

ImagesToLARModel, a tool for creation of three-dimensional models from a stack of images

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Abstract

This is the abstract (we will use LAR [\[CL13\]](#))

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1 Introduction

2 Exporting the library

```
"src/ImagesToLARModel.jl" 3≡
module ImagesToLARModel
"""
Main module for the library. It starts conversion
taking configuration parameters
"""
require(string(Pkg.dir("ImagesToLARModel/src"), "/imagesConversion.jl"))

import JSON
import ImagesConversion

using Logging

export convertImagesToLARModel

function loadConfiguration(configurationFile)
"""
load parameters from JSON file

configurationFile: Path of the configuration file
"""

configuration = JSON.parse(configurationFile)

DEBUG_LEVELS = [DEBUG, INFO, WARNING, ERROR, CRITICAL]

return configuration["inputDirectory"], configuration["outputDirectory"], configuration["bestImage"],
configuration["nx"], configuration["ny"], configuration["nz"],
DEBUG_LEVELS[configuration["DEBUG_LEVEL"]]
end

function convertImagesToLARModel(configurationFile)
"""
Start conversion of a stack of images into a 3D model
loading parameters from a JSON configuration file

configurationFile: Path of the configuration file
"""

inputDirectory, outputDirectory, bestImage, nx, ny, nz, DEBUG_LEVEL = loadConfiguration(open(configurationFile))
convertImagesToLARModel(inputDirectory, outputDirectory, bestImage, nx, ny, nz, DEBUG_LEVEL)
end
```

```

function convertImagesToLARModel(inputDirectory, outputDirectory, bestImage,
                                nx, ny, nz, DEBUG_LEVEL = INFO)
    """
    Start conversion of a stack of images into a 3D model

    inputDirectory: Directory containing the stack of images
    outputDirectory: Directory containing the output
    bestImage: Image chosen for centroids computation
    nx, ny, nz: Border dimensions (Possibly the biggest power of two of images dimensions)
    DEBUG_LEVEL: Debug level for Julia logger. It can be one of the following:
        - DEBUG
        - INFO
        - WARNING
        - ERROR
        - CRITICAL
    """
    # Create output directory
    try
        mkpath(outputDirectory)
    catch
    end

    Logging.configure(level=DEBUG_LEVEL)
    ImagesConversion.images2LARModel(nx, ny, nz, bestImage, inputDirectory, outputDirectory)
end
end
◇

```

```

"src/imagesConversion.jl" 4≡
module ImagesConversion

    require(string(Pkg.dir("ImagesToLARModel/src"), "/generateBorderMatrix.jl"))
    require(string(Pkg.dir("ImagesToLARModel/src"), "/pngStack2Array3dJulia.jl"))
    require(string(Pkg.dir("ImagesToLARModel/src"), "/lar2Julia.jl"))
    require(string(Pkg.dir("ImagesToLARModel/src"), "/model2Obj.jl"))

    import GenerateBorderMatrix
    import PngStack2Array3dJulia
    import Lar2Julia
    import Model2Obj

    import JSON

```

```

using PyCall
@pyimport scipy.sparse as Pysparse

using Logging

export images2LARModel

"""
This is main module for converting a stack
of images into a 3d model
"""

function images2LARModel(nx, ny, nz, bestImage, inputDirectory, outputDirectory)
    """
    Convert a stack of images into a 3d model
    """

    info("Starting model creation")

    numberOfClusters = 2 # Number of clusters for
                        # images segmentation

    info("Moving images into temp directory")
    try
        mkdir(string(outputDirectory, "TEMP"))
    catch
    end

    tempDirectory = string(outputDirectory, "TEMP/")

    newBestImage = PngStack2Array3dJulia.convertImages(inputDirectory, tempDirectory, bestImage)

    imageWidth, imageHeight = PngStack2Array3dJulia.getImageData(string(tempDirectory, newBestImage))
    imageDepth = length(readdir(tempDirectory))

    # Computing border matrix
    info("Computing border matrix")
    try
        mkdir(string(outputDirectory, "BORDERS"))
    catch
    end
    borderFilename = GenerateBorderMatrix.getOriented3BorderPath(string(outputDirectory, "BORDERS"))

    # Starting images conversion and border computation
    info("Starting images conversion")

```

```

        startImageConversion(tempDirectory, newBestImage, outputDirectory, borderFilename,
                             imageHeight, imageWidth, imageDepth,
                             nx, ny, nz,
                             numberOfClusters)

end

function startImageConversion(sliceDirectory, bestImage, outputDirectory, borderFilename,
                             imageHeight, imageWidth, imageDepth,
                             imageDx, imageDy, imageDz,
                             numberOfClusters)

    """
    Support function for converting a stack of images into a model

    sliceDirectory: directory containing the image stack
    imageForCentroids: image chosen for centroid computation
    """

    # Create clusters for image segmentation
    info("Computing image centroids")
    debug("Best image = ", bestImage)
    centroidsCalc = PngStack2Array3dJulia.calculateClusterCentroids(sliceDirectory, bestImage, n
    debug(string("centroids = ", centroidsCalc))

    try
        mkdir(string(outputDirectory, "BORDERS"))
    catch
    end
    debug(string("Opening border file: ", "border_", imageDx, "-", imageDy, "-", imageDz, ".json"))
    boundaryMat = getBorderMatrix(string(outputDirectory, "BORDERS/", "border_", imageDx, "-",
                                     imageDy, "-", imageDz, ".json"))

    beginImageStack = 0
    endImage = beginImageStack

    info("Converting images into a 3d model")
    tasks = Array{RemoteRef, 0}
    for zBlock in 0:(imageDepth / imageDz - 1)
        startImage = endImage
        endImage = startImage + imageDz
        info("StartImage = ", startImage)
        info("endImage = ", endImage)

        task = @spawn imageConversionProcess(sliceDirectory, outputDirectory,
                                             beginImageStack, startImage, endImage,

```

```

                                imageDx, imageDy, imageDz,
                                imageHeight, imageWidth,
                                centroidsCalc, boundaryMat)

    push!(tasks, task)

end

# Waiting for processes completion
for task in tasks
    wait(task)
end

info("Merging obj models")
Model2Obj.mergeObj(string(outputDirectory, "MODELS"))

end

function imageConversionProcess(sliceDirectory, outputDirectory,
                                beginImageStack, startImage, endImage,
                                imageDx, imageDy, imageDz,
                                imageHeight, imageWidth,
                                centroids, boundaryMat)
    """
    Support function for converting a stack of image on a single
    independent process
    """

    info("Transforming png data into 3d array")
    theImage = PngStack2Array3dJulia.pngstack2array3d(sliceDirectory, startImage, endImage, centroids, boundaryMat)

    centroidsSorted = sort(vec(reshape(centroids, 1, 2)))
    foreground = centroidsSorted[2]
    background = centroidsSorted[1]
    debug(string("background = ", background, " foreground = ", foreground))

    # V and FV contains vertices and faces of this part of model
    V = Array{Array{Int}, 0}
    FV = Array{Array{Int}, 0}
    facesOffset = 0
    for xBlock in 0:(imageHeight / imageDx - 1)
        for yBlock in 0:(imageWidth / imageDy - 1)
            yStart = xBlock * imageDx
            xStart = yBlock * imageDy
            #xEnd = xStart + imageDx
            #yEnd = yStart + imageDy
            xEnd = xStart + imageDy

```

```

yEnd = yStart + imageDx
debug("*****")
debug(string("xStart = ", xStart, " xEnd = ", xEnd))
debug(string("yStart = ", yStart, " yEnd = ", yEnd))
debug("theImage dimensions: ", size(theImage)[1], " ", size(theImage[1])[1], " ", size(t

# Getting a slice of theImage array

image = Array{UInt8, (convert{Int, length(theImage)}, convert{Int, xEnd - xStart}, conver
debug("image size: ", size(image))
for z in 1:length(theImage)
    for x in 1 : (xEnd - xStart)
        for y in 1 : (yEnd - yStart)
            image[z, x, y] = theImage[z][x + xStart, y + yStart]
        end
    end
end

nx, ny, nz = size(image)
chains3D = Array{UInt8, 0}
zStart = startImage - beginImageStack
for y in 0:(nx - 1)
    for x in 0:(ny - 1)
        for z in 0:(nz - 1)
            if(image[z + 1, x + 1, y + 1] == foreground)
                push!(chains3D, y + ny * (x + nx * z))
            end
        end
    end
end

if(length(chains3D) != 0)
    # Computing boundary chain
    debug("chains3d = ", chains3D)
    debug("Computing boundary chain")
    objectBoundaryChain = Lar2Julia.larBoundaryChain(boundaryMat, chains3D)
    debug("Converting models into obj")
    try
        mkdir(string(outputDirectory, "MODELS"))
    catch
    end
    # IMPORTANT: inverting xStart and yStart for obtaining correct rotation of the model
    V_part, FV_part = Model2Obj.computeModel(imageDx, imageDy, imageDz, yStart, xStart, zS
    facesOffset += length(V_part)
    append!(V, V_part)
    append!(FV, FV_part)

```



```

        else
            debug("Model is empty")
        end
    end
end
end
outputFilename = string(outputDirectory, "MODELS/model_output_", startImage, "_", endImage)
Model2Obj.writeToObj(V, FV, outputFilename)
end

function getBorderMatrix(borderFilename)
    """
    TO REMOVE WHEN PORTING OF LARCC IN JULIA IS COMPLETED

    Get the border matrix from json file and convert it in
    CSC format
    """
    # Loading borderMatrix from json file
    borderData = JSON.parsefile(borderFilename)
    row = Array{Int64, 1}(length(borderData["ROW"]))
    col = Array{Int64, 1}(length(borderData["COL"]))
    data = Array{Int64, 1}(length(borderData["DATA"]))

    for i in 1:length(borderData["ROW"])
        row[i] = borderData["ROW"][i]
    end

    for i in 1:length(borderData["COL"])
        col[i] = borderData["COL"][i]
    end

    for i in 1:length(borderData["DATA"])
        data[i] = borderData["DATA"][i]
    end

    # Converting csr matrix to csc
    csrBorderMatrix = Pysparse.csr_matrix((data,col,row), shape=(borderData["ROWCOUNT"],borderData["COLCOUNT"]), dtype=Int64)
    denseMatrix = pycall(csrBorderMatrix["toarray"],PyAny)

    cscBoundaryMat = sparse(denseMatrix)

    return cscBoundaryMat
end
end
◇

```

```

"src/generateBorderMatrix.jl" 10≡
    module GenerateBorderMatrix
        """
        Module for generation of the boundary matrix
        """

        type MatrixObject
            ROWCOUNT
            COLCOUNT
            ROW
            COL
            DATA
        end

        export computeOriented3Border, writeBorder, getOriented3BorderPath

        require(string(Pkg.dir("ImagesToLARModel/src"), "/larUtils.jl"))

        import LARUtils
        using PyCall

        import JSON

        @pyimport sys
        unshift!(PyVector(pyimport("sys")["path"]), "") # Search for python modules in folder
        # Search for python modules in package folder
        unshift!(PyVector(pyimport("sys")["path"]), Pkg.dir("ImagesToLARModel/src"))
        @pyimport larcc # Importing larcc from local folder

        # Compute the 3-border operator
        function computeOriented3Border(nx, ny, nz)
            """
            Compute the 3-border matrix using a modified
            version of larcc
            """
            V, bases = LARUtils.getBases(nx, ny, nz)
            boundaryMat = larcc.signedCellularBoundary(V, bases)
            return boundaryMat
        end

        function writeBorder(boundaryMatrix, outputFile)
            """
            Write 3-border matrix on json file

```

```

boundaryMatrix: matrix to write on file
outputFile: path of the outputFile
"""

rowcount = boundaryMatrix[:shape][1]
colcount = boundaryMatrix[:shape][2]

row = boundaryMatrix[:indptr]
col = boundaryMatrix[:indices]
data = boundaryMatrix[:data]

# Writing informations on file
outfile = open(outputFile, "w")

matrixObj = MatrixObject(rowcount, colcount, row, col, data)
JSON.print(outfile, matrixObj)
close(outfile)

end

function getOriented3BorderPath(borderPath, nx, ny, nz)
    """
    Try reading 3-border matrix from file. If it fails matrix
    is computed and saved on disk in JSON format

    borderPath: path of border directory
    nx, ny, nz: image dimensions
    """

    filename = string(borderPath, "/border_", nx, "-", ny, "-", nz, ".json")
    if !isfile(filename)
        border = computeOriented3Border(nx, ny, nz)
        writeBorder(border, filename)
    end
    return filename
end
end
◇

"src/lar2Julia.jl" 11≡
module Lar2Julia
    """

```

```

larcc functions for Julia
"""
export larBoundaryChain, cscChainToCellList

import JSON

using Logging

function larBoundaryChain(cscBoundaryMat, brcCellList)
    """
    Compute boundary chains
    """

    # Computing boundary chains
    n = size(cscBoundaryMat)[1]
    m = size(cscBoundaryMat)[2]

    debug("Boundary matrix size: ", n, "\t", m)

    data = ones{Int64, length(brcCellList)}

    i = Array{Int64, length(brcCellList)}
    for k in 1:length(brcCellList)
        i[k] = brcCellList[k] + 1
    end

    j = ones{Int64, length(brcCellList)}

    debug("cscChain rows length: ", length(i))
    debug("cscChain columns length: ", length(j))
    debug("cscChain data length: ", length(brcCellList))

    debug("rows ", i)
    debug("columns ", j)
    debug("data ", data)

    cscChain = sparse(i, j, data, m, 1)
    cscmat = cscBoundaryMat * cscChain
    out = cscBinFilter(cscmat)
    return out
end

function cscBinFilter(CSCm)
    k = 1
    data = nonzeros(CSCm)
    sgArray = copysign(1, data)

```

```

while k <= nnz(CSCm)
    if data[k] % 2 == 1 || data[k] % 2 == -1
        data[k] = 1 * sgArray[k]
    else
        data[k] = 0
    end
    k += 1
end

return CSCm
end

function cscChainToCellList(CSCm)
    """
    Get a csc containing a chain and returns
    the cell list of the "+1" oriented faces
    """
    data = nonzeros(CSCm)
    # Now I need to remove zero element (problem with Julia nonzeros)
    nonzeroData = Array{Int64, 0}
    for n in data
        if n != 0
            push!(nonzeroData, n)
        end
    end

    cellList = Array{Int64, 0}
    for (k, theRow) in enumerate(findn(CSCm)[1])
        if nonzeroData[k] == 1
            push!(cellList, theRow)
        end
    end
    return cellList
end
end
◇

```

```

"src/larUtils.jl" 13≡
module LARUtils
    """
    Utility functions for extracting 3d models from images
    """

```

```

export ind, invertIndex, getBases

function ind(x, y, z, nx, ny)
    """
    Transform coordinates into linearized matrix indexes
    """
    return x + (nx+1) * (y + (ny+1) * (z))
end

function invertIndex(nx,ny,nz)
    """
    Invert indexes
    """
    nx, ny, nz = nx + 1, ny + 1, nz + 1
    function invertIndex0(offset)
        a0, b0 = trunc(offset / nx), offset % nx
        a1, b1 = trunc(a0 / ny), a0 % ny
        a2, b2 = trunc(a1 / nz), a1 % nz
        return b0, b1, b2
    end
    return invertIndex0
end

function getBases(nx, ny, nz)
    """
    Compute all LAR relations
    """

    function the3Dcell(coords)
        x,y,z = coords
        return [ind(x,y,z,nx,ny),ind(x+1,y,z,nx,ny),ind(x,y+1,z,nx,ny),ind(x,y,z+1,nx,ny),ind(x+1,y,z+1,nx,ny),ind(x,y+1,z+1,nx,ny),ind(x+1,y+1,z+1,nx,ny)]
    end

    # Calculating vertex coordinates (nx * ny * nz)
    V = Array{Int64}[]
    for z in 0:nz
        for y in 0:ny
            for x in 0:nx
                push!(V,[x,y,z])
            end
        end
    end
end

```

```

# Building CV relationship
CV = Array{Int64}[]
for z in 0:nz-1
    for y in 0:ny-1
        for x in 0:nx-1
            push!(CV,the3Dcell([x,y,z]))
        end
    end
end

# Building FV relationship
FV = Array{Int64}[]
v2coords = invertIndex(nx,ny,nz)

for h in 0:(length(V)-1)
    x,y,z = v2coords(h)

    if (x < nx) && (y < ny)
        push!(FV, [h,ind(x+1,y,z,nx,ny),ind(x,y+1,z,nx,ny),ind(x+1,y+1,z,nx,ny)])
    end

    if (x < nx) && (z < nz)
        push!(FV, [h,ind(x+1,y,z,nx,ny),ind(x,y,z+1,nx,ny),ind(x+1,y,z+1,nx,ny)])
    end

    if (y < ny) && (z < nz)
        push!(FV, [h,ind(x,y+1,z,nx,ny),ind(x,y,z+1,nx,ny),ind(x,y+1,z+1,nx,ny)])
    end

end

# Building VV relationship
VV = map((x)->[x], 0:length(V)-1)

# Building EV relationship
EV = Array{Int64}[]
for h in 0:length(V)-1
    x,y,z = v2coords(h)
    if (x < nx)
        push!(EV, [h,ind(x+1,y,z,nx,ny)])
    end
    if (y < ny)
        push!(EV, [h,ind(x,y+1,z,nx,ny)])
    end
    if (z < nz)

```

```

        push!(EV, [h,ind(x,y,z+1,nx,ny)])
    end
end

# return all basis
return V, (VV, EV, FV, CV)
end
end
◇

```

```

"src/model2Obj.jl" 16≡
module Model2Obj
"""
Module that takes a 3d model and write it on
obj files
"""

require(string(Pkg.dir("ImagesToLARModel/src"), "/larUtils.jl"))

import LARUtils

using Logging

export writeToObj, mergeObj, computeModel

function lessThanVertices(v1, v2)
"""
Utility function for comparing vertices coordinates
"""

if v1[1] == v2[2]
    if v1[2] == v2[2]
        return v1[3] < v2[3]
    end
    return v1[2] < v2[2]
end
return v1[1] < v2[2]
end

function removeDoubleVerticesAndFaces(V, FV, facesOffset)
"""
Removes double vertices and faces from a LAR model

```



```

V: Array containing all vertices
FV: Array containing all faces
facesOffset: offset for faces indices
"""

newV, indices = removeDoubleVertices(V)
reindexedFaces = reindexVerticesInFaces(FV, indices, facesOffset)
newFV = unique(FV)

return newV, newFV

end

function removeDoubleVertices(V)
    """
    Remove double vertices from a LAR model

    V: Array containing all vertices of the model
    """

    # Sort the vertices list and returns the ordered indices
    orderedIndices = sortperm(V, lt = lessThanVertices, alg=MergeSort)

    orderedVerticesAndIndices = collect(zip(sort(V, lt = lessThanVertices),
                                             orderedIndices))

    newVertices = Array{Array{Int}, 0}
    indices = zeros{Int, length(V)}
    prevv = Nothing
    i = 1
    for (v, ind) in orderedVerticesAndIndices
        if v == prevv
            indices[ind] = i - 1
        else
            push!(newVertices, v)
            indices[ind] = i
            i += 1
            prevv = v
        end
    end
    return newVertices, indices
end

function reindexVerticesInFaces(FV, indices, offset)
    """
    Reindex vertices indexes in faces array

```

```

FV: Faces array of the LAR model
indices: new Indices for faces
offset: offset for faces indices
"""

for f in FV
    for i in 1: length(f)
        f[i] = indices[f[i] - offset] + offset
    end
end
return FV
end

function computeModel(imageDx, imageDy, imageDz,
                     xStart, yStart, zStart,
                     facesOffset, objectBoundaryChain)
    """
    Takes the boundary chain of a part of the entire model
    and returns a LAR model

    imageDx, imageDy, imageDz: Boundary dimensions
    xStart, yStart, zStart: Offset of this part of the model
    facesOffset: Offset for the faces
    objectBoundaryChain: Sparse csc matrix containing the cells
    """

    V, bases = LARUtils.getBases(imageDx, imageDy, imageDz)
    FV = bases[3]

    V_model = Array{Array{Int}, 0}()
    FV_model = Array{Array{Int}, 0}()

    vertex_count = 1

    #b2cells = Lar2Julia.cscChainToCellList(objectBoundaryChain)
    # Get all cells (independently from orientation)
    b2cells = findn(objectBoundaryChain)[1]

    debug("b2cells = ", b2cells)

    for f in b2cells
        old_vertex_count = vertex_count
        for vtx in FV[f]
            push!(V_model, [convert{Int}(V[vtx + 1][1] + xStart),
                           convert{Int64}(V[vtx + 1][2] + yStart),

```

```

        convert(Int64, V[vtx + 1][3] + zStart]))
    vertex_count += 1
end

    push!(FV_model, [old_vertex_count + facesOffset, old_vertex_count + 1 + facesOffset, old_v
    push!(FV_model, [old_vertex_count + facesOffset, old_vertex_count + 3 + facesOffset, old_v
end

# Removing double vertices
return removeDoubleVerticesAndFaces(V_model, FV_model, facesOffset)

end

function writeToObj(V, FV, outputFilename)
    """
    Take a LAR model and write it on obj file

    V: array containing vertices coordinates
    FV: array containing faces
    outputFilename: prefix for the output files
    """

    outputVtx = string(outputFilename, "_vtx.stl")
    outputFaces = string(outputFilename, "_faces.stl")

    fileVertex = open(outputVtx, "w")
    fileFaces = open(outputFaces, "w")

    for v in V
        write(fileVertex, "v ")
        write(fileVertex, string(v[1], " "))
        write(fileVertex, string(v[2], " "))
        write(fileVertex, string(v[3], "\n"))
    end

    for f in FV

        write(fileFaces, "f ")
        write(fileFaces, string(f[1], " "))
        write(fileFaces, string(f[2], " "))
        write(fileFaces, string(f[3], "\n"))
    end

    close(fileVertex)
    close(fileFaces)

```

```

end

function mergeObj(modelDirectory)
    """
    Merge stl files in a single obj file

    modelDirectory: directory containing models
    """

    files = readdir(modelDirectory)
    vertices_files = files[find(s -> contains(s,string("_vtx.stl")), files)]
    faces_files = files[find(s -> contains(s,string("_faces.stl")), files)]
    obj_file = open(string(modelDirectory, "/", "model.obj"), "w") # Output file

    vertices_counts = Array{Int64, length(vertices_files)}
    number_of_vertices = 0
    for i in 1:length(vertices_files)
        vtx_file = vertices_files[i]
        f = open(string(modelDirectory, "/", vtx_file))
        debug("Opening ", vtx_file)

        # Writing vertices on the obj file
        for ln in eachline(f)
            write(obj_file, ln)
            number_of_vertices += 1
        end
        # Saving number of vertices
        vertices_counts[i] = number_of_vertices
        close(f)
    end

    for i in 1 : length(faces_files)
        faces_file = faces_files[i]
        f = open(string(modelDirectory, "/", faces_file))
        debug("Opening ", faces_file)
        for ln in eachline(f)
            splitted = split(ln)
            write(obj_file, "f ")
            if i > 1
                write(obj_file, string(parse(splitted[2]) + vertices_counts[i - 1], " "))
                write(obj_file, string(parse(splitted[3]) + vertices_counts[i - 1], " "))
                write(obj_file, string(parse(splitted[4]) + vertices_counts[i - 1]))
            else
                write(obj_file, string(splitted[2], " "))
                write(obj_file, string(splitted[3], " "))
                write(obj_file, splitted[4])
            end
        end
    end
end

```

```

        end
        write(obj_file, "\n")
    end
    close(f)
end
close(obj_file)

# Removing all tmp files
for vtx_file in vertices_files
    rm(string(modelDirectory, "/", vtx_file))
end

for fcs_file in faces_files
    rm(string(modelDirectory, "/", fcs_file))
end

end
end
◇

```

```

"src/pngStack2Array3dJulia.jl" 21≡
module PngStack2Array3dJulia

    """
    This module loads a stack of png files returning
    an array of pixel values divided into segments
    """

    export calculateClusterCentroids, pngstack2array3d, getImageData, convertImages

    using Images # For loading png images
    using Colors # For grayscale images
    using PyCall # For including python clustering
    using Logging
    @pyimport scipy.ndimage as ndimage
    @pyimport scipy.cluster.vq as cluster

    NOISE_SHAPE_DETECT=10

    function getImageData(imageFile)
        """
        Get width and height from a png image
        """
    end
end

```

```

input = open(imageFile, "r")
data = readbytes(input, 24)

if (data[2:4] != [80, 78, 71] && data[13:16] != [73, 72, 68, 82])
    error("This is not a png image")
end

w = data[17:20]
h = data[21:24]

width = reinterpret{Int32, reverse(w)}[1]
height = reinterpret{Int32, reverse(h)}[1]

close(input)

return width, height
end

function calculateClusterCentroids(path, image, numberOfClusters = 2)
    """
    Loads an image and calculate cluster centroids for segmentation

    path: Path of the image folder
    image: name of the image
    numberOfClusters: number of desired clusters
    """
    imageFilename = string(path, image)

    img = imread(imageFilename) # Open png image with Julia Package

    rgb_img = convert{Image{ColorTypes.RGB}}, img)
    gray_img = convert{Image{ColorTypes.Gray}}, rgb_img)
    imArray = raw(gray_img)

    imageWidth = size(imArray)[1]
    imageHeight = size(imArray)[2]

    # Getting pixel values and saving them with another shape
    image3d = Array{Array{UInt8,2}, 0}

    # Inserting page on another list and reshaping
    push!(image3d, imArray)
    pixel = reshape(image3d[1], (imageWidth * imageHeight), 1)

    # Segmenting image using kmeans

```

```

# https://en.wikipedia.org/wiki/Image_segmentation#Clustering_methods

centroids,_ = cluster.kmeans(pixel, numberOfClusters)

return centroids

end

function pngstack2array3d(path, minSlice, maxSlice, centroids)
    """
    Import a stack of PNG images into a 3d array

    path: path of images directory
    minSlice and maxSlice: number of first and last slice
    centroids: centroids for image segmentation
    """

    # image3d contains all images values
    image3d = Array{Array{UInt8,2}, 0}

    debug("maxSlice = ", maxSlice, " minSlice = ", minSlice)
    files = readdir(path)

    for slice in minSlice : (maxSlice - 1)
        debug("slice = ", slice)
        imageFilename = string(path, files[slice + 1])
        debug("image name: ", imageFilename)
        img = imread(imageFilename) # Open png image with Julia Package

        # Converting image in grayscale
        rgb_img = convert{ColorTypes.Gray}(Image{ColorTypes.RGB}, img)
        gray_img = convert{ColorTypes.Gray}(Image{ColorTypes.Gray}, rgb_img)
        imArray = raw(gray_img) # Putting pixel values into RAW 3d array
        debug("imArray size: ", size(imArray))

        # Inserting page on another list and reshaping
        push!(image3d, imArray)
    end

    # Removing noise using a median filter and quantization
    for page in 1:length(image3d)

        # Denoising
        image3d[page] = ndimage.median_filter(image3d[page], NOISE_SHAPE_DETECT)
    end
end

```

```

# Image Quantization
debug("page = ", page)
debug("image3d[page] dimensions: ", size(image3d[page])[1], "\t", size(image3d[page])[2])
pixel = reshape(image3d[page], size(image3d[page])[1] * size(image3d[page])[2] , 1)
qnt,_ = cluster.vq(pixel,centroids)

# Reshaping quantization result
centers_idx = reshape(qnt, size(image3d[page],1), size(image3d[page],2))
#centers_idx = reshape(qnt, size(image3d[page]))

# Inserting quantized values into 3d image array
tmp = Array{UInt8, size(image3d[page],1), size(image3d[page],2)}

for j in 1:size(image3d[1],2)
    for i in 1:size(image3d[1],1)
        tmp[i,j] = centroids[centers_idx[i,j] + 1]
    end
end

image3d[page] = tmp

end

return image3d
end

function convertImages(inputPath, outputPath, bestImage)
    """
    Get all images contained in inputPath directory
    saving them in outputPath directory in png format.
    If images have one of two odd dimensions, they will be resized
    and if folder contains an odd number of images another one will be
    added

    inputPath: Directory containing input images
    outputPath: Temporary directory containing png images
    bestImage: Image chosen for centroids computation

    Returns the new name for the best image
    """

    imageFiles = readdir(inputPath)
    numberOfImages = length(imageFiles)
    outputPrefix = ""
    for i in 1: length(string(numberOfImages)) - 1

```



```

    outputPrefix = string(outputPrefix,"0")
end

newBestImage = ""
imageNumber = 0
for imageFile in imageFiles
    img = imread(string(inputPath, imageFile))

    # resizing images if they do not have even dimensions
    dim = size(img)
    if(dim[1] % 2 != 0)
        debug("Image has odd x; resizing")
        xrange = 1: dim[1] - 1
    else
        xrange = 1: dim[1]
    end

    if(dim[2] % 2 != 0)
        debug("Image has odd y; resizing")
        yrange = 1: dim[2] - 1
    else
        yrange = 1: dim[2]
    end

    img = subim(img, xrange, yrange)

    outputFilename = string(outputPath, outputPrefix[length(string(imageNumber)):end], imageNumber, ".png")
    imwrite(img, outputFilename)

    # Searching the best image
    if(imageFile == bestImage)
        newBestImage = string(outputPrefix[length(string(imageNumber)):end], imageNumber, ".png")
    end

    imageNumber += 1
end

# Adding another image if they are odd
if(numberOfImages % 2 != 0)
    debug("Odd images, adding one")
    bestImage = imread(string(outputPath, "/", newBestImage))
    imArray = zeros(UInt8, size(bestImage))
    img = grayim(imArray)
    outputFilename = string(outputPath, "/", outputPrefix[length(string(imageNumber)):end], imageNumber, ".png")
    imwrite(img, outputFilename)
end

```

```

    return newBestImage
end

end
◇

```

2.1 Installing the library

3 Conclusions

3.1 Results

3.2 Further improvements

References

[CL13] CVD-Lab, *Linear algebraic representation*, Tech. Report 13-00, Roma Tre University, October 2013.

A Utility functions

B Tests

Generation of the border matrix

```

"test/generateBorderMatrix.jl" 26≡
push!(LOAD_PATH, "../..")
import GenerateBorderMatrix
import JSON
using Base.Test

function testComputeOriented3Border()
    """
    Test function for computeOriented3Border
    """
    boundaryMatrix = GenerateBorderMatrix.computeOriented3Border(2,2,2)

    rowcount = boundaryMatrix[:shape][1]
    @test rowcount == 36
    colcount = boundaryMatrix[:shape][2]

```


Conversion of a png stack to a 3D array

```
"test/pngStack2Array3dJulia.jl" 27≡
push!(LOAD_PATH, "../..")
import PngStack2Array3dJulia
using Base.Test

function testGetImageData()
    """
    Test function for getImageData
    """

    width, height = PngStack2Array3dJulia.getImageData("images/0.png")

    @test width == 50
    @test height == 50

end

function testCalculateClusterCentroids()
    """
    Test function for calculateClusterCentroids
    """

    path = "images/"
    image = 0
    centroids = PngStack2Array3dJulia.calculateClusterCentroids(path, image, 2)

    expected = [0, 253]
    centroids = vec(reshape(centroids, 1, 2))

    @test sort(centroids) == expected
end

function testPngstack2array3d()
    """
    Test function for pngstack2array3d
    """

    path = "images/"
    minSlice = 0
    maxSlice = 4
    centroids = PngStack2Array3dJulia.calculateClusterCentroids(path, 0, 2)
    image3d = PngStack2Array3dJulia.pngstack2array3d(path, minSlice, maxSlice, centroids)

    @test size(image3d)[1] == 5
    @test size(image3d[1])[1] == 50
    @test size(image3d[1])[2] == 200
end
```

```

end

function executeAllTests()
    @time testCalculateClusterCentroids()
    @time testPngstack2array3d()
    @time testGetImageData()
    println("Tests completed.")
end

executeAllTests()

◇

```

Test for LAR utilities

```

"test/LARUtils.jl" 29≡
push!(LOAD_PATH, "../..")
import LARUtils
using Base.Test

function testInd()
    """
    Test function for ind
    """

    nx = 2
    ny = 2

    @test LARUtils.ind(0, 0, 0, nx, ny) == 0
    @test LARUtils.ind(1, 1, 1, nx, ny) == 13
    @test LARUtils.ind(2, 5, 4, nx, ny) == 53
    @test LARUtils.ind(1, 1, 1, nx, ny) == 13
    @test LARUtils.ind(2, 7, 1, nx, ny) == 32
    @test LARUtils.ind(1, 0, 3, nx, ny) == 28
end

function executeAllTests()
    @time testInd()
    println("Tests completed.")
end

executeAllTests()

◇

```

