

# Lecture 3: System Estimation by IV

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# Motivation Example: Simultaneous Equations

- As before, write the population model as

$$y_1 = x_1\beta_1 + u_1 \quad (1)$$

$$y_2 = x_2\beta_2 + u_2 \quad (2)$$

⋮

$$y_G = x_G\beta_G + u_G \quad (3)$$

where  $y_g$  is a response variable,  $g = 1, \dots, G$ . The explanatory variables,  $x_g$ , can be different across equations.

- Now we want to allow  $E(x'_g u_g) \neq 0$  for at least some equations  $g$ .
- EXAMPLE:** Individual Labor Supply. Consider a labor supply function and a wage offer (inverse labor demand) function:

$$h^s(w) = \gamma_1 w + z_1\delta_1 + u_1 \quad (4)$$

$$w^o(h) = \gamma_2 h + z_2\delta_2 + u_2 \quad (5)$$

Equation 4 shows how much each unit in the population would work at any given wage,  $w$ . Once we hold fixed  $z_1$  and  $u_1$ , we can trace out the (linear) supply curve as a function of  $w$ .

## Motivation Example: Simultaneous Equations

- We bring in the wage offer function to recognize that, for retrospective data, we observe the pair  $(h_i, w_i)$ , with  $w_i$  not being randomly assigned. What is a sensible assumption about how  $(h_i, w_i)$  are generated? A standard approach is to assume that we observe equilibrium hours and wages for each individual. That is, the data are generated as

$$h_i = \gamma_1 w_i + z_{i1} \delta_1 + u_{i1} \quad (6)$$

$$w_i = \gamma_2 h_i + z_{i2} \delta_2 + u_{i2} \quad (7)$$

# Identification

- General two-equation structural system (in the population):

$$y_1 = \gamma_1 y_2 + z_1 \delta_1 + u_1 \quad (8)$$

$$y_2 = \gamma_2 y_1 + z_2 \delta_2 + u_2 \quad (9)$$

where  $z_1$  is  $1 \times M_1$  and  $z_2$  is  $1 \times M_2$ . Let  $z$  be  $1 \times M$  contain all (nonredundant) exogenous variables

$$E(z'u_1) = E(z'u_2) = 0$$

where in almost all applications  $z_1$  and  $z_2$  (and therefore  $z$ ) include unity. We act as if that is true here, so that the structural errors  $u_1$  and  $u_2$  have zero means.

- $\gamma_1, \delta_1, \gamma_2, \delta_2$  are the structural parameters.
- The moment conditions imply that if a variable is exogenous in any equation, it is exogenous in all equations; this is the traditional starting point.
- Although we do not need them to study identification, we can obtain reduced forms for  $y_1$  and  $y_2$  if  $\gamma_1 \gamma_2 \neq 1$ .

# Identification

- Generally, a reduced form expresses an endogenous variable as a function of exogenous variables and unobserved errors.
- In this case, solve the two equations for  $y_1$  and  $y_2$ :

$$\begin{aligned}y_1 &= \gamma_1(\gamma_2 y_1 + z_2 \delta_2 + u_2) + z_1 \delta_1 + u_1 \\&= \gamma_1 \gamma_2 y_1 + z_1 \delta_1 + z_2 \gamma_1 \delta_2 + u_1 + \gamma_1 u_2.\end{aligned}$$

- Therefore, if  $\gamma_1 \gamma_2 \neq 1$ ,

$$\begin{aligned}y_1 &= (1 - \gamma_1 \gamma_2)^{-1}(z_1 \delta_1 + z_2 \gamma_2 \delta_2 + u_1 + \gamma_1 u_2) \\&= \mathbf{z}\boldsymbol{\pi}_1 + v_1\end{aligned}$$

where  $\boldsymbol{\pi}_1$  is the  $M \times 1$  vector of reduced form parameters and  $v_1 = (1 - \gamma_1 \gamma_2)^{-1}(u_1 + \gamma_1 u_2)$  is a reduced form error.

- We can do the same for  $y_2$ , so we have

$$\begin{aligned}y_1 &= \mathbf{z}\boldsymbol{\pi}_1 + v_1 \\y_2 &= \mathbf{z}\boldsymbol{\pi}_2 + v_2.\end{aligned}$$

Both reduced form errors satisfy  $E(\mathbf{z}'v_1) = E(\mathbf{z}'v_2) = 0$ , which means  $\boldsymbol{\pi}_1$  and  $\boldsymbol{\pi}_2$  can be consistently estimated by OLS.

# Identification

- We can always consistently estimate the RF (Reduced Form) parameters. When are the structural parameters identified?
- Identification in the two-equation case is straightforward. Consider identification of the first structural equation. Write it with the RF of  $y_2$ :

$$y_1 = \gamma_1 y_2 + z_1 \delta_1 + u_1$$

$$y_2 = \mathbf{z} \pi_2 + v_2$$

- Because  $y_2$  is the only endogenous explanatory variable, we need at least one instrument for it. That means we must have something in  $\mathbf{z}$  in the RF with a nonzero coefficient that is not also in  $z_1$ .
- But  $y_2 = \gamma_2 y_1 + z_2 \delta_2 + u_2$  and so  $\pi_2$  has a nonzero coefficient on something not in  $z_1$  if and only if there is at least one element of  $z_2$  that is not also in  $z_1$  with nonzero coefficient in  $\delta_2$ .

# Identification

- So, we can read identification of each equation off of the structural system:

$$y_1 = \gamma_1 y_2 + z_1 \delta_1 + u_1$$

$$y_2 = \gamma_2 y_1 + z_2 \delta_2 + u_2$$

The first equation is identified if and only if there is at least one element in  $z_2$  not in  $z_1$  with a nonzero coefficient (element of  $\delta_2$ ) in the second equation. Similarly, the second equation is identified if and only if there is something in  $z_1$  not in  $z_2$  with a corresponding nonzero element in  $\delta_1$ .

# Identification

In the system

$$\begin{aligned} h &= \gamma_1 w + \delta_1 \text{exper} + \delta_2 \text{exper}^2 + \delta_3 \text{othinc} + \delta_4 \text{kids} + u_1 \\ w &= \gamma_2 h + \delta_1 \text{exper} + \delta_2 \text{exper}^2 + \delta_3 \text{educ} + u_2, \end{aligned}$$

the labor supply function is identified if and only if  $\delta_3 \neq 0$ . The wage offer function is identified if and only if at least one of  $\delta_3$  and  $\delta_4$  is different from zero.

- Important: Our imposing of exclusion restrictions means that it must be the case that *educ* is legitimately excluded from the supply equation and *othinc* and *kids* are properly excluded from the wage offer equation.

## Example: Log-linear Supply-Demand System (Zoutman et al., 2018)

Assume log-linear supply-demand system.

$$y_{it}^S = \varepsilon^S p_{it} + \eta z_{it} + \Gamma^S x_{it} + v_{it}^S \quad (\text{supply})$$

$$y_{it}^D = \varepsilon^D p_{it} + \gamma z_{it} + \Gamma^D x_{it} + v_{it}^D \quad (\text{demand})$$

Can similarly write down reduced-form.

$$\begin{pmatrix} y_{it} \\ p_{it} \end{pmatrix} = \begin{pmatrix} \pi_{zy} \\ \pi_{zp} \end{pmatrix} z_{it} + \begin{pmatrix} \pi_{xy} \\ \pi_{xp} \end{pmatrix} x_{it} + \xi_{it}.$$

Without further restrictions.

$$\underbrace{\begin{pmatrix} \pi_{zy} \\ \pi_{zp} \end{pmatrix}}_{\text{Two reduced-form estimates}} = \underbrace{\begin{pmatrix} \frac{\varepsilon^S \gamma - \varepsilon^D \eta}{\varepsilon^S - \varepsilon^D} \\ \frac{\gamma - \eta}{\varepsilon^S - \varepsilon^D} \end{pmatrix}}_{\text{Four unknown structural parameters}} \quad \text{NOT identified.}$$

## Example: Log-linear Supply-Demand System (Zoutman et al., 2018)

What additional exclusion restriction do we need?

- Interestingly, if  $z_{it}$  happens to represent an "ad valorem" tax that enters log price linearly, then it works!
- SER (Standard Exclusion Restriction):  $\eta = 0$  i.e. tax is levied on demand side.
- RER (Ramsey Exclusion Restriction)  $z_{it} = \log(1 + \tau_{it})$ ,  $\gamma = \varepsilon^D$  i.e. demand only depends on price after tax.

## Example: Log-linear Supply-Demand System (Zoutman et al., 2018)

With these assumptions, we can write:

$$\begin{pmatrix} \pi_{zy} \\ \pi_{zp} \end{pmatrix} = \begin{pmatrix} \frac{\varepsilon^S \varepsilon^D}{\varepsilon^S - \varepsilon^D} \\ \frac{\varepsilon^D}{\varepsilon^S - \varepsilon^D} \end{pmatrix} \quad \text{Identified}$$

Obviously, we will still need **the relevance condition for IVs**:

- $\pi_{zp} \neq 0$  (Variation in tax rate does affect pre-tax price, o.w. entire incidence is on demand side.)
- $\pi_{zp} \neq -1$  (After-tax price is not independent of tax rate, o.w. entire incidence is on supply side.)

Estimation follows standard 2SLS.

## System IV Estimator

- As before, the SUR and panel data cases can both be written as

$$Y_i = X_i\beta + u_i \quad (10)$$

where  $Y_i$  is  $G \times 1$  (or  $T \times 1$ ) and  $X_i$  is  $G \times K$  (or  $T \times K$ ), and  $\beta$  is the  $K \times 1$  vector of parameters to be estimated.

- How do we choose the matrix of instruments,  $Z_i$ ?
  - SUR: Assume that for each equation  $g$ , the moment conditions are

$$E(z'_{ig} u_{ig}) = 0, \quad (11)$$

for a  $1 \times L_g$  vector  $z_{ig}$ , written for a random draw.

- Then the  $G \times L$  matrix of instruments is

$$Z_i = \begin{pmatrix} z_{i1} & 0 & \cdots & 0 \\ 0 & z_{i2} & \cdots & 0 \\ 0 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & z_{iG} \end{pmatrix}, \quad (12)$$

where  $L = L_1 + L_2 + \cdots + L_G$ .

## System IV Estimator

- Write the system as in the system OLS/GLS case:

$$Y_i = X_i\beta + u_i.$$

- Assumption SIV.1 (Moment Conditions): For a  $G \times L$  matrix  $Z_i$ ,

$$E(Z'_i u_i) = 0.$$

- The assumption is weaker, often in important ways, than the assumption that all elements of  $Z_i$  are uncorrelated with all elements in  $u_i$ :  
 $E(Z_i \otimes u_i) = 0$ . We return to this distinction later.
- Assumption SIV.2 (Rank Condition):

$$\text{rank } E(Z'_i X_i) = K.$$

- Later it is useful to define  $C = E(Z'_i X_i)$ .

# System IV Estimator

- In the SUR case

$$E(z_i'x_i) = \begin{pmatrix} E(z_{i1}'x_{i1}) & 0 & \cdots & 0 \\ 0 & E(z_{i2}'x_{i2}) & \cdots & 0 \\ 0 & 0 & \ddots & \vdots \\ \vdots & \vdots & \ddots & 0 \\ 0 & 0 & \cdots & E(z_{iG}'x_{iG}) \end{pmatrix},$$

and so SIV.2 holds if and only if

$$\text{rank } E(z_{ig}'x_{ig}) = K_g, \quad g = 1, \dots, G.$$

- Suppose  $L = K$ . Then

$$\beta = [E(Z_i'X_i)]^{-1} E(Z_i'y_i).$$

- Now, replace population averages with sample averages to get the system instrumental variables (SIV) estimator:

$$\hat{\beta}_{SIV} = \left( N^{-1} \sum_{i=1}^N Z_i' X_i \right)^{-1} \left( N^{-1} \sum_{i=1}^N Z_i' y_i \right).$$

## Empirical Example: Epple and McCallum (2005)

- Edible meat of young chicken (broiler)

$$\begin{array}{ll} \text{(supply)} & Q_t = \alpha_0 + \alpha_1 P_t + \alpha_2 W_t + u_t \end{array} \quad (13)$$

$$\begin{array}{ll} \text{(demand)} & Q_t = \beta_0 + \beta_1 P_t + \beta_2 Y_t + v_t. \end{array} \quad (14)$$

As suggested above, we presume that  $\alpha_1 > 0$ ,  $\alpha_2 < 0$ ,  $\beta_1 < 0$ , and  $\beta_2 > 0$ . In 13 and 14,  $u_t$  and  $v_t$  are stochastic disturbances representing measurement error, a multitude of individually-unimportant omitted variables, and purely random influences. We assume that  $E[u_t] = 0$ ,  $E[v_t] = 0$ ,  $E[u_t^2] = \sigma_u^2$ , and  $E[v_t^2] = \sigma_v^2$  for all  $t = 1, 2, \dots, T$ . We also assume that  $W_t$  and  $Y_t$  can legitimately be treated as exogenous to the particular market under consideration, so that  $W_t$  and  $Y_t$  will be uncorrelated with values of  $u_t$  and  $v_t$  for all current and past periods.

- Time series data from 1960 – 1999
  - Fast technological progress
  - Large change of relative price of chicken to other types of meat

## Alternative Estimates of Demand (per capita)

- OLS

$$q = -4.860 + 0.871y - 0.277p$$

(0.669) (0.068) (0.070)

$R^2 = 0.980 \quad SE = 0.0572 \quad DW = 0.343 \quad T = 52$

- Add price of substitute good (beef)

$$q = -4.679 + 0.852y - 0.264p - 0.118p_b$$

(0.675) (0.069) (0.070) (0.084)

$R^2 = 0.981 \quad SE = 0.0566 \quad DW = 0.443 \quad T = 52$

- Benchmark model: first differencing, no constant

$$\Delta q = 0.711\Delta y - 0.374\Delta p + 0.251\Delta p_b$$

(0.150) (0.058) (0.068)

$R^2 = 0.331 \quad SE = 0.0294 \quad DW = 2.38 \quad T = 51$

## Alternative Estimates of Supply (aggregate)

- Key exclusion restriction: feed price/corn price
- Simple specification does not work well

$$q^A = -9.185 - 1.203p - 0.338p_{cor}$$
$$(0.029) \quad (0.110) \quad (0.075)$$

$$R^2 = 0.942 \quad SE = 0.1412 \quad DW = 0.591 \quad T = 52$$

- Tech progress – time trend, control for autocorrelation, more promising

$$q^A = -2.478 - 0.041p - 0.083p_f + 0.0102\text{time} + 0.647q^A(-1)$$
$$(0.698) \quad (0.052) \quad (0.032) \quad (0.0038) \quad (0.108)$$

$$R^2 = 0.997 \quad SE = 0.0252 \quad DW = 1.883 \quad T = 39.$$

# Identification

- Demand: excluded variables on supply side are feed price, lagged quantity.
- Supply: excluded variables on demand side are changes in beef price and income per capita.
- Also include population change , lagged outputs price, since demand equation in first difference.

## Results

$$\begin{aligned}\Delta q = & 0.843\Delta y - 0.404\Delta p + 0.279\Delta p_b \\ & (0.143) \quad (0.086) \quad (0.093)\end{aligned}$$

$$R^2 = 0.291 \quad SE = 0.0253 \quad DW = 1.929 \quad T = 40$$

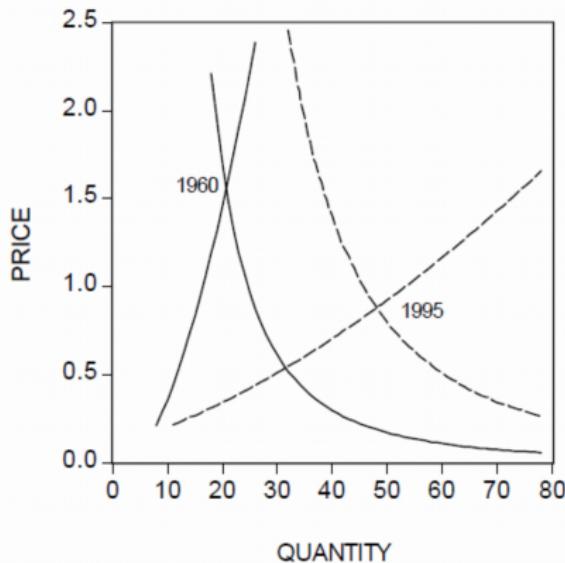
$$\begin{aligned}q^A = & -2.371 + 0.105p - 0.113p_f + 0.0123\text{time} + 0.640q^A(-1) \\ & (0.773) \quad (0.077) \quad (0.037) \quad (0.0043) \quad (0.119)\end{aligned}$$

$$R^2 = 0.996 \quad SE = 0.0279 \quad DW = 1.869 \quad T = 40$$

# Results

Figure 2

DEMAND AND LONG RUN SUPPLY CURVES  
1960 AND 1995



**Figure:** Epple and McCallum (2005) Figure 2