



CHAPTER 2

ARRAYS AND STRUCTURES

All the programs in this file are selected from

Ellis Horowitz, Sartaj Sahni, and Susan Anderson-Freed
“Fundamentals of Data Structures in C”,
Computer Science Press, 1992.



Arrays

Array: a set of **index** and **value**

data structure

For each index, there is a value associated with that index.

representation (possible)

implemented by using consecutive memory.

Structure *Array* is

objects: A set of pairs $\langle index, value \rangle$ where for each value of *index* there is a value from the set *item*. *Index* is a finite ordered set of one or more dimensions, for example, $\{0, \dots, n-1\}$ for one dimension, $\{(0,0),(0,1),(0,2),(1,0),(1,1),(1,2),(2,0),(2,1),(2,2)\}$ for two dimensions, etc.

Functions:

for all $A \in \text{Array}$, $i \in \text{index}$, $x \in \text{item}$, $j, \text{size} \in \text{integer}$

Array Create(j, list) ::= **return** an array of *j dimensions* where *list* is a *j-tuple* whose *ith element* is the *size* of the *ith dimension*. *Items* are undefined.

Item Retrieve(A, i) ::= **if** ($i \in \text{index}$) **return** the item associated with index value *i* in array *A*
else return error

Array Store(A, i, x) ::= **if** ($i \in \text{index}$)
return an array that is identical to array *A* except the new pair $\langle i, x \rangle$ has been inserted **else return error**

end array

*Structure 2.1: Abstract Data Type *Array* (p.50)



Arrays in C

```
int list[5], *plist[5];
```

list[5]: five integers

list[0], list[1], list[2], list[3], list[4]

*plist[5]: five pointers to integers

plist[0], plist[1], plist[2], plist[3], plist[4]

implementation of 1-D array

list[0] base address = α

list[1] $\alpha + \text{sizeof}(\text{int})$

list[2] $\alpha + 2 * \text{sizeof}(\text{int})$

list[3] $\alpha + 3 * \text{sizeof}(\text{int})$

list[4] $\alpha + 4 * \text{sizeof}(\text{int})$



Arrays in C *(Continued)*

Compare `int *list1` and `int list2[5]` in C.

Same: `list1` and `list2` are **pointers**.

Difference: `list2` reserves **five locations**.

Notations:

`list2` - a pointer to `list2[0]`

`(list2 + i)` - a pointer to `list2[i]` (**`&list2[i]`**)

`*(list2 + i)` - **`list2[i]`**



Example: 1-dimension array addressing

```
int one[] = {0, 1, 2, 3, 4};
```

Goal: print out address and value

```
void print1(int *ptr, int rows)
{
/* print out a one-dimensional array using a pointer */
    int i;
    printf("Address Contents\n");
    for (i=0; i < rows; i++)
        printf("%08u%05d\n", ptr+i, *(ptr+i));
    printf("\n");
}
```



call print1(&one[0], 5)

Address	Contents
1228	0
1230	1
1232	2
1234	3
1236	4

*Figure 2.1: One- dimensional array addressing (p.53)



Structures (records)

```
struct {  
    char name[10];  
    int age;  
    float salary;  
} person;
```

```
strcpy(person.name, "james");  
person.age=10;  
person.salary=35000;
```




Create structure data type

```
typedef struct human_being {  
    char name[10];  
    int age;  
    float salary;  
};
```

or

```
typedef struct {  
    char name[10];  
    int age;  
    float salary;  
} human_being;
```

```
human_being person1, person2;
```



Unions

Similar to struct, but only one field is active.

Example: Add fields for male and female.

```
typedef struct sex_type {  
    enum tag_field {female, male} sex;  
    union {  
        int children;  
        int beard;  
    } u;  
};
```

```
typedef struct human_being {  
    char name[10];  
    int age;  
    float salary;  
    date dob;  
    sex_type sex_info;  
}
```

```
human_being person1, person2;  
person1.sex_info.sex=male;  
person1.sex_info.u.beard=FALSE;
```

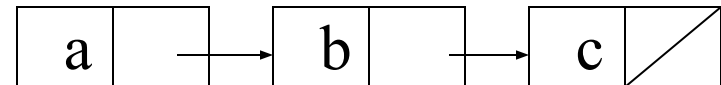
Self-Referential Structures

One or more of its components is a pointer to itself.

```
typedef struct list {  
    char data;  
    list *link;  
}
```

Construct a list with three nodes
item1.link=&item2;
item2.link=&item3;
malloc: obtain a node

```
list item1, item2, item3;  
item1.data='a';  
item2.data='b';  
item3.data='c';  
item1.link=item2.link=item3.link=NULL;
```





Ordered List Examples

ordered (linear) list: (item1, item2, item3, ..., item n)

- (MONDAY, TUESDAY, WEDNESDAY, THURSDAY, FRIDAY, SATURDAY, SUNDAY)
- (2, 3, 4, 5, 6, 7, 8, 9, 10, Jack, Queen, King, Ace)
- (1941, 1942, 1943, 1944, 1945)
- ($a_1, a_2, a_3, \dots, a_{n-1}, a_n$)



Operations on Ordered List

- Find the length, n , of the list.
 - Read the items from left to right (or right to left).
 - Retrieve the i 'th element.
 - Store a new value into the i 'th position.
 - Insert a new element at the position i , causing elements numbered $i, i+1, \dots, n$ to become numbered $i+1, i+2, \dots, n+1$
 - Delete the element at position i , causing elements numbered $i+1, \dots, n$ to become numbered $i, i+1, \dots, n-1$
- array (sequential mapping)? (1)~(4) O (5)~(6) X

Polynomials $A(X)=3X^{20}+2X^5+4$, $B(X)=X^4+10X^3+3X^2+1$

Structure *Polynomial* is

objects: $p(x) = a_1x^{e_1} + \dots + a_nx^{e_n}$; a set of ordered pairs of $\langle e_i, a_i \rangle$
where a_i in *Coefficients* and e_i in *Exponents*, e_i are integers ≥ 0

functions:

for all $poly, poly1, poly2 \in \text{Polynomial}$, $coef \in \text{Coefficients}$, $expon$

$\in \text{Exponents}$

Polynomial Zero()

::= **return** the polynomial,

$$p(x) = 0$$

Boolean IsZero($poly$)

::= **if** ($poly$) **return** *FALSE*

else return *TRUE*

Coefficient Coef($poly$, $expon$)

::= **if** ($expon \in poly$) **return** its
coefficient **else return** Zero

Exponent Lead_Exp($poly$)

::= **return** the largest exponent in

$poly$

Polynomial Attach($poly, coef, expon$) ::= **if** ($expon \in poly$) **return** error
else return the polynomial $poly$
with the term $\langle coef, expon \rangle$
inserted



Polynomial Remove(*poly*, *expon*) ::= **if** (*expon* \square *poly*) **return** the
polynomial *poly* with the
term whose exponent is *expon* deleted

else return error

Polynomial SingleMult(*poly*, *coef*, *expon*) ::= **return** the polynomial
 $poly \cdot coef \cdot x^{expon}$

Polynomial Add(*poly1*, *poly2*) ::= **return** the polynomial
 $poly1 + poly2$

Polynomial Mult(*poly1*, *poly2*) ::= **return** the polynomial
 $poly1 \cdot poly2$

End *Polynomial*

*Structure 2.2: Abstract data type *Polynomial* (p.61)

Polynomial Addition

data structure 1:

```
#define MAX_DEGREE 101
```

```
typedef struct {  
    int degree;  
    float coef[MAX_DEGREE];  
} polynomial;
```

```
/* d = a + b, where a, b, and d are polynomials */
```

```
d = Zero( )
```

```
while (! IsZero(a) && ! IsZero(b)) do {
```

```
    switch COMPARE (Lead_Exp(a), Lead_Exp(b)) {
```

```
        case -1: d =
```

```
            Attach(d, Coef (b, Lead_Exp(b)), Lead_Exp(b));
```

```
            b = Remove(b, Lead_Exp(b));
```

```
            break;
```

```
        case 0: sum = Coef (a, Lead_Exp (a)) + Coef ( b, Lead_Exp(b));
```

```
            if (sum) {
```

```
                Attach (d, sum, Lead_Exp(a));
```

```
                a = Remove(a , Lead_Exp(a));
```

```
                b = Remove(b , Lead_Exp(b));
```

```
            }
```

```
            break;
```




case 1: d =

```
    Attach(d, Coef (a, Lead_Exp(a)), Lead_Exp(a));  
    a = Remove(a, Lead_Exp(a));  
  }  
}
```

insert any remaining terms of a or b into d

advantage: easy implementation

disadvantage: waste space when sparse

*Program 2.4 :Initial version of *padd* function(p.62)

Data structure 2: use one global array to store all polynomials

$$A(X) = 2X^{1000} + 1$$

$$B(X) = X^4 + 10X^3 + 3X^2 + 1$$

*Figure 2.2: Array representation of two polynomials (p.63)

	<i>starta</i>	<i>finisha</i>	<i>startb</i>			<i>finishb</i>	<i>avail</i>
	↓	↓	↓			↓	↓
<i>coef</i>	2	1	1	10	3	1	
<i>exp</i>	1000	0	4	3	2	0	
	0	1	2	3	4	5	6

specification

poly

A

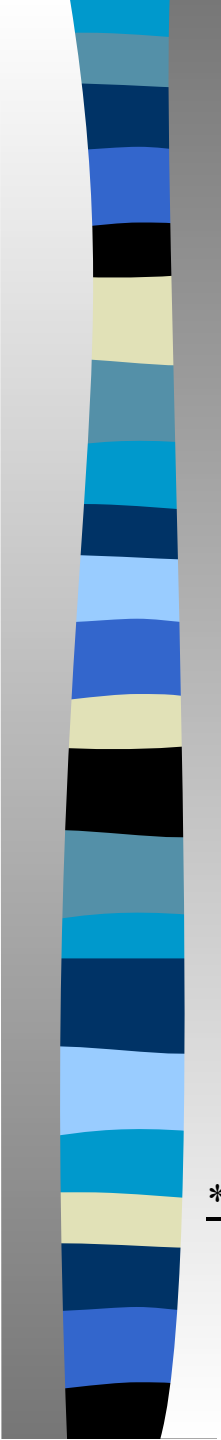
B

representation

<start, finish>

<0,1>

<2,5>



storage requirements: start, finish, $2 * (\text{finish} - \text{start} + 1)$
nonparse: twice as much as (1)
when all the items are nonzero

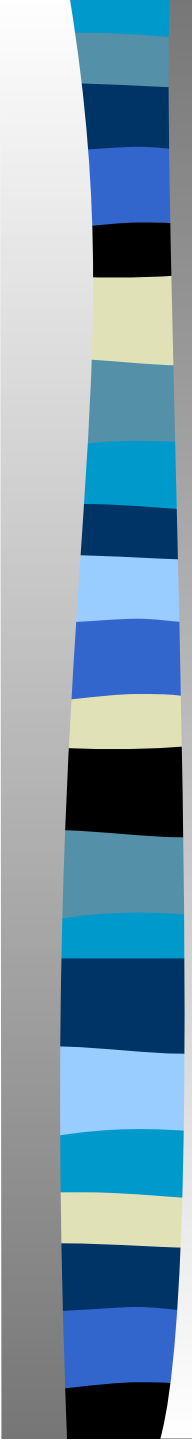
```
MAX_TERMS 100 /* size of terms array */  
typedef struct {  
    float coef;  
    int expon;  
} polynomial;  
polynomial terms[MAX_TERMS];  
int avail = 0;
```

*(p.62)

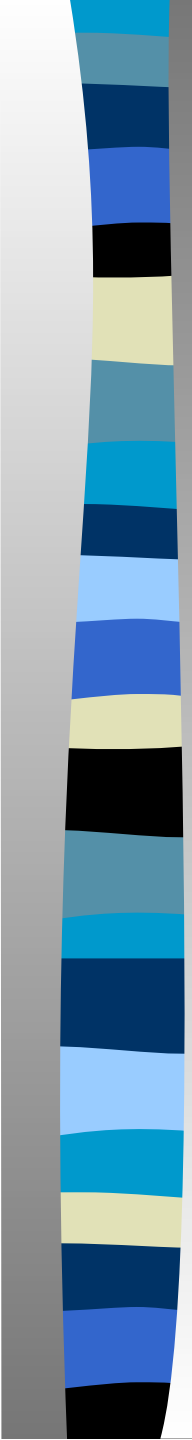


Add two polynomials: $D = A + B$

```
void padd (int starta, int finisha, int startb, int finishb,  
           int * startd, int * finishd)  
{  
    /* add A(x) and B(x) to obtain D(x) */  
    float coefficient;  
    *startd = avail;  
    while (starta <= finisha && startb <= finishb)  
        switch (COMPARE(terms[starta].expon,  
                        terms[startb].expon)) {  
        case -1: /* a expon < b expon */  
            attach(terms[startb].coef, terms[startb].expon);  
            startb++;  
            break;
```



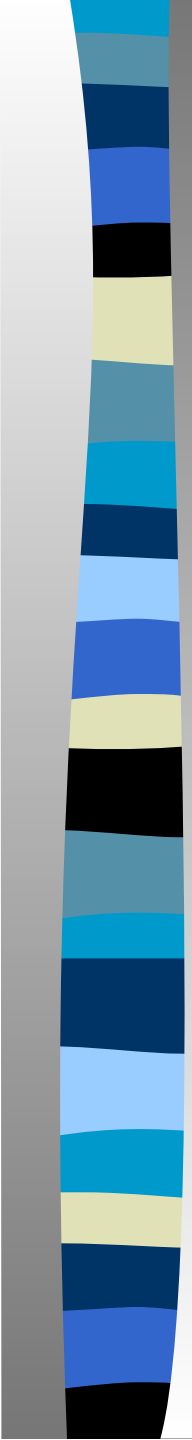
```
case 0: /* equal exponents */
    coefficient = terms[starta].coef +
                terms[startb].coef;
    if (coefficient)
        attach (coefficient, terms[starta].expon);
    starta++;
    startb++;
    break;
case 1: /* a expon > b expon */
    attach(terms[starta].coef, terms[starta].expon);
    starta++;
}
```



```
/* add in remaining terms of A(x) */
for( ; starta <= finisha; starta++)
    attach(terms[starta].coef, terms[starta].expon);
/* add in remaining terms of B(x) */
for( ; startb <= finishb; startb++)
    attach(terms[startb].coef, terms[startb].expon);
*finishd = avail - 1;
}
```

Analysis: $O(n+m)$
where n (m) is the number of nonzeros in A (B).

*Program 2.5: Function to add two polynomial (p.64)



```
void attach(float coefficient, int exponent)
{
    /* add a new term to the polynomial */
    if (avail >= MAX_TERMS) {
        fprintf(stderr, "Too many terms in the polynomial\n");
        exit(1);
    }
    terms[avail].coef = coefficient;
    terms[avail++].expon = exponent;
}
```

***Program 2.6: Function to add a new term (p.65)**

Problem: Compaction is required
 when polynomials that are no longer needed.
 (data movement takes time.)

Sparse Matrix

	col 1	col 2	col 3
row 1	-27	3	4
row 2	6	82	-2
row 3	109	-64	11
row 4	12	8	9
row 5	48	27	47

5*3

(a) 15/15

	col1	col2	col3	col4	col5	col6
row0	15	0	0	22	0	-15
row1	0	11	3	0	0	0
row2	0	0	0	-6	0	0
row3	0	0	0	0	0	0
row4	91	0	0	0	0	0
row5	0	0	28	0	0	0

6*6

(b) 8/36

***Figure 2.3: Two matrices**

sparse matrix
data structure?

SPARSE MATRIX ABSTRACT DATA TYPE

Structure *Sparse_Matrix* is

objects: a set of triples, $\langle row, column, value \rangle$, where *row* and *column* are integers and form a unique combination, and *value* comes from the set *item*.

functions:

for all $a, b \in \text{Sparse_Matrix}$, $x \in \text{item}$, i, j , max_col ,
 $max_row \in \text{index}$

Sparse_Marix **Create**(max_row, max_col) ::=

return a *Sparse_matrix* that can hold up to
 $max_items = max_row \times max_col$ and
whose maximum row size is max_row and
whose maximum column size is max_col .



Sparse_Matrix **Transpose**(a) ::=

return the matrix produced by interchanging the row and column value of every triple.

Sparse_Matrix **Add**(a, b) ::=

if the dimensions of a and b are the same
return the matrix produced by adding corresponding items, namely those with identical *row* and *column* values.
else return error

Sparse_Matrix **Multiply**(a, b) ::=

if number of columns in a equals number of rows in b
return the matrix d produced by multiplying a by b according to the formula: $d[i][j] = \sum (a[i][k] \cdot b[k][j])$ where $d(i, j)$ is the (i, j) th element
else return error.

(1) Represented by a two-dimensional array.

Sparse matrix wastes space.

(2) Each element is characterized by $\langle \text{row, col, value} \rangle$.

	row col value				row col value			
		# of rows (columns)				# of nonzero terms		
a[0]	6	6	8		b[0]	6	6	8
[1]	0	0	15		[1]	0	0	15
[2]	0	3	22		[2]	0	4	91
[3]	0	5	-15		[3]	1	1	11
[4]	1	1	11	transpose →	[4]	2	1	3
[5]	1	2	3		[5]	2	5	28
[6]	2	3	-6		[6]	3	0	22
[7]	4	0	91		[7]	3	2	-6
[8]	5	2	28		[8]	5	0	-15
(a)					(b)			

row, column in ascending order

***Figure 2.4:** Sparse matrix and its transpose stored as triples (p.69)



Sparse_matrix Create(max_row, max_col) ::=

```
#define MAX_TERMS 101 /* maximum number of terms +1 */
typedef struct {
    int col;
    int row;
    int value;
} term;
term a[MAX_TERMS]
```

↑
of rows (columns)
of nonzero terms

*(P.69)

Transpose a Matrix

(1) for each **row** i

take element $\langle i, j, \text{value} \rangle$ and store it
in element $\langle j, i, \text{value} \rangle$ of the transpose.

difficulty: where to put $\langle j, i, \text{value} \rangle$

$(0, 0, 15) \implies (0, 0, 15)$

$(0, 3, 22) \implies (3, 0, 22)$

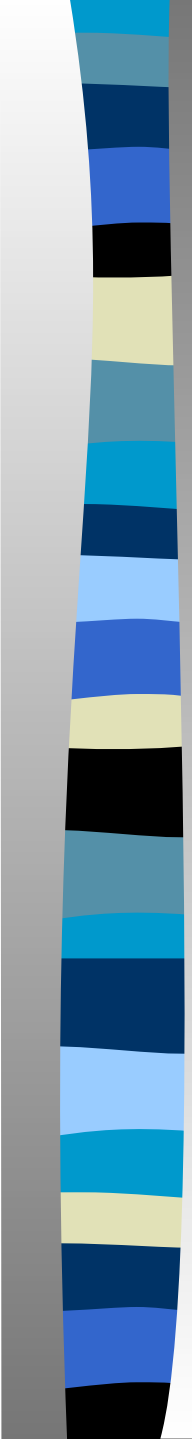
$(0, 5, -15) \implies (5, 0, -15)$

$(1, 1, 11) \implies (1, 1, 11)$

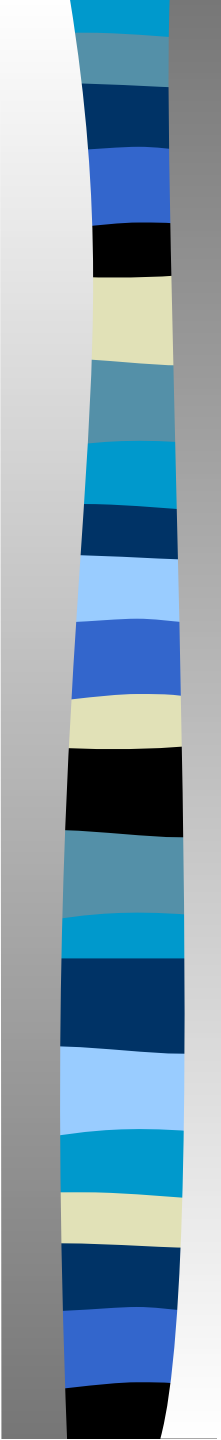
Move elements down very often.

(2) For all elements in **column** j ,

place element $\langle i, j, \text{value} \rangle$ in element $\langle j, i, \text{value} \rangle$



```
void transpose (term a[], term b[])
/* b is set to the transpose of a */
{
    int n, i, j, currentb;
    n = a[0].value; /* total number of elements */
    b[0].row = a[0].col; /* rows in b = columns in a */
    b[0].col = a[0].row; /* columns in b = rows in a */
    b[0].value = n;
    if (n > 0) { /*non zero matrix */
        currentb = 1;
        for (i = 0; i < a[0].col; i++)
            /* transpose by columns in a */
            for( j = 1; j <= n; j++)
                /* find elements from the current column */
                if (a[j].col == i) {
                    /* element is in current column, add it to b */
```



```

columns
{
    elements
    {
        b[currentb].row = a[j].col;
        b[currentb].col = a[j].row;
        b[currentb].value = a[j].value;
        currentb++;
    }
}

```

* Program 2.7: Transpose of a sparse matrix (p.71)

Scan the array “columns” times. $\implies O(\text{columns} * \text{elements})$
 The array has “elements” elements.



Discussion: compared with 2-D array representation

$O(\text{columns} * \text{elements})$ vs. $O(\text{columns} * \text{rows})$

elements \rightarrow columns * rows when nonsparse

$O(\text{columns} * \text{columns} * \text{rows})$

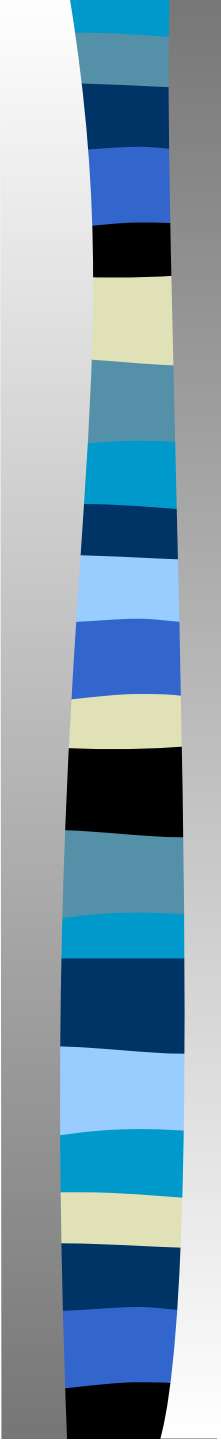
Problem: Scan the array “columns” times.

Solution:

Determine the number of elements in each column of the original matrix.

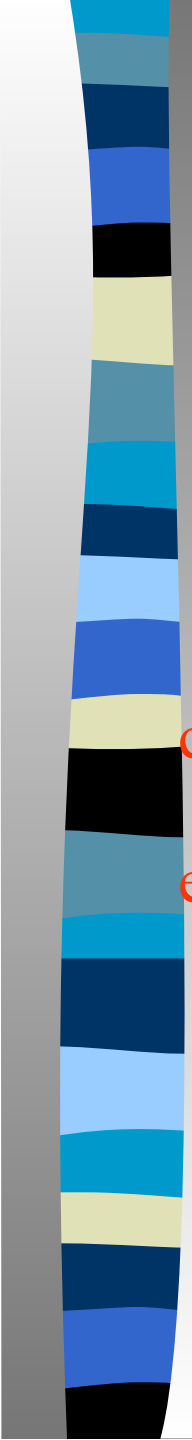
\Rightarrow

Determine the starting positions of each row in the transpose matrix.



a[0]	6	6	8
a[1]	0	0	15
a[2]	0	3	22
a[3]	0	5	-15
a[4]	1	1	11
a[5]	1	2	3
a[6]	2	3	-6
a[7]	4	0	91
a[8]	5	2	28

	[0]	[1]	[2]	[3]	[4]	[5]
row_terms =	2	1	2	2	0	1
starting_pos =	1	3	4	6	8	8



```
void fast_transpose(term a[ ], term b[ ])
{
/* the transpose of a is placed in b */
int row_terms[MAX_COL], starting_pos[MAX_COL];
int i, j, num_cols = a[0].col, num_terms = a[0].value;
b[0].row = num_cols; b[0].col = a[0].row;
b[0].value = num_terms;
if (num_terms > 0){ /*nonzero matrix*/
columns [for (i = 0; i < num_cols; i++)
          row_terms[i] = 0;
elements [for (i = 1; i <= num_terms; i++)
          row_term [a[i].col]++
          starting_pos[0] = 1;
columns [for (i = 1; i < num_cols; i++)
          starting_pos[i]=starting_pos[i-1] +row_terms [i-1];
```



elements

```
for (i=1; i <= num_terms, i++) {  
    j = starting_pos[a[i].col]++;  
    b[j].row = a[i].col;  
    b[j].col = a[i].row;  
    b[j].value = a[i].value;  
}  
}
```

*Program 2.8: Fast transpose of a sparse matrix

Compared with 2-D array representation

$O(\text{columns} + \text{elements})$ vs. $O(\text{columns} * \text{rows})$

elements \rightarrow columns * rows

$O(\text{columns} + \text{elements}) \rightarrow O(\text{columns} * \text{rows})$

Cost: Additional `row_terms` and `starting_pos` arrays are required.

Let the two arrays `row_terms` and `starting_pos` be shared.

Sparse Matrix Multiplication

Definition: $[D]_{m \times p} = [A]_{m \times n} * [B]_{n \times p}$

Procedure: Fix a row of A and find all elements in column j of B for $j=0, 1, \dots, p-1$.

Alternative 1. Scan all of B to find all elements in j.

Alternative 2. Compute the transpose of B.

(Put all column elements consecutively)

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

An Example

$$A = \begin{bmatrix} 1 & 0 & 2 \\ -1 & 4 & 6 \end{bmatrix} \quad B = \begin{bmatrix} 3 & 0 & 2 \\ -1 & 0 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$\begin{array}{ccc|ccc} 2 & 3 & 5 & 3 & 3 & 4 \\ 0 & 0 & 1 & 0 & 0 & 3 \\ 0 & 2 & 2 & 0 & 2 & 2 \\ \hline 1 & 0 & -1 & 1 & 0 & -1 \\ 1 & 1 & 4 & 2 & 2 & 5 \\ 1 & 2 & 6 & & & \end{array}$$

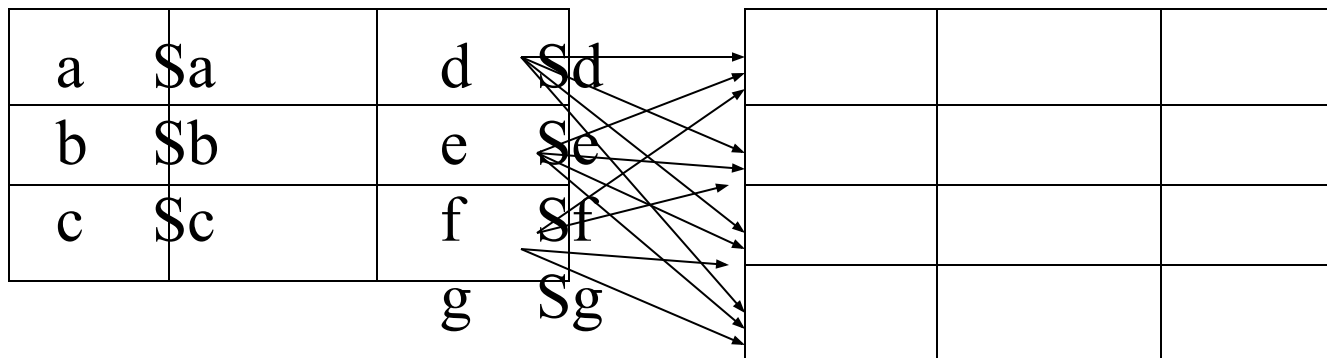
$$B^T = \begin{bmatrix} 3 & -1 & 0 \\ 0 & 0 & 0 \\ 2 & 0 & 5 \end{bmatrix} \quad \begin{array}{ccc|ccc} 3 & 3 & 3 & 3 & 3 & 3 \\ 0 & 0 & 3 & 0 & 0 & 3 \\ 0 & 1 & -1 & 0 & 1 & -1 \\ 2 & 0 & 2 & 2 & 0 & 2 \\ 2 & 2 & 5 & 2 & 2 & 5 \end{array}$$

$(0,0)$
 $(0,2)$
 $(1,0)$
 $(1,2)$

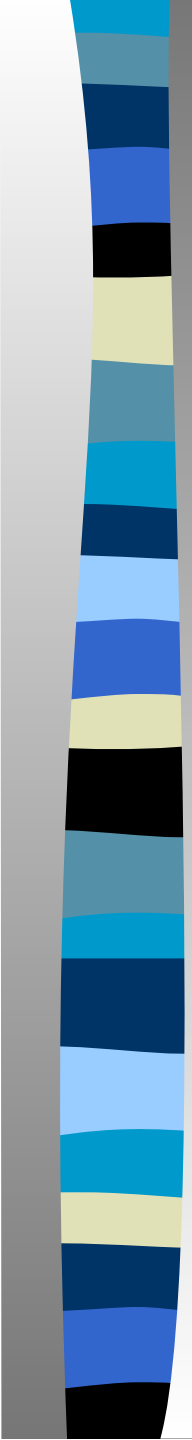
General Case

$$d_{ij} = a_{i0} * b_{0j} + a_{i1} * b_{1j} + \dots + a_{i(n-1)} * b_{(n-1)j}$$

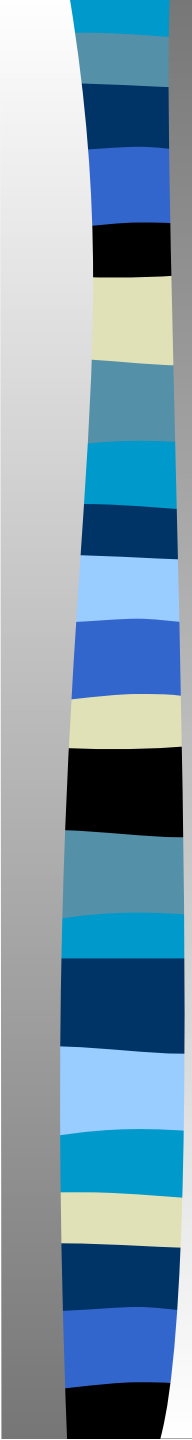
a本來依i成群，經轉置後，b也依j成群。



最多可以產生ad, ae, af, ag,
bd, be, bf, bg,
cd, ce, cf, cg 等entries 。



```
void mmult (term a[ ], term b[ ], term d[ ] )
/* multiply two sparse matrices */
{
    int i, j, column, totalb = b[0].value, totald = 0;
    int rows_a = a[0].row, cols_a = a[0].col,
    totala = a[0].value; int cols_b = b[0].col,
    int row_begin = 1, row = a[1].row, sum = 0;
    int new_b[MAX_TERMS][3];
    if (cols_a != b[0].row){
        fprintf (stderr, "Incompatible matrices\n");
        exit (1);
    }
}
```

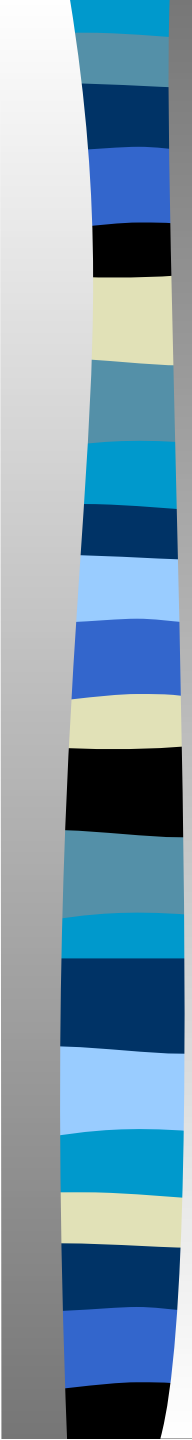


```
fast_transpose(b, new_b);  
/* set boundary condition */  
a[totala+1].row = rows_a;  
new_b[totalb+1].row = cols_b;  
new_b[totalb+1].col = 0;
```

$\text{cols_b} + \text{totalb}$

```
for (i = 1; i <= totala; ) {  
    column = new_b[1].row;  
    for (j = 1; j <= totalb+1;) {  
        /* mutiply row of a by column of b */  
        if (a[i].row != row) {  
            storesum(d, &totald, row, column, &sum);  
            i = row_begin;  
            for (; new_b[j].row == column; j++)  
                ;  
            column = new_b[j].row  
        }  
    }
```

at most rows_a times



```

else switch (COMPARE (a[i].col, new_b[j].col)) {
    case -1: /* go to next term in a */
        i++; break;
    case 0: /* add terms, go to next term in a and b */
        sum += (a[i++].value * new_b[j++].value);
        break;
    case 1: /* advance to next term in b*/
        j++
    }
} /* end of for j <= totalb+1 */
for (; a[i].row == row; i++)
    ;
    row_begin = i; row = a[i].row;
} /* end of for i <=totala */
d[0].row = rows_a;
d[0].col = cols_b; d[0].value = totald;
}

```

***Praogram 2.9: Sparse matrix multiplication (p.75)**



Analyzing the algorithm

$$\begin{aligned} & \text{cols_b} * \text{termsrow}_1 + \text{totalb} + \\ & \text{cols_b} * \text{termsrow}_2 + \text{totalb} + \\ & \dots + \\ & \text{cols_b} * \text{termsrow}_p + \text{totalb} \\ & = \text{cols_b} * (\text{termsrow}_1 + \text{termsrow}_2 + \dots + \text{termsrow}_p) + \\ & \quad \text{rows_a} * \text{totalb} \\ & = \text{cols_b} * \text{totala} + \text{rows_a} * \text{totalb} \\ & O(\text{cols_b} * \text{totala} + \text{rows_a} * \text{totalb}) \end{aligned}$$



Compared with matrix multiplication using array

```
for (i=0; i < rows_a; i++)  
    for (j=0; j < cols_b; j++) {  
        sum =0;  
        for (k=0; k < cols_a; k++)  
            sum += (a[i][k] *b[k][j]);  
        d[i][j] =sum;  
    }
```

$O(\text{rows_a} * \text{cols_a} * \text{cols_b})$ vs.

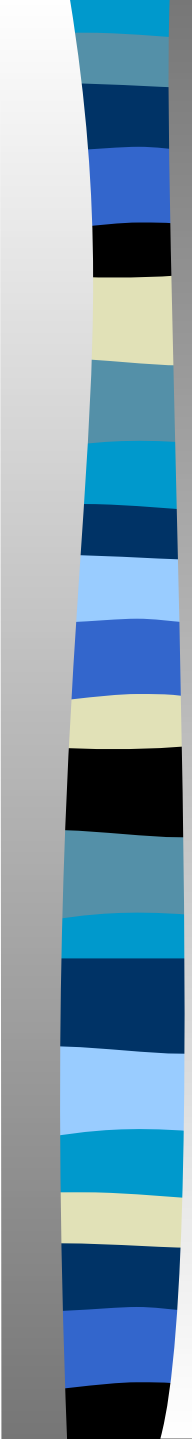
$O(\text{cols_b} * \text{total_a} + \text{rows_a} * \text{total_b})$

optimal case: $\text{total_a} < \text{rows_a} * \text{cols_a}$

$\text{total_b} < \text{cols_a} * \text{cols_b}$

worse case: $\text{total_a} \rightarrow \text{rows_a} * \text{cols_a}$, or

$\text{total_b} \rightarrow \text{cols_a} * \text{cols_b}$



```
void storesum(term d[ ], int *totald, int row, int column,
               int *sum)
{
/* if *sum != 0, then it along with its row and column
   position is stored as the *totald+1 entry in d */
   if (*sum)
       if (*totald < MAX_TERMS) {
           d[++*totald].row = row;
           d[*totald].col = column;
           d[*totald].value = *sum;
       }
       else {
           fprintf(stderr, "Numbers of terms in product
                           exceed %d\n", MAX_TERMS);
           exit(1);
       }
}
```