PRACTICA 2

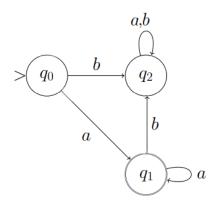
Daniel Márquez Polonio

1 ACTIVIDADES

DESCRIPCIÓN DEL AUTÓMATA

Sea
$$M = (\{q_0, q_1, q_2\}, \{a, b\}, \delta, q_0, \{q_1\})$$
 un DFA con:

$\delta(q,\sigma)$	a	b
q_0	q_1	q_2
q_1	q_1	q_2
q_2	q_2	q_2



$$(q_0, a) \vdash (q_1, E) \land q_1 \in F \Rightarrow a \in L(M)$$

$$(q_0, aaa) \vdash (q_1, aa) \vdash (q_1, a) \vdash (q_1, E) \land q_1 \in F \Rightarrow aaa \in L(M)$$

$$(q_0,aab) \vdash (q_1,ab) \vdash (q_1,b) \vdash (q_2,E) \land q_2 \notin F \Rightarrow aab \notin L(M)$$

AUTÓMATA EN JFLAP

