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(Autonomous Institute, Affiliated to VTU)  
Department of Computer Science and Engineering

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Course Name: Data Structures

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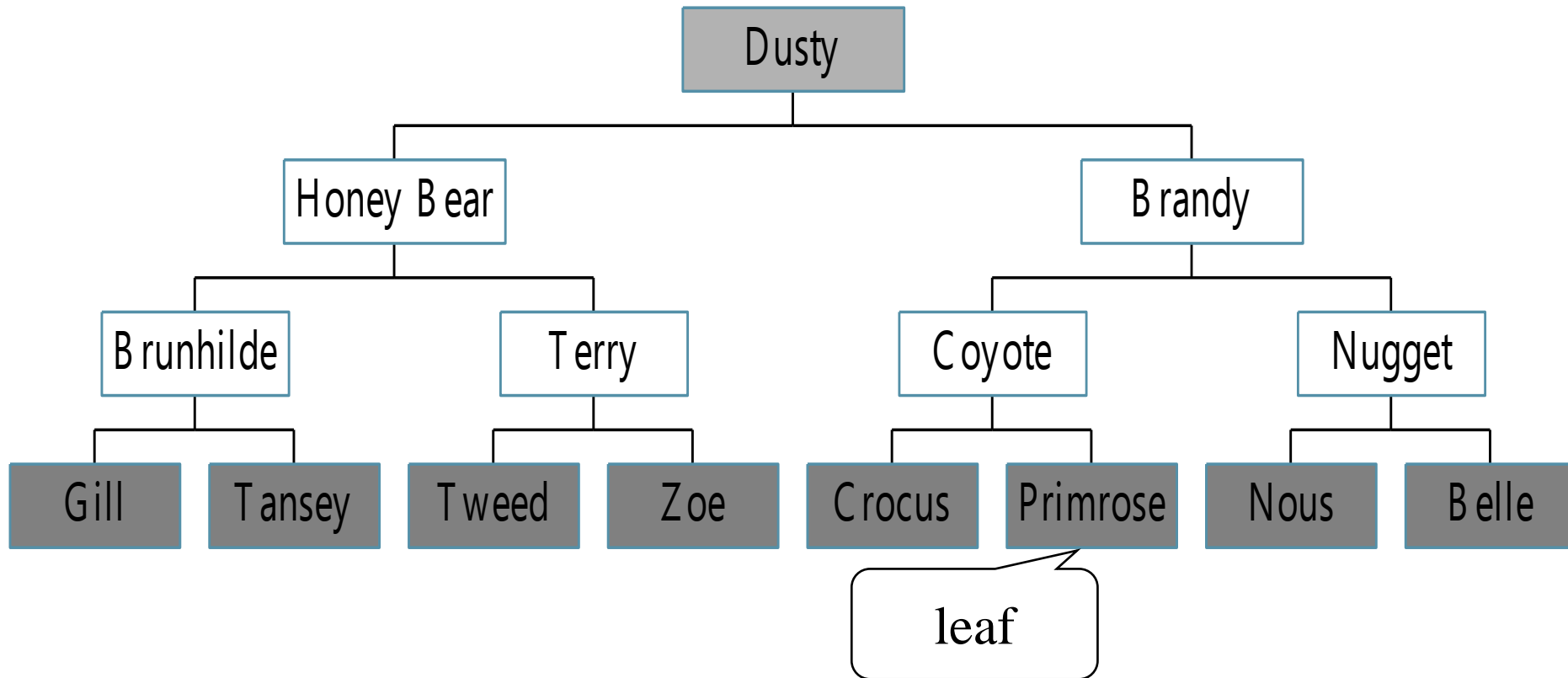
Mamatha Jadhav V

A Parkavi

# Unit 4: Trees

The contents in this presentation are selected from  
Ellis Horowitz, Sartaj Sahni, and Susan Anderson-Freed  
“Fundamentals of Data Structures in C”, Universities Press, 2008

# Trees



# Definition of Tree

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A tree is a finite set of one or more nodes such that:

- There is a specially designated node called the root.
- The remaining nodes are partitioned into  $n \geq 0$  disjoint sets  $T_1, \dots, T_n$ , where each of these sets is a tree.
- We call  $T_1, \dots, T_n$  the subtrees of the root.

# Level and Depth

node (13)

degree of a node

leaf (terminal)

nonterminal

parent

children

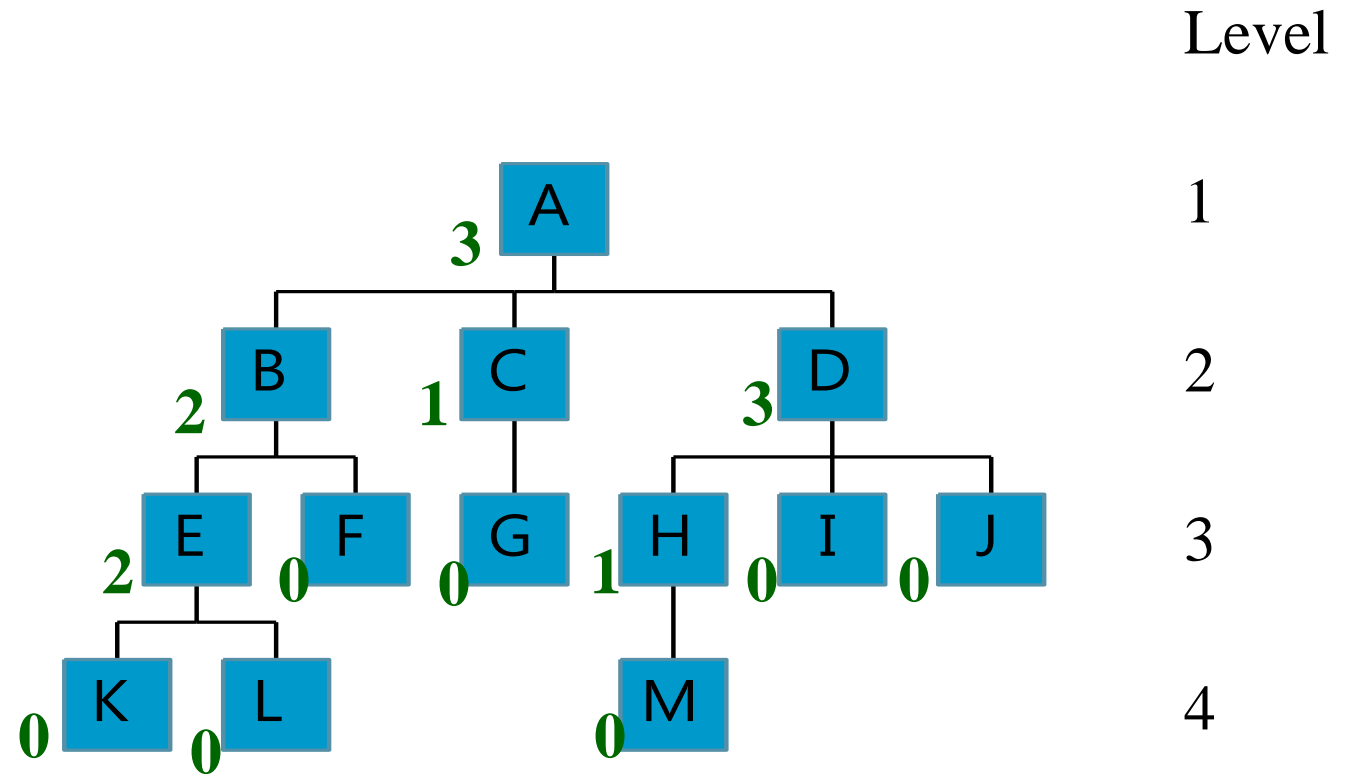
sibling

degree of a tree (3)

ancestor

level of a node

height of a tree (4)



# Terminology

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- The degree of a node is the number of subtrees of the node
  - The degree of A is 3; the degree of C is 1.
- The node with degree 0 is a leaf or terminal node.
- A node that has subtrees is the *parent* of the roots of the subtrees.
- The roots of these subtrees are the *children* of the node.
- Children of the same parent are *siblings*.
- The ancestors of a node are all the nodes along the path from the root to the node.

# Representation of Trees

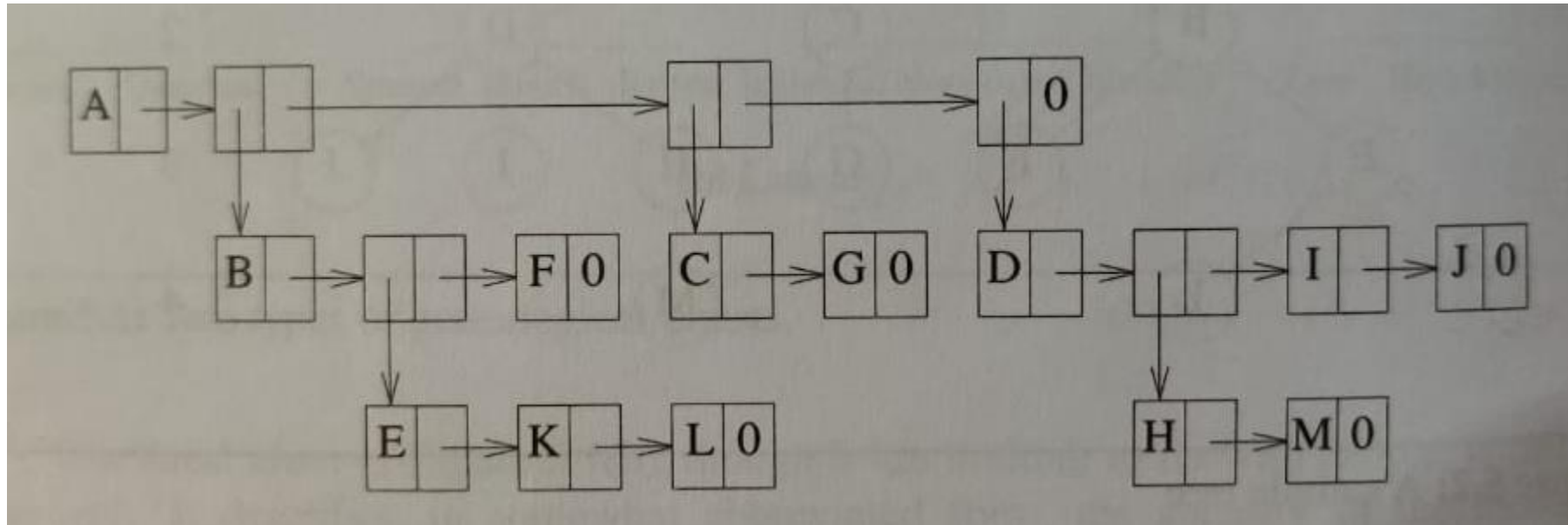
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## □ List Representation

- $(A(B(E(K, L), F), C(G), D(H(M), I, J)))$
- The root comes first, followed by a list of sub-trees

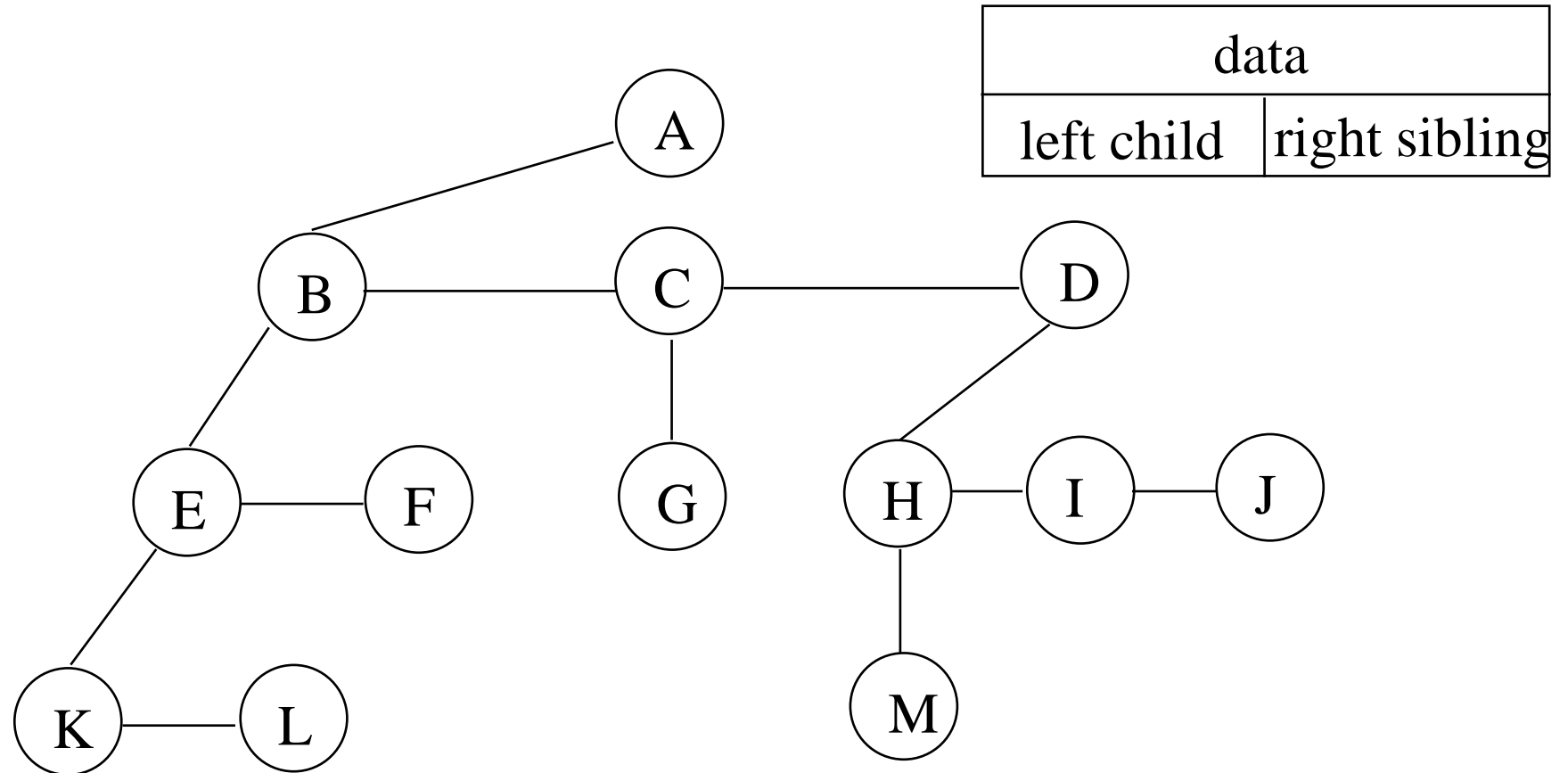
data	child 1	child 2	...	child n
------	---------	---------	-----	---------

# List Representation of the tree





# Left Child - Right Sibling

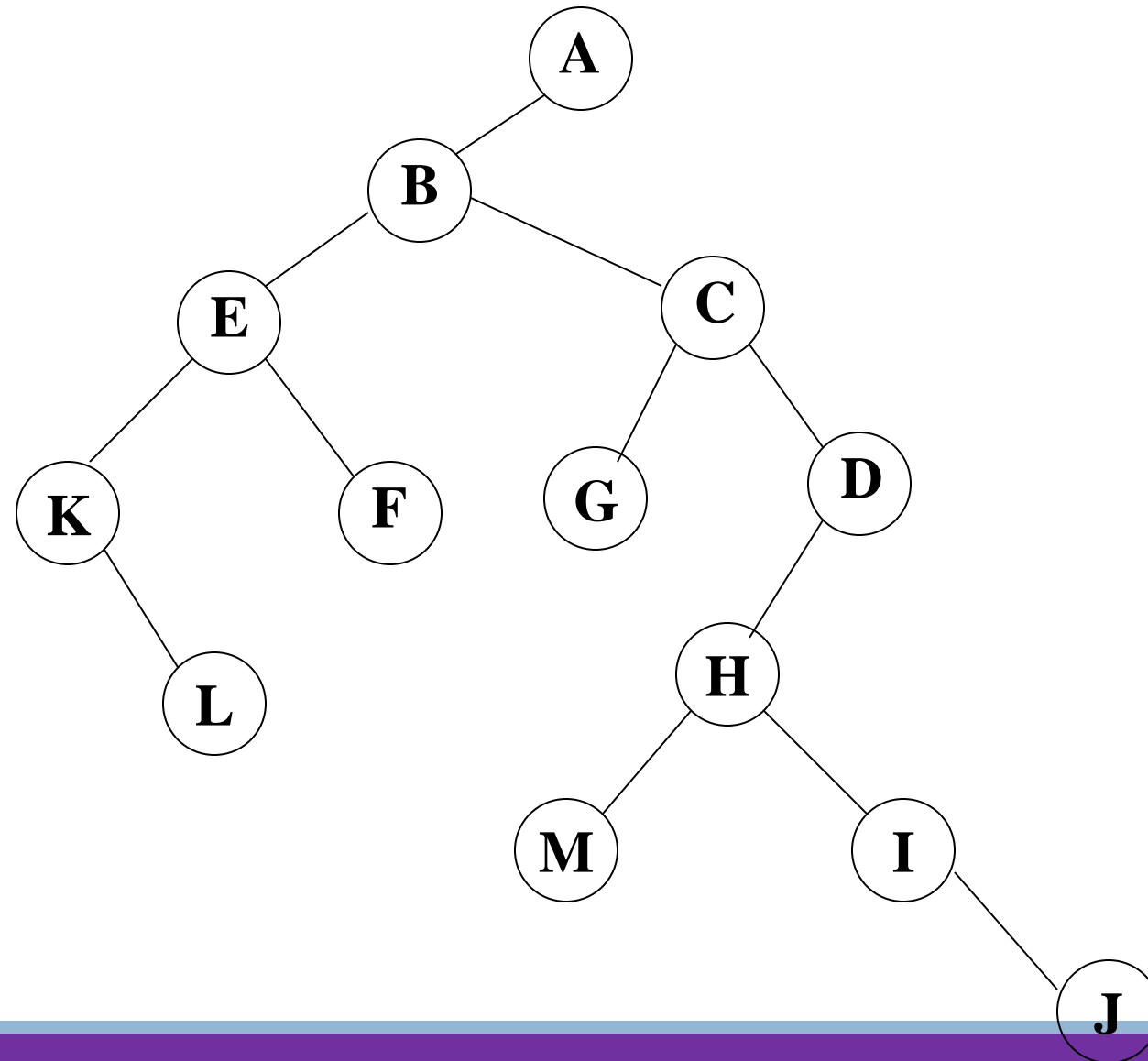


# Binary Trees

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- A binary tree is a finite set of nodes that is either empty or consists of a root and two disjoint binary trees called *the left subtree* and *the right subtree*.
- Any tree can be transformed into binary tree.
  - by left child-right sibling representation
- The left subtree and the right subtree are distinguished.

## Left child-right child tree representation of a tree



# Abstract Data Type Binary\_Tree

ADT *Binary\_Tree* (abbreviated *BinTree*) is

**objects:** a finite set of nodes either empty or consisting of a root node, left *Binary\_Tree*, and right *Binary\_Tree*.

**functions:**

for all  $bt, bt1, bt2 \in BinTree, item \in element$

*Bintree* Create() ::= creates an empty binary tree

*Boolean* IsEmpty( $bt$ ) ::= if ( $bt == \text{empty binary tree}$ ) return *TRUE*  
else return *FALSE*

*BinTree* MakeBT(*bt1*, *item*, *bt2*) ::= return a binary tree whose left subtree is *bt1*,  
whose right subtree is *bt2*, and whose root node  
contains the data *item*

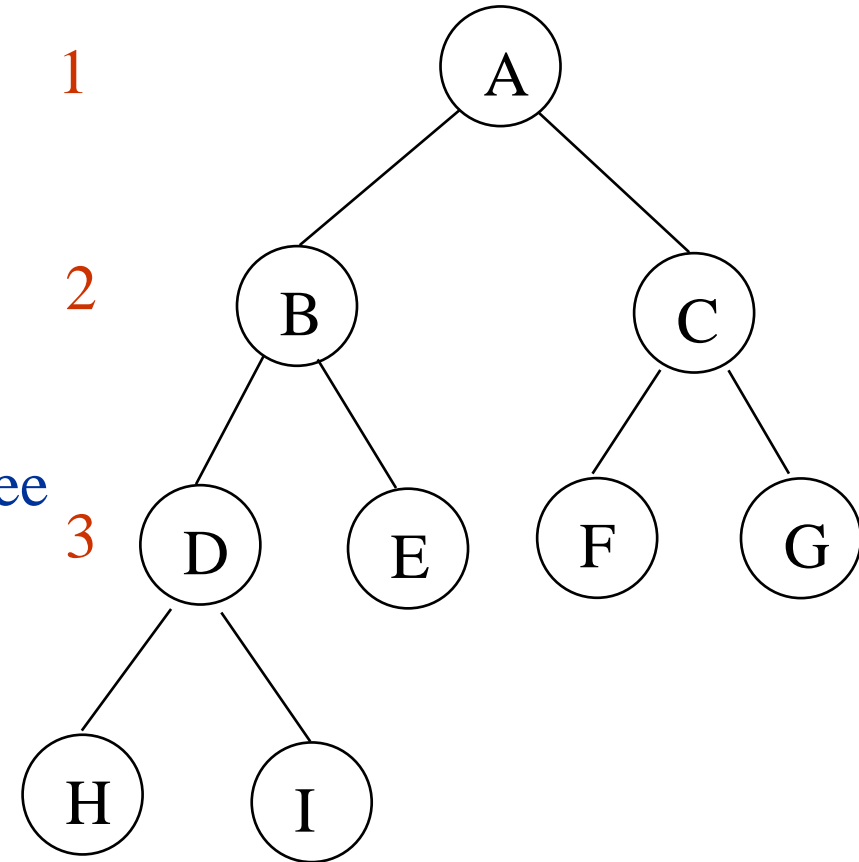
*Bintree* Lchild(*bt*) ::= if (IsEmpty(*bt*)) return error else return the left subtree of *bt*

*element* Data(*bt*) ::= if (IsEmpty(*bt*)) return error else return the data in the root node  
of *bt*

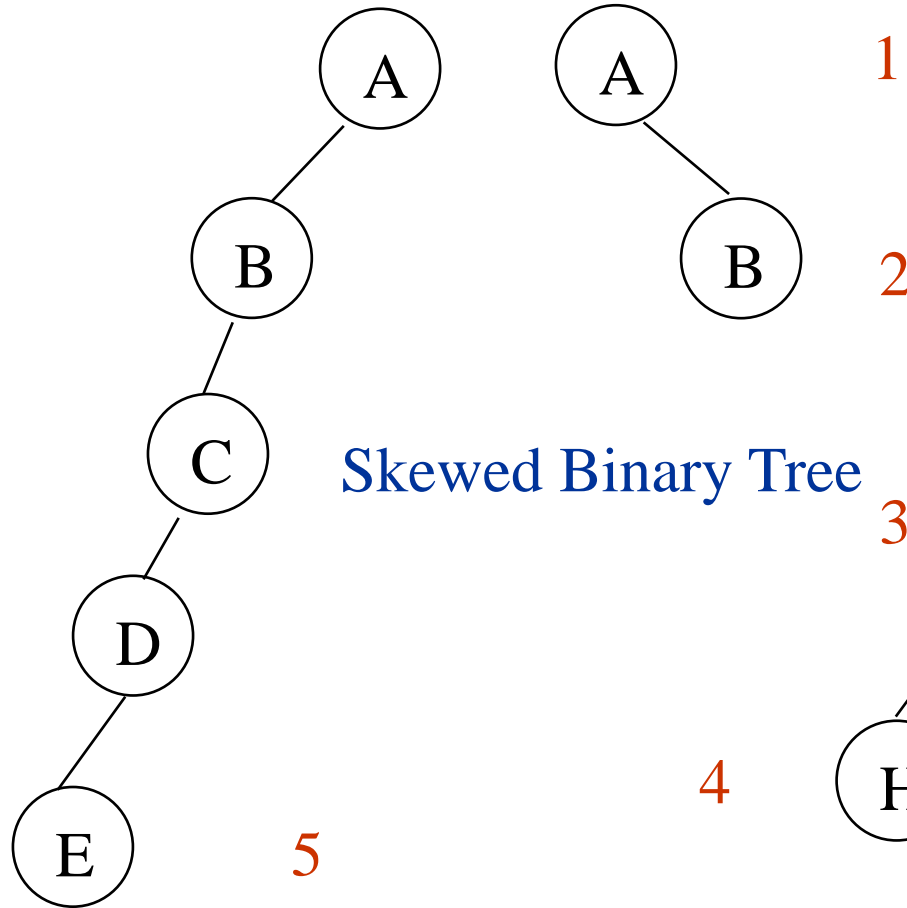
*Bintree* Rchild(*bt*) ::= if (IsEmpty(*bt*)) return error else return the right subtree of *bt*

# Samples of Trees

Complete Binary Tree



Skewed Binary Tree



# Maximum Number of Nodes in BT

- The maximum number of nodes on level  $i$  of a binary tree is  $2^{i-1}$ ,  $i \geq 1$ .
- The maximum number of nodes in a binary tree of depth  $k$  is  $2^k - 1$ ,  $k \geq 1$ .

**Prove by induction.**

$$\sum_{i=1}^k 2^{i-1} = 2^k - 1$$

## Relations between Number of Leaf Nodes and Nodes of Degree 2

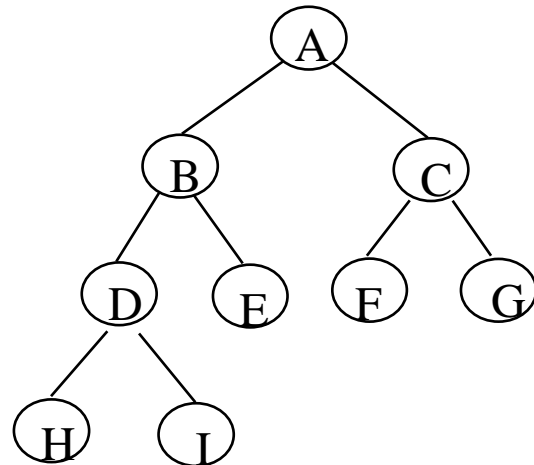
*For any nonempty binary tree,  $T$ , if  $n_0$  is the number of leaf nodes and  $n_2$  the number of nodes of degree 2, then  $n_0 = n_2 + 1$*



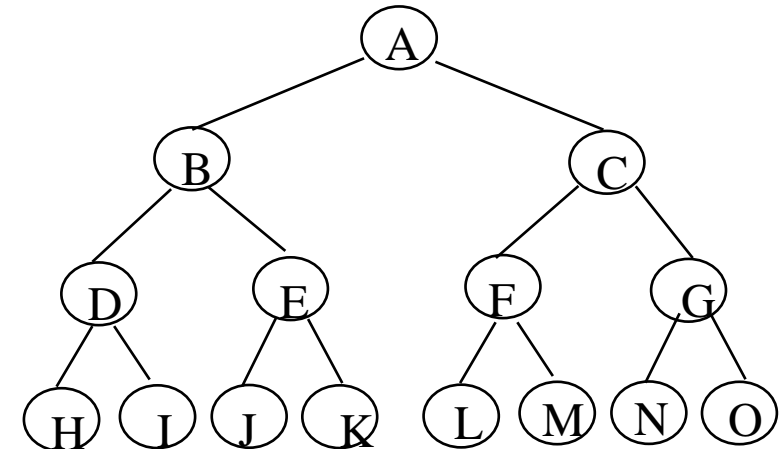
# Full BT VS Complete BT

- A full binary tree of depth  $k$  is a binary tree of depth  $k$  having  $2^k - 1$  nodes,  $k \geq 0$ .
- A binary tree with  $n$  nodes and depth  $k$  is complete *iff* its nodes correspond to the nodes numbered from 1 to  $n$  in the full binary tree of depth  $k$ .

Complete binary tree



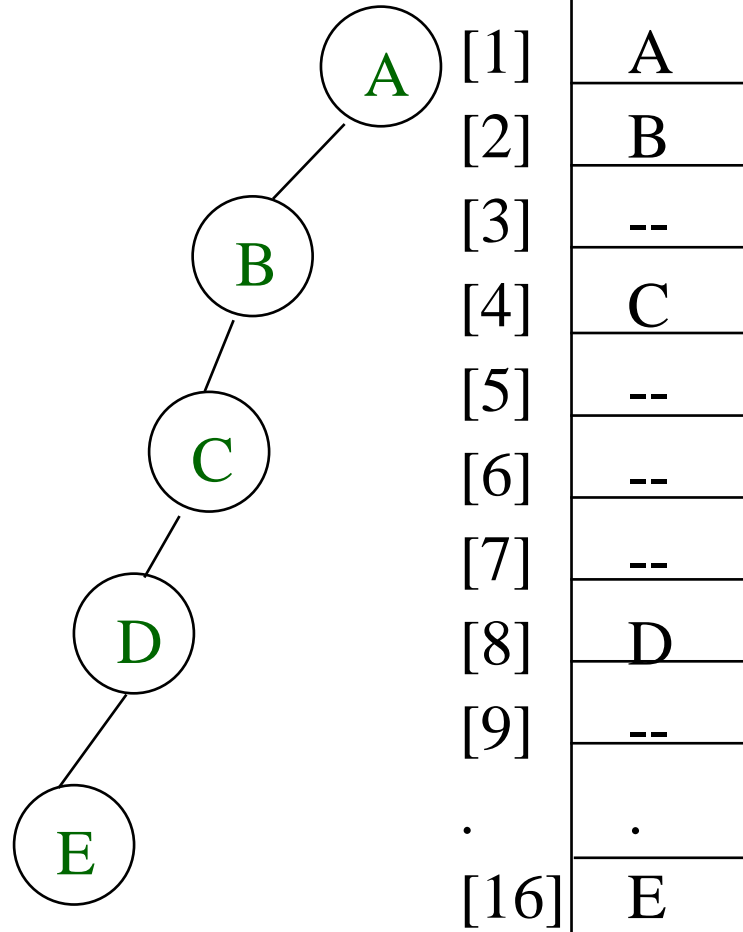
Full binary tree of depth 4



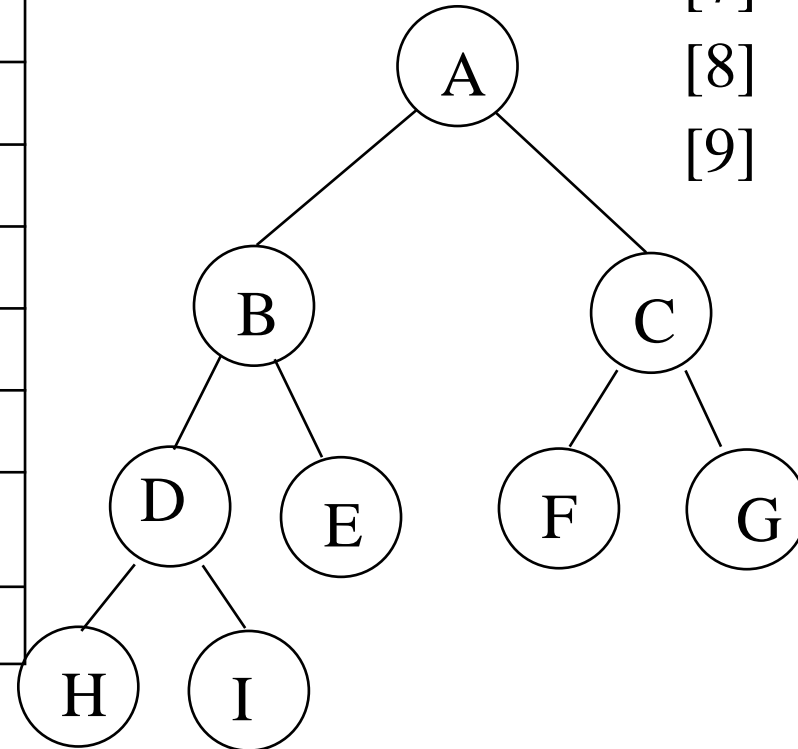
# Binary Tree Representations

- If a complete binary tree with  $n$  nodes (depth =  $\log n + 1$ ) is represented sequentially, then for any node with index  $i$ ,  $1 \leq i \leq n$ , we have:
  - $parent(i)$  is at  $i/2$  if  $i \neq 1$ . If  $i=1$ ,  $i$  is at the root and has no parent.
  - $leftChild(i)$  is at  $2i$  if  $2i \leq n$ . If  $2i > n$ , then  $i$  has no left child.
  - $rightChild(i)$  is at  $2i+1$  if  $2i+1 \leq n$ . If  $2i+1 > n$ , then  $i$  has no right child.

# Sequential Representation



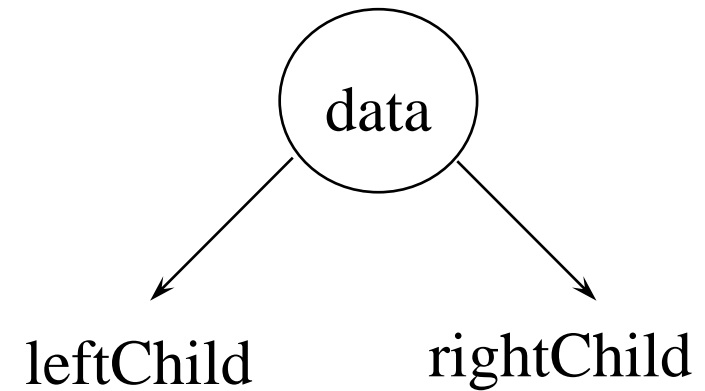
**(1) waste space**  
**(2) insertion/deletion problem**



[1]	A
[2]	B
[3]	C
[4]	D
[5]	E
[6]	F
[7]	G
[8]	H
[9]	I

# Linked Representation

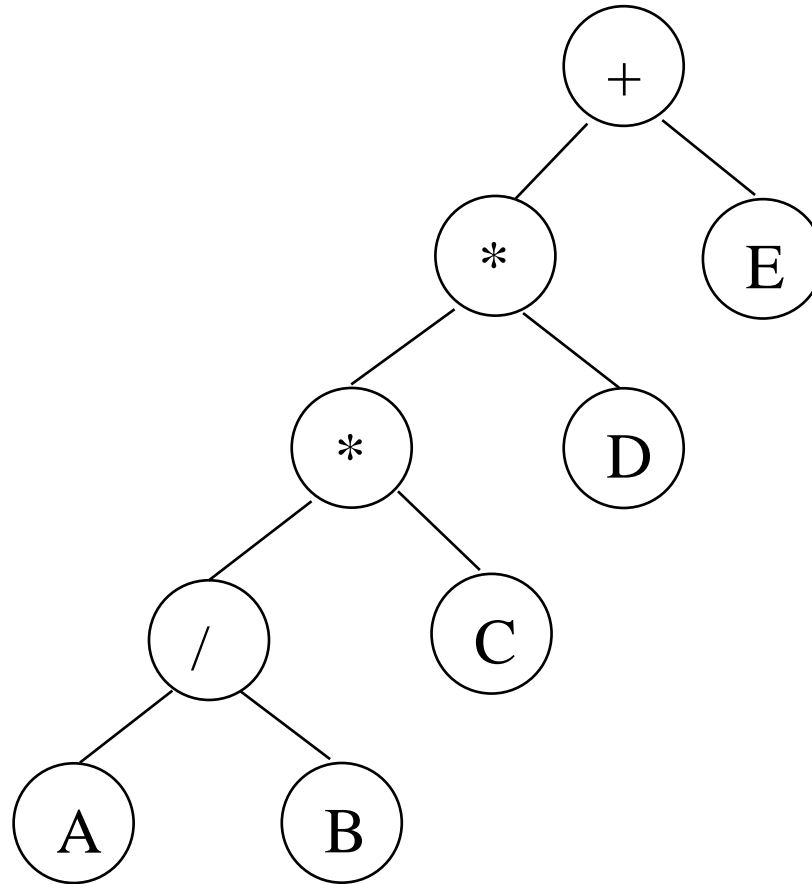
```
typedef struct node *treePointer;  
typedef struct node {  
    int data;  
    treePointer leftChild, rightChild;  
};
```



# Binary Tree Traversals

- Let L, V, and R stand for moving left, visiting the node, and moving right.
- There are six possible combinations of traversal
  - LVR, LRV, VLR, VRL, RVL, RLV
- Adopt convention that we traverse left before right, only 3 traversals remain
  - LVR, LRV, VLR
  - inorder, postorder, preorder

# Arithmetic Expression Using BT



**inorder traversal**

$A / B * C * D + E$

**infix expression**

**preorder traversal**

$+ * * / A B C D E$

**prefix expression**

**postorder traversal**

$A B / C * D * E +$

**postfix expression**

**level order traversal**

$+ * E * D / C A B$

# Inorder Traversal (recursive version)

```
void inorder(treePointer ptr)
/* inorder tree traversal */
{
    if (ptr) {
        inorder(ptr->leftChild);
        printf("%d", ptr->data);
        indorder(ptr->rightChild);
    }
}
```

$$A / B * C * D + E$$

# Preorder Traversal (recursive version)

```
void preorder(treePointer ptr)
/* preorder tree traversal */
{
    if (ptr) {
        printf("%d", ptr->data);
        preorder(ptr->leftChild);
        predorder(ptr->rightChild);
    }
}
```

+ \* \* / A B C D E



# Postorder Traversal (recursive version)

```
void postorder(treePointer ptr)
/* postorder tree traversal */
{
    if (ptr) {
        postorder(ptr->leftChild);
        postorder(ptr->rightChild);
        printf("%d", ptr->data);
    }
}
```

$$A B / C * D * E +$$

# Trace Operations of Inorder Traversal

Call of inorder	Value in root	Action	Call of inorder	Value in root	Action
1	+		11	C	
2	*		12	NULL	
3	*		11	C	printf
4	/		13	NULL	
5	A		2	*	printf
6	NULL		14	D	
5	A	printf	15	NULL	
7	NULL		14	D	printf
4	/	printf	16	NULL	
8	B		1	+	printf
9	NULL		17	E	
8	B	printf	18	NULL	
10	NULL		17	E	printf
3	*	printf	19	NULL	

# Iterative Inorder Traversal

(using stack)

```
void iter_inorder(treePointer node)
{
    int top= -1; /* initialize stack */
    treePointer stack[MAX_STACK_SIZE];
    for (;;) {
        for (; node; node=node->leftChild)
            push(node); /* add to stack */
        node= pop();
        /* delete from stack */
        if (!node) break; /* empty stack */
        printf("%d", node->data);
        node = node->rightChild;
    }
}
```

# Level Order Traversal

(using queue)

```
void level_order(treePointer ptr)
/* level order tree traversal */
{
    int front = rear = 0;
    treePointer queue[MAX_QUEUE_SIZE];
    if (!ptr) return; /* empty queue */
    addq(ptr);
    for (;;) {
        ptr = deleteq();
```

```
if (ptr) {  
    printf("%d", ptr->data);  
    if (ptr->leftChild)  
        addq(ptr->leftChild);  
    if (ptr->rightChild)  
        addq(ptr->rightChild);  
}  
else break;  
}  
}
```

# Copying Binary Trees

```
treePointer copy(treePointer original)
{
    treePointer temp;
    if (original) {
        temp=(treePointer) malloc(sizeof(node));
        temp->leftChild=copy(original->leftChild);
        temp->rightChild=copy(original->rightChild);
        temp->data=original->data;
        return temp;
    }
    return NULL;
}
```

# Equality of Binary Trees

the same topology and data

```
int equal(treePointer first, treePointer second)
{
    /* function returns FALSE if the binary trees first and
       second are not equal, otherwise it returns TRUE */

    return ((!first && !second) || (first && second &&
        (first->data == second->data) &&
        equal(first->leftChild, second->leftChild) &&
        equal(first->rightChild, second->rightChild)))
}
```

# Propositional Calculus Expression

---

A variable is an expression.

If  $x$  and  $y$  are expressions, then  $\neg x$ ,  $x \wedge y$ ,  $x \vee y$  are expressions.

Parentheses can be used to alter the normal order of evaluation ( $\neg > \wedge > \vee$ ).

Example:  $x_1 \vee (x_2 \wedge \neg x_3)$

satisfiability problem: Is there an assignment to make an expression true?



$$(X_1 \wedge \neg X_2) \vee (\neg X_1 \wedge X_3) \vee \neg X_3$$

(t,t,t)

(t,t,f)

(t,f,t)

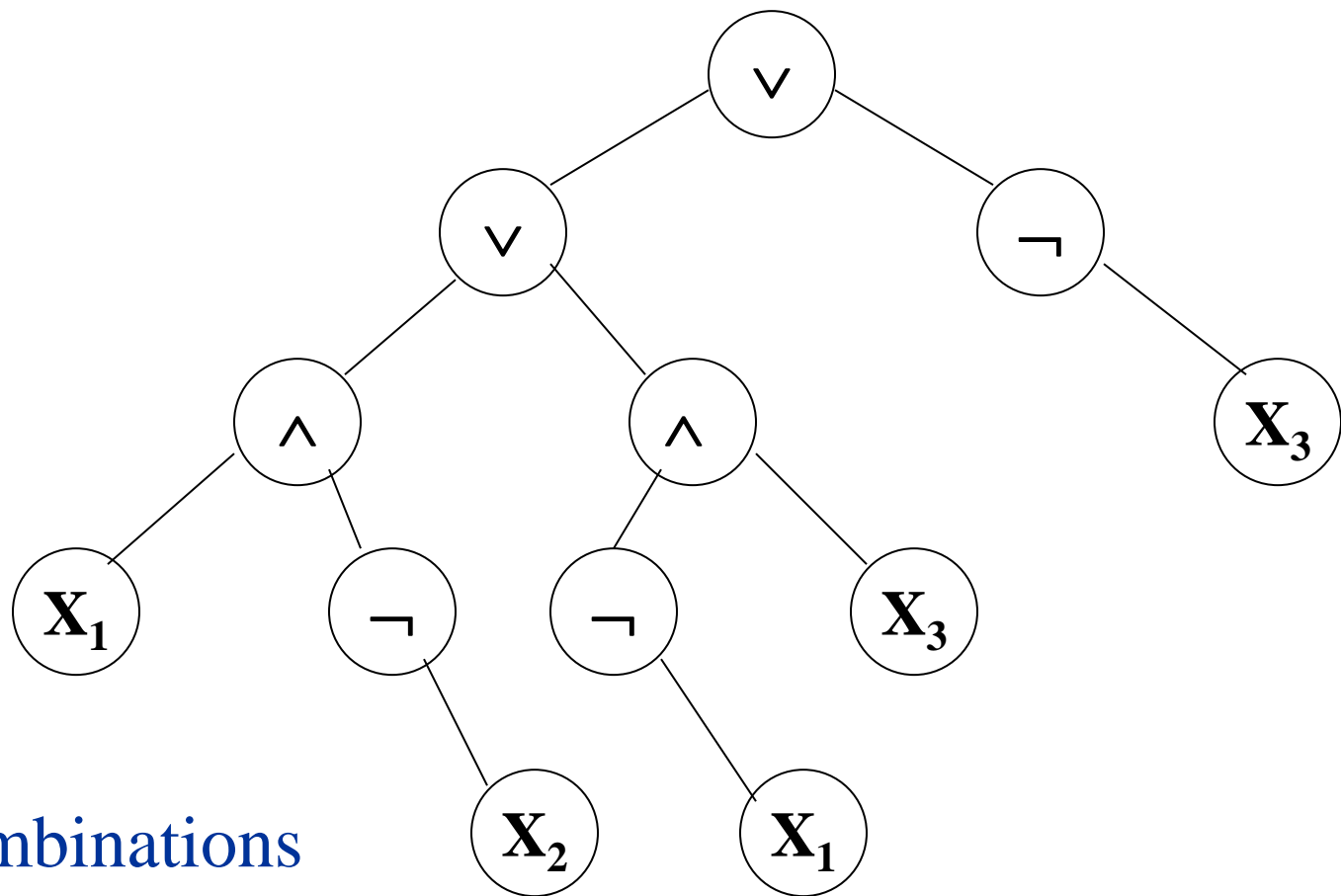
(t,f,f)

(f,t,t)

(f,t,f)

(f,f,t)

(f,f,f)



$2^n$  possible combinations  
for  $n$  variables

postorder traversal (postfix evaluation)

## node structure

<i>leftChild</i>	<i>data</i>	<i>value</i>	<i>rightChild</i>
------------------	-------------	--------------	-------------------

```
typedef enum {not, and, or, true, false } logical;  
typedef struct node *treePointer;  
typedef struct node {  
    treePointer list_child;  
    logical      data;  
    short int    value;  
    treePointer rightChild;  
} ;
```

# First version of satisfiability algorithm

---

```
for (all  $2^n$  possible combinations) {  
    generate the next combination;  
    replace the variables by their values;  
    evaluate root by traversing it in postorder;  
    if (root->value) {  
        printf(<combination>);  
        return;  
    }  
}  
printf("No satisfiable combination \n");
```

# Post-order-eval function

---

```
void post_order_eval(treePointer node)
{
    /* modified post order traversal to evaluate a propositional
    calculus tree */
    if (node) {
        post_order_eval(node->leftChild);
        post_order_eval(node->rightChild);
        switch(node->data) {
            case not: node->value =
                !node->rightChild->value;
                break;
```

---

```
case and:  node->value =
           node->rightChild->value &&
           node->leftChild->value;
           break;
case or:   node->value =
           node->rightChild->value | |
           node->leftChild->value;
           break;
case true: node->value = TRUE;
           break;
case false: node->value = FALSE;
            }
          }
        }
```

# Threaded Binary Trees

- Two many null pointers in current representation of binary trees
  - n: number of nodes
  - number of non-null links:  $n-1$
  - total links:  $2n$
  - null links:  $2n-(n-1)=n+1$
- Replace these null pointers with some useful “threads”.

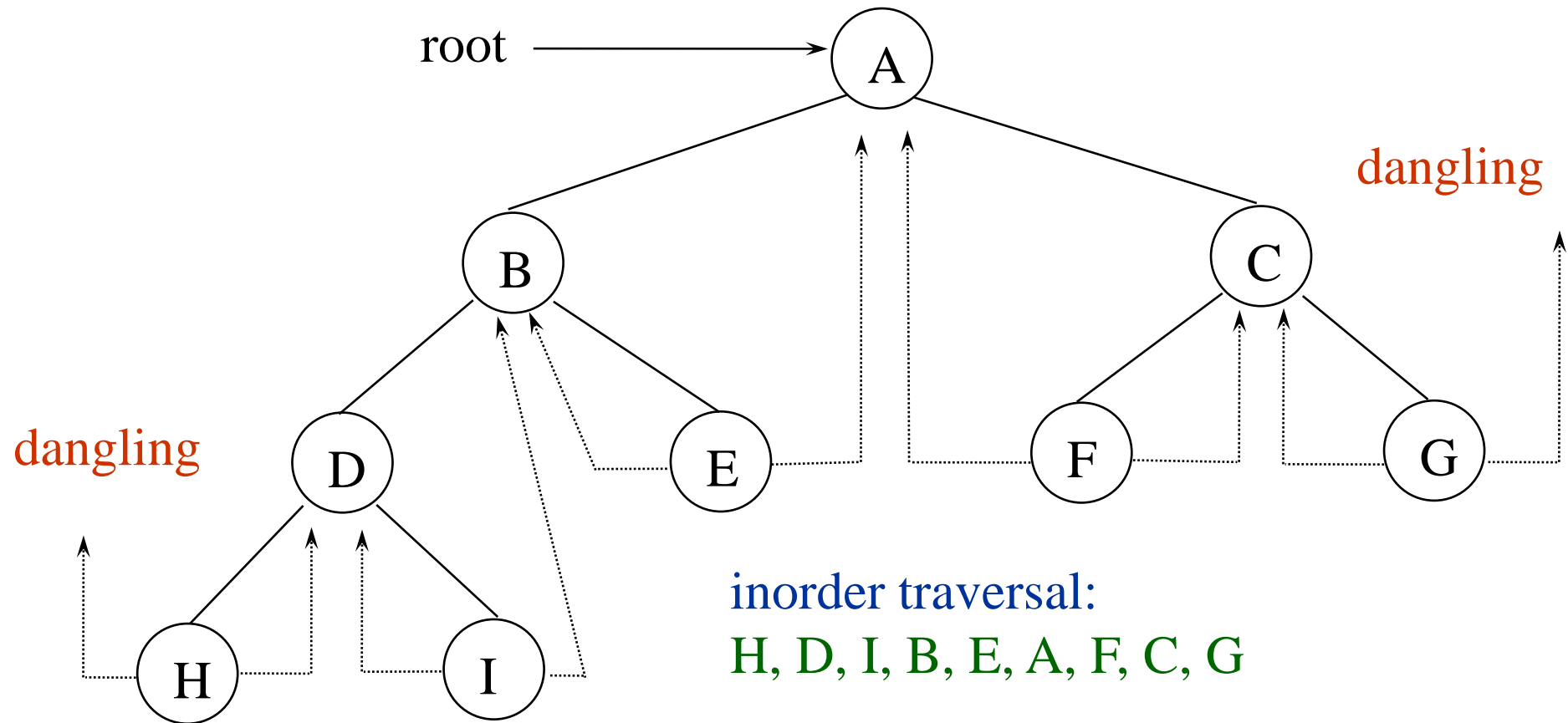
# Threaded Binary Trees *(Continued)*

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If `ptr->leftChild` is null,  
replace it with a pointer to the node that would be  
visited *before* `ptr` in an *inorder traversal*

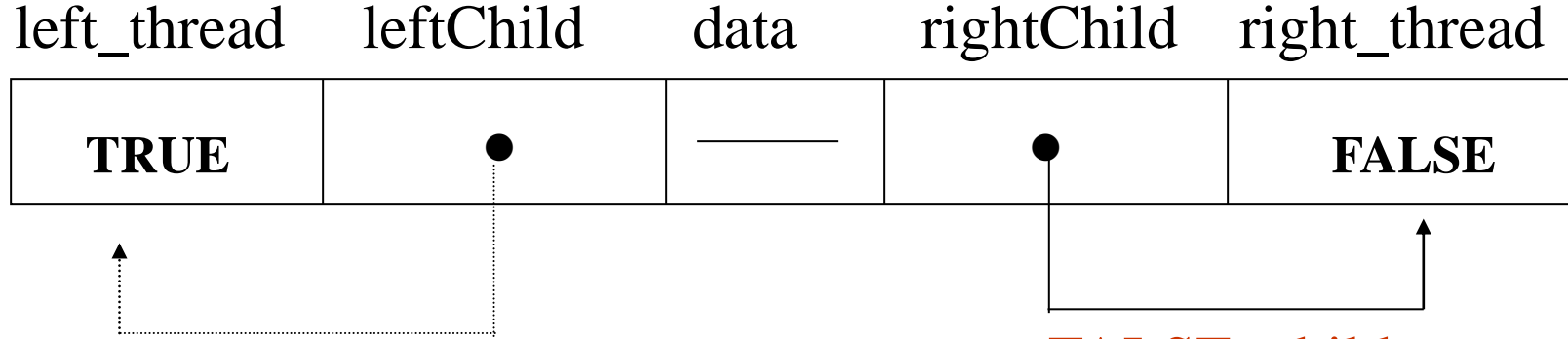
If `ptr->rightChild` is null,  
replace it with a pointer to the node that would be  
visited *after* `ptr` in an *inorder traversal*

# A Threaded Binary Tree





# Data Structures for Threaded BT

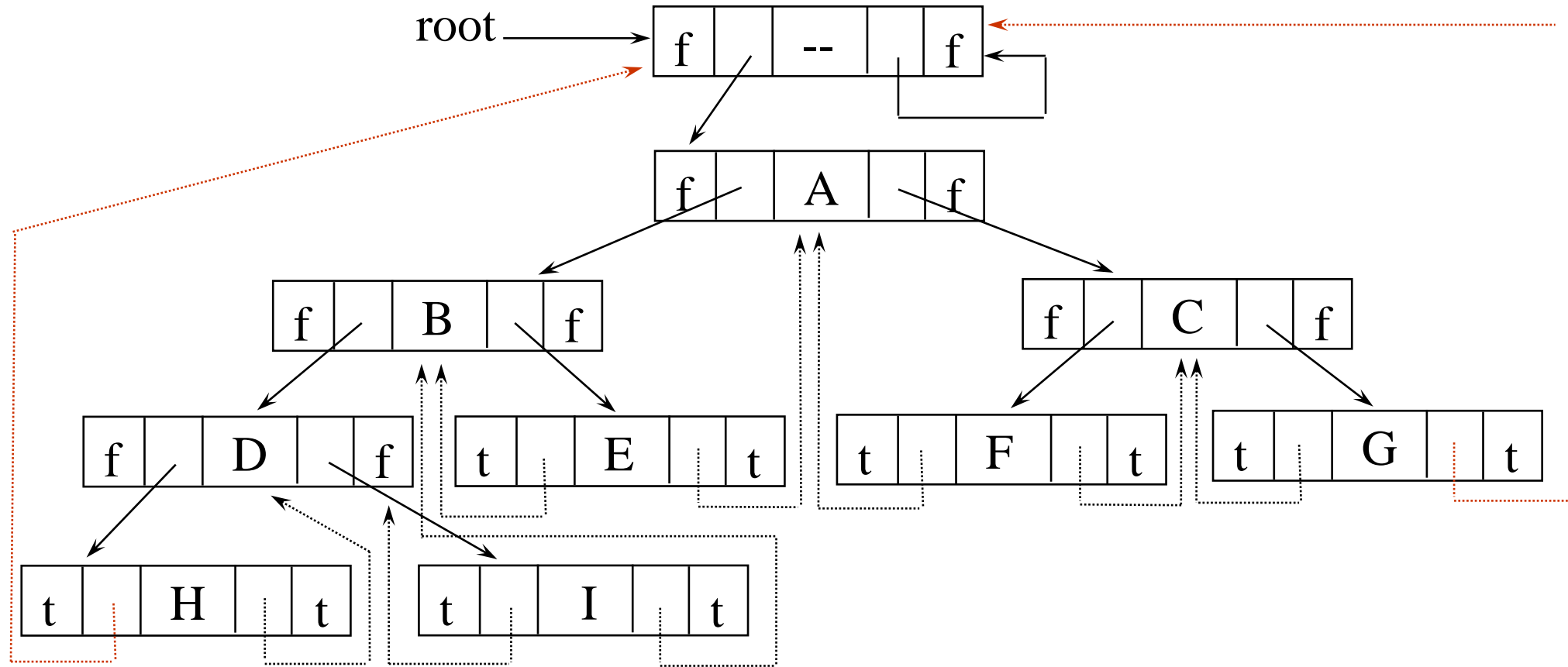


**TRUE: thread**

**FALSE: child**

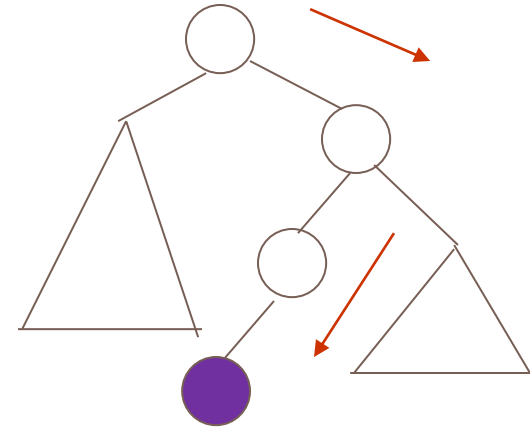
```
typedef struct threaded_tree *threaded_pointer;
typedef struct threaded_tree {
    short int left_thread;
    threaded_pointer leftChild;
    char data;
    threaded_pointer rightChild;
    short int right_thread; };
```

# Memory Representation of A Threaded BT



# Next Node in Threaded BT

```
threaded_pointer insucc(threaded_pointer tree)
{
    threaded_pointer temp;
    temp = tree->rightChild;
    if (!tree->right_thread)
        while (!temp->left_thread)
            temp = temp->leftChild;
    return temp;
}
```



# Inorder Traversal of Threaded BT

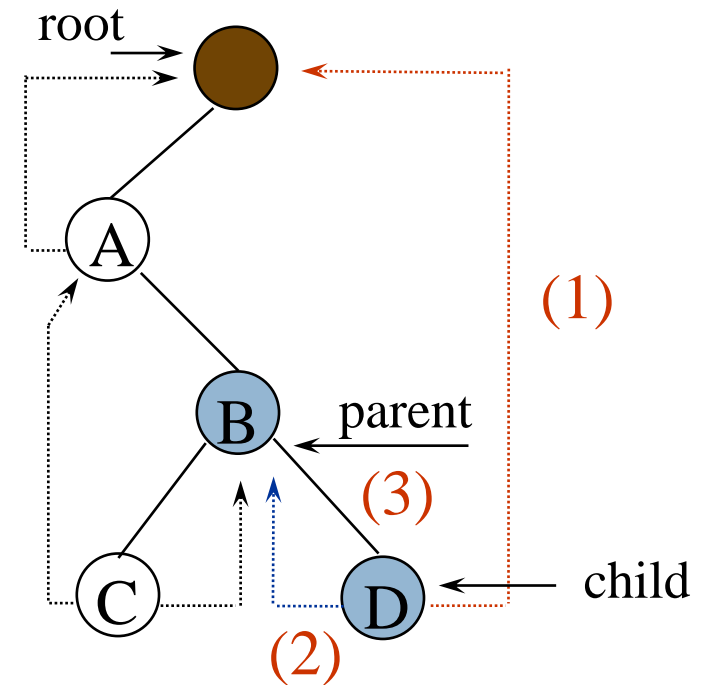
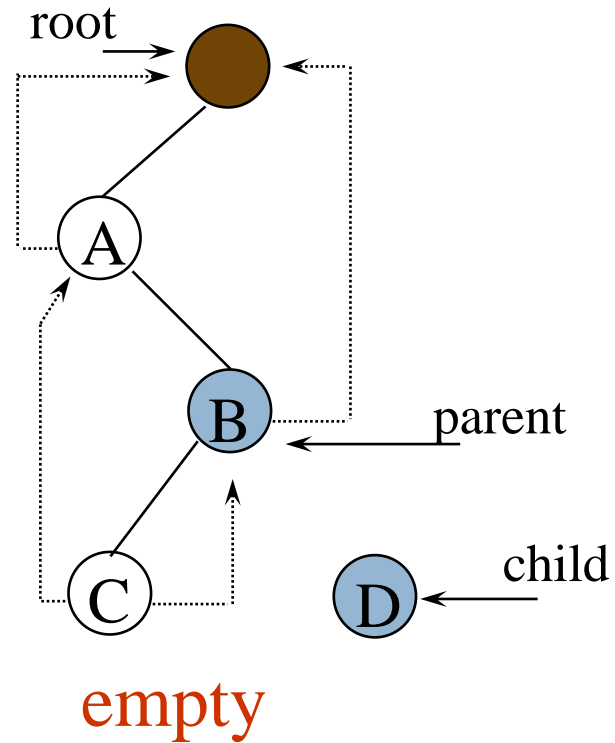
```
void tinorder(threaded_pointer tree)
{
    /* traverse the threaded binary tree inorder */
    threaded_pointer temp = tree;
    for (;;) {
        temp = insucc(temp);
        if (temp==tree) break;
        printf("%3c", temp->data);
    }
}
```

# Inserting Nodes into Threaded BTs

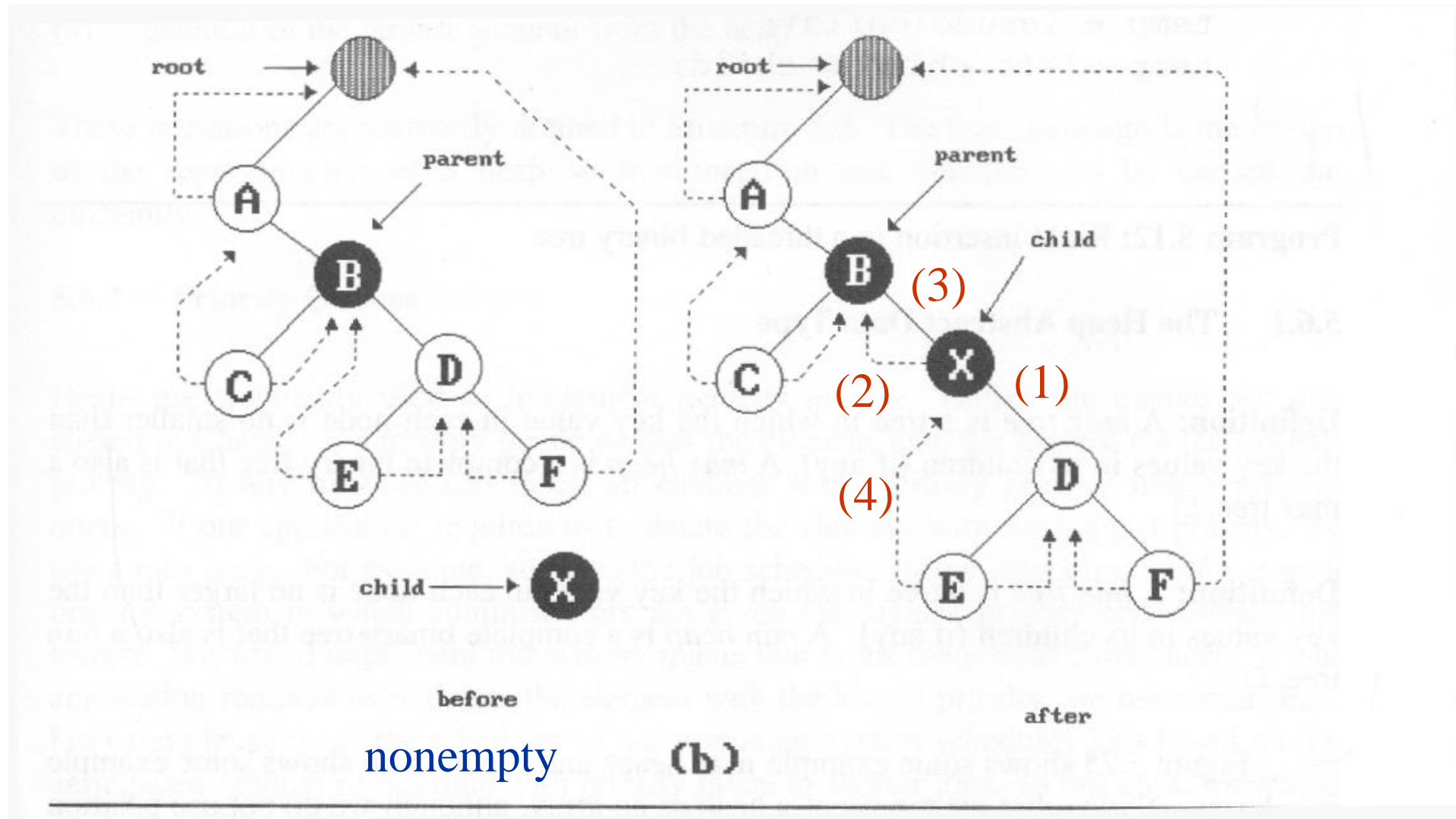
- Insert `child` as the right child of node `parent`
  - change `parent->right_thread` to **FALSE**
  - set `child->left_thread` **and** `child->right_thread` to **TRUE**
  - set `child->leftChild` to point to `parent`
  - set `child->rightChild` to `parent->rightChild`
  - change `parent->rightChild` to point to `child`

# Examples

Insert a node D as a right child of B.



**\*Figure 5.24: Insertion of child as a right child of parent in a threaded binary tree (p.217)**



# Right Insertion in Threaded BTs

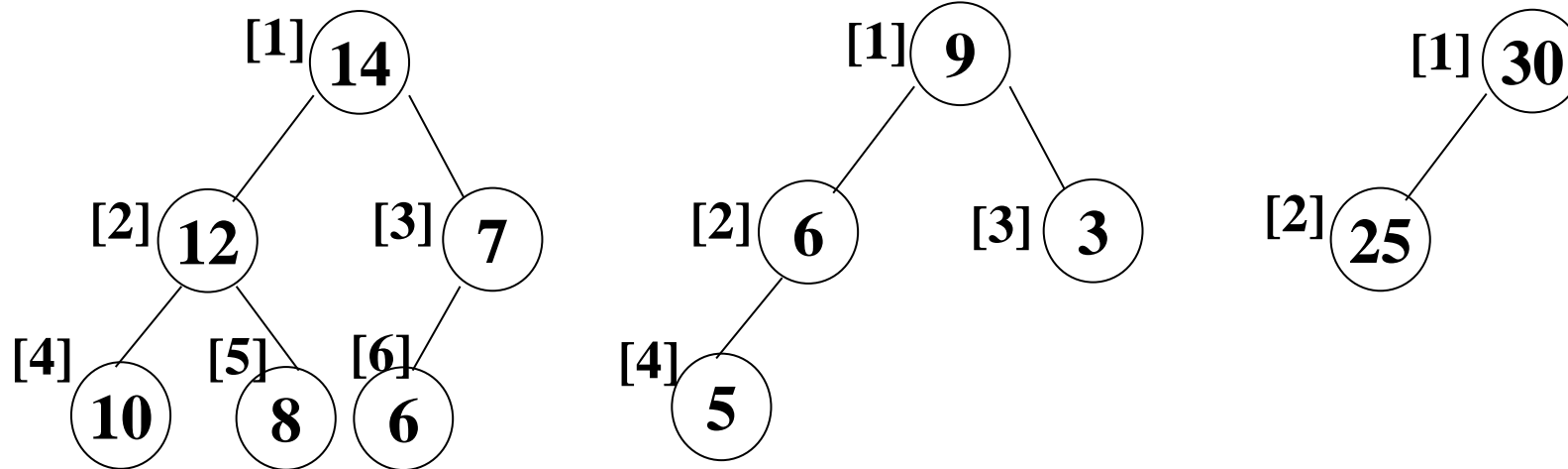
```
void insert_right(threaded_pointer parent,
                  threaded_pointer child)
{
    threaded_pointer temp;
    (1) child->rightChild = parent->rightChild;
    child->right_thread = parent->right_thread;
    (2) child->leftChild = parent;    case (a)
    child->left_thread = TRUE;
    (3) parent->rightChild = child;
    parent->right_thread = FALSE;
    if (!child->right_thread) { case (b)
    (4) temp = insucc(child);
        temp->leftChild = child;
    }
}
```



# Heap

- A *max tree* is a tree in which the key value in each node is **no smaller than** the key values in its children. A *max heap* is a **complete binary tree** that is also a max tree.
- A *min tree* is a tree in which the key value in each node is **no larger than** the key values in its children. A *min heap* is a **complete binary tree** that is also a min tree.
- Operations on heaps
  - creation of an empty heap
  - insertion of a new element into the heap;
  - deletion of the largest element from the heap

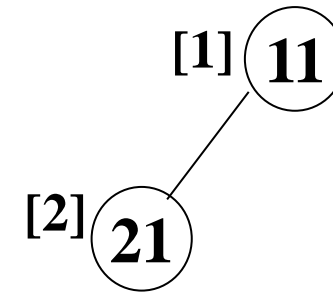
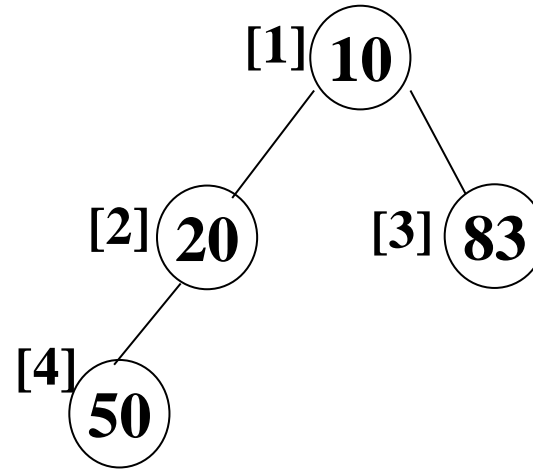
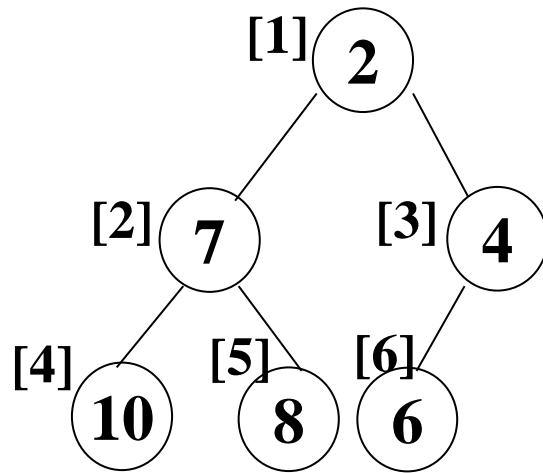
## Sample max heaps



### Property:

The root of max heap (min heap) contains the largest (smallest).

## Sample min heaps



# ADT for Max Heap

structure MaxHeap

objects: a complete binary tree of  $n > 0$  elements organized so that the value in each node is at least as large as those in its children

functions:

for all *heap* belong to *MaxHeap*, *item* belong to *Element*, *n*, *max\_size* belong to integer

MaxHeap Create(max\_size)::= create an empty heap that can hold a maximum of max\_size elements

Boolean HeapFull(heap, n)::= if ( $n == \text{max\_size}$ ) return TRUE else return FALSE

MaxHeap Insert(heap, item, n)::= if ( $\neg \text{HeapFull}(\text{heap}, n)$ ) insert item into heap and return the resulting heap else return error

Boolean HeapEmpty(heap, n)::= if ( $n > 0$ ) return FALSE else return TRUE

Element Delete(heap, n)::= if ( $\neg \text{HeapEmpty}(\text{heap}, n)$ ) return one instance of the **largest** element in the heap and remove it from the heap else return error

# Application: Priority Queue

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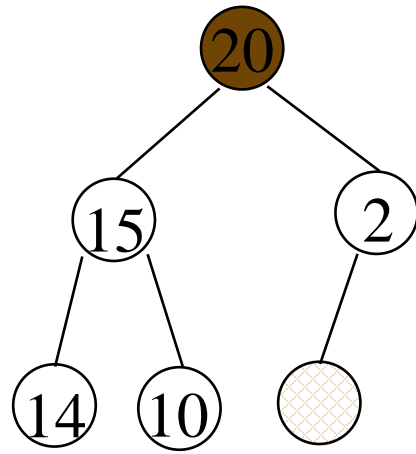
## Machine service

- Amount of time (min heap)
- Amount of payment (max heap)

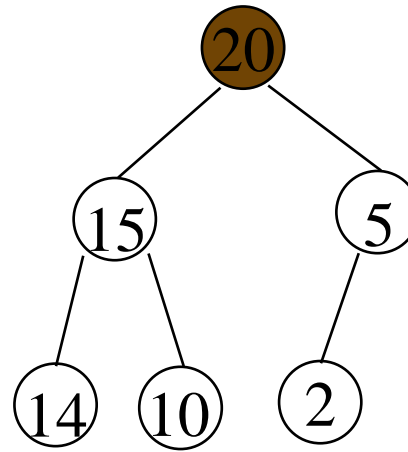
## Factory

- time tag

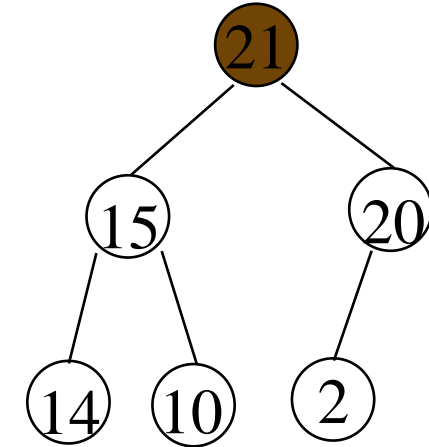
# Example of Insertion to Max Heap



initial location of new node



insert 5 into heap



insert 21 into heap

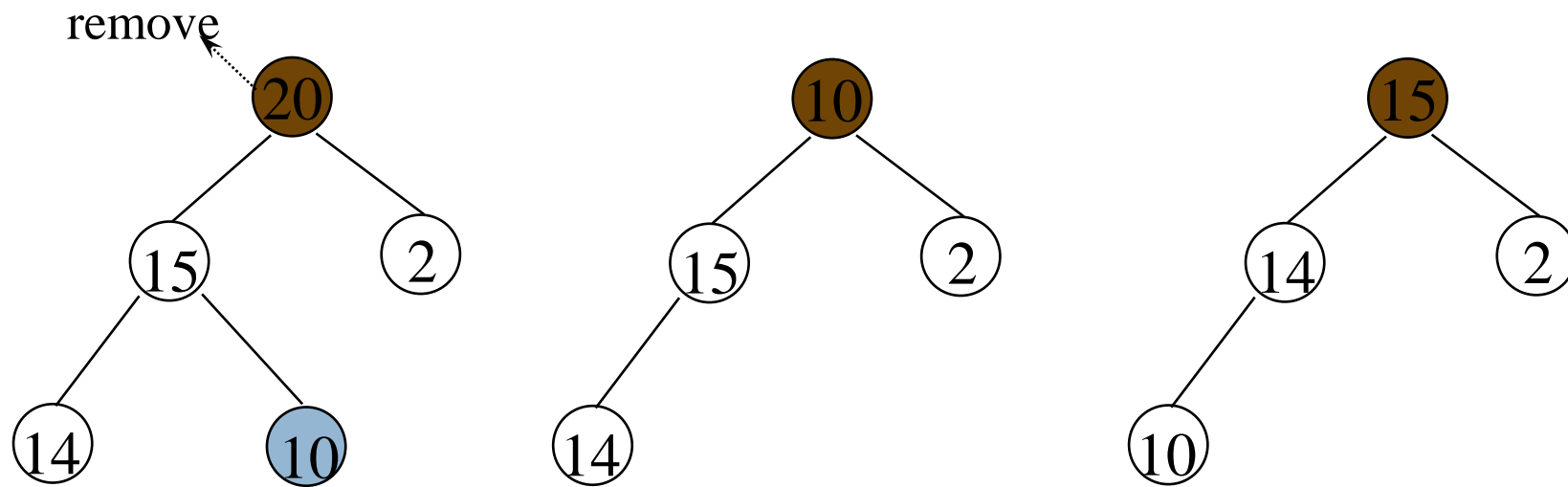
# Insertion into a Max Heap

```
void insert_max_heap(element item, int *n)
{
    int i;
    if (HEAP_FULL(*n)) {
        fprintf(stderr, "the heap is full.\n");
        exit(1);
    }
    i = ++(*n);
    while ((i!=1) && (item.key>heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    }
    heap[i] = item;
}
```

$$2^k - 1 = n \implies k = \lceil \log_2(n+1) \rceil$$

$$O(\log_2 n)$$

# Example of Deletion from Max Heap





# Deletion from a Max Heap

```
element delete_max_heap(int *n)
{
    int parent, child;
    element item, temp;
    if (HEAP_EMPTY(*n)) {
        fprintf(stderr, "The heap is empty\n");    exit(1);    }
    /* save value of the element with the
       highest key */
    item = heap[1];
    /* use last element in heap to adjust heap */
    temp = heap[(*n)--];
    parent = 1;
    child = 2;
}
```

```
while (child <= *n) {  
    /* find the larger child of the current  
       parent */  
    if ((child < *n) &&  
        (heap[child].key < heap[child+1].key))  
        child++;  
    if (temp.key >= heap[child].key) break;  
    /* move to the next lower level */  
    heap[parent] = heap[child];  
    child *= 2;  
}  
heap[parent] = temp;  
return item;  
}
```

# Binary Search Tree

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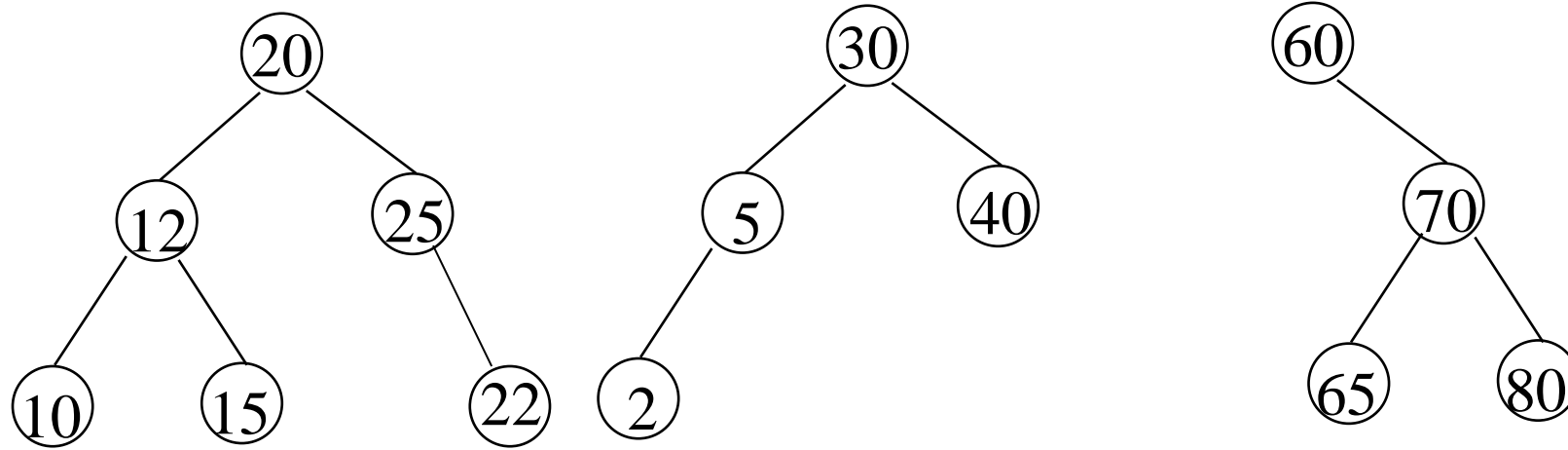
## Heap

- a min (max) element is deleted.  $O(\log_2 n)$
- deletion of an arbitrary element  $O(n)$
- search for an arbitrary element  $O(n)$

## Binary search tree

- Every element has a unique key.
- The keys in a nonempty **left subtree** (**right subtree**) are **smaller** (**larger**) than the key in the root of subtree.
- The left and right subtrees are also binary search trees.

# Examples of Binary Search Trees



# Searching a Binary Search Tree

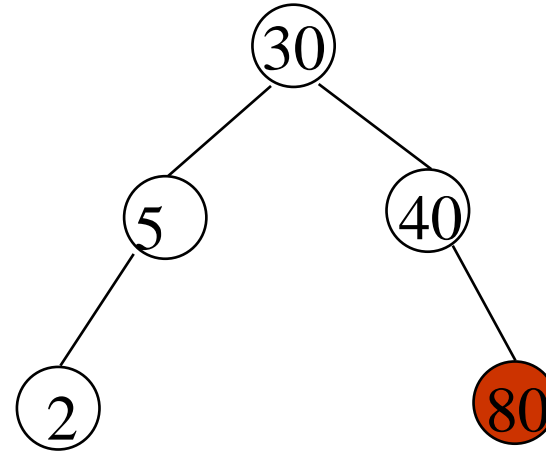
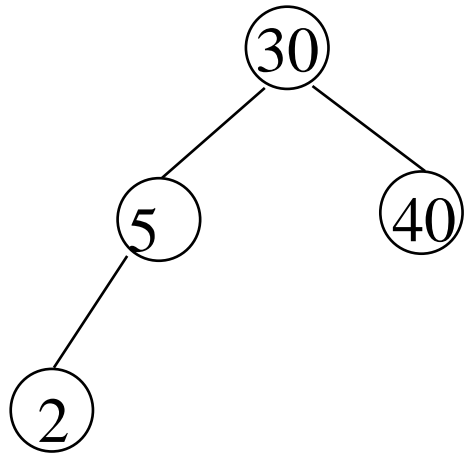
```
treePointer search(treePointer root,  
                  int key)  
{  
/* return a pointer to the node that contains key. If there  
is no such  
node, return NULL */  
  
if (!root) return NULL;  
if (key == root->data) return root;  
if (key < root->data)  
    return search(root->leftChild,  
                  key) ;  
return search(root->rightChild, key) ;  
}
```

# Another Searching Algorithm

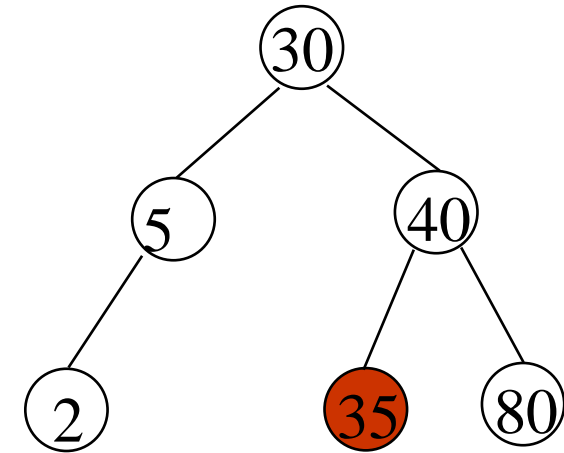
```
treePointer search2 (treePointer tree, int key)
{
    while (tree) {
        if (key == tree->data) return tree;
        if (key < tree->data)
            tree = tree->leftChild;
        else tree = tree->rightChild;
    }
    return NULL;
}
```

$O(h)$

# Insert Node in Binary Search Tree



Insert 80



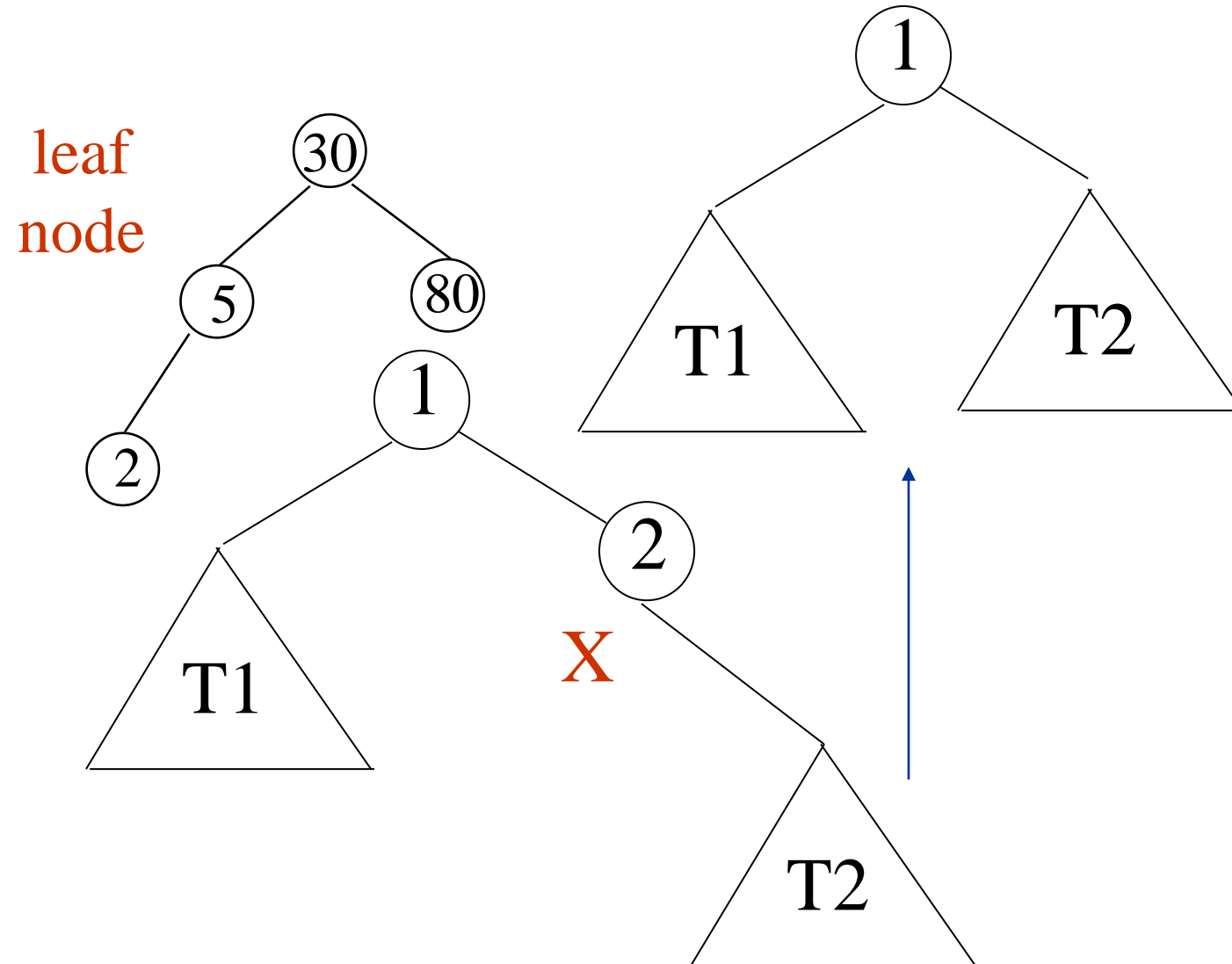
Insert 35

# Insertion into A Binary Search Tree

```
void insert_node(treePointer *node, int num)
{treePointer ptr,
    temp = modified_search(*node, num);
    if (temp || !(*node)) {
        ptr = (treePointer) malloc(sizeof(node));
        if (IS_FULL(ptr)) {
            fprintf(stderr, "The memory is full\n");
            exit(1);
        }
        ptr->data = num;
        ptr->leftChild = ptr->rightChild = NULL;
        if (*node)
            if (num < temp->data) temp->leftChild = ptr;
            else temp->rightChild = ptr;
        else *node = ptr;
    }
}
```

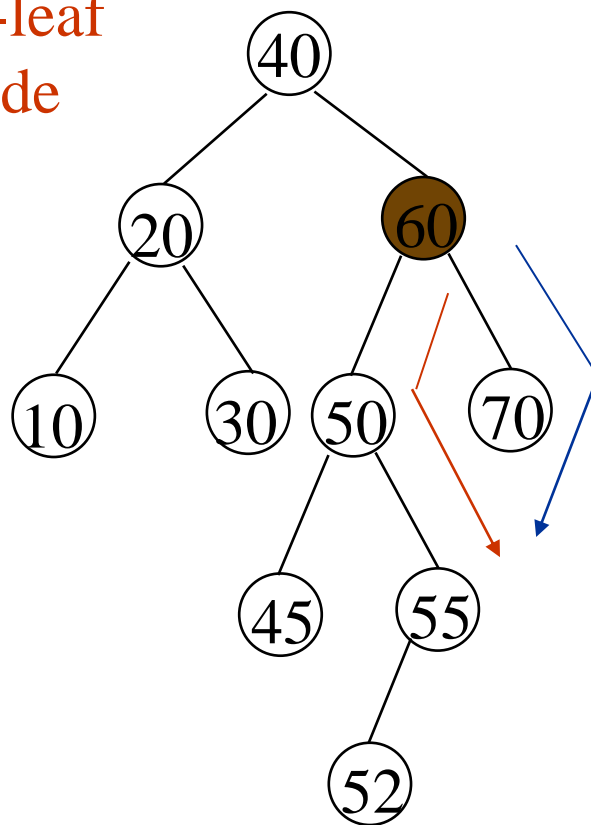


# Deletion for A Binary Search Tree

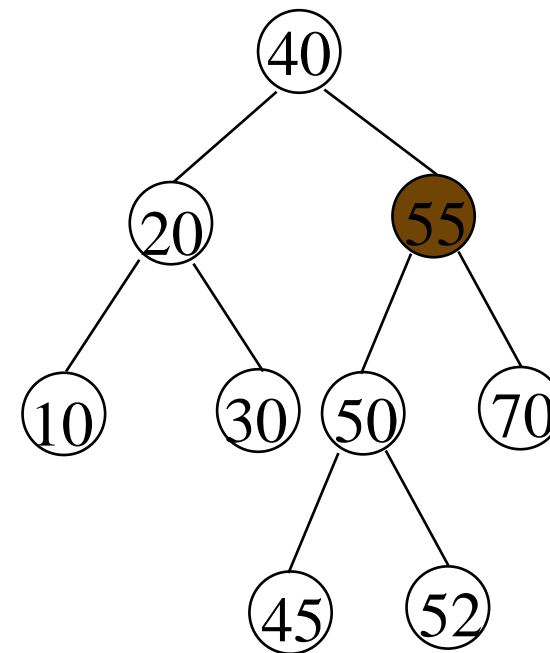


# Deletion for A Binary Search Tree

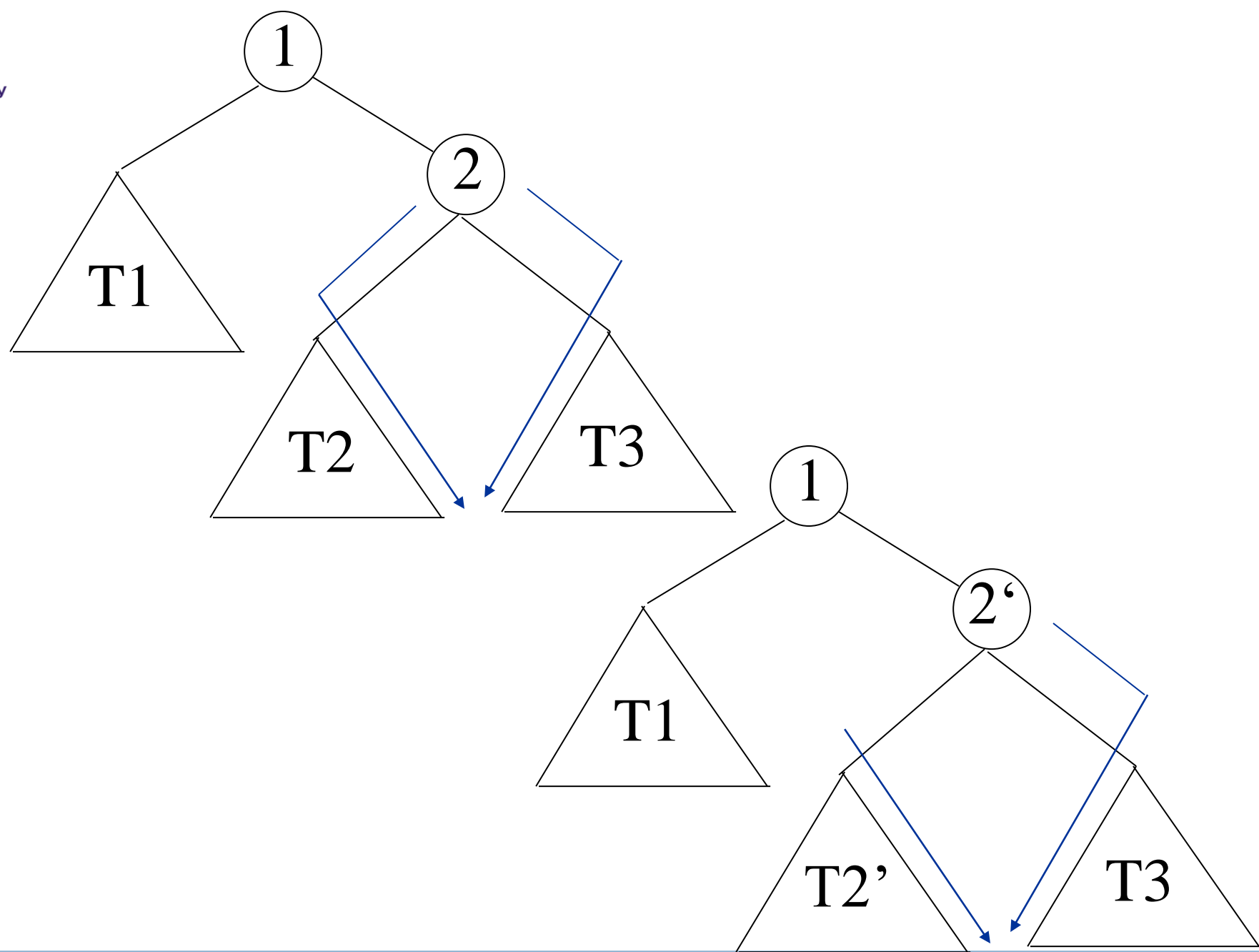
non-leaf  
node



Before deleting 60



After deleting 60



# Selection Trees

---

- (1) Winner tree
- (2) Loser tree

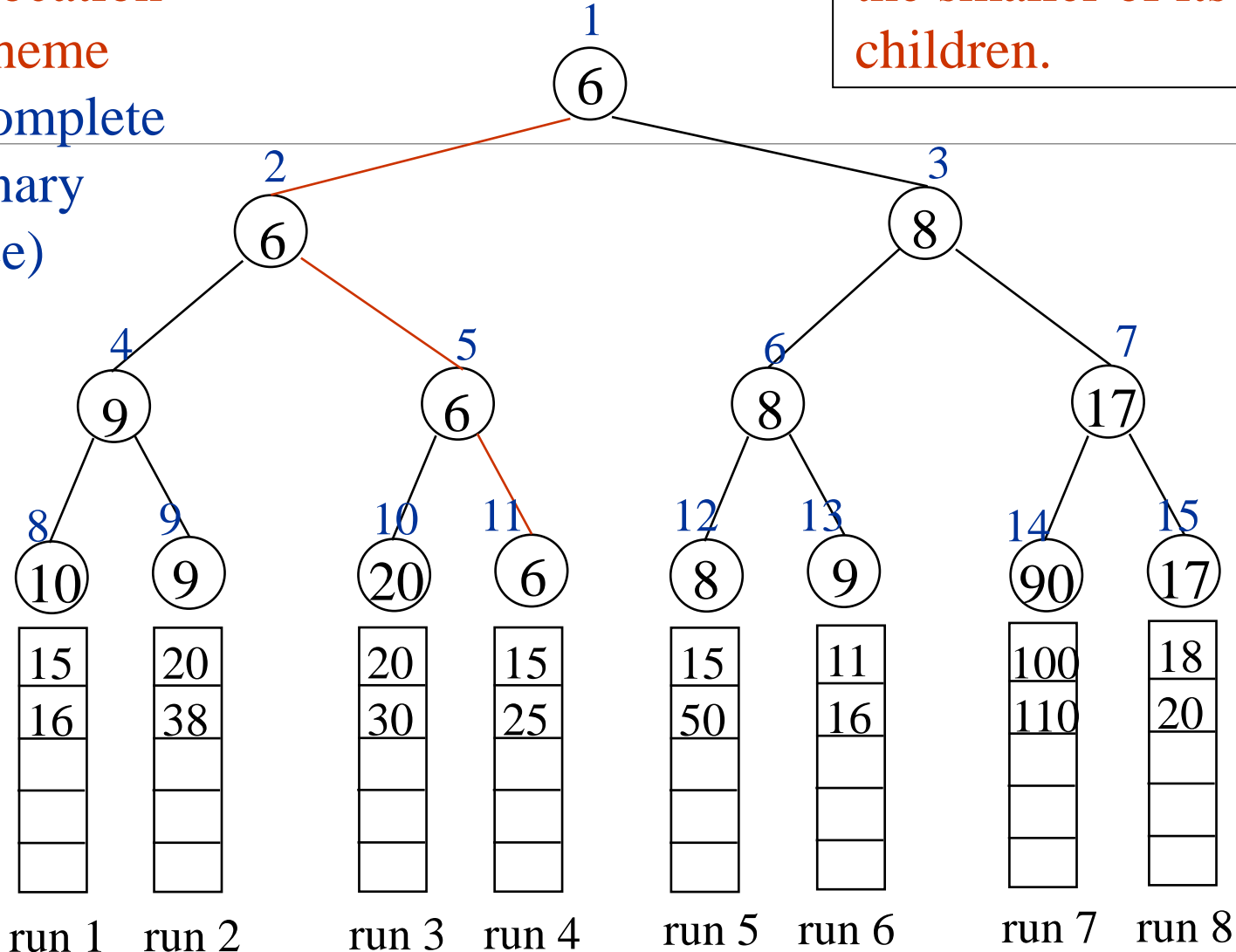
sequential  
allocation  
scheme  
(complete

binary  
tree)

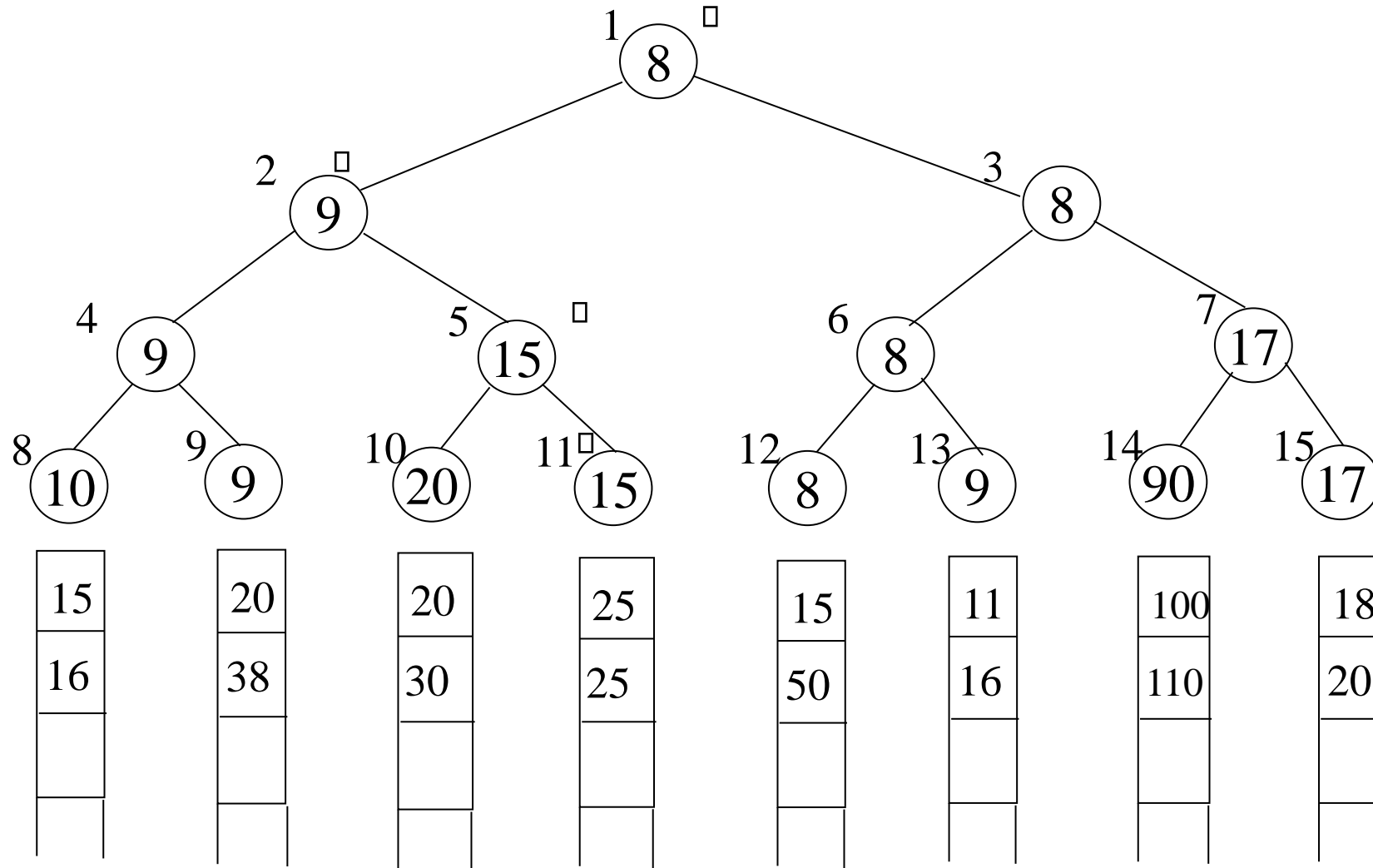
# winner tree

Each node represents  
the smaller of its two  
children.

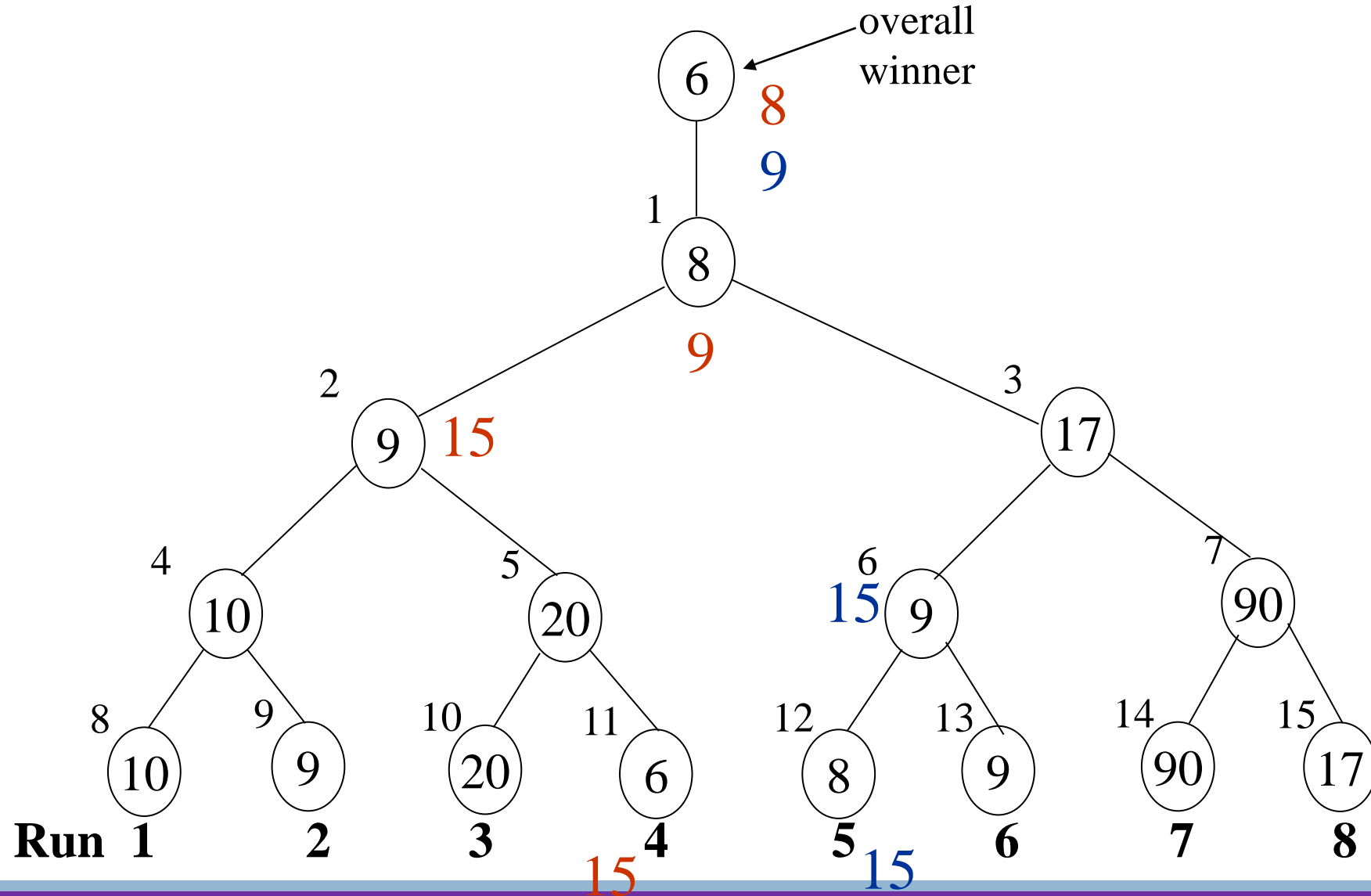
ordered sequence



## Selection tree of after one record has been output and the tree restructured

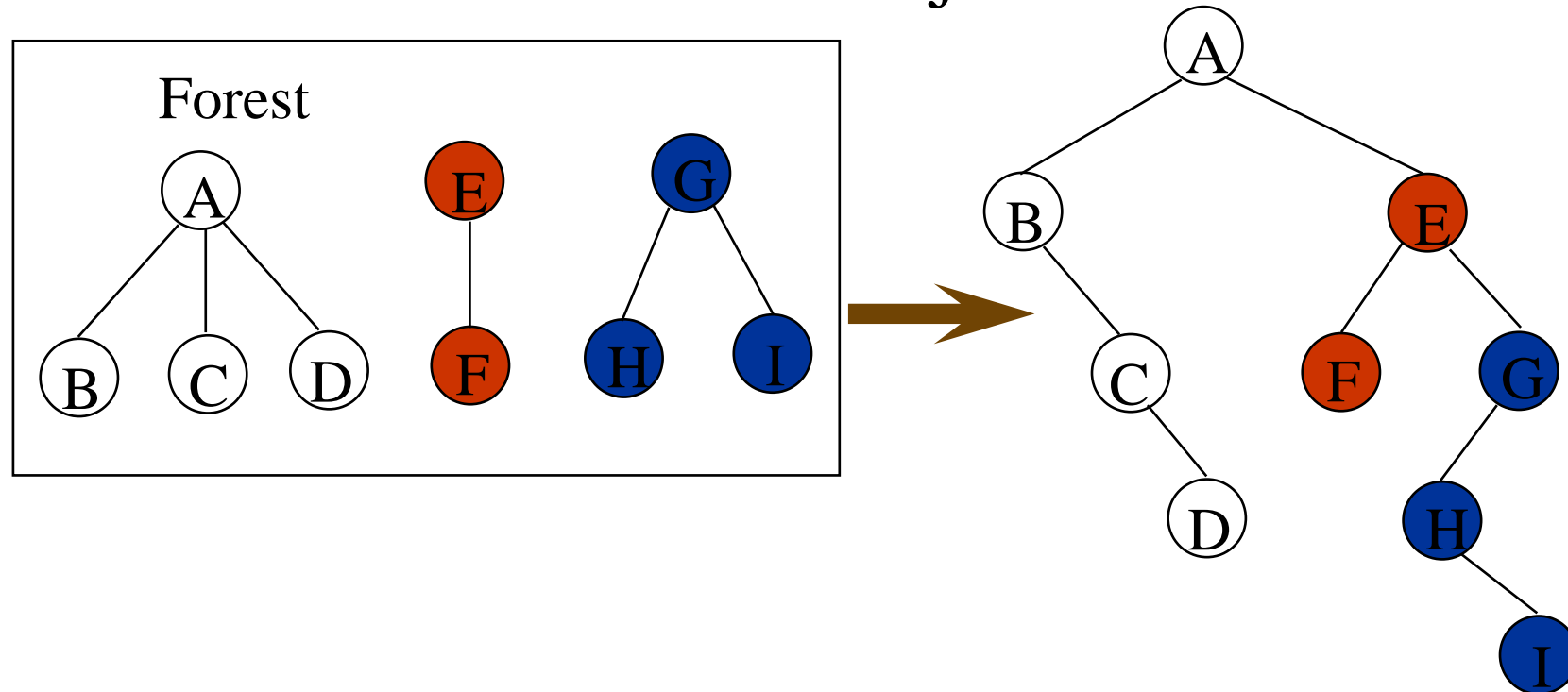


**\*Figure 5.36:** Tree of losers corresponding to Figure 5.34 (p.235)



# Forest

- A forest is a set of  $n \geq 0$  disjoint trees





# Transform a forest into a binary tree

---

$T_1, T_2, \dots, T_n$ : a forest of trees

$B(T_1, T_2, \dots, T_n)$ : a binary tree corresponding to this forest

algorithm

- (1) empty, if  $n = 0$
- (2) has root equal to  $\text{root}(T_1)$   
has left subtree equal to  $B(T_{11}, T_{12}, \dots, T_{1m})$   
has right subtree equal to  $B(T_2, T_3, \dots, T_n)$

# Forest Traversals

## □ Preorder

- If F is empty, then return
- Visit the root of the first tree of F
- Traverse the subtrees of the first tree in tree preorder
- Traverse the remaining trees of F in preorder

## □ Inorder

- If F is empty, then return
- Traverse the subtrees of the first tree in tree inorder
- Visit the root of the first tree
- Traverse the remaining trees of F is indorer

preorder: A B C D E F G H I

inorder: B C A E D G H F I

