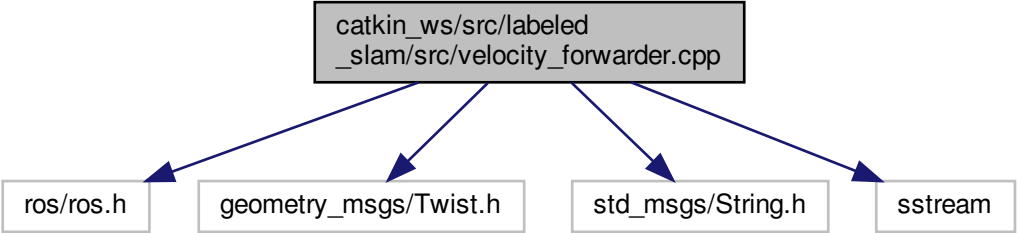


catkin_ws/src/labeled
_slam/src/velocity_forwarder.cpp



```
graph TD; A["catkin_ws/src/labeled_slam/src/velocity_forwarder.cpp"] --> B["ros/ros.h"]; A --> C["geometry_msgs/Twist.h"]; A --> D["std_msgs/String.h"]; A --> E["sstream"];
```

The diagram illustrates the dependencies of the file `catkin_ws/src/labeled_slam/src/velocity_forwarder.cpp`. It is represented as a central node at the top, with four arrows pointing downwards to its dependencies: `ros/ros.h`, `geometry_msgs/Twist.h`, `std_msgs/String.h`, and `sstream`.

ros/ros.h

geometry_msgs/Twist.h

std_msgs/String.h

sstream