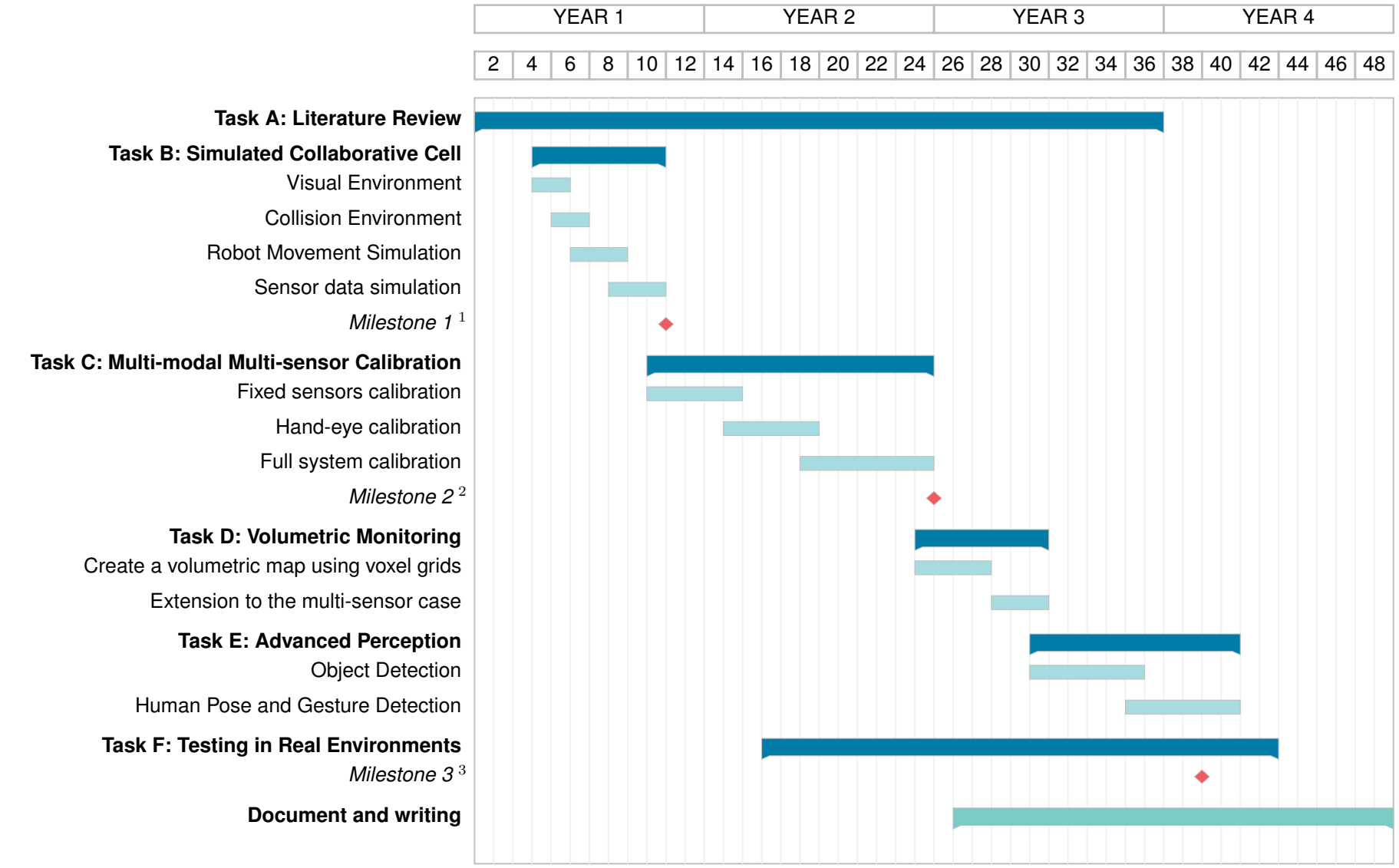

[1] Milestone 1: Log file with simulated data of sensors, robot data and collisions
[2] Milestone 2: Calibration of a simulated data to verify the accuracy of calibration
[3] Milestone 3: Demonstration in which the robot doesn't collide and is able to pick objects