

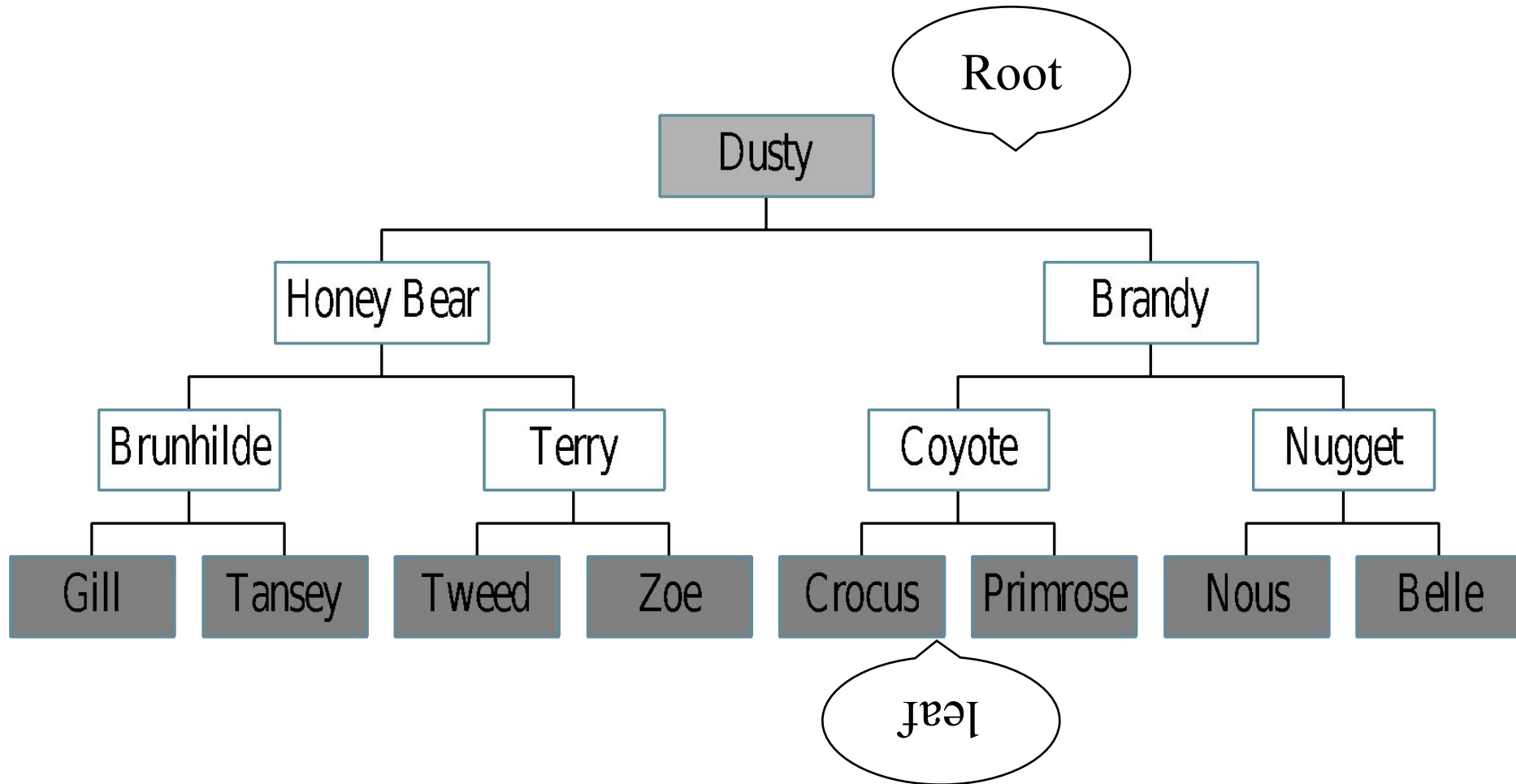
## CHAPTER 5

# Trees

All the programs in this file are selected from

Ellis Horowitz, Sartaj Sahni, and Susan Anderson-Freed  
“Fundamentals of Data Structures in C”,  
Computer Science Press, 1992.

# Trees



# Definition of Tree

- A tree is a finite set of one or more nodes such that:
- There is a specially designated node called the root.
- The remaining nodes are partitioned into  $n \geq 0$  disjoint sets  $T_1, \dots, T_n$ , where each of these sets is a tree.
- We call  $T_1, \dots, T_n$  the subtrees of the root.

# Level and Depth

node (13)

degree of a node

leaf (terminal)

nonterminal

parent

children

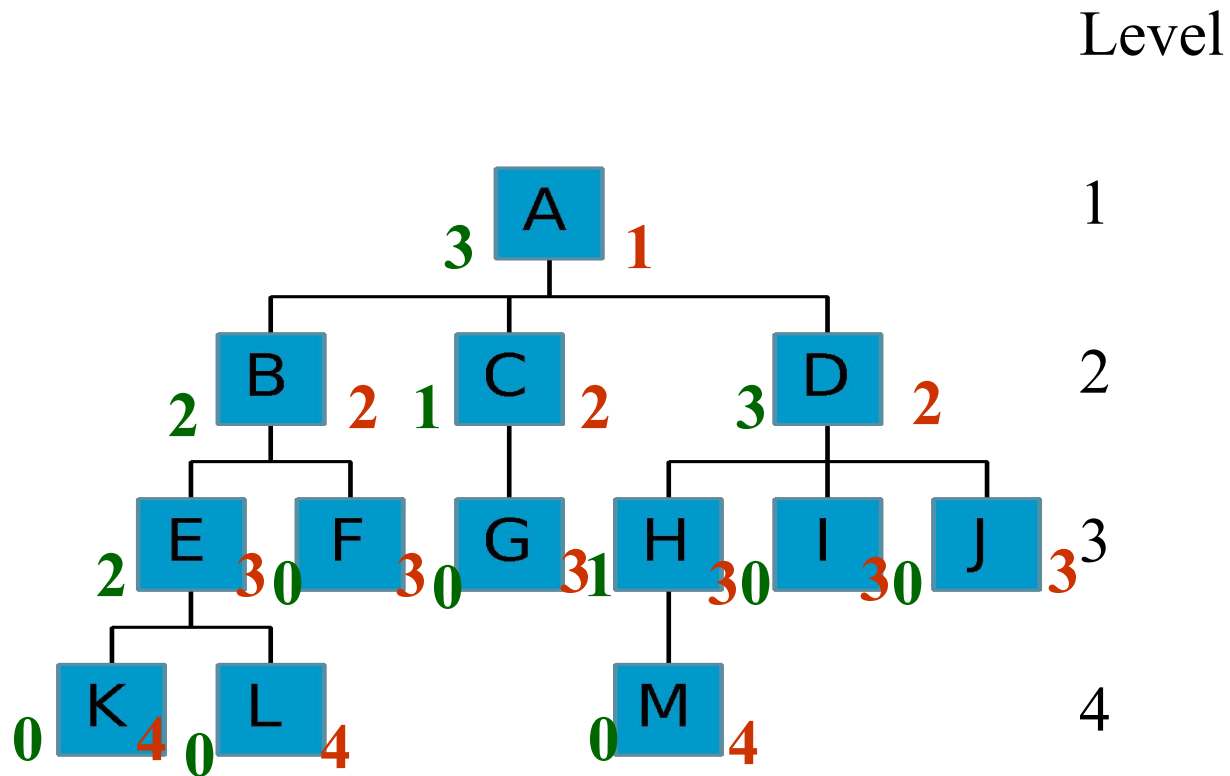
sibling

degree of a tree (3)

ancestor

level of a node

height of a tree (4)



# Terminology

- The degree of a node is the number of subtrees of the node
  - The degree of A is 3; the degree of C is 1.
- The node with degree 0 is a leaf or terminal node.
- A node that has subtrees is the *parent* of the roots of the subtrees.
- The roots of these subtrees are the *children* of the node.
- Children of the same parent are *siblings*.
- The ancestors of a node are all the nodes along the path from the root to the node.

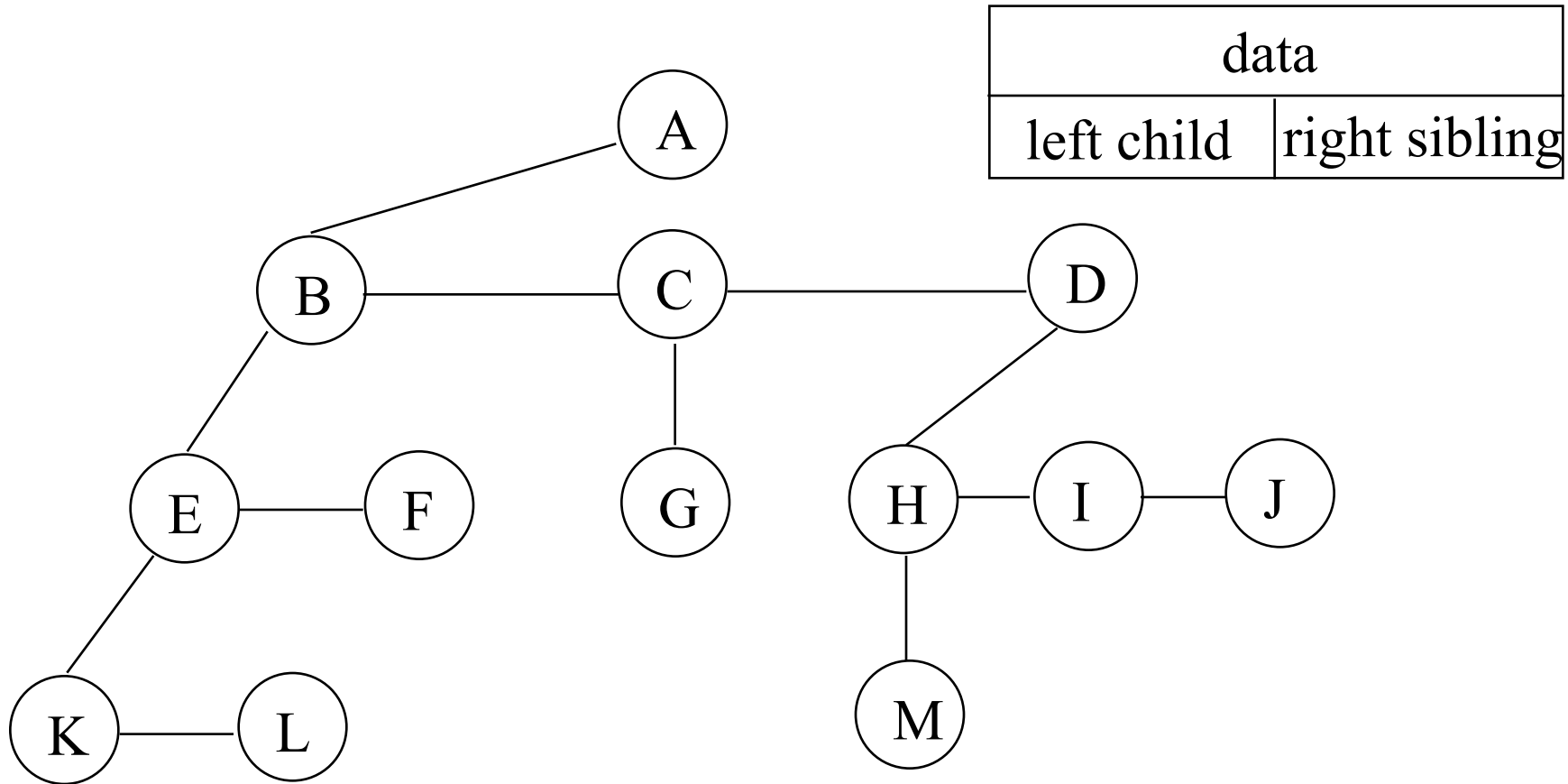
# Representation of Trees

- List Representation
  - $(A(B(E(K, L), F), C(G), D(H(M), I, J)))$
  - The root comes first, followed by a list of sub-trees

data	link 1	link 2	...	link n
------	--------	--------	-----	--------

How many link fields are  
needed in such a  
representation?

# Left Child - Right Sibling

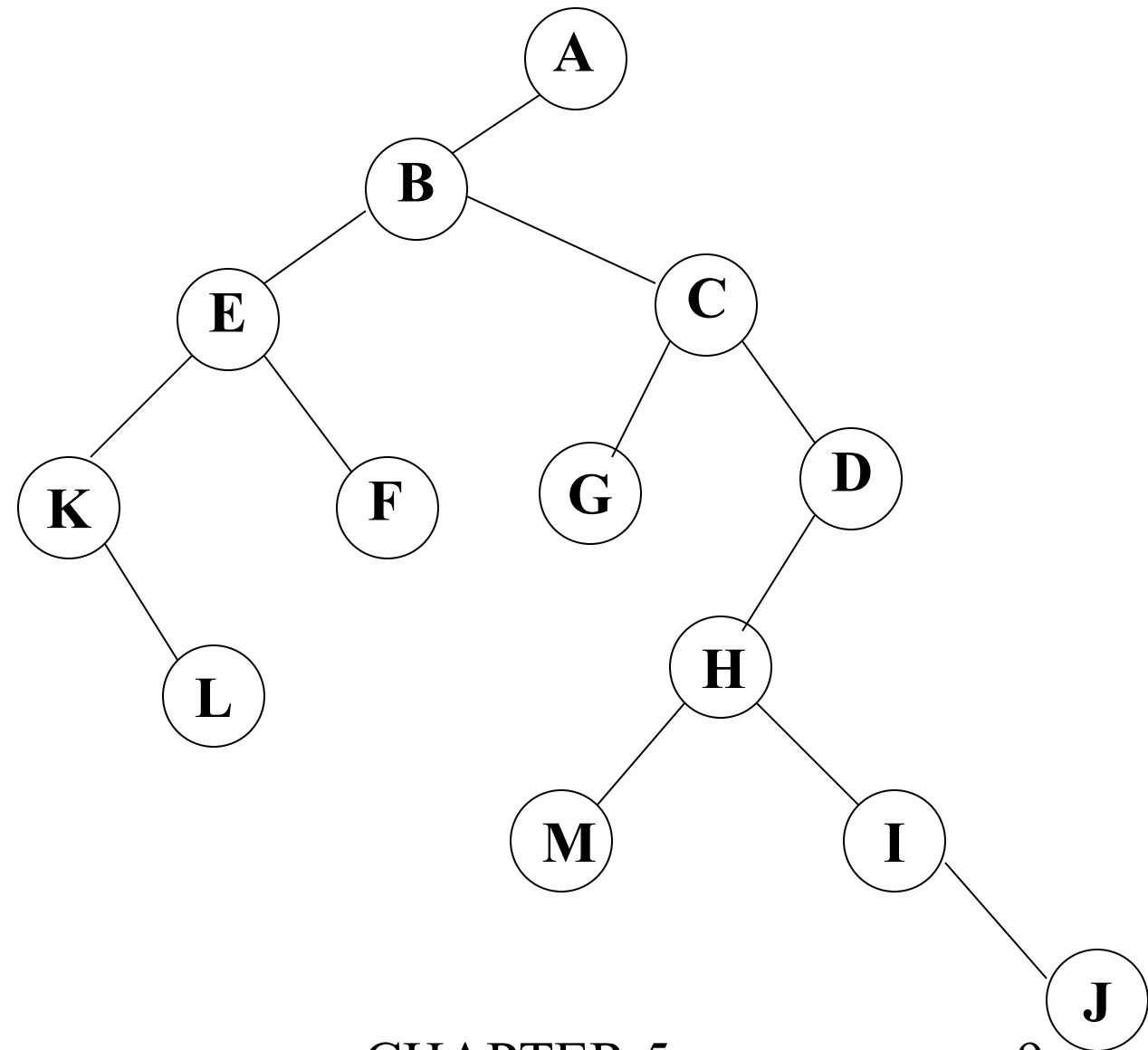


# Binary Trees

- A binary tree is a finite set of nodes that is either empty or consists of a root and two disjoint binary trees called *the left subtree* and *the right subtree*.
- Any tree can be transformed into binary tree.
  - by left child-right sibling representation
- The left subtree and the right subtree are distinguished.



**\*Figure 5.6:** Left child-right child tree representation of a tree (p.191)



# Abstract Data Type *Binary\_Tree*

structure *Binary\_Tree*(abbreviated *BinTree*) is objects: a finite set of nodes either empty or consisting of a root node, left *Binary\_Tree*, and right *Binary\_Tree*.

functions:

for all  $bt, bt1, bt2 \in BinTree, item \in element$   
*Bintree* Create() ::= creates an empty binary tree  
*Boolean* IsEmpty( $bt$ ) ::= if ( $bt == \text{empty binary tree}$ ) return *TRUE* else return *FALSE*

*BinTree* MakeBT( $bt1$ ,  $item$ ,  $bt2$ ) ::= return a binary tree  
whose left subtree is  $bt1$ , whose right subtree is  $bt2$ ,  
and whose root node contains the data  $item$

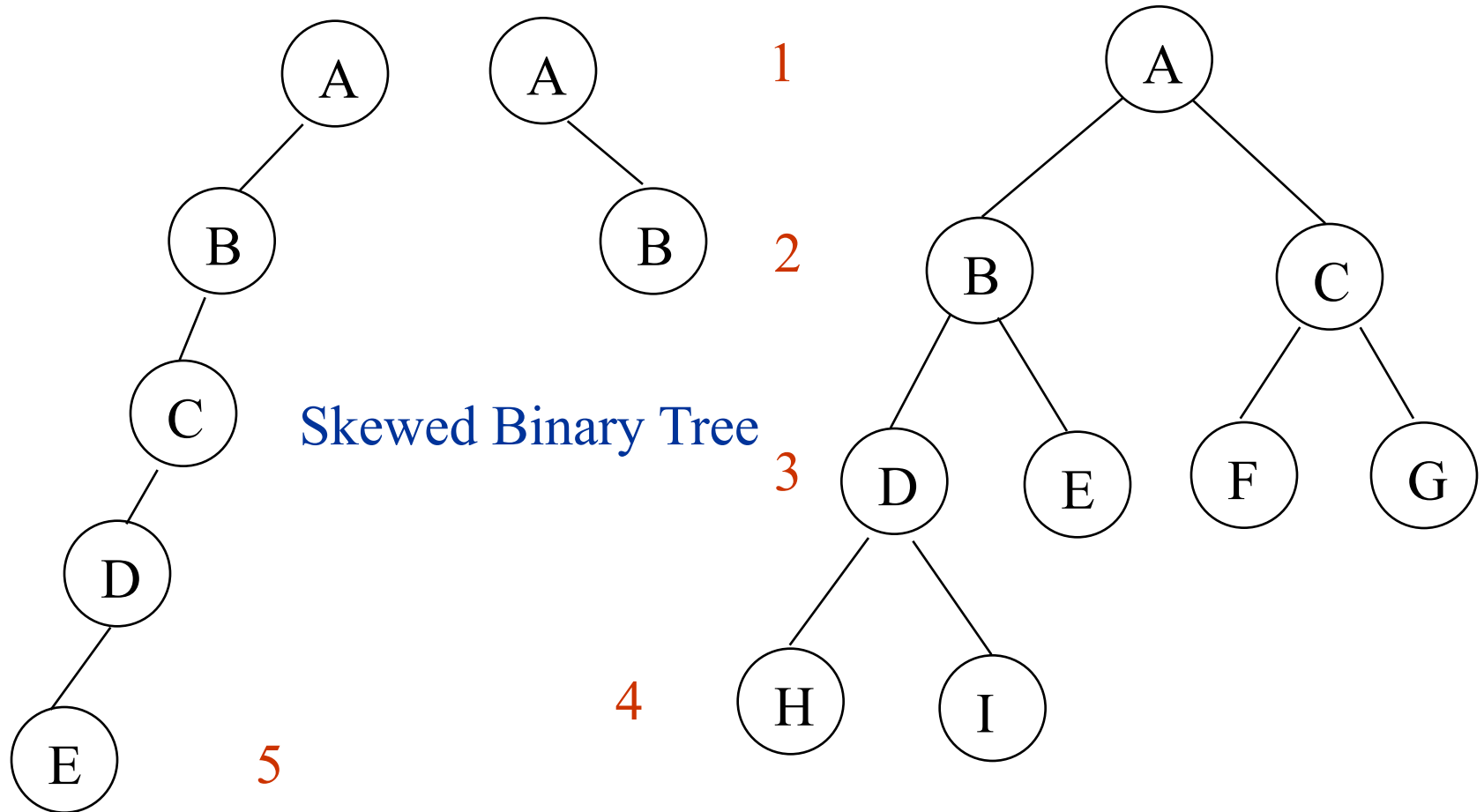
*Bintree* Lchild( $bt$ ) ::= if (IsEmpty( $bt$ )) return error  
else return the left subtree of  $bt$

*element* Data( $bt$ ) ::= if (IsEmpty( $bt$ )) return error  
else return the data in the root node of  $bt$

*Bintree* Rchild( $bt$ ) ::= if (IsEmpty( $bt$ )) return error  
else return the right subtree of  $bt$

# Samples of Trees

Complete Binary Tree



# Maximum Number of Nodes in BT

- The maximum number of nodes on level  $i$  of a binary tree is  $2^{i-1}$ ,  $i \geq 1$ .
- The maximum number of nodes in a binary tree of depth  $k$  is  $2^k - 1$ ,  $k \geq 1$ .

**Prove by induction.**

$$\sum_{i=1}^k 2^{i-1} = 2^k - 1$$

# Relations between Number of Leaf Nodes and Nodes of Degree 2

*For any nonempty binary tree,  $T$ , if  $n_0$  is the number of leaf nodes and  $n_2$  the number of nodes of degree 2, then  $n_0 = n_2 + 1$*

**proof:**

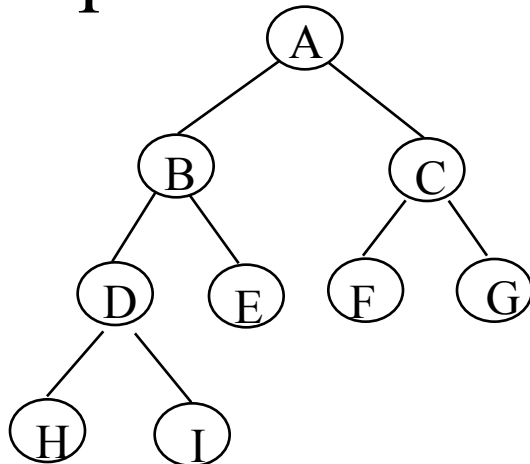
Let  $n$  and  $B$  denote the total number of nodes & branches in  $T$ .

Let  $n_0$ ,  $n_1$ ,  $n_2$  represent the nodes with no children, single child, and two children respectively.

$$\begin{aligned} n &= n_0 + n_1 + n_2, \quad B + 1 = n, \quad B = n_1 + 2n_2 \implies n_1 + 2n_2 + 1 = n \\ n_1 + 2n_2 + 1 &= n_0 + n_1 + n_2 \implies n_0 = n_2 + 1 \end{aligned}$$

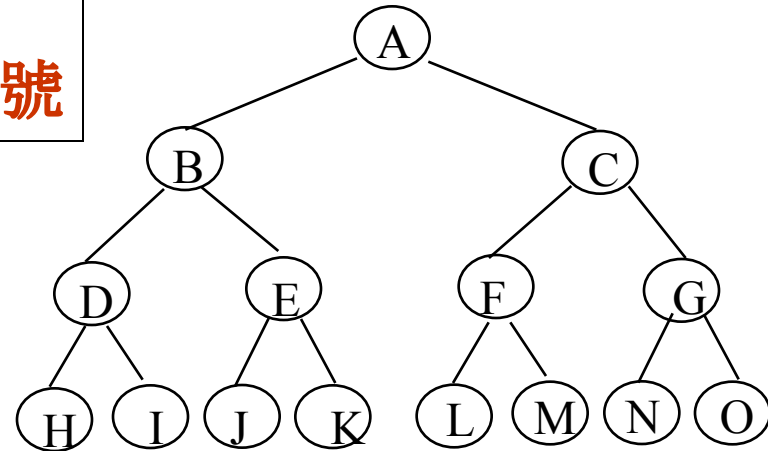
# Full BT VS Complete BT

- A full binary tree of depth  $k$  is a binary tree of depth  $k$  having  $2^{k+1}-1$  nodes,  $k \geq 0$ .
- A binary tree with  $n$  nodes and depth  $k$  is complete *iff* its nodes correspond to the nodes numbered from 1 to  $n$  in the full binary tree of depth  $k$ .



Complete binary tree

由上至下，  
由左至右編號



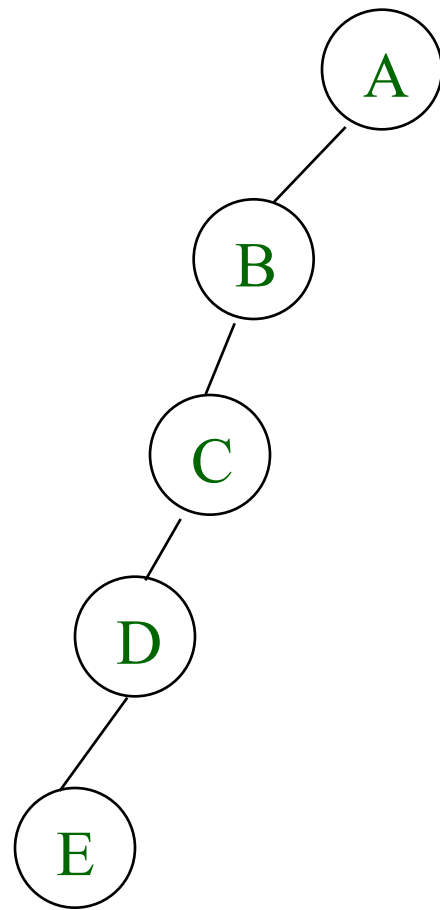
Full binary tree of depth 4

# Binary Tree Representations

- If a complete binary tree with  $n$  nodes (depth =  $\log n + 1$ ) is represented sequentially, then for any node with index  $i$ ,  $1 \leq i \leq n$ , we have:
  - $parent(i)$  is at  $i/2$  if  $i \neq 1$ . If  $i=1$ ,  $i$  is at the root and has no parent.
  - $left\_child(i)$  is at  $2i$  if  $2i \leq n$ . If  $2i > n$ , then  $i$  has no left child.
  - $right\_child(i)$  is at  $2i+1$  if  $2i+1 \leq n$ . If  $2i+1 > n$ , then  $i$  has no right child.



# Sequential Representation

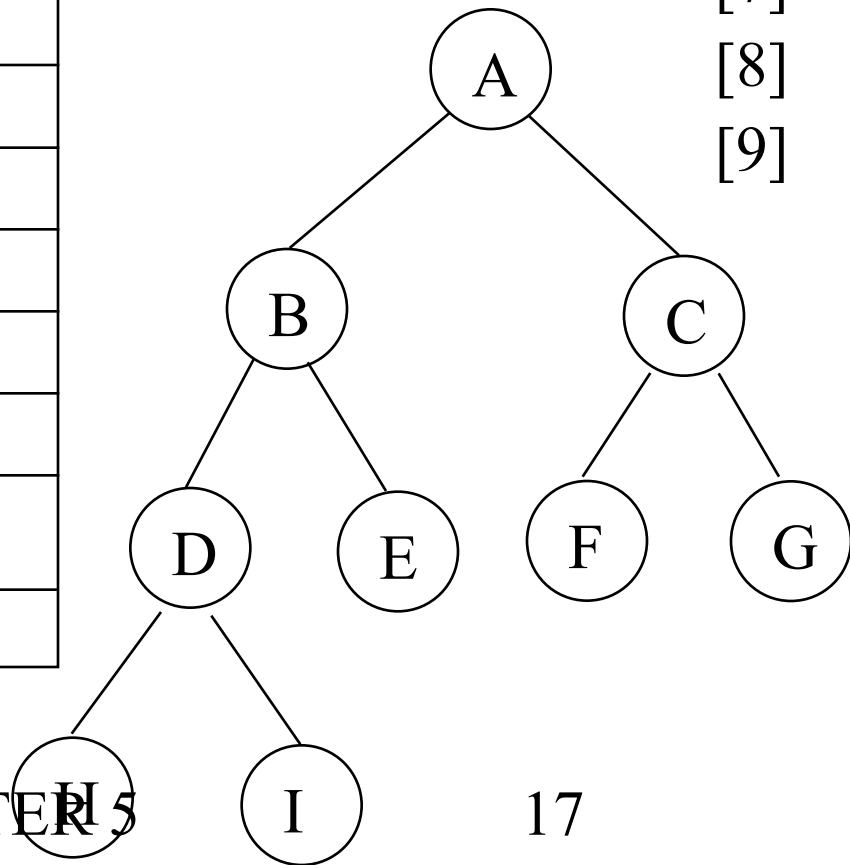


[1]	A
[2]	B
[3]	--
[4]	C
[5]	--
[6]	--
[7]	--
[8]	D
[9]	--
.	.
[16]	E

(1) waste space  
(2) insertion/deletion problem

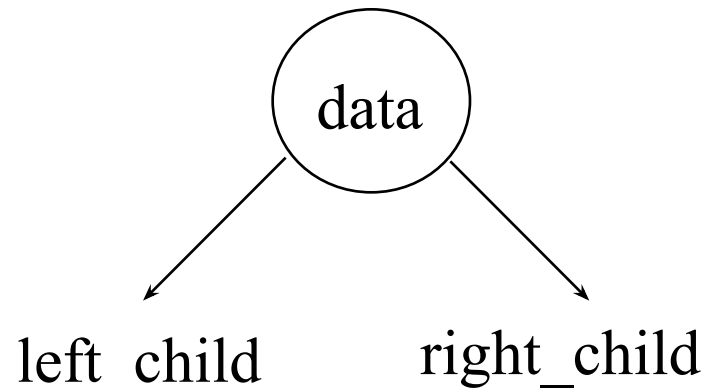
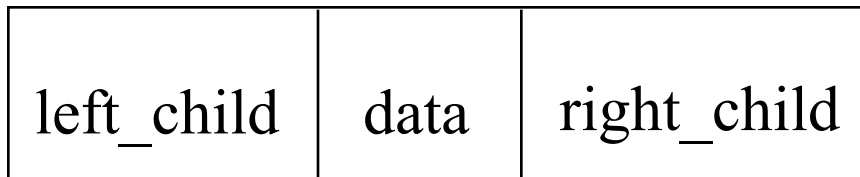
[1]  
[2]  
[3]  
[4]  
[5]  
[6]  
[7]  
[8]  
[9]

A
B
C
D
E
F
G
H
I



# Linked Representation

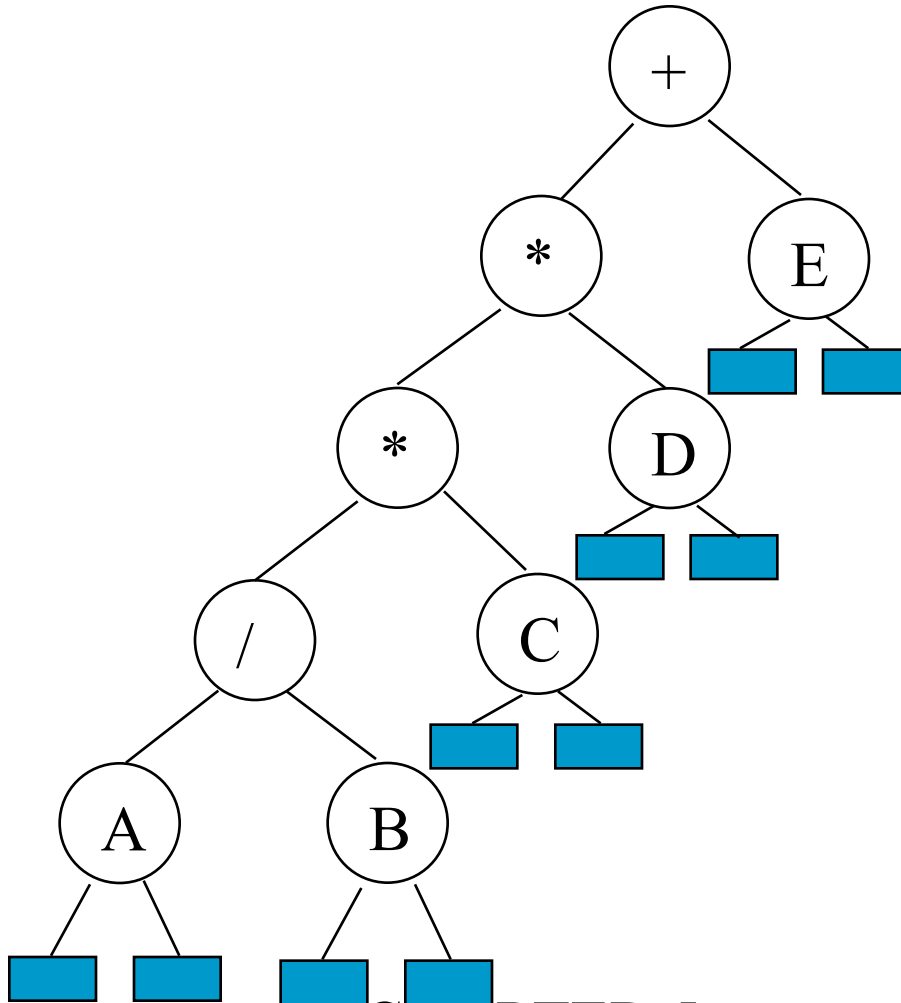
```
typedef struct node *tree_pointer;  
typedef struct node {  
    int data;  
    tree_pointer left_child, right_child;  
};
```



# Binary Tree Traversals

- Let L, V, and R stand for moving left, visiting the node, and moving right.
- There are six possible combinations of traversal
  - LVR, LRV, VLR, VRL, RVL, RLV
- Adopt convention that we traverse left before right, only 3 traversals remain
  - LVR, LRV, VLR
  - inorder, postorder, preorder

# Arithmetic Expression Using BT



inorder traversal

$A / B * C * D + E$

infix expression

preorder traversal

$+ * * / A B C D E$

prefix expression

postorder traversal

$A B / C * D * E +$

postfix expression

level order traversal

$+ * E * D / C A B$

# Inorder Traversal (recursive version)

```
void inorder(tree_pointer ptr)
/* inorder tree traversal */
{
    if (ptr) {
        inorder(ptr->left_child);
        printf("%d", ptr->data);
        indorder(ptr->right_child);
    }
}
```

$A / B * C * D + E$
---------------------

# Preorder Traversal (recursive version)

```
void preorder(tree_pointer ptr)
/* preorder tree traversal */
{
    if (ptr) {
        printf("%d", ptr->data);
        preorder(ptr->left_child);
        predorder(ptr->right_child);
    }
}
```

+ * * / A B C D E
-------------------

# Postorder Traversal (recursive version)

```
void postorder(tree_pointer ptr)
/* postorder tree traversal */
{
    if (ptr) {
        postorder(ptr->left_child);
        postorder(ptr->right_child);
        printf("%d", ptr->data);
    }
}
```

A B / C \* D \* E +

# Iterative Inorder Traversal

(using stack)

```
void iter_inorder(tree_pointer node)
{
    int top= -1; /* initialize stack */
    tree_pointer stack[MAX_STACK_SIZE];
    for (;;) {
        for (; node; node=node->left_child)
            add(&top, node); /* add to stack */
        node= delete(&top);
        /* delete from stack */
        if (!node) break; /* empty stack */
        printf("%D", node->data);
        node = node->right_child;
    }
}
```

**$O(n)$**



# Trace Operations of Inorder Traversal

Call of inorder	Value in root	Action	Call of inorder	Value in root	Action
1	+		11	C	
2	*		12	NULL	
3	*		11	C	printf
4	/		13	NULL	
5	A		2	*	printf
6	NULL		14	D	
5	A	printf	15	NULL	
7	NULL		14	D	printf
4	/	printf	16	NULL	
8	B		1	+	printf
9	NULL		17	E	
8	B	printf	18	NULL	
10	NULL		17	E	printf
3	*	printf	19	NULL	

# Level Order Traversal

(using queue)

```
void level_order(tree_pointer ptr)
/* level order tree traversal */
{
    int front = rear = 0;
    tree_pointer queue[MAX_QUEUE_SIZE];
    if (!ptr) return; /* empty queue */
    addq(front, &rear, ptr);
    for (;;) {
        ptr = deleteq(&front, rear);
```

```

if (ptr) {
    printf("%d", ptr->data);
    if (ptr->left_child)
        addq(front, &rear,
              ptr->left_child);
    if (ptr->right_child)
        addq(front, &rear,
              ptr->right_child);
}
else break;
}
}

```

$+ * E * D / C A B$

# Copying Binary Trees

```
tree_pointer copy(tree_pointer original)
{
    tree_pointer temp;
    if (original) {
        temp=(tree_pointer) malloc(sizeof(node));
        if (IS_FULL(temp)) {
            fprintf(stderr, "the memory is full\n");
            exit(1);
        }
        temp->left_child=copy(original->left_child);
        temp->right_child=copy(original->right_child);
        temp->data=original->data;
        return temp;
    }
    return NULL;
}
```

postorder

# Equality of Binary Trees

the same topology and data

```
int equal(tree_pointer first, tree_pointer second)
{
    /* function returns FALSE if the binary trees first and
       second are not equal, otherwise it returns TRUE */

    return ((!first && !second) || (first && second &&
        (first->data == second->data) &&
        equal(first->left_child, second->left_child) &&
        equal(first->right_child, second->right_child)))
}
```

# Propositional Calculus Expression

- A variable is an expression.
- If  $x$  and  $y$  are expressions, then  $\neg x$ ,  $x \wedge y$ ,  $x \vee y$  are expressions.
- Parentheses can be used to alter the normal order of evaluation ( $\neg > \wedge > \vee$ ).
- Example:  $x_1 \vee (x_2 \wedge \neg x_3)$
- satisfiability problem: Is there an assignment to make an expression true?

$$(x_1 \wedge \neg x_2) \vee (\neg x_1 \wedge x_3) \vee \neg x_3$$

(t,t,t)

(t,t,f)

(t,f,t)

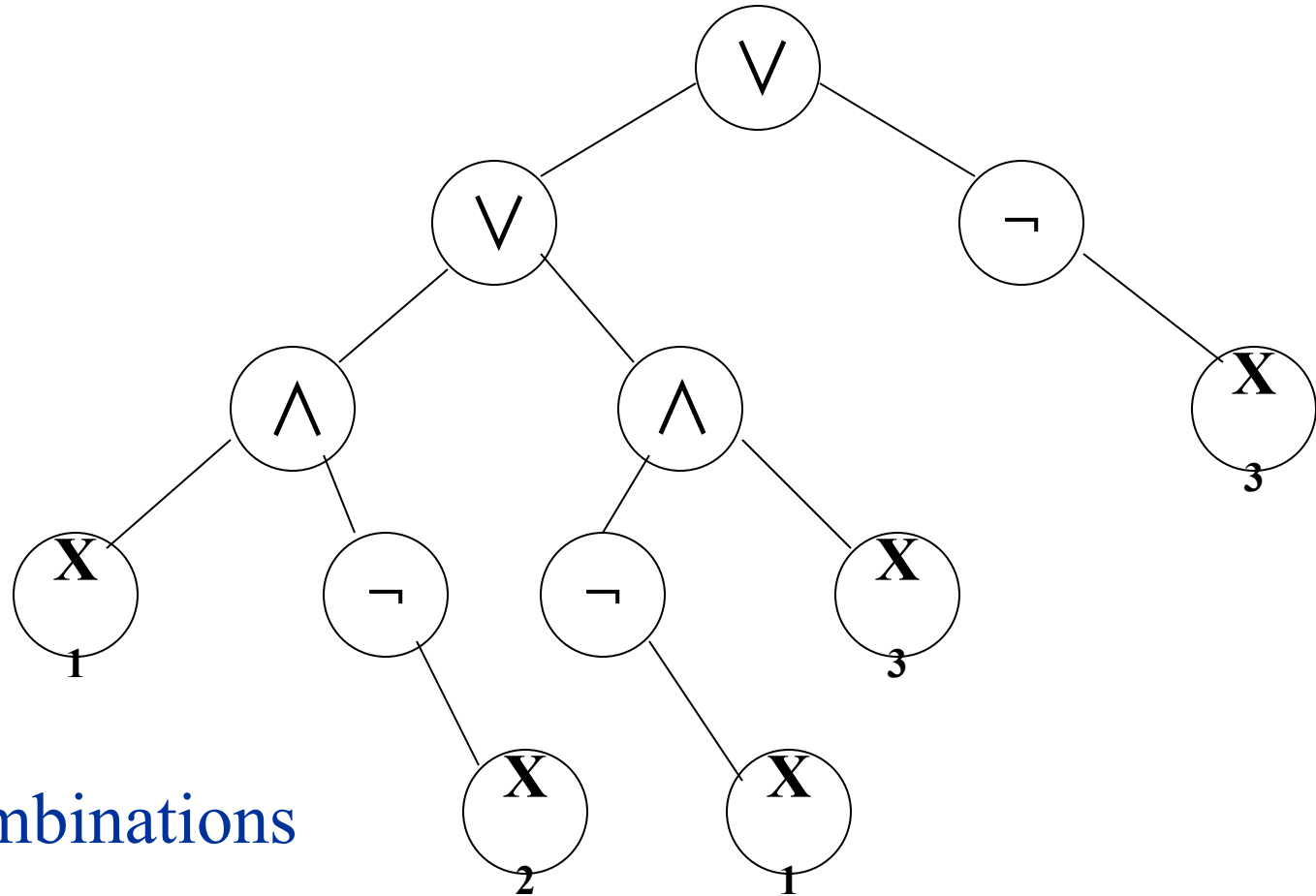
(t,f,f)

(f,t,t)

(f,t,f)

(f,f,t)

(f,f,f)



$2^n$  possible combinations  
for  $n$  variables

postorder traversal (postfix evaluation)

## node structure

<i>left_child</i>	<i>data</i>	<i>value</i>	<i>right_child</i>
-------------------	-------------	--------------	--------------------

```
typedef enum {not, and, or, true, false } logical;
typedef struct node *tree_pointer;
typedef struct node {
    tree_pointer list_child;
    logical      data;
    short int    value;
    tree_pointer right_child;
} ;
```



# First version of satisfiability algorithm

```
for (all  $2^n$  possible combinations) {  
    generate the next combination;  
    replace the variables by their values;  
    evaluate root by traversing it in postorder;  
    if (root->value) {  
        printf(<combination>);  
        return;  
    }  
}  
printf("No satisfiable combination \n");
```

## Post-order-eval function

```
void post_order_eval(tree_pointer node)
{
/* modified post order traversal to evaluate a propositional
calculus tree */
    if (node) {
        post_order_eval(node->left_child);
        post_order_eval(node->right_child);
        switch(node->data) {
            case not: node->value =
                        !node->right_child->value;
                        break;
```

```

case and:    node->value =
            node->right_child->value &&
            node->left_child->value;
            break;
case or:     node->value =
            node->right_child->value ||
            node->left_child->value;
            break;
case true:   node->value = TRUE;
            break;
case false:  node->value = FALSE;
            }
        }
    }

```

# Threaded Binary Trees

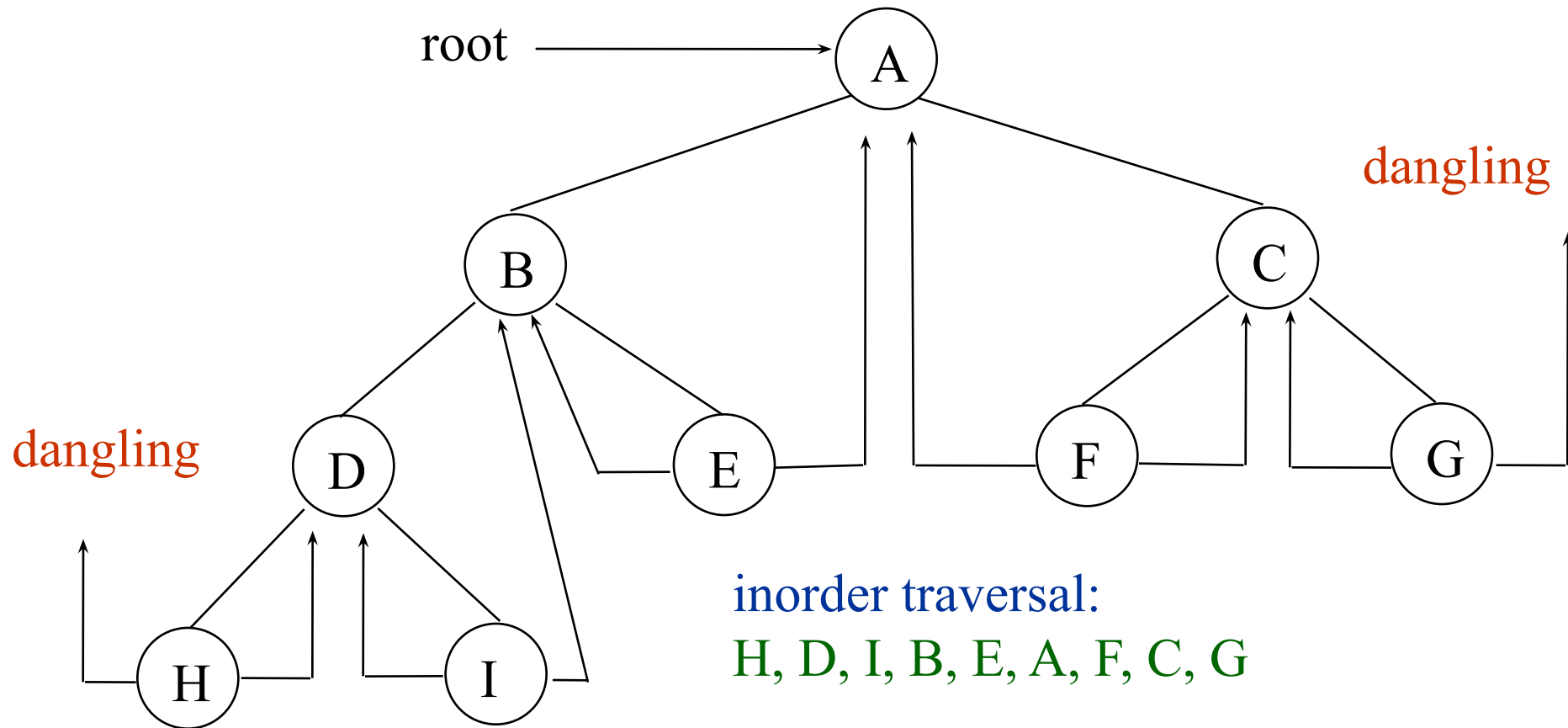
- Two many null pointers in current representation of binary trees
  - n: number of nodes
  - number of non-null links:  $n-1$
  - total links:  $2n$
  - null links:  $2n-(n-1)=n+1$
- Replace these null pointers with some useful “threads”.

# Threaded Binary Trees *(Continued)*

If `ptr->left_child` is null,  
replace it with a pointer to the node that would be  
visited *before* `ptr` in an *inorder traversal*

If `ptr->right_child` is null,  
replace it with a pointer to the node that would be  
visited *after* `ptr` in an *inorder traversal*

# A Threaded Binary Tree



# Data Structures for Threaded BT

left\_thread   left\_child   data   right\_child   right\_thread



TRUE: thread

FALSE: child

```
typedef struct threaded_tree
```

```
    *threaded_pointer;
```

```
typedef struct threaded_tree {
```

```
    short int left_thread;
```

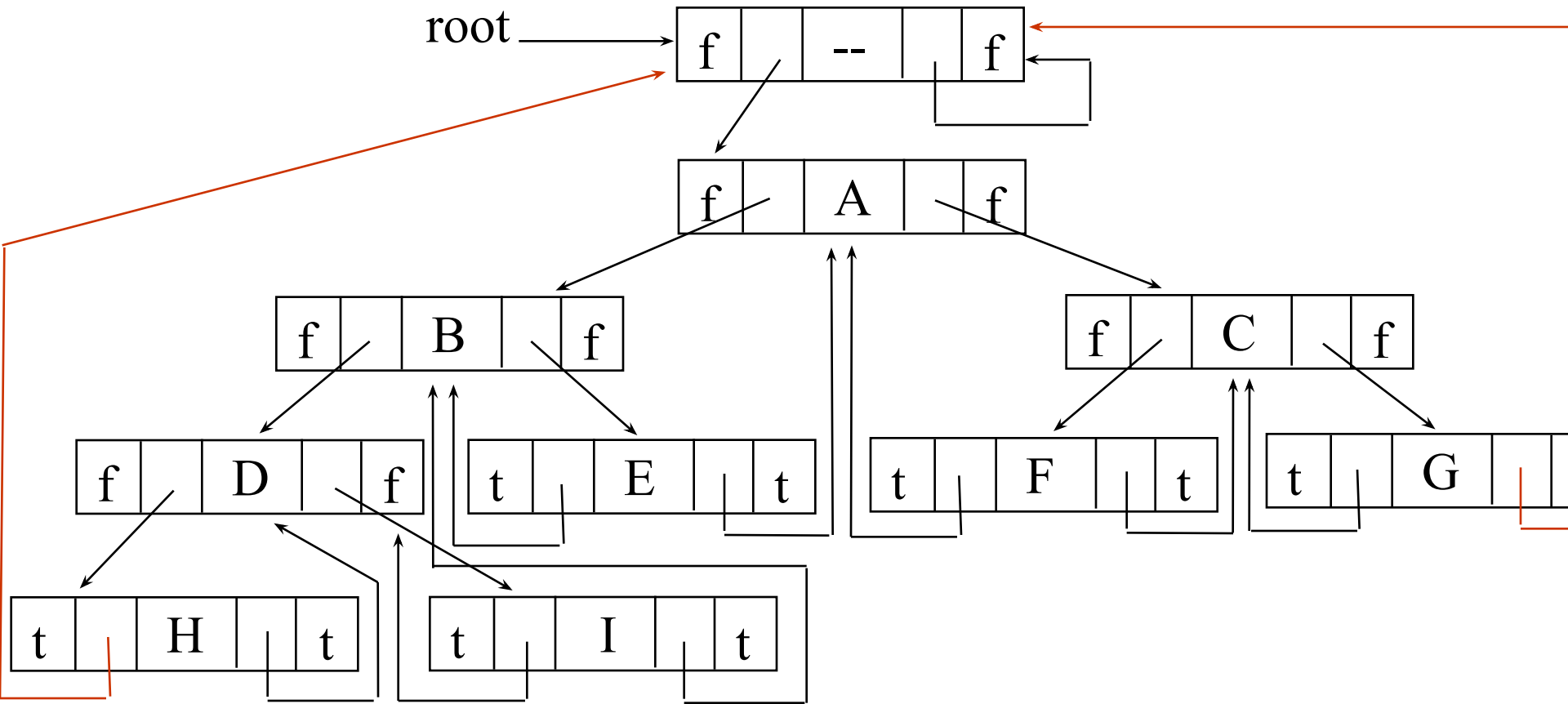
```
    threaded_pointer left_child;
```

```
    char data;
```

```
    threaded_pointer right_child;
```

```
    short int right_thread; };
```

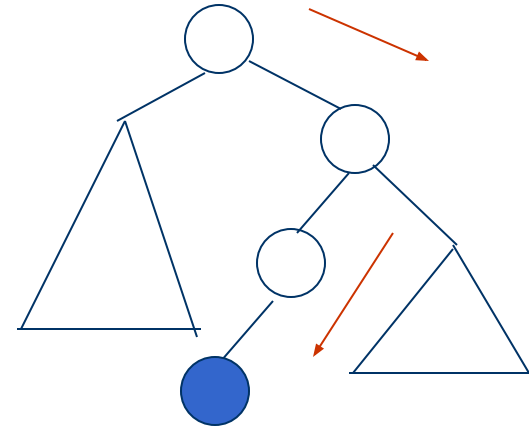
# Memory Representation of A Threaded BT





# Next Node in Threaded BT

```
threaded_pointer insucc(threaded_pointer  
    tree)  
{  
    threaded_pointer temp;  
    temp = tree->right_child;  
    if (!tree->right_thread)  
        while (!temp->left_thread)  
            temp = temp->left_child;  
    return temp;  
}
```



# Inorder Traversal of Threaded BT

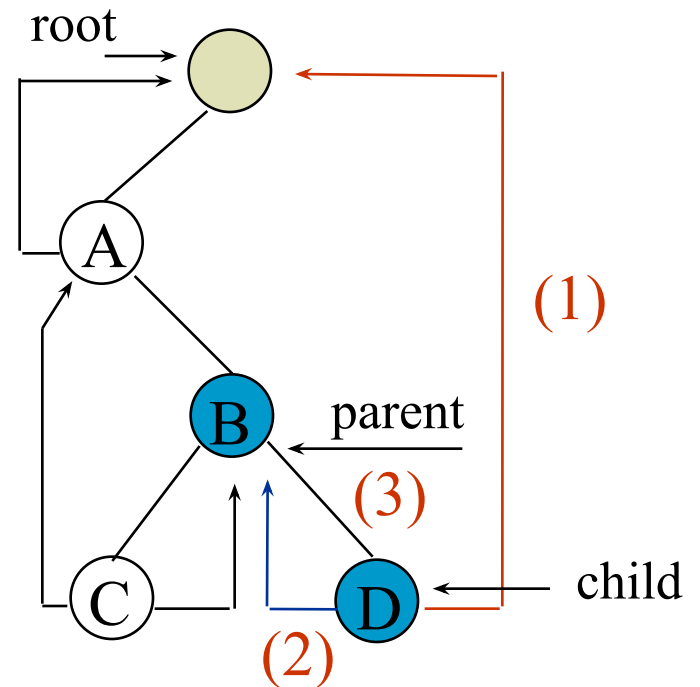
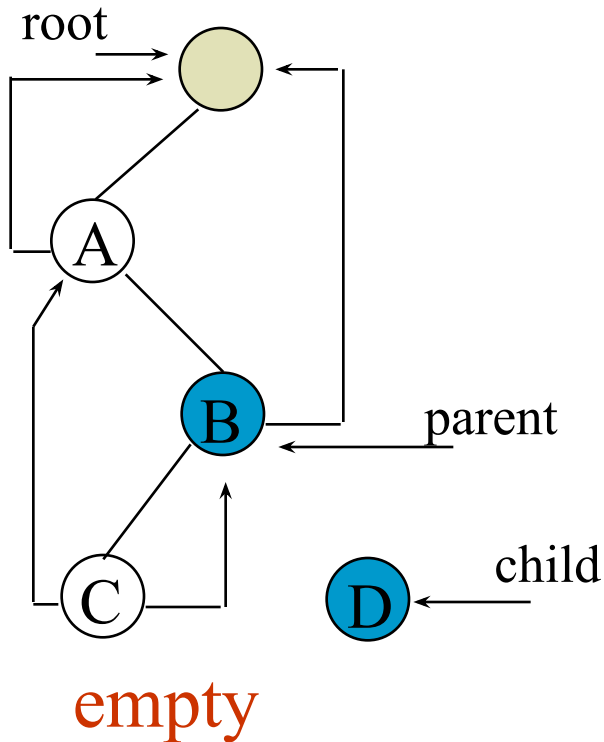
```
void tinorder(threaded_pointer tree)
{
    /* traverse the threaded binary tree
       inorder */
    threaded_pointer temp = tree;
    for (;;) {
        temp = insucc(temp);
        O(n) if (temp==tree) break;
        printf("%3c", temp->data);
    }
}
```

# Inserting Nodes into Threaded BTs

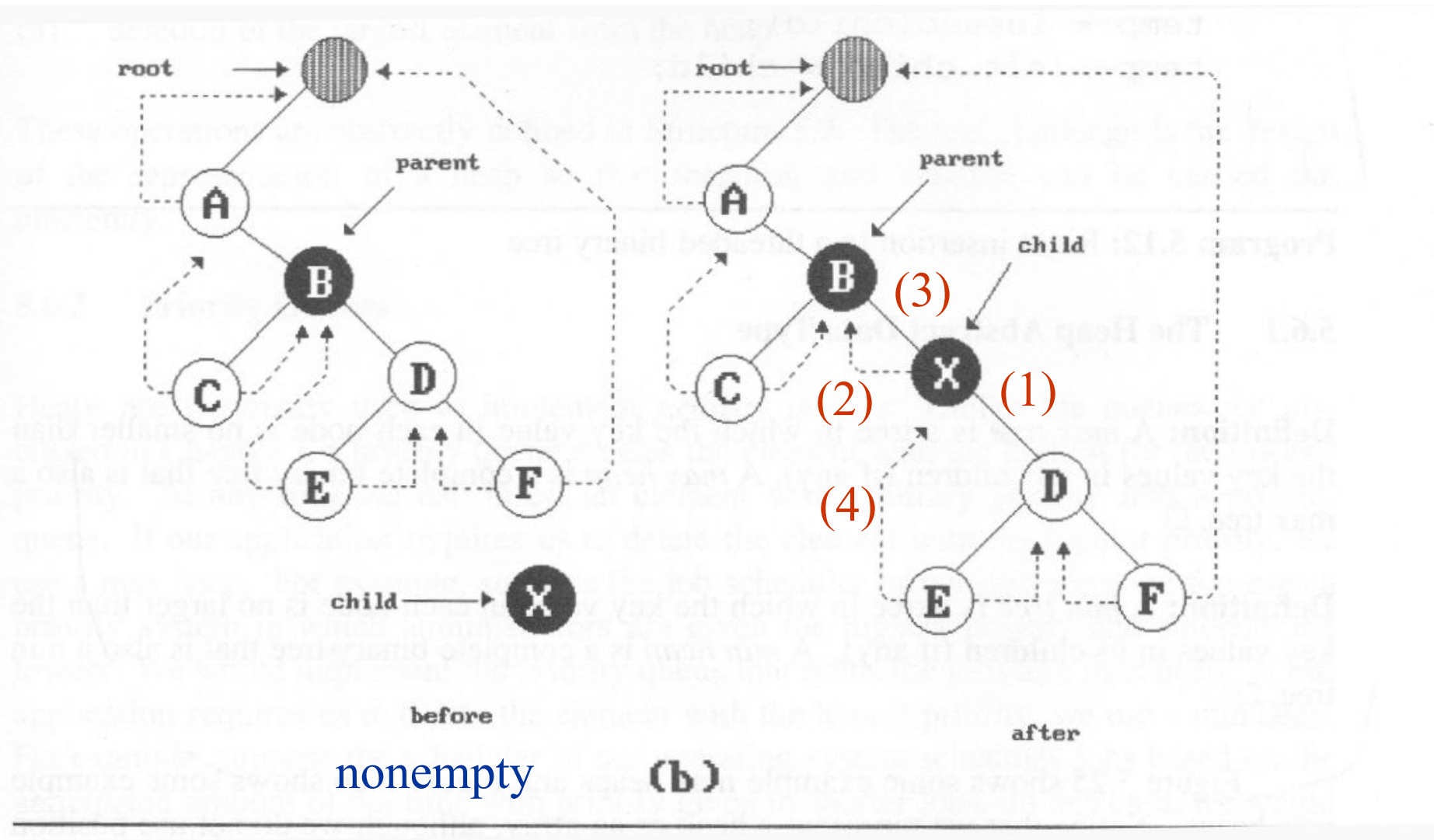
- Insert `child` as the right child of node `parent`
  - **change** `parent->right_thread` to **FALSE**
  - **set** `child->left_thread` **and** `child->right_thread` to **TRUE**
  - **set** `child->left_child` to **point to** `parent`
  - **set** `child->right_child` to `parent->right_child`
  - **change** `parent->right_child` to **point to** `child`

# Examples

Insert a node D as a right child of B.



**\*Figure 5.24:** Insertion of child as a right child of parent in a threaded binary tree (p.217)



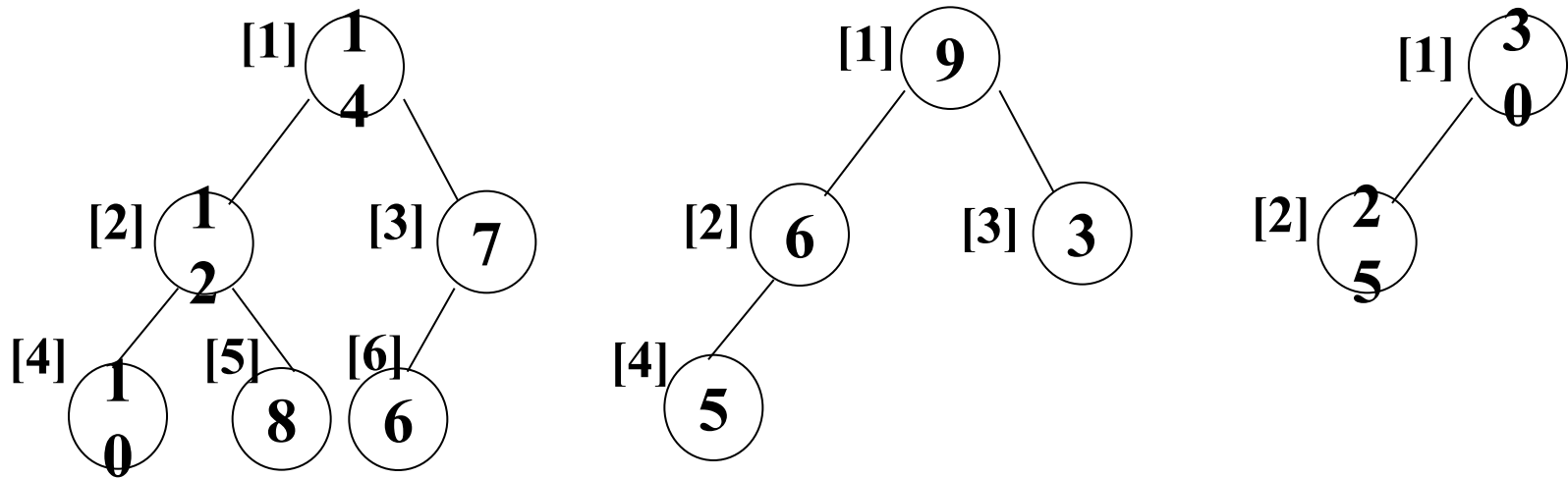
# Right Insertion in Threaded BTs

```
void insert_right(threaded_pointer parent,
                  threaded_pointer child)
{
    threaded_pointer temp;
    (1) child->right_child = parent->right_child;
    child->right_thread = parent->right_thread;
    child->left_child = parent;    case (a)
    (2) child->left_thread = TRUE;
    parent->right_child = child;
    (3) parent->right_thread = FALSE;
        if (!child->right_thread) { case (b)
            temp = insucc(child);
        (4) temp->left_child = child;
    }
}
```

# Heap

- A *max tree* is a tree in which the key value in each node is **no smaller than** the key values in its children. A *max heap* is a **complete binary tree** that is also a max tree.
- A *min tree* is a tree in which the key value in each node is **no larger than** the key values in its children. A *min heap* is a **complete binary tree** that is also a min tree.
- Operations on heaps
  - creation of an empty heap
  - insertion of a new element into the heap;
  - deletion of the largest element from the heap

**\*Figure 5.25: Sample max heaps (p.219)**

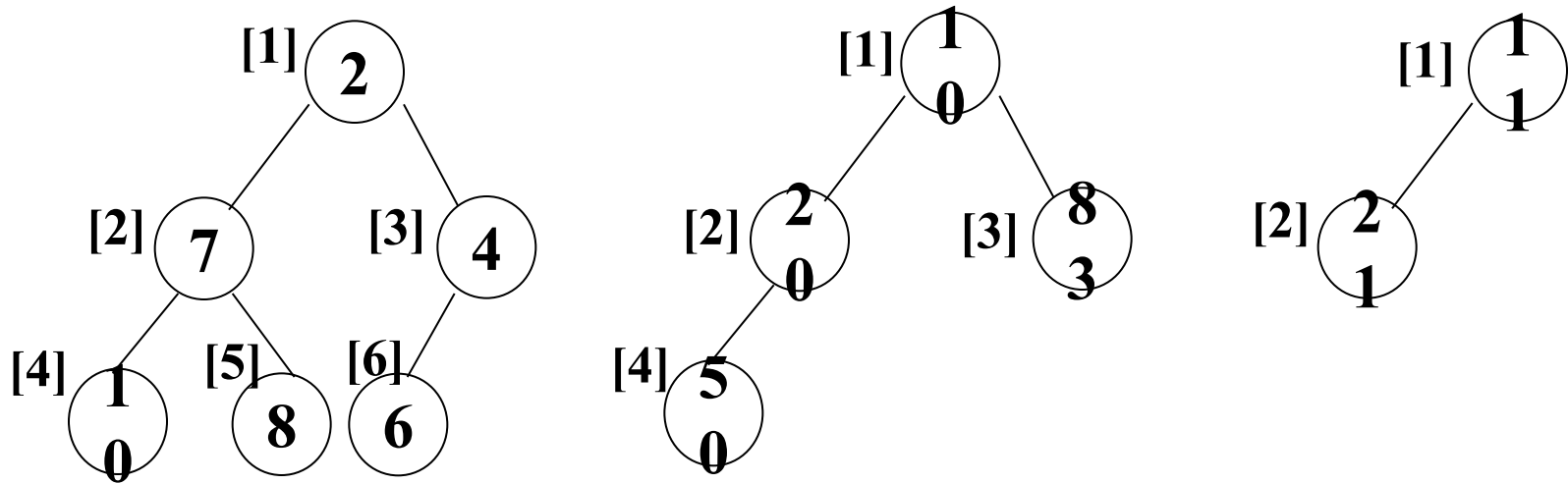


## Property:

The root of max heap (min heap) contains the largest (smallest).



**\*Figure 5.26: Sample min heaps (p.220)**



# structure MaxHeap    ADT for Max Heap

objects: a complete binary tree of  $n > 0$  elements organized so that the value in each node is at least as large as those in its children

functions:

for all *heap* belong to *MaxHeap*, *item* belong to *Element*,  $n$ ,  
*max\_size* belong to integer

MaxHeap Create(*max\_size*)::= create an empty heap that can  
hold a maximum of *max\_size* elements

Boolean HeapFull(*heap*,  $n$ )::= if ( $n == \text{max\_size}$ ) return TRUE  
else return FALSE

MaxHeap Insert(*heap*, *item*,  $n$ )::= if (!HeapFull(*heap*,  $n$ )) insert  
item into heap and return the resulting heap  
else return error

Boolean HeapEmpty(*heap*,  $n$ )::= if ( $n > 0$ ) return FALSE  
else return TRUE

Element Delete(*heap*,  $n$ )::= if (!HeapEmpty(*heap*,  $n$ )) return one  
instance of the **largest** element in the heap  
and remove it from the heap  
else return error

# Application: priority queue

- machine service
  - amount of time (min heap)
  - amount of payment (max heap)
- factory
  - time tag

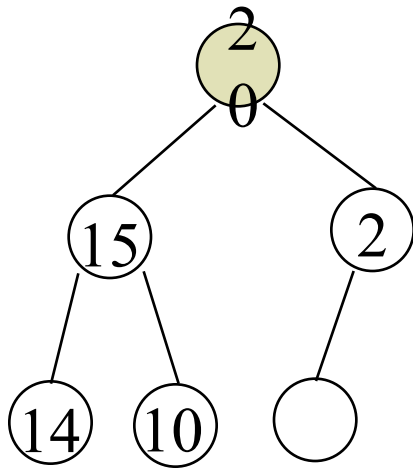
# Data Structures

- unordered linked list
- unordered array
- sorted linked list
- sorted array
- heap

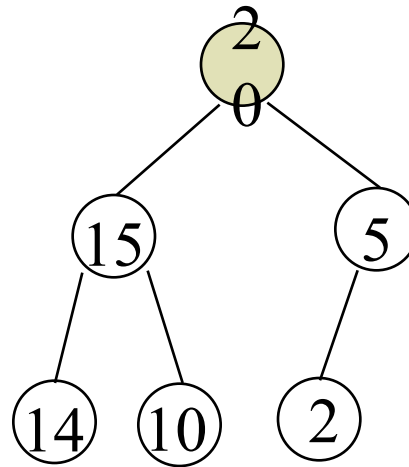
**\*Figure 5.27: Priority queue representations (p.221)**

Representation	Insertion	Deletion
Unordered array	$\Theta(1)$	$\Theta(n)$
Unordered linked list	$\Theta(1)$	$\Theta(n)$
Sorted array	$O(n)$	$\Theta(1)$
Sorted linked list	$O(n)$	$\Theta(1)$
Max heap	$O(\log_2 n)$	$O(\log_2 n)$

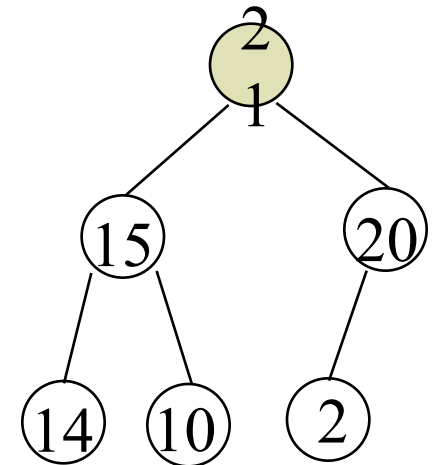
# Example of Insertion to Max Heap



initial location of new node



insert 5 into heap



insert 21 into heap

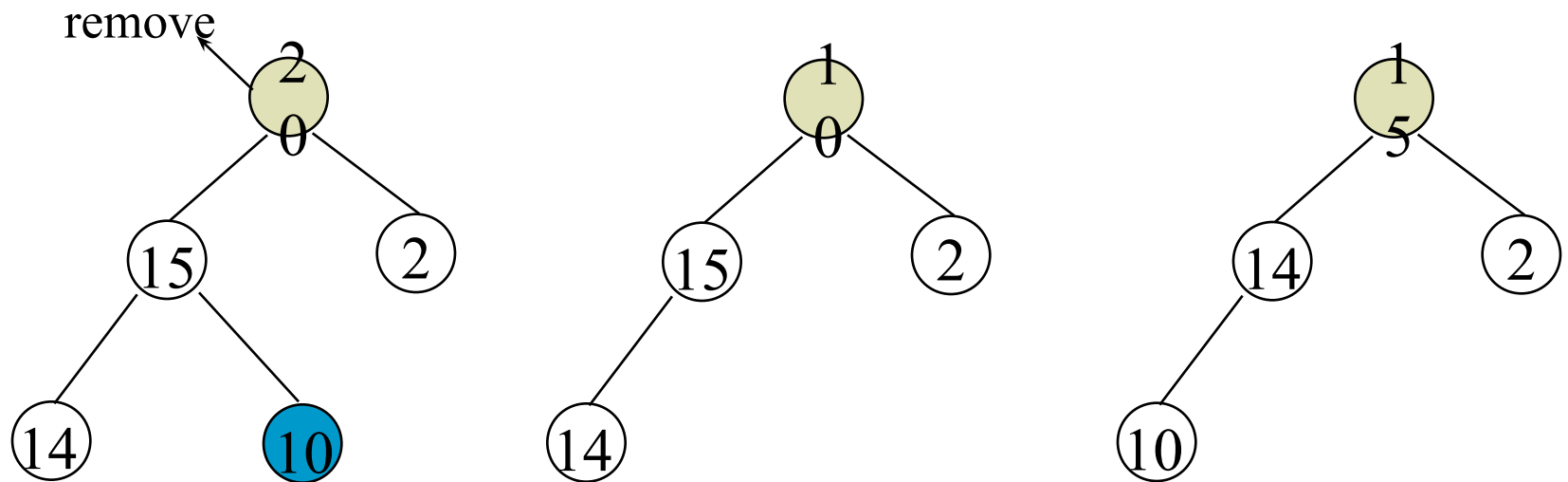
# Insertion into a Max Heap

```
void insert_max_heap(element item, int *n)
{
    int i;
    if (HEAP_FULL(*n)) {
        fprintf(stderr, "the heap is full.\n");
        exit(1);
    }
    i = ++(*n);
    while ((i!=1) && (item.key>heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    }
    heap[i] = item;
}
```

$2^k - 1 = n \implies k = \lceil \log_2(n+1) \rceil$

$O(\log_2 n)$

# Example of Deletion from Max Heap





# Deletion from a Max Heap

```
element delete_max_heap(int *n)
{
    int parent, child;
    element item, temp;
    if (HEAP_EMPTY(*n)) {
        fprintf(stderr, "The heap is empty\n");
        exit(1);
    }
    /* save value of the element with the
       highest key */
    item = heap[1];
    /* use last element in heap to adjust heap
    temp = heap[(*n)--];
    parent = 1;
    child = 2;
```

```

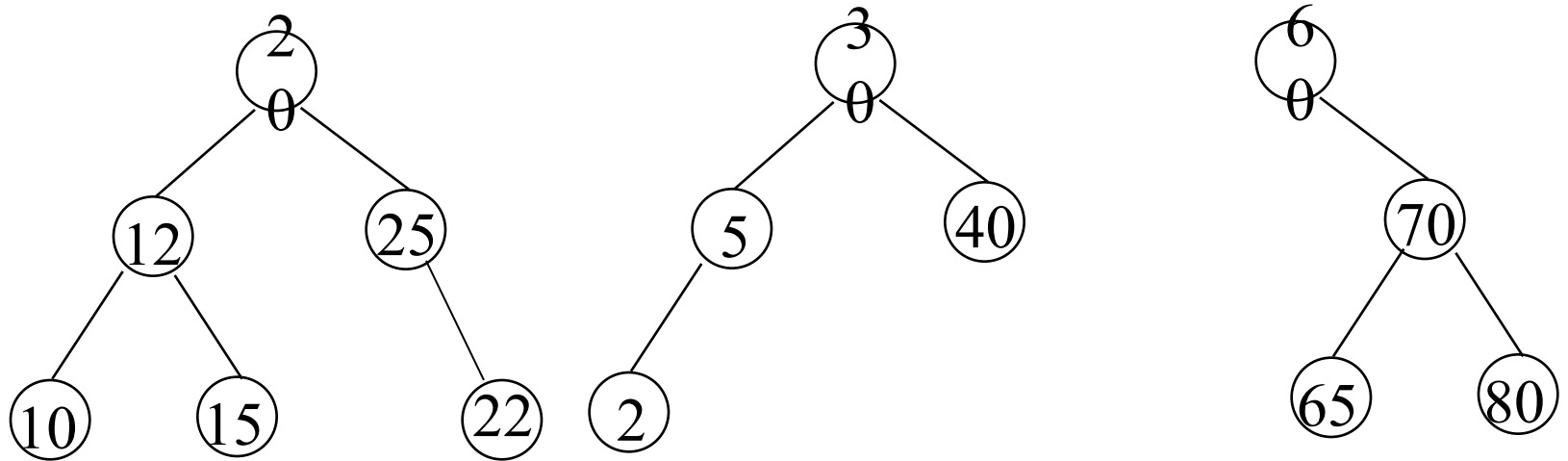
while (child <= *n) {
    /* find the larger child of the current
       parent */
    if ((child < *n) &&
        (heap[child].key < heap[child+1].key))
        child++;
    if (temp.key >= heap[child].key) break;
    /* move to the next lower level */
    heap[parent] = heap[child];
    child *= 2;
}
heap[parent] = temp;
return item;
}

```

# Binary Search Tree

- Heap
  - a min (max) element is deleted.  $O(\log_2 n)$
  - deletion of an arbitrary element  $O(n)$
  - search for an arbitrary element  $O(n)$
- Binary search tree
  - Every element has a unique key.
  - The keys in a nonempty left subtree (right subtree) are smaller (larger) than the key in the root of subtree.
  - The left and right subtrees are also binary search trees.

# Examples of Binary Search Trees



# Searching a Binary Search Tree

```
tree_pointer search(tree_pointer root,
                    int key)
{
    /* return a pointer to the node that
       contains key. If there is no such
       node, return NULL */

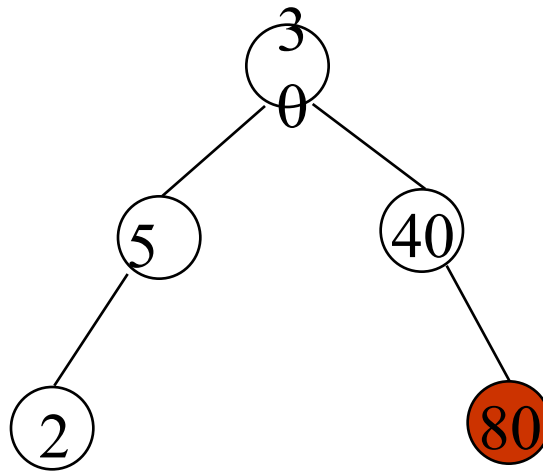
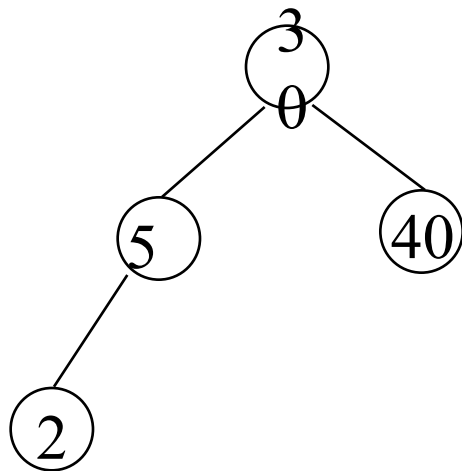
    if (!root) return NULL;
    if (key == root->data) return root;
    if (key < root->data)
        return search(root->left_child,
                      key);
    return search(root->right_child, key);
}
```

# Another Searching Algorithm

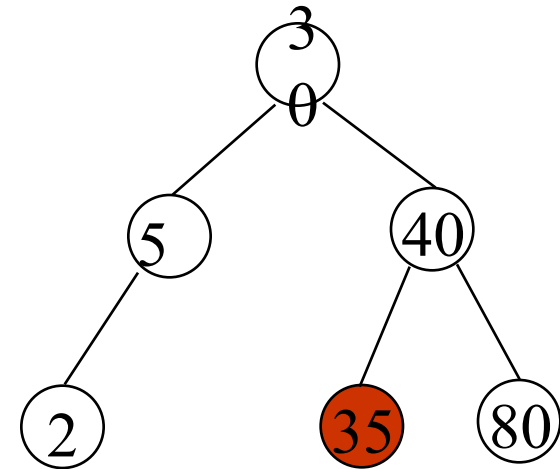
```
tree_pointer search2 (tree_pointer tree,  
    int key)  
{  
    while (tree) {  
        if (key == tree->data) return tree;  
        if (key < tree->data)  
            tree = tree->left_child;  
        else tree = tree->right_child;  
    }  
    return NULL;  
}
```

$O(h)$

# Insert Node in Binary Search Tree



Insert 80



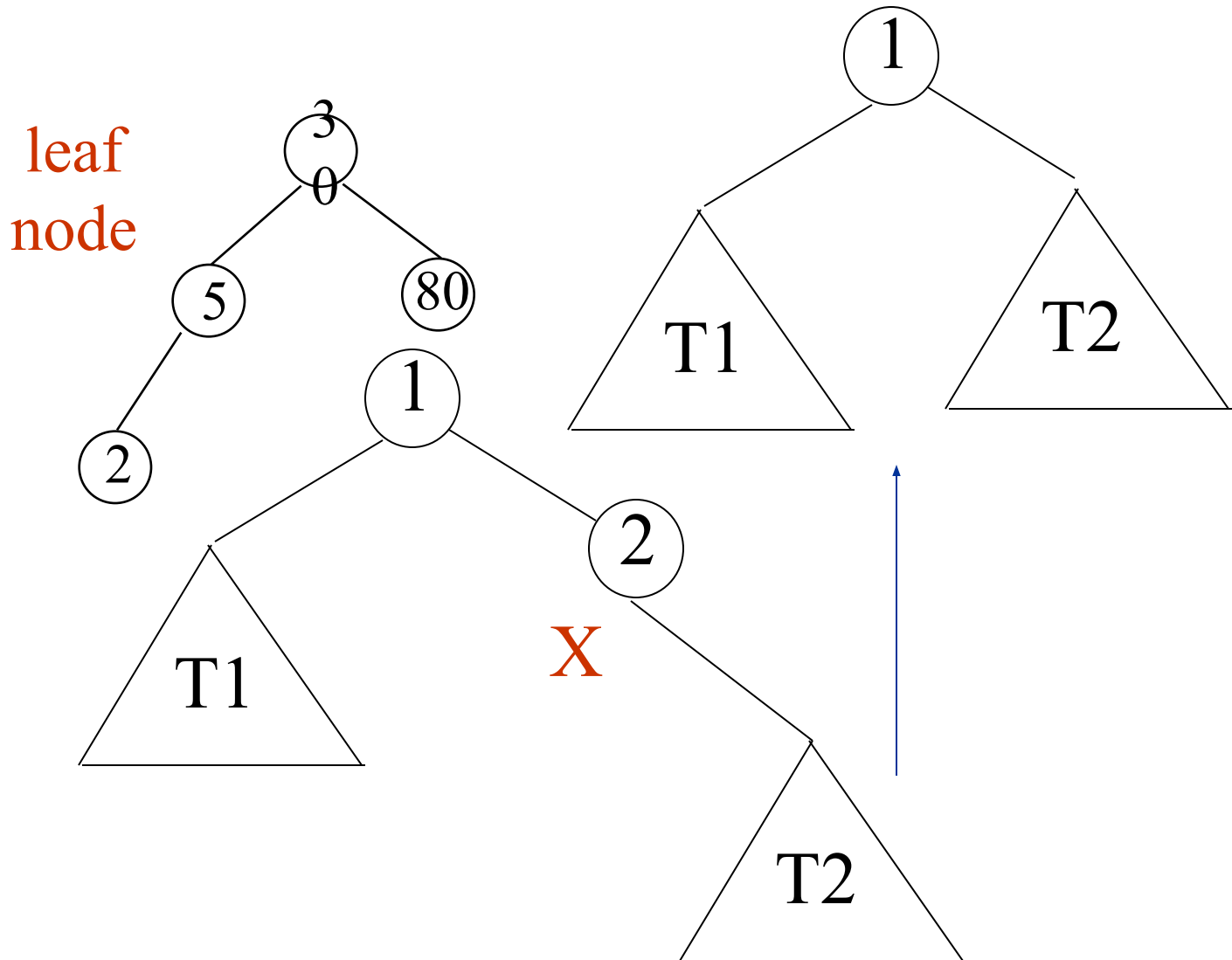
Insert 35

# Insertion into A Binary Search Tree

```
void insert_node(tree_pointer *node, int num)
{
    tree_pointer ptr,
        temp = modified_search(*node, num);
    if (temp || !(*node)) {
        ptr = (tree_pointer) malloc(sizeof(node));
        if (IS_FULL(ptr)) {
            fprintf(stderr, "The memory is full\n");
            exit(1);
        }
        ptr->data = num;
        ptr->left_child = ptr->right_child = NULL;
        if (*node)
            if (num < temp->data) temp->left_child = ptr;
            else temp->right_child = ptr;
        else *node = ptr;
    }
}
```

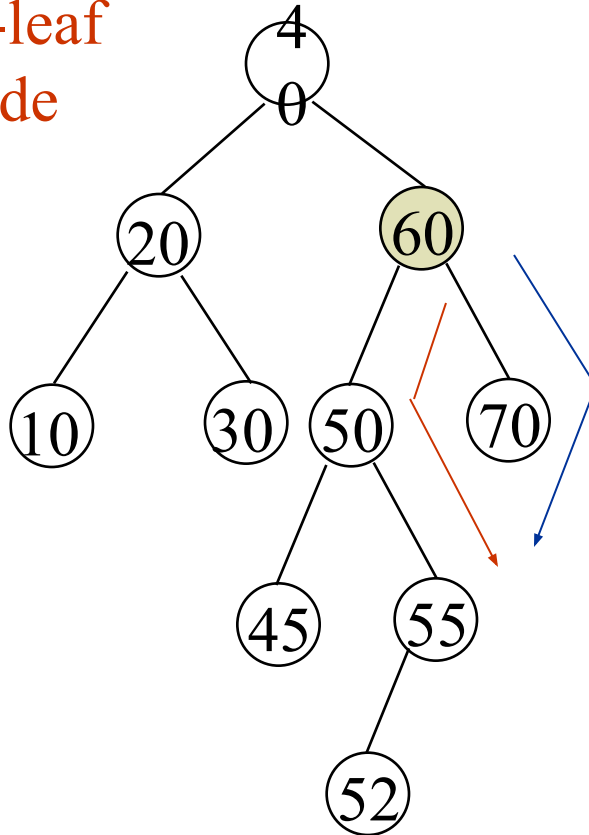


# Deletion for A Binary Search Tree

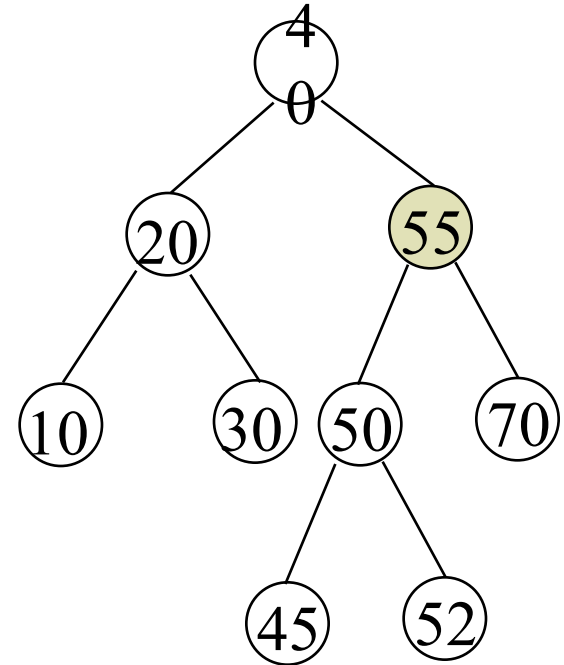


# Deletion for A Binary Search Tree

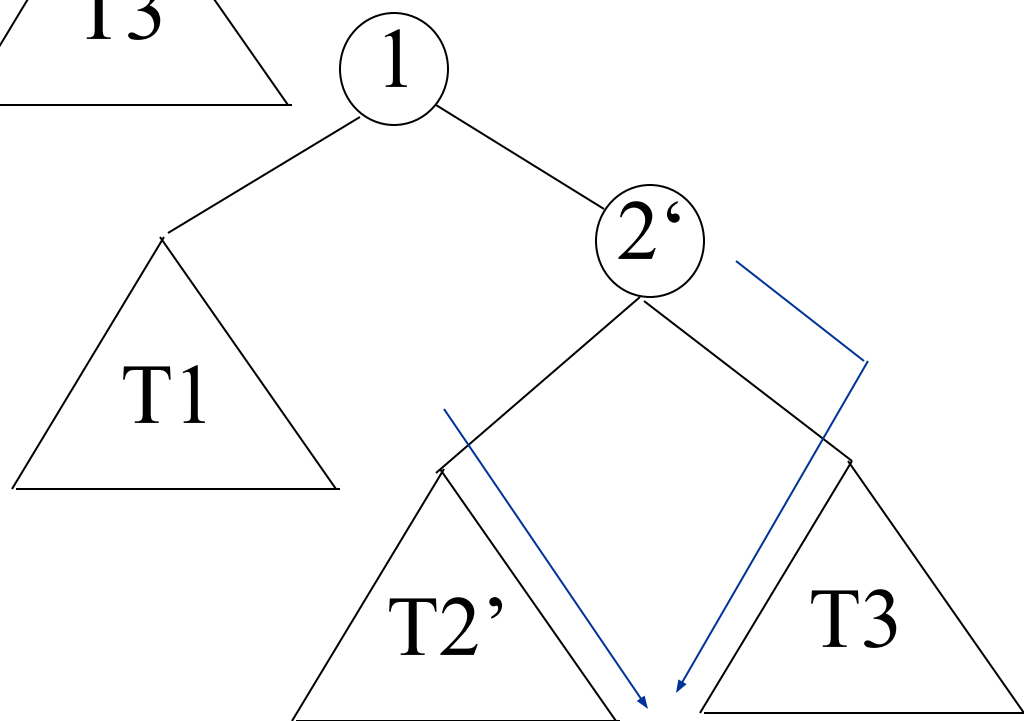
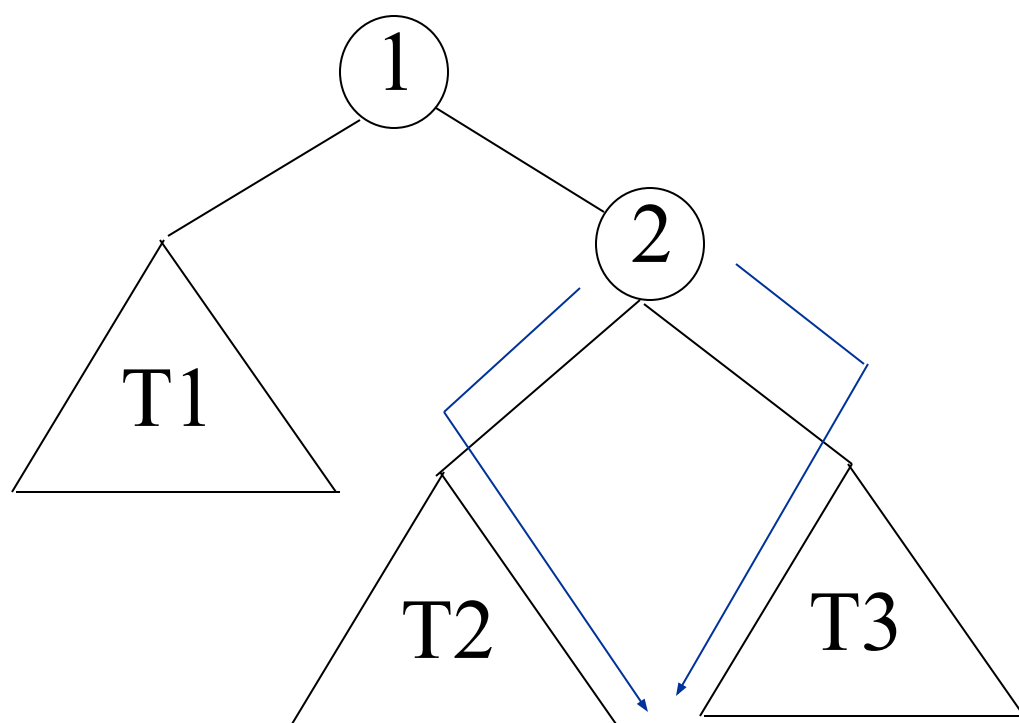
non-leaf  
node



Before deleting 60



After deleting 60



# Selection Trees

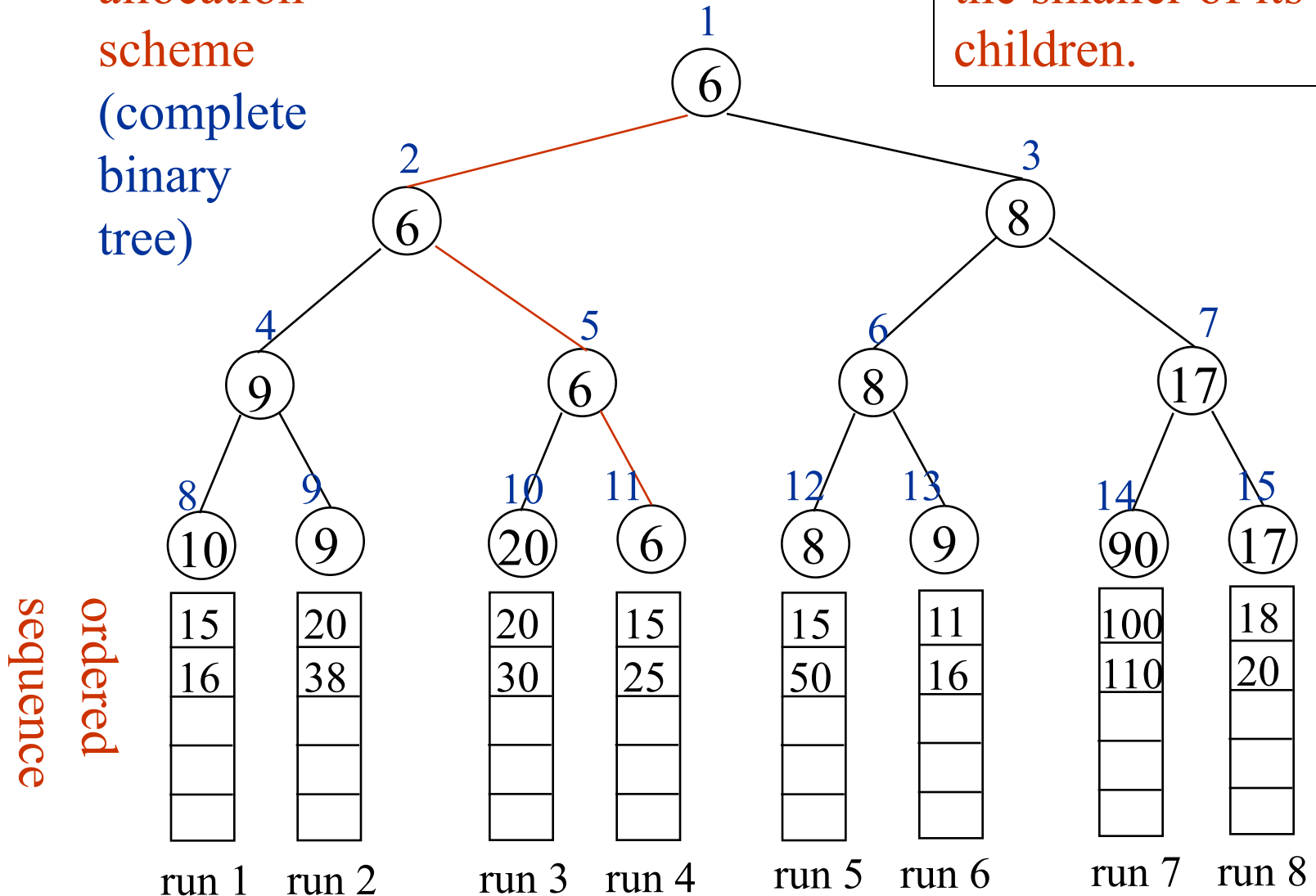
- (1) winner tree
- (2) loser tree

sequential  
allocation  
scheme

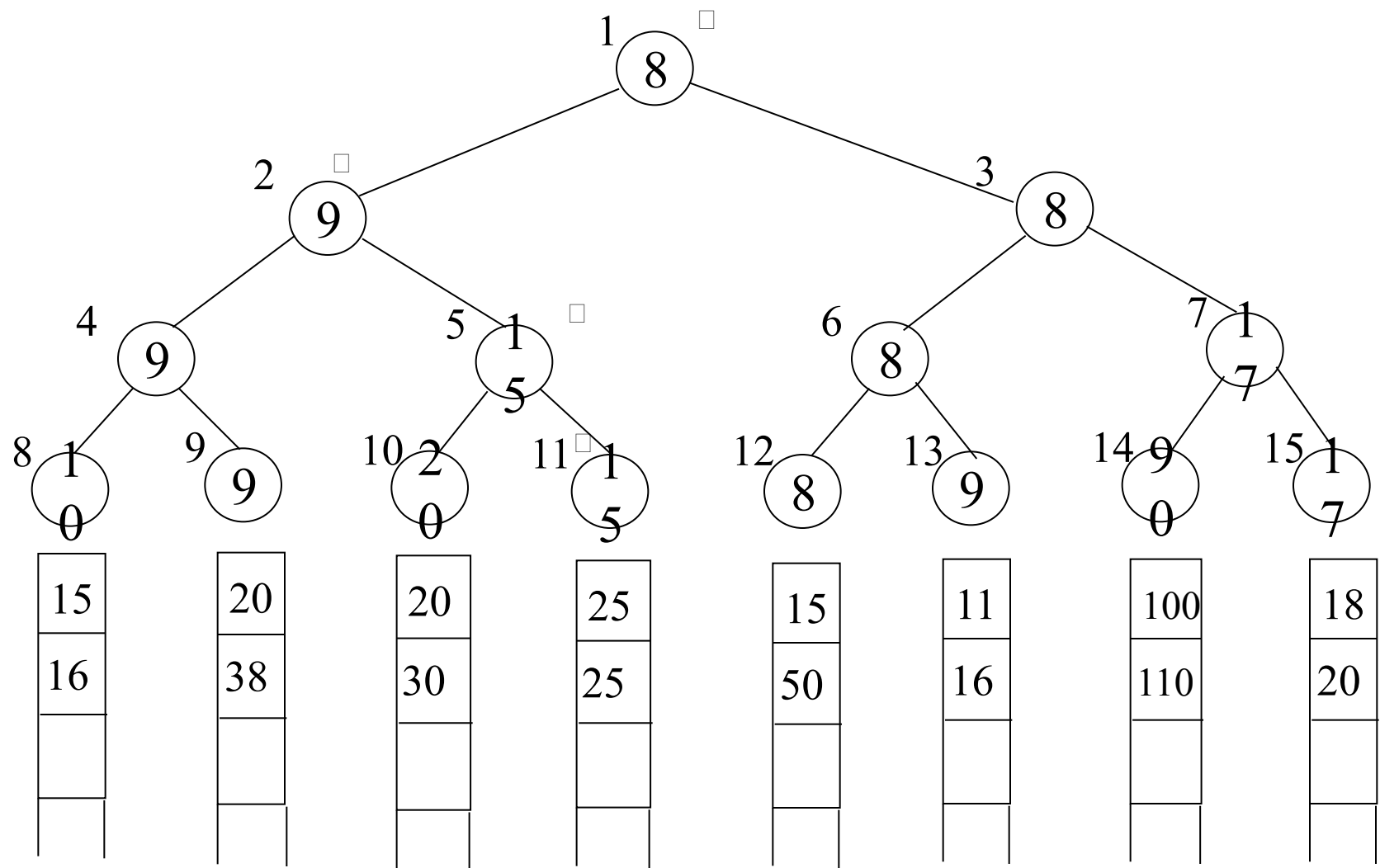
(complete  
binary  
tree)

# winner tree

Each node represents  
the smaller of its two  
children.



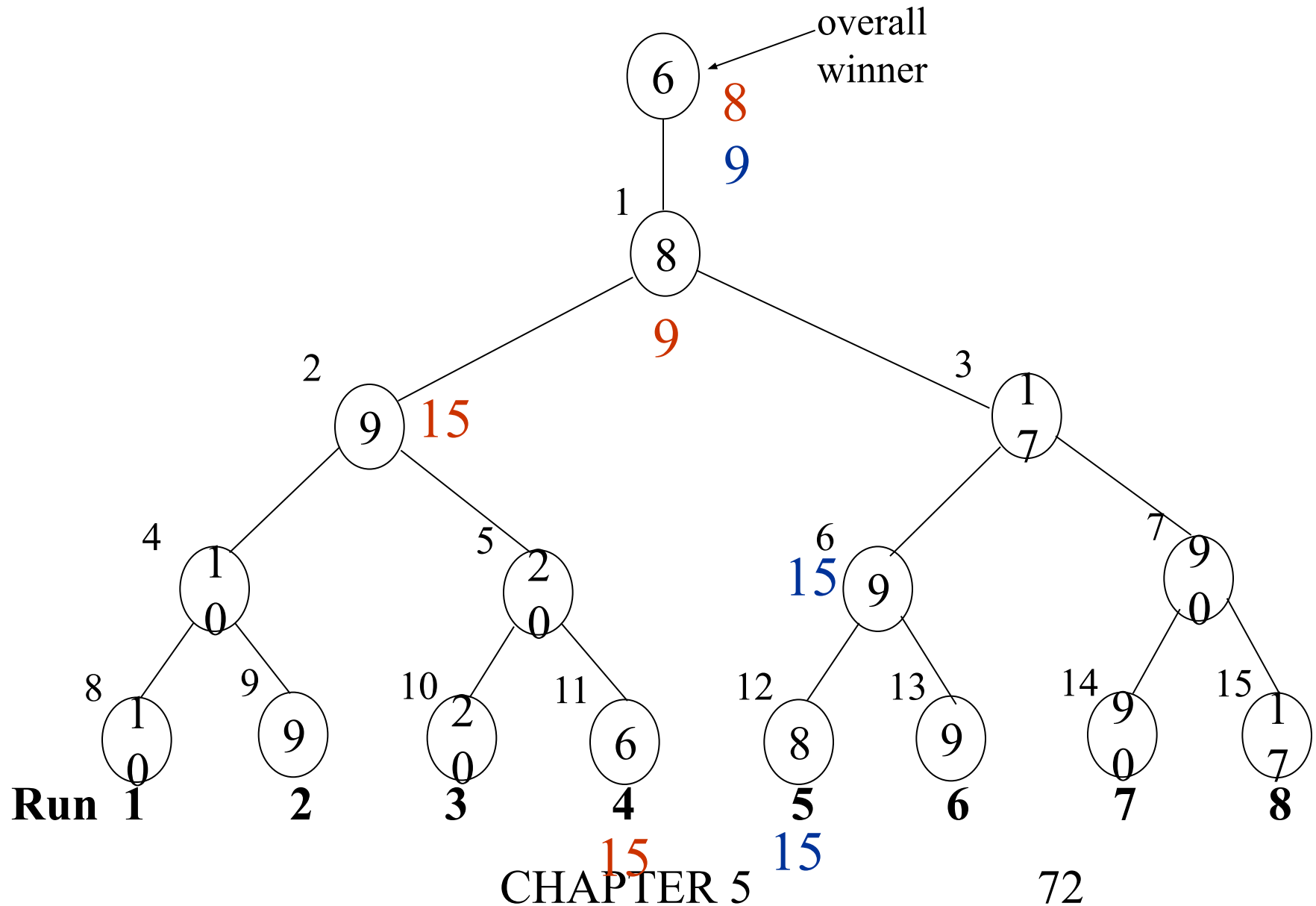
**\*Figure 5.35:** Selection tree of Figure 5.34 after one record has been output and the tree restructured(nodes that were changed are ticked)



# Analysis

- $K$ : # of runs
- $n$ : # of records
- setup time:  $O(K)$   $(K-1)$
- restructure time:  $O(\log_2 K)$   $\lceil \log_2(K+1) \rceil$
- merge time:  $O(n \log_2 K)$
- slight modification: **tree of loser**
  - consider the parent node only (vs. sibling nodes)

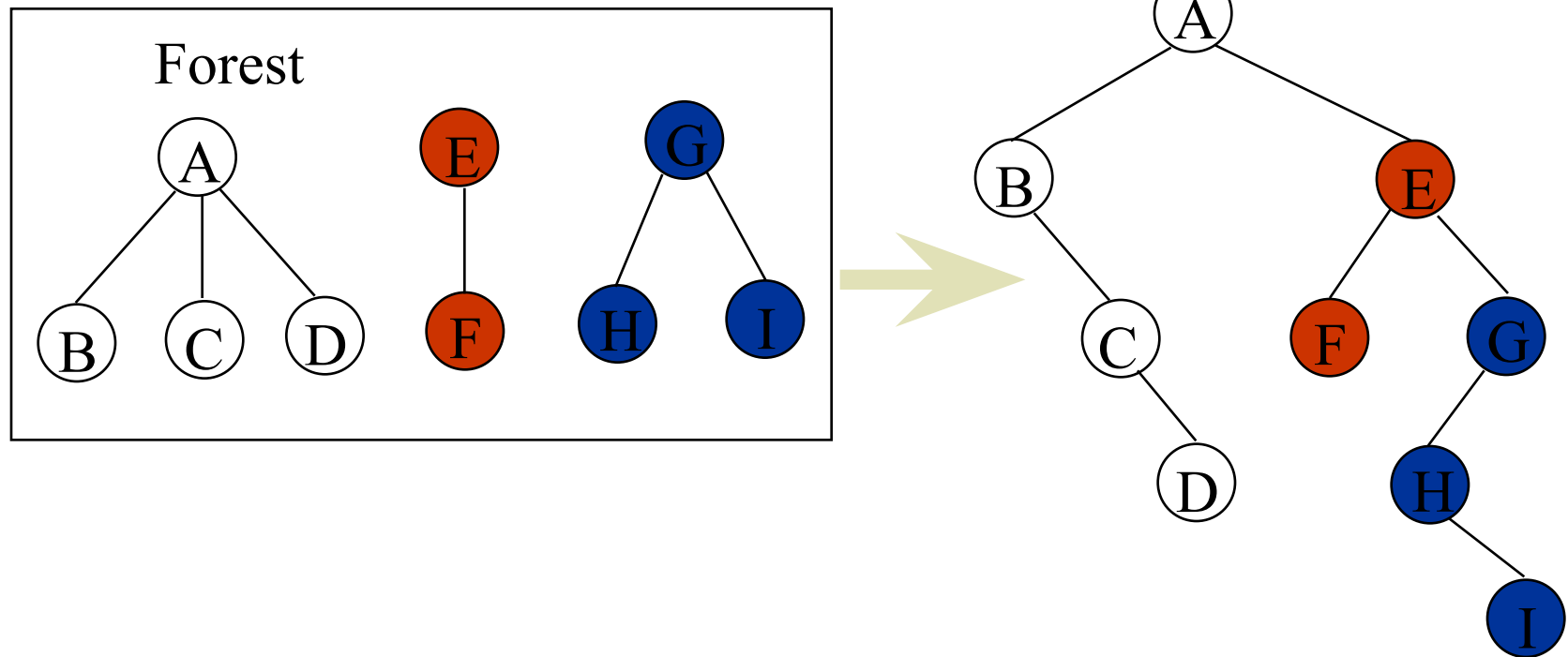
**\*Figure 5.36: Tree of losers corresponding to Figure 5.34 (p.235)**





# Forest

- A forest is a set of  $n \geq 0$  disjoint trees

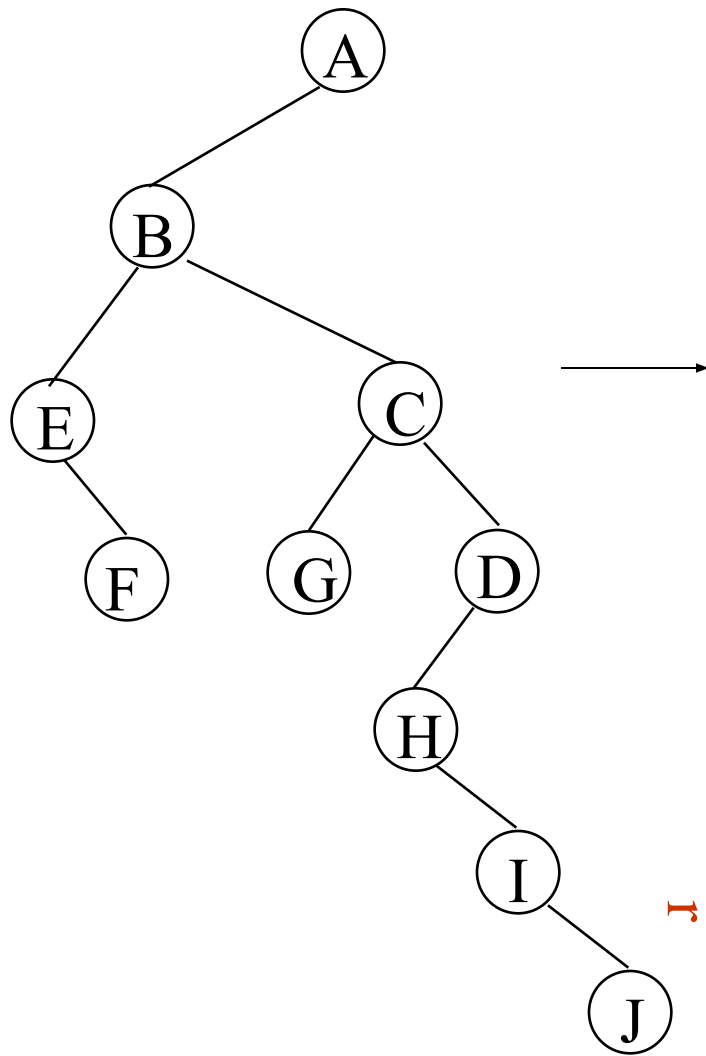


# Transform a forest into a binary tree

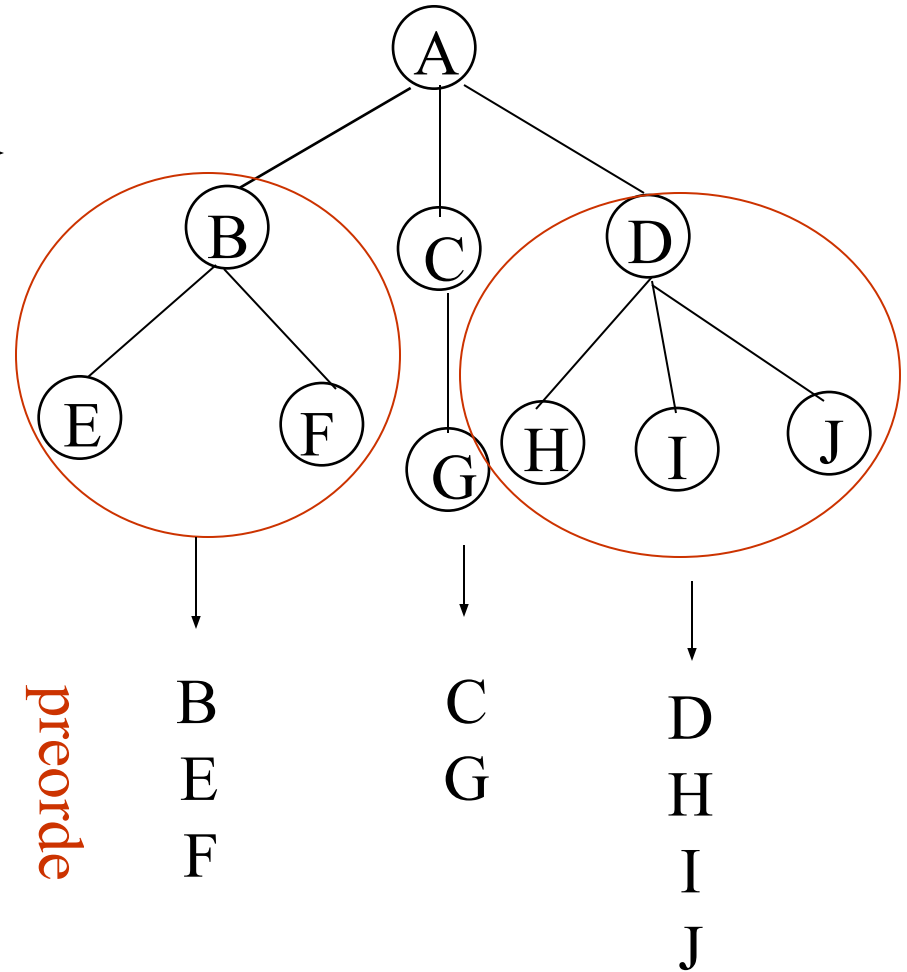
- $T_1, T_2, \dots, T_n$ : a forest of trees  
 $B(T_1, T_2, \dots, T_n)$ : a binary tree corresponding to this forest
- algorithm
  - (1) empty, if  $n = 0$
  - (2) has root equal to  $\text{root}(T_1)$ 
    - has left subtree equal to  $B(T_{11}, T_{12}, \dots, T_{1m})$
    - has right subtree equal to  $B(T_2, T_3, \dots, T_n)$

# Forest Traversals

- Preorder
  - If  $F$  is empty, then return
  - Visit the root of the first tree of  $F$
  - Traverse the subtrees of the first tree in tree preorder
  - Traverse the remaining trees of  $F$  in preorder
- Inorder
  - If  $F$  is empty, then return
  - Traverse the subtrees of the first tree in tree inorder
  - Visit the root of the first tree
  - Traverse the remaining trees of  $F$  in inorder

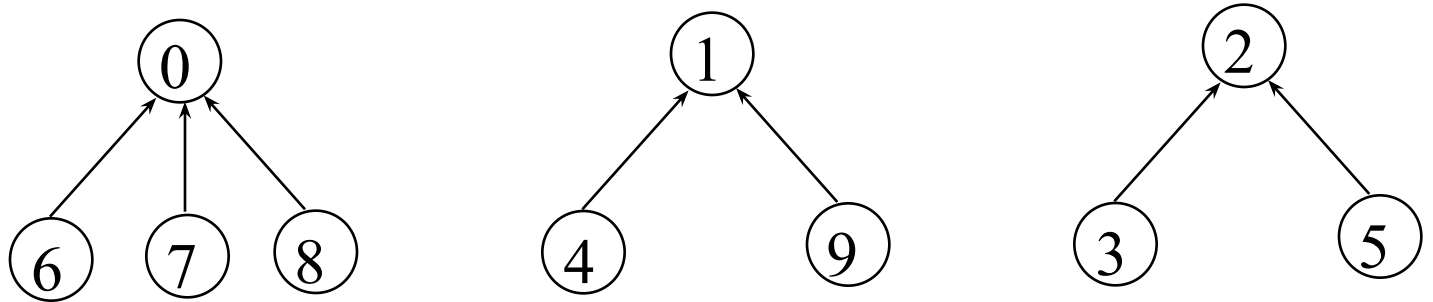


inorder: EFBGCHIJDA  
preorder: ABEFCGDHIJ



# Set Representation

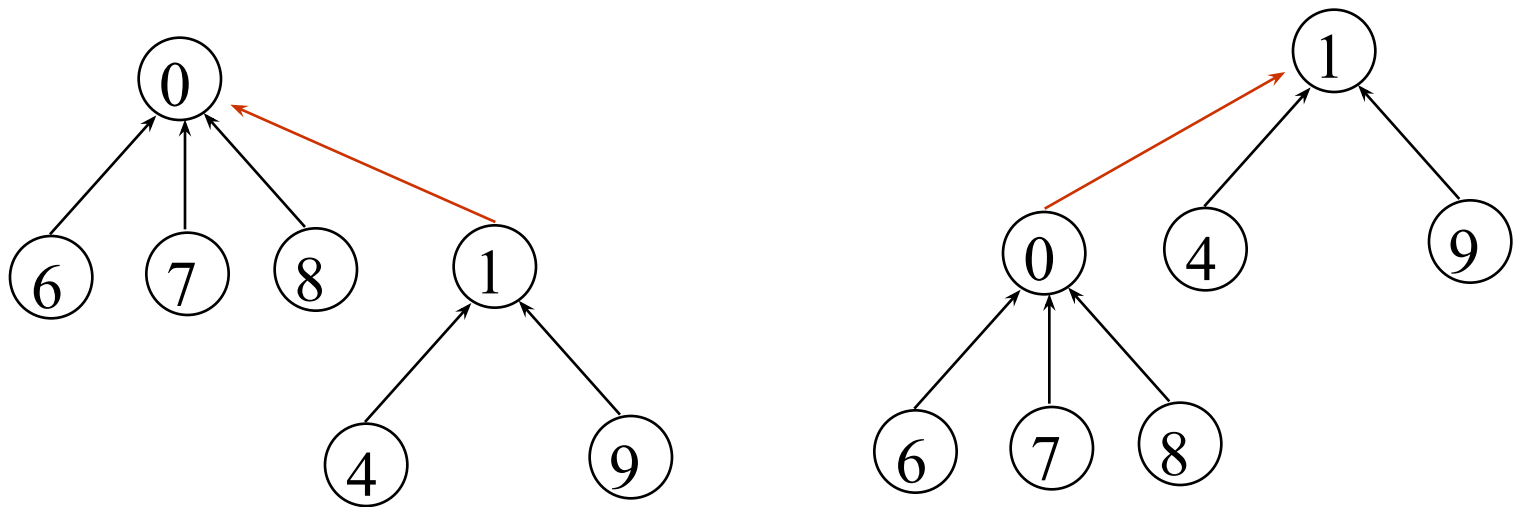
- $S_1 = \{0, 6, 7, 8\}$ ,  $S_2 = \{1, 4, 9\}$ ,  $S_3 = \{2, 3, 5\}$



- $S_i \cap S_j = \varnothing$   
Two operations considered here
  - Disjoint set union  $S_1 \cup S_2 = \{0, 6, 7, 8, 1, 4, 9\}$
  - Find( $i$ ): Find the set containing the element  $i$ .  
 $3 \in S_3, 8 \in S_1$

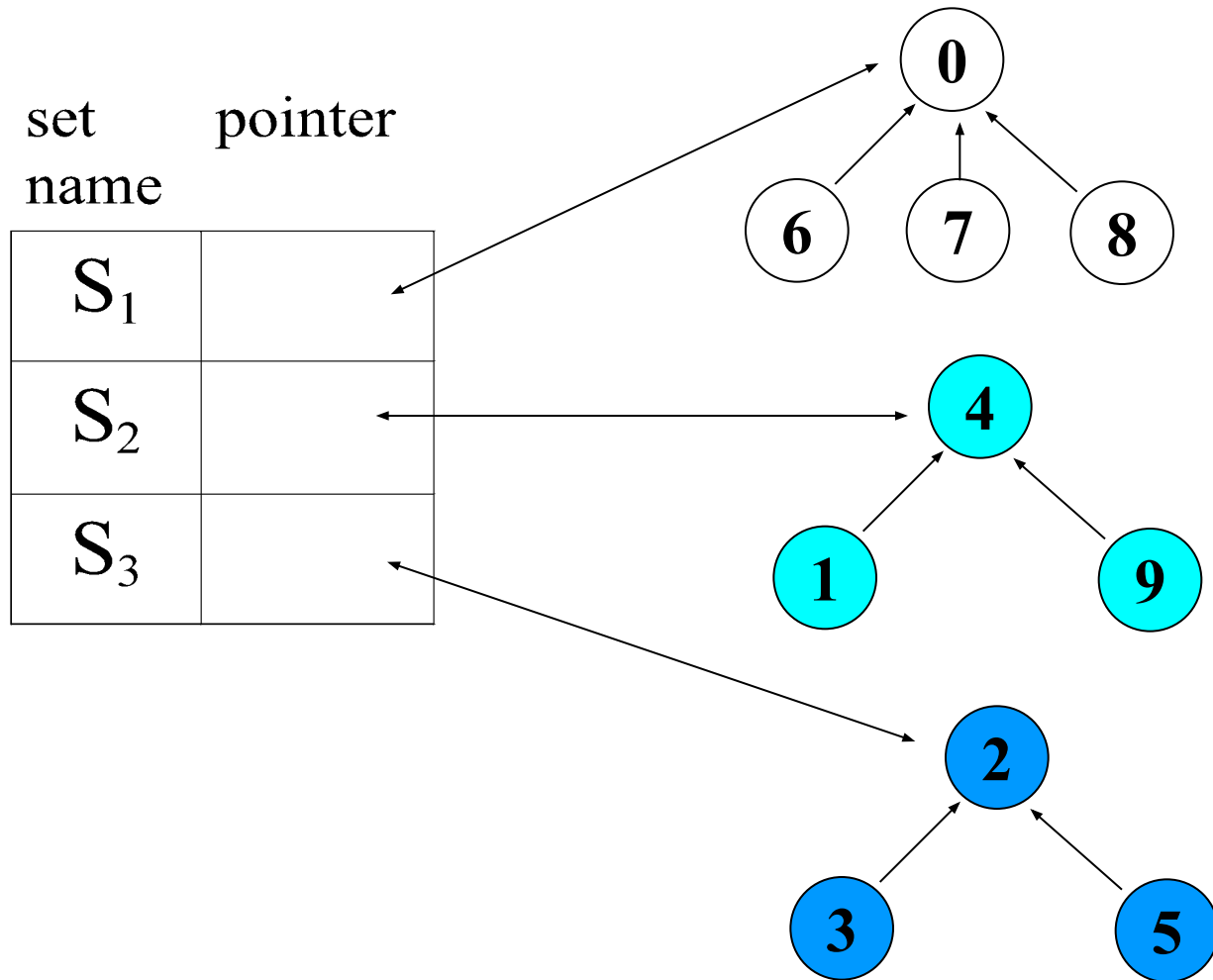
# Disjoint Set Union

Make one of trees a subtree of the other



Possible representation for  $S_1 \cup S_2$

**\*Figure 5.41: Data Representation of  $S_1$ ,  $S_2$  and  $S_3$  (p.240)**



# Array Representation for Set

i	[0]	[1]	[2]	[3]	[4]	[5]	[6]	[7]	[8]	[9]
parent	-1	4	-1	2	-1	2	0	0	0	4

```
int find1(int i)
{
    for (; parent[i] >= 0; i = parent[i])
        return i;
}
```

```
void union1(int i, int j)
{
    parent[i] = j;
}
```



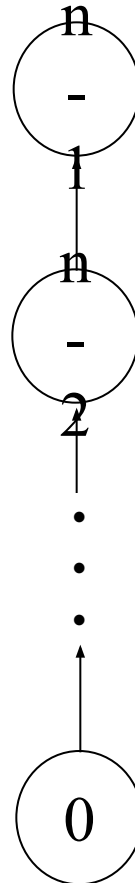
\*Figure 5.43: Degenerate tree (p.242)

union operation

$O(n)$   $n-1$

find operation

$O(n^2)$   $\sum_{i=2}^n i$



union(0,1), find(0)

union(1,2), find(0)

.

.

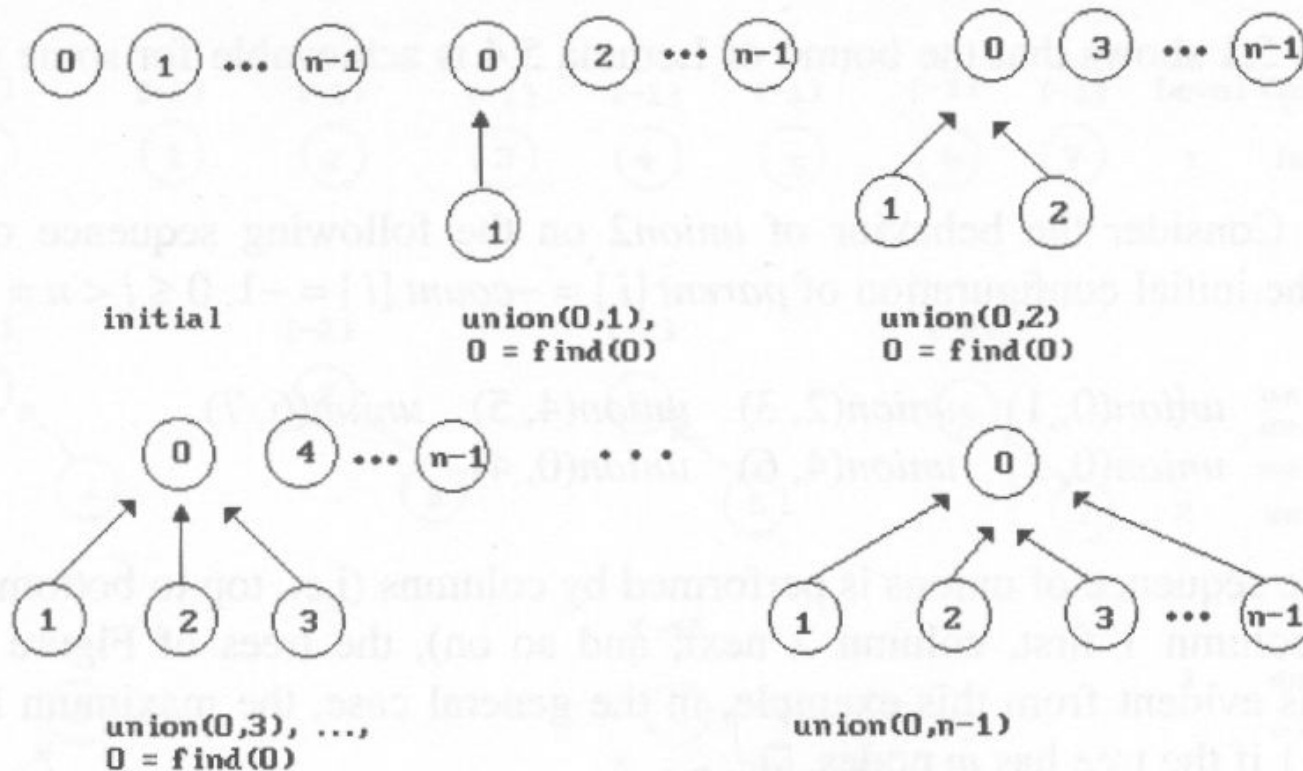
.

union(n-2,n-1),find(0)

degenerate tree

**\*Figure 5.44: Trees obtained using the weighting rule(p.243)**

weighting rule for union( $i,j$ ): if # of nodes in  $i < \#$  in  $j$  then  $j$  the parent of  $i$



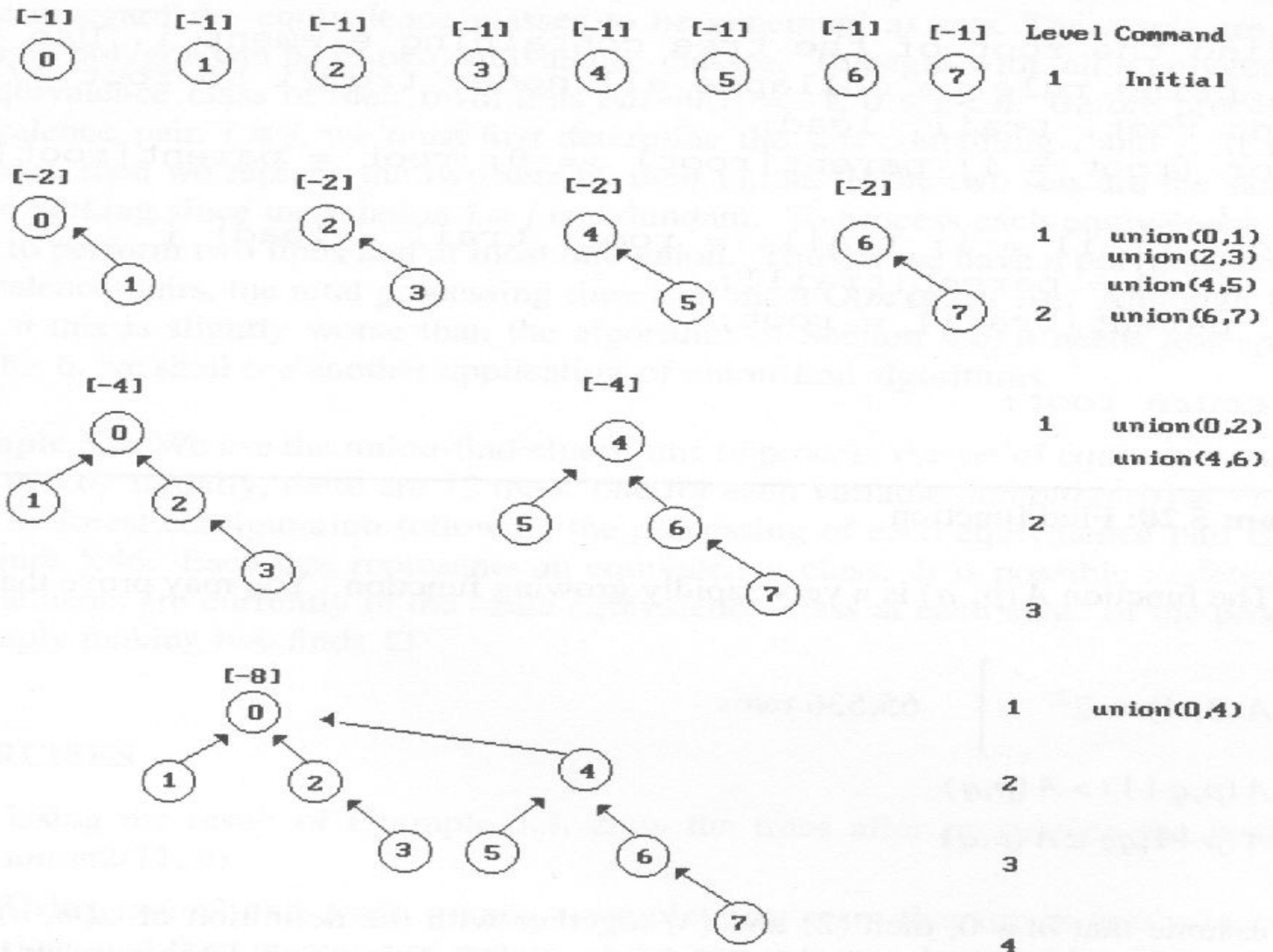
**Figure 5.44:** Trees obtained using the weighting rule

# Modified Union Operation

```
void union2(int i, int j)
{
    Keep a count in the root of tree
    int temp = parent[i]+parent[j];
    if (parent[i]>parent[j]) {
        parent[i]=j;      i has fewer nodes.
        parent[j]=temp;
    }
    else { j has fewer nodes
        parent[j]=i;
        parent[i]=temp;
    }
}
```

If the number of nodes in tree i is less than the number in tree j, then make j the parent of i; otherwise make i the parent of j.

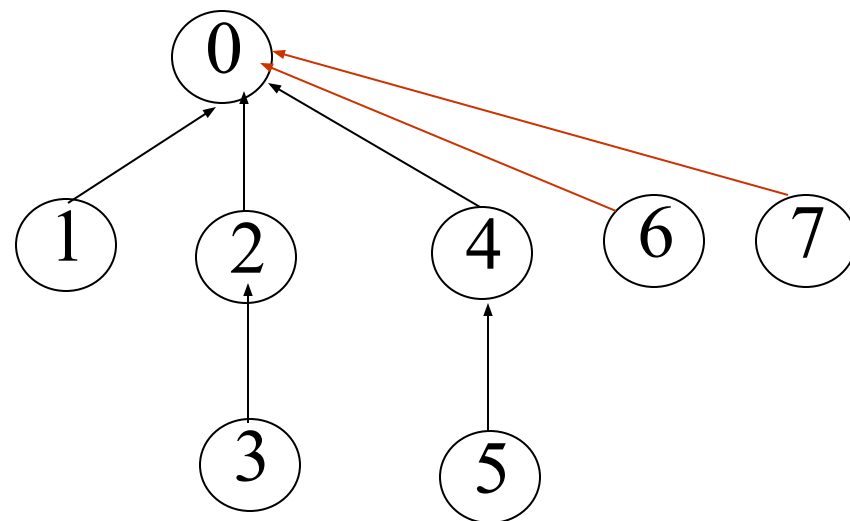
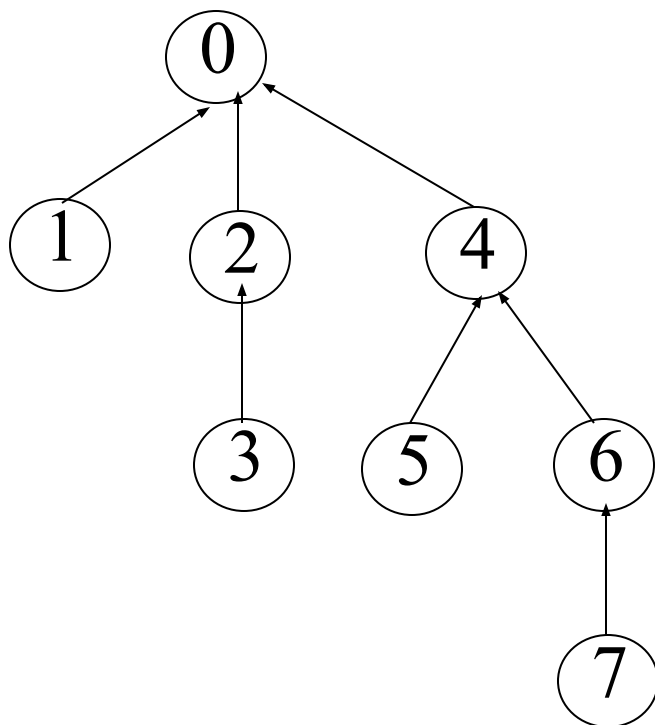
**Figure 5.45: Trees achieving worst case bound (p.245)**



# Modified *Find(i)* Operation

```
int find2(int i)
{
    int root, trail, lead;
    for (root=i; parent[root]>=0;
        root=parent[root]) ;
    for (trail=i; trail!=root;
        trail=lead) {
        lead = parent[trail];
        parent[trail]= root;
    }
    return root;
}
```

If  $j$  is a node on the path from  $i$  to its root then make  $j$  a child of the root



find(7) find(7) find(7) find(7) find(7) find(7) find(7) find(7)

go up	3	1	1	1	1	1	1	1
reset	2							

---

12 moves (vs. 24 moves)

# Applications

- Find equivalence class  $i \equiv j$
- Find  $S_i$  and  $S_j$  such that  $i \in S_i$  and  $j \in S_j$   
(two finds)
  - $S_i = S_j$  do nothing
  - $S_i \neq S_j$  union( $S_i$ ,  $S_j$ )
- example  
 $0 \equiv 4, 3 \equiv 1, 6 \equiv 10, 8 \equiv 9, 7 \equiv 4, 6 \equiv 8,$   
 $3 \equiv 5, 2 \equiv 11, 11 \equiv 0$   
 $\{0, 2, 4, 7, 11\}, \{1, 3, 5\}, \{6, 8, 9, 10\}$

preorder: A B C D E F G H I

inorder: B C A E D G H F I

