

# Advanced Dynamical Systems (MATH60146/70146)

## Coursework 5

Homework issued on: February 28, 2025

Due date: March 7, 2025

Duration: 1 week

Spring 2024-25

Max mark: 20 Points

**Objective:** In this coursework, you will explore **parameter estimation** in chaotic systems using *synchronization-based inference*. Your task is to estimate unknown parameters of a dynamical system by driving a model with real data and identifying the best synchronization.

### 1. Parameter Estimation via Synchronization

(20)

The **Lorenz system** is given by:

$$\begin{aligned}\frac{dx}{dt} &= \sigma(y - x), \\ \frac{dy}{dt} &= x(\rho - z) - y, \\ \frac{dz}{dt} &= xy - \beta z.\end{aligned}$$

where  $\sigma, \rho, \beta$  are system parameters.

**Data:** You have been provided with a dataset `lorenz_xz_data.txt`, which contains time series of the  $x$  and  $z$  components from a simulated Lorenz system with unknown parameters.

- Drive the system using the provided  $x(t)$  data and find the best synchronization using the  $z(t)$  component. You may use any approach to estimate the parameters, but ensure that your method is justified.
- Parameter Space:** The unknown parameters  $\rho$  and  $\beta$  lie within the ranges:

$$\rho \in [26, 29], \quad \beta \in [2.5, 3.2].$$

The minimum resolution for parameter estimation should be  $\pm 0.05$ .

- Visualizing the results:** - Display how the synchronization error  $E$  depends on the estimated parameters. - Present your results in a meaningful visualization.
- Final Discussion:** - Report your estimated parameters. - Discuss potential sources of error in your estimation. - What are the limitations of the method you used?

**Hint:** Since this is a numerical approximation, the synchronization error  $E$  may not be exactly zero. The correct parameters correspond to the **smallest synchronization error**. You may consider grid search, optimization techniques, or other approaches.

**Submission Guidelines:** Submit a single PDF document containing:

- Your code and explanations.
- Figures and visualizations.
- The estimated parameters and discussion.

Best wishes,