CALCULUS OF VARIATIONS

(%o2)

Based on Maths For All Playlist Calculus of Variations Written by Daniel Volinski at danielvolinski@yahoo.es

(%i2) info:build_info()\$info@version;

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5.38.1

(%i2) reset()$kill(all)$

(%i1) derivabbrev:true$

(%i2) ratprint:false$

(%i3) fpprintprec:5$

(%i4) load(linearalgebra)$

(%i5) if get('draw,'version)=false then load(draw)$

(%i6) wxplot_size:[1024,768]$

(%i8) load(odes)$ load(contrib_ode)$

(%i9) if get('optvar,'version)=false then load(optvar)$
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(%i10) if get('optmiz,'version)=false then load(optmiz)\$

1 Straight line

Lagrangian

(%i11) depends(y,x)\$

(%i12) L: $\sqrt{(1+'diff(y,x)^2)}$;

$$\sqrt{\left(y_x\right)^2 + 1} \tag{L}$$

Momentum Conjugate

(%i13) ldisplay(P_y:diff(L,'diff(y,x)))\$

$$P_y = \frac{y_x}{\sqrt{(y_x)^2 + 1}}$$
 (%t13)

Generalized Forces

(%i14) ldisplay(F_y:diff(L,y))\$

$$F_y = 0 (\%t14)$$

Euler-Lagrange Equation

(%i15) aa:el(L,y,x)\$

(%i18) bb:ev(aa,eval,diff)\$

(%i19) map(ldisp,bb:fullratsimp(bb))\$

$$\frac{1}{\sqrt{(y_x)^2 + 1}} = k_0 \tag{\%t19}$$

$$\frac{\sqrt{(y_x)^2 + 1} (y_{xx})}{(y_x)^4 + 2(y_x)^2 + 1} = 0$$
 (%t20)

$$\frac{y_x}{\sqrt{(y_x)^2 + 1}} = k_1 \tag{\%t21}$$

(%i23) bb[1]:reverse(subst([k[0]=E],bb[1]))\$
 bb[3]:reverse(subst([k[1]=P],bb[3]))\$

Conservation Laws

(%i24) map(ldisp,part(bb,[1,3]))\$

$$E = \frac{1}{\sqrt{(y_x)^2 + 1}} \tag{\%t24}$$

$$P = \frac{y_x}{\sqrt{(y_x)^2 + 1}} \tag{\%t25}$$

Equations of Motion

$$(\%i26)$$
 [sol]:solve(bb[2],'diff(y,x,2));

$$[y_{xx} = 0] \tag{\%o26}$$

(%i27) odesol:ode2(sol,y,x);

$$y = \%k2x + \%k1 \tag{odesol}$$

(%i28) method;

$$constcoeff$$
 (%o28)

(%i29) bc2(odesol,x=x_0,y=y_0,x=x_1,y=y_1);

$$y = \frac{x(y_0 - y_1)}{x_0 - x_1} - \frac{x_1 y_0 - x_0 y_1}{x_0 - x_1}$$
 (%o29)

2 Brachistochrone problem

Lagrangian

(%i30) depends(y,x)\$

(%i31) L: $\sqrt{(1+'diff(y,x)^2)}/\sqrt{(2*g*y)}$;

$$\frac{\sqrt{\left(y_x\right)^2 + 1}}{\sqrt{2}\sqrt{gy}}\tag{L}$$

Momentum Conjugate

(%i32) ldisplay(P_y:diff(L,'diff(y,x)))\$

$$P_y = \frac{y_x}{\sqrt{2}\sqrt{gy}\sqrt{(y_x)^2 + 1}} \tag{\%t32}$$

Generalized Forces

(%i33) ldisplay(F_y:diff(L,y))\$

$$F_y = -\frac{g\sqrt{(y_x)^2 + 1}}{2^{\frac{3}{2}}(gy)^{\frac{3}{2}}}$$
 (%t33)

Euler-Lagrange Equation

(%i34) aa:el(L,y,x)\$

(%i36) bb:ev(aa,eval,diff)\$

(%i37) map(ldisp,bb:fullratsimp(bb))\$

$$\frac{\sqrt{gy}}{\sqrt{2gy}\sqrt{(y_x)^2 + 1}} = k_0 \tag{\%t37}$$

$$\frac{2y(y_{xx}) - (y_x)^4 - (y_x)^2}{\sqrt{gy}\sqrt{(y_x)^2 + 1}\left(2^{\frac{3}{2}}y(y_x)^2 + 2^{\frac{3}{2}}y\right)} = -\frac{\sqrt{(y_x)^2 + 1}}{2^{\frac{3}{2}}y\sqrt{gy}}$$
(%t38)

Conservation Laws

(%i39) bb[1]:reverse(subst([k[0]=E],bb[1]));

$$E = \frac{\sqrt{gy}}{\sqrt{2gy}\sqrt{(y_x)^2 + 1}} \tag{\%o39}$$

Equations of Motion

(%i40) [sol]:solve(bb[2],'diff(y,x,2));

$$y_{xx} = -\frac{(y_x)^2 + 1}{2y}$$
 (%o40)

(%i41) odesol:ode2(sol,y,x)\$

(%i42) method;

$$free of x$$
 (%o42)

(%i43) map(ldisp,odesol)\$

$$\frac{e^{-2\%k1} \left(e^{\%k1} \sqrt{y} \operatorname{atan}\left(\frac{e^{-\frac{\%k1}{2}} \sqrt{1 - e^{\%k1}y}}{\sqrt{y}}\right) + e^{\frac{3\%k1}{2}} y \sqrt{1 - e^{\%k1}y}\right)}{\sqrt{y}} = x + \%k2$$
 (%t43)

$$-\frac{e^{-2\%k1}\left(e^{\%k1}\sqrt{y}\,\arctan\left(\frac{e^{-\frac{\%k1}{2}}\sqrt{1-e^{\%k1}y}}{\sqrt{y}}\right) + e^{\frac{3\%k1}{2}}y\sqrt{1-e^{\%k1}y}\right)}{\sqrt{y}} = x + \%k2 \tag{\%t44}$$

3 Optimal control

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(\%i45) aa:ham(['diff(v,t,1)=f,'diff(x,t,1)=v])$
(%i49) bb:ev(aa,eval)$
(%i50) bb:subst([aux[1]=aux_1,aux[2]=aux_2],bb);
                          [aux_2v + aux_1f, aux_{1t} = -aux_2, aux_{2t} = 0, aux_2 = c_2]
                                                                                                    (bb)
(%i51) map(ldisp,bb)$
                                             aux_2v + aux_1f
                                                                                                  (%t51)
                                                                                                  (%t52)
                                             aux_{1t} = -aux_2
                                               aux_{2t} = 0
                                                                                                  (\%t53)
                                               aux_2 = c_2
                                                                                                  (\%t54)
(\%i56) atvalue(aux_1(t),[t=0],a)$
        atvalue(aux_2(t),[t=0],b)$
(%i57) printprops(all,atvalue)$
                                        aux_1(0) = a, aux_2(0) = b
(%i58) convert(part(bb,[2,3]),[aux_1,aux_2],t);
                                   [aux_1(t)_t = -aux_2(t), aux_2(t)_t = 0]
                                                                                                  (\%058)
(%i59) convert([aux_1,aux_2],[aux_1,aux_2],t);
                                            [aux_1(t), aux_2(t)]
                                                                                                  (\%059)
(%i60) desol:desolve(%th(2),%th(1));
                                     [aux_1(t) = a - bt, aux_2(t) = b]
                                                                                                  (desol)
(\%i61) convert(bb[1],[aux_1,aux_2],t);
                                          aux_2(t)v + f aux_1(t)
                                                                                                  (\%061)
(\%i62) \text{ ev}(\%, \text{desol});
                                             bv + f(a - bt)
                                                                                                  (\%062)
```

4 Calculus of Variations: Functionals

Based on NPTEL-NOC IITM Video Calculus of Variations: Functionals

(%i63) kill(labels,x,y)\$

(%i1) $\zeta: [x,y]$ \$

(%i2) f(x,y):=x*y\$

(%i4) $\phi(x,y) := x^2 + y^2$ \$ b:1\$

(%i5) stapoints(f(x,y),[],[ϕ (x,y)-b], ζ)\$

$$stapts_1 = \left[x = \frac{1}{\sqrt{2}}, y = -\frac{1}{\sqrt{2}}, eqmult_1 = \frac{1}{2}\right] \tag{\%t5}$$

$$objsub = -\frac{1}{2} \tag{\%t6}$$

$$gradsub = [0, 0, 0] \tag{\%t7}$$

$$stapts_2 = \left[x = -\frac{1}{\sqrt{2}}, y = \frac{1}{\sqrt{2}}, eqmult_1 = \frac{1}{2}\right] \tag{\%t8}$$

$$objsub = -\frac{1}{2} \tag{\%t9}$$

$$gradsub = [0, 0, 0] \tag{\%t10}$$

$$stapts_3 = \left[x = \frac{1}{\sqrt{2}}, y = \frac{1}{\sqrt{2}}, eqmult_1 = -\frac{1}{2} \right]$$
 (%t11)

$$objsub = \frac{1}{2} \tag{\%t12}$$

$$gradsub = [0, 0, 0] \tag{\%t13}$$

$$stapts_4 = \left[x = -\frac{1}{\sqrt{2}}, y = -\frac{1}{\sqrt{2}}, eqmult_1 = -\frac{1}{2}\right] \tag{\%t14}$$

$$objsub = \frac{1}{2} \tag{\%t15}$$

$$gradsub = [0, 0, 0] \tag{\%t16}$$

(%i17) map(ldisp,stapts)\$

$$\left[x=\frac{1}{\sqrt{2}},y=-\frac{1}{\sqrt{2}},eqmult_1=\frac{1}{2}\right] \tag{\%t17}$$

$$\left[x = -\frac{1}{\sqrt{2}}, y = \frac{1}{\sqrt{2}}, eqmult_1 = \frac{1}{2}\right]$$
 (%t18)

$$\[x = \frac{1}{\sqrt{2}}, y = \frac{1}{\sqrt{2}}, eqmult_1 = -\frac{1}{2} \] \tag{\%t19}$$

$$\[x = -\frac{1}{\sqrt{2}}, y = -\frac{1}{\sqrt{2}}, eqmult_1 = -\frac{1}{2}\] \tag{\%t20}$$

(%i21) makelist(at(f(x,y),stapts[i]),i,1,length(stapts));

$$\left[-\frac{1}{2}, -\frac{1}{2}, \frac{1}{2}, \frac{1}{2} \right] \tag{\%o21}$$

(%i22) makelist(at(ϕ (x,y),stapts[i]),i,1,length(stapts));

$$[1, 1, 1, 1]$$
 (%o22)

(%i23) lagrangian;

$$eqmult_1 (y^2 + x^2 - 1) + xy$$
 (%o23)

(%i24) grad;

$$[y + 2eqmult_1x, 2eqmult_1y + x, y^2 + x^2 - 1]$$
 (%o24)

(%i25) decslkmults;

$$[x, y, eqmult_1] \tag{\%o25}$$

(%i26) gradient(decslkmults);

$$[y + 2eqmult_1x, 2eqmult_1y + x, y^2 + x^2 - 1]$$
 (%o26)

(%**i27**) G:list_matrix_entries(jacobian([f(x,y)], ζ));

$$[y, x] \tag{G}$$

(%i28) J:list_matrix_entries(jacobian([lagrangian],decslkmults));

$$[y+2eqmult_1x,2eqmult_1y+x,y^2+x^2-1] \hspace{1.5cm} ({\bf J})$$

(%i29) sol:algsys(grad,decslkmults)\$

(%i30) map(ldisp,sol)\$

$$\[x = \frac{1}{\sqrt{2}}, y = -\frac{1}{\sqrt{2}}, eqmult_1 = \frac{1}{2}\] \tag{\%t30}$$

$$\left[x=-\frac{1}{\sqrt{2}},y=\frac{1}{\sqrt{2}},eqmult_1=\frac{1}{2}\right] \tag{\%t31}$$

$$\left[x = \frac{1}{\sqrt{2}}, y = \frac{1}{\sqrt{2}}, eqmult_1 = -\frac{1}{2} \right]$$
 (%t32)

$$\left[x = -\frac{1}{\sqrt{2}}, y = -\frac{1}{\sqrt{2}}, eqmult_1 = -\frac{1}{2} \right] \tag{\%t33}$$

5 Examples

Based on Bsc Maths Aligarh Video Calculus of Variations

5.1

Find the extremals of the following functionals:

$$\int_{x_0}^{x_1} (x + y') \, y' \, \mathrm{d}x$$

(%i34) kill(labels,x,y)\$

(%i1) $\zeta: [x,y]$ \$

(%i2) depends(y,x)\$

Lagrangian

(%i3) L:
$$(x+'diff(y,x))*'diff(y,x);$$

$$(y_x) (y_x + x) (L)$$

Momentum Conjugate

$$P = 2\left(y_x\right) + x\tag{\%t4}$$

Generalized Forces

(%i5) ldisplay(F:diff(L,x))\$

$$F = (y_x) (y_{xx} + 1) + (y_x + x) (y_{xx})$$
(%t5)

Euler-Lagrange Equation

(%i6) aa:el(L,y,x)\$

(%i8) bb:ev(aa,eval,diff)\$

(%i9) map(ldisp,bb:fullratsimp(bb))\$

$$2(y_{xx}) + 1 = 0 (\%t9)$$

$$2(y_x) + x = k_1 (\%t10)$$

Solution

(%i11) odesol:ode2(bb[1],y,x);

$$y = -\frac{x^2}{4} + \%k2x + \%k1$$
 (odesol)

(%i12) method;

$$variation of parameters$$
 (%o12)

(%i13) declare([x_1,y_1,x_2,y_2],constant)\$

(%i14) params: [x_1=0,y_1=0,x_2=10,y_2=10]\$

(%i15) odesol:bc2(odesol,x=x_1,y=y_1,x=x_2,y=y_2);

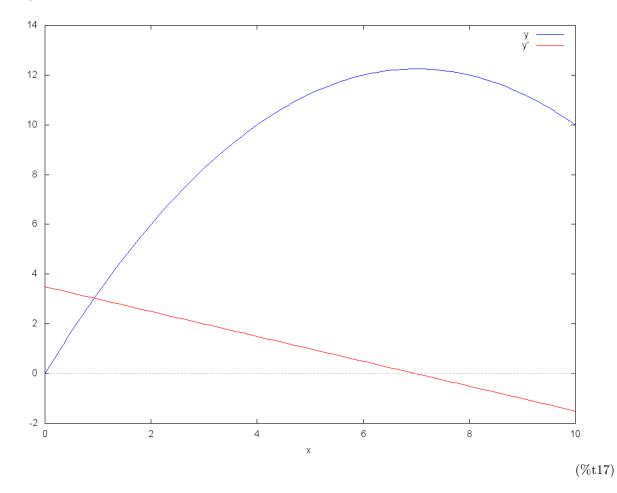
$$y = -\frac{x^2}{4} + \frac{\left(-4y_2 + 4y_1 - x_2^2 + x_1^2\right)x}{4x_1 - 4x_2} - \frac{x_1\left(-4y_2 - x_2^2\right) + 4x_2y_1 + x_1^2x_2}{4x_1 - 4x_2}$$
 (odesol)

(%i16) bb[2],odesol,eval,diff,expand,factor;

$$\frac{4y_2 - 4y_1 + x_2^2 - x_1^2}{2(x_2 - x_1)} = k_1 \tag{\%o16}$$

Graphics

 $\begin{tabular}{ll} (\%i17) & wxplot2d([y,diff(y,x)],[x,x_1,x_2],[ylabel,""], [legend,"y","y'"]),odesol,params \\ \end{tabular}$



5.2

Find the extremals of the following functionals:

$$\int_{x_0}^{x_1} \frac{{y'}^2}{x^3} \, \mathrm{d}x$$

(%i18) kill(labels,x,y)\$

(%i1) $\zeta: [x,y]$ \$

(%i2) depends(y,x)\$

Lagrangian

(%i3) L: 'diff(y,x) $^{2}/x^{3}$;

$$\frac{\left(y_x\right)^2}{x^3} \tag{L}$$

Momentum Conjugate

(%i4) ldisplay(P:diff(L,'diff(y,x)))\$

$$P = \frac{2(y_x)}{x^3} \tag{\%t4}$$

Generalized Forces

(%i5) ldisplay(F:diff(L,x))\$

$$F = \frac{2(y_x)(y_{xx})}{x^3} - \frac{3(y_x)^2}{x^4}$$
 (%t5)

Euler-Lagrange Equation

(%i6) aa:el(L,y,x)\$

(%i8) bb:ev(aa,eval,diff)\$

(%i9) map(ldisp,bb:fullratsimp(bb))\$

$$\frac{2x (y_{xx}) - 6 (y_x)}{x^4} = 0 (\%t9)$$

$$\frac{2\left(y_x\right)}{r^3} = k_1 \tag{\%t10}$$

Solution

(%i11) odesol:ode2(bb[1],y,x);

$$y = \%k2 x^4 - \frac{\%k1}{4}$$
 (odesol)

(%i12) method;

$$exact$$
 (%o12)

(%i13) declare([x_1,y_1,x_2,y_2],constant)\$

(%i14) params: [x_1=0,y_1=0,x_2=10,y_2=10]\$

(%i15) odesol:bc2(odesol,x=x_1,y=y_1,x=x_2,y=y_2);

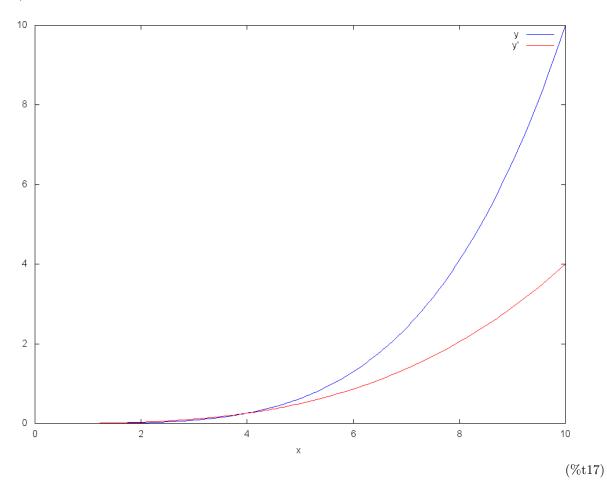
$$y = \frac{(y_1 - y_2)x^4}{x_1^4 - x_2^4} - \frac{4x_2^4y_1 - 4x_1^4y_2}{4(x_1^4 - x_2^4)}$$
 (odesol)

(%i16) bb[2],odesol,eval,diff;

$$\frac{8(y_1 - y_2)}{x_1^4 - x_2^4} = k_1 \tag{\%o16}$$

Graphics

 $\begin{tabular}{ll} (\%i17) & wxplot2d([y,diff(y,x)],[x,x_1,x_2],[ylabel,""], [legend,"y","y'"]),odesol,params \end{tabular}$



5.3

Find the extremals of the following functionals:

$$\int_{x_0}^{x_1} (1 + x^2 y') y' \, \mathrm{d}x$$

(%i18) kill(labels,x,y)\$

(%i1) $\zeta: [x,y]$ \$

(%i2) depends(y,x)\$

Lagrangian

(%i3) L:
$$(1+x^2*'diff(y,x))*'diff(y,x);$$
 $(y_x)(x^2(y_x)+1)$

Momentum Conjugate

$$P = 2x^2 (y_x) + 1 (\%t4)$$

(L)

Generalized Forces

$$F = (2x^{2} (y_{x}) + 1) (y_{xx}) + 2x (y_{x})^{2}$$
(%t5)

Euler-Lagrange Equation

(%i6) aa:el(L,y,x)\$

(%i8) bb:ev(aa,eval,diff)\$

(%i9) map(ldisp,bb:fullratsimp(bb))\$

$$2x^{2} (y_{xx}) + 4x (y_{x}) = 0 (\%t9)$$

$$2x^2 (y_x) + 1 = k_1 \tag{\%t10}$$

Solution

(%i11) odesol:ode2(bb[1],y,x);

$$y = \frac{\%k2}{x} + \%k1 \tag{odesol}$$

(%i12) method;

$$exact$$
 (%o12)

(%i13) declare([x_1,y_1,x_2,y_2],constant)\$

(%i14) params: [x_1=1,y_1=1,x_2=10,y_2=10]\$

(%i15) odesol:bc2(odesol,x=x_1,y=y_1,x=x_2,y=y_2);

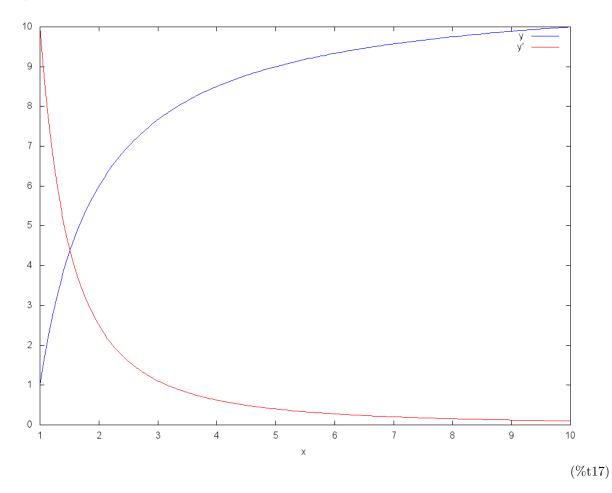
$$y = \frac{x_1 y_1 - x_2 y_2}{x_1 - x_2} - \frac{x_1 x_2 y_1 - x_1 x_2 y_2}{(x_1 - x_2) x}$$
 (odesol)

(%i16) bb[2],odesol,eval,diff,expand,factor;

$$\frac{2x_1x_2y_2 - 2x_1x_2y_1 + x_2 - x_1}{x_2 - x_1} = k_1 \tag{\%o16}$$

Graphics

 $\begin{tabular}{ll} (\%i17) & wxplot2d([y,diff(y,x)],[x,x_1,x_2],[ylabel,""], [legend,"y","y'"]),odesol,params \end{tabular}$



5.4

Find the extremals of the following functionals:

$$\int_{x_0}^{x_1} (y^2 + {y'}^2 - 2y\,\sin(x))\,\mathrm{d}x$$

(%i18) kill(labels,x,y)\$

(%i1) $\zeta: [x,y]$ \$

(%i2) depends(y,x)\$

Lagrangian

(%i3) L: y^2 +'diff(y,x)²-2*y*sin(x);

$$(y_x)^2 + y^2 - 2\sin(x)y$$
 (L)

Momentum Conjugate

(%i4) ldisplay(P:diff(L,'diff(y,x)))\$

$$P = 2(y_x) \tag{\%t4}$$

Generalized Forces

(%i5) ldisplay(F:fullratsimp(diff(L,x)))\$

$$F = 2(y_x)(y_{xx}) + (2y - 2\sin(x))(y_x) - 2\cos(x)y \tag{\%t5}$$

Euler-Lagrange Equation

(%i6) aa:el(L,y,x)\$

(%i7) bb:ev(aa,eval,diff)\$

(%i8) map(ldisp,bb:fullratsimp(bb))\$

$$2(y_{xx}) = 2y - 2\sin(x)$$
 (%t8)

Solution

(%i9) odesol:ode2(bb[1],y,x);

$$y = \frac{\sin(x)}{2} + \%k1 e^x + \%k2 e^{-x}$$
 (odesol)

(%i10) method;

$$variation of parameters$$
 (%o10)

(%i11) declare([x_1,y_1,x_2,y_2],constant)\$

(%i12) params: [x_1=0,y_1=0,x_2=10,y_2=10]\$

(%i13) odesol:bc2(odesol,x=x_1,y=y_1,x=x_2,y=y_2);

$$y = \frac{\sin\left(x\right)}{2} - \frac{\left(-e^{x_2}\sin\left(x_2\right) + e^{x_1}\sin\left(x_1\right) + 2e^{x_2}y_2 - 2e^{x_1}y_1\right)e^x}{2e^{2x_1} - 2e^{2x_2}} + \frac{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x}{2e^{2x_1} - 2e^{2x_2}} + \frac{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x}{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x} + \frac{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x}{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x} + \frac{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x}{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2}e^{2x_2}\right)e^{x_2}} + \frac{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{2x_2 + x_1}\sin\left(x_1\right) - 2e^{2x_2 + x_1}y_1\right)e^x}{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{x_2}e^{x_2}\right)e^{x_2}} + \frac{\left(e^{2x_1}\left(2e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right) + e^{x_2}e^{x_2}e^{x_2}}{\left(e^{x_2}y_2 - e^{x_2}\sin\left(x_2\right)\right)e^{x_2}} + e^{x_2}e^{x_2}e^{x_2}e^{x_2}$$

Graphics

(%i14) wxplot2d([y,diff(y,x)],[x,x_1,x_2],[ylabel,""], [legend,"y","y'"]),odesol,params\$

