

# Statistics Study Notes

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## 1 Time Series

ADF-Test: 检验结果为负, 越负越拒绝原假设, 即有单位根。单位根存在, 即  $y_t = a + by_{t-1} + e_t$ ,  $|b| = 1$ , 为随机。

## 2 Maximum Likelihood

## 3 Kalman Filter

### 3.1 State Space Representation

$$\begin{aligned}\xi_{t+1} &= \mathbf{F}\xi_t + \mathbf{v}_{t+1} \\ \mathbf{y}_t &= \mathbf{A}'\mathbf{x}_t + \mathbf{H}'\xi_t + \mathbf{w}_t\end{aligned}$$

### 3.2 Definition

$$\begin{aligned}\mathbf{P}_{t|t-1} &\equiv E[(\xi_t - \hat{\xi}_{t|t-1})(\xi_t - \hat{\xi}_{t|t-1})'] \\ \mathbf{K}_t &= \mathbf{F}\mathbf{P}_{t|t-1}\mathbf{H}(\mathbf{H}'\mathbf{P}_{t|t-1}\mathbf{H} + \mathbf{R})^{-1} \\ E[(\xi_t - \hat{\xi}_{t|t-1})(\xi_t - \hat{\xi}_{t|t-1})'] &= \mathbf{P}_{t|t-1} \\ E[(\mathbf{y}_t - \hat{\mathbf{y}}_{t|t-1})(\mathbf{y}_t - \hat{\mathbf{y}}_{t|t-1})'] &= \mathbf{H}'\mathbf{P}_{t|t-1}\mathbf{H} + \mathbf{R} \\ E\{(\xi_t - \hat{\xi}_{t|t-1})(\mathbf{y}_t - \hat{\mathbf{y}}_{t|t-1})'\} &= \mathbf{P}_{t|t-1}\mathbf{H}\end{aligned}$$

### 3.3 Steps

$$\hat{\xi}_{1|0} = E(\xi_1)$$

$$P_{1|0} = E\{[\xi_1 - E(\xi_1)][\xi_1 - E(\xi_1)]'\}$$

### 3.4 Iteration

### 3.5 Smoothing

$$\mathbf{J}_t \equiv \mathbf{P}_{t|t} \mathbf{F}' \mathbf{P}_{t+1|t}^{-1}$$

$$\hat{\xi}_{t|T} = \hat{\xi}_{t|t} + J(\hat{\xi}_{t+1|T} - \hat{\xi}_{t+1|t})$$