

EX 6

1.

try to solve the problem of dimensionality reduction
feature extraction and comprehension visualization

2.

3	3	3
E	3	m

we try to $\mathbb{R}^{w \times h \times d} \rightarrow \mathbb{R}^3$

we have $36 \times 36 \times 3$ RGB images
the dimensionality reduction of dataset is
 $36 \times 36 \times 3$ but the intrinsic parameter
are 3 2 for transmission one for

notation go with dimensionality reduction

ML EXAMS 16/01/2023

EX. 1

1.1

if $C = C_1$ and $B = b_1$ then NO ①

if $C = C_1$ and $B = b_2$ then YES ②

if $C = C_2$ and $A = a_1$ then YES ③

if $C = C_2$ and $A = a_2$ and $B = b_1$ then YES ④

if $C = C_2$ and $A = a_2$ and $B = b_2$ then YES ⑤

if $C = C_2$ and $A = a_3$ then NO ⑥

if $C = C_3$ then NO ⑦

1.2

S_1 is comintent because of ②

S_2 is comintent because of ④

S_3 is comintent because of ⑦

S_4 is NOT comintent because of ②

1.3

accuracy $\frac{3}{4} = \frac{\text{number of comintent instances}}{\text{number of all instances}} = 0.75$

EX.2

2.1

LOGISTIC REGRESSION is a probabilistic discriminative model based on maximum likelihood

Consider a dataset with two classes $D = \{(x_n, t_n)\}_{n=1}^N$ $t_n \in \{0, 1\}$
likelihood function:

$$p(t|\tilde{\omega}) = \prod_{n=1}^N y_n^{t_n} (1-y_n)^{1-t_n}$$

$$\text{with } y_n = p(z| \tilde{x}_n)$$

where t_n is the value in the dataset corresponding to x_n

y_n : is the posterior of the current model $\tilde{\omega}$ to x_n

cross-entropy error function (negative log-likelihood)

$$E(\tilde{\omega}) = -\ln(p(t|\tilde{\omega})) = -\sum_{n=1}^N [t_n \ln(y_n) + (1-t_n) \ln(1-y_n)]$$

what we are try to do with logistic regression is to minimize $E(\tilde{\omega})$

$$\tilde{\omega}^* = \underset{\tilde{\omega}}{\operatorname{argmin}} (E(\tilde{\omega}))$$

2.2

compute prediction with $\tilde{\omega}_1 = (2, 0, -2)$ for the first point

$$\tilde{\omega}_1^\top x_i = 2 \cdot 0 + 0 \cdot 0 + (-2 \cdot 1) = -2$$

the sigmoid of $-2 \approx 0$

now for the second point

$$\tilde{\omega}_1^\top x_i = 2 \cdot 1 + 0 \cdot 2 + (-2 \cdot 3) = -4$$

the sigmoid of $-4 \approx 0$

now for the third function

$$\tilde{\omega}_1^\top x_i = 2 \cdot 4 + 0 \cdot 4 + (-2 \cdot 1) = 2$$

the sigmoid of $2 \approx 1$

so the result is $(0, 0, 1)$ that are the exact point of target

now we do the same for $\tilde{\omega}_2 = (-2, -2, 0)$

$$\tilde{\omega}_2^\top x_i = -2 \cdot 0 + -2 \cdot 0 + 1 \cdot 4 = 4 \rightarrow 1$$

$$\tilde{\omega}_2^\top x_i = -2 \cdot 1 + -2 \cdot 2 + 4 \cdot 3 = 6 \rightarrow 1$$

$$\tilde{\omega}_2^\top x_i = -2 \cdot 4 + -2 \cdot 4 + 1 \cdot 4 = -12 \rightarrow 0$$

$\tilde{\omega}_2$ fits ~~best~~ better the solution

EX 3

3.1

the model of one step MDP is $\langle \{x_0\}, A, S, R \rangle$ where

$\{x_0\}$ = unique state

A = finite set of actions

S = transition function $f: X \times A \rightarrow X$

R = reward function $R(x)$

optimal policy $\pi^*(x_0) = a_i$

3.2

as π^* before the solution for the problem is an optimal

policy $\pi^*(x_0) = a_i$

and π^* is optimal if and only if any other policy π

$$\text{and } \pi^* \quad V^\pi(x) > V^\pi(x) \quad \forall x$$

and $V^\pi(x) = E(R_1 + \gamma R_2 + \gamma^2 R_3 + \dots)$ is cumulative discount reward where γ is discount factor

3.3

because we have a stochastic behavior and unknown reward function
the algorithm is

1. for each $a_i \in A$

- execute a_i and collect reward r_{ci}

2. Optimal policy $\pi^*(x_0) = a_i$ with $i = \underset{i=1 \dots |A|}{\operatorname{argmax}} r_{ci}$

non tengo cuenta de
cada otra accion

we need exactly $|A|$ iterations

1. initialize $\Theta_{(0)}[i] \leftarrow 0$ and $c(i) \leftarrow 0$ for $i = 1, \dots, |A|$

2. for each time $t = 1, \dots, T$ until termination condition

- choose an action a

- execute a and collect reward r_{ct}

- increment $c(t)$

- update $\Theta_{(t+1)}[i] \leftarrow \frac{1}{c(t)} (r_{ct} + (c(t)-1) \Theta_{(t-1)}[i])$

3 optimal policy $\pi^*(x_0) = a_i$ with $i = \underset{i=1 \dots |A|}{\operatorname{argmax}} \Theta_{(T)}[i]$

for choose the action we can use an algorithm like ϵ -greedy
where $0 \leq \epsilon \leq 1$

$\epsilon \rightarrow$ random action

1- $\epsilon \rightarrow$ best action

EX 4

A.1

$$\text{※ panomo} = 7 \times 7 \times 3 \times 3 + 3 = 740$$

A.2

$$W_{\text{out}} = 128 - \frac{7}{1} + 2 \cdot 1 + 1 = 124$$

$$h_{\text{out}} = 128 - \frac{7}{1} + 2 \cdot 1 + 1 = 124$$

A.3

feature map 64 consider ~~case~~ case \rightarrow ~~case~~ case \rightarrow ~~case~~ case

kernel dimension 3×3 ~~case~~ image in input $32 \times 32 \times 3$
feature

$$\text{※ panomo} : 3 \times 3 \times 3 \times 64 + 64$$

EX 5

5.1

SVM aims to maximum margin for better accuracy gaining more in detail a margin is defined as: $\frac{\|y(x_n)\|}{\|w\|}$ no the goal of SVM is given data and an hyperplane w

$$\min_{m=1, \dots, N} \frac{\|y(x_n)\|}{\|w\|} = \dots = \frac{1}{\|w\|} \min_{n=1, \dots, N} [t_n (w^T x_n + x_0)]$$

no own goal in

$$w^*, w_0 = \underset{w, w_0}{\text{anymax}} \frac{1}{\|w\|} \min_{n=1, \dots, N} [t_n (w^T x_n + x_0)]$$

In the canonical formulation of the problem the maximum margin hyperplane can be seen as an optimization problem

$$w^*, w_0 = \underset{w, w_0}{\text{anymax}} \frac{1}{\|w\|} = \underset{w, w_0}{\text{anymin}} \frac{1}{2} \|w\|^2$$

this can be solved by using Lagrangian multipliers:

$$w^* = \sum_{n=1}^N \alpha_n^* t_n x_n$$

considering also support vectors $SV = \{x_k \in D \mid t_k y(x_k) = 1\}$
we obtain:

$$w_0 = \frac{1}{|SV|} \sum_{k \in SV} \left(t_k - \sum_{j \in S} \alpha_j^* t_j x_k^T x_j \right)$$

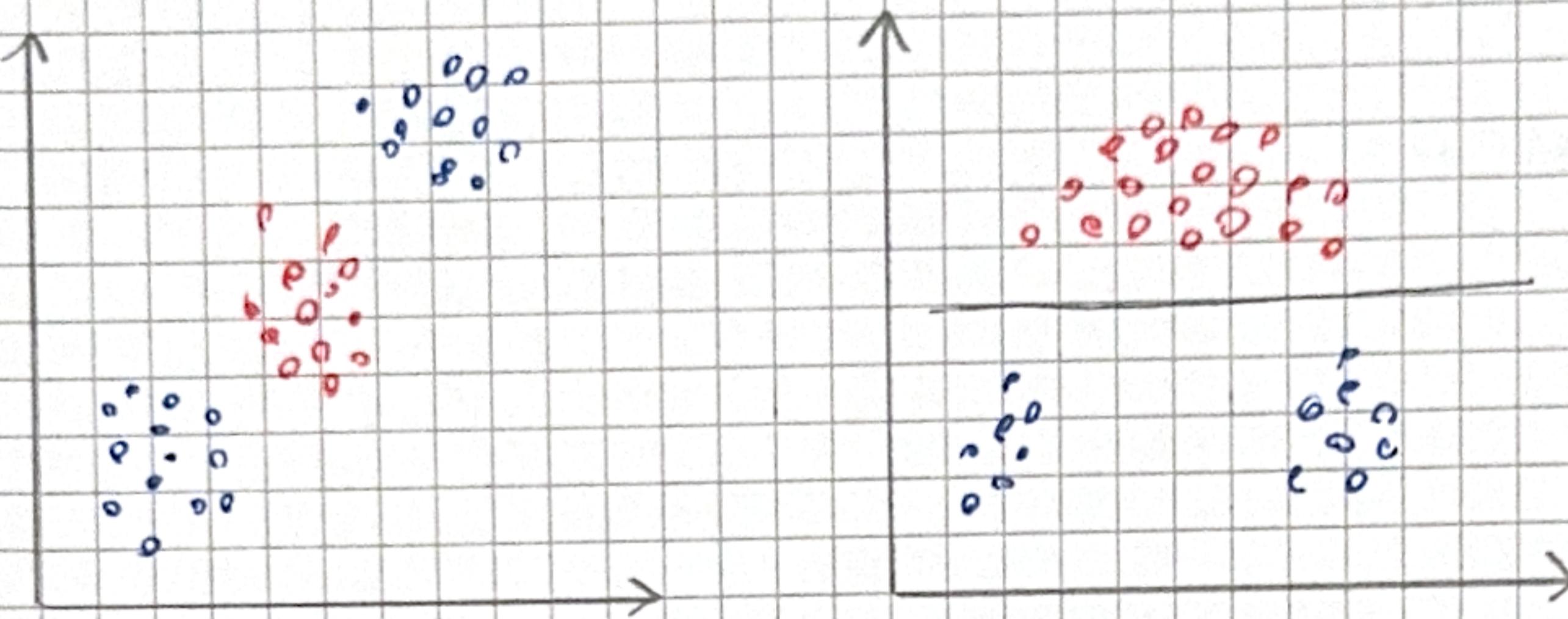
②

if we consider non linear sum we can use kernel trick that mean
 non linear inner product $x^T x$ with kernel $K(x, x')$
 so we will have (consider polynomial kernel)

$$w_0 = \frac{1}{|SV|} \sum_{x_i \in SV} (t_k - \sum_{x_j \in S} \alpha_j t_j K(x_i, x_j))$$

$$y(x, w^*) = \text{argmax } (w_0 + \sum_{n=1}^N \alpha_n (\beta x^T x + \gamma)^d)$$

§ 2



EX. 6

② 6.2

VOTING

given a dataset D

1. use D to train a set of models $y_m(x)$

for $m = 1, \dots, M$

2. make predictions with

$$y_{\text{voting}}(x) = \sum_{m=1}^M w_m y_m(x)$$

$$y_{\text{voting}}(x) = \underset{C}{\text{argmax}} \sum_{m=1}^M w_m \mathbb{I}(y_m(x) = C)$$

$$\mathbb{I}(e) = \begin{cases} 1 & \text{if } e = \text{true} \\ 0 & \text{otherwise} \end{cases}$$

voting on all dataset by generating

M bootstrap from dataset.

6.1

BAGGING

given a dataset D

1. use D to train a set of models

2. generate M bootstrap D₁, ..., D_M

3. use each of model's dataset to train model

3. make prediction using voting scheme

$$y_{\text{bagging}}(x) = \frac{1}{M} \sum_{m=1}^M y_m(x)$$