

Network QoS

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Lecture 11

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Outline

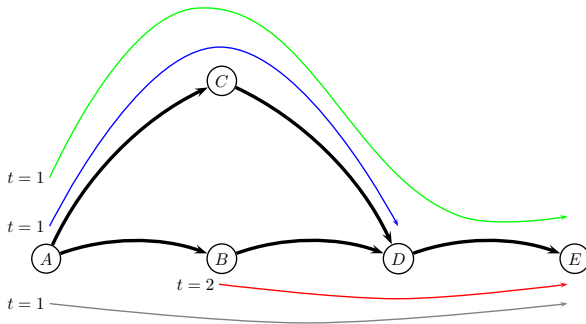
- 1 Adversarial Queueing Theory: Recap and Traffic Stability
 - AQT: Recap
 - Traffic Stability
 - Alternative Definitions of Adversaries
- 2 Topology Stability
 - Universal Stability for $r = 1$
 - Universal Stability for $r < 1$
- 3 An Adversarial Framework for Wireless Networks
 - Model
 - The MaxWeight Protocol

System and Traffic Model

- Slotted time
- Directed graph $G = (V, E)$
 - single rate-1 queue Q_e at link tail
 - unlimited buffer space
 - employs scheduling policy \mathcal{P}
- Unit size packets
 - $p = (\pi_p, a_p)$
 - π_p simple path in G and a_p arrival time at path source
 - take a single time slot to traverse a link
- (r, b) -adversary
 - for any time interval I and edge $e \in E$
$$N(e, I) \leq r|I| + b$$
 - $N(e, I)$: # packets injected during interval I with $e \in \text{path}$
- Stability
 - $\sup_t \sum_{e \in E} Q_e(t) < \infty$
 - $Q_e(t)$: queue size at tail of e at time t

Protocols

- Work-conserving (WC)



FIFO	Nearest-to-Go (NTG)	Farthest-to-Go (FTG)	Shortest-in-System (SIS)
LIFO	Farthest-from-Source (FFS)	Nearest-to-Source (NTS)	Longest-in-System (LIS)

Last Week Results

- Stability vs. delay
 - for any $(r < 1, b)$ -adversary and any WC protocol, the system is stable iff it has bounded delay
 - “if” direction holds also for $r = 1$
- Farthest-to-go
 - universally stable
- FIFO
 - not universally stable for any rate $r > 0$
- Some protocols are universally stable, and some are not. E.g.,

Protocol	Universally Stable?
FIFO	No
LIFO	No
Nearest-to-Go (NTG)	No
Farthest-from-Source (FFS)	No
Farthest-to-Go (FTG)	Yes
Nearest-to-Source (NTS)	Yes
Shortest-in-System (SIS)	Yes
Longest-in-System (LIS)	Yes

This Week

- Easy traffic
 - are there rates for which any WC protocol is stable?
 - e.g., sometimes even FIFO might be stable
 - depends on topology?
- Universally stable topologies
 - are there topologies for which any WC protocol is stable?
 - at any rate ≤ 1 ?

Stability Against Low-rate Adversaries

Theorem

For any $G = (V, E)$ there exists some $r(G) > 0$ s.t. any WC protocol \mathcal{P} is stable on G against $(r < r(G), b \geq 0)$ -adversaries.

Proof (for FIFO and $r(G) = 1/d$)

- Assume $r < \frac{1}{d}$
- Prove that every packet has bounded delay T in every link
 \Rightarrow overall bounded delay implies stability
- Given any $\delta \in (0, 1)$ define
 - $w_\delta = \frac{b}{1-r} \cdot \frac{1}{\delta}$
 - $r_\delta = r + \delta(1-r)$
 - for small enough δ , $r_\delta \in (r, \frac{1}{d})$
- “smooth-out” bursts over intervals I of length w_δ
$$N(e, I) \leq w_\delta r + b = w_\delta r + w_\delta(1-r)\delta = w_\delta \cdot r_\delta$$

Stability Against Low-rate Adversaries

Theorem

For any $G = (V, E)$ there exists some $r(G) > 0$ s.t. any WC protocol \mathcal{P} is stable on G against $(r < r(G), b \geq 0)$ -adversaries.

Proof (for FIFO and $r(G) = 1/d$)

- Every packet p arriving at Q_e at t , leaves by $T_t = t + w_\delta \cdot r_\delta$
 - By induction on t
- Base case: $t \leq d \cdot w_\delta \cdot r_\delta$
 - assume by contradiction p is still in Q_e at T_t
 - $Q_e(t) \geq w_\delta \cdot r_\delta + 1$
 - FIFO...
 - $N(e, [0, t]) \leq \lceil d \cdot r_\delta \rceil \cdot w_\delta \cdot r_\delta \leq w_\delta \cdot r_\delta$
 - (number of w_δ windows \times bound per window) + ($r_\delta < \frac{1}{d}$)
 - contradiction

Stability Against Low-rate Adversaries

Theorem

For any $G = (V, E)$ there exists some $r(G) > 0$ s.t. any WC protocol \mathcal{P} is stable on G against $(r < r(G), b \geq 0)$ -adversaries.

Proof (for FIFO and $r(G) = 1/d$)

- Induction step: consider $t > d \cdot w_\delta \cdot r_\delta$
 - assume by contradiction p is still in Q_e at T_t
 - $Q_e(t) \geq w_\delta \cdot r_\delta + 1$
 - FIFO...
 - every packet in e 's buffer at t was injected after $t - d \cdot w_\delta \cdot r_\delta$
 - assume the contrary
 - by I.H. it waited in every prior link $\leq w_\delta \cdot r_\delta$ time
 - hence, it was in the system $\leq d \cdot w_\delta \cdot r_\delta$ time
 - it cannot be in the buffer at t
 - $N(e, [t - d \cdot w_\delta \cdot r_\delta, t]) \leq w_\delta \cdot r_\delta$
 - same as base case
 - contradiction



Alternative Definition of Adversaries

- Above proof implies an alternative definition of adversaries
- (w, ε) -window adversary
 - for any time interval I of length w , and edge $e \in E$

$$N(e, I) \leq \lceil w(1 - \varepsilon) \rceil$$

- An adversary is an $(r < 1, b)$ -adversary iff it is a $(w, \varepsilon > 0)$ -window adversary
 - \Leftarrow trivial, by choosing $r = (1 - \varepsilon)$ and $b = w$
 - \Rightarrow follows from the proof by choosing a sufficiently small δ :
 - $w_\delta = \frac{b}{1-r} \cdot \frac{1}{\delta}$
 - $r_\delta = r + \delta(1 - r) \quad \left(\xrightarrow[\delta \rightarrow 0]{} r \right)$
 - set $w = w_\delta$ and $\varepsilon = 1 - r_\delta$

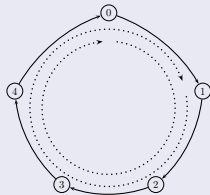
Unstable Topologies ($r = 1$)

Theorem (instability of cycles ($r = 1$))

LIS is unstable for the n -cycle ($n \geq 3$) against $(1, b)$ -adversaries

Proof sketch.

- i -loop
 - packet from i to i
- $(1, b)$ -adversary:
 - phases P_k , $k = 1, 2, \dots$
 - sub-phase $S_{k,1}$: for nk time units inject 1-loops
 - sub-phase $S_{k,2}$: for nk time units: inject 0-loops
- Under LIS, by end of P_k
 - 1 packet in node 1
 - $nk - 1$ packets in node 0
- Proof by induction on k
- $\lim_{t \rightarrow \infty} Q_{(0,1)}(t) = \infty$



Directed Acyclic Graphs (DAGs)

Theorem

A network $G = (V, E)$ is universally stable for $r = 1$ iff G is a DAG

- Notation

- for every link $e = (u, v) \in E$, define
 - d_e : edge level (max-distance from source node)
 - potential $f(e)$:

$$f(e) = \begin{cases} 1 & u \text{ is a source} & (d_e = 0) \\ 1 + \sum_{u \text{ incoming edges } e'} f(e') & \text{otherwise} & (d_e > 0) \end{cases}$$

- $A_e(t)$: number of packets in the *network* at t requiring e
- $Q_e(t)$: number of packets in e 's queue at t
- assume system is empty at $t = 0$
- Proof idea:
 - show that $A_e(t) \leq b \cdot f(e)$
 - hence, stable ($Q_e(t) \leq A_e(t)$)
 - combine with instability of cycles

Directed Acyclic Graphs (DAGs)

Lemma

For all $e \in E$ and t , $A_e(t) \leq b \cdot f(e)$

Proof (by induction on edge level)

- Basis: $d(e) = 0$, and arbitrary t
 - i.e., $e = (u, v)$ leaves a source node u
 - $A_e(\cdot) = Q_e(\cdot)$
 - let $t' \leq t$ be maximal such that $Q_e(t') = 0$
 - exists since system is empty at 0
 - Adversary's injections during $(t', t]$
 - $N(e, (t', t]) \leq (t - t') + b$
 - at least $t - t'$ packets traverse e during $(t', t]$
 - by maximality of $t' + \text{WC}$
 - hence, $Q_e(t) \leq b = b \cdot 1 = b \cdot f(e)$
- Induction step: assume true for all t and e' s.t. $d(e') < d(e)$

Directed Acyclic Graphs (DAGs)

Lemma

For all $e \in E$ and t , $A_e(t) \leq b \cdot f(e)$

Proof (by induction on edge level)

- Choose t' as in the base case
 - hence, $A_e(t) \leq A_e(t') + b$
- At t' , $Q_e(t') = 0$ (by choice of t')
 - packets contributing to $A_e(t')$ cross some incoming edge of u
 - $A_e(t') \leq \sum_{u \text{ incoming edges } e'} A_{e'}(t')$
 - for every incoming edge e' of u
 - $d(e') < d(e)$

$$A_e(t') + \overbrace{(t - t') + b}^{r|I| + b} - \overbrace{(t - t')}^{Q_e \neq \emptyset}$$

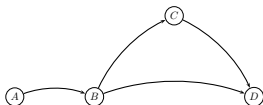
- Hence,

$$\begin{aligned} A_e(t) &\leq b + A_e(t') \\ &\leq b + \sum_{u \text{ incoming edges } e'} A_{e'}(t') \\ &\leq b + \sum_{u \text{ incoming edges } e'} b \cdot f(e') = b \cdot f(e) \end{aligned}$$

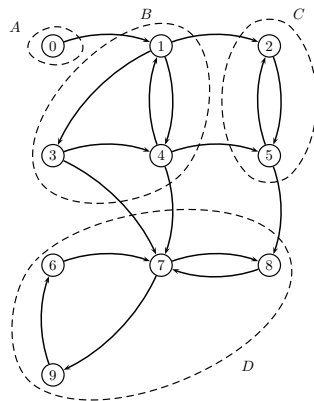
□

Decomposing Universal Stability

- Goal:
 - find characteristics of networks that guarantee stability ($r < 1$)
 - DAGs for $r = 1$
- Strongly-connected components
- G is a DAG of its strongly-connected components



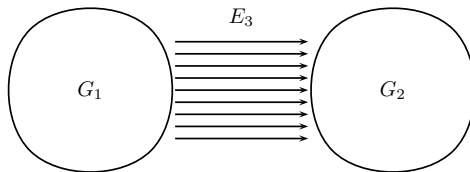
- Stability and connected components
 - if a connected component is not universally stable
 - entire network is not
 - is the converse also true?



Composing Universal Stability ($r < 1$)

Theorem

If $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are universally stable ($V_1 \cap V_2 = \emptyset$), then for any $E_3 \subset V_1 \times V_2$, $G = (V_1 \cup V_2, E_1 \cup E_2 \cup E_3)$ is universally stable.



Composing Universal Stability ($r < 1$)

Theorem

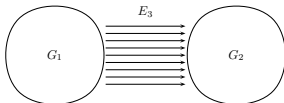
If $G_1 = (V_1, E_1)$ and $G_2 = (V_2, E_2)$ are universally stable ($V_1 \cap V_2 = \emptyset$), then for any $E_3 \subset V_1 \times V_2$, $G = (V_1 \cup V_2, E_1 \cup E_2 \cup E_3)$ is universally stable.

Corollary

A network is universally stable iff every strongly-connected component is universally stable

- Simple proof by induction on number of connected components
 - “Hard” part is the above theorem...

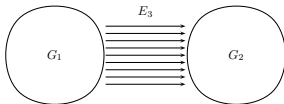
Composing Universal Stability ($r < 1$)



Proof of Theorem

- We will use the window-adversary definition
- Assume G_1 and G_2 are universally stable for $(w, \varepsilon > 0)$ -window adversaries
- Goal: show that G is stable for $(w, \varepsilon > 0)$ window adversaries
- Assume some $(w, \varepsilon > 0)$ window adversary
- G_1 stable: has some bounded delay T_1 (since $\varepsilon > 0$)
 - $\forall t$, any packet injected to G_1 at t leaves G_1 by $t + T_1$
- Consider any time interval I of length T_2
 - how many packets can enter G_2 during such an interval?

Composing Universal Stability ($r < 1$)



Proof of Theorem

- We would like to find some $0 < \varepsilon' \leq \varepsilon$ satisfying

$$(T_1 + T_2 + w)(1 - \varepsilon) \leq T_2(1 - \varepsilon')$$

- implies: number of packets entering G_2 during interval of length T_2 is at most $T_2(1 - \varepsilon')$
- i.e., traffic entering G_2 “generated” by a (T_2, ε') -window adversary
- This is satisfied for $T_2 = \frac{(T_1 + w)(1 - \varepsilon)}{\varepsilon - \varepsilon'}$
- G_2 is stable, hence it has bounded delay
- All traffic entering G has bounded delay $\Rightarrow G$ is stable □

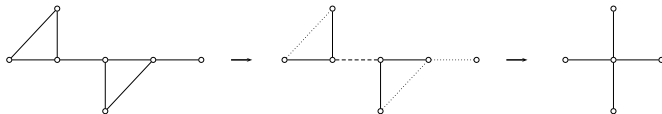
Universal Stability for $r < 1$

- Are DAGs still the only universally stable topologies?
 - Specifically, are cycles universally stable for $r < 1$?

Theorem

Cycles are universally stable for $r < 1$

- What are the exact conditions for universal stability for $r < 1$?
- Graph minor of G :
 - any graph resulting from contracting/deleting edges



Universal Stability for $r < 1$

- Are DAGs still the only universally stable topologies?
 - Specifically, are cycles universally stable for $r < 1$?

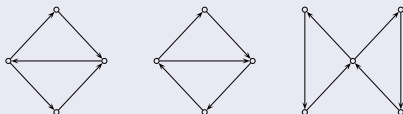
Theorem

Cycles are universally stable for $r < 1$

- What are the exact conditions for universal stability for $r < 1$?

Theorem (for networks with no parallel edges)

A network is universally stable for $r < 1$ iff it excludes the minors



- Verifying if H is/isn't a minor of G : NP-hard in general
- For fixed minors (as in this case): poly-time solvable

Open Questions & References

- Are there non trivial (topology,protocol) pairs that are stable?
 - currently only known for universally stable topology/protocol
- Given a protocol P, are there P-stable topologies?
 - topologies stable for protocol P
 - e.g., FIFO-stable topologies?
- Are there protocols/topologies stable only for $r < 1 - \varepsilon$?
 - e.g., only for $r \leq \frac{1}{2}$

• References

- Borodin, Kleinberg, Raghavan, Sudan, and Williamson. Adversarial Queueing Theory, Journal of the ACM 48(1):13–38 (2001)
- Andrews, Awerbuch, Fernández, Leighton, Liu, and Kleinberg. Universal-Stability Results and Performance Bounds for Greedy Contention-Resolution Protocols, Journal of the ACM 48(1):39–69 (2001)
- Goel. Stability of networks and protocols in the adversarial queueing model for packet routing, Networks 37(4):219–224 (2001)

An Adversarial Model for Wireless Networks

- Wireless networks
 - dynamic channel conditions
 - dynamic link capacities
 - links disappearing/re-appearing
 - ad-hoc
 - topology constantly changing
 - routing is difficult
- Digraph $G = (V, E)$ with max-degree Δ , slotted time
 - link capacity $c_e(t)$ ($\forall e \in E$ and time t):
 - dynamic, changes as a function of t
 - controlled by the *adversary*
 - assume: $\forall t, c_e(t) \in \{0, 1\}$
 - $E_t = \{e \in E \mid c_e(t) = 1\}$
 - injected packet p
 - size ℓ_p
 - source s_p , destination d_p
 - path *not specified!!*
 - assume $\ell_p \equiv 1$

Adversaries and Objective

- Question:
 - how would we define a “reasonable” adversary?
 - no specific path
 - not clear if path ever exists
 - even if it exists now, not clear if it will ever reappear
- Assume the adversary identifies *some* path
 - for any time interval I s.t. $|I| = w$, and p injected during I
 - Γ_p : some specific adversary-path between s_p and d_p
 - $N(e, I)$: number of packets p injected during I s.t. $e \in \Gamma_p$
- (w, ε) -window adversary
 - for any time interval I of length w

$$N(e, I) \leq (1 - \varepsilon) \sum_{t \in I} c_e(t) \quad (\leq w)$$

Objective

Determine *scheduling* and *routing* for each packet

- Concern: (when) can we guarantee stability?

Designing a Protocol

- AQT lesson: scheduling matters
 - be careful not to cause overload downstream
- How can this be implemented “locally”?
 - necessary: no permanent global view of the graph/routes
 - forward only if doesn't cause “local” overload
- Note: not work conserving!!
 - in particular, no delay guarantees
- A classical result in stochastic network analysis
 - Tassiulas&Ephremides: load-balancing locally is optimal
- Per-destination queueing
 - $\forall v \in V$: maintain a queue $Q_{v,d}$ for each destination $d \in V$
 - $q_{v,d}^t$: size of $Q_{v,d}$ in time t

The MaxWeight Protocol

Algorithm 1 MaxWeight(β): at any time t

- 1: accept all arrivals at t
 - 2: **for** every $(v, u) \in E_t$ **do**
 - 3: $d_{(v,u)}^* \leftarrow \arg \max_d \left\{ (q_{v,d}^t)^\beta - (q_{u,d}^t)^\beta \right\}$
 - 4: **if** $q_{v,d^*}^t - q_{u,d^*}^t \geq \Delta$ **then**
 - 5: forward a $d_{(v,u)}^*$ -packet from v to u
 - 6: **end if**
 - 7: **end for**
 - 8: drop all packets that have arrived at their destination
-

“constant” $\beta \geq 1$

Theorem (for large enough β)

MaxWeight(β) ensures the system is stable

Proof Idea

- Proof method: potential function

- recall AAP

- $|O \setminus A| \leq \Phi \leq O(\log n) |A|$

- here: a “classical” drift argument

$$P(t) = \sum_{v,d \in V} (q_{v,d}^t)^{\beta+1}$$

- Proof idea:

- show that $P(t)$ is always bounded:

- if queues become too large, $P(t)$ decreases (fast)!!

- a.k.a.: *negative drift*

- stability: since $\sum_{v,d \in V} q_{v,d}^t \leq P(t)$

The Key (Technical...) Lemma

Lemma

Every packet p injected at t can be associated with packets forwarded along Γ_p s.t. the sum of potential changes due to these forwardings until time $(t + w - 1)$ is at least

$$O(q^{\beta-1}) - \frac{\varepsilon}{1-\varepsilon}(\beta+1)q^\beta$$

where q is height of p 's injection queue at t .

Corollary

$\exists q^ = q^*(n, w, \varepsilon)$ s.t. if $q \geq q^*$ then the sum of potential change is less than $-\varepsilon q^\beta$.*

- I.e., the decrease is $\Omega(q^\beta)$.

Proof Sketch

- A packet is only forwarded to a smaller queue
 \implies potential increase is only due to injections
- By contradiction: adversary makes the system unstable
 \implies the potential increases unboundedly
- ⊗
- There's no point to repeat a configuration
 - configuration S_t : state of all the queues at t
 - for all $t < t'$, $S_t \neq S_{t'}$
 - otherwise, we can just "remove" the period between t and t'
- Number of configurations with max-queue size q : $q^{(n^2)}$
 $\implies t_q = O(q^{(n^2)})$: first time a queue reaches load q
 - after $q^{(n^2)}$ steps there's an injection to a queue with load q

Proof Sketch

- A packet is only forwarded to a smaller queue
 \implies potential increase is only due to injections
- By contradiction: adversary makes the system unstable
 \implies the potential increases unboundedly
- ⊗
- Overall potential inc. during $[t_q, t_q + w)$ can be shown to be
 - $O(t_q) = O(q^{(n^2)})$
- By lemma, potential dec. during $[t_q, t_q + w)$
 - $\Omega(q^\beta)$
 - for $q \geq q^*$
- for $\beta > n^2$ and large enough q the difference is < 0
 - I.e., a *negative drift*
- Contradiction!

Aftermath and References

- Aftermath

- results extend also to arbitrary edge capacities/packet lengths
- works also for $\beta = 1$
 - a much more complex proof...
- various related models / results
 - both generalizations and special cases

- References

- Andrews, Jung, and Stolyar. Stability of the Max-Weight Routing and Scheduling Protocol in Dynamic Networks and at Critical Loads, STOC 2007, pp. 145–154
- Lim, Jung, and Andrews. Stability of the Max-Weight Protocol in Adversarial Wireless Networks, Infocom 2012, pp. 1251–1259
- Tassiulas and Ephremides. Stability properties of constrained queueing systems and scheduling policies for maximum throughput in multihop radio networks, IEEE Transactions on Automatic Control 37(12):1936–1948 (1992)