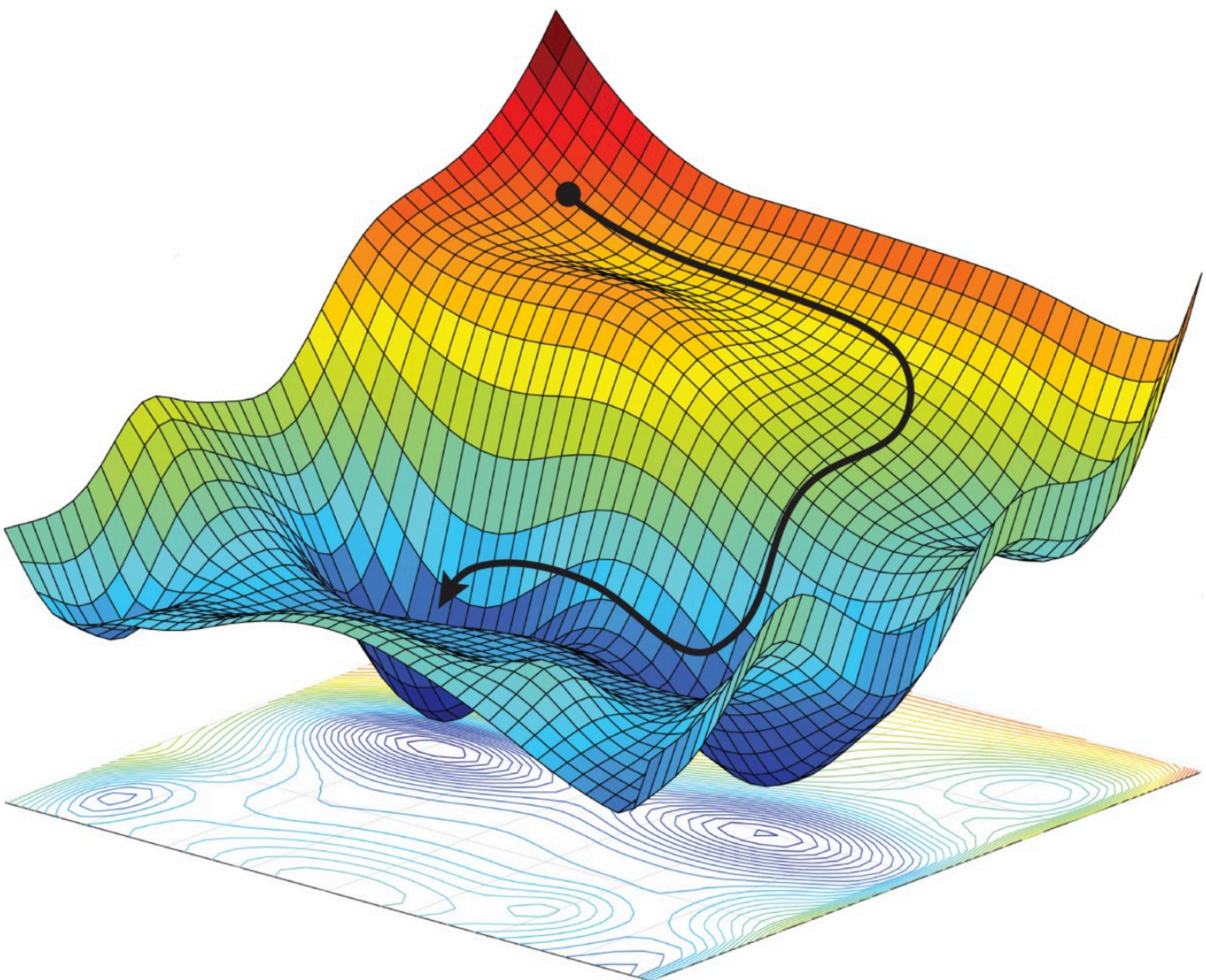
ReLU is a popular choice of “activation function” in neural networks

A diagram of a neural network



- Each node computes a weighted combination of its inputs
- For intermediate layers, if the result is negative, the output of the node is set to 0
 - The weights in each weighted combination are “knobs” that can be tuned

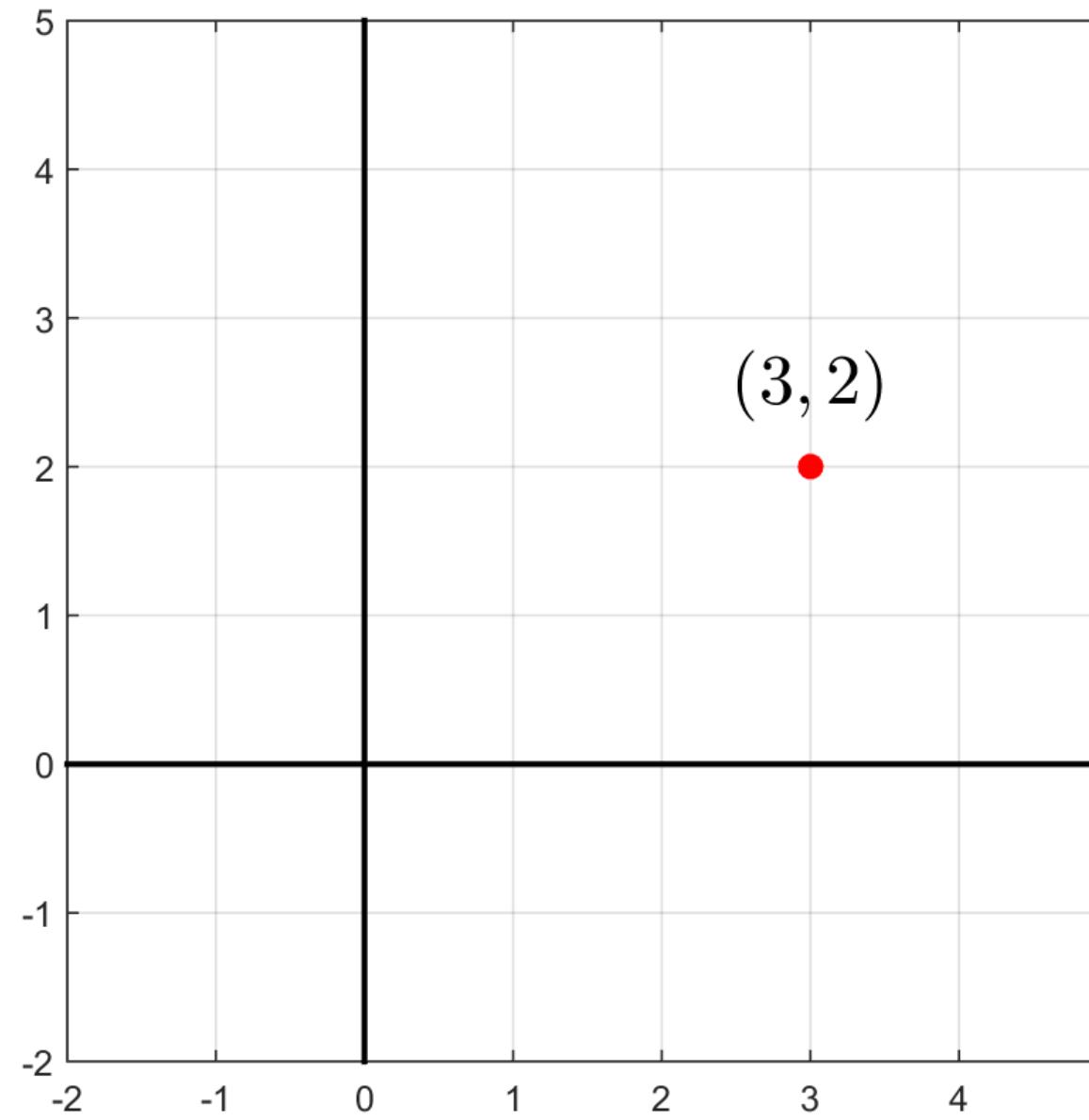
Optimization algorithms



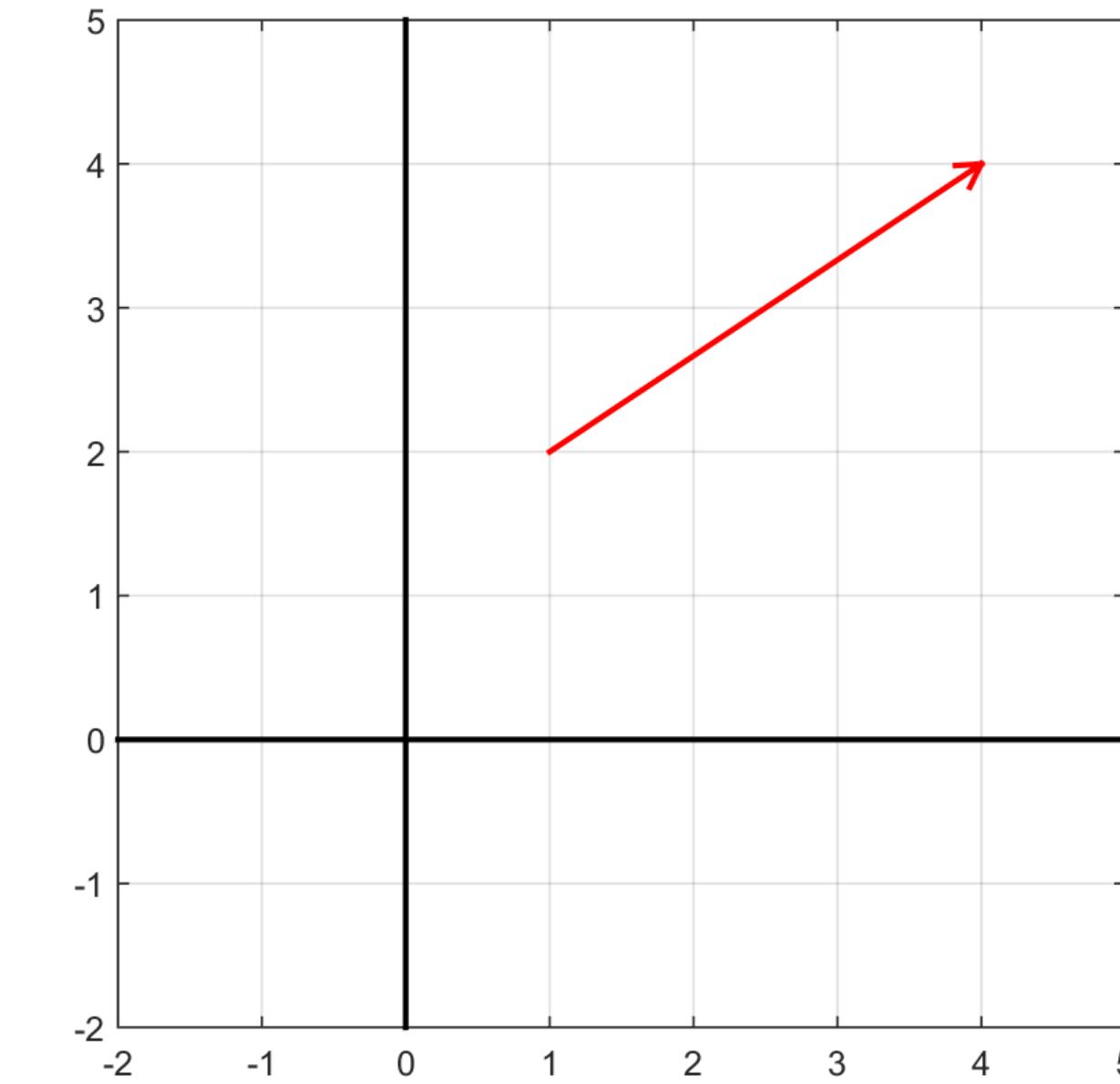
Visualizing an n-tuple

Ordered n-tuple: an ordered list of n numbers

Visualizing $\begin{bmatrix} 3 \\ 2 \end{bmatrix}$



Point picture

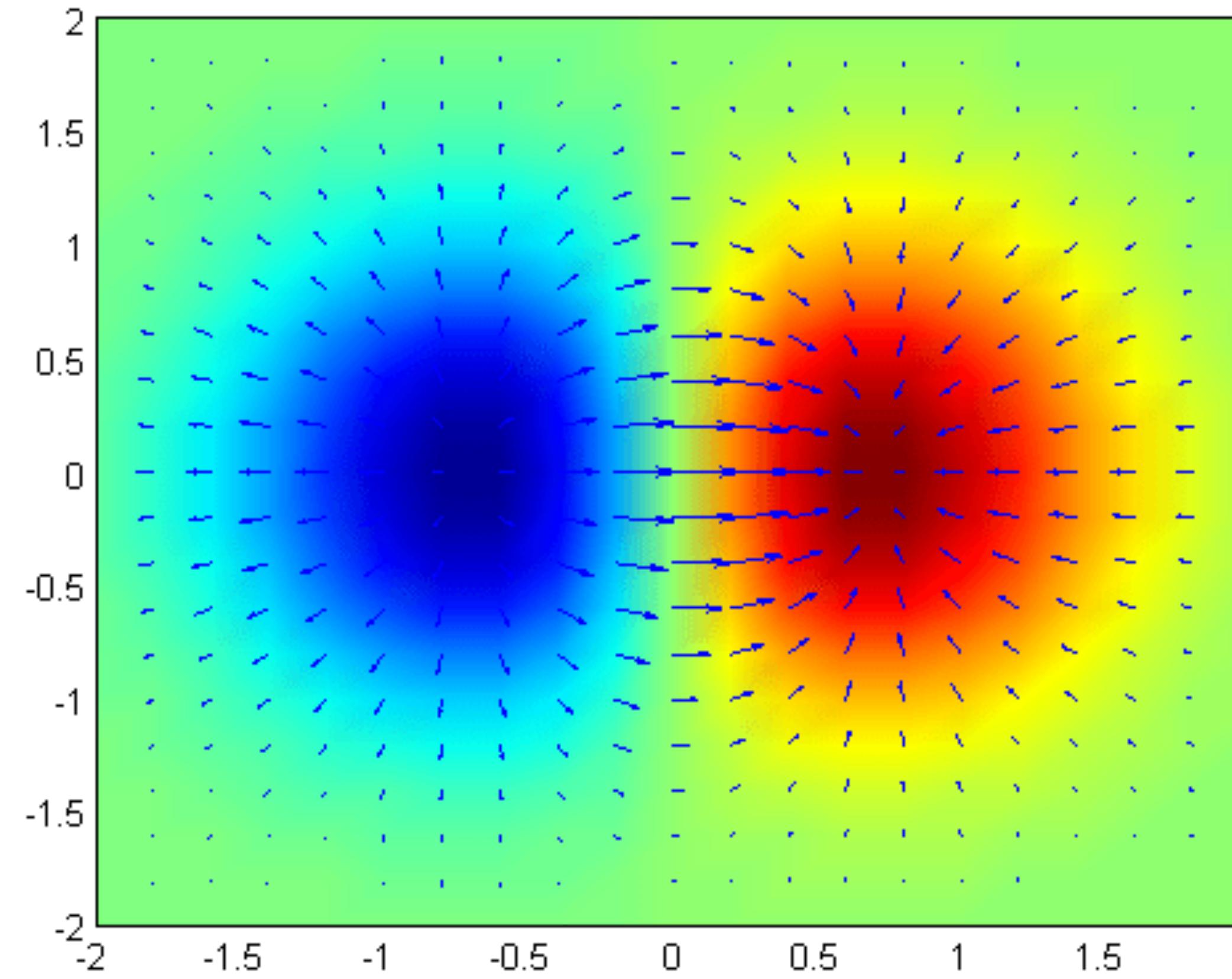


Vector picture

Gradient vector

$$L : \mathbb{R}^n \rightarrow \mathbb{R}$$

$L(\beta)$ is the temperature at the point β



$\nabla L(\beta)$ points in the direction of steepest ascent

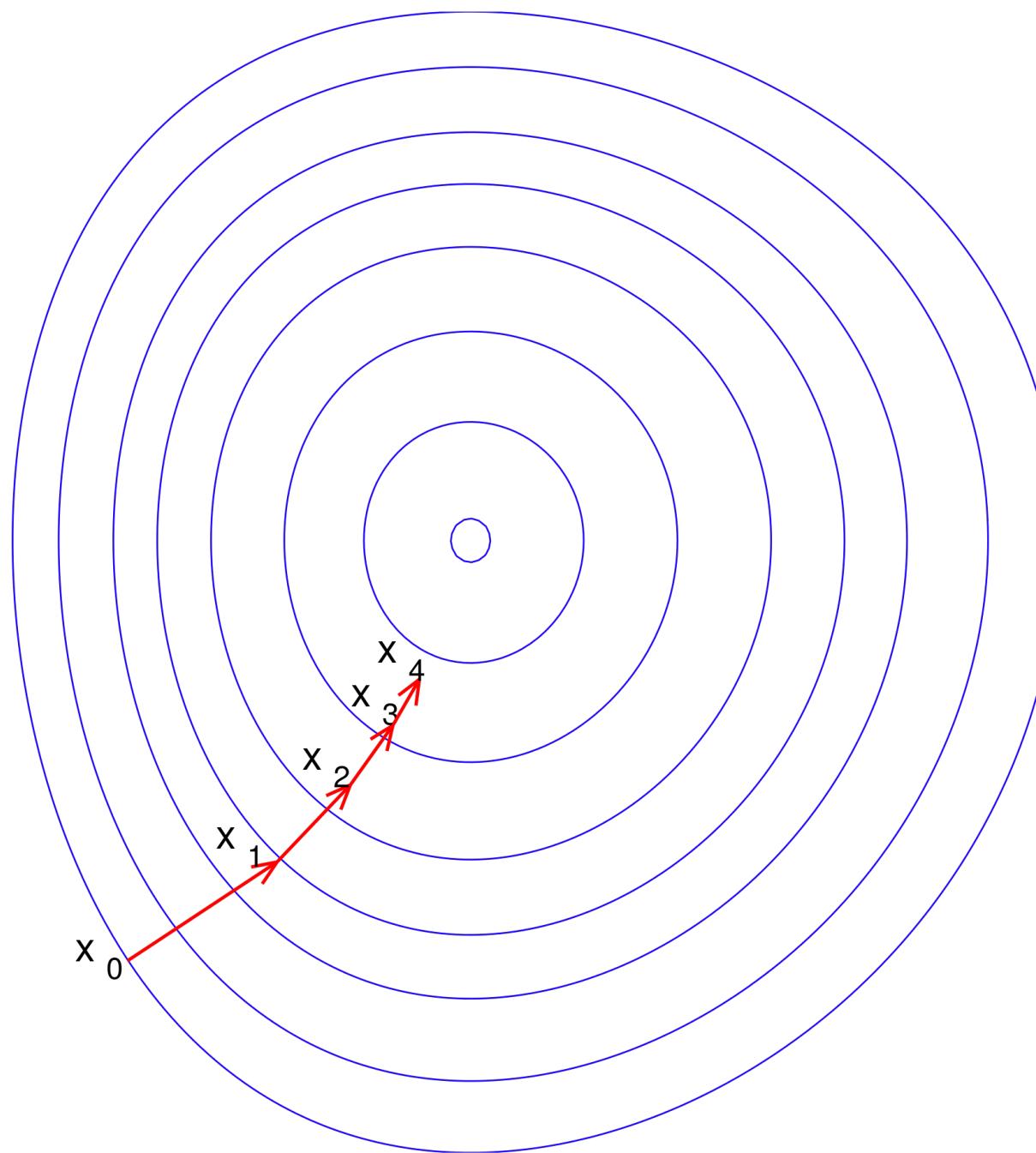
Optimization algorithm

Problem: minimize $L(\beta)$

Gradient descent: repeatedly move in direction of steepest descent

Initialize $\beta^0 \in \mathbb{R}^{d+1}$

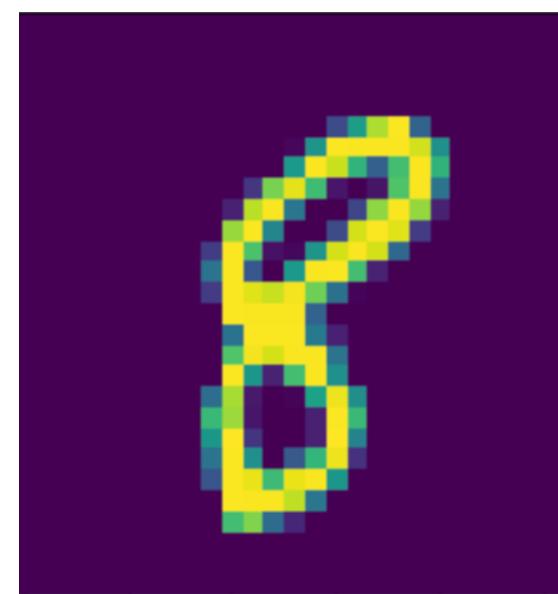
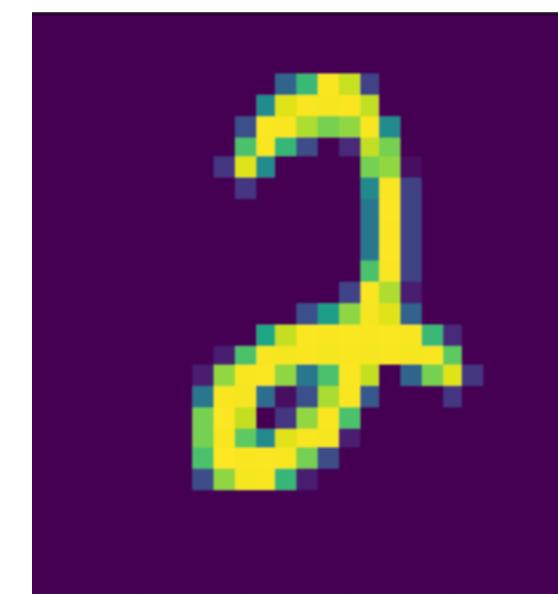
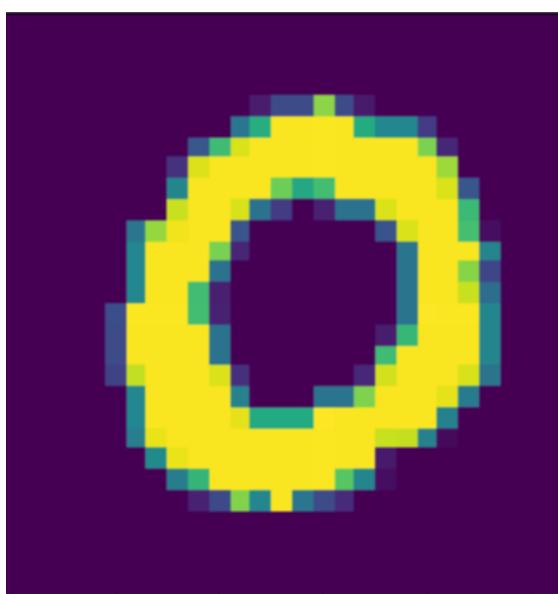
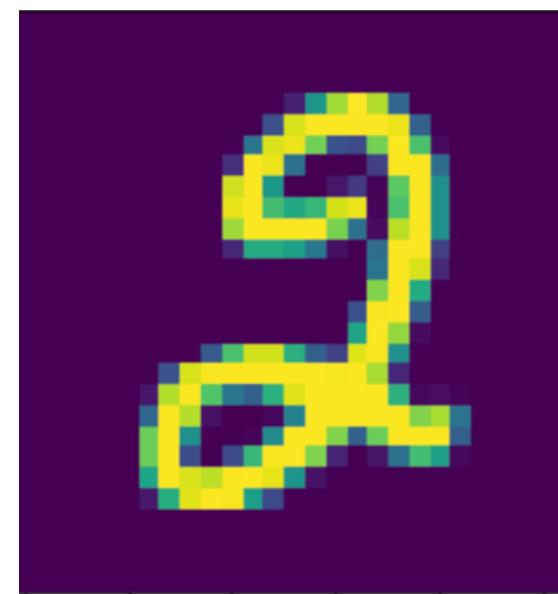
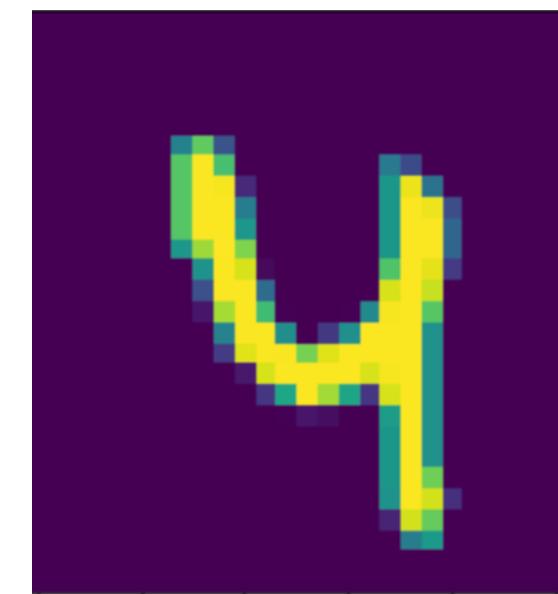
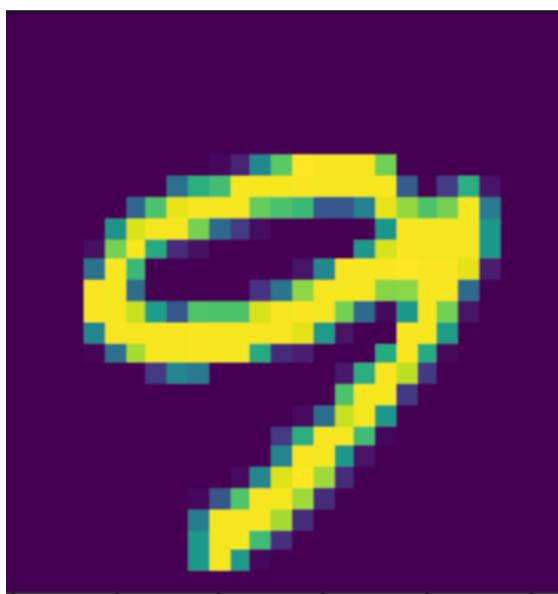
Then do $\beta^{t+1} = \beta^t - \alpha \nabla L(\beta^t)$ for $t = 0, 1, 2, \dots$



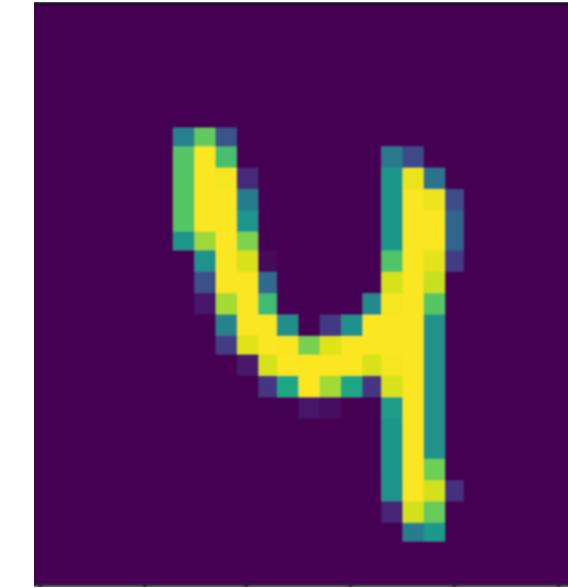
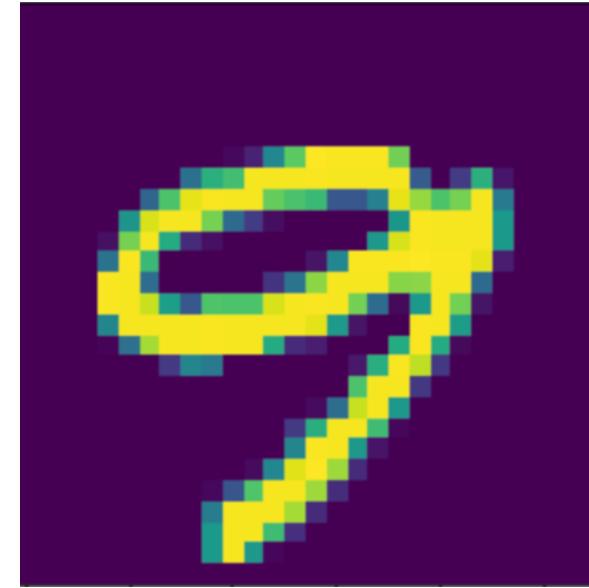
↑
“Learning rate”

PyTorch computes the gradient for us

Handwritten digit classification using PyTorch

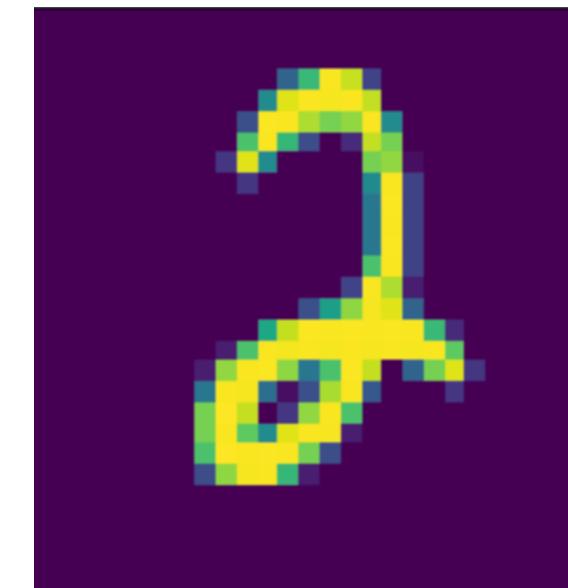
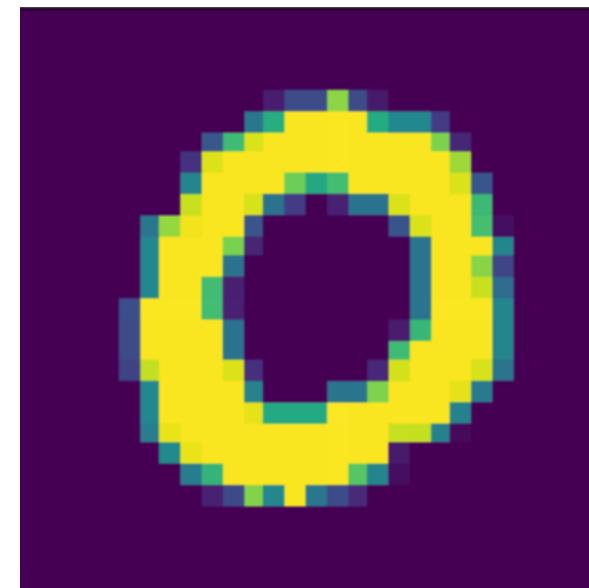


Using PyTorch for deep learning

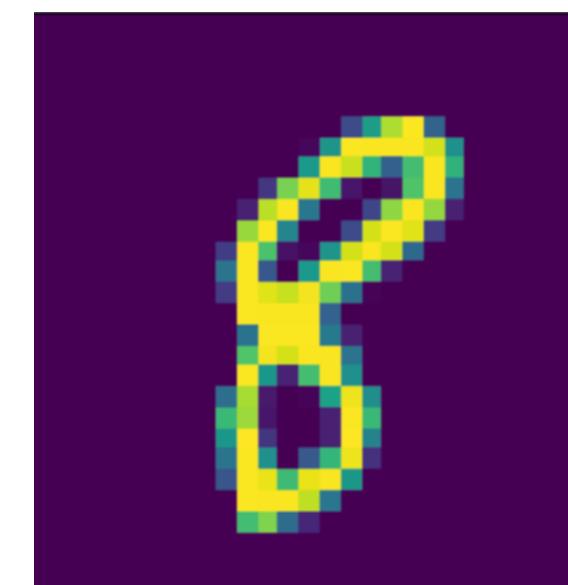
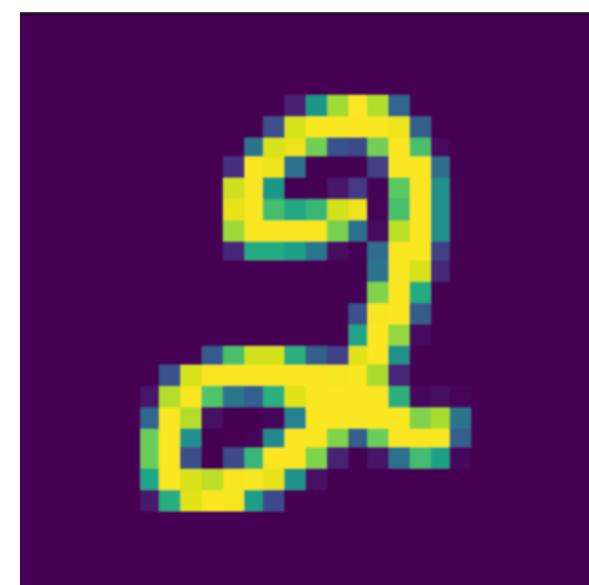


```
In [1]: import numpy as np  
import matplotlib.pyplot as plt  
import pandas as pd  
  
import torch
```

Load MNIST handwritten digit data in .csv format.



```
In [2]: # The MNIST dataset in .csv format can be found on Kaggle here:  
# https://www.kaggle.com/oddrationale/mnist-in-csv  
  
data_dir = '/Users/dvo/MNIST/'  
df_train = pd.read_csv(data_dir + 'mnist_train.csv')  
df_val = pd.read_csv(data_dir + 'mnist_test.csv')
```



Each 28 x 28 MNIST image
is stored as a row in a data frame

Using PyTorch for deep learning

Define a dataset class:

We must implement these three methods

```
In [3]: class DigitsDataset(torch.utils.data.Dataset):  
    →     def __init__(self, df):  
        self.df = df  
  
    →     def __len__(self):  
        return len(self.df)  
  
    →     def __getitem__(self, idx):  
        row = self.df.iloc[idx]  
  
        x = np.float32(row[1:].values)/255  
        y = row[0]  
  
        return x, y
```

Using PyTorch for deep learning

Create training and validation datasets and dataloaders.

This object can get
a batch of data
from the dataset

In [4]:

```
dataset_train = DigitsDataset(df_train)
dataset_val = DigitsDataset(df_val)

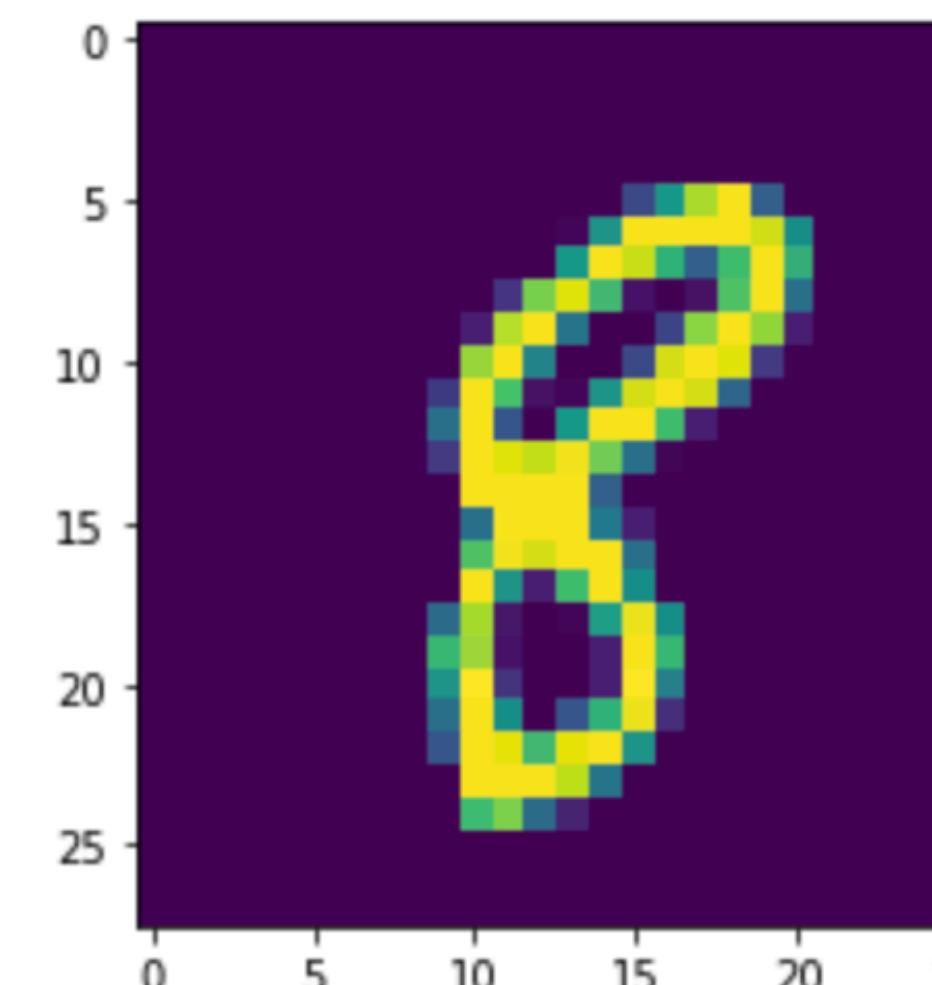
dataloader_train = torch.utils.data.DataLoader(dataset_train, batch_size=64,shuffle=True)
dataloader_val = torch.utils.data.DataLoader(dataset_val, batch_size=64,shuffle=True)
```

Look at a training example and its label. ↴

In [25]:

```
x_batch, Y_batch = next(iter(dataloader_train))
plt.imshow(np.reshape(X_batch[0],(28,28)))
print(Y_batch[0])
```

tensor(8)



This command gets
one batch of data

Using PyTorch for deep learning

Define a model class that specifies our neural network architecture.

```
In [6]: class SimpleNeuralNetwork(torch.nn.Module):  
  
    def __init__(self):  
  
        super().__init__()  
        self.dense1 = torch.nn.Linear(784, 100)  
        self.dense2 = torch.nn.Linear(100,10)  
  
        self.ReLU = torch.nn.ReLU()  
        # self.Softmax = torch.nn.Softmax(dim = 1)  
  
    def forward(self, x):  
  
        x = self.dense1(x)  
        x = self.ReLU(x)  
        x = self.dense2(x)  
        # x = self.Softmax(x) # SoftMax is combined with the loss function, so not needed here.  
  
        return x
```

This method
applies the
neural network
to a vector x

←
Specify the
layers in our
neural network

Using PyTorch for deep learning

Create a model (our neural network).

```
In [7]: model = SimpleNeuralNetwork() ← This is our neural network.  
device = torch.device('cpu') # Change this line if a GPU is available  
model = model.to(device) # This line would put the model on the GPU, if device is a GPU.
```

Choose the loss function and the optimization algorithm.

```
In [8]: loss_fun = torch.nn.CrossEntropyLoss()  
optimizer = torch.optim.Adam(model.parameters(), lr = 0.001)
```

Adam is a variant
of stochastic
gradient descent

Training the neural network

In [10]:

```
num_epochs = 10 ← We'll do 10 epochs of SGD
N_train = len(dataset_train)
N_val = len(dataset_val)

train_losses = [] # collect the training losses
val_losses = []

for ep in range(num_epochs):

    model.train() # Put model in train mode. This turns on any model behavior that should only occur during training.
    train_loss = 0.0
    batch_idx = 0

    for X_batch, Y_batch in dataloader_train: ← Sweep through training data,
                                                one batch at a time

        X_batch = X_batch.to(device) # If device is a GPU, this puts the current batch of data on the GPU.
        Y_batch = Y_batch.to(device)

        N_batch = X_batch.shape[0]
        outputs = model(X_batch)
        loss_oneBatch = loss_fun(outputs,Y_batch)

        model.zero_grad()
        loss_oneBatch.backward()
        optimizer.step() ← PyTorch computes the
                           gradient for us

        train_loss += loss_oneBatch*N_batch

    model.eval() # Put model in eval mode. This turns off any model behavior that should only occur during training.
    val_loss = 0.0
    for X_batch, Y_batch in dataloader_val:

        X_batch = X_batch.to(device)
        Y_batch = Y_batch.to(device)

        with torch.no_grad(): # Tell PyTorch it doesn't need to keep track of gradient info.

            N_batch = X_batch.shape[0]
            outputs = model(X_batch)
            loss_oneBatch = loss_fun(outputs,Y_batch)
            val_loss += loss_oneBatch*N_batch

    train_losses.append(train_loss/N_train)
    val_losses.append(val_loss/N_val)

print('epoch: ', ep, 'train loss: ', train_loss/N_train, 'validation loss: ', val_loss/N_val)
```

This line does one iteration of stochastic gradient descent →

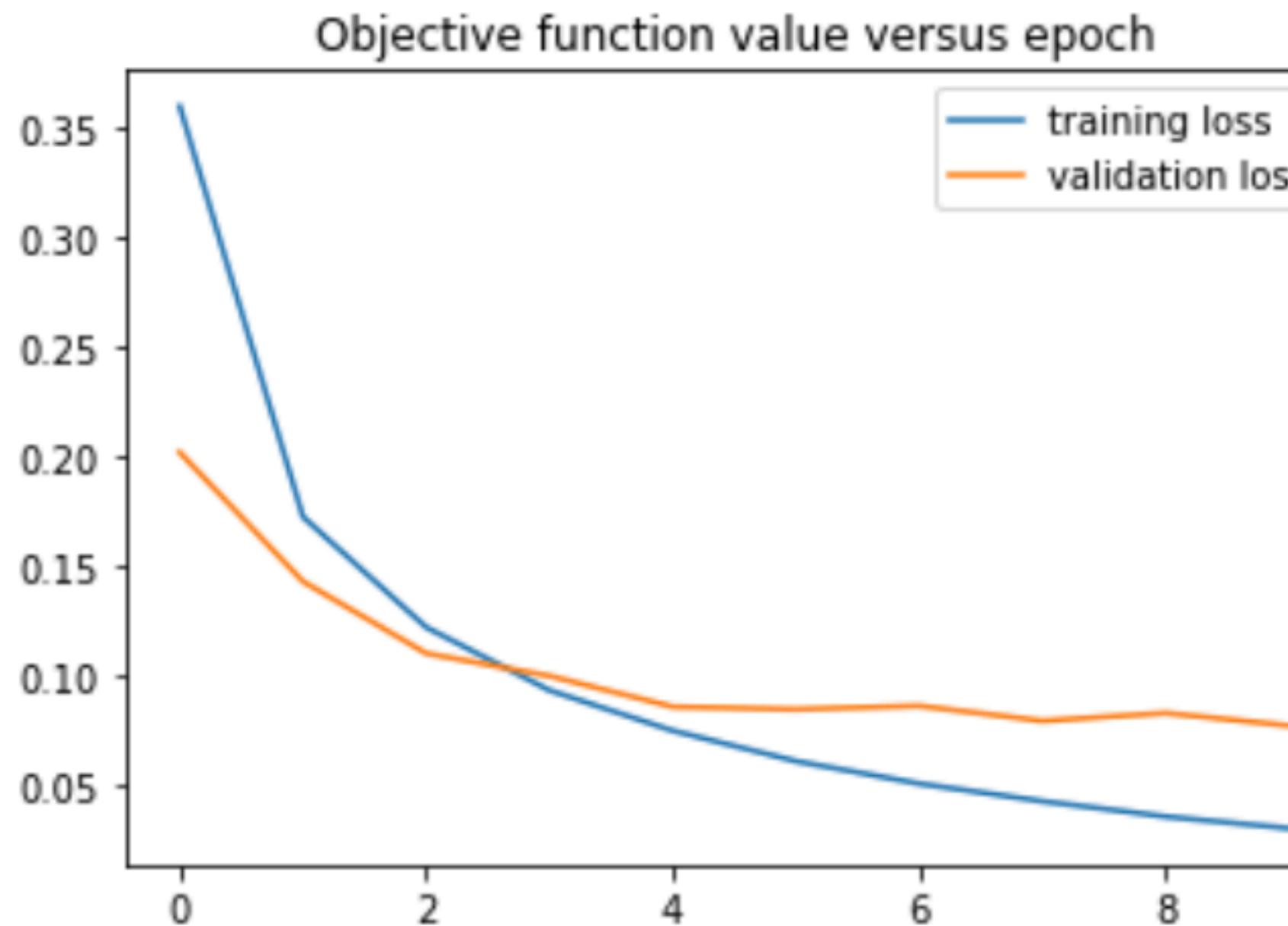
Report performance on both training and validation datasets →

Using PyTorch for deep learning

Plot the objective function value vs. epoch for both the training and validation datasets.

```
In [12]: plt.plot(train_losses, label = 'training loss')
plt.plot(val_losses, label = 'validation loss')
plt.legend(loc = 'upper right')
plt.title('Objective function value versus epoch')
```

```
Out[12]: Text(0.5, 1.0, 'Objective function value versus epoch')
```



If the validation loss
starts increasing,
we are overfitting the
training data

Using PyTorch for deep learning

Compute our prediction accuracy on the validation dataset.

In [19]:

```
num_correct = 0
model.eval()

for X_batch, Y_batch in dataloader_val:

    X_batch = X_batch.to(device)
    Y_batch = Y_batch.to(device)

    with torch.no_grad(): # Tell PyTorch it doesn't need to keep track of gradient info.

        outputs = model(X_batch)
        num_correct += sum(np.argmax(outputs, axis = 1) == Y_batch)

print('Accuracy: ', num_correct/N_val)
```

Accuracy: tensor(0.9762)

Count how many predicted labels agree with the ground truth labels

