Trabalho Prático 0 - AEDS III 0.0.0

Generated by Doxygen 1.8.13

Contents

1	Data	Struct	ure Index															1
	1.1	Data S	Structures						 	 	 	 	 	 			 	1
2	File	Index																3
	2.1	File Lis	st						 	 	 	 	 	 			 	3
3	Data	Struct	ure Docun	mer	ntati	on												5
	3.1	cell Str	ruct Refere	ence	е.				 	 	 	 	 	 			 	5
		3.1.1	Detailed	Des	scrip	otion			 	 	 	 	 	 			 	5
		3.1.2	Field Doo	cum	nenta	ation	١.		 	 	 	 	 	 			 	5
			3.1.2.1	m	ax				 	 	 	 	 	 			 	5
			3.1.2.2	m	in .				 	 	 	 	 	 			 	5
			3.1.2.3	SL	um				 	 	 	 	 	 			 	5
4	File	Docum	entation															7
	4.1	src/arv	ore.c File I	Ref	eren	ice			 	 	 	 	 	 			 	7
		4.1.1	Function	Do	cum	enta	ation	١.	 	 	 	 	 	 			 	7
			4.1.1.1	ac	dd()				 	 	 	 	 	 			 	7
			4.1.1.2	m	ain()) .			 	 	 	 	 	 			 	8
			4.1.1.3	SL	np()				 	 	 	 	 	 			 	8
	4.2	src/lib/	cell.c File f	Ref	eren	ice			 	 	 	 	 	 			 	8
		4.2.1	Function	Do	cum	enta	ation	١.	 	 	 	 	 	 			 	8
			4.2.1.1	C	ell_c	reat	:e()		 	 	 	 	 	 			 	9
			4.2.1.2	C	ell_d	lestr	oy()		 	 	 	 	 	 			 	9
			4213	C	ell fi	ill()												9

ii CONTENTS

		4.2.1.4	Cell_print()	10
4.3	src/lib/	cell.h File	Reference	10
	4.3.1	Typedef	Documentation	10
		4.3.1.1	Cell	10
	4.3.2	Function	Documentation	11
		4.3.2.1	Cell_create()	11
		4.3.2.2	Cell_destroy()	11
		4.3.2.3	Cell_fill()	11
		4.3.2.4	Cell_print()	12
4.4	src/lib/	matrix.c F	ile Reference	12
	4.4.1	Function	Documentation	12
		4.4.1.1	Matrix_create()	12
		4.4.1.2	Matrix_destroy()	13
		4.4.1.3	Matrix_fill()	13
		4.4.1.4	Matrix_print()	13
4.5	src/lib/	matrix.h F	ile Reference	14
	4.5.1	Function	Documentation	14
		4.5.1.1	Matrix_create()	14
		4.5.1.2	Matrix_destroy()	15
		4.5.1.3	Matrix_fill()	15
		4.5.1.4	Matrix_print()	15
4.6	src/lib/	segtree.c	File Reference	16
	4.6.1	Function	Documentation	16
		4.6.1.1	SegTree_construct()	16
		4.6.1.2	SegTree_create()	17
		4.6.1.3	SegTree_destroy()	17
		4.6.1.4	SegTree_query()	18
		4.6.1.5	SegTree_rangeQuery()	18
		4.6.1.6	SegTree_rangeUpdate()	19
		4.6.1.7	SegTree_size()	20

CONTENTS

		4.6.1.8	SegTree_update()	. 20
4.7	src/lib/	segtree.h l	File Reference	. 21
	4.7.1	Function	Documentation	. 21
		4.7.1.1	SegTree_construct()	. 21
		4.7.1.2	SegTree_create()	. 22
		4.7.1.3	SegTree_destroy()	. 22
		4.7.1.4	SegTree_query()	. 23
		4.7.1.5	SegTree_rangeQuery()	. 23
		4.7.1.6	SegTree_rangeUpdate()	. 24
		4.7.1.7	SegTree_size()	. 25
		4.7.1.8	SegTree_update()	. 25
4.8	src/ma	triz.c File I	Reference	. 26
	4.8.1	Function	Documentation	. 26
		4.8.1.1	main()	. 26
Index				27
HIUCX				21

Chapter 1

Data Structure Index

1	.1	Data	Stru	ictu	res

Here are the	e data structures	with brief	descri	ption	s:										
cell															
	Cell structure					 	 		 	 			 	 	. !

2 Data Structure Index

Chapter 2

File Index

2.1 File List

Here is a list of all files with brief descriptions:

src/arvore.c .												 				 								7
src/matriz.c .												 				 								26
src/lib/cell.c .								 				 				 								8
src/lib/cell.h .												 				 								10
src/lib/matrix.c												 				 								12
src/lib/matrix.h												 				 								14
src/lib/segtree.d	С											 				 								16
src/lib/segtree.l	h											 				 								21

File Index

Chapter 3

Data Structure Documentation

3.1 cell Struct Reference

Cell structure.

#include <cell.h>

Data Fields

- long long min
- long long max
- long long sum

3.1.1 Detailed Description

Cell structure.

This struct stores the max, min and the sum of the interval.

3.1.2 Field Documentation

3.1.2.1 max

long long max

3.1.2.2 min

long long min

Minimum and Maximum value of the interval

3.1.2.3 sum

long long sum

Sum of the interval

The documentation for this struct was generated from the following file:

• src/lib/cell.h

Chapter 4

File Documentation

4.1 src/arvore.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "lib/segtree.h"
#include "lib/cell.h"
```

Functions

- int add (int a)
- int sub (int a)
- int main ()

Main function.

4.1.1 Function Documentation

4.1.1.1 add()

```
int add ( int a)
```

4.1.1.2 main()

```
int main ( )
```

Main function.

This function uses the Bryan solution based on a Segment Tree that stores the input array data.

Returns

0

4.1.1.3 sub()

```
int sub ( \quad \text{int $a$} \ )
```

4.2 src/lib/cell.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include "cell.h"
```

Functions

• Cell Cell_create ()

Creates a new cell and initialize it's values with 0.

void Cell_destroy (Cell *cell)

Destroys the given cell.

• void Cell_print (Cell cell)

Prints the content of the given cell.

• void Cell_fill (Cell *cell, int *array, int i, int j)

Fill the cell data with the given array and intervals.

4.2.1 Function Documentation

4.2.1.1 Cell_create()

```
Cell Cell_create ( )
```

Creates a new cell and initialize it's values with 0.

Complexity: O(1)

Returns

The created cell

4.2.1.2 Cell_destroy()

Destroys the given cell.

Complexity: O(1)

Parameters

cell The cell to be destroyed	
-------------------------------	--

4.2.1.3 Cell_fill()

Fill the cell data with the given array and intervals.

Complexity: O(size-end)

Parameters

	cell	The cell
	array	The array
in	i	Start of the interval
in	j	End of the interval

4.2.1.4 Cell_print()

Prints the content of the given cell.

It doesn't print a new line.

Complexity: O(1)

Parameters

```
in cell The cell
```

4.3 src/lib/cell.h File Reference

Data Structures

struct cell

Cell structure.

Typedefs

typedef struct cell Cell

Functions

• Cell Cell_create ()

Creates a new cell and initialize it's values with 0.

void Cell_destroy (Cell *cell)

Destroys the given cell.

void Cell_print (Cell cell)

Prints the content of the given cell.

• void Cell_fill (Cell *cell, int *array, int i, int j)

Fill the cell data with the given array and intervals.

4.3.1 Typedef Documentation

4.3.1.1 Cell

```
typedef struct cell Cell
```

4.3.2 Function Documentation

4.3.2.1 Cell_create()

```
Cell Cell_create ( )
```

Creates a new cell and initialize it's values with 0.

Complexity: O(1)

Returns

The created cell

4.3.2.2 Cell_destroy()

Destroys the given cell.

Complexity: O(1)

Parameters

```
cell The cell to be destroyed
```

4.3.2.3 Cell_fill()

Fill the cell data with the given array and intervals.

Complexity: O(size-end)

Parameters

	cell	The cell
	array	The array
in	i	Start of the interval
Generat	ed ^j by Doxy	End of the interval

4.3.2.4 Cell_print()

Prints the content of the given cell.

It doesn't print a new line.

Complexity: O(1)

Parameters

4.4 src/lib/matrix.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include "cell.h"
#include "matrix.h"
```

Functions

```
• Cell ** Matrix_create (int n)
```

Builds the matrix with the given array.

void Matrix_fill (Cell **matrix, int *array, int n)

Fills the matrix with the given data.

• void Matrix_destroy (Cell **matrix, int n)

Destroys the matrix.

void Matrix_print (Cell **matrix, int n)

Prints the matrix.

4.4.1 Function Documentation

4.4.1.1 Matrix_create()

```
Cell** Matrix_create (
    int n )
```

Builds the matrix with the given array.

Complexity: O(n2)

Parameters

ıy

Returns

A pointer to the created matrix

4.4.1.2 Matrix_destroy()

Destroys the matrix.

Complexity: O(n)

Parameters

	matrix	The matrix
in	n	The length of the input array

4.4.1.3 Matrix_fill()

Fills the matrix with the given data.

 $Complexity: O(n^3), because the \ maximum \ interval \ given \ to \ Cell_Fill \ has \ size \ n, \ and \ is \ executed \ n^2 \ times.$

Parameters

	matrix	The matrix
	array	The array
in	n	The length of the input array

4.4.1.4 Matrix_print()

```
void Matrix_print (
```

```
Cell ** matrix,
int n )
```

Prints the matrix.

Complexity: O(n²)

Parameters

	matrix	The matrix
in	n	The length of the input array

4.5 src/lib/matrix.h File Reference

```
#include "cell.h"
```

Functions

Cell ** Matrix_create (int n)

Builds the matrix with the given array.

void Matrix_fill (Cell **matrix, int *array, int n)

Fills the matrix with the given data.

void Matrix_destroy (Cell **matrix, int n)

Destroys the matrix.

void Matrix_print (Cell **matrix, int n)

Prints the matrix.

4.5.1 Function Documentation

4.5.1.1 Matrix_create()

```
Cell** Matrix_create (
    int n )
```

Builds the matrix with the given array.

Complexity: O(n2)

Parameters

in	n	The length of the input array

Returns

A pointer to the created matrix

4.5.1.2 Matrix_destroy()

Destroys the matrix.

Complexity: O(n)

Parameters

	matrix	The matrix
in	n	The length of the input array

4.5.1.3 Matrix_fill()

Fills the matrix with the given data.

Complexity: O(n³), because the maximum interval given to Cell_Fill has size n, and is executed n² times.

Parameters

	matrix	The matrix
	array	The array
in	n	The length of the input array

4.5.1.4 Matrix_print()

Prints the matrix.

Complexity: O(n²)

Parameters

	matrix	The matrix
in	n	The length of the input array

4.6 src/lib/segtree.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <limits.h>
#include "segtree.h"
#include "cell.h"
```

Functions

void SegTree_construct (Cell *segtree, int pos, int *array, int start, int end)

Recursively constructs the Segment Tree.

int SegTree_size (int n)

Calculates the Segment Tree's number of nodes with the given the input array size.

• Cell * SegTree_create (int *array, int n)

Creates a new Segment Tree.

void SegTree_destroy (Cell *segtree)

Destroys the given Segment Tree.

• Cell SegTree_rangeQuery (Cell *segtree, int pos, int start, int end, int currStart, int currEnd)

Perform a range query on the Segment Tree recursivelly.

• Cell SegTree_query (Cell *segtree, int n, int start, int end)

Interface for the recursive range query.

void SegTree_rangeUpdate (Cell *segtree, int pos, int start, int end, int currStart, int currEnd, int(*transform)(int n))

Recursively updates the Segment Tree.

• void SegTree_update (Cell *segtree, int n, int start, int end, int(*transform)(int n))

Interface for the recursive segtree update.

4.6.1 Function Documentation

4.6.1.1 SegTree_construct()

Recursively constructs the Segment Tree.

Complexity:

With n being the Segment Tree's number of nodes, the complexity is O(n), because we need to visit every node of the tree to calculate its data.

Parameters

	segtree	The Segment Tree array
in	pos	The current position on the segtree
in	array	The input array
in	start	The start of the interval (0-indexed, inclusive)
in	end	The end of the interval (0-indexed, inclusive)

4.6.1.2 SegTree_create()

Creates a new Segment Tree.

Complexity:

The complexity for creating a new Segment Tree is related to the function $SegTree_construct$, which is O(N), being N the number of nodes of the tree.

The number of nodes N, in the best case is $2 \cdot n-1$, with n being the input array length. In worst case N will not pass from $4 \cdot n-1$. The full explanation for this is on the SegTree_size function description.

In all cases, the complexity for creating a new Segment Tree is O(n).

Parameters

in	array	The input array
in	n	The input array length

Returns

A pointer to the created Segment Tree

4.6.1.3 SegTree_destroy()

Destroys the given Segment Tree.

Complexity: O(1)

Parameters

segtree The segtree

4.6.1.4 SegTree_query()

Interface for the recursive range query.

Complexity: The complexity here is related to the complexity of the SegTree_rangeQuery function, which is O(log N), being N the number of nodes of the tree.

The number of nodes N, in the best case is $2 \cdot n-1$, with n being the input array length. In worst case N will not pass from $4 \cdot n-1$. The full explanation for this is on the SegTree_size function description.

With $2 \cdot n-1$ or $4 \cdot n-1$, the complexity of the function is $O(\log n)$.

Parameters

	segtree	The segtree
in	n	The input array length
in	start	The start of the interval (1-indexed, inclusive)
in	end	The end of the interval (1-indexed, inclusive)

Returns

The results of the query

4.6.1.5 SegTree_rangeQuery()

Perform a range query on the Segment Tree recursivelly.

Complexity:

In the best case, the range of the query will be from 0 to (L - 1), being L the length of the input array. In this case, the complexity for retrieving data from the segtree is O(1).

In the worst case, the range of the query will have length of 1 (query of 1 element). In this case, the alghoritm will dive into the tree til reach the correspondant leaf. The complexity for retrieving the leaf data will be of O(H), with H begin the height of the tree.

As the Segment Tree is a Full Binary Tree, the height of the tree will correspond log N, being N the number of nodes. So the complexity for retrieving data from a leaf is O(log N).

Parameters

	segtree	The segtree
in	pos	The position
in	start	The start of the interval (0-indexed, inclusive)
in	end	The end of the interval (0-indexed, inclusive)
in	currStart	The current start of the interval (0-indexed, inclusive)
in	currEnd	The current end of the interval (0-indexed, inclusive)

Returns

The results of the query

4.6.1.6 SegTree_rangeUpdate()

Recursively updates the Segment Tree.

Complexity:

As the updates are realized on the leafs of the tree, and then the nodes that represent the intervals have to be updated, the cost on the update will be related to the amount of nodes that has to be updated plus the height of the tree. The cost to reach a leaf is log H, being H the height of the tree. Let LF the number of leafs to be updated, that is the same as the size of the interval to be updated (end-start-1).

As the Segment Tree is a Full Binary Tree, the height of the tree will correspond log N, being N the number of nodes. So the complexity for retrieving data from a leaf is O(log N).

The complexity of a update is O(LF·log N).

Parameters

	segtree	The segtree
in	pos	The current position on the segtree array
Generated SolyAto bxygen		The start of the interval (0-indexed, inclusive)
in	end	The end of the interval (0-indexed, inclusive)
in	currStart	The current start of the interval (0-indexed, inclusive)
in	currEnd	The current end of the interval (0-indexed, inclusive)

4.6.1.7 SegTree size()

```
int SegTree_size (
          int n )
```

Calculates the Segment Tree's number of nodes with the given the input array size.

The number of nodes n required for a segtree is calculated with the length of the input array. In the best case, the length L is a power of 2, so the number of nodes is $n=2\cdot L-1$. If L is not a power of 2, we have to find the next power of 2 after L. In this case, the number of nodes will not pass from $n=2\cdot 2^{\wedge}((\log L)+1)-1$, which can be simplified to $n=4\cdot L-1$.

Being n the input array length, let np the power of 2 that is equal or higher than n. The size of the Segment Tree array will be 2·np-1.

The strategy adopted here is to calculate the log2 of n and get the ceil of the result. This way, we can power 2 for the result and get the next power of 2. Then, we use $2 \cdot (2^{n}) - 1$ to get the the size of the Segment Tree array.

Complexity: (1)

Parameters

	in	n	The input array size
--	----	---	----------------------

Returns

The size of the Segment Tree array

4.6.1.8 SegTree_update()

Interface for the recursive segtree update.

Complexity: The complexity here is related to the complexity of the SegTree_rangeUpdate function, which is $O(L \leftarrow F \cdot log N)$, being N the number of nodes of the tree, and LF is end - start - 1.

The number of nodes N, in the best case is 2·n-1, with n being the input array length. In worst case N will not pass from 4·n-1. The full explanation for this is on the SegTree_size function description.

With 2·n-1 or 4·n-1, the complexity of the function is O(LF·log n).

Parameters

	segtree	The segtree
in	n	The length of the input array
in	start	The start of the interval (1-indexed, inclusive)
in	end	The end of the interval (1-indexed, inclusive)
in	transform	The transform function

4.7 src/lib/segtree.h File Reference

```
#include "cell.h"
```

Functions

• void SegTree_construct (Cell *segtree, int pos, int *array, int start, int end)

Recursively constructs the Segment Tree.

• int SegTree_size (int n)

Calculates the Segment Tree's number of nodes with the given the input array size.

Cell * SegTree_create (int *array, int n)

Creates a new Segment Tree.

void SegTree_destroy (Cell *segtree)

Destroys the given Segment Tree.

• Cell SegTree_rangeQuery (Cell *segtree, int pos, int start, int end, int currStart, int currEnd)

Perform a range query on the Segment Tree recursivelly.

Cell SegTree_query (Cell *segtree, int n, int start, int end)

Interface for the recursive range query.

void SegTree_rangeUpdate (Cell *segtree, int pos, int start, int end, int currStart, int currEnd, int(*transform)(int n))

Recursively updates the Segment Tree.

• void SegTree_update (Cell *segtree, int n, int start, int end, int(*transform)(int n))

Interface for the recursive segtree update.

4.7.1 Function Documentation

4.7.1.1 SegTree_construct()

Recursively constructs the Segment Tree.

Complexity:

With n being the Segment Tree's number of nodes, the complexity is O(n), because we need to visit every node of the tree to calculate its data.

Parameters

	segtree	The Segment Tree array
in	pos	The current position on the segtree
in	array	The input array
in	start	The start of the interval (0-indexed, inclusive)
in	end	The end of the interval (0-indexed, inclusive)

4.7.1.2 SegTree_create()

Creates a new Segment Tree.

Complexity:

The complexity for creating a new Segment Tree is related to the function $SegTree_construct$, which is O(N), being N the number of nodes of the tree.

The number of nodes N, in the best case is $2 \cdot n-1$, with n being the input array length. In worst case N will not pass from $4 \cdot n-1$. The full explanation for this is on the SegTree_size function description.

In all cases, the complexity for creating a new Segment Tree is O(n).

Parameters

in	array	The input array
in	n	The input array length

Returns

A pointer to the created Segment Tree

4.7.1.3 SegTree_destroy()

Destroys the given Segment Tree.

Complexity: O(1)

Parameters

The segtree

4.7.1.4 SegTree_query()

Interface for the recursive range query.

Complexity: The complexity here is related to the complexity of the SegTree_rangeQuery function, which is O(log N), being N the number of nodes of the tree.

The number of nodes N, in the best case is $2 \cdot n-1$, with n being the input array length. In worst case N will not pass from $4 \cdot n-1$. The full explanation for this is on the SegTree_size function description.

With $2 \cdot n-1$ or $4 \cdot n-1$, the complexity of the function is $O(\log n)$.

Parameters

	segtree	The segtree
in	n	The input array length
in	start	The start of the interval (1-indexed, inclusive)
in	end	The end of the interval (1-indexed, inclusive)

Returns

The results of the query

4.7.1.5 SegTree_rangeQuery()

Perform a range query on the Segment Tree recursivelly.

Complexity:

In the best case, the range of the query will be from 0 to (L - 1), being L the length of the input array. In this case, the complexity for retrieving data from the segtree is O(1).

In the worst case, the range of the query will have length of 1 (query of 1 element). In this case, the alghoritm will dive into the tree til reach the correspondant leaf. The complexity for retrieving the leaf data will be of O(H), with H begin the height of the tree.

As the Segment Tree is a Full Binary Tree, the height of the tree will correspond log N, being N the number of nodes. So the complexity for retrieving data from a leaf is O(log N).

Parameters

	segtree	The segtree
in	pos	The position
in	start	The start of the interval (0-indexed, inclusive)
in	end	The end of the interval (0-indexed, inclusive)
in	currStart	The current start of the interval (0-indexed, inclusive)
in	currEnd	The current end of the interval (0-indexed, inclusive)

Returns

The results of the query

4.7.1.6 SegTree_rangeUpdate()

Recursively updates the Segment Tree.

Complexity:

As the updates are realized on the leafs of the tree, and then the nodes that represent the intervals have to be updated, the cost on the update will be related to the amount of nodes that has to be updated plus the height of the tree. The cost to reach a leaf is log H, being H the height of the tree. Let LF the number of leafs to be updated, that is the same as the size of the interval to be updated (end-start-1).

As the Segment Tree is a Full Binary Tree, the height of the tree will correspond log N, being N the number of nodes. So the complexity for retrieving data from a leaf is $O(\log N)$.

The complexity of a update is O(LF·log N).

Parameters

	segtree	The segtree	
in	pos	The current position on the segtree array	
in	start	The start of the interval (0-indexed, inclusive)	Generated by Doxyger
in	end	The end of the interval (0-indexed, inclusive)	
in	currStart	The current start of the interval (0-indexed, inclusive)	
in	currEnd	The current end of the interval (0-indexed, inclusive)	

4.7.1.7 SegTree size()

```
int SegTree_size (
          int n )
```

Calculates the Segment Tree's number of nodes with the given the input array size.

The number of nodes n required for a segtree is calculated with the length of the input array. In the best case, the length L is a power of 2, so the number of nodes is $n=2\cdot L-1$. If L is not a power of 2, we have to find the next power of 2 after L. In this case, the number of nodes will not pass from $n=2\cdot 2^{\wedge}((\log L)+1)-1$, which can be simplified to $n=4\cdot L-1$.

Being n the input array length, let np the power of 2 that is equal or higher than n. The size of the Segment Tree array will be 2·np-1.

The strategy adopted here is to calculate the log2 of n and get the ceil of the result. This way, we can power 2 for the result and get the next power of 2. Then, we use $2 \cdot (2^{n}) - 1$ to get the the size of the Segment Tree array.

Complexity: (1)

Parameters

in	n	The input array size
----	---	----------------------

Returns

The size of the Segment Tree array

4.7.1.8 SegTree_update()

Interface for the recursive segtree update.

Complexity: The complexity here is related to the complexity of the SegTree_rangeUpdate function, which is $O(L \leftarrow F \cdot log N)$, being N the number of nodes of the tree, and LF is end - start - 1.

The number of nodes N, in the best case is $2 \cdot n-1$, with n being the input array length. In worst case N will not pass from $4 \cdot n-1$. The full explanation for this is on the SegTree_size function description.

With 2·n-1 or 4·n-1, the complexity of the function is O(LF·log n).

Parameters

	segtree	The segtree
in	n	The length of the input array
in	start	The start of the interval (1-indexed, inclusive)
in	end	The end of the interval (1-indexed, inclusive)
in	transform	The transform function

4.8 src/matriz.c File Reference

```
#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include "lib/matrix.h"
#include "lib/cell.h"
```

Functions

• int main ()

Main function.

4.8.1 Function Documentation

4.8.1.1 main()

int main ()

Main function.

This function uses the Nubby solution based on a matrix that stores the data for each possible interval.

Complexity: O(n²)

Returns

0

Index

add	Matrix_create
arvore.c, 7	matrix.c, 12
arvore.c	matrix.h, 14
add, 7	Matrix_destroy
main, 7	matrix.c, 13
sub, 8	matrix.h, 15
	Matrix_fill
Cell	matrix.c, 13
cell.h, 10	matrix.h, 15
cell, 5	Matrix print
max, 5	matrix.c, 13
min, 5	matrix.h, 15
sum, 5	matriz.c
cell.c	main, <mark>26</mark>
Cell_create, 8	max
Cell_destroy, 9	cell, 5
Cell_fill, 9	min
Cell_print, 9	cell, 5
cell.h	
Cell, 10	SegTree_construct
Cell_create, 11	segtree.c, 16
Cell_destroy, 11	segtree.h, 21
Cell_fill, 11	SegTree_create
Cell_print, 12	segtree.c, 17
Cell_create	segtree.h, 22
cell.c, 8	SegTree_destroy
cell.h, 11	segtree.c, 17
Cell_destroy	segtree.h, 22
cell.c, 9	SegTree_query
cell.h, 11	segtree.c, 18
Cell_fill	segtree.h, 23
cell.c, 9	SegTree_rangeQuery
cell.h, 11	segtree.c, 18
Cell_print	segtree.h, 23
cell.c, 9	SegTree_rangeUpdate
cell.h, 12	segtree.c, 19
and the	segtree.h, 24
main	SegTree_size
arvore.c, 7	segtree.c, 20
matriz.c, 26	segtree.h, 25
matrix.c	SegTree_update
Matrix_create, 12	segtree.c, 20
Matrix_destroy, 13	segtree.h, 25
Matrix_fill, 13	segtree.c
Matrix_print, 13	SegTree_construct, 16
matrix.h	SegTree_create, 17
Matrix_create, 14	SegTree_destroy, 17
Matrix_destroy, 15	SegTree_query, 18
Matrix_fill, 15	SegTree_rangeQuery, 18
Matrix_print, 15	SegTree_rangeUpdate, 19

28 INDEX

```
SegTree_size, 20
     SegTree_update, 20
segtree.h
     SegTree_construct, 21
     SegTree_create, 22
     SegTree_destroy, 22
     SegTree_query, 23
    SegTree_rangeQuery, 23
     SegTree_rangeUpdate, 24
     SegTree_size, 25
     SegTree_update, 25
src/arvore.c, 7
src/lib/cell.c, 8
src/lib/cell.h, 10
src/lib/matrix.c, 12
src/lib/matrix.h, 14
src/lib/segtree.c, 16
src/lib/segtree.h, 21
src/matriz.c, 26
sub
    arvore.c, 8
sum
    cell, 5
```